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Smoothing: 

-Use Low Pass Averaging Filter (To eliminate Guassian Noise)

-Use Low Pass Median Filter (To eliminate Salt and Pepper Noise)

Sharpening:

-Use High Pass Filter

```
In [1]: from PIL import Image
        from PIL import ImageFilter
        import cv2
        import math
        import numpy as np
        import matplotlib.pyplot as plt
```

```
In [2]: from google.colab import drive
        drive.mount('/content/drive')
```

Drive already mounted at /content/drive; to attempt to forcibly remount, call drive.mount("/content/drive", force_remount=True).

```
In [3]: img_gaussian_path = '/content/drive/MyDrive/Sem-7/DIP-Lab/SmoothSharp/DIP_3-1.jpg'
```

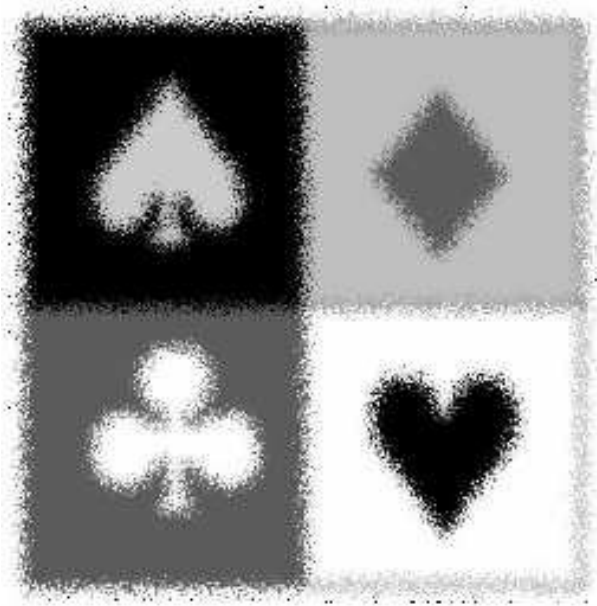
```
In [4]: img_saltpepper_path = '/content/drive/MyDrive/Sem-7/DIP-Lab/SmoothSharp/DIP_3-2.png'
```

```
In [5]: img_sharpening_path = '/content/drive/MyDrive/Sem-7/DIP-Lab/SmoothSharp/DIP_3-3.jpg'
```

Low Pass Averaging Filter

```
In [6]: input_img = Image.open(img_gaussian_path)
input_img
```

Out[6]:



```
In [7]: input_img = input_img.convert('L')
```

```
In [8]: width, height = input_img.size
```

```
In [9]: width
```

Out[9]: 257

```
In [10]: height
```

Out[10]: 257

Mask

```
In [11]: mask = np.array([[1, 1, 1],[1, 1, 1],[1, 1, 1]])  
mask = mask / 9
```

```
In [12]: mask
```

```
Out[12]: array([[0.11111111, 0.11111111, 0.11111111],  
               [0.11111111, 0.11111111, 0.11111111],  
               [0.11111111, 0.11111111, 0.11111111]])
```

Adding Replication Padding to the Input Image

```
In [13]: left = right = top = bottom = 1  
new_width = width + right + left  
new_height = height + top + bottom
```

```
In [14]: new_height  
new_width
```

```
Out[14]: 259
```

Convolve the 3X3 mask over the image

```
In [15]: padded_input_img = Image.new(input_img.mode, (new_width, new_height), (0))  
padded_input_img.paste(input_img, (left, top))
```

```
In [16]: img = np.asarray(padded_input_img)
img
```

