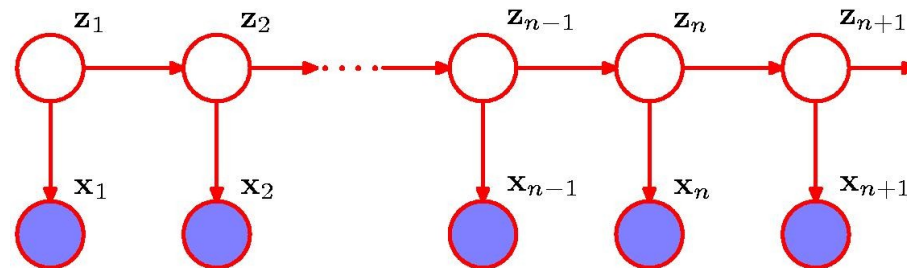


Hidden Markov Models

Implementing the forward-, backward- and Viterbi-algorithms
using log-space and scaling



The Viterbi Algorithm

$\omega(\mathbf{z}_n)$ is the probability of the most likely sequence of states $\mathbf{z}_1, \dots, \mathbf{z}_n$ generating the observations $\mathbf{x}_1, \dots, \mathbf{x}_n$

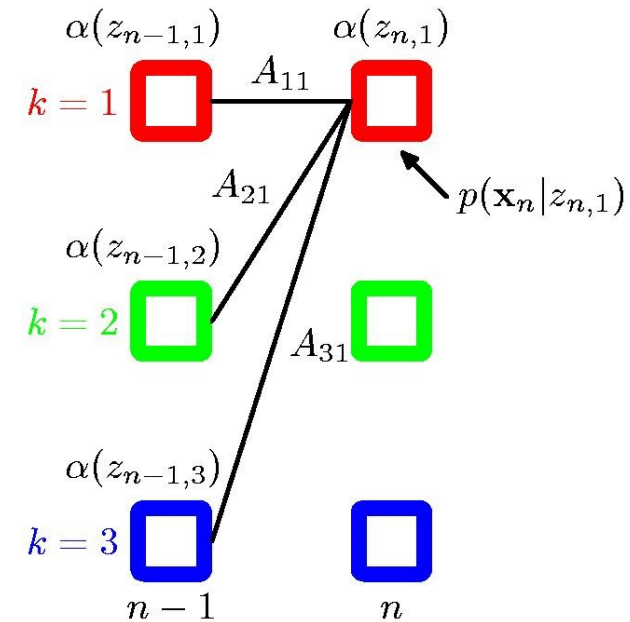
$$\omega(\mathbf{z}_n) = \max_{\mathbf{z}_1, \dots, \mathbf{z}_{n-1}} p(\mathbf{x}_1, \dots, \mathbf{x}_n, \mathbf{z}_1, \dots, \mathbf{z}_n)$$

Recursion:

$$\omega(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \max_{\mathbf{z}_{n-1}} \omega(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1})$$

Basis:

$$\omega(\mathbf{z}_1) = p(\mathbf{x}_1, \mathbf{z}_1) = p(\mathbf{z}_1) p(\mathbf{x}_1 | \mathbf{z}_1) = \prod_{k=1}^K \{ \pi_k p(\mathbf{x}_1 | \phi_k) \}^{z_{1k}}$$



Takes time $O(K^2N)$ and space $O(KN)$ using memorization

Th

$\omega(\mathbf{z}_n)$ is the probability of generating the observation \mathbf{x}_n given the hidden states $\mathbf{z}_1, \dots, \mathbf{z}_n$

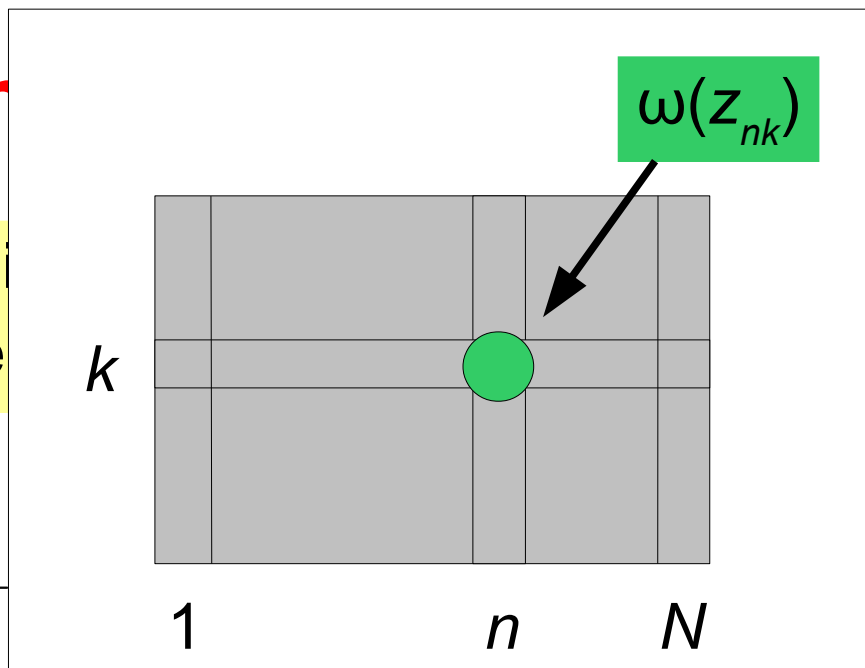
$$\omega(\mathbf{z}_n) \equiv \max_{\mathbf{z}_1, \dots, \mathbf{z}_{n-1}} p(\mathbf{x}_n | \mathbf{z}_n)$$

Recursion:

$$\omega(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \max_{\mathbf{z}_{n-1}} \omega(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1})$$

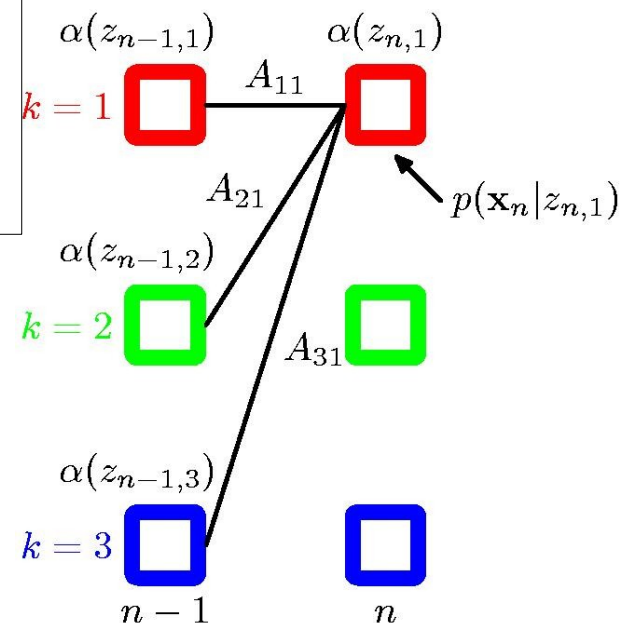
Basis:

$$\omega(\mathbf{z}_1) = p(\mathbf{x}_1, \mathbf{z}_1) = p(\mathbf{z}_1) p(\mathbf{x}_1 | \mathbf{z}_1) = \prod_{k=1}^K \{\pi_k p(\mathbf{x}_1 | \phi_k)\}^{z_{1k}}$$



m

of states $\mathbf{z}_1, \dots, \mathbf{z}_n$



Takes time $O(K^2N)$ and space $O(KN)$ using memorization

Th

$\omega(\mathbf{z}_n)$ is the probability of generating the observation \mathbf{x}_n given the hidden states $\mathbf{z}_1, \dots, \mathbf{z}_n$

