

Assignment 4 - Problem 2

Given fuzzy set about the nominal x -gyro bias (x_{gb})

$$A = \left\{ \frac{0.2}{x_{gb} - 3\delta x} + \frac{0.4}{x_{gb} - 2\delta x} + \frac{0.6}{x_{gb} - \delta x} + \frac{0.8}{x_{gb}} + \frac{0.6}{x_{gb} + \delta x} + \frac{0.4}{x_{gb} + 2\delta x} + \frac{0.2}{x_{gb} + 3\delta x} \right\}$$

When $x_{gb} = 2^\circ/\text{hour}$ and $\delta x = 0.1$. We get the gyro bias in the x direction as

$$A = \left\{ \frac{0.2}{1.7} + \frac{0.4}{1.8} + \frac{0.6}{1.9} + \frac{0.8}{2.0} + \frac{0.6}{2.1} + \frac{0.4}{2.2} + \frac{0.2}{2.3} \right\}$$

Given fuzzy set B , describing accelerometer bias in x direction as $B = \left\{ \frac{0.1}{0.25} + \frac{0.4}{0.27} + \frac{0.9}{0.3} + \frac{0.4}{0.33} + \frac{0.1}{0.35} \right\}$

a) Given classical implication operator

$$\mu_R = \max[\min(\mu_A, \mu_B), (1 - \mu_A)] \quad \text{--- (1)}$$

Given Relation R : IF A THEN B

According to propositional calculus,

$$R: A \rightarrow B : \bar{A} \vee (A \wedge B) \text{ where } \vee, \wedge \text{ are}$$

S-norm and T-norm operators respectively. --- (2)

we have

$$\mu_A = \left\{ \frac{0.2}{x_1} + \frac{0.4}{x_2} + \frac{0.6}{x_3} + \frac{0.8}{x_4} + \frac{0.6}{x_5} + \frac{0.4}{x_6} + \frac{0.2}{x_7} \right\}$$

$$\mu_B = \left\{ \frac{0.1}{y_1} + \frac{0.4}{y_2} + \frac{0.9}{y_3} + \frac{0.4}{y_4} + \frac{0.1}{y_5} \right\}$$

from ① and ②

$\min(\mu_A, \mu_B)$ is $(A \cap B)$ and we are using cartesian product as T-norm operator here

$\min(\mu_A, \mu_B) =$

	y_1	y_2	y_3	y_4	y_5
x_1	0.1	0.2	0.2	0.2	0.1
x_2	0.1	0.4	0.4	0.4	0.1
x_3	0.1	0.4	0.6	0.4	0.1
x_4	0.1	0.4	0.8	0.4	0.1
x_5	0.1	0.4	0.6	0.4	0.1
x_6	0.1	0.4	0.4	0.4	0.1
x_7	0.1	0.2	0.2	0.2	0.1

$$(1 - \mu_A) = [0.8 \ 0.6 \ 0.4 \ 0.2 \ 0.4 \ 0.6 \ 0.8]$$

we observe that $\min(\mu_A, \mu_B)$ is 2-D and

$(1 - \mu_A)$ is 1-D.

Hence, we are considering cylindrical extension

of $(1 - \mu_A)$

$$C.E(1 - \mu_A) = \begin{bmatrix} 0.8 & 0.8 & 0.8 & 0.8 & 0.8 \\ 0.6 & 0.6 & 0.6 & 0.6 & 0.6 \\ 0.4 & 0.4 & 0.4 & 0.4 & 0.4 \\ 0.2 & 0.2 & 0.2 & 0.2 & 0.2 \\ 0.4 & 0.4 & 0.4 & 0.4 & 0.4 \\ 0.6 & 0.6 & 0.6 & 0.6 & 0.6 \\ 0.8 & 0.8 & 0.8 & 0.8 & 0.8 \end{bmatrix}$$

R: IF A THEN B:-

$$M_R = \max[\min(M_A, M_B), (1 - M_A)]$$

$$= \begin{bmatrix} 0.8 & 0.8 & 0.8 & 0.8 & 0.8 \\ 0.6 & 0.6 & 0.6 & 0.6 & 0.6 \\ 0.4 & 0.4 & 0.6 & 0.4 & 0.4 \\ 0.2 & 0.4 & 0.8 & 0.4 & 0.2 \\ 0.4 & 0.4 & 0.6 & 0.4 & 0.4 \\ 0.6 & 0.6 & 0.6 & 0.6 & 0.6 \\ 0.8 & 0.8 & 0.8 & 0.8 & 0.8 \end{bmatrix}$$

