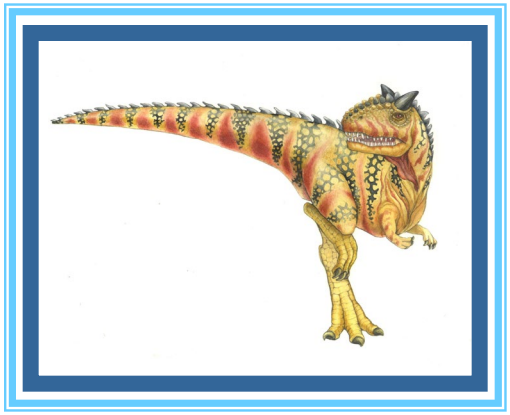
Chapter 4: Threads & Concurrency



Implicit Threading

- Growing in popularity as numbers of threads increase, program correctness more difficult with explicit threads
- Creation and management of threads done by compilers and run-time libraries rather than programmers
- Five methods explored
  - Thread Pools
  - Fork-Join
  - OpenMP
  - Grand Central Dispatch
  - Intel Threading Building Blocks

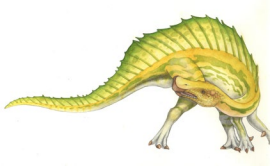
Thread Pools

- Create a number of threads in a pool where they await work
- Advantages:
  - Usually slightly faster to service a request with an existing thread than create a new thread
  - Allows the number of threads in the application(s) to be bound to the size of the pool
  - Separating task to be performed from mechanics of creating task allows different strategies for running task
    - i.e,Tasks could be scheduled to run periodically
- Windows API supports thread pools:

```
DWORD WINAPI PoolFunction(AVOID Param) {
    /*
    * this function runs as a separate thread.
    */
}
```

Java Thread Pools

- Three factory methods for creating thread pools in Executors class:
  - `static ExecutorService newSingleThreadExecutor()`
  - `static ExecutorService newFixedThreadPool(int size)`
  - `static ExecutorService newCachedThreadPool()`

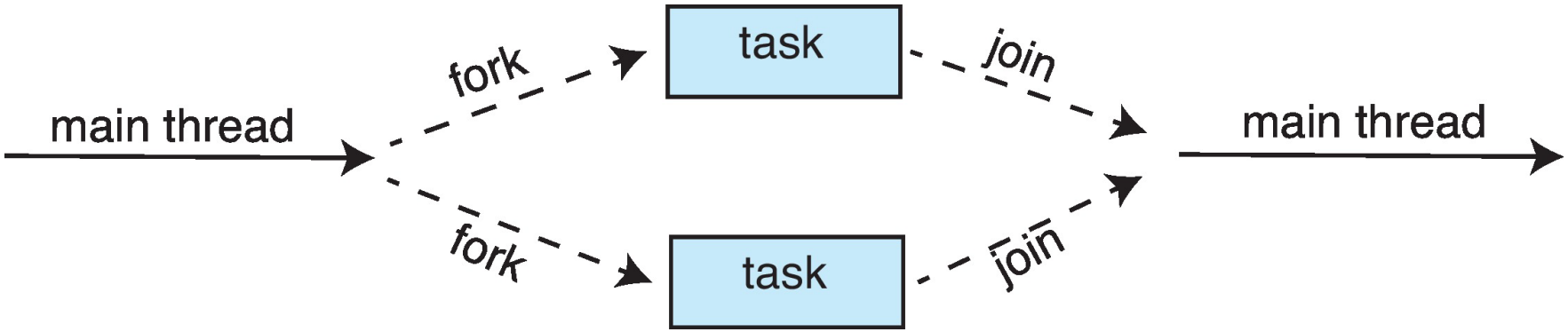


Java Thread Pools (Cont.)

```
import java.util.concurrent.*;

public class ThreadPoolExample
{
public static void main(String[] args) {
   int numTasks = Integer.parseInt(args[0].trim());

   /* Create the thread pool */
   ExecutorService pool = Executors.newCachedThreadPool();

   /* Run each task using a thread in the pool */
   for (int i = 0; i < numTasks; i++)
      pool.execute(new Task());

   /* Shut down the pool once all threads have completed */
   pool.shutdown();
}
```

Fork-Join Parallelism

- Multiple threads (tasks) are **forked**, and then **joined**.

