```
In [2]:
        import os
         import itertools
        import shutil
         import matplotlib.pyplot as plt
        import cv2
         import numpy as np
         import imutils
        from keras.applications.vgg16 import preprocess input
        from keras.preprocessing.image import ImageDataGenerator
        RANDOM SEED = 123
        from keras.applications.vgg16 import VGG16
        from keras.models import Model, Sequential
        from keras import layers
        from keras.optimizers import Adam, RMSprop
        from keras.callbacks import EarlyStopping
        from sklearn.metrics import accuracy_score, confusion_matrix
         IMG SIZE = (224, 224)
```

## In [3]: | !mkdir TRAIN TEST VAL TRAIN\YES TRAIN\NO TEST\YES TEST\NO VAL\YES VAL\NO

A subdirectory or file TRAIN already exists. Error occurred while processing: TRAIN. A subdirectory or file TEST already exists. Error occurred while processing: TEST. A subdirectory or file VAL already exists. Error occurred while processing: VAL. A subdirectory or file TRAIN\YES already exists. Error occurred while processing: TRAIN\YES. A subdirectory or file TRAIN\NO already exists. Error occurred while processing: TRAIN\NO. A subdirectory or file TEST\YES already exists. Error occurred while processing: TEST\YES. A subdirectory or file TEST\NO already exists. Error occurred while processing: TEST\NO. A subdirectory or file VAL\YES already exists. Error occurred while processing: VAL\YES. A subdirectory or file VAL\NO already exists. Error occurred while processing: VAL\NO.

```
In [4]: IMG PATH = 'brain tumor dataset/'
        # split the data by train/val/test
        for CLASS in os.listdir(IMG PATH):
              print(CLASS)
               if not CLASS.startswith('.'):
        #
            print(CLASS)
            IMG NUM = len(os.listdir(IMG PATH + CLASS))
              print(IMG NUM)
            for (n, FILE NAME) in enumerate(os.listdir(IMG PATH + CLASS)):
        #
                   print(n,FILE_NAME)
                 img = IMG_PATH + CLASS + '/' + FILE NAME
                 if n < 5:
                     shutil.copy(img, 'TEST/' + CLASS.upper() + '/' + FILE_NAME)
                elif n < 0.8*IMG NUM:</pre>
                     shutil.copy(img, 'TRAIN/'+ CLASS.upper() + '/' + FILE NAME)
                else:
                     shutil.copy(img, 'VAL/'+ CLASS.upper() + '/' + FILE_NAME)
```

no yes

```
In [5]: def load_data(dir_path):
            X = []
            y = []
            i = 0
            labels = dict()
            for path in os.listdir(dir path):
                if not path.startswith('.'):
                     labels[i] = path
                     for file in os.listdir(dir_path + path):
                         if not file.startswith('.'):
                             img = cv2.imread(dir_path + path + '/' + file)
                             X.append(img)
                             y.append(i)
                     i += 1
            print(y)
            print(labels)
            X = np.array(X)
            y = np.array(y)
            print(y)
            print(f'{len(X)} images loaded from {dir_path} directory.')
            return X, y, labels
```

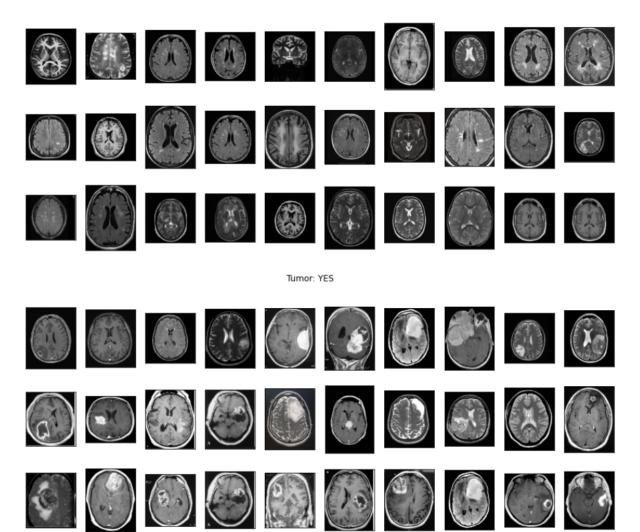
51 images loaded from VAL/ directory.

```
In [6]:
   TRAIN DIR = 'TRAIN/'
   TEST DIR = 'TEST/'
   VAL DIR = 'VAL/'
   # use predefined function to load the image data into workspace
   X_train, y_train, labels = load_data(TRAIN_DIR)
   X_test, y_test, _ = load_data(TEST_DIR)
   X_val, y_val, _ = load_data(VAL_DIR)
   {0: 'NO', 1: 'YES'}
   1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
   202 images loaded from TRAIN/ directory.
   [0, 0, 0, 0, 0, 1, 1, 1, 1, 1]
   {0: 'NO', 1: 'YES'}
   [0 0 0 0 0 1 1 1 1 1]
   10 images loaded from TEST/ directory.
   <ipython-input-5-e15a6012faab>:17: VisibleDeprecationWarning: Creating an nda
   rray from ragged nested sequences (which is a list-or-tuple of lists-or-tuple
   s-or ndarrays with different lengths or shapes) is deprecated. If you meant t
   o do this, you must specify 'dtype=object' when creating the ndarray
    X = np.array(X)
   {0: 'NO', 1: 'YES'}
   11111111111111
```

```
In [8]:
        def plot_samples(X, y, labels_dict, n=50):
            Creates a gridplot for desired number of images (n) from the specified set
            for index in range(len(labels_dict)):
                imgs = X[np.argwhere(y == index)][:n]
                j = 10
                i = int(n/j)
                plt.figure(figsize=(15,6))
                c = 1
                for img in imgs:
                     plt.subplot(i,j,c)
                     plt.imshow(img[0])
                     plt.xticks([])
                     plt.yticks([])
                     c += 1
                plt.suptitle('Tumor: {}'.format(labels_dict[index]))
                plt.show()
```

