

EC 415: Homework 4

Due by Friday 04/09/2021 6:00PM

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Exercise 4.21

Suppose that the noise in improvesnr.m is replaced with narrowband noise (as discussed in Section 4.1.3). Investigate the improvements in SNR

- a. when the narrowband interference occurs outside the 3000 to 4000 Hz passband,
- b. when the narrowband interference occurs inside the 3000 to 4000 Hz passband.

For part (a) use $n = 0.1 * (\cos(2 * \pi * f_1 * t) + \cos(2 * \pi * f_2 * t))$ to model narrowband noise around the frequencies f_1 and f_2 . Choose $f_1 = 2000$ Hz and $f_2 = 5000$ Hz.

For part (b) use $n = 0.1 * \cos(2 * \pi * f_3 * t)$ to model narrowband noise around the frequency f_3 . Choose $f_3 = 3500$ Hz.

Solution

- a. TODO
- b. TODO

Exercise 5.9

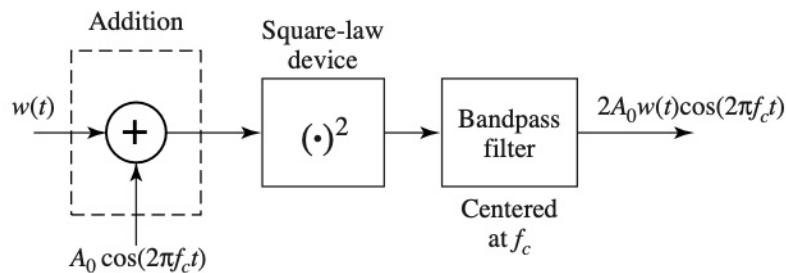


Figure 5.8 The square-law mixing transmitter of Exercises 5.9 through 5.11.

Figure 1: Figure 5.8

Consider the system shown in Figure 5.8. Show that the output of the system is $2A_0 w(t) \cos(2\pi f_c t)$, as indicated.

Solution

TODO

Exercise 5.12

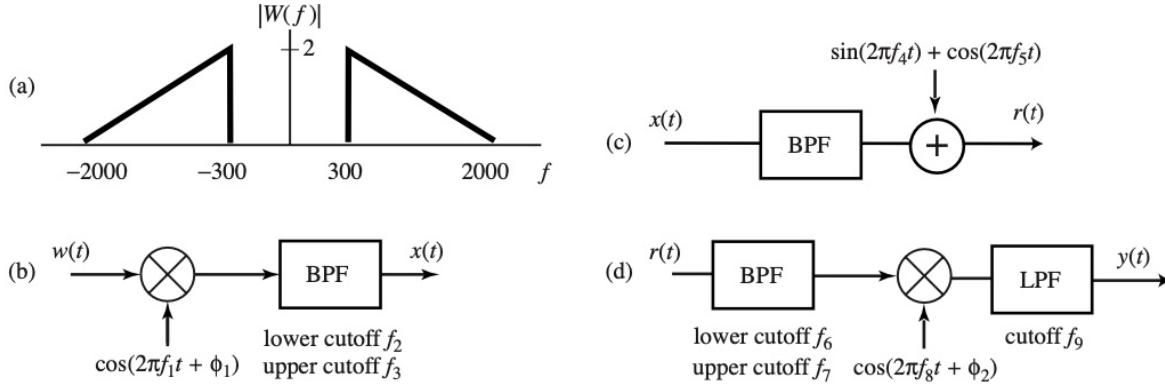


Figure 5.9 The transmission system for Exercise 5.12: (a) the magnitude spectrum of the message, (b) the transmitter, (c) the channel, and (d) the receiver.

