

Computational Physics – Lecture 10: Molecular dynamics III

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Contents

- Molecular dynamics simulations
 - Time step
 - Equilibration
 - Measurements
 - Pseudocode
 - Thermostats
- Molecular dynamics \leftrightarrow Monte Carlo
- Exercises

Molecular dynamics simulation

Ingredients

- Boundary conditions
- Forces
- Initial conditions
- Integration algorithm
- **Time step**
- Equilibration
- Measurements

Molecular dynamics

Time step

- Choice is crucial
 - Too short \rightarrow phase space is sampled inefficiently
 - Too long \rightarrow energy will fluctuate (wildly)
- The maximum time step is defined by the fastest motion in the system
 - In standard MD with any real material at ordinary temperature $\Delta t = O(\text{fs})$
 10^6 - 10^8 time steps can be simulated (depends in general on the computational cost of the calculation of the forces) \rightarrow simulate processes that occur within 1 – 100 ns

Molecular dynamics

Time step

- Optimization and parallelization of software
- Special purpose hardware

→ Processes that occur within $1\ \mu\text{s}$ - $1\ \text{ms}$ can be simulated

Molecular dynamics simulation

Ingredients

- Boundary conditions
- Forces
- Initial conditions
- Integration algorithm
- Time step
- **Equilibration**
- Measurements

Molecular dynamics

Equilibration

- Since the system does not start from an equilibrium state, a certain number of time steps are to be taken until the system has reached an equilibrium → short MD simulation by itself

Molecular dynamics simulation

Ingredients

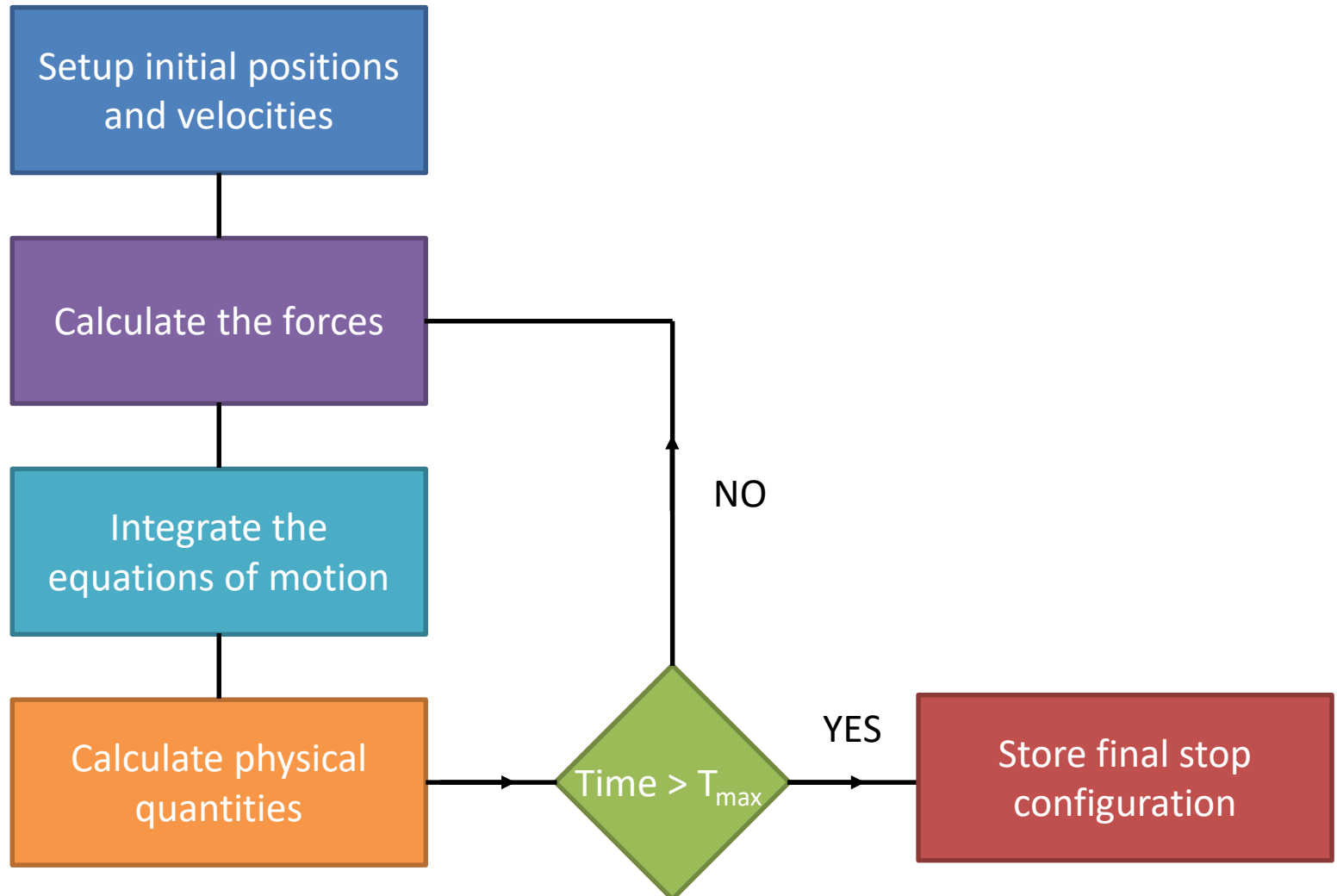
- Boundary conditions
- Forces
- Initial conditions
- Integration algorithm
- Time step
- Equilibration
- **Measurements**

