

Computational Physics – Lecture 16: Diffusion equation II

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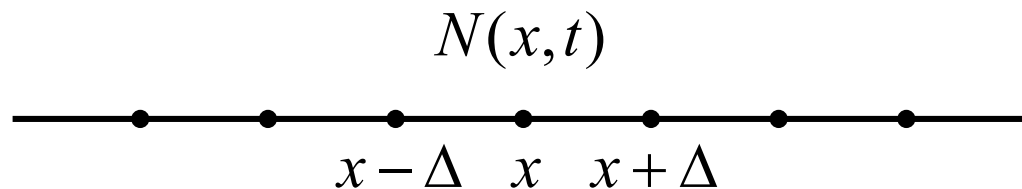
- How to solve the diffusion equation numerically
 - Random walk and diffusion equation
 - FTCS and Crank-Nicolson method
 - Diffusion equation in matrix notation
 - Product formula approach
- Exercise (Not for students who get < 10 ECTS for the course)

How to solve the diffusion equation numerically?

Random walk and diffusion

- We start by looking at a random walk of particles on a line
- Time proceeds in steps τ
- At each step, with probability $\frac{1}{2}$, a particle jumps to the left or to the right by a distance Δ
- The number of particles at position x changes according to

$$N(x, t + \tau) = \frac{1}{2} N(x + \Delta, t) + \frac{1}{2} N(x - \Delta, t)$$



Random walk and diffusion

- Subtract $N(x, t)$ from both sides, divide both sides by τ and rearrange a little to obtain

$$\frac{N(x, t + \tau) - N(x, t)}{\tau} = \frac{\Delta^2}{2\tau} \frac{N(x + \Delta, t) - 2N(x, t) + N(x - \Delta, t)}{\Delta^2}$$

- Next, we assume that the time step τ and the distance Δ are “small” and that $N(x, t)$ is sufficiently “smooth” such that its first and second derivatives exists
- Then, we may use

$$\frac{N(x, t + \tau) - N(x, t)}{\tau} \approx \frac{\partial}{\partial t} N(x, t)$$

$$\frac{N(x + \Delta, t) - 2N(x, t) + N(x - \Delta, t)}{\Delta^2} \approx \frac{\partial^2}{\partial x^2} N(x, t)$$

Random walk and diffusion

- We find the diffusion equation (in 1D)

$$\frac{\partial N(x,t)}{\partial t} = \frac{\Delta^2}{2\tau} \frac{\partial^2 N(x,t)}{\partial x^2} \equiv D \frac{\partial^2 N(x,t)}{\partial x^2}$$

- Note on the continuum limit $\tau, \Delta \rightarrow 0$
 - The identification $D \Leftrightarrow \Delta^2/2\tau$ only makes mathematical sense if

$$0 < \lim_{\tau \rightarrow 0} \lim_{\Delta \rightarrow 0} \frac{\Delta^2}{2\tau} = \lim_{\Delta \rightarrow 0} \lim_{\tau \rightarrow 0} \frac{\Delta^2}{2\tau} < \infty$$

- The discrete model is always well-defined

From continuum model to discrete model

- Diffusion equation

$$\frac{\partial N(x,t)}{\partial t} = D \frac{\partial^2 N(x,t)}{\partial x^2}$$

- We use


$$\frac{\partial}{\partial t} N(x,t) \rightarrow \frac{N(x,t+\tau) - N(x,t)}{\tau}$$

$$\frac{\partial^2}{\partial x^2} N(x,t) \rightarrow \frac{N(x+\Delta,t) - 2N(x,t) + N(x-\Delta,t)}{\Delta^2}$$

to bring the equations in a form that is suitable
for numerical simulation

Explicit forward in time central difference in space (FTCS) method

$$\frac{N(x, t + \tau) - N(x, t)}{\tau} = D \frac{N(x + \Delta, t) - 2N(x, t) + N(x - \Delta, t)}{\Delta^2}$$


$$N(x, t + \tau) = \left(1 - \frac{2\tau D}{\Delta^2}\right) N(x, t) + (N(x + \Delta, t) + N(x - \Delta, t))$$

- Stability criterion: $\tau \leq \Delta^2 / 2D$
 - a doubling of the spatial resolution requires a simultaneous reduction of the time step by a factor of four
- Numerical dispersion can approach exact dispersion for sufficiently fine gridding (see also lecture on the 1D Maxwell equation)

