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TECHNOLOGY, RESEARCH, SOCIAL INNOVATION & PARTNERSHIPS

# Design and Analysis of Algorithm

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DEPARTMENT OF COMPUTER SCIENCE AND ENGINEERING

# DAA Objectives & Outcomes

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## Course Objectives:

- Study the performance analysis of algorithms
- Select algorithmic strategies to solve given problem.
- Explore solution space to solve the problems.
- Provide the knowledge about complexity theory

## Course Outcomes:

1. Analyze the algorithm complexity using asymptotic notations and describe the divide-and-conquer paradigm and recite algorithms that employ this paradigm.
2. Describe greedy and dynamic programming algorithmic strategies and analysis algorithms that employ this paradigm.
3. Illustrate the solution space using backtracking and branch and bound algorithmic techniques.
4. Describe the concept of complexity theory.

## Course prerequisite

Data Structure II

C, C++, Java or other programming languages

## Module I - Fundamentals of Algorithm

The Role of Algorithms in Computing Algorithmic specifications, Analyzing algorithm, asymptotic notations, order of growth

Algorithm design strategy, Divide and conquer - Merge Sort, Quick sort, Large Integer multiplication, solving recurrences

( substitution method & Master's theorem )

# Why Study this Course?

REF BOOK: THOMAS CORMEN

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Donald E. Knuth stated “Computer Science is the study of algorithms”

- Cornerstone of computer science. Programs will not exist without algorithms.

Algorithms are needed (most of which are novel) to solve the many problems listed here

- Computational Primitives –CG –Geometric Algorithms
- Communication Network –Shortest path Algorithms
- Genome Structure in Bioinformatics –Dynamic Programming
- Search engines –Page Rank Algorithm by Google
- Challenging (i.e. Good for brain !!!)

Real Blend of Creativity and Precision

Very interesting if you can concentrate on this course



# Algorithm: A brief History

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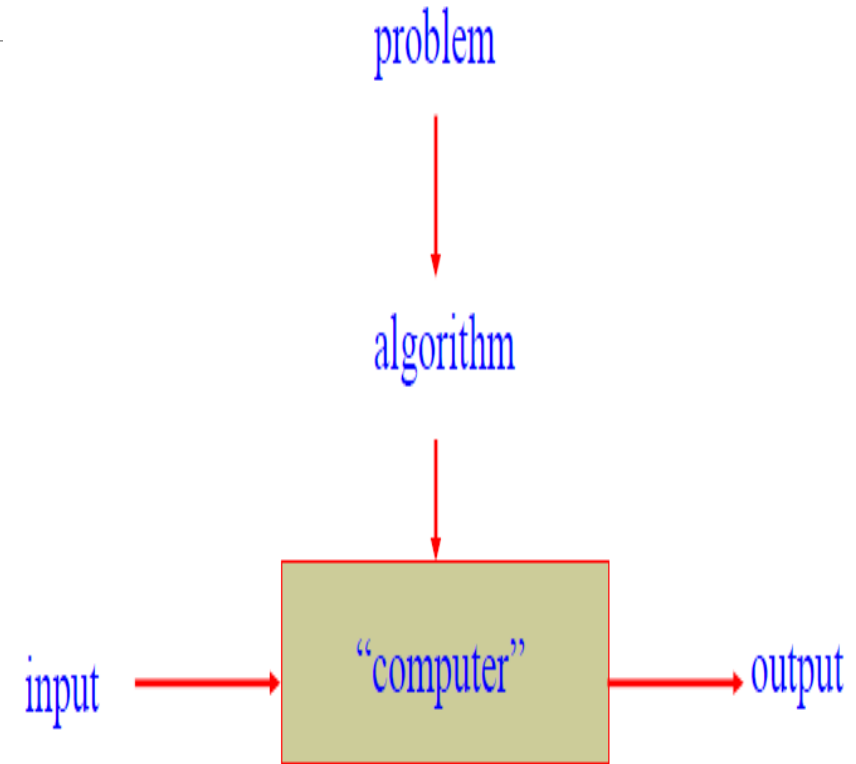
- The word algorithm comes from the name of **Persian author, Abu Ja'far Mohammed ibn Musa al Khwarizmi (c. 825 A.D.)**, who wrote a textbook on mathematics.
- The book was translated into Latin in the 12th century under the title **Algoritmi de numero Indorum**. This title means "Algoritmi on the numbers of the Indians", where "Algoritmi" was the translator's Latinization of Al-Khwarizmi's name.
- Many centuries later, decimal system was adopted in Europe, and the *procedures in Al Khwarizmi's book were named after him as "Algorithms"*.



# What is an Algorithm?

An algorithm is a sequence of unambiguous instructions for solving a computational problem i.e., for obtaining a required output for any legitimate input in a finite amount of time.

It is any well defined computational procedure that takes some value or set of values as **input** and produces some value, or set of values as **output**



# Algorithm & its Properties

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More precisely, An *algorithm* is a finite set of instructions that accomplishes a particular task.

Algorithm must satisfy the following properties:

- Input
  - Valid inputs must be clearly specified.
- Output
  - can be proved to produce the correct output given a valid input.
- Finiteness
  - terminates after a finite number of steps
- Definiteness
  - Each instruction must be clear and unambiguously specified
- Effectiveness
  - Every instruction must be sufficiently simple and basic.

# Examples of Algorithms – Computing the Greatest Common Divisor of Two Integers

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**Problem:** Find  $\text{gcd}(m,n)$ , the greatest common divisor of two nonnegative, not both zero integers  $m$  and  $n$

//First try –**School level algorithm:**

Step1: factorize  $m$ . ( $m = m_1 * m_2 * m_3 \dots$ )

Step2: factorize  $n$ . ( $n = n_1 * n_2 * \dots$ )

Step 3: Identify common factors , multiply and return.



# Pseudocode of Euclid's Algorithm

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**Algorithm : *Euclid* ( $m, n$ )**

//Computes  $\text{gcd}(m, n)$  by Euclid's algorithm

//Input: Two non negative, not-both-zero integers  $m$  and  $n$

//Output: Greatest common divisor of  $m$  and  $n$   **$\text{gcd}(m, n) = \text{gcd}(n, m \bmod n)$**

While ( $m$  does not divide  $n$ ) **do**

$r \leftarrow n \bmod m$

$n \leftarrow m$

$m \leftarrow r$

return  $m$

**Questions:**

Finiteness: how do we know that Euclid's algorithm actually comes to a stop?

