



KESHAV MEMORIAL INSTITUTE OF TECHNOLOGY

AN AUTONOMOUS INSTITUTION - ACCREDITED BY NAAC WITH 'A' GRADE

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Deep Learning

CNN

EXERCISE-1

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BY

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EXERCISE 2: 3×3 convolution on 5×5 image with and without padding

1.Import necessary libraries

```
from PIL import Image  
import numpy as np  
import matplotlib.pyplot as plt
```

2. Load the cat image and perform image Preprocessing

```
# Load the cat image and convert it to grayscale  
image_path = 'img.jpeg' # replace with the path to your cat image  
new_image = Image.open(image_path).convert('L') # Convert to grayscale  
# Convert the image to a numpy array  
image_array = np.array(new_image)
```

3.Display the original image

```
# Display the original image  
plt.imshow(image_array, cmap='gray')  
plt.title("Original Image")  
plt.axis('off')  
plt.show()
```

Original Image



4. Define the 3x3 filter (kernel) matrix

```
] : # Define the 3x3 filter (kernel) matrix  
filter_kernel = np.array([  
    [1, 0, -1],  
    [1, 0, -1],  
    [1, 0, -1]  
])
```

5. Define Convolution Function

```
# Convolution function
def convolve(image, kernel, padding=0):
    # Add padding if needed
    if padding > 0:
        image = np.pad(image, ((padding, padding), (padding, padding)), mode='constant')

    # Dimensions of the image and kernel
    image_height, image_width = image.shape
    kernel_height, kernel_width = kernel.shape

    # Calculate output dimensions
    output_height = image_height - kernel_height + 1
    output_width = image_width - kernel_width + 1

    # Initialize the output matrix
    output = np.zeros((output_height, output_width))

    # Perform convolution
    for i in range(output_height):
        for j in range(output_width):
            region = image[i:i+kernel_height, j:j+kernel_width]
            output[i, j] = np.sum(region * kernel)

    return output
```

6.Convolution Operation Without padding

```
: # Convolve without padding  
output_without_padding = convolve(image_array, filter_kernel, padding=0)  
plt.imshow(output_without_padding, cmap='gray')  
plt.title("Convolution Output without Padding")  
plt.axis('off')  
plt.show()
```

Convolution Output without Padding



7.Convolution Operation With padding of 4

```
# Convolve with padding of 1
output_with_padding = convolve(image_array, filter_kernel, padding=4)
plt.imshow(output_with_padding, cmap='gray')
plt.title("Convolution Output with Padding")
plt.axis('off')
plt.show()
```

Convolution Output with Padding



EXERCISE 2: MAX AND AVERAGE POOLING ON THE FEATURE MAP

POOLING

1.Import Necessary Libraries

```
!pip install opencv-python-headless
```

Collecting opencv-python-headless

Using cached opencv_python_headless-4.10.0.84-cp37-abi3-manylinux_2_17_x86_64.manylinux2014_x86_64.whl (49.9 MB)

Requirement already satisfied: numpy>=1.17.0 in /opt/conda/lib/python3.10/site-packages (from opencv-python-headless) (1.26.3)

Installing collected packages: opencv-python-headless

Successfully installed opencv-python-headless-4.10.0.84

```
import numpy as np
import cv2
import matplotlib.pyplot as plt
```

2. Take image as input and Preprocess it

```
|: # Save or provide a path to a small test image for demonstration  
test_image_path = "cat_image.png"  
  
|: # Load the image and convert it to grayscale  
def process_image(image_path):  
    image = cv2.imread(image_path, cv2.IMREAD_GRAYSCALE)  
    if image is None:  
        raise ValueError("Invalid image path or unable to load image.")  
    return image
```

3. Implement Max Pooling

```
] : def max_pooling(matrix, pool_size=(2, 2), stride=2):  
    pooled_matrix = []  
    for i in range(0, matrix.shape[0], stride):  
        row = []  
        for j in range(0, matrix.shape[1], stride):  
            row.append(np.max(matrix[i:i+pool_size[0], j:j+pool_size[1]]))  
        pooled_matrix.append(row)  
    return np.array(pooled_matrix)
```

4. Implement Average Pooling

```
: def average_pooling(matrix, pool_size=(2, 2), stride=2):  
    pooled_matrix = []  
    for i in range(0, matrix.shape[0], stride):  
        row = []  
        for j in range(0, matrix.shape[1], stride):  
            row.append(np.mean(matrix[i:i+pool_size[0], j:j+pool_size[1]]))  
        pooled_matrix.append(row)  
    return np.array(pooled_matrix)
```

5. Define Function to display Original Image and Pooled images

```
def plot_results(original, max_pooled, avg_pooled):  
  
    # Display the original and pooled images  
    plt.figure(figsize=(12, 4))  
  
    plt.subplot(1, 3, 1)  
    plt.title("Original Image")  
    plt.imshow(original, cmap='gray')  
    plt.axis('off')  
  
    plt.subplot(1, 3, 2)  
    plt.title("Max Pooled Image")  
    plt.imshow(max_pooled, cmap='gray')  
    plt.axis('off')  
  
    plt.subplot(1, 3, 3)  
    plt.title("Average Pooled Image")  
    plt.imshow(avg_pooled, cmap='gray')  
    plt.axis('off')  
  
    plt.tight_layout()  
    plt.show()
```


5. Main function to perform pooling on an image

```
: # Main function to perform pooling on an image
def apply_pooling(image_path, pool_size=(2, 2), stride=4):
    image = process_image(image_path)
    max_pooled = max_pooling(image, pool_size, stride)
    avg_pooled = average_pooling(image, pool_size, stride)
    plot_results(image, max_pooled, avg_pooled)
```

```
: test_image_path = "cat_image.png"
  apply_pooling(test_image_path)
```



Original Image



Max Pooled Image



Average Pooled Image