[Considering maximum of the two matrices $\min(M_A, M_B)$ and $C.E.(1 - M_A)$]

b) Given new gyro with fuzzy bias

$$A' = \left\{ \frac{0}{1.7} + \frac{0.5}{1.8} + \frac{0.7}{1.9} + \frac{0.95}{2.0} + \frac{0.7}{2.1} + \frac{0.5}{2.2} + \frac{0}{2.3} \right\}$$

(i) Max-min Composition $T = A' \circ R$: ~~is~~ given ~~by~~

$$A' = \begin{bmatrix} 0 \\ 0.5 \\ 0.7 \\ 0.95 \\ 0.7 \\ 0.5 \\ 0 \end{bmatrix} \quad R = \begin{bmatrix} 0.8 & 0.8 & 0.8 & 0.8 & 0.8 \\ 0.6 & 0.6 & 0.6 & 0.6 & 0.6 \\ 0.4 & 0.4 & 0.6 & 0.4 & 0.4 \\ 0.2 & 0.4 & 0.8 & 0.4 & 0.2 \\ 0.4 & 0.4 & 0.6 & 0.4 & 0.4 \\ 0.6 & 0.6 & 0.6 & 0.6 & 0.6 \\ 0.8 & 0.8 & 0.8 & 0.8 & 0.8 \end{bmatrix}$$

$$T = \max_{\text{rows}} \left[\min_{\text{columns}} \begin{bmatrix} 0 \\ 0.5 \\ 0.7 \\ 0.95 \\ 0.7 \\ 0.5 \\ 0 \end{bmatrix}, \begin{bmatrix} 0.8 & 0.8 & 0.8 & 0.8 & 0.8 \\ 0.6 & 0.6 & 0.6 & 0.6 & 0.6 \\ 0.4 & 0.4 & 0.6 & 0.4 & 0.4 \\ 0.2 & 0.4 & 0.8 & 0.4 & 0.2 \\ 0.4 & 0.4 & 0.6 & 0.4 & 0.4 \\ 0.6 & 0.6 & 0.6 & 0.6 & 0.6 \\ 0.8 & 0.8 & 0.8 & 0.8 & 0.8 \end{bmatrix} \right]$$

$$= \text{max rows} \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0.5 & 0.5 & 0.5 & 0.5 & 0.5 \\ 0.4 & 0.4 & 0.6 & 0.4 & 0.4 \\ 0.2 & 0.4 & 0.8 & 0.4 & 0.2 \\ 0.4 & 0.4 & 0.6 & 0.4 & 0.4 \\ 0.5 & 0.5 & 0.5 & 0.5 & 0.5 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$T = A'OR = [0.5 \ 0.5 \ 0.8 \ 0.5 \ 0.5]$$

The associated accelerometer bias using Max-min

$$\text{Composition is } \left\{ \frac{0.5}{0.25} + \frac{0.5}{0.27} + \frac{0.8}{0.3} + \frac{0.5}{0.33} + \frac{0.5}{0.35} \right\}$$

ii) Max-product composition $T = A'OR$

$$T = \text{Max rows} \begin{bmatrix} 0 & 0.5 & 0.7 & 0.95 & 0.7 & 0.5 \end{bmatrix} \cdot \begin{bmatrix} 0.8 & 0.8 & 0.8 & 0.8 & 0.8 \\ 0.6 & 0.6 & 0.6 & 0.6 & 0.6 \\ 0.4 & 0.4 & 0.6 & 0.4 & 0.4 \\ 0.2 & 0.4 & 0.8 & 0.4 & 0.2 \\ 0.4 & 0.4 & 0.6 & 0.4 & 0.4 \\ 0.6 & 0.6 & 0.6 & 0.6 & 0.6 \\ 0.8 & 0.8 & 0.8 & 0.8 & 0.8 \end{bmatrix}$$

$$= \text{max rows} \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0.3 & 0.3 & 0.3 & 0.3 & 0.3 \\ 0.28 & 0.28 & 0.42 & 0.28 & 0.28 \\ 0.19 & 0.38 & 0.76 & 0.38 & 0.19 \\ 0.28 & 0.28 & 0.42 & 0.28 & 0.28 \\ 0.3 & 0.3 & 0.3 & 0.3 & 0.3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$= [0.3 \ 0.38 \ 0.76 \ 0.38 \ 0.3]$$

The associated accelerometer bias using Max-product

$$\text{Composition is } \left\{ \frac{0.3}{0.25} + \frac{0.38}{0.27} + \frac{0.76}{0.3} + \frac{0.38}{0.33} + \frac{0.3}{0.35} \right\}$$