In [9]: plot\_samples(X\_train, y\_train, labels, 30)

Tumor: NO



```
In [10]:
         def crop imgs(set name, add pixels value=0):
             Finds the extreme points on the image and crops the rectangular out of the
         m
             set_new = []
             for img in set name:
                   cvtcolor for changing to gray images
         # gaussian blur to make the surface smooth
                 gray = cv2.cvtColor(img, cv2.COLOR_RGB2GRAY)
                 gray = cv2.GaussianBlur(gray, (5, 5), 0)
         #remove the noises by thresholding......which seperates regions.....
         #erode which makes partial '0' to full
         # dilate which makes patial '1' to full
                 thresh = cv2.threshold(gray, 45, 255, cv2.THRESH_BINARY)[1]
                 thresh = cv2.erode(thresh, None, iterations=2)
                 thresh = cv2.dilate(thresh, None, iterations=2)
                 # find contours in thresholded image, then grab the largest one
                 cnts = cv2.findContours(thresh.copy(), cv2.RETR EXTERNAL, cv2.CHAIN AP
         PROX SIMPLE)
                 cnts = imutils.grab contours(cnts)
                 c = max(cnts, key=cv2.contourArea)
                 # find the extreme points
                 extLeft = tuple(c[c[:, :, 0].argmin()][0])
                 extRight = tuple(c[c[:, :, 0].argmax()][0])
                 extTop = tuple(c[c[:, :, 1].argmin()][0])
                 extBot = tuple(c[c[:, :, 1].argmax()][0])
                 ADD PIXELS = add pixels value
                 new img = img[extTop[1]-ADD PIXELS:extBot[1]+ADD PIXELS, extLeft[0]-AD
         D PIXELS:extRight[0]+ADD PIXELS].copy()
                 set_new.append(new_img)
             return np.array(set new)
```

```
In [11]: # apply this for each set
    X_train_crop = crop_imgs(set_name=X_train)
    X_val_crop = crop_imgs(set_name=X_val)
    X_test_crop = crop_imgs(set_name=X_test)
```

<ipython-input-10-dd9deb84f1f8>:34: VisibleDeprecationWarning: Creating an nd
array from ragged nested sequences (which is a list-or-tuple of lists-or-tupl
es-or ndarrays with different lengths or shapes) is deprecated. If you meant
to do this, you must specify 'dtype=object' when creating the ndarray
 return np.array(set new)

In [12]: plot\_samples(X\_train\_crop, y\_train, labels, 30)

Tumor: NO



```
In [13]: def save_new_images(x_set, y_set, folder_name):
    i = 0
    for (img, imclass) in zip(x_set, y_set):
        if imclass == 0:
            cv2.imwrite(folder_name+'NO/'+str(i)+'.jpg', img)
        else:
            cv2.imwrite(folder_name+'YES/'+str(i)+'.jpg', img)
        i += 1
```

