

Disk scheduling is done by operating systems to schedule I/O requests arriving for the disk. Disk scheduling is also known as I/O scheduling.

Disk scheduling is important because:

- Multiple I/O requests may arrive by different processes and only one I/O request can be served at a time by the disk controller. Thus other I/O requests need to wait in the waiting queue and need to be scheduled.
- Two or more request may be far from each other so can result in greater disk arm movement.
- Hard drives are one of the slowest parts of the computer system and thus need to be accessed in an efficient manner.

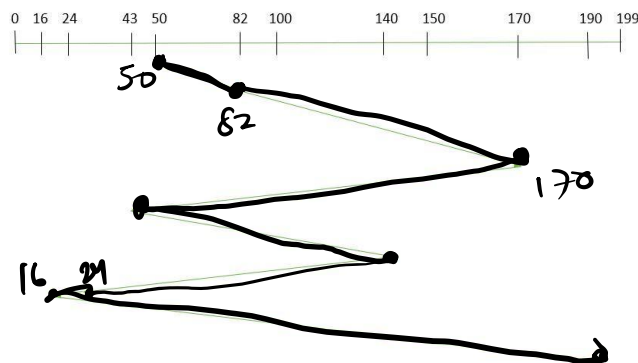
There are many Disk Scheduling Algorithms but before discussing them let's have a quick look at some of the important terms:

- ✓ **Seek Time:** Seek time is the time taken to locate the disk arm to a specified track where the data is to be read or write. So the disk scheduling algorithm that gives minimum average seek time is better.
- ✓ **Rotational Latency:** Rotational Latency is the time taken by the desired sector of disk to rotate into a position so that it can access the read/write heads. So the disk scheduling algorithm that gives minimum rotational latency is better.
- ✓ **Transfer Time:** Transfer time is the time to transfer the data. It depends on the rotating speed of the disk and number of bytes to be transferred.
- ✓ **Disk Access Time:** Disk Access Time is:
Disk Access Time = Seek Time + Rotational Latency + Transfer Time
- ✓ **Disk Response Time:** Response Time is the average of time spent by a request waiting to perform its I/O operation. *Average Response time* is the response time of the all requests. *Variance Response Time* is measure of how individual request are serviced with respect to average response time. So the disk scheduling algorithm that gives minimum variance response time is better.

Disk Scheduling Algorithms

- ✓ 1. **FCFS:** FCFS is the simplest of all the Disk Scheduling Algorithms. In FCFS, the requests are addressed in the order they arrive in the disk queue. Let us understand this with the help of an example.

Suppose the order of request is- (82, 170, 43, 140, 24, 16, 190)
And current position of Read/Write head is : 50

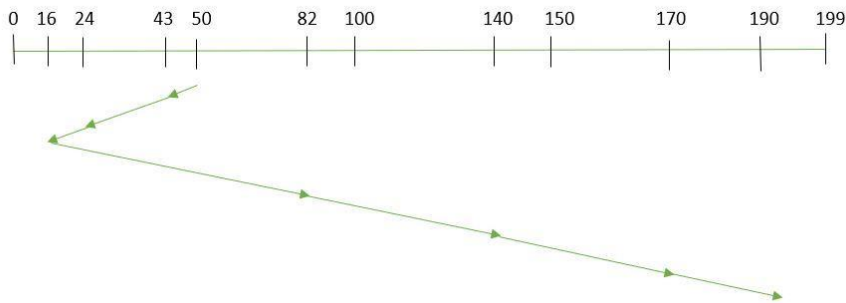


So, total seek time:

$$\begin{aligned} &= (82-50) + (170-82) + (170-43) + (140-43) + (140-24) + (24-16) + (190-16) \\ &= 642 \end{aligned}$$

2. In SSTF (Shortest Seek Time First), requests having shortest seek time are executed first. So, the seek time of every request is calculated in advance in the queue and then they are scheduled according to their calculated seek time. As a result, the request near the disk arm will get executed first. SSTF is certainly an improvement over FCFS as it decreases the average response time and increases the throughput of system.

Let us understand this with the help of an example.