Crank-Nicolson method

$$\frac{N(x, t + \tau) - N(x, t)}{\tau} = D \frac{N(x + \Delta, t) - 2N(x, t) + N(x - \Delta, t)}{\Delta^2}$$



$$\frac{N(x, t + \tau) - N(x, t)}{\tau} = D \frac{N(x + \Delta, t + \tau / 2) - 2N(x, t + \tau / 2) + N(x - \Delta, t + \tau / 2)}{\Delta^2}$$



$$\frac{N(x, t + \tau) - N(x, t)}{\tau} = D \frac{N(x + \Delta, t + \tau) - 2N(x, t + \tau) + N(x - \Delta, t + \tau) + N(x + \Delta, t) - 2N(x, t) + N(x - \Delta, t)}{2\Delta^2}$$



$$-\frac{\tau D}{\Delta^2} N(x + \Delta, t + \tau) + 2\left(1 + \frac{\tau D}{\Delta^2}\right) N(x, t + \tau) - \frac{\tau D}{\Delta^2} N(x - \Delta, t + \tau) = \underbrace{\frac{\tau D}{\Delta^2} N(x + \Delta, t) + 2\left(1 - \frac{\tau D}{\Delta^2}\right) N(x, t) + \frac{\tau D}{\Delta^2} N(x - \Delta, t)}_{\text{known}}$$



Tridiagonal linear system: $AN = b$

Unconditionally stable implicit method

Diffusion equation in matrix notation

- Tremendous simplification of notation
- Example: $\frac{\partial^2}{\partial x^2} N(x,t) \rightarrow \frac{N(x+\Delta,t) - 2N(x,t) + N(x-\Delta,t)}{\Delta^2}$

$$\Delta^{-2} \underbrace{\begin{pmatrix} -2 & 1 & 0 & & 0 \\ 1 & -2 & 1 & & \\ 0 & 1 & -2 & & \\ & & \ddots & \ddots & \\ & & & -2 & 1 \\ 0 & & 0 & 1 & -2 \end{pmatrix}}_H \begin{pmatrix} N(1,t) \\ N(2,t) \\ N(3,t) \\ \vdots \\ \vdots \\ N(L,t) \end{pmatrix} \equiv \Delta^{-2} H \underbrace{\begin{pmatrix} N(1,t) \\ N(2,t) \\ N(3,t) \\ \vdots \\ \vdots \\ N(L,t) \end{pmatrix}}_{\Phi(t)} \equiv \Delta^{-2} H \Phi(t)$$

Diffusion equation in matrix notation

- We keep time as a continuous variable

$$\frac{\partial \Phi(t)}{\partial t} = \alpha H \Phi(t) \quad (*)$$

- The square matrix H is a (linear) “operator” that acts on a vector
- The length of the vector $\Phi(t)$ is L , the number of lattice points that we use to represent the space in which the diffusion occurs
- As we have seen before, equation (*) is the generic form for most, if not all, basic equations of physics. Formal solution: $\Phi(t + \tau) = e^{\tau \alpha H} \Phi(t)$



Product formula approach

- In matrix form

$$\frac{\partial}{\partial t} \begin{pmatrix} \Phi_1(t) \\ \Phi_2(t) \\ \Phi_3(t) \\ \vdots \\ \vdots \\ \Phi_L(t) \end{pmatrix} = -D\Delta^{-2} \underbrace{\begin{pmatrix} 2 & -1 & 0 & & 0 \\ -1 & 2 & -1 & & \\ 0 & -1 & 2 & & \\ & & & \ddots & 0 \\ & & & & 2 & -1 \\ 0 & & 0 & -1 & 2 \end{pmatrix}}_H \begin{pmatrix} \Phi_1(t) \\ \Phi_2(t) \\ \Phi_3(t) \\ \vdots \\ \vdots \\ \Phi_L(t) \end{pmatrix}$$

- We decompose the matrix $H = A + B$ where

K. Michielsen, H. De Raedt, J. Przeslawski, and N. García, "Computer Simulation of Time-Resolved Optical Imaging of Objects Hidden in Turbid Media" Phys. Rep. 304, 89 – 144 (1998)

Product formula approach

$$A = -D\Delta^{-2} \begin{pmatrix} 1 & -1 & 0 & & & 0 \\ -1 & 1 & 0 & 0 & 0 & \\ \hline 0 & 0 & \bullet & \bullet & 0 & \\ & 0 & \bullet & \bullet & 0 & 0 & 0 \\ \hline & & 0 & 0 & \bullet & \bullet & 0 \\ & & & 0 & \bullet & \bullet & 0 \\ \hline 0 & & & 0 & 0 & 0 & \ddots \end{pmatrix} \quad B = -D\Delta^{-2} \begin{pmatrix} 1 & 0 & 0 & 0 & & 0 \\ \hline 0 & 1 & -1 & 0 & & \\ 0 & -1 & 1 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & \bullet & \bullet & 0 \\ & & 0 & \bullet & \bullet & 0 & 0 \\ \hline & & & 0 & 0 & \ddots & \cdots \\ 0 & & & & 0 & \vdots & \ddots \end{pmatrix}$$

