

# MAT1002 Lecture 25, Tuesday, Apr/23/2024

## Outline

- Surfaces in  $\mathbb{R}^3$  and areas (16.5)
  - ↳ Tangent planes
  - ↳ Surface areas
- Surface integrals (16.6)
  - ↳ Scalar functions: mass of a surface
  - ↳ Vector field: Flux

## Tangent Planes to Parametric Surfaces

Let  $S$  be a parametric surface given by

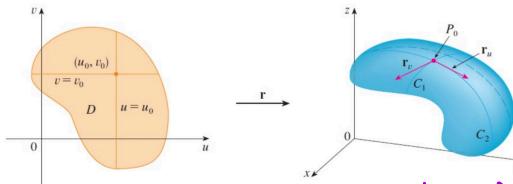
参数曲面

$$\mathbf{r}(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle, \text{ 的切平面}$$

More precisely,

where  $x, y$  and  $z$  have continuous partial derivatives. Let  $P_0 = \mathbf{r}(u_0, v_0)$  be a point in  $S$ . If we hold  $u$  constant by setting  $u = u_0$ , then  $\mathbf{r}(u_0, v)$  becomes a parametrization (with parameter  $v$ ) of a curve  $C_1$  lying on  $S$ , as shown below.

$$= \vec{r}(u_0, v)$$



切向量

$$\mathbf{t}_v \left\langle \frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, \frac{\partial z}{\partial v} \right\rangle$$

A tangent vector to  $C_1$  at  $P_0$  is given by

$$\mathbf{r}_v := \left\langle \frac{\partial x}{\partial v}(u_0, v_0), \frac{\partial y}{\partial v}(u_0, v_0), \frac{\partial z}{\partial v}(u_0, v_0) \right\rangle.$$

切向量

Similarly, by holding  $v$  constant,  $\mathbf{r}(u, v_0)$  gives a curve  $C_2$  lying on  $S$ , and its tangent vector at  $P_0$  is

$$\mathbf{r}_u := \left\langle \frac{\partial x}{\partial u}(u_0, v_0), \frac{\partial y}{\partial u}(u_0, v_0), \frac{\partial z}{\partial u}(u_0, v_0) \right\rangle.$$

$$\mathbf{t}_u \left\langle \frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u} \right\rangle$$

**Def:** • A parametrization  $\vec{r}(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle$  is said to be **smooth** if  $\vec{r}_u$  and  $\vec{r}_v$  are continuous and  $\vec{r}_u \times \vec{r}_v \neq \vec{0}$  for every point in the parameter domain.

cross product  
never 0

• A surface is said to be **smooth** if it can be parametrized with a smooth parametrization  $\vec{r}$ . The **tangent plane** to such a surface  $S$  at a point  $P \in S$  is the plane through  $P$  with normal vector

$$(\vec{r}_u \times \vec{r}_v)(P).$$



法向量

# 曲面面积

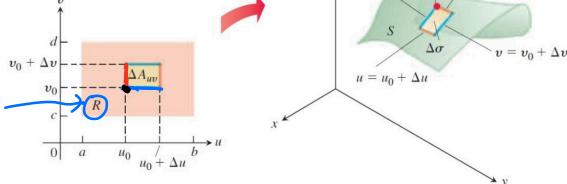
## Surface Areas: Parametric Forms

Let  $S$  be a smooth parametric surface. The surface area of  $S$  is equal to the sum of the areas of many small subregions, as shown below. The area  $\Delta\sigma$  of each subregion is approximately the area of a parallelogram, which is

Smooth on the interior of the parameter domain

$$|\Delta u \mathbf{r}_u \times \Delta v \mathbf{r}_v| = |\mathbf{r}_u \times \mathbf{r}_v| \Delta u \Delta v.$$

Parameter domain; may not be a rectangle in general



$$\begin{aligned} & \vec{r}(u_0, v_0 + \Delta v) - \vec{r}(u_0, v_0) \\ & \approx \vec{r}_v \Delta v \\ & \vec{r}(u_0 + \Delta u, v_0) - \vec{r}(u_0, v_0) \\ & \approx \frac{\partial \vec{r}}{\partial u}(u_0, v_0) \Delta u \\ & = \vec{r}_u \Delta u \end{aligned}$$

