

PHY 1001: Mechanics

Tutorial Session 4

T-05: Feb - 28 - 2024, Wednesday, 19:00~19:50

T-12: Feb - 28 - 2024, Wednesday, 20:00~20:50



* Force of a Golf Swing. A 0.0450 - kg golf ball initially at rest is given a speed of 25.0 m/s when a club strikes. If the club and ball are in contact for $2.00 \text{ ms} = 2.00 \times 10^{-3} \text{ s}$, what average force acts on the ball? Is the effect of the ball's weight during the time of contact significant? Why or why not?

Solution:

According to the *impulse-momentum change theorem*, the average force on an object and the object's change in momentum are related by

$$F_{av}\Delta t = mv_f - mv_i = m\Delta v \tag{1}$$

where $v_i = 0$ and $v_f = 25 \ m/s$ for the golf ball. Thus

$$F_{av} = \frac{m\Delta v}{\Delta t} = \frac{0.0450 * 25.0}{2.00 \times 10^{-3}} N = 563 N$$
 (2)

The force exerted by the club is much greater than the weight of ball (w = mg = 0.441 N), so the effect of the weight of ball during the time of contact is not significant.

QED.



* Hockey Puck and Impulse. A 0.160 - kg hockey puck is moving on an icy, frictionless, horizontal surface. At t = 0, the puck is moving to the right at 3.00 m/s.

Questions:

- (a) Calculate the velocity of the puck (magnitude and direction) after a force of **25.0 N** directed to the right has been applied for **0.050 s**.
- (b) If, instead, a force of 12.0 N directed to the left is applied from t = 0 to t = 0.050 s, what is the final velocity of the puck?



Question (a):

(a) Calculate the velocity of the puck (magnitude and direction) after a force of **25.0 N** directed to the right has been applied for **0.050 s**.

Answer (a):

- (1) Based on the *impulse-momentum change theorem* $J_x = F_x \Delta t = \Delta p_x$, we know the initial momentum and the impulse so can solve for the final momentum and then the final velocity.
- (2) Take the x axis to be toward the right, so $v_{1x} = +3.00 \text{ m/s}$. Then compute the impulse

$$J_x = F_x \Delta t = (+25 \text{ N})(0.050 \text{ s}) = 1.25 \text{ N} \cdot \text{s}$$
 (1)

(3) Final momentum is then $p_{2x} = p_{1x} + J_x = 1.73 \text{ N} \cdot \text{s}$ and the final velocity is

$$v_{2x} = \frac{p_{2x}}{m} = 10.8 \text{ m/s}$$
 (to the right) (2)

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Question (b):

(b) If, instead, a force of 12.0 N directed to the left is applied from t = 0 to t = 0.050 s, what is the final velocity of the puck?

Answer (b):

- (1) In this case, $J_x = F_x \Delta t = (-12.0 \text{ N})(0.050 \text{ s}) = -0.600 \text{ kg} \cdot \text{m/s}$ (negative since force is to left).
- (2) Then $p_{2x} = J_x + p_{1x} = (-0.600 + 0.480) \text{kg} \cdot \text{m/s} = -0.120 \text{ kg} \cdot \text{m/s}$. the final velocity is

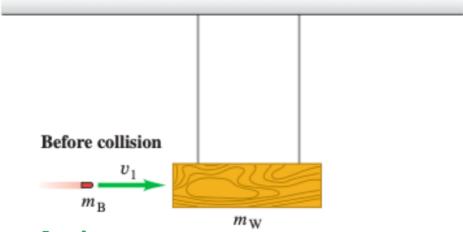
$$v_{2x} = \frac{p_{2x}}{m} = -0.750 \text{ m/s}$$
 (to the left) (3)

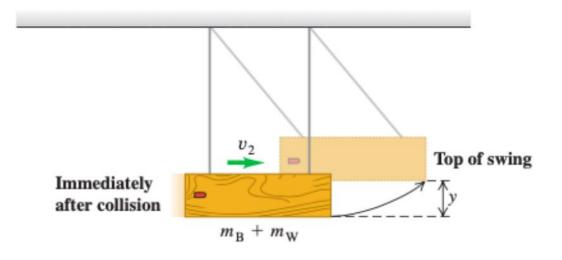
(3) In part (a) the impulse and initial momentum are in the same direction and v_x increases. In part (b) the impulse and initial momentum are in opposite directions and the velocity decreases.