Molecular dynamics

Measurements

- Construct estimators for physical quantities of interest

Molecular dynamics Scheme



Molecular dynamics

Pseudocode: Program

Understanding Molecular Simulation, D. Frenkel
and B. Smit, Academic Press (2001)

```
program md
call init
t=0
do while (t.lt.tmax)
  call force(f,en)
  call integrate(f,en)
  t=t+delt
  call sample
enddo
stop
end
```

simple MD program

initialization

MD loop

determine the forces

integrate equations of motion

sample averages

subroutines

Molecular dynamics

Pseudocode: Initialization

Understanding Molecular Simulation, D. Frenkel
and B. Smit, Academic Press (2001)

```
subroutine init
sumv=0
sumv2=0
do i=1,npart
  x(i)=lattice_pos(i)
  v(i)=(ranf()-0.5)
  sumv=sumv+v(i)
  sumv2=sumv2+v(i)**2
enddo
sumv=sumv/npart
sumv2=sumv2/npart
fs=sqrt(3*temp/sumv2)
do i=1,npart
  v(i)=(v(i)-sumv)*fs
  xm(i)=x(i)-v(i)*dt
enddo
return
end
```

initialization of MD program

place the particles on a lattice
assign random velocities in [-0.5,0.5]
velocity center of mass
kinetic energy (mass = 1)

velocity center of mass
mean squared velocity
scale factor of the velocities ($E_{kin} = 3NT/2$)
set desired kinetic energy
set velocity center of mass to zero
position previous time step

Molecular dynamics

Pseudocode: Calculation of the forces

Understanding Molecular Simulation, D. Frenkel
and B. Smit, Academic Press (2001)

```
subroutine force(f,en)
en=0
do i=1,npart
  f(i)=0
enddo
do i=1,npart-1
  do j=i+1,npart
    xr=x(i)-x(j)
    xr=xr-box*nint(xr/box)
    r2=xr**2
    if (r2.lt.rc2) then
      r2i=1/r2
      r6i=r2i**3
      ff=48*r2i*r6i*(r6i-0.5)
      f(i)=f(i)+ff*xr
      f(j)=f(j)-ff*xr
      en=en+4*r6i*(r6i-1)-ecut
    endif
  enddo
enddo
return
end
```

determine the force and energy
set energy to zero

set forces to zero

loop over all pairs

periodic boundary conditions

test cut-off

Lennard-Jones potential
update force

update potential energy

Molecular dynamics

Pseudocode: Integrate eqns. of motion

Understanding Molecular Simulation, D. Frenkel
and B. Smit, Academic Press (2001)

```
subroutine integrate(f,en)
sumv=0
sumv2=0
do i=1,npart
  xx=2*x(i)-xm(i)+delt**2*f(i)
  vi=(xx-xm(i))/(2*delt)
  sumv=sumv+vi
  sumv2=sumv2+vi**2
  xm(i)=x(i)
  x(i)=xx
enddo
temp=sumv2/(3*npart)
etot=(en+sumv2)/(2*npart)
return
end
```

integrate equations of motion

MD loop

Verlet algorithm $\mathbf{r}(t + \Delta t) = 2\mathbf{r}(t) - \mathbf{r}(t - \Delta t) + \mathbf{a}(t)(\Delta t)^2$

velocity $\mathbf{v}(t) = \frac{\mathbf{r}(t + \Delta t) - \mathbf{r}(t - \Delta t)}{2\Delta t}$

velocity center of mass

total kinetic energy

update positions previous time

update positions current time

instantaneous temperature

total energy (potential + kinetic) per particle

Molecular dynamics

Temperature

- MD naturally samples from the microcanonical ensemble (N, V, E)
 - Calculate forces on all particles from the derivative of the force field
 - Integrate the equations of motion with some time step
 - Recalculate the forces and repeat the process to generate a dynamical trajectory in the (N, V, E) ensemble
 - The mean kinetic energy is constant \rightarrow average kinetic temperature T_K is constant

