============= Initialized Observation Utils with Obs Spec =============

using obs modality: low\_dim with keys: ['robot0\_gripper\_qpos', 'robot0\_eef\_pos', 'object', 'robot0\_eef\_quat']

using obs modality: rgb with keys: []

using obs modality: depth with keys: []

using obs modality: scan with keys: []

============= Loaded Environment Metadata =============

run failed with error:

'Unable to synchronously open object (component not found)'

Traceback (most recent call last):

File "../robomimic/scripts/train.py", line 378, in main

train(config, device=device)

File "../robomimic/scripts/train.py", line 78, in train

shape\_meta = FileUtils.get\_shape\_metadata\_from\_dataset(

File "/home/shoaib/Shoaib/Krish/Personal/Project/robomimic/robomimic/utils/file\_utils.py", line 153, in get\_shape\_metadata\_from\_dataset

initial\_shape = demo["obs/{}".format(k)].shape[1:]

File "h5py/\_objects.pyx", line 54, in h5py.\_objects.with\_phil.wrapper

File "h5py/\_objects.pyx", line 55, in h5py.\_objects.with\_phil.wrapper

File "/home/shoaib/miniconda3/envs/krish\_project/lib/python3.8/site-packages/h5py/\_hl/group.py", line 357, in \_\_getitem\_\_

oid = h5o.open(self.id, self.\_e(name), lapl=self.\_lapl)

File "h5py/\_objects.pyx", line 54, in h5py.\_objects.with\_phil.wrapper

File "h5py/\_objects.pyx", line 55, in h5py.\_objects.with\_phil.wrapper

File "h5py/h5o.pyx", line 241, in h5py.h5o.open

KeyError: 'Unable to synchronously open object (component not found)'