STATISTICAL METHODS FOR THE PHYSICAL SCIENCES

Week 3 tutorial: Using random numbers

Change of variables: the transformation relation: discrete variables

- Consider a random variable X, with a probability mass function $p_X(x)$. We want to know the pmf for a transformation of this, i.e. $p_Y(y)$ for a new variable Y = f(X).
- For discrete variables the transformation is simple, we simply map each value of *x* on to the corresponding *y*:

$$Pr(Y = y_i) = Pr(Y = f(x_i)) = Pr(X = x_i)$$

 E.g. summing the roll of 2 6-sided dice to get X and transforming to Y=1/X:

$$\Pr(X=2) = \frac{1}{36}, \Pr(X=3) = \frac{2}{36} \cdots \longleftrightarrow \Pr(Y=1/2) = \frac{1}{36}, \Pr(Y=1/3) = \frac{2}{36} \cdots$$

• More generally, we can allow for the possibility that Y maps on to multiple values of X, by defining the inverse function X = g(Y) and writing:

$$\Pr(Y = y) = \sum_{x \in g(Y)} \Pr(X = x)$$

Change of variables: the transformation relation: continuous variables

 Consider a continuous random variable X, with a probability density function $p_X(x)$. The simplest case is where Y = f(X) is an increasing or decreasing function – one-to-one correspondence of *X* to *Y*:

$$|p(x)\mathrm{d}x| = |p(y)\mathrm{d}y|$$

• However, we need to consider also cases where f(X) has a more complex shape. Defining again the inverse function X = g(Y), we can state that:

$$\Pr(a < Y < b) = \Pr(g(a) < X < g(b))$$

$$\rightarrow \int_{a}^{b} p_{Y}(y) dy = \left| \int_{g(a)}^{g(b)} p_{X}(x) dx \right| = \int_{a}^{b} p_{X}(x) \left| \frac{dx}{dy} \right| dy$$

- We have to use the absolute value to ensure the integral is positive when f(X) is a decreasing function. E.g., consider the simple case of Y=1/Xagain.
- Removing the integrals (which are now identical) we have:

emoving the integrals (which are now identical) we have: where:
$$p_Y(y) = p_X(x) \left| \frac{\mathrm{d}x}{\mathrm{d}y} \right| = p_X(x) \left| \frac{\mathrm{d}f(x)}{\mathrm{d}x} \right|^{-1} = \frac{p_X(g(y))}{|f'(g(y))|} \qquad f'(x) = \frac{\mathrm{d}y}{\mathrm{d}x}$$

Change of variables: example

- If the transformation is not one-to-one, e.g. more than one *X* maps to one *Y*, we need to sum over corresponding patches of the distribution
- Consider an example where X is distributed as a standard normal: $X \sim N(0,1)$, and we want the pdf of $Z = X^2$
- X is symmetric about zero, so first define: Y = |X|

$$\to p(y) = p(x) + p(-x) = 2N(0,1) = \frac{2}{\sqrt{2\pi}} \mathrm{e}^{-y^2/2} \qquad \text{(for $y > 0$)}$$

• And we sub in: $z=y^2$ and use $\frac{\mathrm{d}y}{\mathrm{d}z}=z^{-1/2}/2$ to get:

$$p(z) = p(y) \left| \frac{\mathrm{d}y}{\mathrm{d}z} \right| = \frac{2}{\sqrt{2\pi}} e^{-z/2} \left| \frac{z^{-1/2}}{2} \right| = \frac{z^{-1/2} e^{-z/2}}{\sqrt{2\pi}}$$

which is the χ_1^2 distribution (chi-squared for 1 d.o.f.), as we would expect!

Generating (pseudo-)random numbers

- Most higher-level programming languages have their own pseudorandom number generators.
- The numbers generated by these functions are almost always distributed as U(0,1)
- They are 'pseudo'-random because they are generated from algorithms (genuine random numbers can be obtained from random physical processes, e.g. radioactive decay).
- Typically they generate a sequence initiated by a **seed** number (which the user may specify). Each successive call of the generator function within the same run of code remembers the previous call, such that a sequence of (to all intents and purposes) random numbers is generated.
- Starting with the same seed will repeat the same sequence!
- Many functions will use, e.g. a system file or the system clock, to generate the seed. Be sure you know what your code is doing!