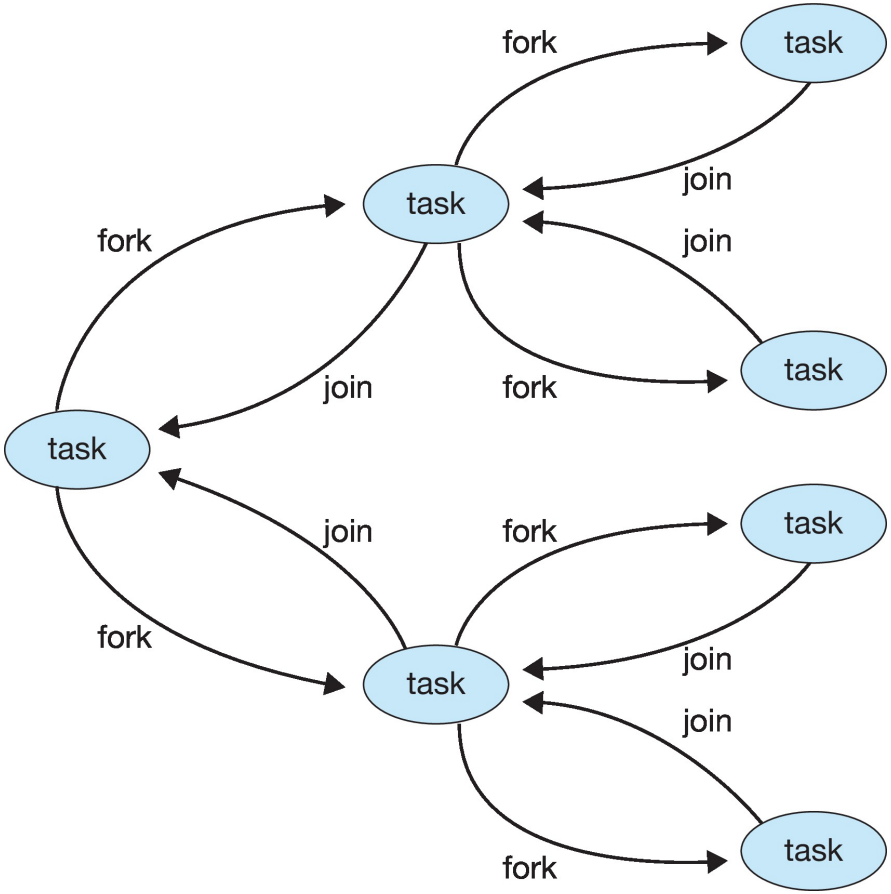


Fork-Join Parallelism

- General algorithm for fork-join strategy:

```
Task(problem)
   if problem is small enough
      solve the problem directly
   else
      subtask1 = fork(new Task(subset of problem)
      subtask2 = fork(new Task(subset of problem)

      result1 = join(subtask1)
      result2 = join(subtask2)

      return combined results
```

Fork-Join Parallelism

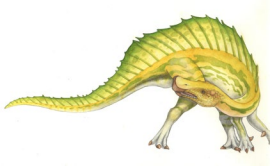


Fork-Join Parallelism in Java

```
ForkJoinPool pool = new ForkJoinPool();
// array contains the integers to be summed
int[] array = new int[SIZE];

SumTask task = new SumTask(0, SIZE - 1, array);
int sum = pool.invoke(task);
```