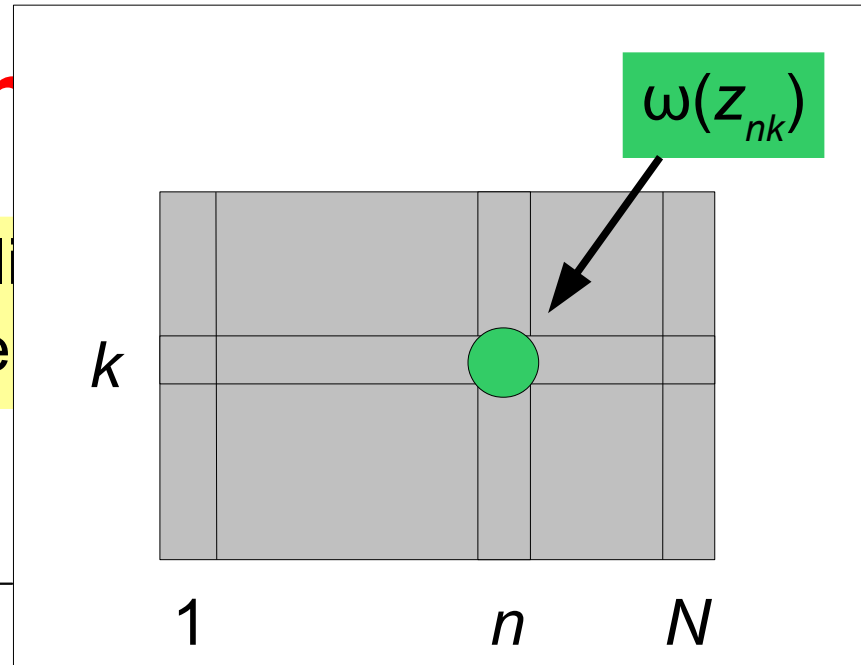
$$\omega(\mathbf{z}_n) \equiv \max_{\mathbf{z}_1, \dots, \mathbf{z}_{n-1}} p(\mathbf{x}_n | \mathbf{z}_n)$$

Recursion:

$$\omega(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \max_{\mathbf{z}_{n-1}} \omega(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1})$$

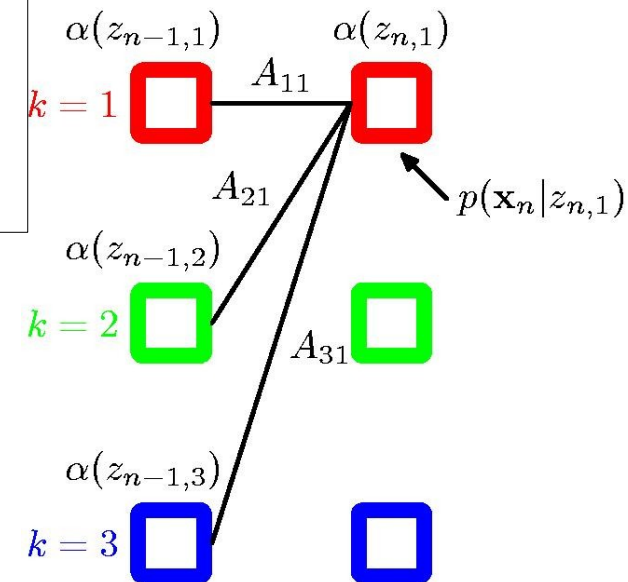
Basis:

Problem: The values $\omega(\mathbf{z}_{nk})$ can come very close to zero, by multiplying them we potentially exceed the precision of double precision floating points



m

of states $\mathbf{z}_1, \dots, \mathbf{z}_n$



Takes time $O(K^2N)$ and space $O(KN)$ using memorization

Th

m

$\omega(\mathbf{z}_n)$ is the probability of states $\mathbf{z}_1, \dots, \mathbf{z}_n$ generating the observation \mathbf{x}_n

of states $\mathbf{z}_1, \dots, \mathbf{z}_n$

$$\omega(\mathbf{z}_n) \equiv \max_{\mathbf{z}_1, \dots, \mathbf{z}_{n-1}} p(\mathbf{x}_n | \mathbf{z}_n) \omega(\mathbf{z}_{n-1})$$

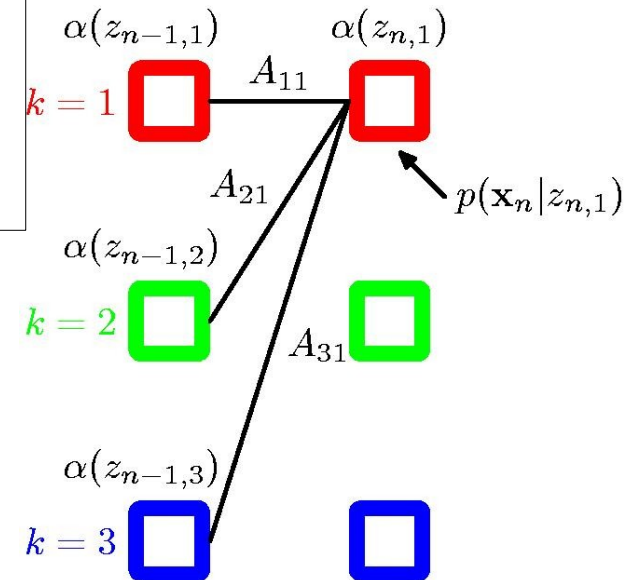
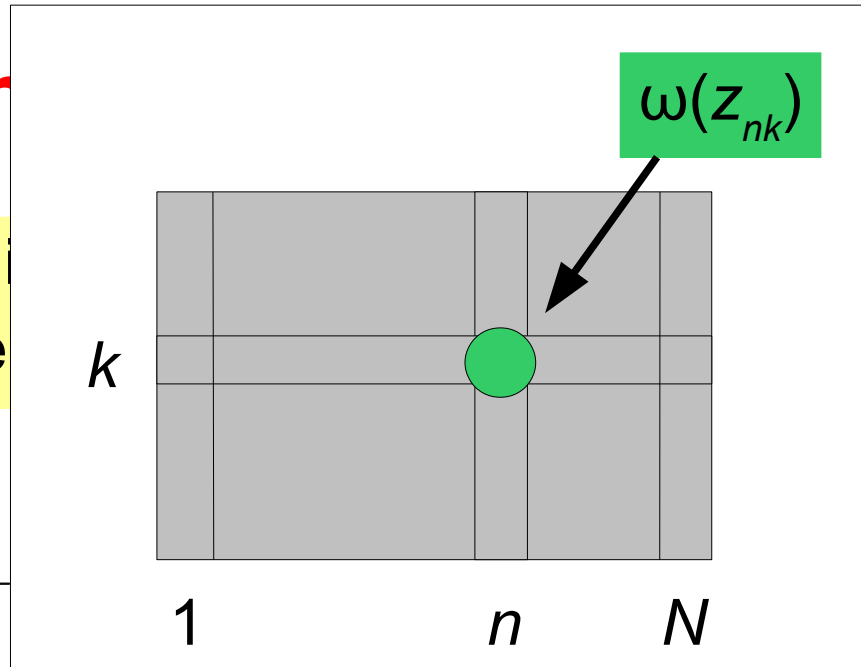
Recursion:

