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# Control Systems

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## 1 Op-Amp RC Oscillator Circuits

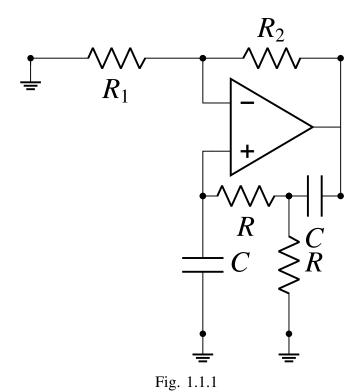
Abstract—This manual is an introduction to control systems in feedback circuits. Links to sample Python codes are available in the text.

Download python codes using

svn co https://github.com/gadepall/school/trunk/ control/feedback/codes

### 1 Op-Amp RC Oscillator Circuits

1.1. For the circuit shown in Fig. 1.1.1, find L(s),  $L(j\omega)$ , the frequency for zero loop phase, and  $R_2/R_1$  for oscillation.



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**Solution:** The equivalent control system representation is shown in Fig. 1.1.2. Oscillators do not include input signal.

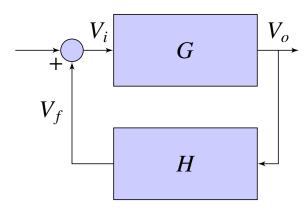


Fig. 1.1.2

## 1.2. Find the open loop gain G.

**Solution:** Let the closed loop gain, open-loop gain of op-amp connected in non-inverting configuration be  $T_1$  and  $G_1$  respectively. From Table ??

$$T_1 = \frac{G_1 (R_1 + R_2)}{(R_1 + R_2) + G_1 R_1}$$
 (1.2.1)

$$T_1 = \frac{(R_1 + R_2)}{(R_1 + R_2)/G_1 + R_1}$$
 (1.2.2)

Assuming  $G_1 \to \infty$ 

$$T_1 = 1 + \frac{R_2}{R_1} \tag{1.2.3}$$

The open loop gain of the circuit shown in Fig. 1.1.1 is equal to the closed loop gain of an opamp connected in non-inverting configuration.

$$G = T_1 \tag{1.2.4}$$

$$\implies G = 1 + \frac{R_2}{R_1} \tag{1.2.5}$$

1.3. Find the feedback factor *H*.

**Solution:** The small signal model is shown in Fig. 1.3 Applying KCL at node  $V_f$ 

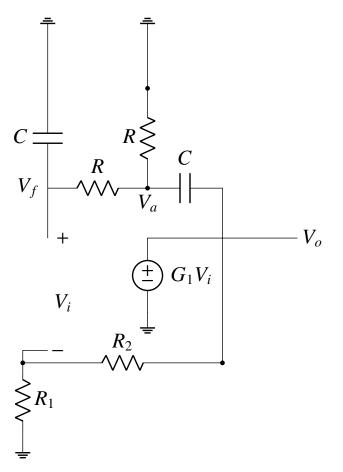


Fig. 1.3

$$\frac{V_f - 0}{\frac{1}{sC}} + \frac{V_f - V_a}{R} = 0 \tag{1.3.1}$$

$$V_f\left(sC + \frac{1}{R}\right) = \frac{V_a}{R} \tag{1.3.2}$$

$$V_a = V_f (sRC + 1) \tag{1.3.3}$$

Applying KCL at node  $V_a$ 

$$\frac{V_a - V_f}{R} + \frac{V_a - 0}{R} + \frac{V_a - V_o}{\frac{1}{sC}} = 0$$
 (1.3.4)

$$V_a \left(\frac{2}{R} + sC\right) = \frac{V_f}{R} + V_o sC \tag{1.3.5}$$

Substitute  $V_a$  value from equation (1.3.3)

$$V_f(sRC+1)\left(\frac{2}{R}+sC\right) = \frac{V_f}{R} + V_o sC$$
 (1.3.6)

$$V_f\left(3 + sRC + \frac{1}{sRC}\right) = V_o \tag{1.3.7}$$

The feedback factor H is given by

$$H = \frac{V_f}{V_o} \tag{1.3.8}$$

$$\implies H = \frac{1}{\left(3 + sRC + \frac{1}{sRC}\right)} \tag{1.3.9}$$

1.4. Find the loop gain L(s).

**Solution:** The transfer function of the equivalent positive feedback circuit in Fig. 1.1.2 is

$$T = \frac{G}{1 - GH} \tag{1.4.1}$$

Therefore, loop gain is given by

$$L = GH \tag{1.4.2}$$

From equations (1.2.5) and (1.3.9)

$$L(s) = \left(1 + \frac{R_2}{R_1}\right) \left(\frac{1}{3 + sRC + \frac{1}{sRC}}\right)$$
 (1.4.3)

$$\implies L(s) = \left(\frac{1 + \frac{R_2}{R_1}}{3 + sRC + \frac{1}{sRC}}\right) \tag{1.4.4}$$

1.5. Find the loop gain in terms of  $i\omega$ .

**Solution:** Substitute  $s = j\omega$  in equation (1.4.4)

$$L(j\omega) = \left(\frac{1 + \frac{R_2}{R_1}}{3 + j\omega RC + \frac{1}{j\omega RC}}\right)$$
(1.5.1)

$$\implies L(j\omega) = \left(\frac{1 + \frac{R_2}{R_1}}{3 + j\left(\omega RC - \frac{1}{\omega RC}\right)}\right) \quad (1.5.2)$$

1.6. Find the frequency for zero loop phase.

**Solution:** The frequency at which loop phase will be zero (i.e. loop gain will be a real number). To obtain the required frequency, equate the imaginary part of the loop gain  $L(j\omega)$  to zero.

$$j\left(\omega RC - \frac{1}{\omega RC}\right) = 0 \tag{1.6.1}$$

$$\omega^2 = \frac{1}{(RC)^2}$$
 (1.6.2)

$$\implies \omega = \frac{1}{RC} \tag{1.6.3}$$

(1.3.7) 1.7. Find  $R_2/R_1$  for oscillation.