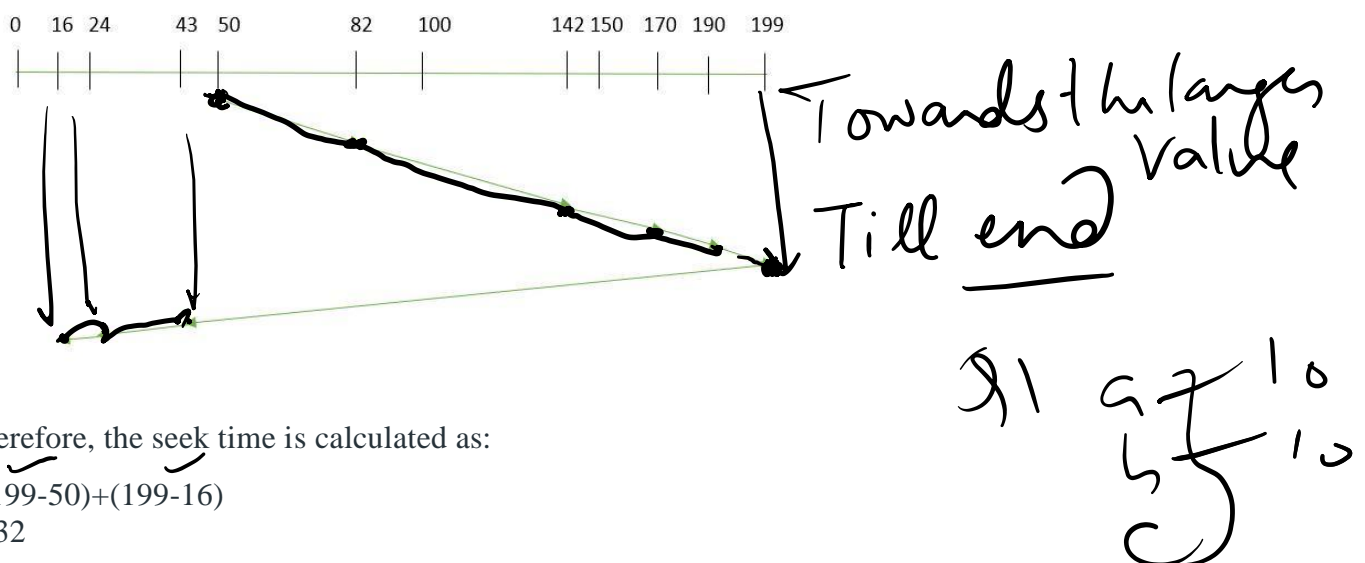
So, total seek time:

$$1. = (50-43) + (43-24) + (24-16) + (82-16) + (140-82) + (170-140) + (190-170) \\ = 208$$

3. SCAN: In SCAN algorithm the disk arm moves into a particular direction and services the requests coming in its path and after reaching the end of disk, it reverses its direction and again services the request arriving in its path.

So, this algorithm works as an elevator and hence also known as **elevator algorithm**. As a result, the requests at the midrange are serviced more and those arriving behind the disk arm will have to wait.

“Towards larger value”

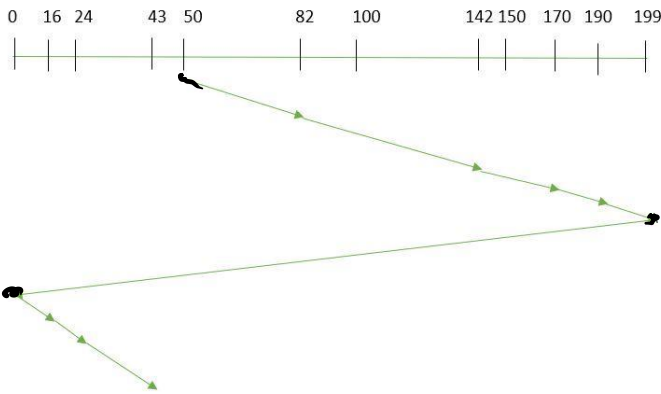


Therefore, the seek time is calculated as:

$$= (199-50) + (199-16) \\ = 332$$

4. **CSCAN:** In SCAN algorithm, the disk arm again scans the path that has been scanned, after reversing its direction. So, it may be possible that too many requests are waiting at the other end or there may be zero or few requests pending at the scanned area.

