# Slide 8-Finding Matrix Inverse by using elementary matrices/row operations MAT2040 Linear Algebra

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**Definition 8.1** (Row Equivalent Matrices) Let  $A \in \mathbb{R}^{m \times n}$  and suppose we apply a series of elementary row operations  $\mathrm{op}_1, \mathrm{op}_2, \cdots, \mathrm{op}_k$  on A and obtain the matrix B. Then, matrix A is said to be **row** equivalent to matrix B.

Moreover, suppose the corresponding elementary matrix for elementary row operation  $op_i$   $(i = 1, \dots, k)(i = 1, \dots, k)$ , then

$$EA = B$$
,

where  $E = E_k E_{k-1} \cdots E_1$ .

## **Illustration:**

$$A \xrightarrow{op_1} A_1 \xrightarrow{op_2} A_2 \xrightarrow{op_3} \cdots \xrightarrow{op_k} A_k = B.$$

Thus, 
$$B = E_k A_{k-1} = E_k E_{k-1} A_{k-2} = \cdots = E_k E_{k-1} \cdots E_2 A_1 = E_k E_{k-1} \cdots E_1 A = EA$$
.



## Theorem 8.2 (Equivalent conditions for invertible matrix)

 $A \in \mathbb{R}^{n \times n}$ , the following are equivalent:

- (1) A is invertible,
- (2) the linear system  $A\mathbf{x} = \mathbf{0}$  has only a trivial solution,
- (3) matrix A is row equivalent to  $I_n$ ,
- (4) A is a product of elementary matrices,
- (5) there exists an invertible matrix  $E \in \mathbb{R}^{n \times n}$  such that  $EA = I_n$ .
- (6)  $A\mathbf{x} = \mathbf{b}$  has a unique solution for any  $\mathbf{b}$ .

### Proof.

$$(1) \Rightarrow (2)$$

Since A is invertible, then  $A\mathbf{x} = \mathbf{0}$  has a unique solution  $\mathbf{x} = A^{-1}\mathbf{0} = \mathbf{0}$ .

$$(2) \Rightarrow (3)$$

Suppose

$$[A|\mathbf{0}] \xrightarrow{\text{elementary row operations}} [B|\mathbf{0}] (\text{reduced row - echelon form})$$

Since the linear system  $A\mathbf{x} = \mathbf{0}$  has only a trivial solution, thus each row of B must has a leading 1.

Thus,  $B = I_n$ .

$$(3) \Rightarrow (4)$$

By theorem 8.2, there are elementary matrices  $E_1, \dots, E_k$ , such that  $E_k \dots E_1 A = I_n$ . Thus  $A = E_1^{-1} \dots E_k^{-1}$  is a product of elementary matrices since  $E_1^{-1}, \dots, E_k^{-1}$  are also elementary matrices.

$$(4)\Rightarrow (5)$$

Suppose  $A = E_1 \cdots E_k$  ( $E_1, \cdots, E_k$  are elementary matrices), then  $E_k^{-1} \cdots E_1^{-1} A = I_n$ . Let  $E = E_k^{-1} \cdots E_1^{-1}$ , then E is invertible and  $EA = I_n$ .

$$(5) \Rightarrow (1)$$

Since  $EA = I_n$  and E is invertible, then  $A = E^{-1}$  is also invertible, and  $A^{-1} = E$ 

$$(1)\Rightarrow (6)$$

 $A\mathbf{x} = \mathbf{b} \Rightarrow \mathbf{x} = A^{-1}\mathbf{b}$  is the unique solution for any  $\mathbf{b}$ .

$$(6) \Rightarrow (1)$$

If A is singular, then  $A\mathbf{x} = \mathbf{0}$  has infinity many solutions from (2) by the contrapositive statement. Now taking  $\mathbf{z} \neq \mathbf{0}$  is the solution of  $A\mathbf{x} = \mathbf{0}$ , and suppose that  $\mathbf{y}$  is the unique solution of  $A\mathbf{x} = \mathbf{b}$ , then

A(y + z) = Ay + Az = b + 0 = b, thus y + z is also the solution of

 $A\mathbf{x} = \mathbf{b}$ . But  $\mathbf{y} \neq \mathbf{y} + \mathbf{z}$ . This is a contradiction.

#### Remark.

If A is invertible, then A is row equivalent to I, i.e.,  $A \xrightarrow{\text{row op}_1, \cdots, \text{op}_k} I$ , suppose the corresponding elementary matrices for the row operations  $\text{op}_1, \text{op}_2, \cdots, \text{op}_k$  are  $E_1, E_2, \cdots, E_k$ , then  $I = E_k \cdots E_1 A$ . Thus,  $A^{-1} = E_k \cdots E_1 I$ . Thus, for the same series of elementary row operations, it will transforms a nonsingular matrix A to I and transform I to  $A^{-1}$ . This suggests a method to find  $A^{-1}$  by performing row operations for augmented matrix [A|I].

# Method to find $A^{-1}$ (A is invertible)

$$[A|I] \xrightarrow{\text{Gauss Jordan elimination}} [I|P]$$
, then  $P = A^{-1}$ .

**Illustration:** Suppose elementary row operations  $\operatorname{op}_1, \operatorname{op}_2, \cdots, \operatorname{op}_k$  (the corresponding elementary matrices are  $E_1, E_2, \cdots, E_k$ ) are used in the Gauss-Jordan elimination for [A|I] to obtain the reduced row echelon form [I|P]. Then,  $E_k \cdots E_1[A|I] = [I|P] \Rightarrow E_k \cdots E_1A = I, E_k \cdots E_1I = P \Rightarrow P = E_k \cdots E_1 = A^{-1} \Rightarrow P = A^{-1}$ .