QED.



* The figure below shows a ballistic pendulum, a simple system for measuring the speed of a bullet. A bullet of mass m_B makes a completely inelastic collision with a block of wood of mass m_W , which is suspended like a pendulum. After the impact, the block swings up to a maximum height y. In terms of y, m_B , and m_W , what is the initial speed v_1 of the bullet?



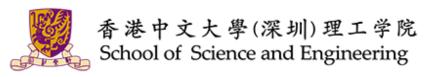


Analysis:

We analyze this event in two stages:

- (1) the embedding of the bullet in the block; and
- (2) the pendulum swing of the block.

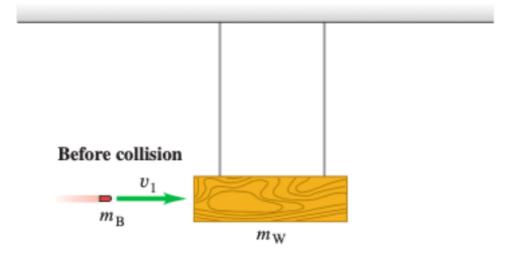
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Analysis:

(First stage-the embedding of the bullet in the block)

- ➤ During the first stage, the bullet embeds itself in the block so quickly that the block does not move appreciably.
- The supporting strings remain nearly vertical, so negligible external horizontal force acts on the bullet—block system, and the horizontal component of momentum is conserved.
- The collision between bullet—block is inelastic, therefore the mechanical energy is not conserved.

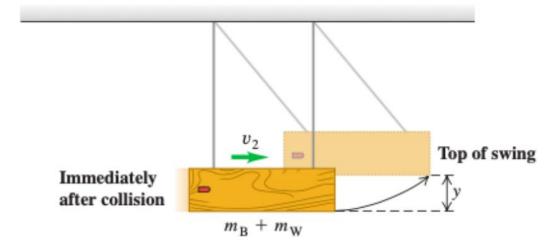




Analysis:

(Second stage-the pendulum swing of the block)

- ➤ In the second stage, the block and bullet move together.
- The only forces acting on this system are gravity (a conservative force) and the string tensions (which do no work).
- Thus, as the block swings, mechanical energy is conserved.
- Momentum is not conserved in this process due to the external forces.



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Solution:

(1) In the first stage, all velocities are in the +x -direction. Momentum conservation gives

$$m_B v_1 = (m_B + m_W) v_2 (1)$$

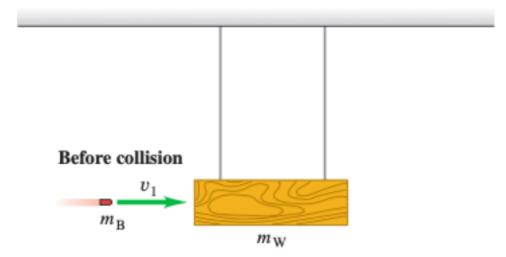
$$v_1 = \frac{(m_B + m_W)}{m_R} v_2 \tag{2}$$

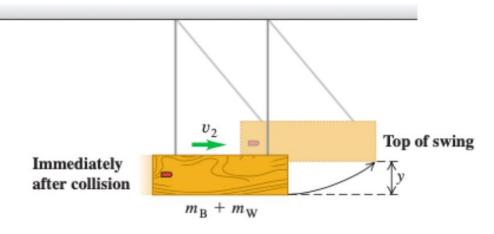
(2) At the beginning of second stage, the bullet—block system has kinetic energy, which is converted into the potential energy at the end of the second stage. Thus,

$$\frac{m_B + m_W}{2} v_2^2 = (m_B + m_W) gy \rightarrow v_2 = \sqrt{2gy} \quad (3)$$

(3) By substituting this expression for v_2 into the equation above, one gets the <u>Answer</u>:

$$v_1 = \frac{(m_B + m_W)}{m_B} \sqrt{2gy} \tag{4}$$





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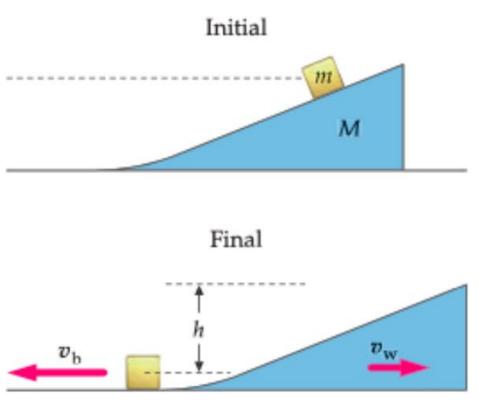