**Solution:** For oscillations to start,

- the imaginary part of the loop gain should become zero.
- the loop gain must be at least equal to unity. From equation (1.5.2)

$$\left(\frac{1 + \frac{R_2}{R_1}}{3 + j(0)}\right) \ge 1$$
(1.7.1)

$$1 + \frac{R_2}{R_1} \ge 3 \tag{1.7.2}$$

$$\implies \frac{R_2}{R_1} \ge 2 \tag{1.7.3}$$

1.8. Draw the block diagram and circuit diagram for H.

**Solution:** See figs 1.8.4 and 1.8.5 .From Fig.

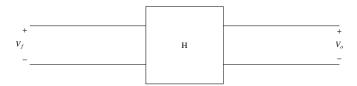


Fig. 1.8.4: Feedback block diagram

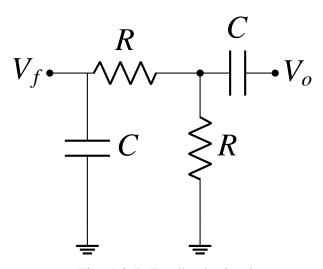


Fig. 1.8.5: Feedback circuit

1.8.5, the analysis is same as problem 1.3

$$\frac{V_f}{V_o} = \frac{1}{\left(3 + sRC + \frac{1}{sRC}\right)}$$
 (1.8.1)

$$\implies H = \frac{1}{\left(3 + sRC + \frac{1}{sRC}\right)} \tag{1.8.2}$$

1.9. Find the input and output resistances of the feedback network.

**Solution:** To find the input resistance  $R_{11}$  short the output node  $V_o$  to ground.

$$R_{11} = Z||(R + (R||Z))$$
 (1.9.1)

where  $Z = \frac{1}{sC}$  is the impedance of the capacitor.

$$\implies R_{11} = \left(\frac{1}{sC} \| \left( R + R \| \frac{1}{sC} \right) \right) \tag{1.9.2}$$

To find the output resistance  $R_{22}$  short the input node  $V_f$  to ground.

$$R_{22} = Z + (R||R) \tag{1.9.3}$$

$$\implies R_{22} = \frac{1}{sC} + \frac{R}{2}$$
 (1.9.4)

1.10. Draw the block diagram and circuit diagram for *G*.

**Solution:** See figs 1.10.6 and 1.10.7.From

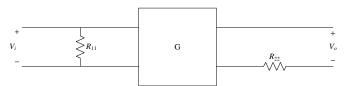


Fig. 1.10.6: Open loop block diagram

Fig. 1.10.7 using same analysis as problem 1.2

$$G = \frac{V_o}{V_i} \tag{1.10.1}$$

$$G = \frac{R_1 + R_2}{R_1} \tag{1.10.2}$$

$$\implies G = 1 + \frac{R_2}{R_1} \tag{1.10.3}$$

Hence verified with equation (1.2.5).

1.11. Find the amplitude and frequency for some arbitrary values given in Table 1.11.

**Solution:** From equation (1.2.5)

$$G = 1 + \frac{R_2}{R_1} = 3 \tag{1.11.1}$$

From equation (1.3.9)

$$H = \frac{1}{3 + 0.25s + \frac{1}{0.25s}} \tag{1.11.2}$$

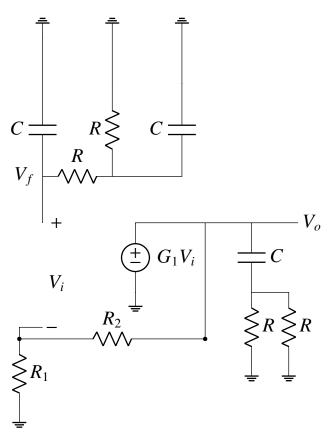


Fig. 1.10.7: Open loop circuit diagram

Parameter	Value
R	250Ω
C	1mF
$R_2$	$2k\Omega$
$R_1$	$1k\Omega$

**TABLE 1.11** 

From equation (1.4.1)

$$T = \frac{3(0.0625s^2 + 0.75s + 1)}{0.0625s^2 + 1}$$
(1.11.3)

The following code plots the oscillating response of the system.

codes/ee18btech11047/ee18btech11047.py

Amplitude: From Fig. 1.11 V(peak-peak) is

$$V_{p-p} = 71.8 \tag{1.11.4}$$

$$V_{max} = \frac{V_{p-p}}{2} = 35.9 \tag{1.11.5}$$

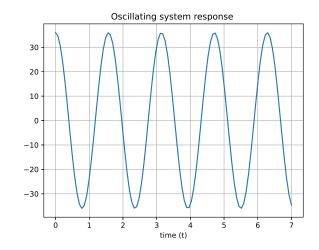


Fig. 1.11

Frequency: From equation (1.6.3)

$$\omega = \frac{1}{RC} = 4rad/sec \tag{1.11.6}$$

$$f = \frac{\omega}{2\pi} = 0.636Hz \tag{1.11.7}$$