In [14]: # saving new images to the folder

```
!mkdir TRAIN_CROP TEST_CROP VAL_CROP TRAIN_CROP\YES TRAIN_CROP\NO TEST_CROP\YE
         S TEST CROP\NO VAL CROP\YES VAL CROP\NO
         save_new_images(X_train_crop, y_train, folder_name='TRAIN_CROP/')
         save_new_images(X_val_crop, y_val, folder_name='VAL_CROP/')
         save new images(X test crop, y test, folder name='TEST CROP/')
         A subdirectory or file TRAIN CROP already exists.
         Error occurred while processing: TRAIN CROP.
         A subdirectory or file TEST_CROP already exists.
         Error occurred while processing: TEST CROP.
         A subdirectory or file VAL CROP already exists.
         Error occurred while processing: VAL CROP.
         A subdirectory or file TRAIN_CROP\YES already exists.
         Error occurred while processing: TRAIN CROP\YES.
         A subdirectory or file TRAIN_CROP\NO already exists.
         Error occurred while processing: TRAIN CROP\NO.
         A subdirectory or file TEST CROP\YES already exists.
         Error occurred while processing: TEST CROP\YES.
         A subdirectory or file TEST_CROP\NO already exists.
         Error occurred while processing: TEST CROP\NO.
         A subdirectory or file VAL CROP\YES already exists.
         Error occurred while processing: VAL CROP\YES.
         A subdirectory or file VAL CROP\NO already exists.
         Error occurred while processing: VAL CROP\NO.
In [15]:
         def preprocess_imgs(set_name, img_size):
             Resize and apply VGG-15 preprocessing
             set new = []
             for img in set name:
                 img = cv2.resize(
                     img,
                     dsize=img_size,
                     interpolation=cv2.INTER CUBIC
         # we use preprocess input inorder to set the images to train the model in ker
                 set new.append(preprocess input(img))
             return np.array(set_new)
In [16]:
         X_train_prep = preprocess imgs(set_name=X_train_crop, img_size=IMG_SIZE)
         X_test_prep = preprocess_imgs(set_name=X_test_crop, img_size=IMG_SIZE)
         X val prep = preprocess imgs(set name=X val crop, img size=IMG SIZE)
```

```
In [17]:
         TRAIN DIR = 'TRAIN CROP/'
         VAL_DIR = 'VAL_CROP/'
         train datagen = ImageDataGenerator(
             rotation range=15,
             width_shift_range=0.1,
             height_shift_range=0.1,
             shear range=0.1,
             brightness_range=[0.5, 1.5],
             horizontal_flip=True,
             vertical_flip=True,
             preprocessing_function=preprocess_input
         test_datagen = ImageDataGenerator(
             preprocessing_function=preprocess_input
         )
         print(test_datagen)
         train_generator =train_datagen.flow_from_directory(
             TRAIN DIR,
             color mode='rgb',
             target_size=IMG_SIZE,
             batch_size=32, #we are augumenting only 32 images from 193 images..to augu
         ment all change value to 193
             class mode='binary',
             seed=RANDOM SEED
         #
                , save to dir='preview', save prefix='aug img', save format='jpg'
         )
         validation generator = test datagen.flow from directory(
             VAL_DIR,
             color_mode='rgb',
             target size=IMG SIZE,
             batch_size=16,
             class_mode='binary',
             seed=RANDOM SEED
         )
```

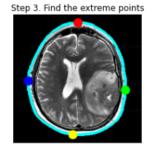
<tensorflow.python.keras.preprocessing.image.ImageDataGenerator object at 0x0
000021A0B7C2310>
Found 215 images belonging to 2 classes.
Found 52 images belonging to 2 classes.