Definiteness: non-ambiguity

Effectiveness: effectively computable.

**Which algorithm is faster, the Euclid's or previous one?**

# Example of Euclid's Algorithm

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## Simple Algorithm

$m = 36, n = 48$

$m = 2 * 2 * 3 * 3$

$n = 2 * 2 * 2 * 2 * 3$

Common factors

2, 2, 3

GCD = 12

9 divisions

## Euclid Algorithm

36 divides 48

$r = 48 \bmod 36$

$n = 36$

$m = 12$

Return 12

2 divisions

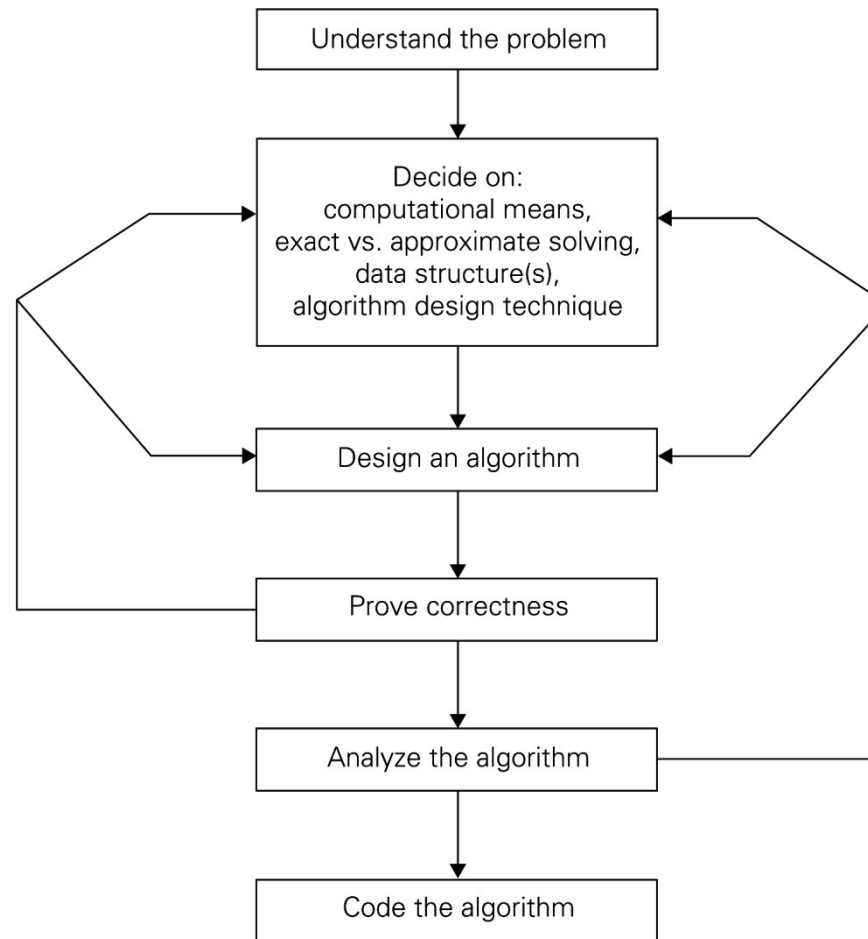
- Another example:  
 $m = 434$  and  $n = 966$

# Fundamentals of Algorithmic Problem Solving

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- Understanding the problem
  - Asking questions, do a few examples by hand, think about special cases, etc.
- Deciding on
  - Exact vs. approximate problem solving
- Appropriate data structure
- Design an algorithm
- Proving correctness
- Analyzing an algorithm
  - Time efficiency : how fast the algorithm runs
  - Space efficiency: how much extra memory the algorithm needs.
- Coding an algorithm

# Algorithm Design and Analysis Process



# Algorithms as a Technology

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Even if computers were infinitely fast and memory was plentiful and free

- Study of algorithms still important – still need to establish algorithm correctness
- Since time and space resources are infinitely fast, any correct algorithm for solving a problem would do.

Real-world computers may be fast but not infinitely fast.

Memory is cheap but not free

Hence Computing time is bounded resource and so need space in memory.

We should use resources wisely by efficient algorithm in terms of space and time

# Algorithm Efficiency

## Time and space efficiency are the goal

Algorithms often differ dramatically in their efficiency

- Example: Two sorting algorithms
  - **INSERTION-SORT** – time efficiency is  $c_1 n^2$
  - **MERGE-SORT** – time efficiency is  $c_1 n \log n$
- For which problem instances would one algorithm be preferable to the other?
- For example,
- A **faster computer 'A'** ( $10^{10}$  instructions/sec) running insertion sort against a **slower computer 'B'** ( $10^7$  instructions/sec) running merge sort. Suppose that  $c_1=2$ ,  $c_2=50$  and  $n=10^7$ .

- To sort  $10^{10}$  numbers, computer 'A' takes

$$\begin{aligned}
 &= \frac{c_1 * n^2 \text{ Instructions}}{\text{Instructions per second}} \\
 &= \frac{2 * (10^7)^2 \text{ Instructions}}{10^{10} \text{ Instructions per second}} = \mathbf{20,000 \text{ seconds}}
 \end{aligned}$$

- While, computer 'B' takes

$$\begin{aligned}
 &= \frac{c_2 * n \log_2 n \text{ Instructions}}{\text{Instructions per second}} \\
 &= \frac{50 * 10^7 \log_2 10^7 \text{ Instructions}}{10^7 \text{ Instructions per second}} = \mathbf{1163 \text{ seconds}}
 \end{aligned}$$

# Efficiency

Problem Size	Machine A Insertion-Sort	Machine B Merge- Sort
$n$	$2n^2/10^9$	$50n\log n/10^7$
10,000	0.20	0.66
50,000	5.00	3.90
100,000	20.00	8.30
500,000	500.00	47.33
1,000,000	2,000.00	99.66
5,000,000	50,000.00	556.34
10,000,000	200,000.00	1,162.67
50,000,000	5,000,000.00	6,393.86

# Methods of Specifying an Algorithm

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- Natural language
  - Ambiguous
    - Example : “Mike ate the sandwich on a bed.”
- Flowchart
  - Graphic representations called flowcharts , only if the algorithm is small and simple.
- Pseudocode
  - A mixture of a natural language and programming language-like structures
  - Precise and concise.
- Pseudocode in this course
  - omits declarations of variables
  - use indentation to show the scope of such statements as for, if, and while.
  - use □ for assignment