* A wedge of mass *M* is placed on a frictionless, horizontal surface, and a block of mass *m* is placed on the wedge, which also has a frictionless surface (see figure below). The block's center of mass moves downward a distance *h* as the block slides from its initial position to the horizontal floor.

Questions:

- (a) What are the speeds of the block and of the wedge as they separate from each other and go their own ways?
- (b) Check your calculation plausibility by considering the limiting case when $M \gg m$.





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Question (a):

What are the speeds of the block and of the wedge as they separate from each other and go their own ways?

Solution (a):

(1) From the conservation of momentum

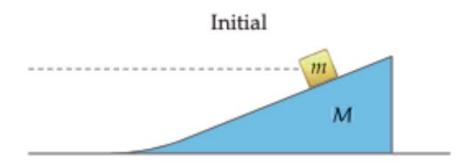
$$Mv_w - mv_b = 0 (1)$$

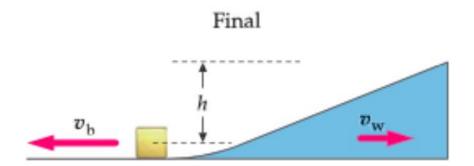
and conservation of energy

$$mgh = \frac{1}{2}mv_b^2 + \frac{1}{2}Mv_w^2 \tag{2}$$

(2) Then solve for v_h and v_w

$$v_b = \sqrt{2gh \frac{M}{m+M}}, \quad v_w = \sqrt{2gh \frac{m^2}{M(m+M)}}$$
 (3)







Question (b):

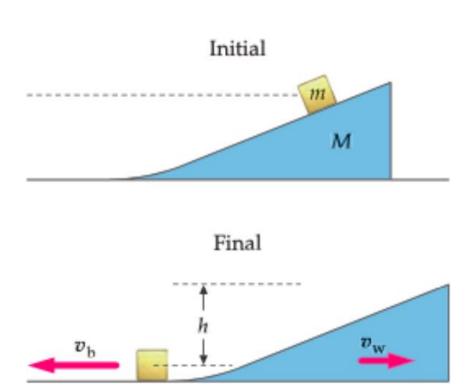
Check your calculation plausibility by considering the limiting case when $M \gg m$.

Solution (b):

In the limit of $M \gg m$, one finds $v_b = \sqrt{2gh}$ and $v_w = 0$ as expected.

$$mgh = \frac{1}{2}mv_b^2$$

QED.

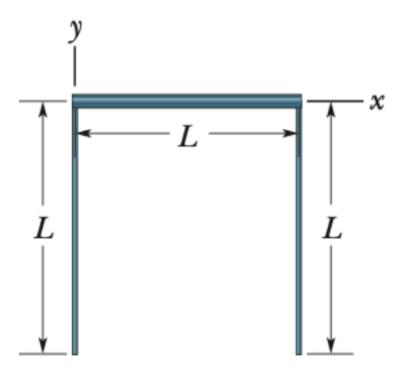




* * (Halliday, C9_P4) In the figure below, three uniform thin rods, each of length L = 24 cm, form an inverted U. The vertical rods each have a mass of M = 14 g; the horizontal rod has a mass of 3M = 42 g.

Questions:

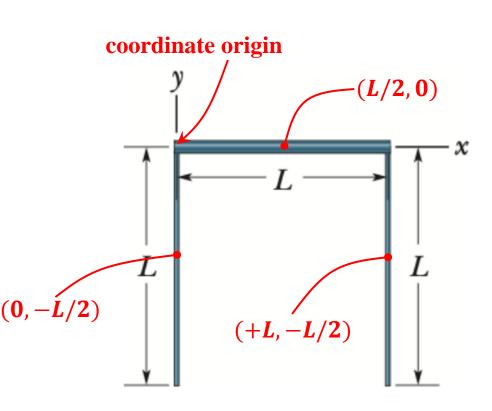
- (a) What is the *x* coordinate of the system's center of mass?
- (b) What is the y coordinate of the system's center of mass?