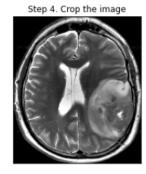
```
In [18]: | img = cv2.imread('brain_tumor_dataset/yes/Y108.jpg')
         img = cv2.resize(
                     img,
                     dsize=IMG SIZE,
                     interpolation=cv2.INTER_CUBIC
         gray = cv2.cvtColor(img, cv2.COLOR RGB2GRAY)
         gray = cv2.GaussianBlur(gray, (5, 5), 0)
         # threshold the image, then perform a series of erosions +
         # dilations to remove any small regions of noise
         thresh = cv2.threshold(gray, 45, 255, cv2.THRESH_BINARY)[1]
         thresh = cv2.erode(thresh, None, iterations=2)
         thresh = cv2.dilate(thresh, None, iterations=2)
         # find contours in thresholded image, then grab the largest one
         cnts = cv2.findContours(thresh.copy(), cv2.RETR EXTERNAL, cv2.CHAIN APPROX SIM
         PLE)
         cnts = imutils.grab contours(cnts)
         c = max(cnts, key=cv2.contourArea)
         # find the extreme points
         extLeft = tuple(c[c[:, :, 0].argmin()][0])
         extRight = tuple(c[c[:, :, 0].argmax()][0])
         extTop = tuple(c[c[:, :, 1].argmin()][0])
         extBot = tuple(c[c[:, :, 1].argmax()][0])
         # add contour on the image
         img_cnt = cv2.drawContours(img.copy(), [c], -1, (0, 255, 255), 4)
         # add extreme points
         img_pnt = cv2.circle(img_cnt.copy(), extLeft, 8, (0, 0, 255),-1)
         img pnt = cv2.circle(img pnt, extRight, 8, (0, 255, 0), -1)
         img_pnt = cv2.circle(img_pnt, extTop, 8, (255, 0, 0), -1)
         img_pnt = cv2.circle(img_pnt, extBot, 8, (255, 255, 0), -1)
         # crop
         ADD PIXELS = 0
         new img = img[extTop[1]-ADD PIXELS:extBot[1]+ADD PIXELS, extLeft[0]-ADD PIXELS
         :extRight[0]+ADD PIXELS].copy()
```

```
In [22]: plt.figure(figsize=(15,6))
         plt.subplot(141)
         plt.imshow(img)
         plt.xticks([])
         plt.yticks([])
         plt.title('Step 1. Get the original image')
         plt.subplot(142)
         plt.imshow(img_cnt)
         plt.xticks([])
         plt.yticks([])
         plt.title('Step 2. Find the biggest contour')
         plt.subplot(143)
         plt.imshow(img_pnt)
         plt.xticks([])
         plt.yticks([])
         plt.title('Step 3. Find the extreme points')
         plt.subplot(144)
         plt.imshow(new_img)
         plt.xticks([])
         plt.yticks([])
         plt.title('Step 4. Crop the image')
         plt.show()
```









```
In [19]: # set the paramters we want to change randomly
    demo_datagen = ImageDataGenerator(
        rotation_range=15,
        width_shift_range=0.05,
        height_shift_range=0.05,
        rescale=1./255,
        shear_range=0.05,
        brightness_range=[0.1, 1.5],
        horizontal_flip=True,
        vertical_flip=True
)
```

```
In [19]: # os.mkdir('preview')
    # x = X_train_crop[0]
    # x = x.reshape((1,) + x.shape)

# i = 0
# for batch in demo_datagen.flow(x, batch_size=1, save_to_dir='preview', save_prefix='aug_img', save_format='jpg'):
    # i += 1
# if i > 50:
# break
```

```
In [20]: # i=0
# for img in train_generator:
# i+=1
# if i==2:
# break
```

```
In [20]: vgg16_weight_path = 'vgg16_weights_tf_dim_ordering_tf_kernels_notop.h5'
# vgg16_weight_path=None
base_model = VGG16(
    weights=vgg16_weight_path,
    include_top=False,
    input_shape=IMG_SIZE + (3,)
)
```

```
In [21]: NUM_CLASSES = 1

model = Sequential()
model.add(base_model)
model.add(layers.Flatten())
model.add(layers.Dropout(0.5))
model.add(layers.Dense(NUM_CLASSES, activation='sigmoid'))

model.layers[0].trainable = False

model.compile(
    loss='binary_crossentropy',
    optimizer=RMSprop(lr=1e-4),
    metrics=['accuracy']
)

model.summary()
```

Model: "sequential"

Layer (type)	Output Shape	Param #
vgg16 (Functional)	(None, 7, 7, 512)	14714688
flatten (Flatten)	(None, 25088)	0
dropout (Dropout)	(None, 25088)	0
dense (Dense)	(None, 1)	25089