$$\omega(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \max_{\mathbf{z}_{n-1}} \omega(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1})$$

Basis:

Problem: The values $\omega(z_{nk})$ can come very close to zero, by multiplying them we potentially exceed the precision of double precision floating points

Solution: Because $\log(\max f) = \max \log f$, we can work in “log-space” which turns multiplications into additions ...



The Viterbi Algorithm in log-space

$\omega(\mathbf{z}_n)$ is the probability of the most likely sequence of states $\mathbf{z}_1, \dots, \mathbf{z}_n$ generating the observations $\mathbf{x}_1, \dots, \mathbf{x}_n$

$$\log \omega(\mathbf{z}_n) = \max_{\mathbf{z}_1, \dots, \mathbf{z}_{n-1}} \log p(\mathbf{x}_1, \dots, \mathbf{x}_n, \mathbf{z}_1, \dots, \mathbf{z}_n)$$

Recursion:

$$\log \omega(\mathbf{z}_n) = \log p(\mathbf{x}_n | \mathbf{z}_n) + \max_{\mathbf{z}_{n-1}} (\log \omega(\mathbf{z}_{n-1}) + \log p(\mathbf{z}_n | \mathbf{z}_{n-1}))$$

$$\hat{\omega}(\mathbf{z}_n) = \log p(\mathbf{x}_n | \mathbf{z}_n) + \max_{\mathbf{z}_{n-1}} (\hat{\omega}(\mathbf{z}_{n-1}) + \log p(\mathbf{z}_n | \mathbf{z}_{n-1}))$$

Basis:

$$\hat{\omega}(\mathbf{z}_1) = \log \prod_{k=1}^K \{\pi_k p(\mathbf{x}_1 | \phi_k)\}^{z_{1k}} = \sum_{k=1}^K z_{1k} (\log \pi_k + \log p(\mathbf{x}_1 | \phi_k))$$

The Viterbi algorithm in log-space

$\omega(\mathbf{z}_n)$ is the probability of generating the sequence of states \mathbf{z}_n

$$\log \omega(\mathbf{z}_n) = \sum_{k=1}^K \log \omega(\mathbf{z}_n) = \sum_{k=1}^K \log p(\mathbf{x}_n | \mathbf{z}_n) + \max_{\mathbf{z}_{n-1}} (\log \omega(\mathbf{z}_{n-1}) + \log p(\mathbf{z}_n | \mathbf{z}_{n-1}))$$

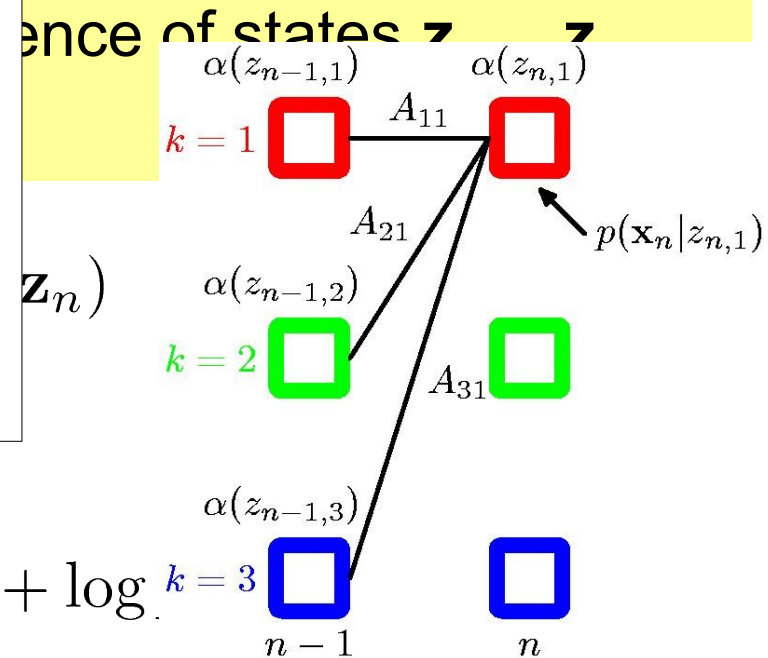
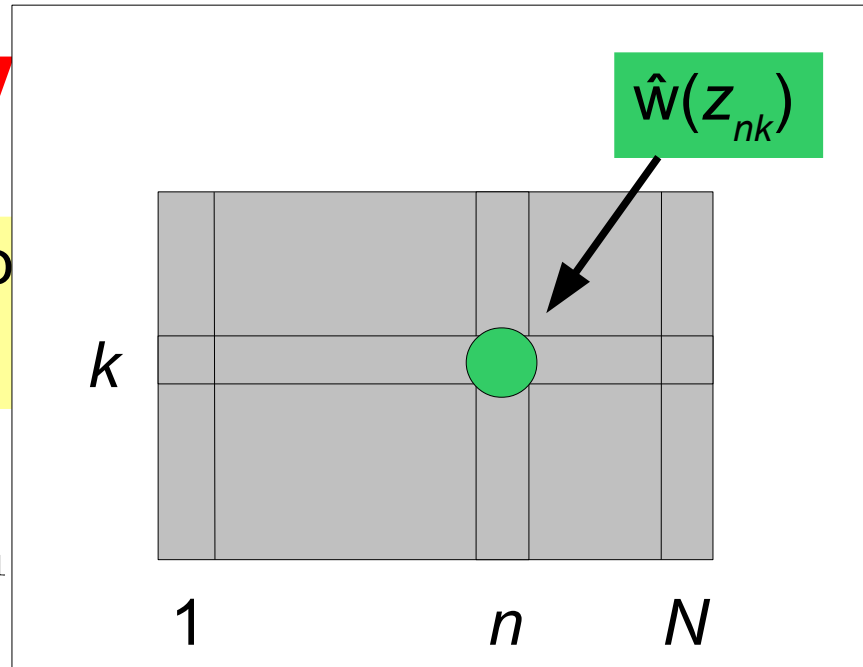
Recursion:

$$\log \omega(\mathbf{z}_n) = \log p(\mathbf{x}_n | \mathbf{z}_n) + \max_{\mathbf{z}_{n-1}} (\log \omega(\mathbf{z}_{n-1}) + \log p(\mathbf{z}_n | \mathbf{z}_{n-1}))$$

$$\hat{\omega}(\mathbf{z}_n) = \log p(\mathbf{x}_n | \mathbf{z}_n) + \max_{\mathbf{z}_{n-1}} (\hat{\omega}(\mathbf{z}_{n-1}) + \log p(\mathbf{z}_n | \mathbf{z}_{n-1}))$$

