



香港中文大學 (深圳)

The Chinese University of Hong Kong

# CSC3100 Data Structures

## Lecture 22: Graph shortest path

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# Outline

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- ▶ We focus on weighted graphs
- ▶ Graphs with non-negative weights
  - Single-Source Shortest Path: Dijkstra's algorithm
- ▶ All-Pair Shortest Path: Floyd's algorithm
- ▶ Graphs with negative weights
  - Bellman-Ford algorithm



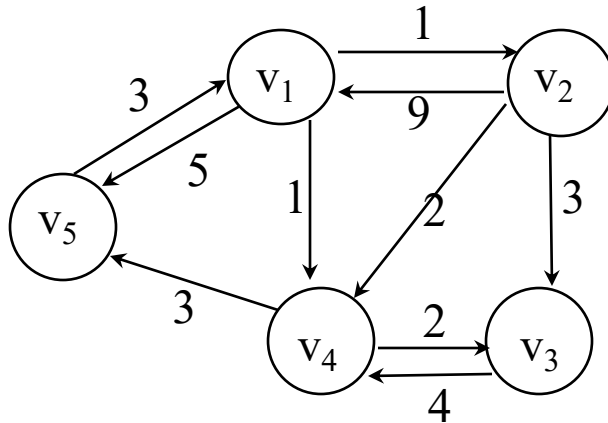
# All pairs shortest path

- **A representation:** a weight matrix where

$W(i, j) = 0$  if  $i = j$

$W(i, j) = \infty$  if there is no edge between  $i$  and  $j$

$W(i, j)$  = "weight of edge"



	1	2	3	4	5
1	0	1	$\infty$	1	5
2	9	0	3	2	$\infty$
3	$\infty$	$\infty$	0	4	$\infty$
4	$\infty$	$\infty$	2	0	3
5	3	$\infty$	$\infty$	$\infty$	0

- **Problem:** find the shortest distance/path between every pair of vertices of a graph



# A straightforward method

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- ▶ A naive method is to run a single-source shortest path algorithm for each vertex
  - Run Dijkstra's algorithm  $|V|$  times
  - Dijkstra's algorithm's time complexity:  $O(|E| \times \log|V|)$
  - Total time cost:  $O(|V| \times |E| \times \log|V|)$
- ▶ Floyd's algorithm
  - Total time cost:  $O(|V|^3)$
  - For dense graphs, Floyd's algorithm is faster
  - It is easier to implement



# Floyd's algorithm

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- ▶ We have shown principle of optimality applies to shortest path problems
- ▶ How can we define the shortest distance  $d_{i,j}$  in terms of "smaller" problems?
- ▶ Main idea of Floyd's algorithm
  - One way is to restrict the paths to only include vertices from a restricted subset
  - Initially, the subset is empty
  - Then, it is incrementally increased until it includes all the vertices



# The subproblems

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- ▶ Let  $D^{(k)}[i, j]$  = weight of a shortest path from  $v_i$  to  $v_j$  using only vertices from  $\{v_1, v_2, \dots, v_k\}$  as intermediate vertices in the path
  - $D^{(0)} = W$
  - $D^{(n)} = D$  which is the goal matrix
- ▶ How do we compute  $D^{(k)}$  from  $D^{(k-1)}$  ?

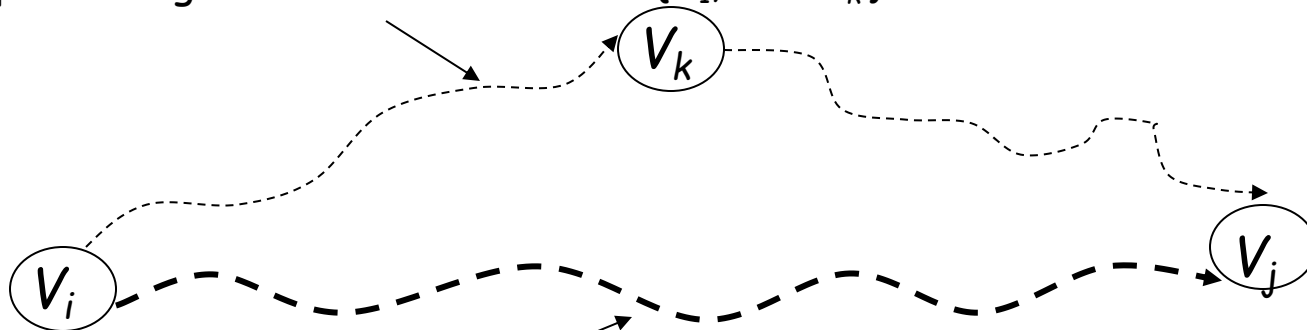


# The recursive definition:

Case 1: A shortest path from  $v_i$  to  $v_j$  restricted to using only vertices from  $\{v_1, v_2, \dots, v_k\}$  as intermediate vertices does not use  $v_k$  Then  $D^{(k)}[i, j] = D^{(k-1)}[i, j]$