Analysis:

- ➤ We will refer to the arrangement as a 'table'.
- ➤ We locate the coordinate origin at the left end of the table-top (as shown in the left figure).
- \triangleright With +x rightward and +y upward, then
 - the center of mass of the right leg is at (0, -L/2) (x,y)=(+L,-L/2),
 - the center of mass of the left leg is at (x,y) = (0,-L/2),
 - and the center of mass of the table-top is at (x, y) = (L/2, 0).





Solution (a):

- (1) Let M = 14 g be the mass of the vertical rod, and the mass of the horizontal rod is then 3M = 42 g.
- (2) The x coordinate of the (whole table) center of mass is then

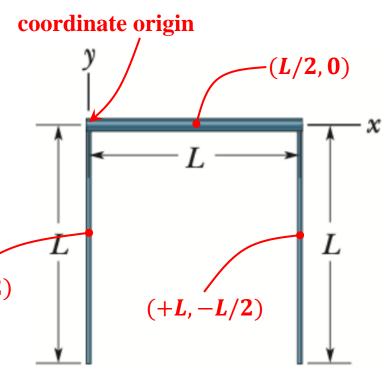
$$x_{com} = \frac{M \times (0) + M \times (+L) + 3M \times (+L/2)}{M + M + 3M} = \frac{L}{2} = 12 \text{ cm}$$

Solution (b):

The y coordinate of the (whole table) center of mass is

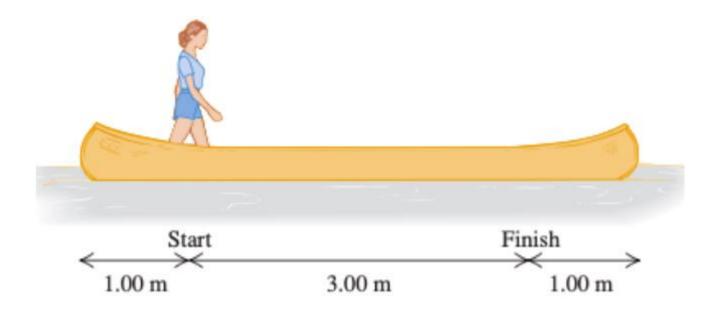
$$y_{com} = \frac{M \times (-L/2) + M \times (-L/2) + 3M \times (0)}{M + M + 3M} = -\frac{L}{5} = -4.8 \text{ cm}$$

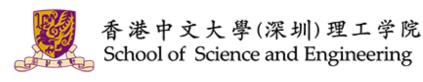
<u>Comment:</u> From the coordinates, we see that the whole table center of mass is a small distance 4.8 cm directly below the middle of the tabletop.





* Center of Mass. A 45.0-kg woman stands up in a 60.0-kg canoe 5.00 m long. She walks from a point 1.00 m from one end to a point 1.00 m from the other end (Fig. below). If you ignore resistance to motion of the canoe in the water, how far does the canoe move during this process?



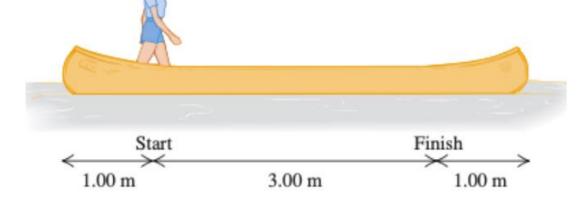


Solution:

- (1) There is no net horizontal external force so $v_{cm} = 0$ all the time, and thus the center of mass of the system never moves.
- (2) Let +x be to the right, with the origin at the initial position of the left-hand end of the canoe. Initially, before the woman walks

$$x_{cm1} = \frac{mx_{w1} + Mx_{c1}}{m + M}$$
 (1)

Where m = 45.0 kg, M = 60.0 kg, $x_{w1} = 1.00 \text{ m}$ and $x_{c1} = 2.50 \text{ m}$.



(3) After she walks to **1.50 m** to the right of the center of mass of the canoe, the center of mass is

$$x_{cm2} = \frac{mx_{w2} + Mx_{c2}}{m + M}$$
 (2)
$$x_{w2} = x_{c2} + 1.50 \text{ m}$$
 (3)

Thus, one finds $x_{c2} = 1.21$ m and the canoe moves $\Delta x = x_{c2} - x_{c1} = -1.29$ m to the left. QED.