A "tiny" piece

By adding terms of the form  $|\mathbf{r}_u \times \mathbf{r}_v| \Delta u \Delta v$  and taking limit as  $\|P\| \rightarrow 0$ , we define the surface area of  $S$  to be  $\iint_S d\sigma$ , where

$$\text{Area of a "tiny" region of } S \quad \iint_S d\sigma := \iint_R |\mathbf{r}_u \times \mathbf{r}_v| du dv,$$

and  $R$  is the parameter domain.

$$\iint_R |\mathbf{r}_u \times \mathbf{r}_v| du dv$$

$$\text{即 } \iint_R |\mathbf{r}_u \times \mathbf{r}_v| du dv$$

e.g. Parametrize the following surface "American football", and find its area.

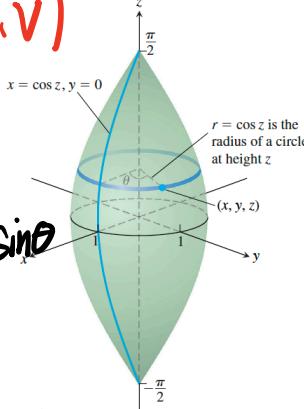
$$\begin{aligned} x &= \cos z \cos \theta & \mathbf{r}(u, v) \\ y &= \cos z \sin \theta \\ z &= z \end{aligned}$$

$$\mathbf{r}_z = -\sin z \cos \theta, -\sin z \sin \theta$$

$$\mathbf{r}_\theta = \cos z \sin \theta, \cos z \cos \theta$$

0

$$\begin{vmatrix} -\sin z \cos \theta & -\sin z \sin \theta & 1 \\ -\cos z \sin \theta & \cos z \cos \theta & 0 \end{vmatrix}$$



Ans:

$$2\pi [\sqrt{z} + \ln(1+\sqrt{z})].$$

$$\langle -\cos z \cos \theta, -\cos z \sin \theta, -\sin z \cos \theta \rangle$$

$$\begin{aligned} & \sqrt{\cos^2 z + 1 + \sin^2 z} \\ & = \sqrt{\cos^2 z + \sin^2 z} \end{aligned}$$

$$= \sqrt{\cos^2 z + \sin^2 z}$$

$$\int_0^{2\pi} d\theta \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \cos z \sqrt{1 + \sin^2 z} dz \quad \begin{aligned} \sin z &= w \\ dw &= \cos z dz \end{aligned}$$

Explicit form :  $z = f(x,y)$  積式  $2\pi \cdot \int_0^1 \sqrt{w^2 + 1} dw$   $w = \tan x$

For a surface  $S$  given by  $z = f(x,y)$  -  $(x,y) \in R$ , we can take

$$\int u dv = uv - \int v du \quad x = u, \quad y = v, \quad z = f(u,v), \quad (u,v) \in \tilde{R} \quad dw = \sec^2 x$$

One can show that surface area of  $S$  is

\*: One can easily check that

$$\int \sec^3 x dx \quad \begin{array}{c} \sqrt{w+1} \\ \diagdown \\ W \\ \diagup \\ 1 \end{array} \quad A = \iint_{\tilde{R}} \sqrt{f_u^2 + f_v^2 + 1} dudv, \quad \vec{r}_u \times \vec{r}_v = \langle -f_u, -f_v, 1 \rangle$$

$$u = \sec x \quad dv = \sec^2 x dx \quad = \iint_R \sqrt{f_x^2 + f_y^2 + 1} dx dy \quad x = u, \quad y = v \quad z = f(u,v)$$

where  $R$  is the domain of  $f$  (i.e., projection of  $S$  onto xy-plane).

$$du = \tan x \sec x dx \quad dv = \tan x \quad ds = \sqrt{z_x^2 + z_y^2 + 1} dx dy$$

$$= \sec x \tan x$$

$$- \int \sec x \tan^2 x dx$$

$$\boxed{\text{For } S: z = f(x,y), \quad ds = \sqrt{f_x^2 + f_y^2 + 1} dx dy.}$$

$$\int \sec^3 x dx = \sec x \tan x - \int \sec^3 x dx + \int \sec x dx \quad \Gamma_u = \langle 1, 0, f_u \rangle$$

e.g. Consider the surface  $S := \{(x,y,z) : z = x^2 + y^2, \quad x^2 + y^2 \leq 4\}$ .  $\Gamma_v = \langle 0, 1, f_v \rangle$