Basis:

$$\hat{\omega}(\mathbf{z}_1) = \log \prod_{k=1}^K \{\pi_k p(\mathbf{x}_1 | \phi_k)\}^{z_{1k}} = \sum_{k=1}^K z_{1k} (\log \pi_k + \log p(\mathbf{x}_1 | \phi_k))$$



The Viterbi algorithm in log-space

$\omega(\mathbf{z}_n)$ is the probability of generating the sequence of states \mathbf{z}_n

$$\log \omega(\mathbf{z}_n) = \sum_{k=1}^K \log \omega(\mathbf{z}_n^{(k)})$$

Recursion:

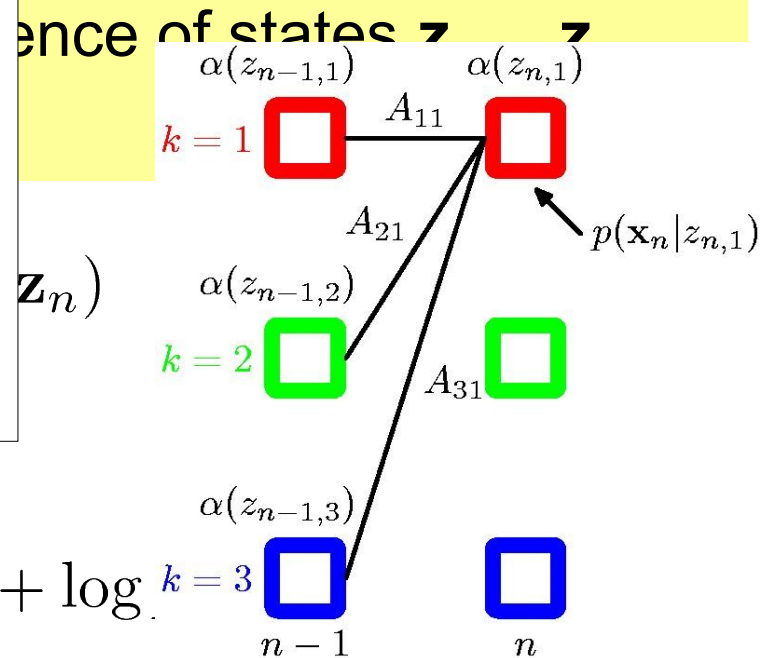
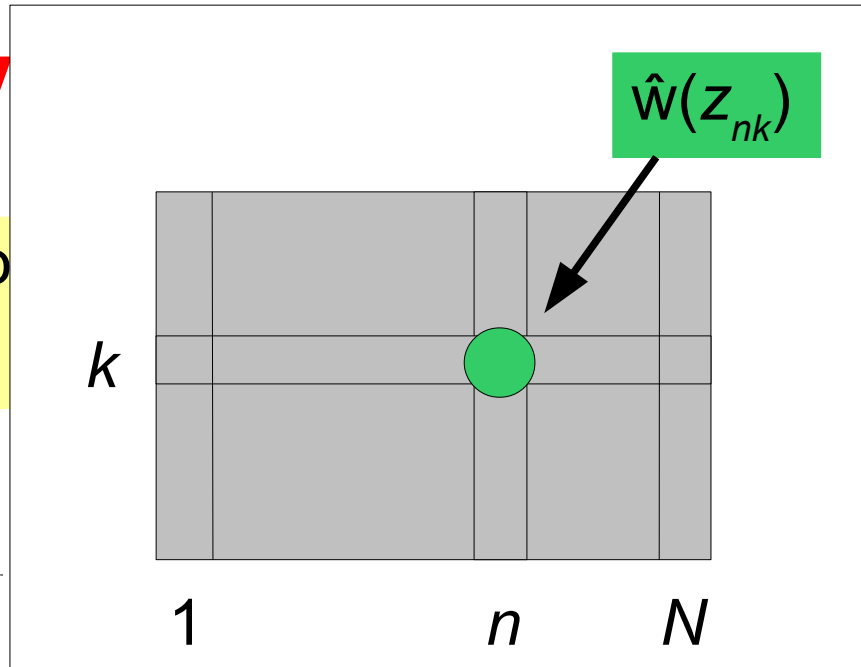
$$\log \omega(\mathbf{z}_n) = \log p(\mathbf{x}_n | \mathbf{z}_n) + \max_{\mathbf{z}_{n-1}} (\log \omega(\mathbf{z}_{n-1}) + \log p(\mathbf{z}_n | \mathbf{z}_{n-1}))$$

$$\hat{\omega}(\mathbf{z}_n) = \log p(\mathbf{x}_n | \mathbf{z}_n) + \max_{\mathbf{z}_{n-1}} (\hat{\omega}(\mathbf{z}_{n-1}) + \log p(\mathbf{z}_n | \mathbf{z}_{n-1}))$$

Basis:

$$\hat{\omega}(\mathbf{z}_n) = \log \prod_{k=1}^K \pi_{1k} p(\mathbf{x}_1 | \phi_{1k}) + \sum_{k=1}^K z_{1k} (\log \pi_{1k} + \log p(\mathbf{x}_1 | \phi_{1k}))$$

Still takes time $O(K^2N)$ and space $O(KN)$ using memorization, and the most likely sequence of states can be found by *backtracking*



Backtracking

Pseudocode for backtracking not using log-space:

```
z[1..N] = undef
z[N] = arg maxk ω[k][N]
for n = N-1 to 1:
    z[n] = arg maxk ( p(x[n+1] | z[n+1]) * ω[k][n] * p(z[n+1] | k) )
print z[1..N]
```

Pseudocode for backtracking using log-space:

```
z[1..N] = undef
z[N] = arg maxk ω^[k][N]
for n = N-1 to 1:
    z[n] = arg maxk ( log p(x[n+1] | z[n+1]) + ω^[k][n] + log p(z[n+1] | k) )
print z[1..N]
```

Takes time $O(NK)$ but requires the entire ω - or ω^{\wedge} -table in memory

A problem with “log-space”?

$$\omega(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \max_{\mathbf{z}_{n-1}} \omega(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1})$$

$$\hat{\omega}(\mathbf{z}_n) = \log p(\mathbf{x}_n | \mathbf{z}_n) + \max_{\mathbf{z}_{n-1}} (\hat{\omega}(\mathbf{z}_{n-1}) + \log p(\mathbf{z}_n | \mathbf{z}_{n-1}))$$

What if $p(\mathbf{x}_n | \mathbf{z}_n)$ or $p(\mathbf{z}_n | \mathbf{z}_{n-1})$ is 0? Then the product of probabilities becomes 0, but what should it be in log-space?