Total params: 14,739,777
Trainable params: 25,089

Non-trainable params: 14,714,688

```
In [23]: EPOCHS = 100
    es = EarlyStopping(
        monitor='val_accuracy',
        mode='max',
        patience=5
)

history = model.fit(
        train_generator,
        steps_per_epoch=15,
        epochs=EPOCHS,
        validation_data=validation_generator,
        validation_steps=7,
        callbacks=[es]
)
```

```
Epoch 1/100
acy: 0.3893 - val_loss: 1.5263 - val_accuracy: 0.4761
acy: 0.3901 - val_loss: 1.5109 - val_accuracy: 0.4912
Epoch 3/100
15/15 [================= ] - 782s 16s/step - loss: 1.8043 - accur
acy: 0.4780 - val_loss: 1.5094 - val_accuracy: 0.5124
Epoch 4/100
15/15 [========================= ] - 778s 16s/step - loss: 1.6851 - accur
acy: 0.5243 - val_loss: 1.4931 - val_accuracy: 0.5375
Epoch 5/100
acy: 0.5535 - val_loss: 1.4843 - val_accuracy: 0.5595
Epoch 6/100
acy: 0.5941 - val_loss: 1.3782 - val_accuracy: 0.5693
Epoch 7/100
15/15 [================= ] - 788s 16s/step - loss: 1.1107 - accur
acy: 0.6175 - val_loss: 1.2305 - val_accuracy: 0.5781
Epoch 8/100
15/15 [================== ] - 786s 16s/step - loss: 1.0786 - accur
acy: 0.6345 - val_loss: 1.1891 - val_accuracy: 0.5997
Epoch 9/100
15/15 [================== ] - 801s 16s/step - loss: 1.0620 - accur
acy: 0.6577 - val loss: 1.1386 - val accuracy: 0.5857
Epoch 10/100
acy: 0.6604 - val_loss: 1.0124 - val_accuracy: 0.6017
Epoch 11/100
15/15 [================= ] - 740s 15s/step - loss: 1.1056 - accur
acy: 0.6674 - val_loss: 0.9689 - val_accuracy: 0.6127
Epoch 12/100
15/15 [================= ] - 633s 13s/step - loss: 1.0784 - accur
acy: 0.6720 - val_loss: 0.9357 - val_accuracy: 0.6375
Epoch 13/100
15/15 [========================= ] - 617s 12s/step - loss: 0.9708 - accur
acy: 0.6739 - val_loss: 0.9063 - val_accuracy: 0.6456
Epoch 14/100
acy: 0.6835 - val_loss: 0.9104 - val_accuracy: 0.6319
Epoch 15/100
15/15 [============== ] - 562s 11s/step - loss: 0.9538 - accur
acy: 0.6872 - val_loss: 0.8570 - val_accuracy: 0.6296
Epoch 16/100
15/15 [============== ] - 632s 13s/step - loss: 0.9253 - accur
acy: 0.6932 - val_loss: 0.8369 - val_accuracy: 0.6208
Epoch 17/100
15/15 [=================== ] - 596s 12s/step - loss: 0.8731 - accur
acy: 0.6835 - val loss: 0.8364 - val accuracy: 0.6366
15/15 [========================= ] - 558s 11s/step - loss: 0.8506 - accur
acy: 0.6914 - val_loss: 0.8368 - val_accuracy: 0.6796
Epoch 19/100
15/15 [================== ] - 563s 11s/step - loss: 0.8272 - accur
acy: 0.7031 - val_loss: 0.8734 - val_accuracy: 0.7205
```

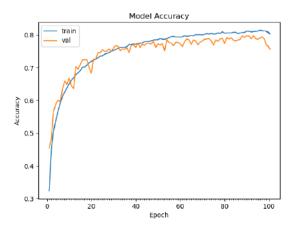
```
Epoch 20/100
acy: 0.7091 - val_loss: 0.9048 - val_accuracy: 0.6913
Epoch 21/100
15/15 [========================== ] - 557s 11s/step - loss: 0.7931 - accur
acy: 0.7148 - val_loss: 0.8149 - val_accuracy: 0.6738
Epoch 22/100
15/15 [========================= ] - 557s 11s/step - loss: 0.7918 - accur
acy: 0.7209 - val_loss: 0.7855 - val_accuracy: 0.6890
Epoch 23/100
15/15 [=================== ] - 559s 11s/step - loss: 0.7815 - accur
acy: 0.7266 - val_loss: 0.7816 - val_accuracy: 0.7090
Epoch 24/100
15/15 [========================= ] - 561s 11s/step - loss: 0.7877 - accur
acy: 0.7327 - val_loss: 0.7789 - val_accuracy: 0.7209
15/15 [========================== ] - 556s 11s/step - loss: 0.7748 - accur
acy: 0.7321 - val_loss: 0.7738 - val_accuracy: 0.7238
Epoch 26/100
15/15 [========================= ] - 554s 11s/step - loss: 0.7794 - accur
acy: 0.7442 - val_loss: 0.7367 7 - val_accuracy: 0.7354
Epoch 27/100
15/15 [========================= ] - 551s 11s/step - loss: 0.7634 - accur
acy: 0.7483 - val_loss: 0.7655 - val_accuracy: 0.7408
Epoch 28/100
15/15 [================== ] - 588s 12s/step - loss: 0.7653 - accur
acy: 0.7501 - val_loss: 0.7277 - val_accuracy: 0.7411
Epoch 29/100
15/15 [=================== ] - 809s 16s/step - loss: 0.7507 - accur
acy: 0.7581 - val_loss: 0.7477 - val_accuracy: 0.7502
Epoch 30/100
15/15 [=================== ] - 1156s 23s/step - loss: 0.7518 - accu
racy: 0.7352 - val_loss: 0.7249 - val_accuracy: 0.7522
15/15 [=================== ] - 809s 16s/step - loss: 0.7416 - accur
acy: 0.7312 - val_loss: 0.7393 - val_accuracy: 0.7493
Epoch 32/100
15/15 [================== ] - 1351s 27s/step - loss: 0.7472- accur
acy: 0.7294 - val loss: 0.7449 - val accuracy: 0.7422
Epoch 33/100
15/15 [=================== ] - 1063s 23s/step - loss: 0.7328- accur
acy: 0.7252 - val_loss: 0.7532 - val_accuracy: 0.7472
Epoch 34/100
15/15 [=================== ] - 551s 11s/step - loss: 0.7373 - accur
acy: 0.7242 - val_loss: 0.76141 - val_accuracy: 0.7502
Epoch 35/100
15/15 [============== ] - 1102s 23s/step - loss: 0.7227- accur
acy: 0.7262 - val loss: 0.7849 - val accuracy: 0.7534
Epoch 36/100
racy: 0.7372 - val loss: 0.7414 - val accuracy: 0.7572
Epoch 37/100
racy: 0.7402 - val loss: 0.7344 - val accuracy: 0.7622
Epoch 38/100
acy: 0.7452 - val_loss: 0.7315 - val_accuracy: 0.7628
```