$\frac{1}{2} \sec x \tan x$  (a) Find the tangent plane to  $S$  at the point  $(1, 1, z)$ .  $\vec{F}_u \times \vec{F}_v = \langle -f_u, -f_v, 1 \rangle$

$+\frac{1}{2} \int \sec x dx$  (b) Find the surface area of  $S$ .

$$2 - x^2 - y^2 = 0$$



$$\text{Ans: (a)} \quad -2x - 2y + z = -2.$$

$$(b) \quad \frac{\pi}{6} (17\sqrt{17} - 1).$$

$$\frac{1}{2} \ln |\sec x + \tan x| \quad \Gamma_x = \langle 1, 0, 2x \rangle$$

$$\Gamma_y = \langle 0, 1, 2y \rangle$$

$$\frac{W}{2} \sqrt{1 + W^2} + \frac{1}{2} \ln (W + \sqrt{W^2 + 1})$$

$$fx = -2x \quad fy = -2y$$

$$fz = 1 \quad -2(x-1) + -2(y-1)$$

$$\frac{(4r^2 + 1)^{\frac{3}{2}}}{12} \Big|_0^2 + (z-2) = 0 \quad -2x - 2y + z = -2$$

$$2\pi \cdot \int_0^2 \sqrt{4r^2 + 1} r dr$$

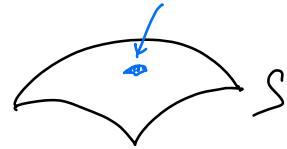
$$|F_x \times F_v| = \langle -2x, -2y, 1 \rangle \quad \int_0^{2\pi} \int_0^2 \sqrt{4r^2 + 1} r dr \quad \frac{\pi}{6} (17\sqrt{17} - 1)$$

# Surface Integrals 曲面積分 "mass"

Let  $S$  be a smooth surface. Suppose that the planar density of  $S$  at  $(x, y, z)$  is given by  $g(x, y, z)$ , say  $\text{kg}/\text{m}^2$ . Then the mass of  $S$  is given by the **surface integral** of  $g$ ,

$$\iint_S g(x, y, z) d\sigma,$$

$$\text{Mass} \approx g(x_{ij}^*, y_{ij}^*, z_{ij}^*) \Delta \sigma_{ij}$$



where  $\iint_S g(x, y, z) d\sigma$  is the limit of  $\sum_k g(x_k^*, y_k^*, z_k^*) \Delta \sigma_k$  as the areas of the small regions ( $\Delta \sigma_k$ ) goes to 0.

If  $S$  is in parametric form given by  $(x, y, z) = \mathbf{r}(u, v)$ , then

$$\iint_S g(x, y, z) d\sigma = \iint_R g(\mathbf{r}(u, v)) |\mathbf{r}_u \times \mathbf{r}_v| du dv,$$

where  $R$  is the parameter domain.

$$\iint_S g(x, y, z) d\sigma = \iint_R g(\mathbf{r}(u, v)) |\mathbf{r}_u \times \mathbf{r}_v| du dv$$

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If  $S$  is in explicit form  $z = f(x, y)$ , where  $f$  is defined on  $R$ , then

$$\iint_S g(x, y, z) d\sigma = \iint_R g(x, y, f(x, y)) \sqrt{f_x^2 + f_y^2 + 1} dx dy.$$

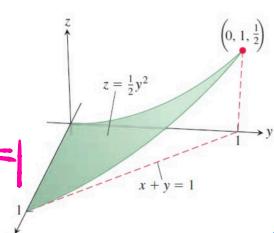
$$\begin{aligned} & \text{量} \\ & \iint_S g(x, y, z) d\sigma \\ & = \iint_R g(x, y, f(x, y)) \sqrt{f_x^2 + f_y^2 + 1} dx dy \end{aligned}$$