# Pseudocode Conventions

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- Comments begin with `//` and continue until the end of line.
- Blocks are indicated with matching braces `{` and `}`. A compound statement (i.e., a collection of simple statements) can be represented as a block. The body of a procedure also forms a block. Statements are delimited by;
- Assignment of values to variables is done using the assignment statement
- `<variable>:=<expression>;`
- There are two Boolean values *true* and *false*. In order to produce these values,
  - Logical operators : *and*, *or*, and *not*
  - Relational operators `<`, `≤`, `=`, `≠`, `≥`, and `>`
- Elements of multidimensional arrays are accessed using `[` and `]`. Ex `A[i,j]`

# Pseudocode Conventions

- Looping statement can be employed as follows :

(while, for, repeat, until)

## While Loop:

```
While < condition > do
{
<statement-1>
.
.
.
<statement-n>
}
```

## For Loop:

```
For variable: = value-1 to value-2 step
step-value do
{
<statement-1>
.
.
.
<statement-n>
}
```

```
For i:=1 to 10 step 2 do
{
}
i=1,3,5,7,9
For i:=1 to 10 do
{
}
i=1,2,3,...,10.
```

A conditional statement has the following forms:

- If <condition> **then** <statement>
- If <condition> **then** <statement 1> **else** <statement 2>

We also employ the following case statement:

## case

```
{
: <condition 1>: <statement 1>
.
: <condition n>: <statement n>
: else: <statement n + 1>
}
```

# Pseudocode Conventions

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Input and output are done using the instructions ***read*** and ***write***. No format is used to specify the size of input or output quantities.

An algorithm consists of a heading and a body. The heading takes the form

**Algorithm** Name (<parameter list>)

{

// body

}

**Example** : Algorithm to find and return the maximum of n given numbers:

**Algorithm** Max (A, n)

// A is an array of size n.

{

Result :=A[1];

**For** i :=2 to n **do**

**If** A[i] > Result **then** Result :=A[i];

**Return** Result;

}

# Analysis of Algorithms

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## Two main issues related to algorithms

- How to design algorithms
- How to analyze algorithm efficiency

## Analysis of Algorithms

- How good is the algorithm?
  - time efficiency
  - space efficiency
- Does there exist a better algorithm?
  - lower bounds
  - optimality

# Common Rates of Growth

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Let  $n$  be the size of input to an algorithm, and  $k$  some constant. The following are common rates of growth.

- Constant:  $\Theta(k)$ , for example  $\Theta(1)$
- Linear:  $\Theta(n)$
- Logarithmic:  $\Theta(\log_k n)$
- Linear :  $n$   $\Theta(n)$  or  $n \log n$ :  $\Theta(n \log_k n)$
- Quadratic:  $\Theta(n^2)$
- Polynomial:  $\Theta(n^k)$
- Exponential:  $\Theta(k^n)$

# Why Analyse?

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- Practical reasons:
  - Resources are scarce
  - Greed to do more with less
  - Avoid performance bugs
- Core Issues:
- Predict performance
  - How much time does binary search take?
- Compare algorithms
  - How quick is Quicksort?
- Provide guarantees
  - Size not with standing, Red-Black tree inserts in  $O(\log n)$
- Understand theoretical basis
  - Sorting by comparison cannot do better than  $(n \log n)$

# What to analyse?

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**Core Issue: Cannot control what we cannot measure**

Time

- The *time complexity*,  $T(n)$ , taken by a program P is the sum of the running times for each statement executed

Space

The *space complexity* of a program is the amount of memory that it needs to run to completion

Examples : Sum of Natural Numbers

// Sum of Natural Numbers

Algorithm sum (a, n)

```
{
s := 0 ;
For i := 1 to n do
s := s + a[i];
return s;
}
```

Time  $T(n) = n$  (additions)

Space  $S(n) = 2$  (n, s)

# Tabular Method

Iterative function to sum a list of numbers (steps/execution )

Statement	s/e	Frequency	Total steps
Algorithm sum (a, n)	0	-	0
{	0	-	0
s := 0 ;	1	1	1
For i := 1 to n do	1	n+1	n+1
s := s + a[i];	1	n	n
return s;	1	1	1
}			
Total T(n)			2n+3

Machine Model: Random  
Access Machine (RAM)

Computing Model

- Input data & size
- Operations
- Intermediate Stages
- Output data & size



# Asymptotic Analysis

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Core Idea: Cannot compare actual times; hence compare Growth or how time increases with input

- $O$  notation (“Big Oh”)
- $\Omega$  notation (Omega)
- $\Theta$  notation (Theta)
- $o$  notation (Little oh)
- $\omega$  notation (Little omega)

# ASYMPTOTICS NOTATIONS

## O-notation (**Big Oh**)

REF BOOK: THOMAS CORMEN

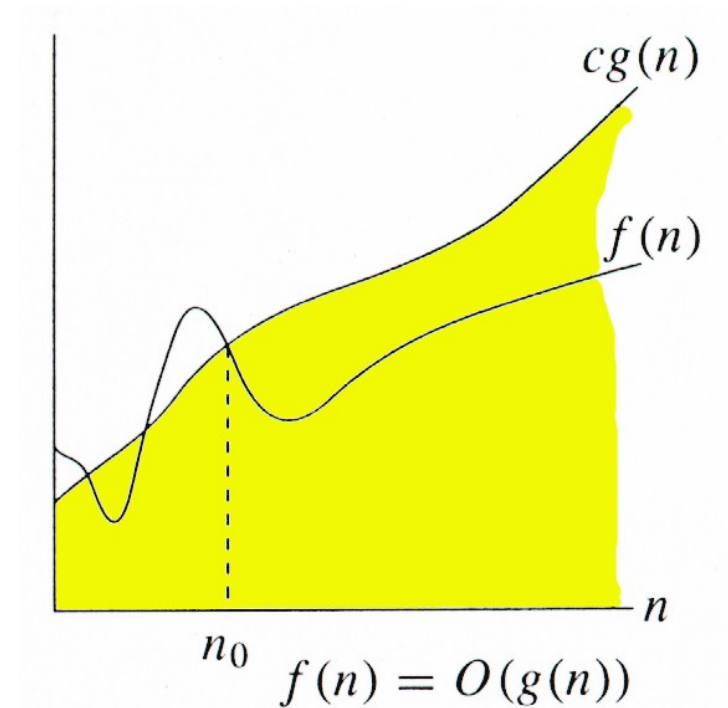
### *Asymptotic Upper Bound*

For a given function  $g(n)$ , we denote  $O(g(n))$  as the set of functions:

$$O(g(n)) = \{ f(n) \mid \text{there exists positive constants } c \text{ and } n_0 \text{ such that } 0 \leq f(n) \leq c g(n) \text{ for all } n \geq n_0 \}$$