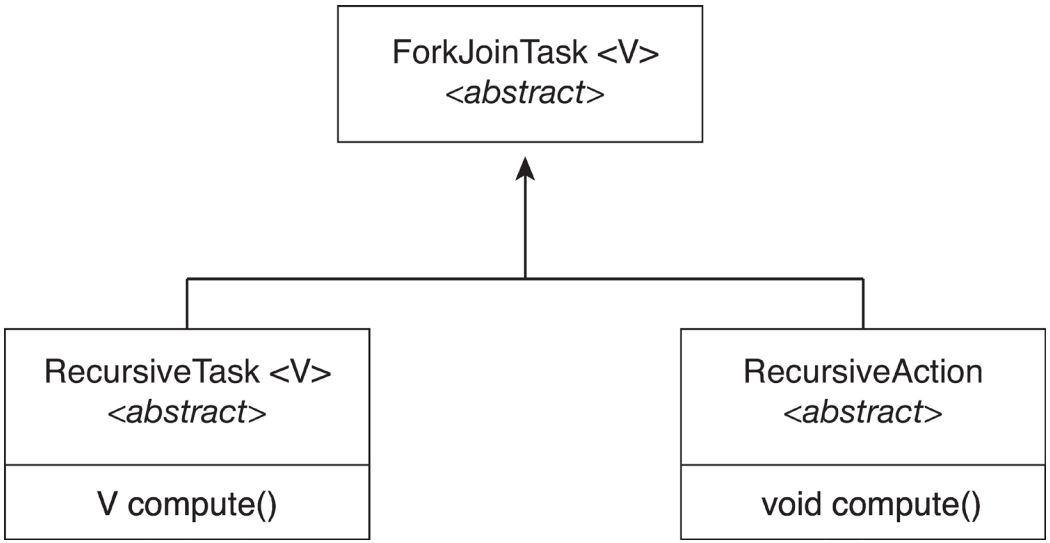
Fork-Join Parallelism in Java

```
import java.util.concurrent.*;

public class SumTask extends RecursiveTask<Integer>
{
   static final int THRESHOLD = 1000;

   private int begin;
   private int end;
   private int[] array;

   public SumTask(int begin, int end, int[] array) {
      this.begin = begin;
      this.end = end;
      this.array = array;
   }

   protected Integer compute() {
      if (end - begin < THRESHOLD) {
         int sum = 0;
         for (int i = begin; i <= end; i++)
            sum += array[i];

         return sum;
      }
      else {
         int mid = (begin + end) / 2;

         SumTask leftTask = new SumTask(begin, mid, array);
         SumTask rightTask = new SumTask(mid + 1, end, array);

         leftTask.fork();
         rightTask.fork();

         return rightTask.join() + leftTask.join();
      }
   }
}
```



Fork-Join Parallelism in Java

- The **`ForkJoinTask`** is an abstract base class
- **`RecursiveTask`** and **`RecursiveAction`** classes extend **`ForkJoinTask`**
- **`RecursiveTask`** returns a result (via the return value from the **`compute()`** method)
- **`RecursiveAction`** does not return a result



OpenMP

- Set of compiler directives and an API for C, C++, FORTRAN
- Provides support for parallel programming in shared-memory environments
- Identifies **parallel regions** – blocks of code that can run in parallel

`#pragma omp parallel`

Create as many threads as there are cores

```
#include <omp.h>
#include <stdio.h>

int main(int argc, char *argv[])
{
   /* sequential code */

   #pragma omp parallel
   {
      printf("I am a parallel region.");
   }

   /* sequential code */

   return 0;
}
```

- Run the for loop in parallel

```
#pragma omp parallel for
for (i = 0; i < N; i++) {
   c[i] = a[i] + b[i];
}
```

Grand Central Dispatch

- Apple technology for macOS and iOS operating systems
- Extensions to C, C++ and Objective-C languages, API, and run-time library
- Allows identification of parallel sections
- Manages most of the details of threading
- Block is in “^{ }” :

```
^{ printf("I am a block"); }
```

- Blocks placed in dispatch queue
  - Assigned to available thread in thread pool when removed from queue

Grand Central Dispatch

- Two types of dispatch queues:
  - **serial** – blocks removed in FIFO order, queue is per process, called **main queue**
    - Programmers can create additional serial queues within program
  - **concurrent** – removed in FIFO order but several may be removed at a time
    - Four system wide queues divided by quality of service:
      - `QOS_CLASS_USER_INTERACTIVE`
      - `QOS_CLASS_USER_INITIATED`
      - `QOS_CLASS_USER_UTILITY`
      - `QOS_CLASS_USER_BACKGROUND`

Grand Central Dispatch

- For the Swift language a task is defined as a closure – similar to a block, minus the caret
- Closures are submitted to the queue using the `dispatch_async()` function:

```
let queue = dispatch_get_global_queue
   (QOS_CLASS_USER_INITIATED, 0)

dispatch_async(queue,{ print("I am a closure.") })
```

Intel Threading Building Blocks (TBB)

- Template library for designing parallel C++ programs
- A serial version of a simple for loop

```
for (int i = 0; i < n; i++) {
   apply(v[i]);
}
```

- The same for loop written using TBB with **`parallel_for`** statement:

```
parallel_for (size_t(0), n, [=](size_t i) {apply(v[i]);});
```