Reminder: pdf [p(x)] and cdf [F(x)]

$$\Pr(X \leq x) = F(x) = \int_{-\infty}^{x} p(x') dx'$$
 (where x' is a dummy variable)
$$p(x') = \int_{-\infty}^{x} p(x') dx'$$

Also we have:

$$\Pr(a \le X \le b) = F(b) - F(a) = \int_a^b p(x)dx$$

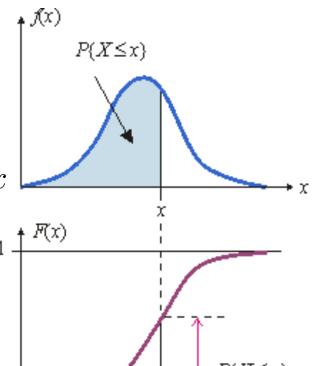
which means that:

$$\int_{-\infty}^{+\infty} p(x)dx = 1$$

• We can also define quantiles α :

$$F(x_{\alpha}) = \int_{-\infty}^{x_{\alpha}} p(x)dx = \alpha \iff x_{\alpha} = F^{-1}(\alpha)$$

But note that the quantiles α are distributed uniformly between 0 and 1!



From U(0,1) to a different distribution: the inverse transformation method

- Quantiles are distributed as U(0,1)
- Thus for a variable $p_X(x)$ the cdf, $u = F_X(x)$ is distributed as U(0,1)
- If it can be found, the inverse function $F_X^{-1}(u)$ can be used to transform from a U(0,1) random variable back to x.
- Hence random numbers can be generated that are drawn from any
 pdf, provided we know the cdf and can find the inverse function (if not
 solvable analytically it can be computed using numerical integration...)

Proof that it works:
$$\Pr(X \le x) = \Pr(F_X^{-1}(U) \le x)$$

$$= \Pr(F_X(F_X^{-1}(U)) \le F_X(x))$$

$$= \Pr(U \le F_X(x))$$

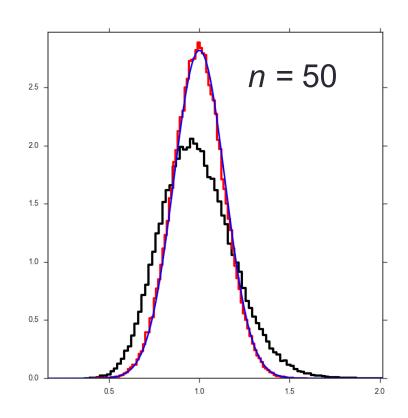
$$= \Pr(0 \le U \le F_X(x))$$

$$= F_X(x) - 0$$

$$= F_X(x)$$

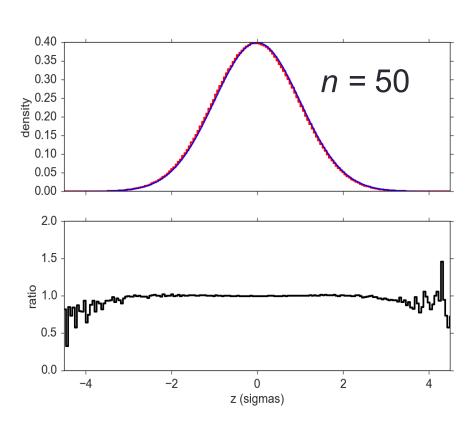
Example: testing the central limit theorem

- We can generate random numbers drawn from any distribution using, e.g. the Python scipy stats package
- Now try averaging sequences of n random numbers from a uniform distribution, or a chisquared (with 1 d.o.f.) distribution.
- Repeat 10⁵+ times and compare the distribution of averages with a normal distribution of the same variance and mean...
- Try for different n!



The limits of the central limit theorem

- As the name suggests, the theorem only holds strictly in the limit of very large n...
- The more skewed the averaged distribution, the higher n needed to approximate normal (the effect can be dramatic!)
- Even if the normal distribution is well-matched in the centre, it may be a poor match in the tails of the distribution
- So the significance of extreme values (estimated under the assumption that the sample is normally distributed) should be treated with caution, simulations may be needed for a rigorous test!



Upper: simulated pdf from averaging *n* uniformly distributed values (red) and normal pdf (blue)

Lower: ratio of the simulated to the normal pdf