A problem with “log-space”?

$$\omega(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \max_{\mathbf{z}_{n-1}} \omega(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1})$$

$$\hat{\omega}(\mathbf{z}_n) = \log p(\mathbf{x}_n | \mathbf{z}_n) + \max_{\mathbf{z}_{n-1}} (\hat{\omega}(\mathbf{z}_{n-1}) + \log p(\mathbf{z}_n | \mathbf{z}_{n-1}))$$

What if $p(\mathbf{x}_n | \mathbf{z}_n)$ or $p(\mathbf{z}_n | \mathbf{z}_{n-1})$ is 0? Then the product of probabilities becomes 0, but what should it be in log-space?

It should be some representation of “minus infinity”

```
// Pseudo code for computing  $w^k[n]$  for some  $n > 1$ 
```

```
 $w^n[k] = \text{undef}$ 
```

```
if  $p(x[n] | k) \neq 0$ :
```

```
  for  $j = 1$  to  $K$ :
```

```
    if  $p(k | j) \neq 0$ :
```

```
       $w^n[k] = \max(w^k[n], \log(p(x[n] | k)) + w^j[j][n-1] + \log(p(k | j)))$ 
```

The Forward Algorithm

$\alpha(\mathbf{z}_n)$ is the joint probability of observing $\mathbf{x}_1, \dots, \mathbf{x}_n$ and being in state \mathbf{z}_n

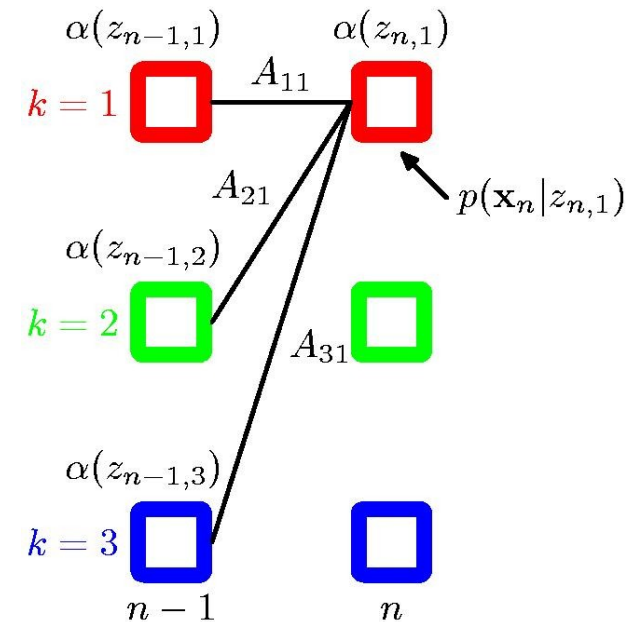
$$\alpha(\mathbf{z}_n) \equiv p(\mathbf{x}_1, \dots, \mathbf{x}_n, \mathbf{z}_n)$$

Recursion:

$$\alpha(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \sum_{\mathbf{z}_{n-1}} \alpha(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1})$$

Basis:

$$\alpha(\mathbf{z}_1) = p(\mathbf{x}_1, \mathbf{z}_1) = p(\mathbf{z}_1) p(\mathbf{x}_1 | \mathbf{z}_1) = \prod_{k=1}^K \{ \pi_k p(\mathbf{x}_1 | \phi_k) \}^{z_{1k}}$$



Takes time $O(K^2N)$ and space $O(KN)$ using memorization

The Forward Algorithm

$\alpha(\mathbf{z}_n)$ is the joint prob

of being in state \mathbf{z}_n

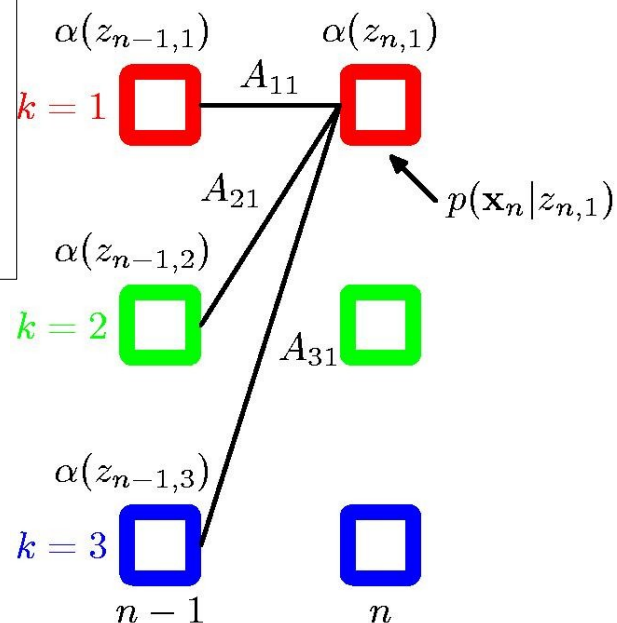
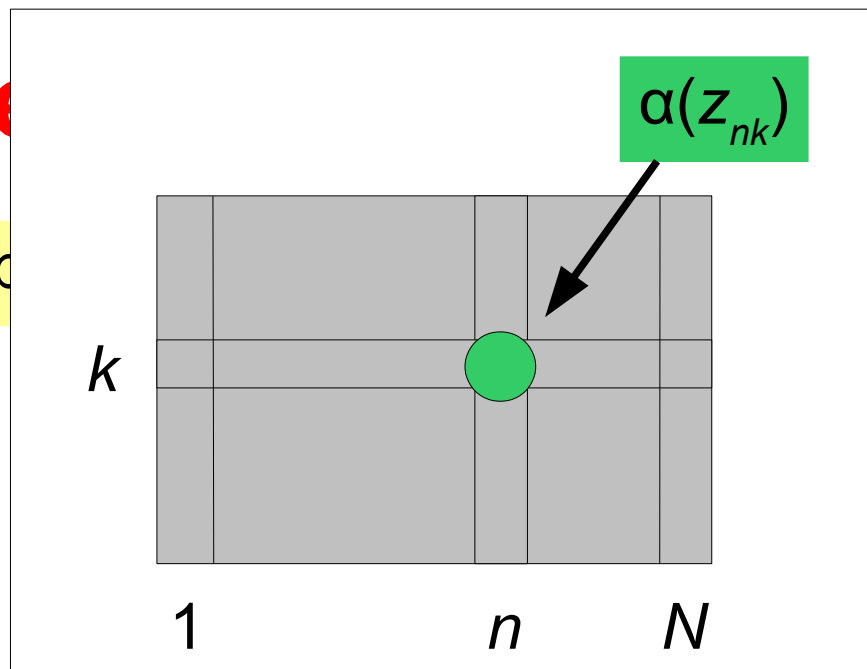
$$\alpha(\mathbf{z}_n) \equiv p(\mathbf{x}_1, \dots, \mathbf{x}_n | \mathbf{z}_n)$$

