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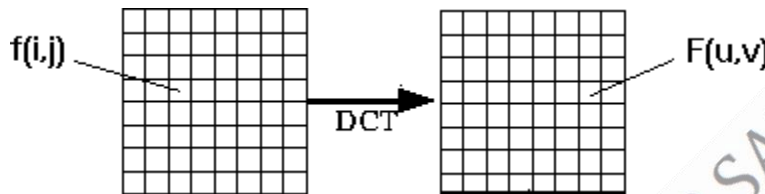
Image Transform (DCT)

Aim:- To perform Discrete Cosine transform on a small matrix of an image.

Theory:-

The Discrete Cosine Transform (DCT)

The discrete cosine transform (DCT) helps separate the image into parts (or spectral sub-bands) of differing importance (with respect to the image's visual quality). The DCT is similar to the discrete Fourier transform: it transforms a signal or image from the spatial domain to the frequency domain (Fig 7.8).



DCT Encoding

The general equation for a 1D (N data items) DCT is defined by the following equation:

$$F(u) = \left(\frac{2}{N}\right)^{\frac{1}{2}} \sum_{i=0}^{N-1} \Lambda(i) \cdot \cos \left[\frac{\pi \cdot u}{2 \cdot N} (2i + 1) \right] f(i)$$

and the corresponding *inverse* 1D DCT transform is simple $F^{-1}(u)$, i.e.:

where

$$\Lambda(i) = \begin{cases} \frac{1}{\sqrt{2}} & \text{for } i = 0 \\ 1 & \text{otherwise} \end{cases}$$

The general equation for a 2D (N by M image) DCT is defined by the following equation:

$$F(u, v) = \left(\frac{2}{N}\right)^{\frac{1}{2}} \left(\frac{2}{M}\right)^{\frac{1}{2}} \sum_{i=0}^{N-1} \sum_{j=0}^{M-1} \Lambda(i) \cdot \Lambda(j) \cdot \cos \left[\frac{\pi \cdot u}{2 \cdot N} (2i + 1) \right] \cos \left[\frac{\pi \cdot v}{2 \cdot M} (2j + 1) \right] \cdot f(i, j)$$

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and the corresponding *inverse* 2D DCT transform is simple $F^{-1}(u,v)$, i.e.:

where

$$\Lambda(\xi) = \begin{cases} \frac{1}{\sqrt{2}} & \text{for } \xi = 0 \\ 1 & \text{otherwise} \end{cases}$$

The basic operation of the DCT is as follows:

- The input image is N by M;
- $f(i,j)$ is the intensity of the pixel in row i and column j;
- $F(u,v)$ is the DCT coefficient in row k1 and column k2 of the DCT matrix.
- For most images, much of the signal energy lies at low frequencies; these appear in the upper left corner of the DCT.
- Compression is achieved since the lower right values represent higher frequencies, and are often small - small enough to be neglected with little visible distortion.
- The DCT input is an 8 by 8 array of integers. This array contains each pixel's gray scale level;
- 8 bit pixels have levels from 0 to 255.
- Therefore an 8 point DCT would be:

where

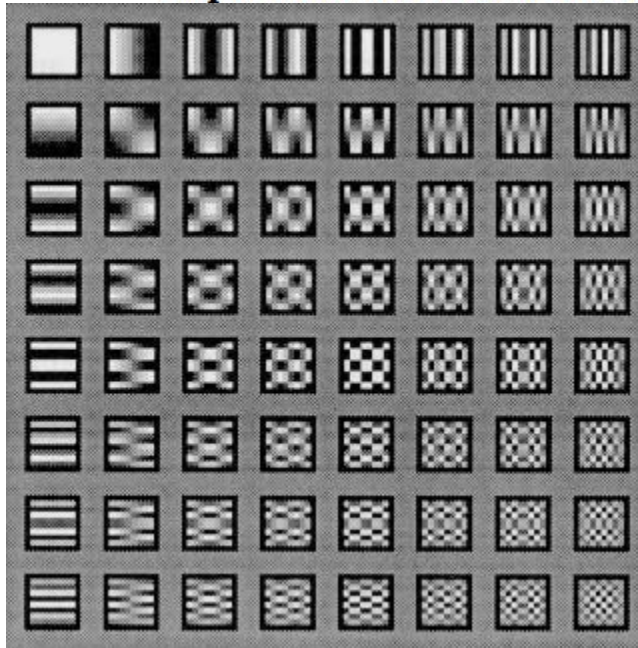
$$\Lambda(\xi) = \begin{cases} \frac{1}{\sqrt{2}} & \text{for } \xi = 0 \\ 1 & \text{otherwise} \end{cases}$$

Question: What is $F[0,0]$?

answer: They define DC and AC components.

- The output array of DCT coefficients contains integers; these can range from -1024 to 1023.
- It is computationally easier to implement and more efficient to regard the DCT as a set of **basis functions** which given a known input array size (8 x 8) can be precomputed and stored. This involves simply computing values for a convolution mask (8 x8 window) that get applied (summ values x pixelthe window overlap with image apply window accros all rows/columns of image). The values as simply calculated from the DCT formula. The 64 (8 x 8) DCT basis functions are illustrated in Fig [7.9](#).