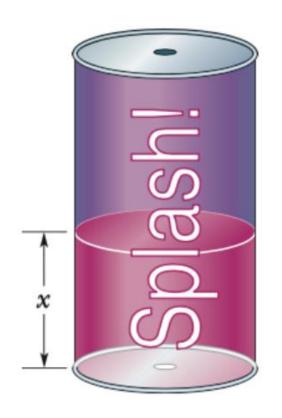
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** (Halliday, C9_P8) A uniform soda can of mass M = 0.140 kg is H = 12.0 cm tall and <u>fully filled</u> with m = 0.354 kg of soda (Figure shown below). Then small holes are drilled in the top and bottom (with negligible loss of metal) to drain the soda.

Questions:

- (a) What is the height **h** of the Center of Mass (COM) of the can and contents initially?
- (b) What is the height h of the COM of the can and contents after the can loses all the soda?
- (c) What happens to *h* as the soda drains out?
- (d) If x is the height of the remaining soda at any given instant, find x when the COM reaches its lowest point.





Question (a):

(a) What is the height h of the Center of Mass (COM) of the can and contents initially?

Solution (a):

- (1) Since the can is uniform, its center of mass is at its geometrical center, a distance H/2 above its base.
- (2) The center of mass of the soda alone is at its geometrical center, a distance H/2 above the base of the can, and when the can is full this is H/2.
- (3) Thus the center of mass of the can and the soda it contains is a distance

$$h = \frac{M(H/2) + m(H/2)}{M+m} = \frac{H}{2} = 6.0 cm$$
 (1)

above the base, on the cylinder axis.



Question (b):

(b) What is the height h of the COM of the can and contents after the can loses all the soda?

Solution (b):

We now consider the can alone. The center of mass is H/2 = 6.0 cm above the base, on the cylinder axis.

Question (c):

(c) What happens to *h* as the soda drains out?

Solution (c):

Intuitively, the COM h should decrease from H/2 first as x decreases then rise up to H/2 again when all the soda is drained. This implies that there must be a minimum in h.



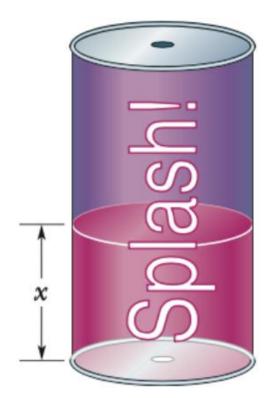
Question (d):

(d) If x is the height of the remaining soda at any given instant, find x when the COM reaches its lowest point.

Solution (d):

- (1) When the top surface of the soda is a distance x above the base of the can, the mass of the soda in the can is $m_p = m(x/H)$, where m is the soda in the can is full (x = H).
- (2) The center of mass of the soda alone is a distance x/2 above the base of the can. Hence

$$h = \frac{M(H/2) + m_p(x/2)}{M + m_p} = \frac{MH^2 + mx^2}{2(MH + mx)}$$
(2)





Solution (d):

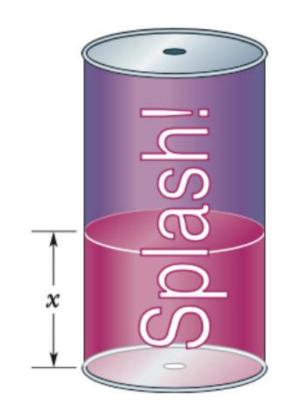
(3) By setting the derivative of h w.r.t. x equal to 0 and solving for x, we obtain

$$\frac{dh}{dx} = \frac{m^2x^2 + 2MmHx - MmH^2}{2(MH + mx)^2}$$
 (3)

$$\rightarrow x = \frac{MH}{m} \left[\sqrt{1 + \frac{m}{M}} - 1 \right] \tag{4}$$

(4) In the end, by substituting the above expression found for x into Eq. (2) and some algebraic manipulation, we obtain

$$h = \frac{MH}{m} \left[\sqrt{1 + \frac{m}{M}} - 1 \right] = 4.2 cm$$
 (5)





** (Halliday, C9_P72) In the two-dimensional collision in Figure below, the projectile particle has mass $m_1 = m$, initial speed $v_{1i} = 3v_0$, and final speed $v_{1f} = \sqrt{5}v_0$, The initially stationary target particle has mass $m_2 = 2m$ and final speed $v_{2f} = v_2$. The projectile is scattered at an angle given by $\tan \theta_1 = 2$.