Case 2: A shortest path from  $v_i$  to  $v_j$  restricted to using only vertices from  $\{v_1, v_2, \dots, v_k\}$  as intermediate vertices does use  $v_k$  Then  $D^{(k)}[i, j] = D^{(k-1)}[i, k] + D^{(k-1)}[k, j]$

Shortest path using intermediate vertices  $\{V_1, \dots, V_k\}$



Shortest path using intermediate vertices  $\{V_1, \dots, V_{k-1}\}$



# The recursive definition

► Since

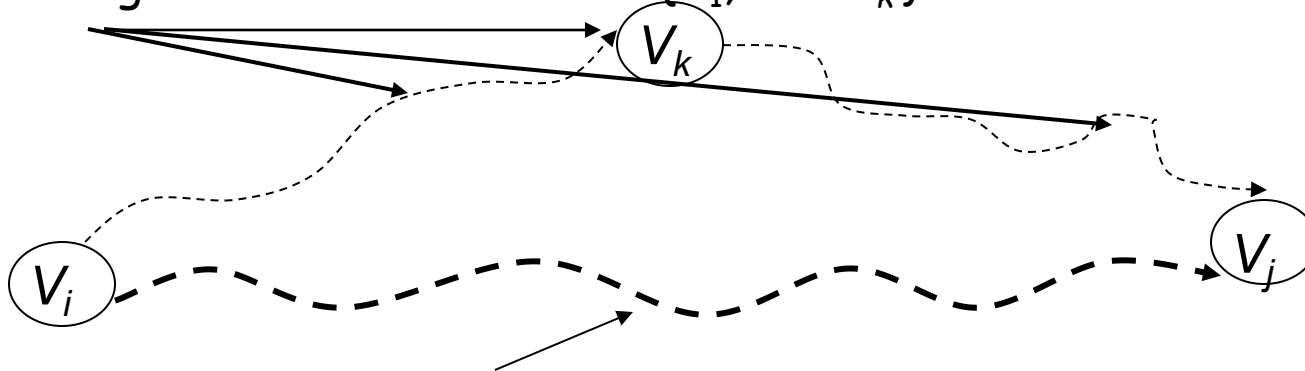
$$D^{(k)}[i, j] = D^{(k-1)}[i, j] \text{ or}$$

$$D^{(k)}[i, j] = D^{(k-1)}[i, k] + D^{(k-1)}[k, j]$$

We conclude:

$$D^{(k)}[i, j] = \min\{ D^{(k-1)}[i, j], D^{(k-1)}[i, k] + D^{(k-1)}[k, j] \}$$

Shortest path using intermediate vertices  $\{V_1, \dots, V_k\}$



Shortest Path using intermediate vertices  $\{V_1, \dots, V_{k-1}\}$





# The pointer array $P$

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- ▶ How to recover the shortest paths?
  - We can use a pointer array  $P$ , which initially contains 0
  - Each time that a shorter path from  $i$  to  $j$  is found, the  $k$  that provided the minimum distance is saved
  - We print the intermediate nodes on the shortest path by a recursive procedure, which print the shortest paths from  $i$  to  $k$ , and from  $k$  to  $j$



# Floyd's algorithm using $n+1$ $D$ matrices

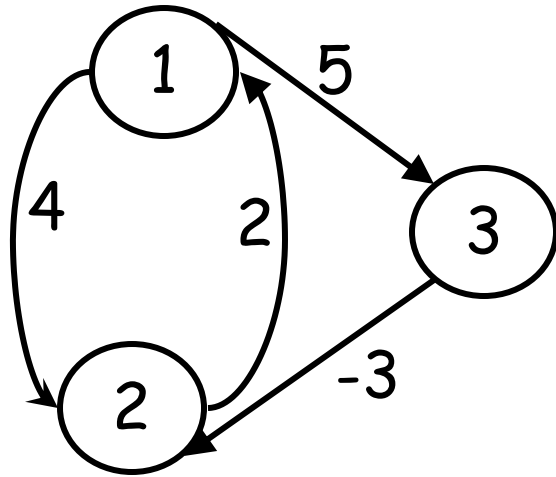
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Floyd//Computes shortest distance between all pairs of  
//nodes, and saves  $P$  to enable finding shortest paths

