## MAT 3007 Optimization Homework 1 Due: 11:59 pm on June 15, 2025 Solution

## 1. Consider the following optimization problem

$$\min f(x)$$
 s.t.  $x \in X$ ,

where  $f: \mathbb{R}^n \to \mathbb{R}$  and  $X \subseteq \mathbb{R}^n$ . For each of the following cases, give an example demonstrating that problem P may have an optimal solution, and an example demonstrating that P may not have an optimal solution, or argue that such an example does not exist.

(a) The function f is discontinuous and the set X is compact (compact means closed and bounded).

The problem P has an optimal solution if

$$X = [0, 1] \subseteq \mathbb{R}, \quad f(x) = \begin{cases} 1, & 0 < x \le 1, \\ 0, & x = 0. \end{cases}$$

The problem P does not have an optimal solution if

$$X = [0, 1] \subseteq \mathbb{R}, \quad f(x) = \begin{cases} 1, & x = 0, \\ x, & 0 < x \le 1. \end{cases}$$

In both cases, X is compact and f is discontinuous.

(b) The function f is continuous and the set X is not closed. The problem P has an optimal solution if

$$X = [0, 1) \subseteq \mathbb{R}, \quad f(x) = x.$$

The problem P does not have an optimal solution if

$$X = (0,1) \subseteq \mathbb{R}, \quad f(x) = x.$$

In both cases, X is not closed and f is continuous.

(c) The function f is linear and the set X is not bounded. The problem P has an optimal solution if

$$X = \mathbb{R}, \quad f(x) = 0.$$

The problem P does not have an optimal solution if

$$X = \mathbb{R}, \quad f(x) = x.$$

In both cases, X is not bounded and f is linear.

(d) The function f is nonlinear and the set X is compact. The problem P has an optimal solution if

$$X = [0, 1], \quad f(x) = x^2.$$

The problem P does not have an optimal solution if

$$X = [0, 1], \quad f(x) = \begin{cases} x, & 0 < x \le 1, \\ 1, & x = 0. \end{cases}$$

In both cases, X is compact and f is nonlinear.

(e) The function f is linear and the set X is not closed. The problem P has an optimal solution if

$$X = [0, 1), \quad f(x) = x.$$

The problem P does not have an optimal solution if

$$X = (0,1), \quad f(x) = x.$$

In both cases, X is not closed and f is linear.

(f) The function f is linear and the set X is compact. The problem P has an optimal solution if

$$X = [0, 1], \quad f(x) = x.$$

In this case, if the set X is nonempty, then the problem P must have an optimal solution. Since the function f is linear, it is also continuous (you can verify this with the definition of continuity), and then by the Weierstrass Theorem, we know that a continuous function attains its maximum and minimum over a compact set.

- 2. For each of the following statements, state whether it is true or false. If true, provide a proof, and if false provide a counter-example.
  - (a) Any optimization problem whose feasible region is bounded must have an optimal solution.

False. Consider Problem 1 (a).

(b) Any optimization problem whose feasible region is unbounded cannot have an optimal solution.

False. Consider  $\{\min x : x \ge 0\}$ .

(c) Every global optimal solution to an optimization problem must have the same objective function value.

Ture. By definition; if not, one of the solutions cannot be globally optimal.

(d) I have solved an optimization problem and got an optimal solution  $x^*$ . Suppose now a constraint is added to the problem. If I find that  $x^*$  satisfies all remaining constraints, then  $x^*$  is an optimal solution of the modified problem.

True. Suppose it is not true, i.e. the new problem has a solution x' with a better objective value than that of  $x^*$ . Note that x' is feasible to the old problem, and since both problems have the same objective function, x' has a better objective value than  $x^*$  in the old problem. This contradicts the fact that  $x^*$  is an optimal solution of the old problem.

(e) Consider the following optimization problem:

$$\min[f(x)]^2$$
 s.t.  $x \in X$ ,

where f(x) is a general function and X is a non-empty set. Suppose at a feasible solution  $x^* \in X$  the objective value is 0, then  $x^*$  must be an optimal solution.

True. 0 is a lower bound of the problem.

(f) Consider the optimization problem

$$(P): \min\{c^{\top}x : Ax = b\}$$

where  $x \in \mathbb{R}^n$ ,  $c \in \mathbb{R}^n$ ,  $A \in \mathbb{R}^{m \times n}$ , and  $b \in \mathbb{R}^m$ . If (P) has at least two feasible solutions with distinct objective function values then (P) is unbounded.