It is used to represent the worst case growth of an algorithm in time or a data structure in space when they are dependent on  $n$ , where  $n$  is big enough

Example :



# Big Oh - Example

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$$f(n) = n^2 + 5n = O(n^2)$$

$$g(n) = n^2 \dots\dots\dots c = 2$$

n	$n^2 + 5n$	$2n^2$
1	5	2
2	14	8
5	50	50

$$f(n) \leq c g(n) \text{ for all } n \geq n_0 \text{ where } c=2 \text{ \& } n_0=5$$

# Big Oh - Example

---

Let  $f(N) = 2N^2$ . Then

- $f(N) = O(N^4)$  (loose bound)
- $f(N) = O(N^3)$  (loose bound)
- $f(N) = O(N^2)$  (It is the best answer and the bound is asymptotically tight.)

$O(N^2)$ : reads “order N-squared” or “Big-Oh N-squared”.

# Big Oh - Example

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Prove that if  $T(n) = 15n^3 + n^2 + 4$ ,  $T(n) = O(n^3)$ .

Proof.

Let  $c = 20$  and  $n_0 = 1$ .

Must show that  $0 \leq f(n)$  and  $f(n) \leq cg(n)$ .

$0 \leq 15n^3 + n^2 + 4$  for all  $n \geq n_0 = 1$ .

$f(n) = 15n^3 + n^2 + 4 \leq 20n^3$  ( $20g(n) = cg(n)$ )

As per definition of Big O, hence  $T(n) = O(n^3)$

# ASYMPTOTICS NOTATIONS

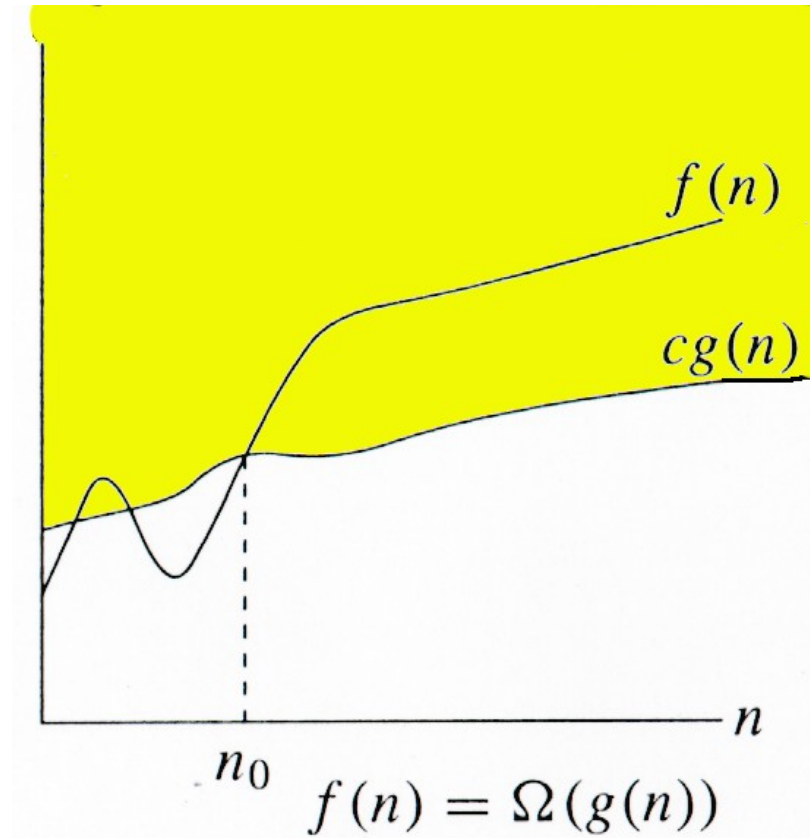
## $\Omega$ -notation

REF BOOK: THOMAS CORMEN

### *Asymptotic lower bound*

$\Omega(g(n))$  represents a set of functions such that:

$\Omega(g(n)) = \{f(n): \text{there exist positive constants } c \text{ and } n_0 \text{ such that } 0 \leq c g(n) \leq f(n) \text{ for all } n \geq n_0\}$



# Big Omega - Example

Example 1 :

$$f(n) = n^2 + 5n$$

$$g(n) = n^2 \dots\dots\dots c = 1$$

n	$n^2 + 5n$	$c \cdot n^2$
1	5	1
2	14	4
5	50	25

$f(n) \geq c g(n)$  for all  $n \geq n_0$  where  $c=1$  &  $n_0=1$

Example 1 :

Prove that if  $T(n) = 15n^3 + n^2 + 4$ ,  $T(n) = \Omega(n^3)$ .

Proof.

Let  $c = 15$  and  $n_0 = 1$ .

Must show that  $0 \leq cg(n)$  and  $cg(n) \leq f(n)$ .