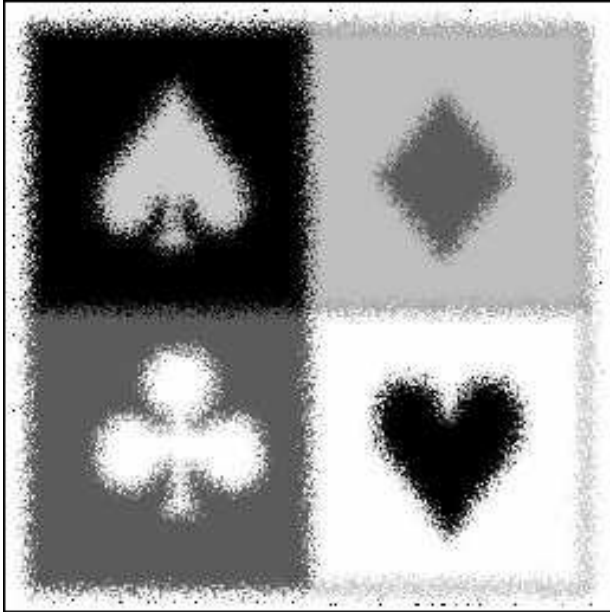
```
Out[16]: array([[ 0,  0,  0, ...,  0,  0,  0],
 [ 0, 254, 254, ..., 255, 254,  0],
 [ 0, 254, 254, ..., 255, 254,  0],
 ...,
 [ 0, 255, 255, ..., 255, 254,  0],
 [ 0, 254, 254, ..., 254, 254,  0],
 [ 0,  0,  0, ...,  0,  0,  0]], dtype=uint8)
```

```
In [17]: img_new = np.zeros([new_height, new_width])
for i in range(1, new_height-1):
    for j in range(1, new_width-1):
        temp = img[i-1, j-1]*mask[0, 0]+img[i-1, j]*mask[0, 1]+img[i-1, j + 1]*mask[0, 2]+img[i,
j-1]*mask[1, 0]+ img[i, j]*mask[1, 1]+img[i, j + 1]*mask[1, 2]+img[i + 1, j-1]*mask[2, 0]+img[i +
1, j]*mask[2, 1]+img[i + 1, j + 1]*mask[2, 2]
        img_new[i,j]= temp

img_new = img_new.astype(np.uint8)
```

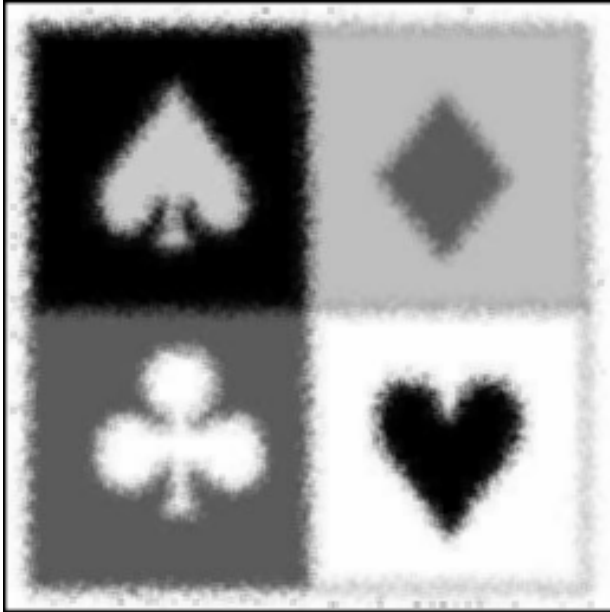
```
In [18]: img_final_input = Image.fromarray(np.uint8(img)).convert('RGB')  
img_final_input
```

Out[18]:



```
In [19]: img_final_output = Image.fromarray(np.uint8(img_new)).convert('RGB')  
img_final_output
```

Out[19]:

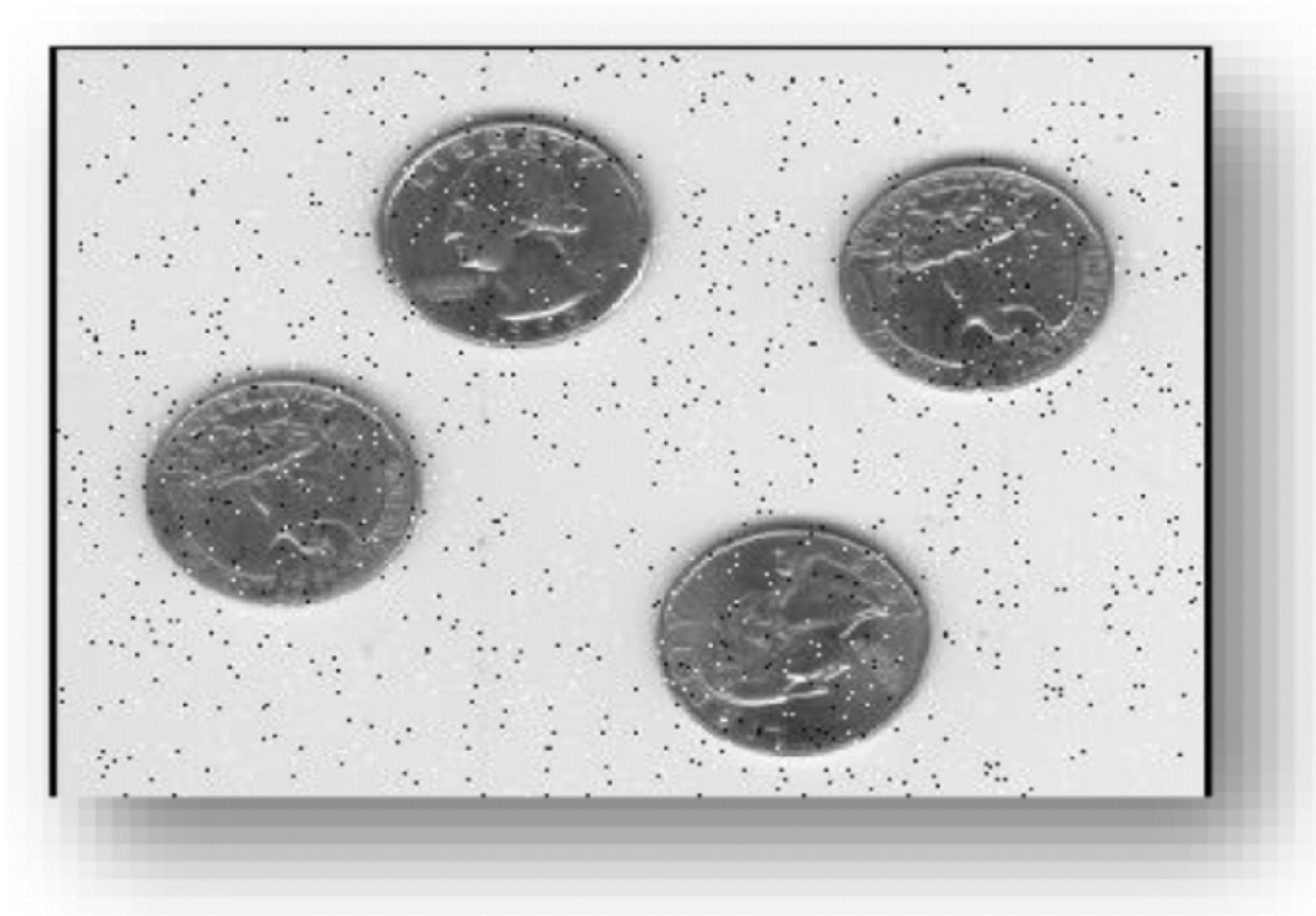


Observation: The image gets blurred - smoothened by eliminating gaussian noise

Low Pass Median Filter

```
In [20]: input_img = Image.open(img_saltpepper_path)
         input_img
```

Out[20]:



```
In [21]: input_img = input_img.convert('L')
```



```
In [22]: width, height = input_img.size  
width  
height
```

Out[22]: 479

```
In [23]: mask = np.array([[1, 1, 1],[1, 1, 1],[1, 1, 1]])
```

```
In [24]: mask
```

```
Out[24]: array([[1, 1, 1],  
               [1, 1, 1],  
               [1, 1, 1]])
```

```
In [25]: left = right = top = bottom = 1  
new_width = width + right + left  
new_height = height + top + bottom
```

```
In [26]: new_height  
new_width
```