This is example 16.6.4.  $dx dy$

Sol:

$$\begin{aligned} I &= \iint_R \sqrt{x(1+y^2)} \sqrt{1+y^2} dx dy \\ &= \iint_R \sqrt{x(1+y^2)} dx dy \\ &= \int_0^1 \int_0^{1-x} \sqrt{x(1+y^2)} dy dx \\ &= \dots \text{ (see the book).} \end{aligned}$$

$$\begin{aligned} z &= f(x, y) = \frac{y^2}{2} \\ f_x &= 0 \quad f_y = y \quad f_z = 1 \\ d\sigma &= \sqrt{y^2+1} dx dy \quad y + \frac{y^3}{3} \Big|_0^1 \end{aligned}$$



$$\int_0^1 dx \int_0^{1-x} \sqrt{x(1+y^2)} dy$$

$$= \int_0^1 \int_0^{1-x} \sqrt{x}(1+y^2) dy dx$$

$$= \int_0^1 \sqrt{x} \left[ (1-x) + \frac{1}{3}(1-x)^3 \right] dx$$

Integrate and evaluate.

$$= \int_0^1 \left( \frac{4}{3}x^{1/2} - 2x^{3/2} + x^{5/2} - \frac{1}{3}x^{7/2} \right) dx$$

Routine algebra

$$= \left[ \frac{8}{9}x^{3/2} - \frac{4}{5}x^{5/2} + \frac{2}{7}x^{7/2} - \frac{2}{21}x^{9/2} \right]_0^1$$

$$= \frac{8}{9} - \frac{4}{5} + \frac{2}{7} - \frac{2}{27} = \frac{284}{945} \approx 0.30.$$

Suppose  $S = S_1 \cup S_2 \cup \dots \cup S_n$ , where

- each  $S_i$  is smooth, and
- $S_i \cap S_j$  is  $\emptyset$ , a point, or a curve.

Then  $\iint_S f(x,y,z) d\sigma = \sum_{i=1}^n \iint_{S_i} f(x,y,z) d\sigma$ .

e.g. (16.6.2) Let  $f(x,y,z) = xyz$  and

let  $S$  be the cube surface on the right.

Find  $I := \iint_S f(x,y,z) d\sigma$ .

Sol. There are six faces, corresponding to

$$x=0, x=1, y=0, y=1, z=0, z=1.$$

$S_1$

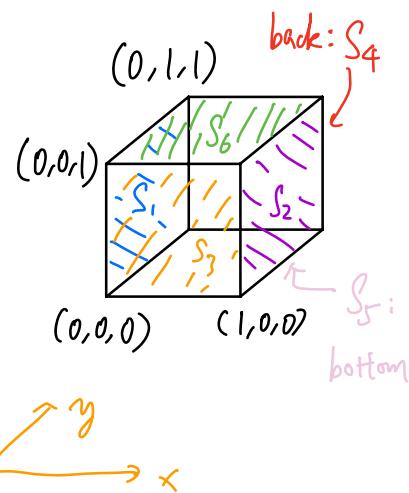
$S_2$

$S_3$

$S_4$

$S_5$

$S_6$



$\iint_S f(x,y,z) d\sigma = \iint_{S_3} f(x,y,z) d\sigma = \iint_{S_5} f(x,y,z) d\sigma = 0$  Since

$f(x,y,z) \equiv 0$  on these faces.

For  $S_6$ , by explicit form, we have  $f(x,y,z) = xyz$

$$\iint_{S_6} f(x,y,z) d\sigma = \int_0^1 \int_0^1 xy \sqrt{0^2+0^2+1} dx dy = \left( \int_0^1 x dx \right) \left( \int_0^1 y dy \right)$$

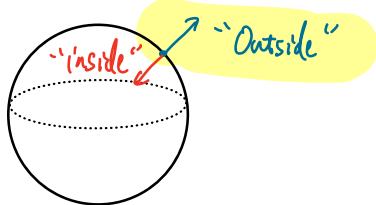
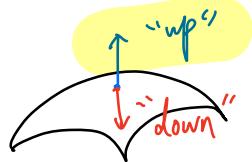
Separable  $= \frac{1}{2} \cdot \frac{1}{2} = \frac{1}{4}$   $f_x = 0, f_y = 0$ .