Towards the larger value

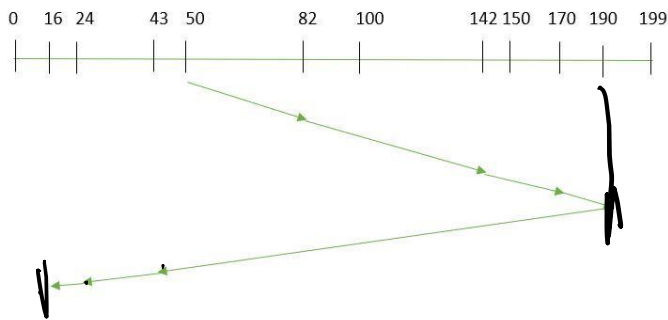


Seek time is calculated as:

$$= (199 - 50) + (199 - 0) + (43 - 0)$$

$$= 391$$

5.LOOK: It is similar to the SCAN disk scheduling algorithm except for the difference that the disk arm in spite of going to the end of the disk goes only to the last request to be serviced in front of the head and then reverses its direction from there only. Thus it prevents the extra delay which occurred due to unnecessary traversal to the end of the disk.



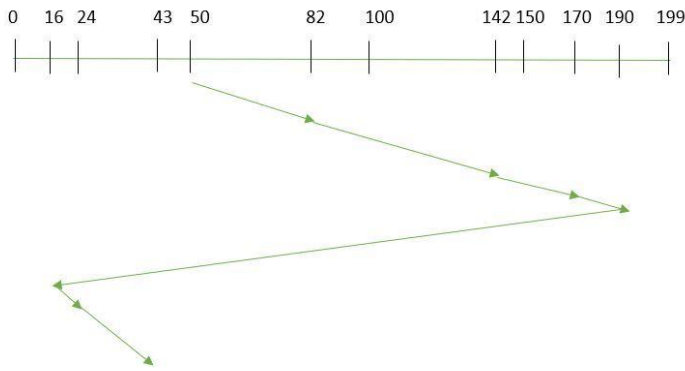
So, the seek time is calculated as:

$$= (190 - 50) + (190 - 16)$$

$$= 314$$

CLOOK: As LOOK is similar to SCAN algorithm, in similar way, CLOOK is similar to CSCAN disk scheduling algorithm. In CLOOK, the disk arm in spite of going to the end goes only to the last request to be serviced in front of the head and then from there goes to the other end's last request. Thus, it also prevents the extra delay which occurred due to unnecessary traversal to the end of the disk.

Suppose the requests to be addressed are-82,170,43,140,24,16,190. And the Read/Write arm is at 50, and it is also given that the disk arm should move “**towards the larger value**”



So, the seek time is calculated as:

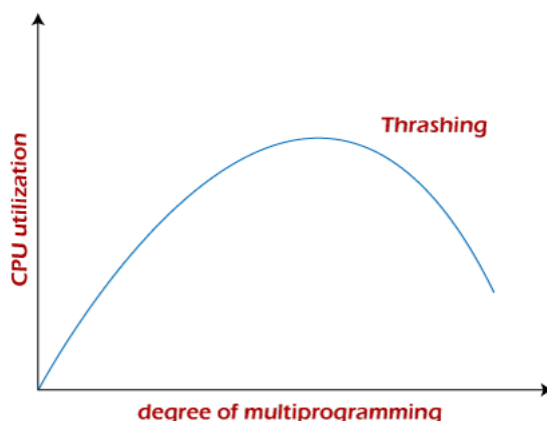
$$1. = (190 - 50) + (190 - 16) + (43 - 16) \\ = 341$$

Access Matrix is a security model of protection state in computer system.

- It is represented as a matrix.
- Access matrix is used to define the rights of each process executing in the domain with respect to each object.
- The rows of matrix represent domains and columns represent objects.
- Each cell of matrix represents set of access rights which are given to the processes of domain means each entry (i, j) defines the set of operations that a process executing in domain D_i can invoke on object O_j .