Suppose (P) has two feasible solutions  $x^1$  and  $x^2$  such that  $c^{\top}x^1 < c^{\top}x^2$ . Let  $d = x^1 - x^2$ . Then  $c^{\top}d < 0$ . Consider any point  $x(\lambda) = x^2 + \lambda d$  for some  $\lambda > 0$ . Clearly

$$Ax(\lambda) = Ax^2 + \lambda Ad = Ax^2 + \lambda A(x^1 - x^2) = b.$$

Thus  $x(\lambda)$  is a feasible solution. Now

$$c^{\top}x(\lambda) = c^{\top}x^2 + \lambda c^{\top}d.$$

Since  $c^{\top}d < 0$ , taking  $\lambda \to +\infty$  we have  $x(\lambda)$  remains feasible and  $c^{\top}x(\lambda) \to -\infty$ . Thus the problem is unbounded.

(g) Consider the optimization problem:

$$\min f(x)$$
 s.t.  $g(x) \le 0$ .

Suppose the current optimal objective value is v. Now, if I change the right-hand side of the constraint to 1 and resolve the problem, the new optimal objective value will be less than or equal to v.

True. Changing the right-hand-side of the constraint to 1 enlarges the feasible region, and therefore may allow a smaller objective value than v.

3. Quantas Airways Ltd. must schedule its hundreds of reservation salesclerks around the clock to have at least  $r_t$  on duty during each 1-hour period starting at (24-hour) clock hour  $t = 0, \ldots, 23$ . A shift beginning at time t extends for 9 hours with 1 hour out for lunch in the fourth, fifth, or sixth hours of the shift. Shifts beginning at hour t cost the company  $c_t$  per day, including wages and night-hour premiums. Formulate an LP model to compute a minimum total cost daily shift schedule.

Let  $x_t$  be the number of clerks working a shift starting at hour t and  $y_{t,i}$  be the number of clerks working a shift starting at hour t who take lunch during hour i. The problem can be formulated as

min 
$$\sum_{t=0}^{23} c_t x_t$$
  
s.t.  $\sum_{j=t-8}^{t} x_j - \sum_{j=t-5}^{t-3} y_{j,t} \ge r_t$ ,  $t = 0, \dots, 23$  (cover hour  $t$ ),  $\sum_{i=t+3}^{t+5} y_{t,i} = x_t$ ,  $t = 0, \dots, 23$  (shift  $t$  lunches),  $x_t, y_{t,i} \ge 0$ ,  $\forall t, \forall i$ ,

where hour subscripts j, t < 0 are interpreted as j+24, t+24 and those j, t > 23 are interpreted as j-24, t-24.

4. Formulate the following optimization problems as linear programs or explain why you think it cannot be done.

(a) 
$$\min \quad 2x_2 + |x_1 - x_3|$$
 s.t. 
$$|x_1 + 2| + |x_2| \le 5,$$
 
$$x_3^2 \le 1$$
 Let  $y_1 = |x_1 - x_3|, y_2 = |x_1 + 2|, y_3 = |x_2|.$ 

$$\begin{array}{ll} \min & 2x_2 + y_1 \\ \text{s.t.} & y_1 \geq x_1 - x_3 \\ & y_1 \geq -x_1 + x_3 \\ & y_2 + y_3 \leq 5 \\ & y_2 \geq x_1 + 2 \\ & y_2 \geq -x_1 - 2 \\ & y_3 \geq x_2 \\ & y_3 \geq -x_2 \\ & x_3 \leq 1 \\ & x_3 \geq -1 \end{array}$$

(b) 
$$\min_{x_1, x_2} \{ \max(|2x_1 + 3x_2|, |x_1 - x_2|) : |x_1| + 2\max(x_1, x_2) \le 1 \}$$

$$\min_{x,y} \quad y$$
s.t.  $y \ge -(2x_1 + 3x_2)$ 
 $y \ge (2x_1 + 3x_2)$ 
 $y \ge (x_1 - x_2)$ 
 $y \ge -(x_1 - x_2)$ 
 $3x_1 \le 1$ 
 $x_1 + 2x_2 \le 1$ 
 $-x_1 + 2x_2 \le 1$ 