1.  $D^0 \leftarrow W$  // initialize  $D$  array to  $W[ ]$
2.  $P \leftarrow 0$  // initialize  $P$  array to  $[0]$
3. for  $k \leftarrow 1$  to  $n$
4.     do for  $i \leftarrow 1$  to  $n$
5.         do for  $j \leftarrow 1$  to  $n$
6.             if ( $D^{k-1}[i, j] > D^{k-1}[i, k] + D^{k-1}[k, j]$ )
7.                 then  $D^k[i, j] \leftarrow D^{k-1}[i, k] + D^{k-1}[k, j]$
8.                  $P[i, j] \leftarrow k;$
9.             else  $D^k[i, j] \leftarrow D^{k-1}[i, j]$



# Example



$$W = D^0 =$$

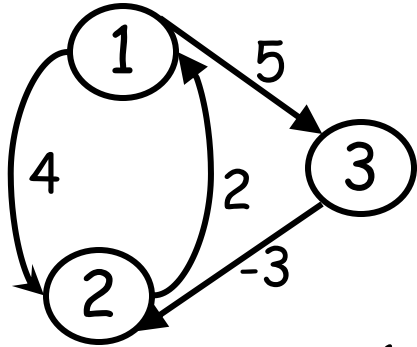
	1	2	3
1	0	4	5
2	2	0	$\infty$
3	$\infty$	-3	0

$$P =$$

	1	2	3
1	0	0	0
2	0	0	0
3	0	0	0



# Example


$$D^0 =$$

	1	2	3
1	0	4	5
2	2	0	$\infty$
3	$\infty$	-3	0

$k = 1$

Vertex 1 can be  
intermediate node

$$D^1 =$$

	1	2	3
1	0	4	5
2	2	0	7
3	$\infty$	-3	0

$$\begin{aligned} D^1[2,3] &= \min( D^0[2,3], D^0[2,1]+D^0[1,3] ) \\ &= \min( \infty, 7 ) \\ &= 7 \end{aligned}$$

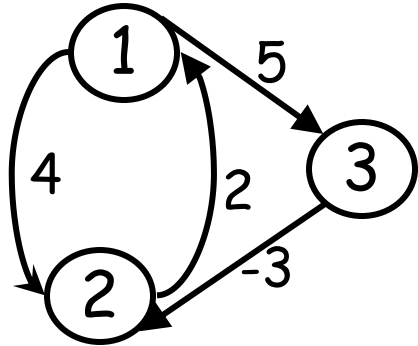
$$P =$$

	1	2	3
1	0	0	0
2	0	0	1
3	0	0	0

$$\begin{aligned} D^1[3,2] &= \min( D^0[3,2], D^0[3,1]+D^0[1,2] ) \\ &= \min( -3, \infty ) \\ &= -3 \end{aligned}$$



# Example



$$D^1 = 1$$

	1	2	3
1	0	4	5
2	2	0	7
3	$\infty$	-3	0

$k = 2$   
 Vertices 1, 2 can be  
 intermediate

$$D^2 =$$

	1	2	3
1	0	4	5
2	2	0	7
3	-1	-3	0

$$\begin{aligned} D^2[1,3] &= \min( D^1[1,3], D^1[1,2]+D^1[2,3] ) \\ &= \min( 5, 4+7 ) \\ &= 5 \end{aligned}$$

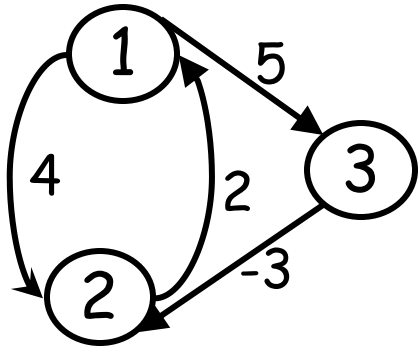
$$P =$$

	1	2	3
1	0	0	0
2	0	0	1
3	2	0	0

$$\begin{aligned} D^2[3,1] &= \min( D^1[3,1], D^1[3,2]+D^1[2,1] ) \\ &= \min( \infty, -3+2 ) \\ &= -1 \end{aligned}$$