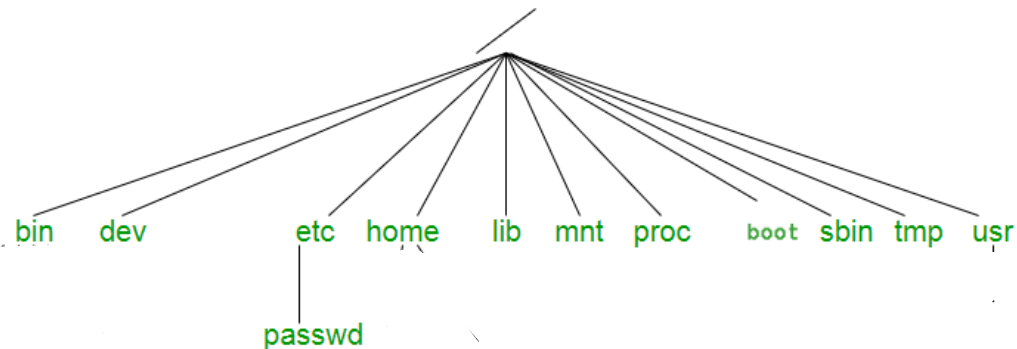
Thrashing

- **thrash** is the poor performance of a virtual memory (or paging) system when the same pages are being loaded repeatedly due to a lack of main memory to keep them in memory.
- Depending on the configuration and algorithm, the actual throughput of a system can degrade by multiple orders of magnitude.
- **thrashing** occurs when a computer's virtual memory resources are overused, leading to a constant state of paging and page faults, inhibiting most application-level processing. It causes the performance of the computer to degrade or collapse.
- The situation can continue indefinitely until the user closes some running applications or the active processes free up additional virtual memory resources.



- if a process is allocated too few frames, then there will be too many and too frequent page faults.
- As a result, no valuable work would be done by the CPU, and the CPU utilization would fall drastically.

Unix file structure



Directories or Files and their description –

- **/** : The slash / character alone denotes the root of the filesystem tree.
- **/bin** : Stands for “binaries” and contains certain fundamental utilities, such as ls or cp, which are generally needed by all users.
- **/boot** : Contains all the files that are required for successful booting process.
- **/dev** : Stands for “devices”. Contains file representations of peripheral devices and pseudo-devices.
- **/etc** : Contains system-wide configuration files and system databases. Originally also contained “dangerous maintenance utilities” such as init, but these have typically been moved to /sbin or elsewhere.
- **/home** : Contains the home directories for the users.
- **/lib** : Contains system libraries, and some critical files such as kernel modules or device drivers.
- **/media** : Default mount point for removable devices, such as USB sticks, media players, etc.
- **/mnt** : Stands for “mount”. Contains filesystem mount points. These are used, for example, if the system uses multiple hard disks or hard disk partitions. It is also often used for remote (network) filesystems, CD-ROM/DVD drives, and so on.
- **/proc** : procfs virtual filesystem showing information about processes as files.
- **/root** : The home directory for the superuser “root” – that is, the system administrator. This account’s home directory is usually on the initial filesystem, and hence not in /home (which may be a mount point for another filesystem) in case specific maintenance needs to be performed, during which other filesystems are not available. Such a case could occur, for example, if a hard disk drive suffers physical failures and cannot be properly mounted.
- **/tmp** : A place for temporary files. Many systems clear this directory upon startup; it might have tmpfs mounted atop it, in which case its contents do not survive a reboot, or it might be explicitly cleared by a startup script at boot time.
- **/usr** : Originally the directory holding user home directories, its use has changed. It now holds executables, libraries, and shared resources that are not system critical, like the X Window System, KDE, Perl, etc. However, on some Unix systems, some user accounts may still have a home directory that is a direct subdirectory of /usr, such as the default as in Minix. (on modern

systems, these user accounts are often related to server or system use, and not directly used by a person).

- **/usr/bin** : This directory stores all binary programs distributed with the operating system not residing in /bin, /sbin or (rarely) /etc.
- **/usr/include** : Stores the development headers used throughout the system. Header files are mostly used by the **#include** directive in C/C++ programming language.
- **/usr/lib** : Stores the required libraries and data files for programs stored within /usr or elsewhere.
- **/var** : A short for “variable.” A place for files that may change often – especially in size, for example e-mail sent to users on the system, or process-ID lock files.
- **/var/log** : Contains system log files.
- **/var/mail** : The place where all the incoming mails are stored. Users (other than root) can access their own mail only. Often, this directory is a symbolic link to /var/spool/mail.
- **/var/spool** : Spool directory. Contains print jobs, mail spools and other queued tasks.
- **/var/tmp** : A place for temporary files which should be preserved between system reboots.

For windows do read

NTFS and FAT