By symmetry,  $\iint_{S_2} = \iint_{S_4} = \frac{1}{4}$ . Hence  $I = 0 \cdot 3 + \frac{1}{4} \cdot 3 = \frac{3}{4}$ .

## Orientable Surfaces

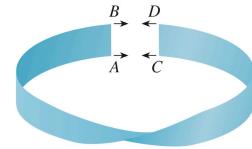
Roughly speaking, these are surfaces with two sides.

e.g.



Not all surfaces are orientable. e.g., the Möbius strip.

In this course, we will only talk about orientable surfaces.



## Flux : 3D

Suppose some flowing fluid in the 3D-Space has constant velocity  $\vec{v}$  (m/sec).

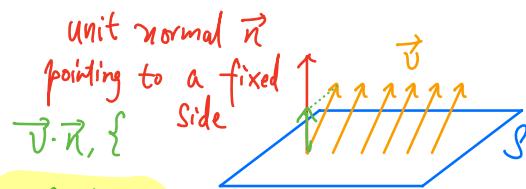
How much fluid (in terms of volume) flows through a surface  $S$  per unit time (with respect to some given direction, say "up")?

It is **unit normal**

$$(\vec{v} \cdot \vec{n}) \text{Area}(S)$$

$$\text{m/sec} \cdot \text{m}^2 = \text{m}^3/\text{sec}$$

$$(\vec{v} \cdot \vec{n}) \cdot \text{Area}$$



"effective" part of  $\vec{v}$  through flat surface  $S$

等效面積

This is the concept of 3D-flux. Adding all the microscopic flux using a Riemann sum motivates the following definition.

### Definition

Let  $\mathbf{F}$  be a continuous vector field in  $\mathbb{R}^3$ , defined on an orientable surface  $S$ , with a unit normal vector  $\mathbf{n}$  specifying the orientation of  $S$ . The surface integral of  $\mathbf{F}$  over  $S$ , or the flux of  $\mathbf{F}$  across  $S$ , is defined to be

$$\iint_S \mathbf{F} \cdot \mathbf{n} d\sigma. \quad d\sigma : \text{small surface area}$$

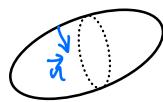
- $\vec{n} = \vec{n}(x, y, z)$

$$\iint_S \mathbf{F} \cdot \vec{n} d\sigma$$

$$\vec{n} = \pm \frac{\vec{r}_u \times \vec{r}_v}{|\vec{r}_u \times \vec{r}_v|}$$

- $\vec{n}$  specifies a side of the surface and the measuring direction of the flux.

e.g.



### Flux : Computation

If  $S$  is a surface with parametrization  $\mathbf{r}(u, v)$ , then the unit normal vectors to  $S$  at a point are

$$\mathbf{n} = \pm \frac{\mathbf{r}_u \times \mathbf{r}_v}{|\mathbf{r}_u \times \mathbf{r}_v|}.$$

Here, the sign is determined by the context or question, which you need to check.

Suppose that the flux direction is given by the one with “+”. Then

$$\begin{aligned} \iint_S \mathbf{F} \cdot \mathbf{n} d\sigma &= \iint_R \mathbf{F} \cdot \frac{\mathbf{r}_u \times \mathbf{r}_v}{|\mathbf{r}_u \times \mathbf{r}_v|} |\mathbf{r}_u \times \mathbf{r}_v| du dv \\ &= \iint_R \mathbf{F} \cdot (\mathbf{r}_u \times \mathbf{r}_v) du dv. \end{aligned}$$

$\frac{\mathbf{r}_u \times \mathbf{r}_v}{|\mathbf{r}_u \times \mathbf{r}_v|} du dv$

$$\text{Flux} = \iint \pm \mathbf{F}(x(u, v), y(u, v), z(u, v)) \frac{\vec{r}_u \times \vec{r}_v}{|\vec{r}_u \times \vec{r}_v|} du dv$$