Out[26]: 687

```
In [27]: padded_input_img = Image.new(input_img.mode, (new_width, new_height), (0))  
padded_input_img.paste(input_img, (left, top))
```

```
In [28]: img = np.asarray(padded_input_img)
img
```

```
Out[28]: array([[ 0,  0,  0, ...,  0,  0,  0],
 [ 0, 255, 255, ..., 255, 255,  0],
 [ 0, 255, 255, ..., 255, 255,  0],
 ...,
 [ 0, 255, 255, ..., 252, 255,  0],
 [ 0, 255, 255, ..., 255, 255,  0],
 [ 0,  0,  0, ...,  0,  0,  0]], dtype=uint8)
```

```
In [29]: img_new1 = np.zeros([new_height,new_width])

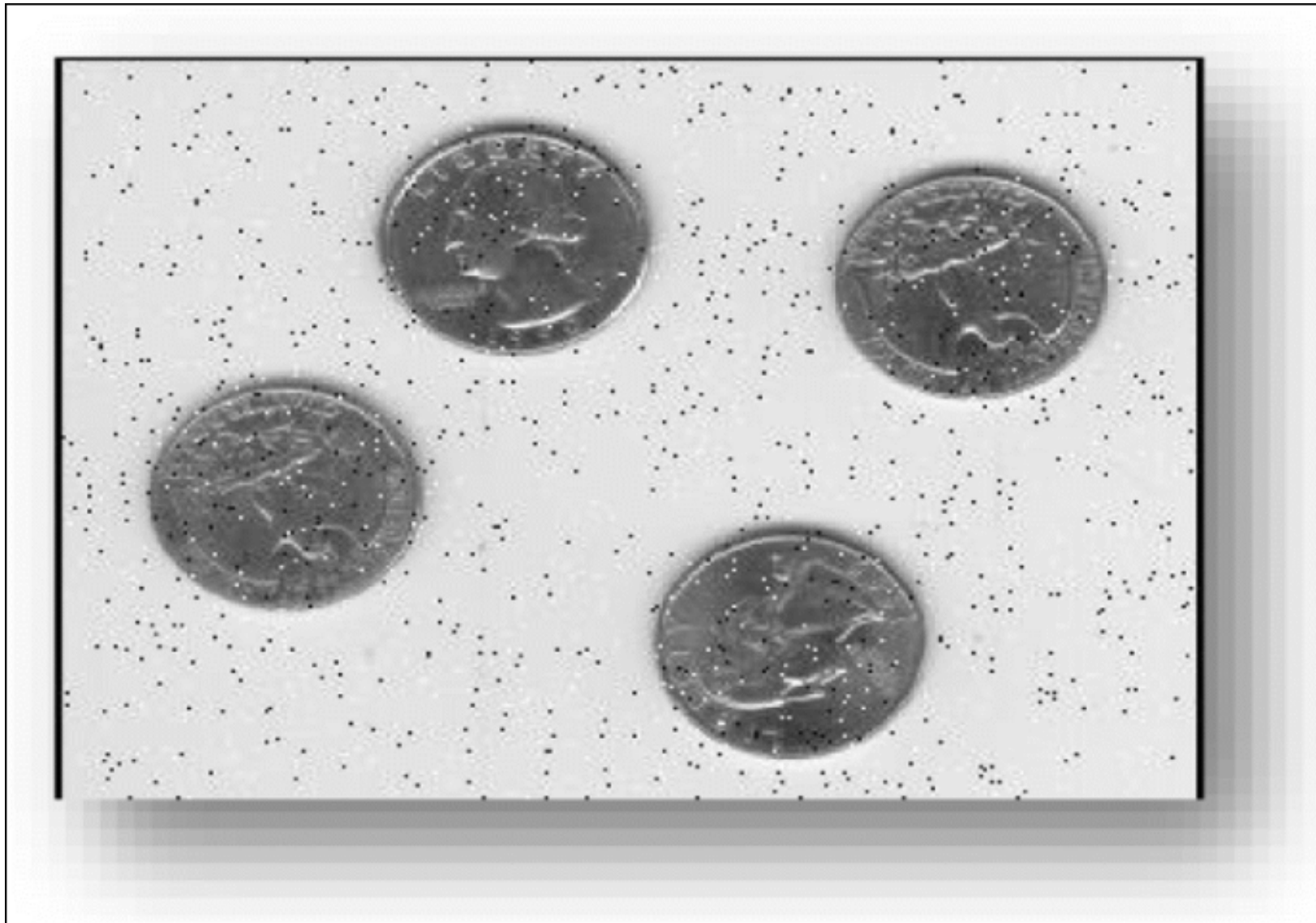
for i in range(1, new_height-1):
    for j in range(1, new_width-1):
        temp = [img[i-1, j-1],
                img[i-1, j],
                img[i-1, j + 1],
                img[i, j-1],
                img[i, j],
                img[i, j + 1],
                img[i + 1, j-1],
                img[i + 1, j],
                img[i + 1, j + 1]]

        temp = sorted(temp)
        img_new1[i, j]= temp[4]

img_new1 = img_new1.astype(np.uint8)
```