$0 \leq 15n^3$  for all  $n \geq n_0 = 1$ .

$$cg(n) = 15n^3 \leq 15n^3 + n^2 + 4 = f(n)$$

# ASYMPTOTICS NOTATIONS

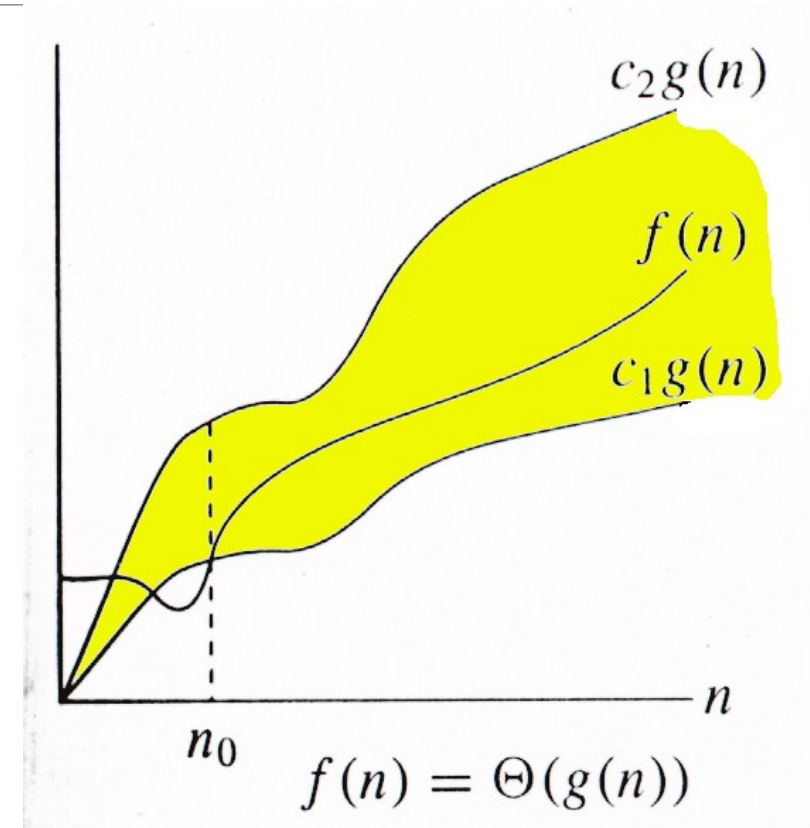
## $\Theta$ -notation

REF BOOK: THOMAS CORMEN

### *Asymptotic tight bound*

$\Theta(g(n))$  represents a set of functions such that:

$\Theta(g(n)) = \{f(n): \text{there exist positive constants } c_1, c_2, \text{ and } n_0 \text{ such that } 0 \leq c_1 g(n) \leq f(n) \leq c_2 g(n) \text{ for all } n \geq n_0\}$





# Theta Example

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$f(N) = \Theta(g(N))$  iff  $f(N) = O(g(N))$  and  $f(N) = \Omega(g(N))$

It can be read as “ $f(N)$  has order exactly  $g(N)$ ”.

The growth rate of  $f(N)$  equals the growth rate of  $g(N)$ . The growth rate of  $f(N)$  is the same as the growth rate of  $g(N)$  for large  $N$ .

Theta means the bound is the tightest possible.

If  $T(N)$  is a polynomial of degree  $k$ ,  $T(N) = \Theta(N^k)$ .

For logarithmic functions,  $T(\log_m N) = \Theta(\log N)$ .

# o notation (Little oh)

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The function  $f(n) = o(g(n))$  iff  $\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = 0$

$o(g(n)) = \{f(n): \exists c > 0, \exists n_0 > 0 \text{ such that}$   
 $\forall n \geq n_0, \text{ we have } 0 \leq f(n) < cg(n)\}.$

Example: The function  $3n + 2 = o(n^2)$  as  $\lim_{n \rightarrow \infty} \frac{3n + 2}{n^2} = 0$

# $\omega$ notation (Little omega)

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The function  $f(n) = \omega(g(n))$  iff

$$\lim_{n \rightarrow \infty} \frac{g(n)}{f(n)} = 0$$

$\mathcal{W}(g(n)) = \{f(n): \exists c > 0, \exists n_0 > 0 \text{ such that}$   
 $\forall n \geq n_0, \text{ we have } 0 < cg(n) < f(n)\}.$

# Asymptotic Notations

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It is a way to compare “sizes” of functions

**O-notation** -----Less than equal to (“ $\leq$ ”)

**$\Theta$ -notation** -----Equal to (“ $=$ ”)

**$\Omega$ -notation** -----Greater than equal to (“ $\geq$ ”)

$$\mathbf{O} \approx \leq$$

$$\mathbf{\Omega} \approx \geq$$

$$\mathbf{\Theta} \approx =$$

$$\mathbf{o} \approx <$$

$$\mathbf{\omega} \approx >$$

# Examples On Asymptotic Notations

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Explain How is  $f(x) = 4n^2 - 5n + 3$  is  $O(n^2)$

Show that

- 1)  $30n+8$  is  $O(n)$
- 2)  $100n + 5 \neq \Omega(n^2)$
- 3)  $5n^2 = \Omega(n)$
- 4)  $100n + 5 = O(n^2)$
- 5)  $n^2/2 - n/2 = \Omega(n^2)$

# Algorithm Design Techniques/Strategies

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REF BOOK: THOMAS CORMEN

- Brute force
- Divide and conquer
- Space and time tradeoffs
- Greedy approach
- Dynamic programming
- Backtracking
- Branch and bound