# Example


$$D^2 =$$

	1	2	3
1	0	4	5
2	2	0	7
3	-1	-3	0

$$k = 3$$

Vertices 1, 2, 3 can  
be intermediate

$$D^3 =$$

	1	2	3
1	0	2	5
2	2	0	7
3	-1	-3	0

$$\begin{aligned} D^3[1,2] &= \min(D^2[1,2], D^2[1,3] + D^2[3,2]) \\ &= \min(4, 5 + (-3)) \\ &= 2 \end{aligned}$$

$$P =$$

	1	2	3
1	0	3	0
2	0	0	1
3	2	0	0

$$\begin{aligned} D^3[2,1] &= \min(D^2[2,1], D^2[2,3] + D^2[3,1]) \\ &= \min(2, 7 + (-1)) \\ &= 2 \end{aligned}$$



# Floyd's algorithm using 2 D matrices

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Floyd's algorithm

1.  $D \leftarrow W$  // initialize  $D$  array to  $W[ ]$
2.  $P \leftarrow 0$  // initialize  $P$  array to  $[0]$
3. for  $k \leftarrow 1$  to  $n$   
    *// Computing  $D'$  from  $D$*
4.     do for  $i \leftarrow 1$  to  $n$
5.         do for  $j \leftarrow 1$  to  $n$
6.             if  $(D[i, j] > D[i, k] + D[k, j])$
7.                 then  $D'[i, j] \leftarrow D[i, k] + D[k, j]$
8.                  $P[i, j] \leftarrow k;$
9.             else  $D'[i, j] \leftarrow D[i, j]$
10.     Move  $D'$  to  $D$



# Can we use only one D matrix?

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- ▶  $D[i, j]$  depends only on elements in the  $k$ -th column and row of the distance matrix
- ▶ We will show that the  $k$ -th row and the  $k$ -th column of the distance matrix are unchanged when  $D^k$  is computed
- ▶ This means  $D$  can be calculated in-place





# The main diagonal values

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- ▶ Before we show that k-th row and column of D remain unchanged we show that the main diagonal remains 0
- ▶ 
$$\begin{aligned} D^{(k)}[j, j] &= \min\{ D^{(k-1)}[j, j], D^{(k-1)}[j, k] + D^{(k-1)}[k, j] \} \\ &= \min\{ 0, D^{(k-1)}[j, k] + D^{(k-1)}[k, j] \} \\ &= 0 \end{aligned}$$



# The $k$ th column

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- ▶  $k$ -th column of  $D^k$  is equal to the  $k$ -th column of  $D^{k-1}$
- ▶ Intuitively true - a path from  $i$  to  $k$  will not become shorter by adding  $k$  to the allowed subset of intermediate vertices
- ▶ For all  $i$ ,  $D^{(k)}[i,k] =$ 
  - $= \min\{ D^{(k-1)}[i,k], D^{(k-1)}[i,k] + D^{(k-1)}[k,k] \}$
  - $= \min\{ D^{(k-1)}[i,k], D^{(k-1)}[i,k] + 0 \}$
  - $= D^{(k-1)}[i,k]$



# The $k$ th row

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- ▶  $k$ -th row of  $D^k$  is equal to the  $k$ -th row of  $D^{k-1}$

$$\begin{aligned}\text{For all } j, D^{(k)}[k, j] &= \\ &= \min\{ D^{(k-1)}[k, j], D^{(k-1)}[k, k] + D^{(k-1)}[k, j] \} \\ &= \min\{ D^{(k-1)}[k, j], 0 + D^{(k-1)}[k, j] \} \\ &= D^{(k-1)}[k, j]\end{aligned}$$



# Question

- ▶ Can we claim that  $D^k$  equals to  $D^{k-1}$ ,  $D^{k-2}$  ?
  - No, we can only claim
    - The 1-st row and 1-st column of  $D^1$  equal to the 1-st row and 1-st column of  $D^0$ , respectively
    - The 2-nd row and 2-nd column of  $D^2$  equal to the 2-nd row and 2-nd column of  $D^1$ , respectively
    - .....