- Second order formula: $e^{\tau H} = e^{\tau A/2} e^{\tau B} e^{\tau A/2}$
- The matrix exponential of a block-diagonal matrix is easy to compute: we need to compute

$$\exp\left(-\tau D\Delta^{-2} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}\right) \equiv e^{aX}$$

Product formula approach

→ We have to calculate e^{aX} with

$$X = \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}; \quad a = -\tau D \Delta^{-2}$$

We use

$$e^{aX} = \sum_{k=0}^{\infty} \frac{a^k}{k!} X^k$$

Product formula approach

$$X^0 = \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}^0 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \equiv I$$

$$X^1 = \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}^1 = X$$

$$X^2 = \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}^2 = \begin{pmatrix} 2 & -2 \\ -2 & 2 \end{pmatrix} = 2X$$

$$X^3 = 2X^2 = 4X$$

$$X^4 = 4X^2 = 8X$$

$$X^5 = 8X^2 = 16X$$

...

Product formula approach

$$\rightarrow e^{aX} = I + aX + \frac{a^2}{2!} 2X + \frac{a^3}{3!} 4X + \frac{a^4}{4!} 8X + \dots$$

$$= I + aX + a^2 X + \frac{2}{3} a^3 X + \frac{1}{3} a^4 X + \dots$$

$$e^a = 1 + a + \frac{a^2}{2!} + \frac{a^3}{3!} + \frac{a^4}{4!} + \dots$$

$$e^{2a} = 1 + 2a + 2a^2 + \frac{4a^3}{3} + \frac{2a^4}{3} + \dots$$

$$\rightarrow 2e^{aX} = 2I + 2aX + 2a^2 X + \frac{4a^3}{3} X + \frac{2a^4}{3} X + \dots$$

$$= 2I + X(2a + 2a^2 + \frac{4}{3}a^3 + \frac{2}{3}a^4 + \dots) = 2I + X(e^{2a} - 1)$$

Product formula approach

$$\begin{aligned}\rightarrow e^{aX} &= I + \frac{X}{2}(e^{2a} - 1) \\ &= I + \frac{1}{2} \begin{pmatrix} e^{2a} - 1 & 1 - e^{2a} \\ 1 - e^{2a} & e^{2a} - 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 + e^{2a} & 1 - e^{2a} \\ 1 - e^{2a} & 1 + e^{2a} \end{pmatrix}\end{aligned}$$

- Special feature of this decomposition:
unconditionally stable (independent of a)
 $\|e^{\tau H}\| \leq 1$ where $\|X\|$ denotes the eigenvalue of
the matrix X of largest absolute value
(eigenvalues 1 and e^{2a})

Product formula approach

- Implementation of the algorithm: example

$$\begin{pmatrix} \Phi_1 \\ \Phi_2 \\ \Phi_3 \\ \vdots \\ \vdots \\ \vdots \\ \Phi_L \end{pmatrix} \leftarrow e^{\tau B} \Phi = \begin{pmatrix} e^{-\tau D \Delta^{-2}} & 0 & 0 & 0 & & 0 \\ \hline 0 & \otimes & \oplus & 0 & & \\ 0 & \oplus & \otimes & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & \otimes & \oplus & 0 \\ & & 0 & \oplus & \otimes & 0 & 0 \\ \hline & & & 0 & 0 & \ddots & \dots \\ 0 & & & 0 & \vdots & \ddots & \end{pmatrix} \begin{pmatrix} \Phi_1 \\ \Phi_2 \\ \Phi_3 \\ \vdots \\ \vdots \\ \vdots \\ \Phi_L \end{pmatrix}$$

- NEVER store the matrix!