Figure 2: Figure 5.9

Consider the transmission system of Figure 5.9. The message signal $w(t)$ has the magnitude spectrum shown in part (a). The transmitter in part (b) produces the transmitted signal $x(t)$, which passes through the channel in part (c). The channel scales the signal and adds narrowband interferers to create the received signal $r(t)$. The transmitter and channel parameters are $\phi_1 = 0.3$ radians, $f_1 = 24.1$ kHz, $f_2 = 23.9$ kHz, $f_3 = 27.5$ kHz, $f_4 = 29.3$ kHz, and $f_5 = 22.6$ kHz. The receiver processing $r(t)$ is shown in Figure 5.9(d). All bandpass and lowpass filters are considered ideal, with a gain of unity in the passband and zero in the stopband.

- Sketch $|R(f)|$ for $30 \text{ kHz} \leq f \leq 30 \text{ kHz}$. Clearly indicate the amplitudes and frequencies of key points in the sketch.
- Assume that ϕ_2 is chosen to maximize the magnitude of $y(t)$ and reflects the value of ϕ_1 and the delays imposed by the two ideal bandpass filters that form the received signal $r(t)$. Select the receiver parameters f_6 , f_7 , f_8 , and f_9 , so the receiver output $y(t)$ is a scaled version of $w(t)$.

Solution

TODO

Exercise 5.16

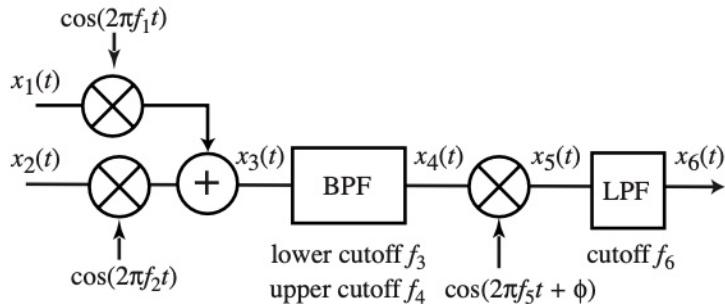


Figure 5.11 The transmission system of Exercise 5.16.

Figure 3: Figure 5.11

Consider the scheme shown in Figure 5.11. The absolute bandwidth of the baseband signal x_1 is 6 MHz and that of the baseband signal $x_2(t)$ is 4MHz, $f_1 = 164\text{MHz}$, $f_2 = 154\text{MHz}$, $f_3 = 148\text{MHz}$, $f_4 = 160\text{MHz}$, $f_5 = 80\text{MHz}$, $\phi = \pi/2$, and $f_6 = 82\text{MHz}$.

- a. What is the absolute bandwidth of $x_3(t)$?
- b. What is the absolute bandwidth of $x_5(t)$?
- c. What is the absolute bandwidth of $x_6(t)$?
- d. What is the maximum frequency in $x_3(t)$?
- e. What is the maximum frequency in $x_5(t)$?

Solution

- a. TODO
- b. TODO
- c. TODO
- d. TODO
- e. TODO

Question 5

Consider the last line of AMLarge.m (see Listing 5.1):

$envv = (\pi/2) * filter(b, 1, abs(v));$

Why is the output of the filter multiplied by the constant $\pi/2$? Justify your answer.

Solution

TODO

Question 6

The attached qam_hw.mat file is a QAM passband signal that is the sum of two modulated messages w_1 and w_2 . These messages were respectively modulated using cosine and sine functions, with carrier signal $f = 1000$ Hz. The sampling period is $T = 1/10000$ s and the total duration of the signal is 0.3s. Note that these parameters are all the same as in the file AM.m (listing 5.2 in the textbook). Plot the following:

1. The modulated signal v.
2. The demodulated signals (before the LPF) x_1 and x_2 .
3. The recovered signals (after the LPF) m_1 and m_2 .

Hints:

1. To load the QAM signal , use the command: `load('qam_hw.mat','v');`
2. Use the same LPF parameters as in AM.m.
3. The x-axis should be [0, 0.3] for all the plots.
4. For the signal v, the y-axis should be [11,11].
5. For the signal x_1 and m_1 , the y-axis should be [5,10].
6. For the signals x_2 and m_2 , the y-axis should be [10,1].

Solution

1. TODO
2. TODO
3. TODO