# Divide & Conquer

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## Control Abstraction

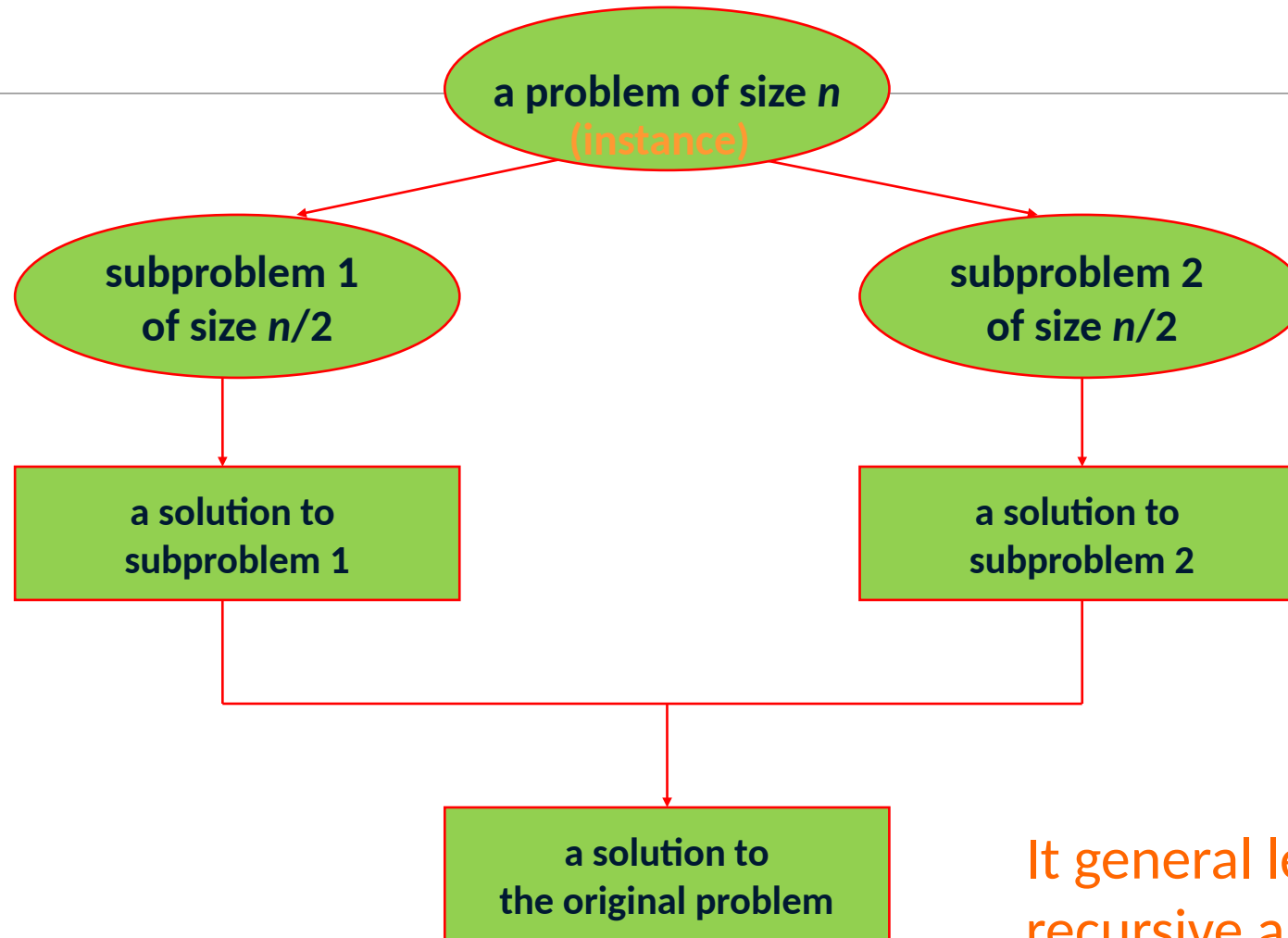
DANDC (P)

```
{  
if SMALL (P) then return S (p);  
else  
{  
divide p into smaller instances p1, p2, .... Pk, k >= 1;  
apply DANDC to each of these sub problems;  
return (COMBINE (DANDC (p1) , DANDC (p2),..., DANDC (pk));  
}  
}
```

**Divide** the problem into smaller sub problems  
**Conquer** the sub problems by solving them recursively.  
**Combine** the solutions to the sub problems into the solution of the original problem.

# Divide-and-Conquer Technique (cont.)

REF BOOK: INTERNET



It general leads to a recursive algorithm!



# Time complexity of the general algorithm

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A Recurrence is an equation or inequality that describes a function in terms of its value on smaller inputs

Special techniques are required to analyze the space and time required

$$T(n) = \begin{cases} aT(n/b) + D(n) + C(n) & , n \geq c \\ O(1) & , n < c \end{cases}$$

Time complexity (recurrence relation):

where  $D(n)$  : time for splitting

$C(n)$  : time for conquer

$c$  : a constant

# Methods for Solving recurrences

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- Substitution Method
  - We guess a bound and then use mathematical induction to prove our guess correct.
- Recursion Tree
  - Convert recurrence into tree
- Master Method

# Math You need to Review

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## properties of logarithms:

$$\log_b(xy) = \log_b x + \log_b y$$

$$\log_b(x/y) = \log_b x - \log_b y$$

$$\log_b x^a = a \log_b x$$

$$\log_b a = \log_x a / \log_x b$$

## ● properties of exponentials:

$$a^{(b+c)} = a^b a^c$$

$$a^{bc} = (a^b)^c$$

$$a^b / a^c = a^{(b-c)}$$

$$b = a^{\log_a b}$$

$$b^c = a^{c \cdot \log_a b}$$

# Substitution Method

- Sum of  $n$  Natural Numbers

```
int sum(int n) {
    int s = 0;
    for(; n > 0; --n)
        s = s + n;
    return s;
}
```

$$\begin{aligned} T(n) &= T(n-1) + 1, & n > 1 \\ &= 1, & n = 1 \end{aligned}$$

Solve Recurrence in Long hand:

$$\begin{aligned} T(n) &= T(n-1) + 1 \\ &= T(n-2) + (1+1) \\ &= \dots \\ &= T(1) + (n-1) \\ &= 1 + (n-1) \\ &= n \end{aligned}$$

- Time  $T(n)$  (additions)

- Space  $S(n) = 2$

- Factorial (Recursive)

```
int fact(int n) {
    if (0 != n) return n*fact(n-1);
    return 1;
}
```

- Time  $T(n)$  (multiplication)

$$\begin{aligned} T(n) &= T(n-1) + 1, & n > 0 \\ &= 0, & n = 0 \end{aligned}$$

$$T(n) = n$$

# Quick Sort

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$$\begin{aligned}T(n) &= 2T(n/2) + O(n) \\&= 2(2(n/2^2) + (n/2)) + n \\&= 2^2 T(n/2^2) + n + n \\&= 2^2 (T(n/2^3) + (n/2^2)) + n + n \\&= 2^3 T(n/2^3) + \underline{n + n + n} \\&= \mathbf{n \log n}\end{aligned}$$

# Binary Search

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## EXAMPLE 2: BINARY SEARCH

$$T(n) = O(1) + T(n/2)$$

$$T(1) = 1$$

Above is another example of recurrence relation and the way to solve it is by Substitution.