Recursion:

$$\alpha(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \sum_{\mathbf{z}_{n-1}} \alpha(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1})$$

Basis:

$$\alpha(\mathbf{z}_1) = p(\mathbf{x}_1, \mathbf{z}_1) = p(\mathbf{z}_1) p(\mathbf{x}_1 | \mathbf{z}_1) = \prod_{k=1}^K \{\pi_k p(\mathbf{x}_1 | \phi_k)\}^{z_{1k}}$$



Takes time $O(K^2N)$ and space $O(KN)$ using memorization

The

hm

$\alpha(\mathbf{z}_n)$ is the joint prob

d being in state \mathbf{z}_n

$$\alpha(\mathbf{z}_n) \equiv p(\mathbf{x}_1, \dots)$$

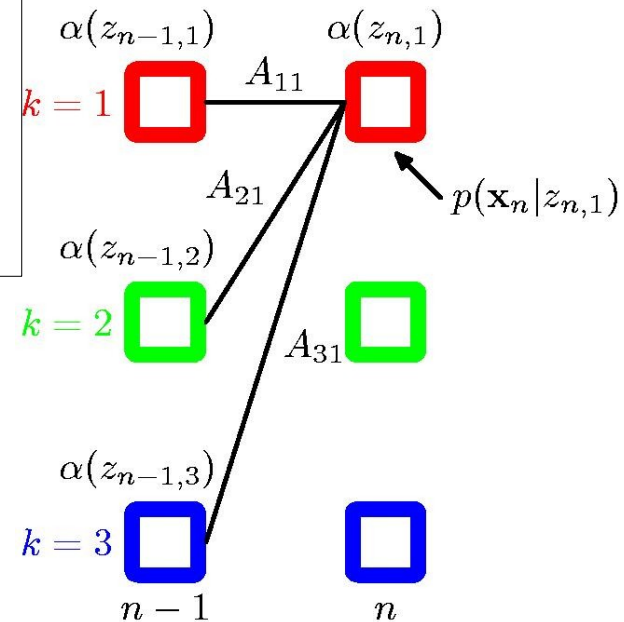
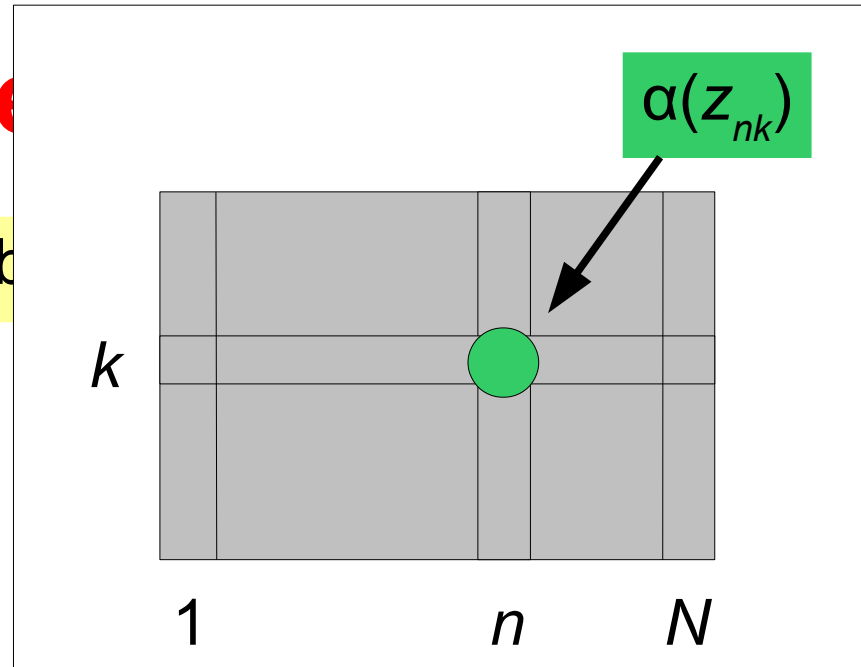
Recursion:

$$\alpha(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \sum_{\mathbf{z}_{n-1}} \alpha(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1})$$

Basis:

Problem: The values $\alpha(\mathbf{z}_{nk})$ can come very close to zero, by multiplying them we potentially exceed the precision of double precision floating points

Another problem: Because $\log(\sum f) \neq \sum(\log f)$, we cannot use the “log-space” trick ...



Forward algorithm using scaled values

$\alpha(\mathbf{z}_n)$ is the joint probability of observing $\mathbf{x}_1, \dots, \mathbf{x}_n$ and being in state \mathbf{z}_n

$$\alpha(\mathbf{z}_n) = p(\mathbf{x}_1, \dots, \mathbf{x}_n, \mathbf{z}_n) = p(\mathbf{x}_1, \dots, \mathbf{x}_n) p(\mathbf{z}_n | \mathbf{x}_1, \dots, \mathbf{x}_n)$$

$$\hat{\alpha}(\mathbf{z}_n) = p(\mathbf{z}_n | \mathbf{x}_1, \dots, \mathbf{x}_n) = \frac{\alpha(\mathbf{z}_n)}{p(\mathbf{x}_1, \dots, \mathbf{x}_n)} = \frac{\alpha(\mathbf{z}_n)}{\prod_{m=1}^n c_m}$$

$$c_n = p(\mathbf{x}_n | \mathbf{x}_1, \dots, \mathbf{x}_{n-1}) \quad p(\mathbf{x}_1, \dots, \mathbf{x}_n) = \prod_{m=1}^n c_m$$

This “normalized version” $\hat{\alpha}(\mathbf{z}_n)$ is a probability distribution over K variables, and we expect it to “behave numerically well” because

$$\sum_{k=1}^K \hat{\alpha}(z_{nk}) = 1$$

The normalized values can not all become arbitrary small ...

Forward algorithm using scaled values

We can modify the forward-recursion to use scaled values

$$\alpha(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \sum_{\mathbf{z}_{n-1}} \alpha(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1}) \Leftrightarrow$$

$$\left(\prod_{m=1}^n c_m \right) \hat{\alpha}(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \sum_{\mathbf{z}_{n-1}} \left(\prod_{m=1}^{n-1} c_m \right) \hat{\alpha}(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1}) \Leftrightarrow$$

$$c_n \hat{\alpha}(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \sum_{\mathbf{z}_{n-1}} \hat{\alpha}(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1})$$

$$\alpha(\mathbf{z}_n) = \left(\prod_{m=1}^n c_m \right) \hat{\alpha}(\mathbf{z}_n)$$

Forward algorithm using scaled values

We can modify the forward-recursion to use scaled values

$$\alpha(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \sum_{\mathbf{z}_{n-1}} \alpha(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1}) \Leftrightarrow$$

$$\left(\prod_{m=1}^n c_m \right) \hat{\alpha}(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \sum_{\mathbf{z}_{n-1}} \left(\prod_{m=1}^{n-1} c_m \right) \hat{\alpha}(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1}) \Leftrightarrow$$

$$c_n \hat{\alpha}(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \sum_{\mathbf{z}_{n-1}} \hat{\alpha}(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1})$$