Questions:

- (a) Find angle θ_2 .
- (b) Find v_2 in terms of v_0 .
- (c) Is the collision elastic?

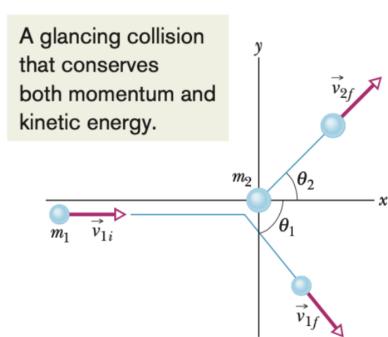


Figure 9-21 An elastic collision between two bodies in which the collision is not head-on. The body with mass m_2 (the target) is initially at rest.

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Question (a): Find angle θ_2 .

Solution (a):

(1) Momentum conservation along the x and y axes gives

$$3mv_0 = m\sqrt{5}v_0\cos\theta_1 + 2mv_2\cos\theta_2 \tag{1}$$

$$0 = -m\sqrt{5}v_0\sin\theta_1 + 2mv_2\sin\theta_2 \tag{2}$$

(2) Given $tan \theta_1 = 2$ and acute angle θ_1 , trigonometry gives

$$\sin \theta_1 = \frac{2}{\sqrt{5}}$$
 and $\cos \theta_1 = \frac{1}{\sqrt{5}}$

Combining the above results gives $v_2 \cos \theta_2 = v_2 \sin \theta_2 = v_0$.

Therefore, $tan\theta_2 = 1$, $\theta_2 = \pi/4$.

Question (b): Find v_2 in terms of v_0 .

Solution (b): Since
$$\theta_2 = \pi/4$$
, $v_2 = \sqrt{2}v_0$.





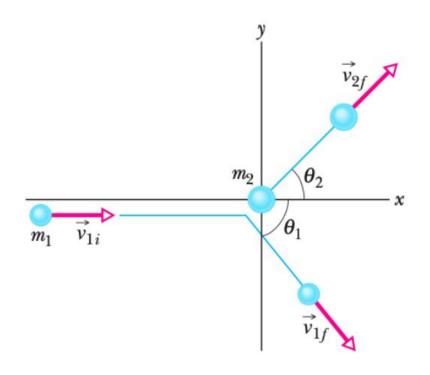
Question (c):

(c) Is the collision elastic?

Solution (c):

- (1) Kinetic energy before the collision is $9/2 mv_0^2$.
- (2) Kinetic energy after the collision is $5/2 mv_0^2 + 4/2mv_0^2 = 9/2mv_0^2$.
- (3) Since the kinetic energy of the system is the same before and after the collision, we conclude that the **collision is elastic**.







** Show that in one-dimensional elastic collision, if the mass and velocity of object 1 are m_1 and v_{1i} , and if the mass and velocity of object 2 are m_2 and v_{2i} , then their final velocities v_{1f} and v_{2f} are given by

$$v_{1f} = \frac{m_1 - m_2}{m_1 + m_2} v_{1i} + \frac{2m_2}{m_1 + m_2} v_{2i}$$
 $v_{2f} = \frac{m_2 - m_1}{m_1 + m_2} v_{2i} + \frac{2m_1}{m_1 + m_2} v_{1i}$

Check the plausibility of the above answer by considering the limiting case with $m_1 \gg m_2$. Note that in this case the velocity of object 1 is unchanged while the object 2 is like hitting a wall in the reference frame of object 1.



Solution: 1D elastic collision.

(1) From conservation of momentum

$$m_1 v_{1i} + m_2 v_{2i} = m_1 v_{1f} + m_2 v_{2f}$$

$$\rightarrow m_1 (v_{1i} - v_{1f}) = m_2 (v_{2f} - v_{2i})$$
(1)

(allow v's to take positive and negative values to capture its vector feature.)

