Assignment # 2

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COMP 352 - Data Structures and Algorithms

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Question #1:

a) Time complexity follows $O(n^2)$ and $\Omega(n)$. The $O(n^2)$ comes from the tail recursion nesting the 2 while loop that goes through all n elements. This means that the time complexity would be $O(n^2)$. The best time $\Omega(n)$, would be if the array is already sorted, in this case done would never be set to false and we would skip the recursion and only return the array. This would give us $\Omega(n)$.

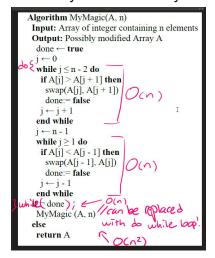


Figure 1: Steps for Question 1a

- b) The resulting array will be (2, 3, 5, 9, 11).
- c) The resulting array will be sorted from least to greatest
- d) The runtime on this particular algorithm cannot be improved easily. It would require writing a completely new algorithm. Small changes can still be made. Like for example: Checking to see if done is true from the last while loop before entering the second while loop.
- e) MyMagic does have tail recursion which should be converted to a do while loop to save on space.

Question #2:

- i) Ω f grows at least as fast as g (n*log n + n^3 > log(n))
- ii) O f grows no faster than g ($log n^2 < log n$)
- iii) Ω f grows at least as fast as g (n^3 > log n)
- iv) Ω f grows at least as fast as g (n³/2 > log n²)
- v) Ω f grows at least as fast as g (10ⁿ > n²)
- vi) O f grows no faster than g (n! < n^n)
- vii) Ω f grows at least as fast as g (log^2n > log n)
- viii) Ω f grows at least as fast as g (n > log n)
- xi) Ω f grows at least as fast as g ($n^1/2 > \log n$)
- x) O f grows no faster than g ($2^n < 3^n$)
- xi) O f grows no faster than $g(2^n < n^n)$

My Mugic (A, 11)

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Question #3:

MagicBoard Version 1 (Recursive):

Main Class in Pseudocode:

```
Main

void main(args)
    Board board ← new Board()
    gameLoop(board)

void gameLoop(board)
    board.displayBoard()
    board.getInput()
    if !board.checkWin() then
        gameLoop(board)
    else
        Print("YOU HAVE WON!!!!")
```

Board Class in Pseudocode: (Game Implementation)

```
Board
  Board()
      d ← RandomNumber(0 to 25)
       checkerboard ← ArrayList<>(d * d)
       fillBoard(∅)
       location ← 0
       moves ← 0
      Node val ← SolveNew(Node(null, 0, checkerboard.get(location)),
null, ArrayList<>())
       Print(val == null ? "No path" : "Has path")
       displayBoard()
  displayBoard(i, loc)
           Print("\t" + ">" + checkerboard.get(i \leftarrow i + 1))
           Print("\t" + checkerboard.get(i ← i + 1))
       if i mod d == 0 then
           Print("\n")
       if i < size then
           displayBoard(i, loc)
```

```
getInput()
    Print("Which Direction would you like to go in?")
    input ← GetUserInput()
    switch input
        case "North" -> move(Direction.North)
        case "South" -> move(Direction.South)
        case "East" -> move(Direction.East)
        case "West" -> move(Direction.West)
fillBoard(i)
    checkerboard.add(1 + RandomNumber(d - 1))
    if i < size then</pre>
        fillBoard(i)
        targetLocation ← 1 + RandomNumber(size - 1)
        checkerboard.set(targetLocation, ∅)
        return
checkWin()
    return checkerboard.get(location) == 0
validateMove(dir, oldLocation, newLocation)
    if newLocation < 0 OR newLocation > size - 1 then
        return false
    else if dir == Direction.East OR dir == Direction.West then
        one = (oldLocation + 1) / d
        two = (newLocation) / d
        if one != two then
            return false
    return true
move(dir)
    steps ← checkerboard.get(location)
    switch (dir)
        case North:
            steps ← steps * -d
            break
        case South:
            steps ← steps * d
            break
        case East:
            break
        case West:
            steps ← steps * -1
            break
    newLocation ← location + steps
    if !validateMove(dir, location, newLocation) then
        return
```

```
location ← newLocation
moves ← moves + 1
checkWin()
```

Programming Part for Solution 1 in Pseudocode:

```
displayPath(n)
    if n == null if return
    displayBoard(∅, n.Position)
    displayPath(n.ParentNode)
displayBoard()
    printBorder()
    Print("Current Moves: " + moves)
    displayBoard(∅, location)
    printBorder()
SolveNew(n, lastMove, posList)
    value ← n.Value
    if value == 0 then
    solvable ← true
    return n
    posList.add(n.Position)
    canGoWest ← lastMove != Direction.East
AND fakeMove(Direction.West, n.Position) > -1
 AND !posList.contains(fakeMove(Direction.West, n.Position))
    canGoEast ← lastMove != Direction.West
 AND fakeMove(Direction.East, n.Position) > -1
 AND !posList.contains(fakeMove(Direction.East, n.Position))
    canGoNorth ← lastMove != Direction.South
AND fakeMove(Direction.North, n.Position) > -1
 AND !posList.contains(fakeMove(Direction.North, n.Position))
    canGoSouth = lastMove != Direction.North
AND fakeMove(Direction.South, n.Position) > -1
 AND !posList.contains(fakeMove(Direction.South, n.Position))
    if canGoWest then
        westPos ← fakeMove(Direction.West, n.Position)
        westVal ← checkerboard.get(westPos)
        n.WestChild \leftarrow Node(n, westPos, westVal)
        node ← SolveNew(n.WestChild, Direction.West, ArrayList<>(posList))
        if node != null then return node
```

```
canGoWest = false
    if canGoEast then
        eastPos ← fakeMove(Direction.East, n.Position)
        eastVal ← checkerboard.get(eastPos)
        n.EastChild ← new Node(n, eastPos, eastVal)
        node = SolveNew(n.EastChild, Direction.East, ArrayList<>(posList))
        if node != null then return node
        else
            canGoEast = false
    if canGoNorth then
        northPos ← fakeMove(Direction.North, n.Position)
        northVal ← checkerboard.get(northPos)
        n.NorthChild ← Node(n, northPos, northVal)
        node ← SolveNew(n.NorthChild, Direction.North, ArrayList<>(posList))
        if (node != null then return node
            canGoNorth = false
    if canGoSouth then
        southPos ← fakeMove(Direction.South, n.Position)
        southVal ← checkerboard.get(southPos)
        n.SouthChild ← Node(n, southPos, southVal)
        node ← SolveNew(n.SouthChild, Direction.South, ArrayList<>(posList))
        if node != null then return node
        else
            canGoSouth ← false
    if !canGoWest && !canGoEast && !canGoNorth && !canGoSouth then
        return null
    return null
fakeMove(dir, location)
    steps ← checkerboard.get( location)
    switch (dir)
        case North:
            steps ← steps * -d
            break
        case South:
            steps ← steps * d
            break
        case East:
            break
        case West:
            steps \leftarrow steps * -1
            break
    newLocation ← location + steps
    if !validateMove(dir, _location, newLocation) then
        return -1
    checkWin()
```