Threading Issues

- Semantics of **fork()** and **exec()** system calls
- Signal handling
  - Synchronous and asynchronous
- Thread cancellation of target thread
  - Asynchronous or deferred
- Thread-local storage
- Scheduler Activations

Semantics of fork() and exec()

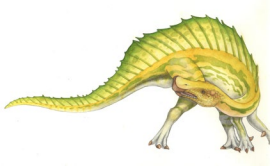
- Does `fork()` duplicate only the calling thread or all threads?
  - Some UNIXes have two versions of fork
- `exec()` usually works as normal – replace the running process including all threads

Signal Handling

- **Signals** are used in UNIX systems to notify a process that a particular event has occurred.
- A **signal handler** is used to process signals
  1. Signal is generated by particular event
  2. Signal is delivered to a process
  3. Signal is handled by one of two signal handlers:
     1. default
     2. user-defined
- Every signal has **default handler** that kernel runs when handling signal
  - **User-defined signal handler** can override default
  - For single-threaded, signal delivered to process

Signal Handling (Cont.)

- Where should a signal be delivered for multi-threaded?
  - Deliver the signal to the thread to which the signal applies
  - Deliver the signal to every thread in the process
  - Deliver the signal to certain threads in the process
  - Assign a specific thread to receive all signals for the process



Thread Cancellation

- Terminating a thread before it has finished
- Thread to be canceled is **target thread**
- Two general approaches:
  - **Asynchronous cancellation** terminates the target thread immediately
  - **Deferred cancellation** allows the target thread to periodically check if it should be cancelled
- Pthread code to create and cancel a thread:

```
pthread_t tid;

/* create the thread */
pthread_create(&tid, 0, worker, NULL);

  . . .

/* cancel the thread */
pthread_cancel(tid);

/* wait for the thread to terminate */
pthread_join(tid,NULL);
```

Thread Cancellation (Cont.)

- Invoking thread cancellation requests cancellation, but actual cancellation depends on thread state

Mode	State	Type
Off	Disabled	–
Deferred	Enabled	Deferred
Asynchronous	Enabled	Asynchronous

- If thread has cancellation disabled, cancellation remains pending until thread enables it
- Default type is deferred
  - Cancellation only occurs when thread reaches **cancellation point**
    - i.e., **`pthread_testcancel()`**
    - Then **cleanup handler** is invoked
- On Linux systems, thread cancellation is handled through signals

Thread Cancellation in Java

- Deferred cancellation uses the **`interrupt()`** method, which sets the interrupted status of a thread.

```
Thread worker;

  . . .

/* set the interruption status of the thread */
worker.interrupt()
```

- A thread can then check to see if it has been interrupted:

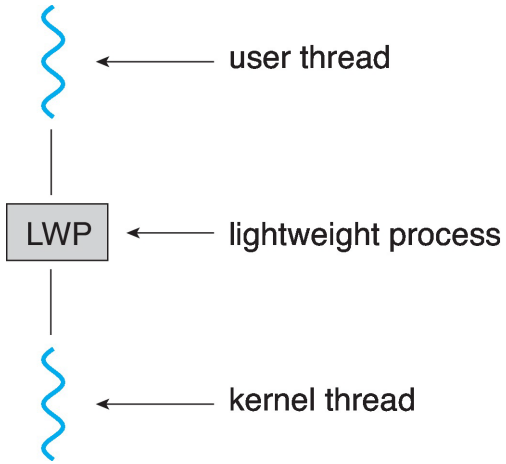
```
while (!Thread.currentThread().isInterrupted()) {
    . . .
}
```

Thread-Local Storage

- **Thread-local storage** (**TLS**) allows each thread to have its own copy of data
- Useful when you do not have control over the thread creation process (i.e., when using a thread pool)
- Different from local variables
  - Local variables visible only during single function invocation
  - TLS visible across function invocations
- Similar to `static` data
  - TLS is unique to each thread

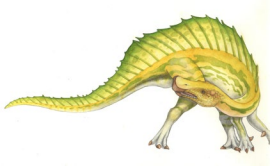
Scheduler Activations

- Both M:M and Two-level models require communication to maintain the appropriate number of kernel threads allocated to the application
- Typically use an intermediate data structure between user and kernel threads – **lightweight process** (**LWP**)
  - Appears to be a virtual processor on which process can schedule user thread to run
  - Each LWP attached to kernel thread
  - How many LWPs to create?
- Scheduler activations provide **upcalls** - a communication mechanism from the kernel to the **upcall handler** in the thread library
- This communication allows an application to maintain the correct number kernel threads