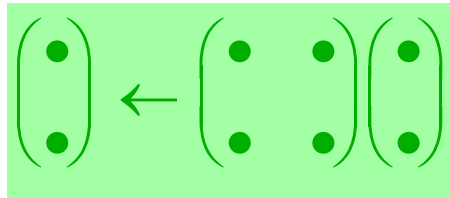
Product formula approach

$$\begin{pmatrix} \Phi_1 \\ \Phi_2 \\ \Phi_3 \\ \vdots \\ \vdots \\ \vdots \\ \Phi_L \end{pmatrix} \leftarrow e^{\tau B} \Phi = \begin{pmatrix} e^{-\tau D \Delta^{-2}} & 0 & 0 & 0 & & 0 \\ 0 & \otimes & \oplus & 0 & & \\ 0 & \oplus & \otimes & 0 & 0 & 0 \\ 0 & 0 & 0 & \otimes & \oplus & 0 \\ & & 0 & \oplus & \otimes & 0 & 0 \\ 0 & & & 0 & 0 & \ddots & \dots \\ & & & & 0 & \vdots & \ddots \end{pmatrix} \begin{pmatrix} \Phi_1 \\ \Phi_2 \\ \Phi_3 \\ \vdots \\ \vdots \\ \vdots \\ \Phi_L \end{pmatrix}$$

- We only need to pick a pair from Φ , multiply them by a 2x2 matrix (except for Φ_1), store the resulting pair in the same memory location as the original pair and repeat for all possible pairs
- The same for $e^{\tau A/2}$, except that the pairs are different
- VERY SIMPLE to program, NEVER fails, EASY to generalize to 2D and 3D and to more complicated diffusion equations

Product formula approach

- Flexible
 - works entirely on vectors defined in real space (no FFT's, ...)
 - no constraints on the shape of the sample
 - important for medical applications
- Efficient and accurate
 - CPU time scales linearly with the number of time steps and the total number of grid points
- Easy to program:


$$\begin{pmatrix} \bullet \\ \bullet \end{pmatrix} \leftarrow \begin{pmatrix} \bullet & \\ & \bullet \end{pmatrix} \begin{pmatrix} \bullet & \\ & \bullet \end{pmatrix} \begin{pmatrix} \bullet \\ \bullet \end{pmatrix}$$

Exercise 1

- Use the 2nd-order product formula algorithm $e^{tH} \approx (e^{tA/2m} e^{tB/m} e^{tA/2m})^m$ to solve the one-dimensional diffusion equation.

Perform simulations for the set of parameters:

- $D = 1$ (only fixes the “scale”)
- $L = 1001$
- $\Delta = 0.1$
- $\tau = 0.001$
- $m = 10000$

$$\langle x^p(t) \rangle = \frac{\int_0^{L\Delta} x^p N(x,t) dx}{\int_0^{L\Delta} N(x,t) dx} \approx \Delta^p \frac{\sum_{i=1}^L (i - i_0)^p \Phi_i(t)}{\sum_{i=1}^L \Phi_i(t)}$$

- For two different initial conditions:

$$\Phi_i(t=0) = \begin{cases} 1 & i = i_0 \equiv (L+1)/2 \\ 0 & i \neq i_0 \equiv (L+1)/2 \end{cases} \quad \text{and} \quad \Phi_i(t=0) = \begin{cases} 1 & i = 1 \\ 0 & i \neq 1 \end{cases}$$

- Plot $\Delta^{-2} (\langle x^2(t) \rangle - \langle x(t) \rangle^2)$ as a function of t
- Interpret the results!

Exercise 2: Diffusion comparison with random walk

– $N = 10000$ particles all start at the center $(L+1)/2$ of the system, making random walks as described earlier. $N_i(t)$ is the number of walkers at site i and discrete time t

– $L = 1001$

– $t = 0, 1, 2, \dots, 10$

$$\langle x^p(t) \rangle = \frac{\sum_{i=1}^L (i - i_0)^p N_i(t)}{\sum_{i=1}^L N_i(t)}$$

- Plot $\langle x^2(t) \rangle - \langle x(t) \rangle^2$ as a function of t
- Compare with results of diffusion equation

$$\Delta = 0.1, \quad \tau = 0.001 \quad \Rightarrow \quad D = \Delta^2 / 2\tau = 5$$

Not for students who get
< 10 ECTS for the course

Report

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- Filename: **Report_7_Surname1_Surname2.pdf**, where Surname1 < Surname2 (alphabetical order).
Example: Report_7_Jin_Willsch.pdf (Do not use “umlauts” or any other special characters in the names)
- Content of the report:
 - Names + matricule numbers + e-mail addresses + title
 - **Introduction:** describe briefly the problem you are modeling and simulating (write in complete sentences)
 - **Simulation model and method:** describe briefly the model and simulation method (write in complete sentences)
 - **Simulation results:** show figures (use grids, with figure captions !) depicting the simulation results. Give a brief description of the results (write in complete sentences)
 - **Discussion:** summarize your findings
 - **Appendix:** Include the listing of the program

Due date: 10 AM, June 26, 2023