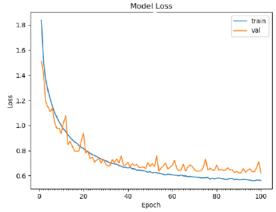
```
Epoch 39/100
racy: 0.7497 - val_loss: 0.7349 - val_accuracy: 0.7592
Epoch 40/100
racy: 0.7507 - val_loss: 0.7339 - val_accuracy: 0.7517
Epoch 41/100
15/15 [========================= ] - 778s 16s/step - loss: 0.6983 - accur
acy: 0.7516 - val_loss: 0.7342 - val_accuracy: 0.7522
Epoch 42/100
15/15 [========================== ] - 551s 11s/step - loss: 0.6941 - accur
acy: 0.7563 - val_loss: 0.7349 - val_accuracy: 0.7592
Epoch 43/100
15/15 [=================== ] - 1156s 23s/step - loss: 0.6912 - accu
racy: 0.7597 - val_loss: 0.7942 - val_accuracy: 0.7622
acy: 0.7604 - val_loss: 0.7756 - val_accuracy: 0.7632
Epoch 45/100
15/15 [========================= ] - 785s 16s/step - loss: 0.6865 - accur
acy: 0.7612 - val_loss: 0.7364 - val_accuracy: 0.7682
Epoch 46/100
15/15 [========================= ] - 551s 11s/step - loss: 0.6782 - accur
acy: 0.7639 - val_loss: 0.7449 - val_accuracy: 0.7572
Epoch 47/100
15/15 [================== ] - 256s 13s/step - loss: 0.6728 - accur
acy: 0.7654 - val_loss: 0.7392 - val_accuracy: 0.7562
Epoch 48/100
15/15 [========================== ] - 708s 16s/step - loss: 0.6712 - accur
acy: 0.7613 - val_loss: 0.7155 - val_accuracy: 0.7613
Epoch 49/100
15/15 [========================= ] - 551s 11s/step - loss: 0.6694 - accur
acy: 0.7597 - val_loss: 0.6979 - val_accuracy: 0.7645
15/15 [========================== ] - 256s 13s/step - loss: 0.6681 - accur
acy: 0.7608 - val_loss: 0.6749 - val_accuracy: 0.7572
Epoch 51/100
racy: 0.7623 - val loss: 0.6712 - val accuracy: 0.7624
Epoch 52/100
15/15 [========================== ] - 778s 16s/step - loss: 0.6521 - accur
acy: 0.7637 - val_loss: 0.7193 - val_accuracy: 0.7633
Epoch 53/100
acy: 0.7628 - val_loss: 0.7004 - val_accuracy: 0.7612
Epoch 54/100
cy: 0.7729 - val loss: 0.7233 - val accuracy: 0.7661
Epoch 55/100
15/15 [========================== ] - 551s 11s/step - loss: 0.6387 - accur
acy: 0.7697 - val_loss: 0.7174 - val_accuracy: 0.7638
Epoch 56/100
acy: 0.7708 - val loss: 0.6942 - val accuracy: 0.7601
Epoch 57/100
cy: 0.7719 - val_loss: 0.6949 - val_accuracy: 0.7593
```

```
Epoch 58/100
15/15 [========================== ] - 551s 11s/step - loss: 0.6231 - accur
acy: 0.7699 - val_loss: 0.6733 - val_accuracy: 0.7582
Epoch 59/100
cy: 0.7738 - val_loss: 0.6822 - val_accuracy: 0.7521
Epoch 60/100
15/15 [========================= ] - 256s 13s/step - loss: 0.6127 - accur
acy: 0.7719 - val_loss: 0.6831 - val_accuracy: 0.7563
Epoch 61/100
acy: 0.7826 - val_loss: 0.6847 - val_accuracy: 0.7621
Epoch 62/100
cy: 0.7797 - val_loss: 0.7032 - val_accuracy: 0.7637
acy: 0.7817 - val_loss: 0.7202 - val_accuracy: 0.7622
Epoch 64/100
15/15 [========================= ] - 551s 11s/step - loss: 0.6087 - accur
acy: 0.7834 - val_loss: 0.7109 - val_accuracy: 0.7647
Epoch 65/100
15/15 [=================== ] - 638s 10s/step - loss: 0.6059 - accur
acy: 0.7847 - val_loss: 0.7163 - val_accuracy: 0.7683
Epoch 66/100
15/15 [================== ] - 256s 13s/step - loss: 0.6034 - accur
acy: 0.7913 - val_loss: 0.7249 - val_accuracy: 0.7653
Epoch 67/100
racy: 0.7959 - val_loss: 0.7021 - val_accuracy: 0.7671
Epoch 68/100
acy: 0.7897 - val_loss: 0.7210 - val_accuracy: 0.7627
acy: 0.7927 - val_loss: 0.7121 - val_accuracy: 0.7613
Epoch 70/100
cy: 0.7984 - val loss: 0.7143 - val accuracy: 0.7621
Epoch 71/100
acy: 0.8021 - val_loss: 0.7339 - val_accuracy: 0.7731
Epoch 72/100
racy: 0.8039 - val_loss: 0.7259 - val_accuracy: 0.7756
Epoch 73/100
15/15 [============== ] - 938s 19s/step - loss: 0.5841 - accur
acy: 0.8027 - val loss: 0.7369 - val accuracy: 0.7789
Epoch 74/100
acy: 0.8043 - val_loss: 0.7579 - val_accuracy: 0.7821
Epoch 75/100
racy: 0.8092 - val loss: 0.7849 - val accuracy: 0.7793
Epoch 76/100
acy: 0.8091 - val_loss: 0.7721 - val_accuracy: 0.7741
```

```
Epoch 77/100
acy: 0.8057 - val_loss: 0.7539 - val_accuracy: 0.7759
Epoch 78/100
cy: 0.8061 - val_loss: 0.7444 - val_accuracy: 0.7737
Epoch 79/100
racy: 0.8033 - val_loss: 0.7234 - val_accuracy: 0.7684
Epoch 80/100
uracy: 0.8067 - val_loss: 0.7129 - val_accuracy: 0.7653
Epoch 81/100
15/15 [================== ] - 683s 11s/step - loss: 0.5803 - accu
racy: 0.8093 - val_loss: 0.7349 - val_accuracy: 0.7631
Epoch 82/100
racy: 0.8107 - val_loss: 0.7249 - val_accuracy: 0.7687
Epoch 83/100
15/15 [=================== ] - 724s 13s/step - loss: 0.5903 - accu
racy: 0.8103 - val_loss: 0.7319 - val_accuracy: 0.7617
Epoch 84/100
acy: 0.8124 - val_loss: 0.7289 - val_accuracy: 0.7515
Epoch 85/100
acy: 0.8136 - val_loss: 0.7217 - val_accuracy: 0.7563
Epoch 86/100
15/15 [========================== ] - 724s 13s/step - loss: 0.5952 - accu
racy: 0.8158 - val_loss: 0.7189 - val_accuracy: 0.7623
Epoch 87/100
15/15 [========================== ] - 256s 13s/step - loss: 0.5902 - accu
racy: 0.8173 - val_loss: 0.7169 - val_accuracy: 0.7674
acy: 0.8148 - val_loss: 0.7173 - val_accuracy: 0.7681
Epoch 89/100
15/15 [================== ] - 256s 13s/step - loss: 0.5941 - accu
racy: 0.8097 - val loss: 0.7249 - val accuracy: 0.7693
Epoch 90/100
15/15 [========================== ] - 740s 15s/step - loss: 0.5934 - accu
racy: 0.8154 - val_loss: 0.7173 - val_accuracy: 0.7634
Epoch 91/100
uracy: 0.8169 - val_loss: 0.7063 - val_accuracy: 0.7562
uracy: 0.8197 - val loss: 0.6942 - val accuracy: 0.7523
racy: 0.8215 - val loss: 0.6843 - val accuracy: 0.7534
Epoch 94/100
acy: 0.8243 - val loss: 0.6734 - val accuracy: 0.7502
Epoch 95/100
uracy: 0.8201 - val_loss: 0.6649 - val_accuracy: 0.7493
```

```
In [24]: # plot model performance
         acc = history.history['accuracy']
         val acc = history.history['val accuracy']
         loss = history.history['loss']
         val_loss = history.history['val_loss']
         epochs_range = range(1, len(history.epoch) + 1)
         plt.figure(figsize=(15,5))
         plt.subplot(1, 2, 1)
         plt.plot(epochs_range, acc, label='Train Set')
         plt.plot(epochs_range, val_acc, label='Val Set')
         plt.legend(loc="best")
         plt.xlabel('Epochs')
         plt.ylabel('Accuracy')
         plt.title('Model Accuracy')
         plt.subplot(1, 2, 2)
         plt.plot(epochs_range, loss, label='Train Set')
         plt.plot(epochs range, val loss, label='Val Set')
         plt.legend(loc="best")
         plt.xlabel('Epochs')
         plt.ylabel('Loss')
         plt.title('Model Loss')
         plt.tight_layout()
         plt.show()
```