Molecular dynamics

Temperature

- Sampling from canonical ensembles (N, V, T) requires particles to interact with a **thermostat**
 - In thermal equilibrium T_K fluctuates. Sampling from the (N, V, T) ensemble requires keeping the statistical temperature T_S constant

Molecular dynamics

Temperature

– Velocity scaling

$$\mathbf{v}_n^{new} = \sqrt{T_S / T_K(t)} \mathbf{v}_n^{old} \quad \text{with} \quad 3NT_K(t) = \sum_{n=1}^N m_n \mathbf{v}_n^2$$

- Straightforward to implement
- Results do not correspond to any known ensemble

– Berendsen method: Velocities are rescaled after each step by a factor

$$\lambda = \left[1 + \frac{\Delta t}{\tau} \left(\frac{T_S}{T_K(t)} - 1 \right) \right]^{1/2}, \quad \tau : \begin{array}{l} \text{Parameter to adjust the strength} \\ \text{of the coupling to the heat bath} \end{array}$$

- Straightforward to implement and robust
- Results do not correspond to any known ensemble

Berendsen et al, J. Chem. Phys. 81, 3684 (1984)

Molecular dynamics

Temperature

- Nosé-Hoover thermostat: Modify Newton equations

$$\frac{d\mathbf{r}_n}{dt} = \mathbf{p}_n / m_n, \quad \frac{d\mathbf{p}_n}{dt} = \mathbf{F}_n - \zeta \mathbf{p}_n$$

$$\frac{d\zeta}{dt} = \frac{1}{\tau_T^2} \{T_K(t) / T_S - 1\}$$

where

τ_T : thermostat relaxation time (to be adjusted)

T_S : parameter

- Gives canonical properties

Nosé, J. Chem. Phys. 81, 511 (1984)

Nosé, Mol. Phys. 52, 255 (1984)

Hoover, Phys. Rev. A 31, 1696 (1985)

MD \leftrightarrow MC

MD

- Microcanonical ensemble (NVE) \rightarrow constant temperature simulations require special thermostat techniques
- Only input is the description of the interatomic interaction
- Provides detailed molecular/atomic level information
- Success depends on the availability of good potential functions
- Classical description

MC

- Canonical ensemble (NVT) \rightarrow simple to perform constant temperature simulations
- Speed up of equilibration process due to the flexibility in choosing random moves
- No discrete time approximations (and accompanying inaccuracies)
- Trajectories are based on energies only \rightarrow fictitious dynamics

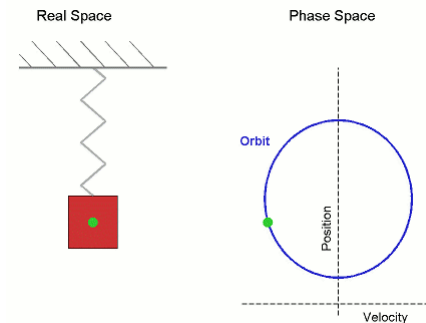
Molecular dynamics

Exercise 1

- Equation of motion $m_n \mathbf{a}_n = \mathbf{F}_n$
 - Mass of particle n : m_n
 - Acceleration of particle n : $\mathbf{a}_n = \frac{d^2 \mathbf{r}_n}{dt^2}$
 - Force acting on particle n : \mathbf{F}_n
- Harmonic oscillator

$$m \frac{d^2 x}{dt^2} = m\ddot{x} = -kx$$

http://en.wikipedia.org/wiki/Simple_harmonic_motion



Molecular dynamics

Exercise 1

- Implement the Euler algorithm for the harmonic oscillator ($V'(x) = kx$)
- Choice of units: $m = 1$, $k = 1$
- Initial position and velocity: $x(0) = 0$ and $v(0) = 1$
- Solve using $\Delta t = 0.1, 0.01, 0.001$ for $j = 1, \dots, [10000 / \Delta t]$
- Plot $x(j\Delta t)$ and compare with $\sin(j\Delta t)$
- Argue whether this algorithm is useful or not
 - It is not!