$$\iint_R \mathbf{F} \cdot (\mathbf{r}_u \times \mathbf{r}_v) du dv$$

Example

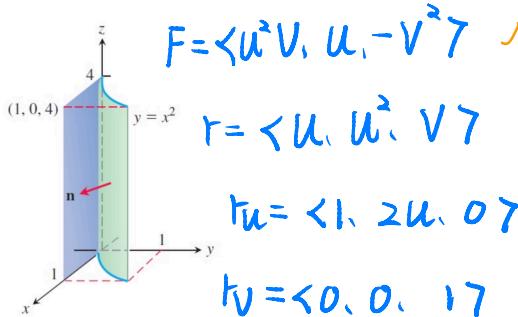
$$x=u \quad z=v \quad y=u^2$$

Find the flux of  $\mathbf{F} := \langle yz, x, -z^2 \rangle$  across the surface

$$S := \{(x, y, z) : y = x^2, 0 \leq x \leq 1, 0 \leq z \leq 4\},$$

in the direction of  $\mathbf{n}$  indicated in the figure.

Example 16.6.5,



$$\int_0^1 du \int_0^4 2u^3 v - u \, dv = \int_0^1 16u^3 - 4u = 4 - 2 = 2$$

e.g. Find the inward flux of  $\vec{F} = \langle z, y, x \rangle$  across the sphere  $x^2 + y^2 + z^2 = 1$ .

Ans:  $-4\pi/3$ .

$$x = \sin\varphi \cos\theta = \langle \sin\varphi \cos\theta, \sin\varphi \sin\theta, \cos\varphi \rangle$$

$$y = \sin\varphi \sin\theta \quad |\vec{r}_\varphi \times \vec{r}_\theta| = \sin\varphi$$

$$z = \cos\varphi$$

$$\vec{r}_\varphi = \langle \cos\varphi \cos\theta, \cos\varphi \sin\theta, -\sin\varphi \rangle$$

$$\mathbf{n} = \langle \sin\varphi \cos\theta, \sin\varphi \sin\theta, \cos\varphi \rangle$$

=  $\langle x, y, z \rangle$  outward

$$\mathbf{r}_\theta = \langle -\sin\theta \sin\varphi, \sin\theta \cos\varphi, 0 \rangle$$

$$\int_0^{2\pi} d\theta \int_0^\pi \langle \cos\varphi, \sin\varphi \sin\theta, \sin\varphi \cos\theta \rangle \cdot (\vec{r}_\varphi \times \vec{r}_\theta) \, d\varphi$$

Remark The computation above is relatively messy by direct parametrizations, but will become one-line after discussing Chap 16.8.

Inward  $-\frac{4}{3}\pi$

Therefore, the surface area differential is given by

$$d\sigma = |\mathbf{r}_u \times \mathbf{r}_v| du dv = \frac{|\nabla F|}{|\nabla F \cdot \mathbf{p}|} dx dy. \quad u = x \text{ and } v = y$$

We obtain similar calculations if instead the vector  $\mathbf{p} = \mathbf{j}$  is normal to the  $xz$ -plane when  $F_y \neq 0$  on  $S$ , or if  $\mathbf{p} = \mathbf{i}$  is normal to the  $yz$ -plane when  $F_x \neq 0$  on  $S$ . Combining these results with Equation (4) then gives the following general formula.

### Formula for the Surface Area of an Implicit Surface

The area of the surface  $F(x, y, z) = c$  over a closed and bounded plane region  $R$  is

$$\text{Surface area} = \iint_R \frac{|\nabla F|}{|\nabla F \cdot \mathbf{p}|} dA, \quad (7)$$

where  $\mathbf{p} = \mathbf{i}, \mathbf{j}$ , or  $\mathbf{k}$  is normal to  $R$  and  $\nabla F \cdot \mathbf{p} \neq 0$ .

Thus, the area is the double integral over  $R$  of the magnitude of  $\nabla F$  divided by the magnitude of the scalar component of  $\nabla F$  normal to  $R$ .

We reached Equation (7) under the assumption that  $\nabla F \cdot \mathbf{p} \neq 0$  throughout  $R$  and that  $\nabla F$  is continuous. Whenever the integral exists, however, we define its value to be the area of the portion of the surface  $F(x, y, z) = c$  that lies over  $R$ . (Recall that the projection is assumed to be one-to-one.)

**EXAMPLE 8** Derive the surface area differential  $d\sigma$  of the surface  $z = f(x, y)$  over a region  $R$  in the  $xy$ -plane (a) parametrically using Equation (5), and (b) implicitly, as in Equation (7).