	$D^0$ 1	2	3
1	0	4	5
2	2	0	$\infty$
3	$\infty$	-3	0

	$D^1$ 1	2	3
1	0	4	5
2	2	0	7
3	$\infty$	-3	0

	$D^2$ 1	2	3
1	0	4	5
2	2	0	7
3	-1	-3	0

	$D^3$ 1	2	3
1	0	2	5
2	2	0	7
3	-1	-3	0



# Floyd's algorithm using a single $D$

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Floyd

```
1.  $D \leftarrow W$  // initialize  $D$  array to  $W[ ]$ 
2.  $P \leftarrow 0$  // initialize  $P$  array to  $[0]$ 
3. for  $k \leftarrow 1$  to  $n$ 
4.     do for  $i \leftarrow 1$  to  $n$ 
5.         do for  $j \leftarrow 1$  to  $n$ 
6.             if ( $D[i, j] > D[i, k] + D[k, j]$ )
7.                 then  $D[i, j] \leftarrow D[i, k] + D[k, j]$ 
8.                  $P[i, j] \leftarrow k;$ 
```

}  $O(|V|^3)$

Total time cost:  $O(|V|^3)$



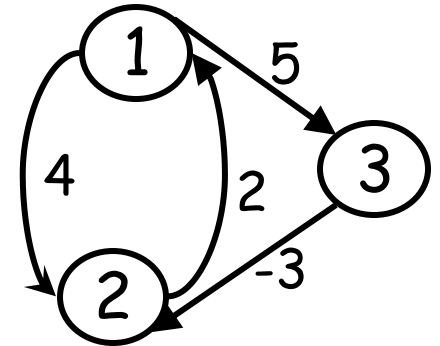
# Printing intermediate nodes on shortest path from $q$ to $r$

```
path(index  $q$ ,  $r$ )
  if ( $P[q, r] \neq 0$ )
    path( $q$ ,  $P[q, r]$ )
    println( "v" +  $P[q, r]$ )
    path( $P[q, r]$ ,  $r$ )
    return;
  //no intermediate nodes
  else return
```

Before calling path check  $D[q, r] < \infty$ ,  
and print node  $q$ , after the call to  
path print node  $r$