(c) 
$$\min_{a,b} \left\{ \max_{i} (|y_i - ax_i - b|) : a \ge 0, b \ge 0 \right\}$$

$$\min_{t,a,b} t$$
s.t.  $t \ge (y_i - ax_i - b) \ \forall i$ 

$$t \ge -(y_i - ax_i - b) \ \forall i$$

$$a \ge 0, b \ge 0$$

5. Given a set of training data  $\{x_i, y_i\}_{i=1,\dots,N}$ , where  $x_i$  is an n-dimensional feature vector and  $y_i$  is a label of value either 0 or 1. Think about each  $x_i$  representing a vector of lab test data of a patient i and  $y_i$  labels if this person has a certain disease. We want to build a linear classifier, i.e., a linear function

$$f(x) = \beta_0 + \sum_{j=1}^{n} \beta_j x_j,$$

so that for a given feature vector x, if  $f(x) \ge 0.5$ , then x is classified as y = 1, otherwise classified as y = 0.

A very popular method to build the classifier is called the absolute deviation regression (ADR). ADR is also called robust regression. The optimization model of ADR is described below.

(ADR) 
$$\min_{\beta_0,...,\beta_n} \sum_{i=1}^{N} \left| y_i - \beta_0 - \sum_{j=1}^{n} \beta_j x_{ij} \right|,$$

where  $x_{ij}$  is the jth component of vector  $x_i$ . Notice that the ADR model is a nonlinear optimization problem.

Answer the following questions.

(a) Write a linear programming reformulation of (ADR). The problem (ADR) can be formulated as a linear program with auxiliary variables  $t_i$ , i = 1, ..., N:

$$\min_{t_i, i=1, \dots, N, \beta_0, \dots, \beta_n} \quad \sum_{i=1}^N t_i,$$
s.t. 
$$t_i \ge y_i - \beta_0 - \sum_{j=1}^n \beta_j x_{ij}, \quad \forall i = 1, \dots, N,$$

$$t_i \ge -(y_i - \beta_0 - \sum_{j=1}^n \beta_j x_{ij}), \quad \forall i = 1, \dots, N.$$

(b) Code your LP reformulation of (ADR) in CV, using the data file "regression.dat" provided.

We can write the CVXPY code as follows:

import pandas as pd

```
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
from cvxpy import *

# modified the regression.dat file to use read_table command
data = pd.read_table('regression.dat', delim_whitespace = True, header =
nData = 100
nFeature = 2
```

```
x = data.values[0: nData, :]
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```
y = data.values[nData: 2 * nData, 0]
   # b for beta
   b = Variable (nFeature + 1)
   # t for auxiliary variables for absolute values
   t = Variable(nData)
   constr = []
   for i in range (nData):
   constr += [t[i] >= y[i] - (b[0] + b[1] * x[i, 0] + b[2] * x[i, 1]),
   -t[i] \le y[i] - (b[0] + b[1] * x[i, 0] + b[2] * x[i, 1])
   obj = sum(t)
   prob = Problem (Minimize (obj), constr)
   result = prob.solve()
   An optimal solution is (\beta_0, \beta_1, \beta_2) = (0.4036; 0.1850, -0.1995) (which may not be unique).
(c) Write a code to plot the data points and the hyperplane obtained from (ADR).
   We can use the following python code:
   b_sol = b.value
   y_fit = np.ones(nData) * 
   b_sol[0, 0] + x[:, 0] * b_sol[1, 0] + x[:, 1] * b_sol[2, 0]
   x1_{\text{max}} = \text{np.max}(x[:, 0])
   x1_min = np.min(x[:, 0])
   x2_{\text{-}}max = np.max(x[:, 1])
   x2_{min} = np.min(x[:, 1])
   \operatorname{mesh}_{x_1}, \operatorname{mesh}_{x_2} = \operatorname{np.meshgrid}(\operatorname{np.arange}(x_1 - \min, x_1 - \max, 0.1))
   np.arange(x2_min, x2_max, 0.1))
   # calculate corresponding z values
   plane_y = b_sol[0, 0] + mesh_x1 * b_sol[1, 0] + mesh_x2 * b_sol[2, 0]
   fig = plt.figure()
   ax = fig.add_subplot(111, projection='3d')
   ax.scatter(x[:, 0], x[:, 1], y)
```

 $\label{local-continuity} $ax.plot_surface (mesh_x1, mesh_x2, plane_y)$ $ The resulting figure shall look like the following one.$ 