#### Solution

(a) We parametrize the surface by taking  $x = u$ ,  $y = v$ , and  $z = f(x, y)$  over  $R$ . This gives the parametrization

$$\mathbf{r}(u, v) = u\mathbf{i} + v\mathbf{j} + f(u, v)\mathbf{k}.$$

Computing the partial derivatives gives  $\mathbf{r}_u = \mathbf{i} + f_u \mathbf{k}$ ,  $\mathbf{r}_v = \mathbf{j} + f_v \mathbf{k}$  and

$$\mathbf{r}_u \times \mathbf{r}_v = -f_u \mathbf{i} - f_v \mathbf{j} + \mathbf{k}. \quad \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 0 & f_u \\ 0 & 1 & f_v \end{vmatrix}$$

Then  $|\mathbf{r}_u \times \mathbf{r}_v| du dv = \sqrt{f_u^2 + f_v^2 + 1} du dv$ . Substituting for  $u$  and  $v$  then gives the surface area differential

$$d\sigma = \sqrt{f_x^2 + f_y^2 + 1} dx dy.$$

(b) We define the implicit function  $F(x, y, z) = f(x, y) - z$ . Since  $(x, y)$  belongs to the region  $R$ , the unit normal to the plane of  $R$  is  $\mathbf{p} = \mathbf{k}$ . Then  $\nabla F = f_x \mathbf{i} + f_y \mathbf{j} - \mathbf{k}$  so that  $|\nabla F \cdot \mathbf{p}| = |-1| = 1$ ,  $|\nabla F| = \sqrt{f_x^2 + f_y^2 + 1}$ , and  $|\nabla F| / |\nabla F \cdot \mathbf{p}| = |\nabla F|$ . The surface area differential is again given by

$$d\sigma = \sqrt{f_x^2 + f_y^2 + 1} dx dy. \quad \blacksquare$$

The surface area differential derived in Example 8 gives the following formula for calculating the surface area of the graph of a function defined explicitly as  $z = f(x, y)$ .

### Formula for the Surface Area of a Graph $z = f(x, y)$

For a graph  $z = f(x, y)$  over a region  $R$  in the  $xy$ -plane, the surface area formula is

$$A = \iint_R \sqrt{f_x^2 + f_y^2 + 1} dx dy. \quad (8)$$

## Formulas for a Surface Integral of a Scalar Function

1. For a smooth surface  $S$  defined **parametrically** as  $\mathbf{r}(u, v) = f(u, v)\mathbf{i} + g(u, v)\mathbf{j} + h(u, v)\mathbf{k}$ ,  $(u, v) \in R$ , and a continuous function  $G(x, y, z)$  defined on  $S$ , the surface integral of  $G$  over  $S$  is given by the double integral over  $R$ ,

$$\iint_S G(x, y, z) d\sigma = \iint_R G(f(u, v), g(u, v), h(u, v)) |\mathbf{r}_u \times \mathbf{r}_v| du dv. \quad (2)$$

2. For a surface  $S$  given **implicitly** by  $F(x, y, z) = c$ , where  $F$  is a continuously differentiable function, with  $S$  lying above its closed and bounded shadow region  $R$  in the coordinate plane beneath it, the surface integral of the continuous function  $G$  over  $S$  is given by the double integral over  $R$ ,

$$\iint_S G(x, y, z) d\sigma = \iint_R G(x, y, z) \frac{|\nabla F|}{|\nabla F \cdot \mathbf{p}|} dA, \quad (3)$$

where  $\mathbf{p}$  is a unit vector normal to  $R$  and  $\nabla F \cdot \mathbf{p} \neq 0$ .

3. For a surface  $S$  given **explicitly** as the graph of  $z = f(x, y)$ , where  $f$  is a continuously differentiable function over a region  $R$  in the  $xy$ -plane, the surface integral of the continuous function  $G$  over  $S$  is given by the double integral over  $R$ ,

$$\iint_S G(x, y, z) d\sigma = \iint_R G(x, y, f(x, y)) \sqrt{f_x^2 + f_y^2 + 1} dx dy. \quad (4)$$

## Surface Integrals of Vector Fields

In Section 16.2 we defined the line integral of a vector field along a path  $C$  as  $\int_C \mathbf{F} \cdot \mathbf{T} ds$ , where  $\mathbf{T}$  is the unit tangent vector to the path pointing in the forward oriented direction. By analogy we now have the following corresponding definition for surface integrals.