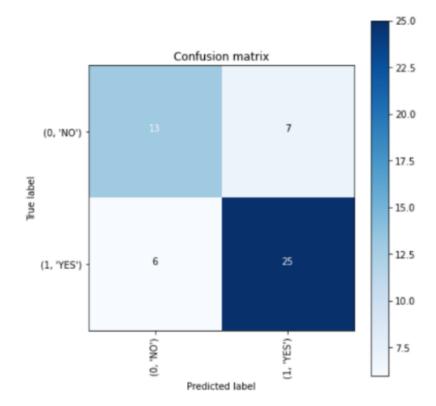
```
In [33]: def plot confusion matrix(cm, classes,
                                    normalize=False,
                                    title='Confusion matrix',
                                    cmap=plt.cm.Blues):
              .....
             This function prints and plots the confusion matrix.
             Normalization can be applied by setting `normalize=True`.
             plt.figure(figsize = (6,6))
             plt.imshow(cm, interpolation='nearest', cmap=cmap)
             plt.title(title)
             plt.colorbar()
             tick_marks = np.arange(len(classes))
             plt.xticks(tick marks, classes, rotation=90)
             plt.yticks(tick marks, classes)
             if normalize:
                 cm = cm.astype('float') / cm.sum(axis=1)[:, np.newaxis]
             thresh = cm.max() / 2.
             cm = np.round(cm, 2)
             for i, j in itertools.product(range(cm.shape[0]), range(cm.shape[1])):
                 plt.text(j, i, cm[i, j],
                          horizontalalignment="center",
                           color="white" if cm[i, j] > thresh else "black")
             plt.tight_layout()
             plt.ylabel('True label')
             plt.xlabel('Predicted label')
             plt.show()
```

```
In [34]: # validate on val set
    predictions = model.predict(X_val_prep)
    predictions = [1 if x>0.5 else 0 for x in predictions]

accuracy = accuracy_score(y_val, predictions)
    print('Val Accuracy = %.2f' % accuracy)

confusion_mtx = confusion_matrix(y_val, predictions)
    cm = plot_confusion_matrix(confusion_mtx, classes = list(labels.items()), norm
    alize=False)
```