If we know c_n then we have a recursion using the normalized values

$$\alpha(\mathbf{z}_n) = \left(\prod_{m=1}^n c_m \right) \hat{\alpha}(\mathbf{z}_n)$$

Forward algorithm using scaled values

We can modify the forward-recursion to use scaled values

$$\alpha(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \sum_{\mathbf{z}_{n-1}} \alpha(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1}) \Leftrightarrow$$

$$\left(\prod_{m=1}^n c_m \right) \hat{\alpha}(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \sum_{\mathbf{z}_{n-1}} \left(\prod_{m=1}^{n-1} c_m \right) \hat{\alpha}(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1}) \Leftrightarrow$$

$$c_n \hat{\alpha}(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \sum_{\mathbf{z}_{n-1}} \hat{\alpha}(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1})$$

If we know c_n then we have a recursion using the normalized values

$$\sum_{k=1}^K c_n \hat{\alpha}(z_{nk}) = c_n \sum_{k=1}^K \hat{\alpha}(z_{nk}) = c_n \cdot 1$$

$$\alpha(\mathbf{z}_n) = \left(\prod_{m=1}^n c_m \right) \hat{\alpha}(\mathbf{z}_n)$$

Forward algorithm using scaled values

We can modify the forward-recursion to use scaled values

Recursion:

In step n compute and store temporarily the K values $\delta(z_{n1}), \dots, \delta(z_{nK})$

$$\delta(\mathbf{z}_n) = c_n \hat{\alpha}(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \sum_{\mathbf{z}_{n-1}} \hat{\alpha}(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1})$$

Compute and store c_n as

$$\sum_{k=1}^K \delta(z_{nk}) = \sum_{k=1}^K c_n \hat{\alpha}(z_{nk}) = c_n \sum_{k=1}^K \hat{\alpha}(z_{nk}) = c_n$$

Compute and store $\hat{\alpha}(z_{nk}) = \delta(z_{nk}) / c_n$

Forward algorithm using

We can modify the forward-recursion to

Recursion:

In step n compute and store temporarily

$$\delta(\mathbf{z}_n) = c_n \hat{\alpha}(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \sum_{\mathbf{z}_{n-1}} \hat{\alpha}(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1})$$

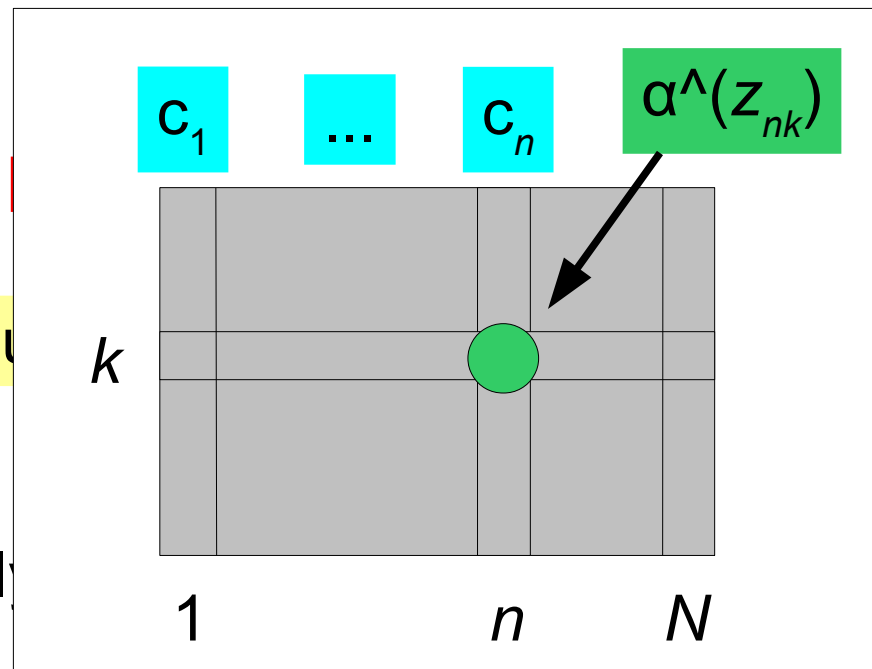
Compute and store c_n as

$$\sum_{k=1}^K \delta(z_{nk}) = \sum_{k=1}^K c_n \hat{\alpha}(z_{nk}) = c_n \sum_{k=1}^K \hat{\alpha}(z_{nk}) = c_n$$

Compute and store $\hat{\alpha}(z_{nk}) = \delta(z_{nk}) / c_n$

Basis:

$$\hat{\alpha}(\mathbf{z}_1) = \frac{\alpha(\mathbf{z}_1)}{c_1} \quad c_1 = p(\mathbf{x}_1) = \sum_{\mathbf{z}_1} p(\mathbf{z}_1) p(\mathbf{x}_1 | \mathbf{z}_1) = \sum_{k=1}^K \pi_k p(\mathbf{x}_1 | \phi_k)$$



Forward algorithm using

We can modify the forward-recursion to

Recursion:

In step n compute and store temporarily

$$\delta(\mathbf{z}_n) = c_n \hat{\alpha}(\mathbf{z}_n) = p(\mathbf{x}_n | \mathbf{z}_n) \sum_{\mathbf{z}_{n-1}} \hat{\alpha}(\mathbf{z}_{n-1}) p(\mathbf{z}_n | \mathbf{z}_{n-1})$$

Compute and store c_n as

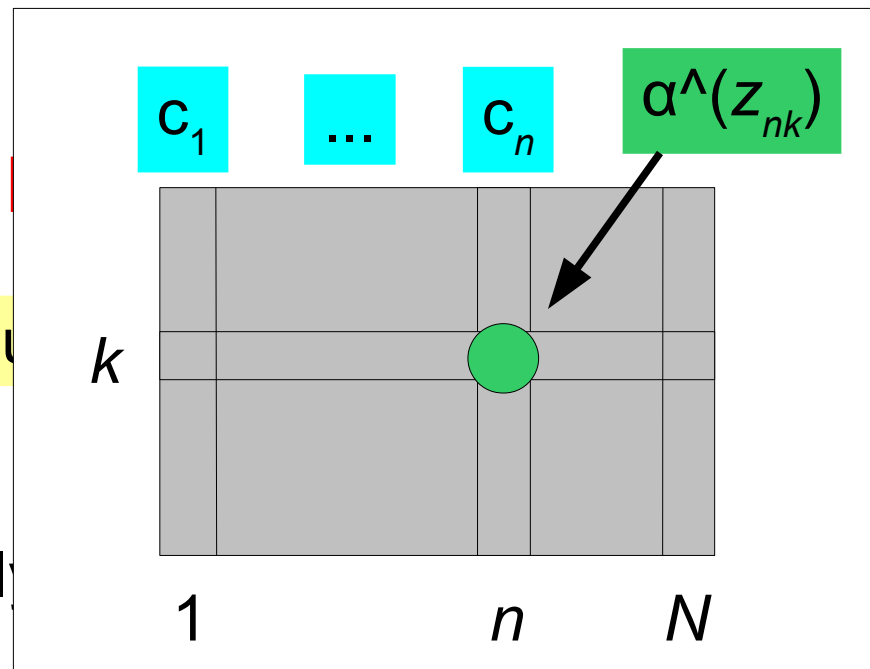
$$\sum_{k=1}^K \delta(z_{nk}) = \sum_{k=1}^K c_n \hat{\alpha}(z_{nk}) = c_n \sum_{k=1}^K \hat{\alpha}(z_{nk}) = c_n$$