(2) According to conservation of energy

$$\frac{1}{2}m_{1}v_{1i}^{2} + \frac{1}{2}m_{2}v_{2i}^{2} = \frac{1}{2}m_{1}v_{1f}^{2} + \frac{1}{2}m_{2}v_{2f}^{2} \rightarrow
\frac{1}{2}m_{1}v_{1i}^{2} - \frac{1}{2}m_{1}v_{1f}^{2} = \frac{1}{2}m_{2}v_{2f}^{2} - \frac{1}{2}m_{2}v_{2i}^{2} \rightarrow
m_{1}(v_{1i} + v_{1f})(v_{1i} - v_{1f}) = m_{2}(v_{2i} + v_{2f})(v_{2f} - v_{2i})$$
(2)



Solution: 1D elastic collision.

(3) Divide Eq. (2) by Eq. (1) \Rightarrow

$$v_{1i} + v_{1f} = v_{2i} + v_{2f} (3)$$

<u>Comments:</u> The above equation essentially indicates that the relative velocity changes sign before and after the collision, namely,

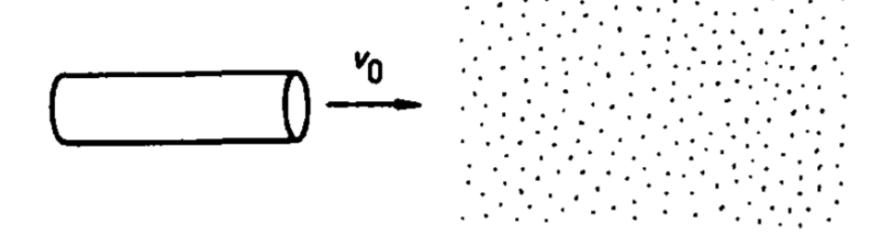
$$(v_{1i} - v_{2i}) = -(v_{1f} - v_{2f}) \tag{4}$$

Solve the final velocities from Eq. (1) and Eq. (3) and find

$$v_{1f} = \frac{m_1 - m_2}{m_1 + m_2} v_{1i} + \frac{2m_2}{m_1 + m_2} v_{2i}$$
 $v_{2f} = \frac{m_2 - m_1}{m_1 + m_2} v_{2i} + \frac{2m_1}{m_1 + m_2} v_{1i}$



* * * Suppose the spacecraft (Enterprise) of mass m_0 and cross-section A is moving with velocity v_0 when it encounters a stationary dust cloud of density ρ at t=0. If the dust sticks to the spacecraft and resistance can be neglected. Solve for the subsequent motion of the spacecraft.





Solution:

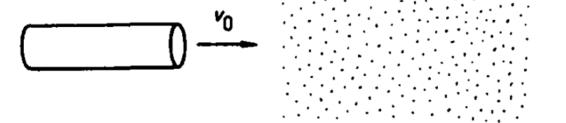
(1) Suppose the dust gives no drag resistance to the spacecraft (Enterprise), then the spacecraft-dust system is isolated. *Newton's second law* gives

$$\frac{d(mv)}{dt} = 0 \qquad or \qquad m\frac{dv}{dt} + v\frac{dm}{dt} = 0 \tag{1}$$

which implies $mv = m_0v_0$ or $m = \frac{m_0v_0}{v}$.

(2) As the spacecraft picks up the dust along its path, its mass increases at the rate

$$\frac{dm}{dt} = \rho A v \tag{2}$$





Solution:

(3) Combining the above two equations yields

$$m\frac{dv}{dt} + \rho Av^2 = 0 \quad plus \quad m = \frac{m_0 v_0}{v} \quad \Rightarrow \tag{3}$$

$$\frac{m_0 v_0}{v} \frac{dv}{dt} + \rho A v^2 = 0 \quad \Rightarrow \tag{4}$$

separate variables
$$\frac{dv}{v^3} = -\frac{\rho A}{m_0 v_0} dt \tag{5}$$

(4) Integrating on both sides gives

$$\int_{v_0}^{v} \frac{dv}{v^3} = -\frac{\rho A}{m_0 v_0} \int_0^t dt \quad \to \tag{6}$$

$$-\frac{1}{2}\left(\frac{1}{v^2} - \frac{1}{v_0^2}\right) = -\frac{\rho A}{m_0 v_0} t \rightarrow v = v_0 \sqrt{\frac{1}{1 + 2\rho A v_0 t/m_0}}$$
(7)

QED.

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