Fields

**DEFINITION** Let  $\mathbf{F}$  be a vector field in three-dimensional space with continuous components defined over a smooth surface  $S$  having a chosen field of normal unit vectors  $\mathbf{n}$  orienting  $S$ . Then the **surface integral of  $\mathbf{F}$  over  $S$**  is

$$\iint_S \mathbf{F} \cdot \mathbf{n} d\sigma. \quad (5)$$

### Flux Across a Parametrized Surface

it follows that

$$\text{Flux} = \iint_R \mathbf{F} \cdot (\mathbf{r}_u \times \mathbf{r}_v) du dv \quad \iint_S \mathbf{F} \cdot \mathbf{n} d\sigma = \iint_R \mathbf{F} \cdot \frac{\mathbf{r}_u \times \mathbf{r}_v}{|\mathbf{r}_u \times \mathbf{r}_v|} |\mathbf{r}_u \times \mathbf{r}_v| du dv = \iint_R \mathbf{F} \cdot (\mathbf{r}_u \times \mathbf{r}_v) du dv.$$

This integral for flux simplifies the computation in Example 5. Since

$$\mathbf{F} \cdot (\mathbf{r}_x \times \mathbf{r}_z) = (x^2 z)(2x) + (x)(-1) = 2x^3 z - x,$$

we obtain directly

$$\text{Flux} = \iint_S \mathbf{F} \cdot \mathbf{n} d\sigma = \int_0^4 \int_0^1 (2x^3 z - x) dx dz = 2$$

in Example 5.

If  $S$  is part of a level surface  $g(x, y, z) = c$ , then  $\mathbf{n}$  may be taken to be one of the two fields

$$\mathbf{n} = \pm \frac{\nabla g}{|\nabla g|}, \quad (6)$$

depending on which one gives the preferred direction. The corresponding flux is

$$\begin{aligned} \text{Flux} &= \iint_S \mathbf{F} \cdot \mathbf{n} d\sigma \\ &= \iint_R \left( \mathbf{F} \cdot \frac{\pm \nabla g}{|\nabla g|} \right) \frac{|\nabla g|}{|\nabla g \cdot \mathbf{p}|} dA && \text{Eqs. (6) and (3)} \\ &= \iint_R \mathbf{F} \cdot \frac{\pm \nabla g}{|\nabla g \cdot \mathbf{p}|} dA. \end{aligned} \quad (7)$$

**EXAMPLE 2** Integrate  $G(x, y, z) = xyz$  over the surface of the cube cut from the first octant by the planes  $x = 1$ ,  $y = 1$ , and  $z = 1$  (Figure 16.47).

**Solution** We integrate  $xyz$  over each of the six sides and add the results. Since  $xyz = 0$  on the sides that lie in the coordinate planes, the integral over the surface of the cube reduces to

$$\iint_{\substack{\text{Cube} \\ \text{surface}}} xyz d\sigma = \iint_{\text{Side } A} xyz d\sigma + \iint_{\text{Side } B} xyz d\sigma + \iint_{\text{Side } C} xyz d\sigma.$$

Side  $A$  is the surface  $f(x, y, z) = z = 1$  over the square region  $R_{xy}$ :  $0 \leq x \leq 1$ ,  $0 \leq y \leq 1$ , in the  $xy$ -plane. For this surface and region,

$$\mathbf{p} = \mathbf{k}, \quad \nabla f = \mathbf{k}, \quad |\nabla f| = 1, \quad |\nabla f \cdot \mathbf{p}| = |\mathbf{k} \cdot \mathbf{k}| = 1$$

$$d\sigma = \frac{|\nabla f|}{|\nabla f \cdot \mathbf{p}|} dA = \frac{1}{1} dx dy = dx dy$$

$$xyz = xy(1) = xy$$

and

$$\iint_{\text{Side } A} xyz d\sigma = \iint_{R_{xy}} xy dx dy = \int_0^1 \int_0^1 xy dx dy = \int_0^1 \frac{y}{2} dy = \frac{1}{4}.$$