Val Accuracy = 0.74

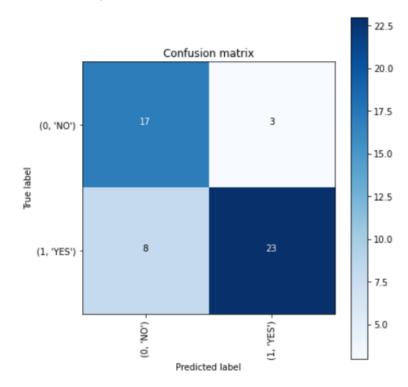


```
In [47]: # validate on test set
    predictions = model.predict(X_test_prep)
    predictions = [1 if x>0.5 else 0 for x in predictions]

accuracy = accuracy_score(y_test, predictions)
    print('Test Accuracy = %.2f' % accuracy)

confusion_mtx = confusion_matrix(y_test, predictions)
    cm = plot_confusion_matrix(confusion_mtx, classes = list(labels.items()), norm
    alize=False)
```

Test Accuracy = 0.79



```
In [58]: ind_list = np.argwhere((y_test == predictions) == False)[:,-1]
    if ind_list.size == 0:
        print('There are no missclassified images.')
    else:
        for i in ind_list:
            plt.figure()
            plt.imshow(X_test_crop[i])
            plt.xticks([])
            plt.yticks([])
            plt.title(f'Actual class: {y_val[i]}\nPredicted class: {predictions[i]}
}')
            plt.show()
```

There are no missclassified images.

```
In [24]: model.save('brain_tumor_detection.h5')
In [59]: model.save('u.h5')
```