# **Example 8.3** Find the inverse of the following matrix

$$(1) \quad A = \left[ \begin{array}{rrr} 1 & 4 & 3 \\ -1 & -2 & 0 \\ 2 & 2 & 3 \end{array} \right]$$

Perform Gauss-Jordan elimination:

$$[A|I] = \begin{bmatrix} 1 & 4 & 3 & 1 & 0 & 0 \\ -1 & -2 & 0 & 0 & 1 & 0 \\ 2 & 2 & 3 & 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 4 & 3 & 1 & 0 & 0 \\ 0 & 2 & 3 & 1 & 1 & 0 \\ 0 & -6 & -3 & -2 & 0 & 1 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 4 & 3 & 1 & 0 & 0 \\ 0 & 2 & 3 & 1 & 1 & 0 \\ 0 & 0 & 6 & 1 & 3 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 4 & 0 & \frac{1}{2} & -\frac{3}{2} & -\frac{1}{2} \\ 0 & 2 & 0 & \frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} \\ 0 & 0 & 6 & 1 & 3 & 1 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 0 & 0 & -\frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ 0 & 2 & 0 & \frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ 0 & 0 & 6 & 1 & 3 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & -\frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ 0 & 1 & 0 & \frac{1}{4} & -\frac{1}{4} & -\frac{1}{4} \\ 0 & 0 & 1 & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

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Thus

$$A^{-1} = \begin{bmatrix} -\frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{4} & -\frac{1}{4} & -\frac{1}{4} \\ \frac{1}{6} & \frac{1}{2} & \frac{1}{6} \end{bmatrix}$$

$$(2) \quad A = \begin{bmatrix} -7 & -6 & -12 \\ 5 & 5 & 7 \\ 1 & 0 & 4 \end{bmatrix}$$

$$[A|I] = \begin{bmatrix} -7 & -6 & -12 & 1 & 0 & 0 \\ 5 & 5 & 7 & 0 & 1 & 0 \\ 1 & 0 & 4 & 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & -10 & -12 & -9 \\ 0 & 1 & 0 & \frac{13}{2} & 8 & \frac{11}{2} \\ 0 & 0 & 1 & \frac{5}{2} & 3 & \frac{5}{2} \end{bmatrix}$$

Thus

$$A^{-1} = \begin{bmatrix} -10 & -12 & -9\\ \frac{13}{2} & 8 & \frac{11}{2}\\ \frac{5}{2} & 3 & \frac{5}{2} \end{bmatrix}$$



# Method to find X such that AX = B (A is invertible)

$$[A|B] \xrightarrow{\text{Gauss Jordan elimination}} [I|X]$$
, then  $X = A^{-1}B$ .

**Illustration:** Suppose elementary row operations  $\operatorname{op}_1, \operatorname{op}_2, \cdots, \operatorname{op}_k$  (the corresponding elementary matrices are  $E_1, E_2, \cdots, E_k$ ) are used in the Gauss-Jordan elimination for [A|B] to obtain the reduced row echelon form [I|P]. Then,  $E_k \cdots E_1[A|B] = [I|P] \Rightarrow E_k \cdots E_1A = I, E_k \cdots E_1B = X \Rightarrow E_k \cdots E_1 = A^{-1} \Rightarrow X = A^{-1}B$ .

**Example 8.4** Find the solution X such that AX = B where

$$A = \begin{bmatrix} 1 & 2 & 3 \\ -2 & -1 & -3 \\ -4 & 5 & 6 \end{bmatrix}, \quad B = \begin{bmatrix} 15 & -15 & -30 \\ 15 & 30 & -15 \\ 5 & -10 & -5 \end{bmatrix}$$

Set

$$[A|B] = \begin{bmatrix} 1 & 2 & 3 & 15 & -15 & -30 \\ -2 & -1 & -3 & 15 & 30 & -15 \\ -4 & 5 & 6 & 5 & -10 & -5 \end{bmatrix}$$

and perform Gauss-Jordan elimination to reduce it into

$$\left[\begin{array}{ccc|ccc|ccc|ccc}
1 & 0 & 0 & 11 & -1 & -20 \\
0 & 1 & 0 & 41 & 14 & -65 \\
0 & 0 & 1 & -26 & -14 & 40
\end{array}\right]$$

Thus

$$X = \left[ \begin{array}{rrr} 11 & -1 & -20 \\ 41 & 14 & -65 \\ -26 & -14 & 40 \end{array} \right]$$

**Theorem 8.5** (One-Sided Inverse Verification is Sufficient) Suppose  $A, B \in \mathbb{R}^{n \times n}$ . If  $BA = I_n$ , then A, B are both invertible and  $AB = I_n$ .

**Proof.** Assume **x** satisfy A**x** = **0**. Then BA**x** = B**0** = **0**. Thus  $\mathbf{x} = I$ **x** = BA**x** = **0**. A**x** = **0** has only zero solution. A is invertible by using theorem 8.2. Assume that  $A^{-1} = C$ , then  $C = I_n C = (BA)C = B(AC) = BI_n = B$ . Thus  $A^{-1} = B$  and  $AB = BA = I_n$ 

**Theorem 8.6** (Nonsingular Product has Nonsingular Terms) Suppose that A and B are square matrices with the same size. The product AB is nonsingular if and only if A and B are both nonsingular.

**Proof.** AB is nonsingular  $\Leftrightarrow \exists$  matrix C (same size with A) s.t. (AB)C = C(AB) = I. By associativity, one has

$$A(BC) = (CA)B = I$$

By theorem 8.5, both A and B are invertible.