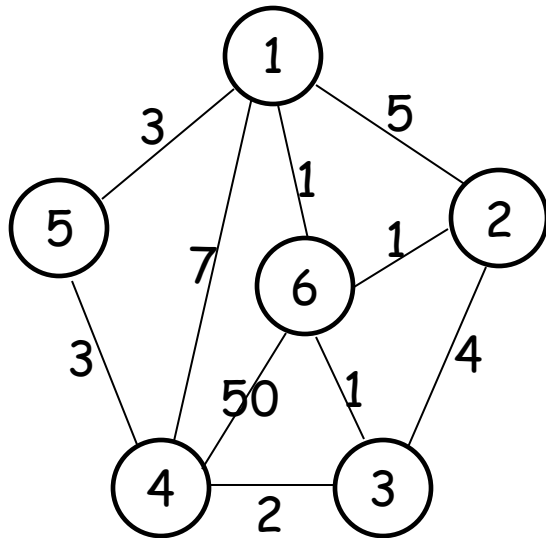
$P =$

	1	2	3
1	0	3	0
2	0	0	1
3	2	0	0





# Example



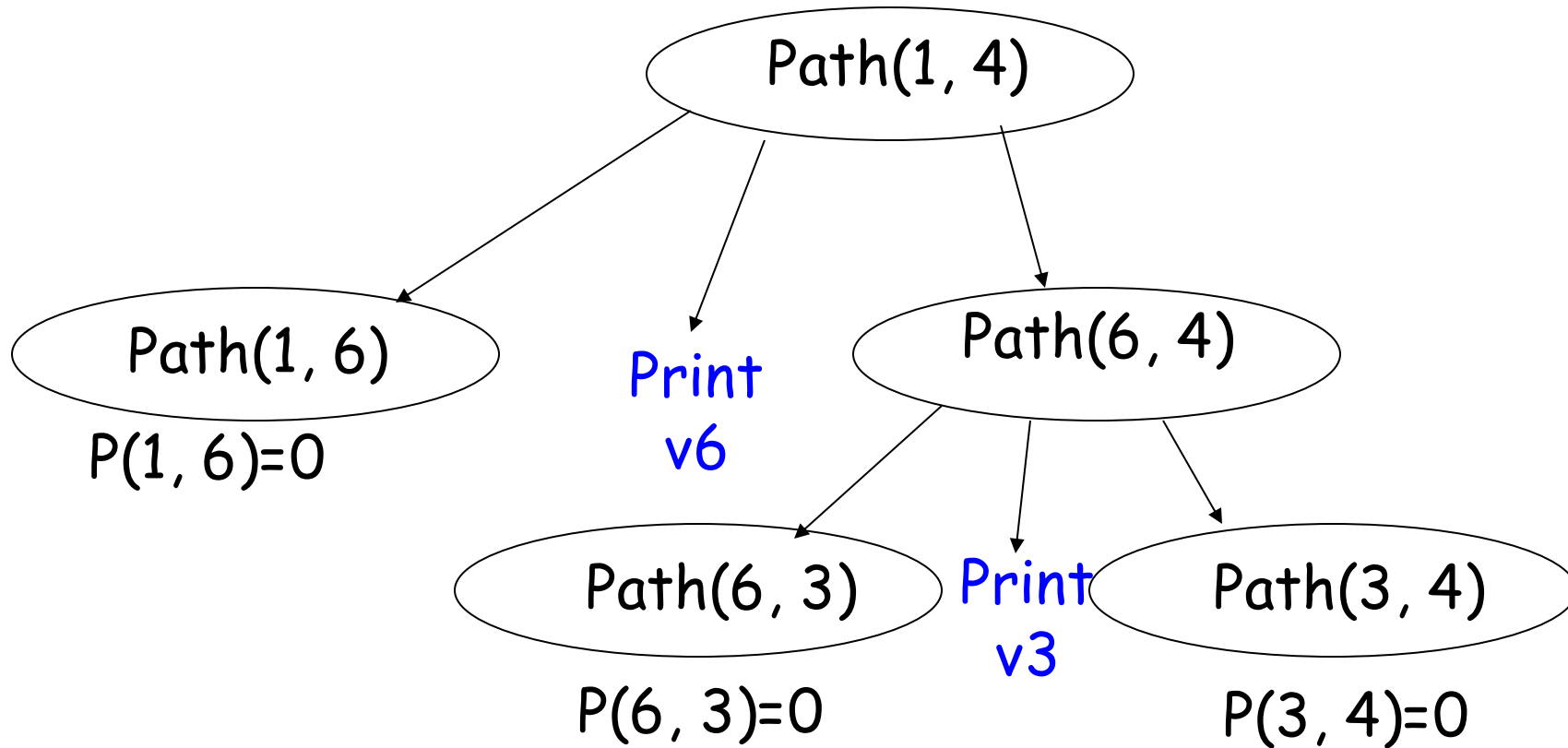
	1	2	3	4	5	6
1	0	2(6)	2(6)	4(6)	3	1
2	2(6)	0	2(6)	4(6)	5(6)	1
$D^6 = 3$	2(6)	2(6)	0	2	5(4)	1
4	4(6)	4(6)	2	0	3	3(3)
5	3	5(6)	5(4)	3	0	4(1)
6	1	1	1	3(3)	4(1)	0

The values in parenthesis are the non-zero P values

How to find the shortest path from vertex 1 to vertex 4?



# The call tree for Path(1, 4)



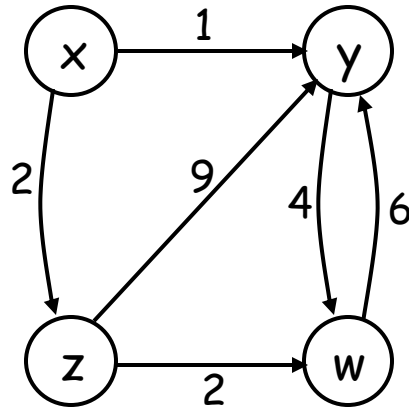
The intermediate nodes on the shortest path from  $v_1$  to  $v_4$  are  $v_6$ ,  $v_3$ , so the shortest path is  $v_1, v_6, v_3, v_4$ .





# Exercise

- ▶ Use the Floyd's algorithm to compute the all-pair shortest distances for the following graph



	x	y	z	w
x	0	1	2	4
y	$\infty$	0	$\infty$	4
z	$\infty$	8	0	2
w	$\infty$	6	$\infty$	0



# Recommended reading

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- ▶ Reading this week
  - Textbook Chapters 24-25
- ▶ Next lecture
  - Graph shortest distance