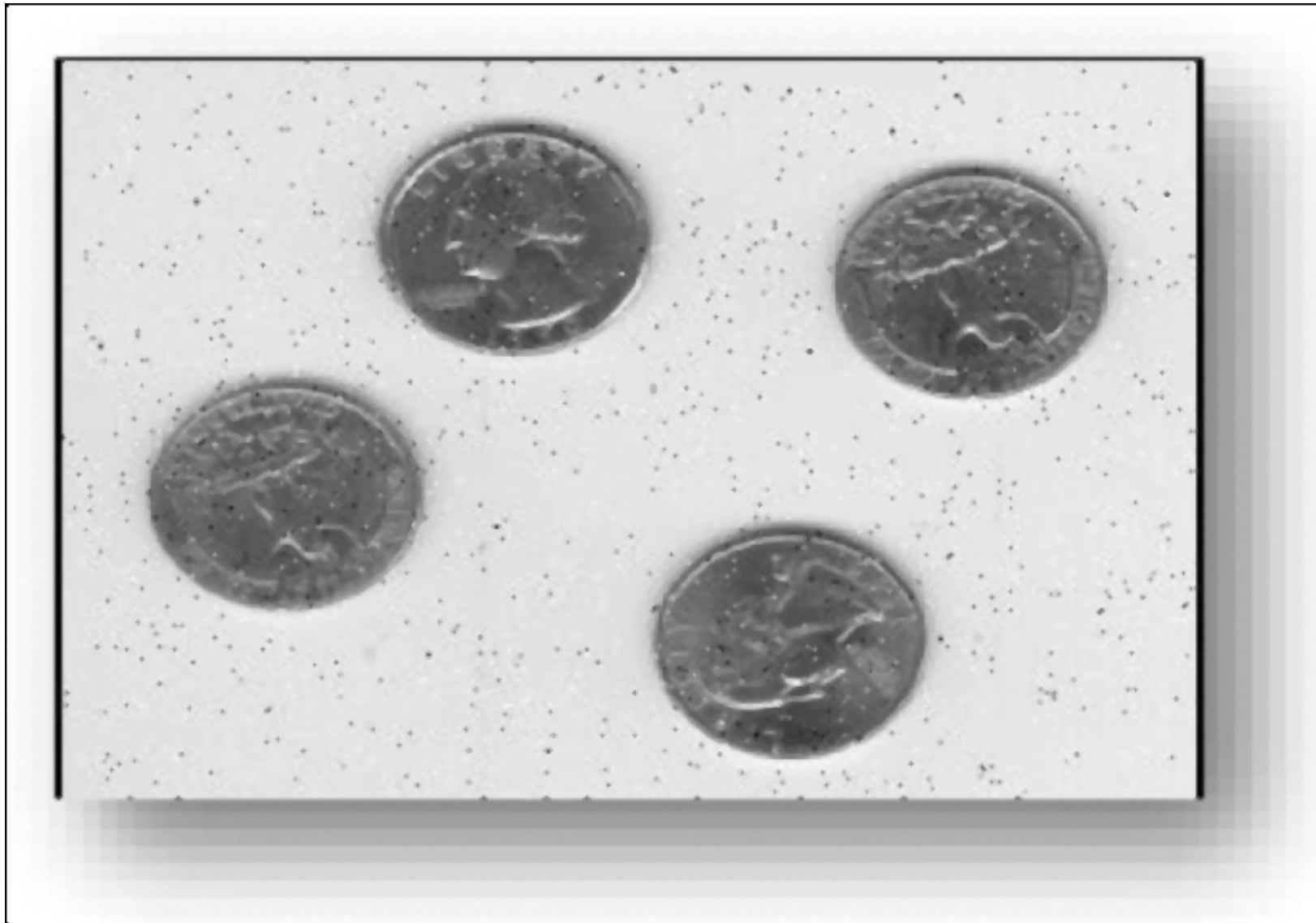
```
In [30]: img_final_input_1 = Image.fromarray(np.uint8(img)).convert('RGB')  
img_final_input_1
```

Out[30]:



```
In [31]: img_final_output_1 = Image.fromarray(np.uint8(img_new1)).convert('RGB')  
img_final_output_1
```

Out[31]:



Observation: The image gets smoothened by eliminating salt and pepper noise

High Pass Filter

```
In [32]: input_img = Image.open(img_sharpening_path)  
         input_img
```