$$T(n) = T(n/2) + 1$$

$$= T(n/2^2) + 1 + 1$$

$$= T(n/2^3) + 1 + 1 + 1$$

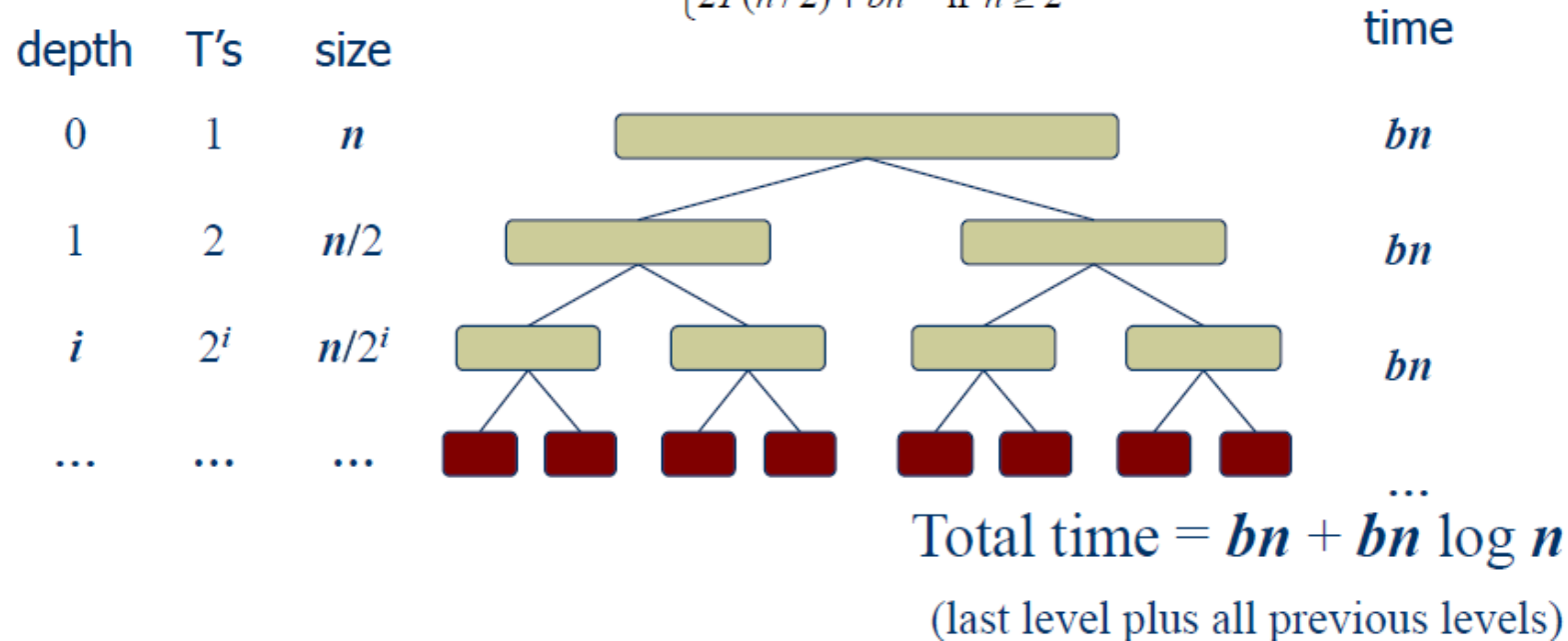
$$= \log n$$

$$T(n) = O(\log n)$$

# The Recursion Tree

Draw the recursion tree for the recurrence relation and look for a pattern:

$$T(n) = \begin{cases} b & \text{if } n < 2 \\ 2T(n/2) + bn & \text{if } n \geq 2 \end{cases}$$



# Master Theorem

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Master method provides a “cookbook” method for solving recurrences of the following form

$$T(n) = a T(n/b) + f(n)$$

where  $a \geq 1$ ,  $b > 1$ . If  $f(n)$  is asymptotically positive function.  $T(n)$  has following asymptotic bounds:

There are 3 cases:

1. If  $f(n) = O(n^{\log_b a - \epsilon})$  for some constant  $\epsilon > 0$ , then  $T(n) = \Theta(n^{\log_b a})$ .
2. If  $f(n) = \Theta(n^{\log_b a} \log^k n)$  with  $k \geq 0$ , then  $T(n) = \Theta(n^{\log_b a} \log^{k+1} n)$ .
3. If  $f(n) = \Omega(n^{\log_b a + \epsilon})$  with  $\epsilon > 0$ , and  $f(n)$  satisfies the regularity condition, then  $T(n) = \Theta(f(n))$ .  
Regularity condition:  $af(n/b) \leq cf(n)$  for some constant  $c < 1$  and all sufficiently large  $n$ .



# Example of Master Method

REF BOOK: THOMAS CORMEN

To use the master theorem, we simply plug the numbers into the formula

**Example 1:**  $T(n) = 9T(n/3) + n$ . Here  $a = 9$ ,  $b = 3$ ,  $f(n) = n$ , and  $n^{\log_b a} = n^{\log_3 9} = \Theta(n^2)$ . Since  $f(n) = O(n^{\log_3 9 - \epsilon})$  for  $\epsilon = 1$ , case 1 of the master theorem applies, and the solution is  $T(n) = \Theta(n^2)$ .

**Example 2:**  $T(n) = T(2n/3) + 1$ . Here  $a = 1$ ,  $b = 3/2$ ,  $f(n) = 1$ , and  $n^{\log_b a} = n^0 = 1$ . Since  $f(n) = \Theta(n^{\log_b a})$ , case 2 of the master theorem applies, so the solution is  $T(n) = \Theta(\log n)$ .

**Example 3:**  $T(n) = 3T(n/4) + n \log n$ . Here  $n^{\log_b a} = n^{\log_4 3} = O(n^{0.793})$ . For  $\epsilon = 0.2$ , we have  $f(n) = \Omega(n^{\log_4 3 + \epsilon})$ . So case 3 applies if we can show that  $af(n/b) \leq cf(n)$  for some  $c < 1$  and all sufficiently large  $n$ . This would mean  $3\frac{n}{4} \log \frac{n}{4} \leq cn \log n$ . Setting  $c = 3/4$  would cause this condition to be satisfied.

**Example 4:**  $T(n) = 2T(n/2) + n \log n$ . Here the master method does not apply.  $n^{\log_b a} = n$ , and  $f(n) = n \log n$ . Case 3 does not apply because even though  $n \log n$  is asymptotically larger than  $n$ , it is not polynomially larger. That is, the ratio  $f(n)/n^{\log_b a} = \log n$  is asymptotically less than  $n^\epsilon$  for all positive constants  $\epsilon$ .

