

MAT 3007 Optimization: Tutorial 4

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Review: Fundamental LP Theorem

Consider a linear problem **in standard form** and assume that A has full row rank m .

(1) existence of extreme points:

If the feasible set is nonempty, there is a basic feasible solution.

\Leftrightarrow Nonempty polyhedra in standard form have at least one extreme point. Remark: Standard form (especially $x \geq 0$) plays an important role in the existence here!

(2) optimality of extreme points:

If there is an optimal solution, there is an optimal solution that is also a basic feasible solution.

More generally, if feasible, then the optimal cost is either $-\infty$, or finite and can be attained by an extreme point as an optimal solution

Remark: In LP, if optimal cost is **finite**, then it's **attainable**!

Review: Fundamental LP Theorem & Exercise

For each of the following statements, state whether it is true or false. If true, provide a proof, else, provide a counterexample.

Now consider the standard form polyhedron $P = \{x \in \mathbb{R}^n \mid Ax = b, x \geq 0\}$. Suppose $A \in \mathbb{R}^{m \times n}$ has m linearly independent rows.

- (a) if $n = m + 1$, then P has at most two basic feasible solutions.
- (b) The set of all optimal solutions is bounded.
- (c) At every optimal solution, no more than m variables can be positive.
- (d) If there is more than one optimal solution, then there are uncountably many optimal solutions.
- (e) If there are several optimal solutions, then there exist at least two optimal basic feasible solutions.

Review: Fundamental LP Theorem & Solution

- (a) ✓ n is the dimension of x , $m(= n - 1)$ is the number of equality constraints. Now x lies in a n -dimensional space but $n - 1$ degrees of freedom are taken away, so actually x lies in a line in this n -dimensional space and for any line, it has at most 2 vertexes.
- (b) ✗ Consider the following toy example, $P = \{(x_1, 0) \in R^2 \mid x_1 \geq 0\}$ is the unbounded optimal solution set.

$$\begin{array}{ll}\min & x_2 \\ \text{s.t.} & x_1 \geq 0 \\ & x_2 \geq 0\end{array}$$

Review: Fundamental LP Theorem & Solution

$$\begin{array}{ll}\min & x_2 \\ \text{s.t.} & x_1 \geq 0 \\ & x_2 \geq 0\end{array}$$

- (c) ✗ Recall the toy example in (b), $m=0$, but every point in $S = \{(x_1, 0) \in R^2 \mid x_1 > 0\}$ has 1 positive variable and optimal (they are all not extreme points!).
- (d) ✓ By convexity of polyhedron.
- (e) ✗ Same as in (b), $P = \{(x_1, 0) \in R^2 \mid x_1 \geq 0\}$ has several optimal solutions but only $(0,0)$ is extreme point i.e. BFS.

Exercise 1

For the standard Lp polyhedron $\{x : Ax = b, x \geq 0\}$, the followings are equivalent:

- (1) x is an extreme point
- (2) x is a basic feasible solution

Solution to Exercise 1 : (1) \Rightarrow (2)

Suppose x is an extreme point, $B = \{B(1), B(2), \dots, B(k)\}$ be the set of indices such that $x_i > 0$. Then we want to prove that $A_{B(1)}, A_{B(2)}, \dots, A_{B(k)}$ are linearly independent.

We prove by contradiction. If not, we have k numbers $\alpha_1, \alpha_2, \dots, \alpha_k$, which are not all zeros, such that $\sum_{j=1}^k \alpha_j A_{B(j)} = 0$.

For $\epsilon > 0$, define two vectors x^+ and x^- as

$$x_{B(j)}^+ = x_{B(j)} + \epsilon \alpha_j, \quad j = 1, \dots, k$$

$$x_{B(j)}^- = x_{B(j)} - \epsilon \alpha_j, \quad j = 1, \dots, k$$

$$x_i^+ = x_i^- = x_i = 0, \quad i \notin B$$

We can choose ϵ small enough such that $x^+ \geq 0$ and $x^- \geq 0$, and we also have $Ax^+ = Ax^- = b$, i.e. x^+ and x^- are two different feasible solutions. Then $x = \frac{1}{2}(x^+ + x^-)$ contradicts the fact that x is an extreme point.