Out[32]:



```
In [33]: input_img = input_img.convert('L')
```

```
In [34]: width, height = input_img.size  
width  
height
```

```
Out[34]: 305
```

```
In [35]: input_img
```

```
Out[35]:
```



```
In [36]: mask = np.array([[ -1,  -1,  -1], [-1,   8,  -1], [-1,  -1,  -1]])  
mask = mask/9
```

```
In [37]: print(input_img)
```

```
<PIL.Image.Image image mode=L size=427x305 at 0x7F127B96DB50>
```

```
In [38]: left = right = top = bottom = 1  
new_width = width + right + left  
new_height = height + top + bottom
```

```
In [39]: new_height  
new_width
```

```
Out[39]: 429
```

```
In [40]: padded_input_img = Image.new(input_img.mode,(new_width,new_height),(0))  
padded_input_img.paste(input_img,(left,top))
```

```
In [41]: img = np.asarray(padded_input_img)  
img
```

```
Out[41]: array([[ 0,  0,  0, ...,  0,  0,  0],  
                [ 0, 196, 193, ..., 35, 51,  0],  
                [ 0, 197, 198, ..., 57, 46,  0],  
                ...,  
                [ 0, 177, 173, ..., 181, 181,  0],  
                [ 0, 123, 127, ..., 192, 192,  0],  
                [ 0,  0,  0, ...,  0,  0,  0]], dtype=uint8)
```

```
In [42]: img_new = np.zeros([new_height, new_width])
         for i in range(1, new_height-1):
             for j in range(1, new_width-1):
                 # print(img[i-1, j-1]*mask[0, 0])
                 temp = img[i-1, j-1]*mask[0, 0]+img[i-1, j]*mask[0, 1]+img[i-1, j + 1]*mask[0, 2]+img[i,
j-1]*mask[1, 0]+ img[i, j]*mask[1, 1]+img[i, j + 1]*mask[1, 2]+img[i + 1, j-1]*mask[2, 0]+img[i +
1, j]*mask[2, 1]+img[i + 1, j + 1]*mask[2, 2]
                 # print(temp)
                 img_new[i,j]= temp

         img_new = img_new.astype(np.uint8)
         # cv2.imwrite('blurred.tif', img_new)
```



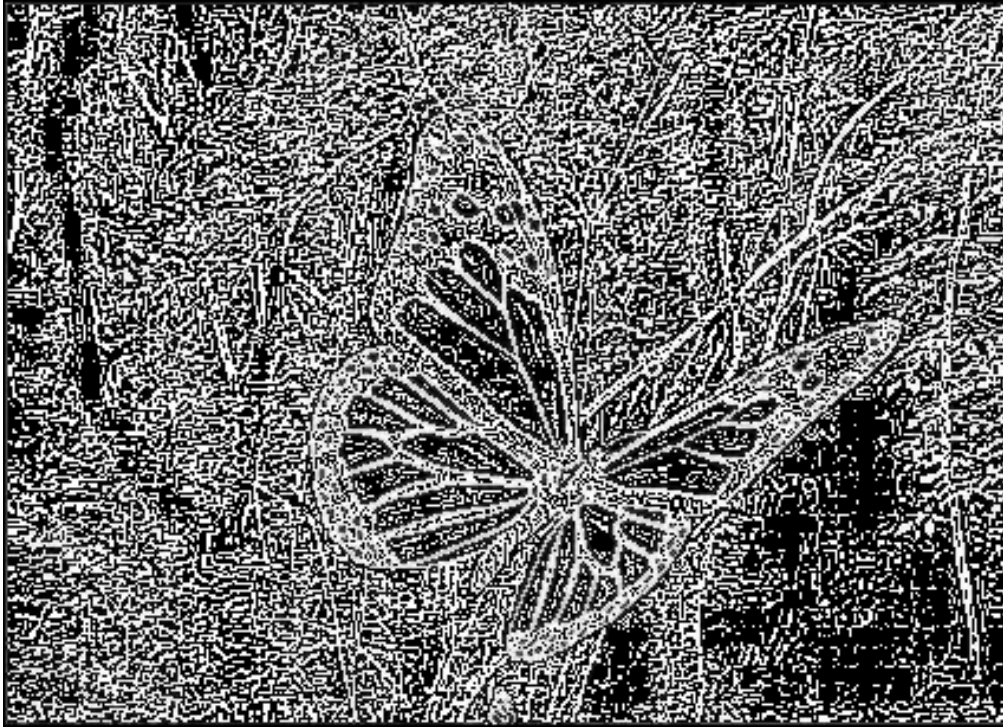
```
In [43]: img_final_input_2 = Image.fromarray(np.uint8(img)).convert('RGB')  
img_final_input_2
```

Out[43]:



```
In [44]: img_final_output_2 = Image.fromarray(np.uint8(img_new)).convert('RGB')  
img_final_output_2
```

Out[44]:



Observation: The image gets sharpened by retaining the high frequency components

Conclusion: Smoothing and Sharpening were successfully performed