Molecular dynamics

Exercise 2

- Implement the two variants (a) and (b) of the Euler-Cromer algorithm for the harmonic oscillator ($V'(x) = x$) and repeat the calculations of exercise 1
- Implementation:

$$(a) = \begin{cases} p((j+1)\Delta t) = p(j\Delta t) - \Delta t V'(x(j\Delta t)) \\ x((j+1)\Delta t) = x(j\Delta t) + \Delta t p((j+1)\Delta t) \end{cases}$$

$$(b) = \begin{cases} x((j+1)\Delta t) = x(j\Delta t) + \Delta t p(j\Delta t) \\ p((j+1)\Delta t) = p(j\Delta t) - \Delta t V'(x((j+1)\Delta t)) \end{cases}$$

Argue whether these algorithms are useful or not



Molecular dynamics

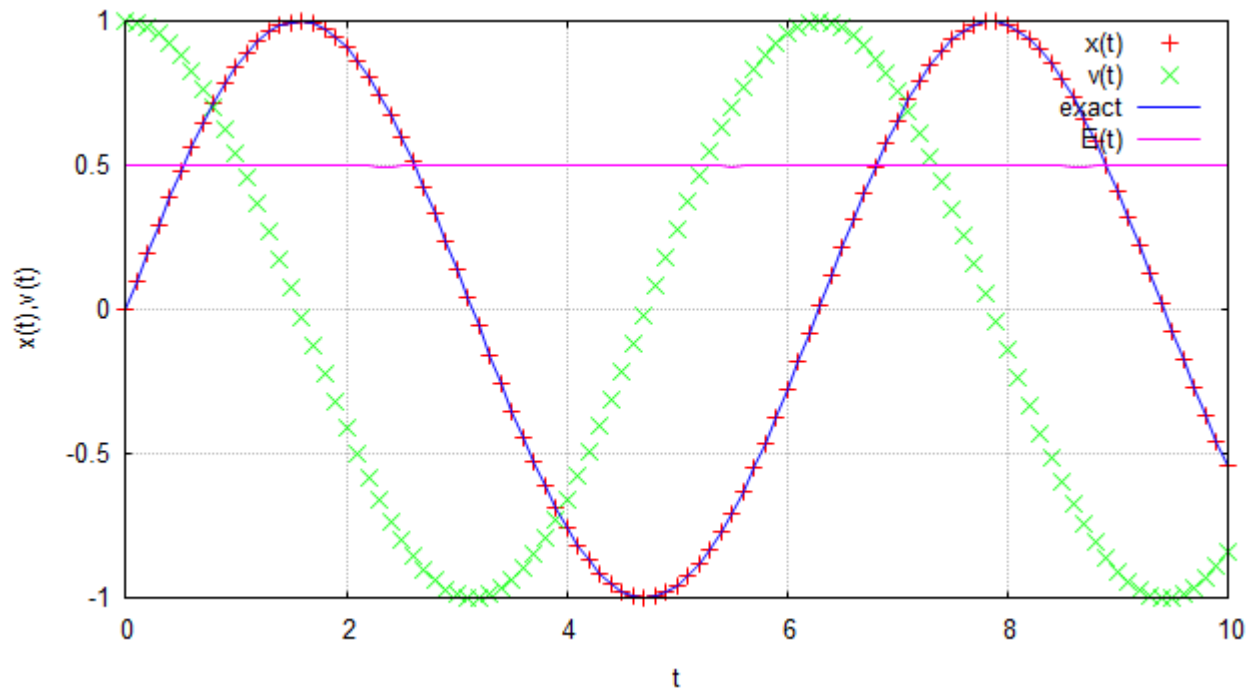
Exercise 2

- Plot $x(t)$, $v(t)$, and the energy $E(t) = v^2(t) / 2 + V(x(t))$ and also plot the analytical solution $x(t) = \sin t$ and $E = 1 / 2$ for comparison. Explain why the energy $E(t)$ is not exactly constant, as it should be according to classical mechanics
 - Use e.g. $\Delta t = 0.01$ for $j = 1, \dots, 1000$ for plotting purposes

Molecular dynamics

Exercise 2

- Example of such a plot



Molecular dynamics

Exercise 3

- Use the velocity Verlet algorithm and repeat the simulations of exercise 2
- Use $\Delta t = 0.1, 0.01$
- Plot $x(t), v(t)$ and the energy $E(t) = v^2(t) / 2 + V(x(t))$ and also plot the analytical solution $x(t) = \sin t$ and $E = 1 / 2$ for comparison.
- Discuss the differences with the results of the Verlet and Euler-Cromer algorithms

Molecular dynamics

Exercise 4

- Use the velocity Verlet algorithm to solve the equation of motion of many coupled oscillators:

$$H = K + V = \frac{1}{2} \sum_{n=1}^N v_n^2 + \frac{1}{2} \sum_{n=1}^{N-1} (x_n - x_{n+1})^2$$
$$\frac{\partial V}{\partial x_k} = 2x_k - x_{k-1} - x_{k+1} \quad , \quad 1 < k < N$$
$$\frac{\partial V}{\partial x_1} = x_1 - x_2 \quad , \quad \frac{\partial V}{\partial x_N} = x_N - x_{N-1}$$