Solution to Exercise 1 : (2) \Rightarrow (1)

Suppose x is a BFS, and not an extreme point. then
 $\exists x^{(1)}, x^{(2)} \neq x, \lambda \in (0, 1)$, such that $x = \lambda x^{(1)} + (1 - \lambda)x^{(2)}$

$$\begin{pmatrix} x_B \\ x_N \end{pmatrix} = \lambda \begin{pmatrix} x_B^{(1)} \\ x_N^{(1)} \end{pmatrix} + (1 - \lambda) \begin{pmatrix} x_B^{(2)} \\ x_N^{(2)} \end{pmatrix}$$

$$x_N = \lambda x_N^{(1)} + (1 - \lambda)x_N^{(2)} \Rightarrow x_N^{(1)} = x_N^{(2)} = 0$$

$$Ax^{(1)} = Ax^{(2)} = b \Rightarrow x_B^{(1)} = x_B^{(2)} = A_B^{-1}b$$

$$x = x^{(1)} = x^{(2)}$$

Exercise 2

Use the simplex method to solve the following problem
(This trivial problem is an illustration of simplex method.)

$$\begin{array}{ll} \min & 3x_1 + 4x_2 \\ \text{s.t.} & x_1 + x_2 \leq 4 \\ & x_2 \leq 5 \\ & x \geq 0 \end{array} \quad (1)$$

Solution to Exercise 2

Recap on simplex procedure for standard form LP:

- (1) Find a BFS with basis B .
- (2) Find reduced cost \bar{c}_j for $j \notin B$
If $\exists j$ s.t. $\bar{c}_j < 0$, then continue; otherwise stop. (\rightarrow Stopping Criterion)
- (3) j th direction is $\mathbf{d} = [-A_B^{-1}A_j; 0; \dots; 1; \dots 0]$
If $\mathbf{d} \geq 0$, then unbounded; otherwise for some $d_i < 0$, choose
 $\theta = \min_{(i \in B | d_i < 0)} (-x_i / d_i)$
- (4) $\mathbf{y} = \mathbf{x} + \theta \mathbf{d}$ is a new BFS with basis B'
- (5) go to (1)

Solution to Exercise 2

Standardization:

$$\begin{array}{ll}\min & 3x_1 + 4x_2 \\ \text{s.t.} & x_1 + x_2 + x_3 = 4 \\ & x_2 + x_4 = 5 \\ & x \geq 0\end{array}$$

$$\mathbf{c} = [3; 4; 0; 0] \quad \mathbf{x} = [x_1; x_2; x_3; x_4] \quad \mathbf{b} = [4; 5]$$

$$A = \begin{pmatrix} 1 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{pmatrix}$$

Note: A has 2 linearly independent rows.

Solution to Exercise 2

- (1) Suppose we choose $B(1) = 1$ and $B(2) = 4$, we reorder all entries by $B = [B(1) \ B(2)]$ and $N = B^c$

$$A_B^{-1} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}^{-1} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

then, a BFS is $x = [x_B \ x_N]$ where $x_B = A_B^{-1}b = [4; 5]$ and $x_N = 0$

- (2) compute $\bar{c}_j = c_j - c_B^T A_B^{-1} A_j$ (we start from the smallest index)
 $\bar{c}_2 = 1 \quad \bar{c}_3 = -3$. Choose index 3.
- (3) Since $d = [d_B; d_N] = [-A_B^{-1} A_3; 0; 1] = [-1; 0; 0; 1]$ (index : 1 4 2 3),
 $\theta = \min_{(i \in B | d_i < 0)} (-x_i / d_i) = 4$
- (4) $y = x + \theta d = [0; 5; 0; 4]$ (index : 1 4 2 3)
- (5) we repeat the above (2)-(4) and find out this is optimal. We conclude:
optimal solution $[x_1; x_2] = [0; 0]$ and optimal value $= 0$.

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