Node Class for Solution 1 in Pseudocode:

```
Node

Node ParentNode ← null

Node WestChild ← null

Node EastChild ← null

Node NorthChild ← null

Node SouthChild ← null

Value

Position

Node(parentNode, position, value)

ParentNode ← parentNode

Position ← position

Value ← value
```

MagicBoard Version 2 (Iterative):

Solution Method:

```
solve()

tree.push(startNode)

value ← startNode.Value

if value == 0 then
    solvable ← true
    return

while(!solvable) then
    if tree.isEmpty() then
        return

n = tree.peek()
    fakeMoveIndex ← fakeMove(Direction.South, n.Position)

if fakeMoveIndex > -1 && (n.lastDir == null
    || n.lastDir.getVal() < Direction.South.getVal())</pre>
```

```
&& ! n.Path.contains(fakeMoveIndex)) then
           southPos \leftarrow fakeMoveIndex
           southVal ← checkerboard.get(southPos)
           n.SouthChild ← Node(n, southPos, southVal,
new ArrayList<>(n.Path))
           n.lastDir ← Direction.South
           tree.push(n.SouthChild)
           if southVal == 0 then
               solvable ← true
               break
           continue
       fakeMoveIndex ← fakeMove(Direction.West, n.Position)
       if fakeMoveIndex > -1 && !n.Path.contains(fakeMoveIndex)
    && (n.lastDir == null || n.lastDir.getVal() < Direction.West.getVal()) then
           westPos ← fakeMoveIndex
           westVal ← checkerboard.get(westPos)
           n.WestChild ← Node(n, westPos, westVal, ArrayList<>(n.Path))
           n.lastDir ← Direction.West
           tree.push(n.WestChild)
           if westVal == 0 then
               solvable = true
               break
           continue
       fakeMoveIndex = fakeMove(Direction.North, n.Position);
       if (fakeMoveIndex > -1 && !n.Path.contains(fakeMoveIndex)
   && (n.lastDir == null || n.lastDir.getVal() < Direction.North.getVal()))</pre>
           northPos ← fakeMoveIndex
           northVal ← checkerboard.get(northPos)
           n.NorthChild = Node(n, northPos, northVal, ArrayList<>(n.Path))
           n.lastDir = Direction.North;
           tree.push(n.NorthChild);
           if northVal == 0 then
               solvable ← true
               break
           continue
       fakeMoveIndex ← fakeMove(Direction.East, n.Position);
       if fakeMoveIndex > -1 && !n.Path.contains(fakeMoveIndex) && (n.lastDir ==
null || n.lastDir.getVal() < Direction.East.getVal()) then</pre>
```

Node Class

```
Node
   Node ParentNode ← null
   Node WestChild ← null
   Node EastChild \leftarrow null
   Node NorthChild ← null
   Node SouthChild ← null
   ArrayList<Integer> Path;
   Value ← -1
   Position ← -1
   Board.Direction lastDir = null
   Node(parentNode, position, value, pathList)
       ParentNode = parentNode
       Position = position
       Value = value
       Path = pathList
       Path.add(Position)
```

```
a)
Time Complexity of Version 1: O(n^2)
Space Complexity of Version 1: O(n) - from height of tree

Time Complexity of Version 2: O(n^2)
Space Complexity of Version 2: O(n) - from height of tree
```

- b) Tree recursion was the type of recursion that was used for question 1. Tree recursion, tree recursion was used to traverse the tree. Therefore the worst case would be O(n) for this tree traversal. Tail-recursion for version 1 would not be possible because the tree is of degree 4 which means there must be at least 4 calls per call which would not be tail-recursion.
- c) Stacks can be used to create a tree because recursion uses an internal stack to recurse over the tree. Stacks are also much easier to enter and remove from the top since they are O(1) insertion and deletion from top. While queues could have been used with amortization and may achieve O(1) for the most part, in our algorithm we delete from the front many times therefore using a queue would cost us O(n). While a stack would achieve the same thing but in O(1).
- d) Please check "Q3A-20-tests.txt" and "Q3B-20-tests.txt" included in submission
- e) I used an arraylist to store the last positions and checked to see if that position was already visited. If it was visited already then it would skip it. This got rid of loops in the maze that would result in a longer execution or even an infinite loop.