Compute and store $\hat{\alpha}(z_{nk}) = \delta(z_{nk}) / c_n$

Basis:

$$\hat{\alpha}(\mathbf{z}_1) = \frac{\alpha(\mathbf{z}_1)}{c_1}$$

$$c_1 = p(\mathbf{x}_1) = \sum_{\mathbf{z}_1} p(\mathbf{z}_1) p(\mathbf{x}_1 | \mathbf{z}_1) = \sum_{k=1}^K \pi_k p(\mathbf{x}_1 | \phi_k)$$



Takes time $O(K^2N)$ and space $O(KN)$ using memorization

The Backward Algorithm

$\beta(\mathbf{z}_n)$ is the conditional probability of future observation $\mathbf{x}_{n+1}, \dots, \mathbf{x}_N$ assuming being in state \mathbf{z}_n

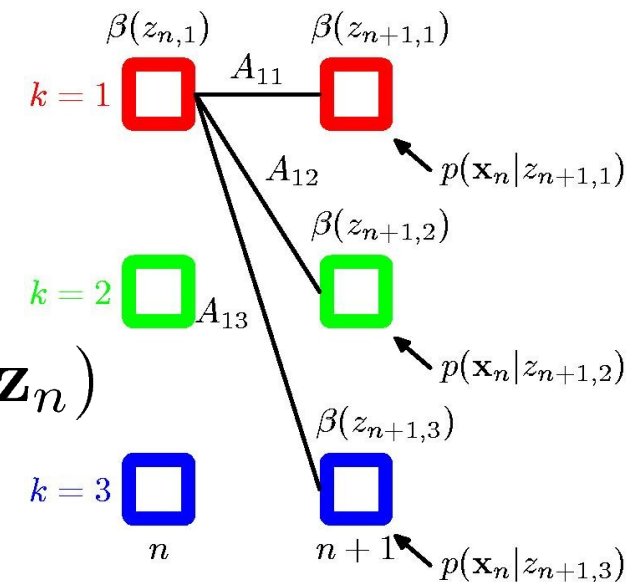
$$\beta(\mathbf{z}_n) \equiv p(\mathbf{x}_{n+1}, \dots, \mathbf{x}_N | \mathbf{z}_n)$$

Recursion:

$$\beta(\mathbf{z}_n) = \sum_{\mathbf{z}_{n+1}} \beta(\mathbf{z}_{n+1}) p(\mathbf{x}_{n+1} | \mathbf{z}_{n+1}) p(\mathbf{z}_{n+1} | \mathbf{z}_n)$$

Basis:

$$\beta(\mathbf{z}_N) = 1$$



Takes time $O(K^2N)$ and space $O(KN)$ using memorization

Backward algorithm using scaled values

We can modify the backward-recursion to use scaled values

Recursion:

In step n compute and store temporarily the K values $\epsilon(z_{n1}), \dots, \epsilon(z_{nK})$

$$\epsilon(\mathbf{z}_n) = c_{n+1} \hat{\beta}(\mathbf{z}_n) = \sum_{\mathbf{z}_{n+1}} \hat{\beta}(\mathbf{z}_{n+1}) p(\mathbf{x}_{n+1} | \mathbf{z}_{n+1}) p(\mathbf{z}_{n+1} | \mathbf{z}_n)$$

Using c_{n+1} computed during the forward-recursion, compute and store

$$\hat{\beta}(z_{nk}) = \epsilon(z_{nk}) / c_{n+1}$$

Basis:

$$\hat{\beta}(\mathbf{z}_N) = 1$$

Backward algorithm us

We can modify the backward-recursion to

Recursion:

In step n compute and store temporarily

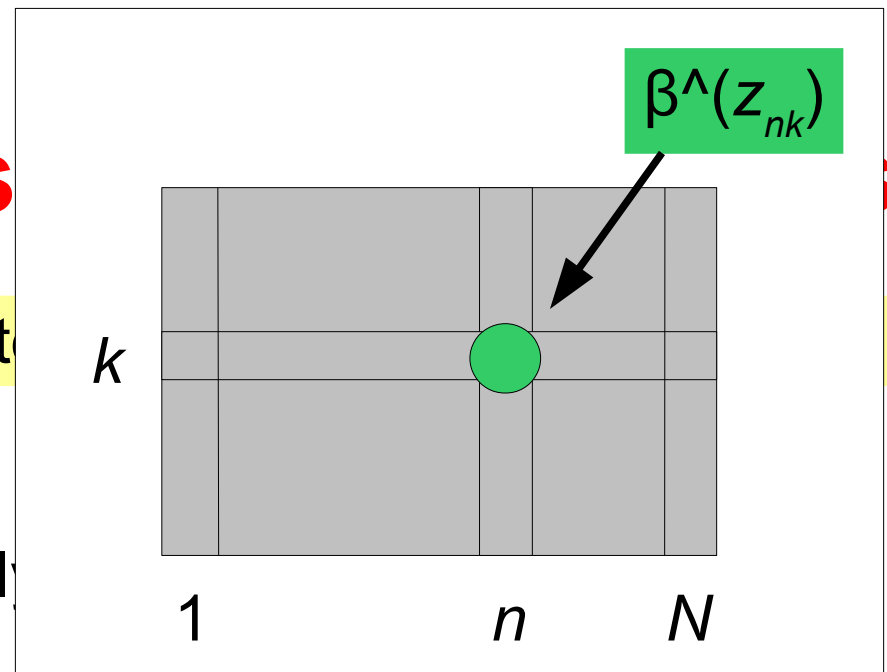
$$\epsilon(\mathbf{z}_n) = c_{n+1} \hat{\beta}(\mathbf{z}_n) = \sum_{\mathbf{z}_{n+1}} \hat{\beta}(\mathbf{z}_{n+1}) p(\mathbf{x}_{n+1} | \mathbf{z}_{n+1}) p(\mathbf{z}_{n+1} | \mathbf{z}_n)$$

Using c_{n+1} computed during the forward-recursion, compute and store

$$\hat{\beta}(z_{nk}) = \epsilon(z_{nk}) / c_{n+1}$$

Basis:

$$\hat{\beta}(\mathbf{z}_N) = 1$$



Takes time $O(K^2N)$ and space $O(KN)$ using memorization