Molecular dynamics

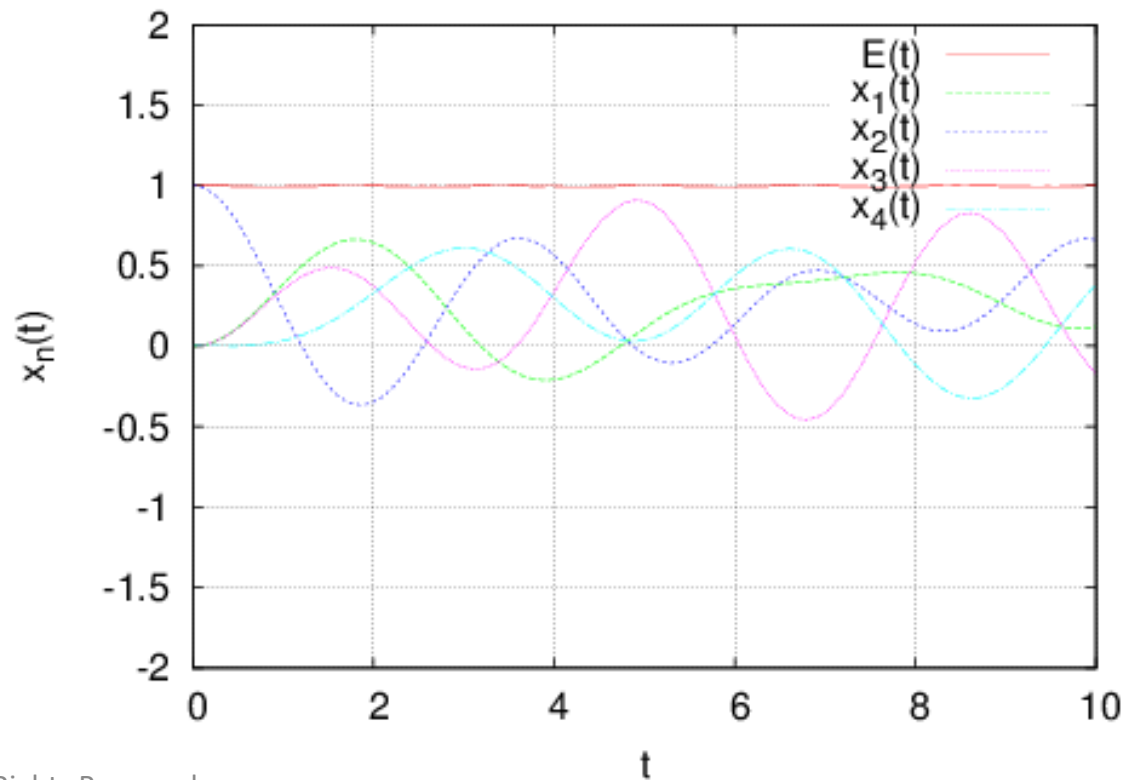
Exercise 4

- For $N = 4, 16, 128$ and $\Delta t = 0.1, 0.01$
- Initial configurations
 1. $v_1(0), \dots, v_N(0) = 0$
 $x_1(0), \dots, x_N(0) = 0$ except $x_{N/2}(0) = 1$
 2. $v_1(0), \dots, v_N(0) = 0$
 $x_k(0) = \sin \frac{\pi j k}{N+1}$ for $k = 1, \dots, N$ and $j = 1, N/2$
- Plot the results for several $x_k(t)$ and interpret!

Molecular dynamics

Exercise 4

- Example for $N = 4, \Delta t = 0.1$ and initial configuration (1)



Report

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- Filename: **Report_5_Surname1_Surname2.pdf**, where Surname1 < Surname2 (alphabetical order).
Example: Report_5_Jin_Willsch.pdf (Do not use “umlauts” or any other special characters in the names)
- Content of the report:
 - Names + matricule numbers + e-mail addresses + title
 - **Introduction**: describe briefly the problem you are modeling and simulating (write in complete sentences)
 - **Simulation model and method**: describe briefly the model and simulation method (write in complete sentences)
 - **Simulation results**: show figures (use grids, with figure captions !) depicting the simulation results. Give a brief description of the results (write in complete sentences)
 - **Discussion**: summarize your findings
 - **Appendix**: Include the listing of the program

Due date: 10 AM, June 5, 2023