Operating System Examples

- Windows Threads
- Linux Threads



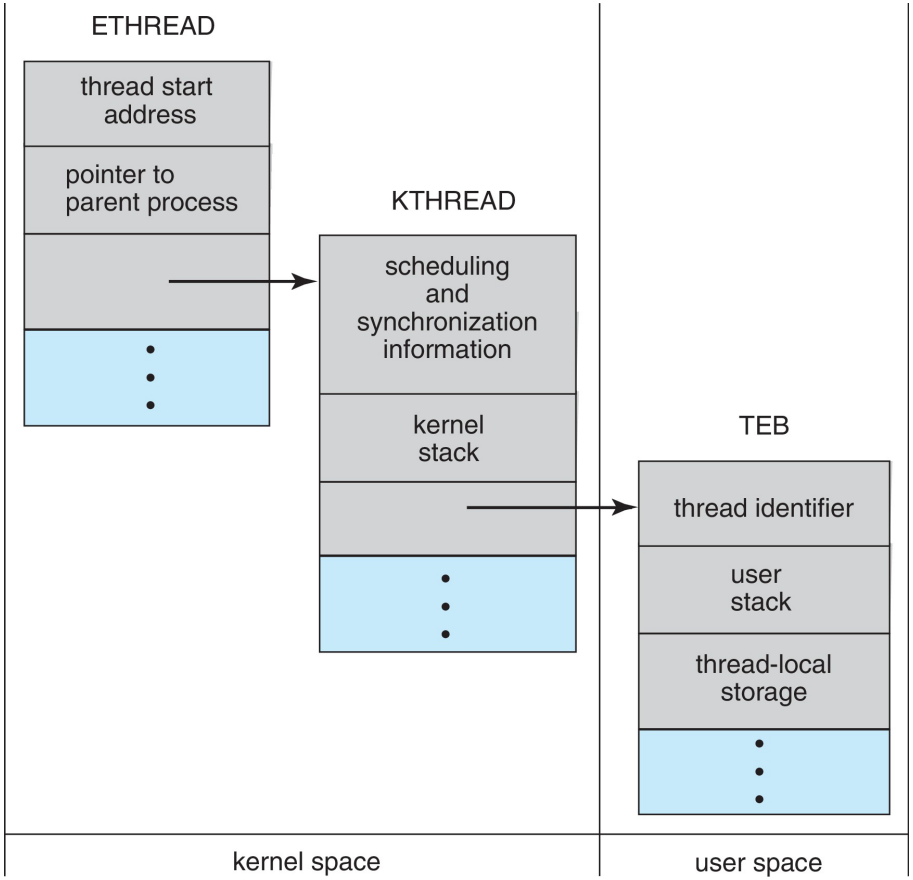
Windows Threads

- Windows API – primary API for Windows applications
- Implements the one-to-one mapping, kernel-level
- Each thread contains
  - A thread id
  - Register set representing state of processor
  - Separate user and kernel stacks for when thread runs in user mode or kernel mode
  - Private data storage area used by run-time libraries and dynamic link libraries (DLLs)
- The register set, stacks, and private storage area are known as the **context** of the thread

Windows Threads (Cont.)

- The primary data structures of a thread include:
  - ETHREAD (executive thread block) – includes pointer to process to which thread belongs and to KTHREAD, in kernel space
  - KTHREAD (kernel thread block) – scheduling and synchronization info, kernel-mode stack, pointer to TEB, in kernel space
  - TEB (thread environment block) – thread id, user-mode stack, thread-local storage, in user space

Windows Threads Data Structures



Linux Threads

- Linux refers to them as ***tasks*** rather than ***threads***
- Thread creation is done through **`clone()`** system call
- **`clone()`** allows a child task to share the address space of the parent task (process)
  - Flags control behavior

flag	meaning
CLONE_FS	File-system information is shared.
CLONE_VM	The same memory space is shared.
CLONE_SIGHAND	Signal handlers are shared.
CLONE_FILES	The set of open files is shared.

- **`struct task_struct`** points to process data structures (shared or unique)

End of Chapter 4