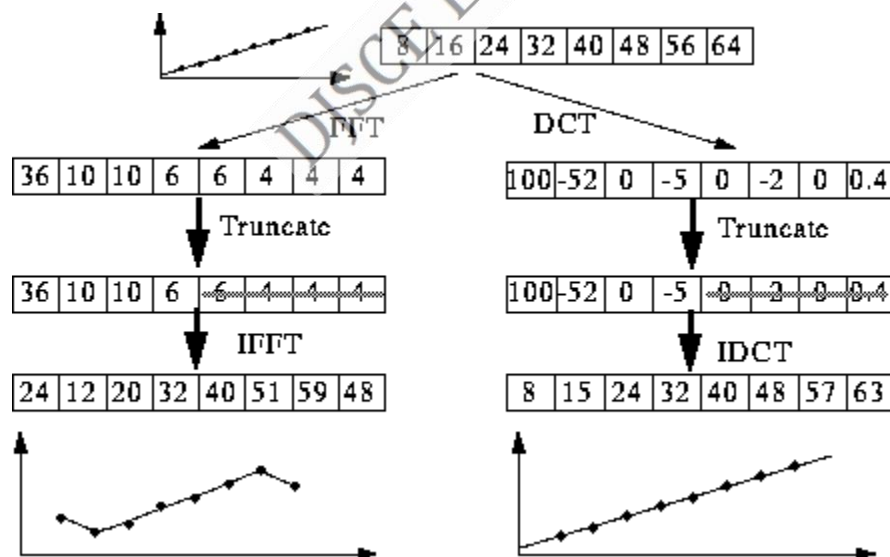
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DCT basis functions

- Why DCT not FFT?

DCT is similar to the Fast Fourier Transform (FFT), but can approximate lines well with fewer coefficients (Fig 7.10)



DCT/FFT Comparison

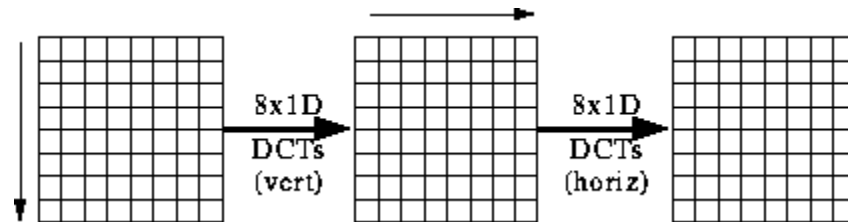
- Computing the 2D DCT
 - Factoring reduces problem to a series of 1D DCTs (Fig 7.11):



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- apply 1D DCT (Vertically) to Columns
- apply 1D DCT (Horizontally) to resultant Vertical DCT above.
- or alternatively Horizontal to Vertical.

The equations are given by:



Implementation Instructions:-

Consider a small matrix representing a small part of image & perform 2 dimensional DCT operation on it & observe the result. Do not use direct matlab/python function.

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```
1 %Experiment 8 - Image Transform (DCT)
2 %Krisha Lakhani - 60001200097
3
4 - clc;
5 - clear all;
6 % Original Matrix
7 - a = [
8     0 1 2 1;
9     1 2 3 2;
10    2 3 4 3;
11    1 2 3 2
12 ];
13
14 - t = zeros(4, 4);
15 - N = 4;
16
17 % Calculating DCT Transformation Matrix
18 - for u = 1:N
19 -     for v = 1:N
20 -         if u == 1
21 -             t(u,v) = 1/sqrt(N);
22 -         else
23 -             t(u,v) = (sqrt(2/N)) * cos(((2*(v-1))+1)*pi*(u-1))/(2*N));
24 -         end
25 -     end
26 - end
27
28 % Calculating DCT Matrix
29 - dct = t*a*transpose(t);
30
31 - disp("Krisha Lakhani - 60001200097")
32 - disp("Original matrix:");
33 - disp(a);
34 - disp("DCT transformation matrix(T):");
35 - disp(t);
36 - disp("DCT matrix:");
37 - disp(dct);
```



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Command Window

Krishna Lakhani - 60001200097

Original matrix:

0	1	2	1
1	2	3	2
2	3	4	3
1	2	3	2

DCT transformation matrix(T):

0.5000	0.5000	0.5000	0.5000
0.6533	0.2706	-0.2706	-0.6533
0.5000	-0.5000	-0.5000	0.5000
0.2706	-0.6533	0.6533	-0.2706

DCT matrix:

8.0000	-1.8478	-2.0000	0.7654
-1.8478	0	0.0000	0.0000
-2.0000	0	0.0000	0.0000
0.7654	0.0000	0.0000	-0.0000

Conclusion:

Successful implementation of Discrete Cosine Transform on a 4x4 image (which is a part of an image) has been carried out and DCT Matrix has been achieved with the help of transformation matrix.