# Master Method (Simplified)

---

Let  $T(n)$  be a monotonically increasing function that satisfies

$$T(n) = a T(n/b) + f(n)$$

$$T(1) = c$$

where  $a \geq 1$ ,  $b \geq 2$ ,  $c > 0$ . If  $f(n)$  is  $\Theta(n^d)$  where  $d \geq 0$  then solution to recurrence relation is given as

$$\text{Case 1: } T(n) \in \begin{matrix} \Theta(n^d) & \text{if } a < b^d \\ \Theta(n^d \log n) & \end{matrix}$$

$$\text{Case 2: } T(n) \in \begin{matrix} \Theta(n^{\log_b a}) & \text{if } a = b^d \end{matrix}$$

$$\text{Case 3: } T(n) \in \begin{matrix} \Theta(n^{\log_b a}) & \text{if } a > b^d \end{matrix}$$

# Divide-and-Conquer Examples

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Sorting : Mergesort and Quicksort

Binary tree traversals

Binary search

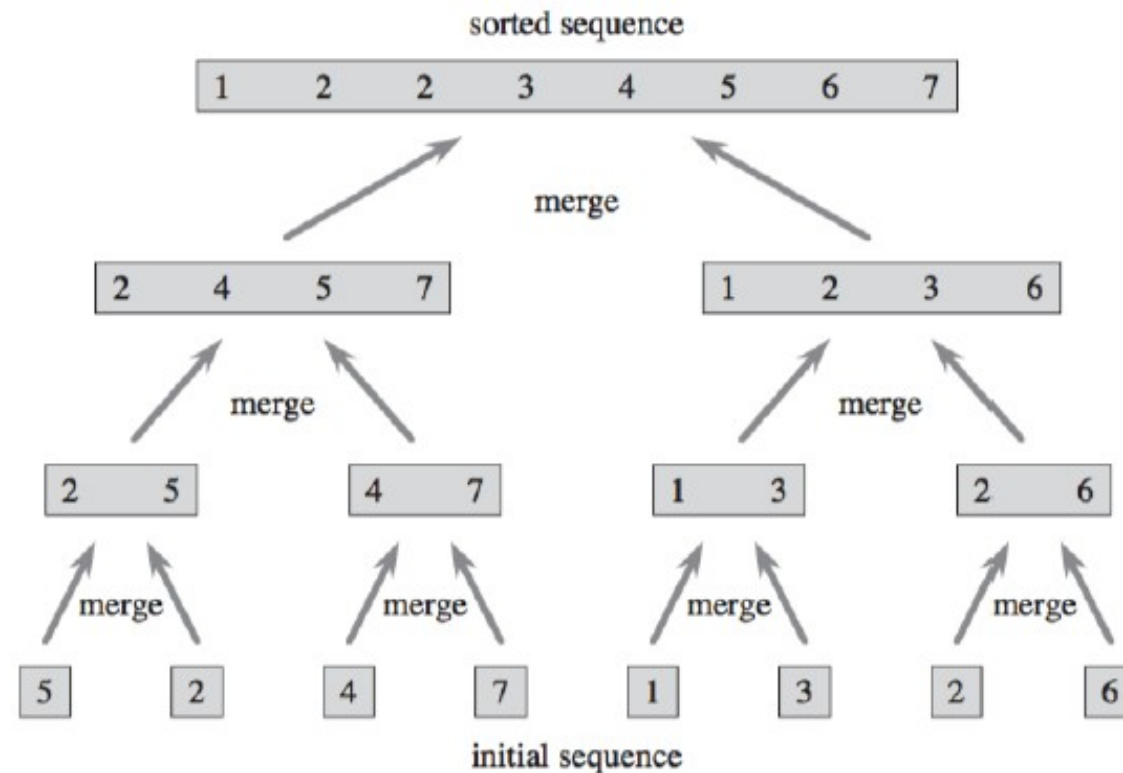
Multiplication of large integers

Matrix multiplication: Strassen's algorithm

Closest-pair and convex-hull algorithms

# Mergesort

Merge sort is a divide and conquer algorithm for sorting arrays. To sort an array, first you split it into two arrays of roughly equal size. Then sort each of those arrays using merge sort, and merge the two sorted arrays.



# Pseudocode of Merge-Sort ( $A, p, r$ )

**INPUT:** a sequence of  $n$  numbers stored in array  $A$

---

**OUTPUT:** an ordered sequence of  $n$  numbers

```
MergeSort ( $A, p, r$ ) // sort  $A[p..r]$  by divide & conquer
1  if  $p < r$ 
2    then  $q \leftarrow \lfloor (p+r)/2 \rfloor$ 
3         MergeSort ( $A, p, q$ )
4         MergeSort ( $A, q+1, r$ )
5         Merge ( $A, p, q, r$ ) // merges  $A[p..q]$  with  $A[q+1..r]$ 
```

**Initial Call:** *MergeSort*( $A, 1, n$ )

# Procedure Merge

REF BOOK: THOMAS CORMEN

**Merge( $A, p, q, r$ )**

1  $n_1 \leftarrow q - p + 1$

2  $n_2 \leftarrow r - q$

3 **for**  $i \leftarrow 1$  **to**  $n_1$

4     **do**  $L[i] \leftarrow A[p + i - 1]$

5 **for**  $j \leftarrow 1$  **to**  $n_2$

6     **do**  $R[j] \leftarrow A[q + j]$

7  $L[n_1 + 1] \leftarrow \square$

8  $R[n_2 + 1] \leftarrow \square$

9  $i \leftarrow 1$

10  $j \leftarrow 1$

11 **for**  $k \leftarrow p$  **to**  $r$

12     **do if**  $L[i] \leq R[j]$

13         **then**  $A[k] \leftarrow L[i]$

14              $i \leftarrow i + 1$

15         **else**  $A[k] \leftarrow R[j]$

16              $j \leftarrow j + 1$

Input: Array containing sorted subarrays  $A[p..q]$  and  $A[q+1..r]$ .

Output: Merged sorted subarray in  $A[p..r]$ .

**Sentinels**, to avoid having to check if either subarray is fully copied at **each step**.

# Analysis of Mergesort

---

Running time  $T(n)$  of Merge Sort:

Divide: computing the middle takes  $\Theta(1)$

Conquer: solving 2 sub problems takes  $2T(n/2)$

Combine: merging  $n$  elements takes  $\Theta(n)$

Total:

$$\begin{aligned} T(n) &= \Theta(1) && \text{if } n = 1 \\ T(n) &= 2T(n/2) + \Theta(n) && \text{if } n > 1 \end{aligned}$$

↳  $T(n) = \Theta(n \lg n)$

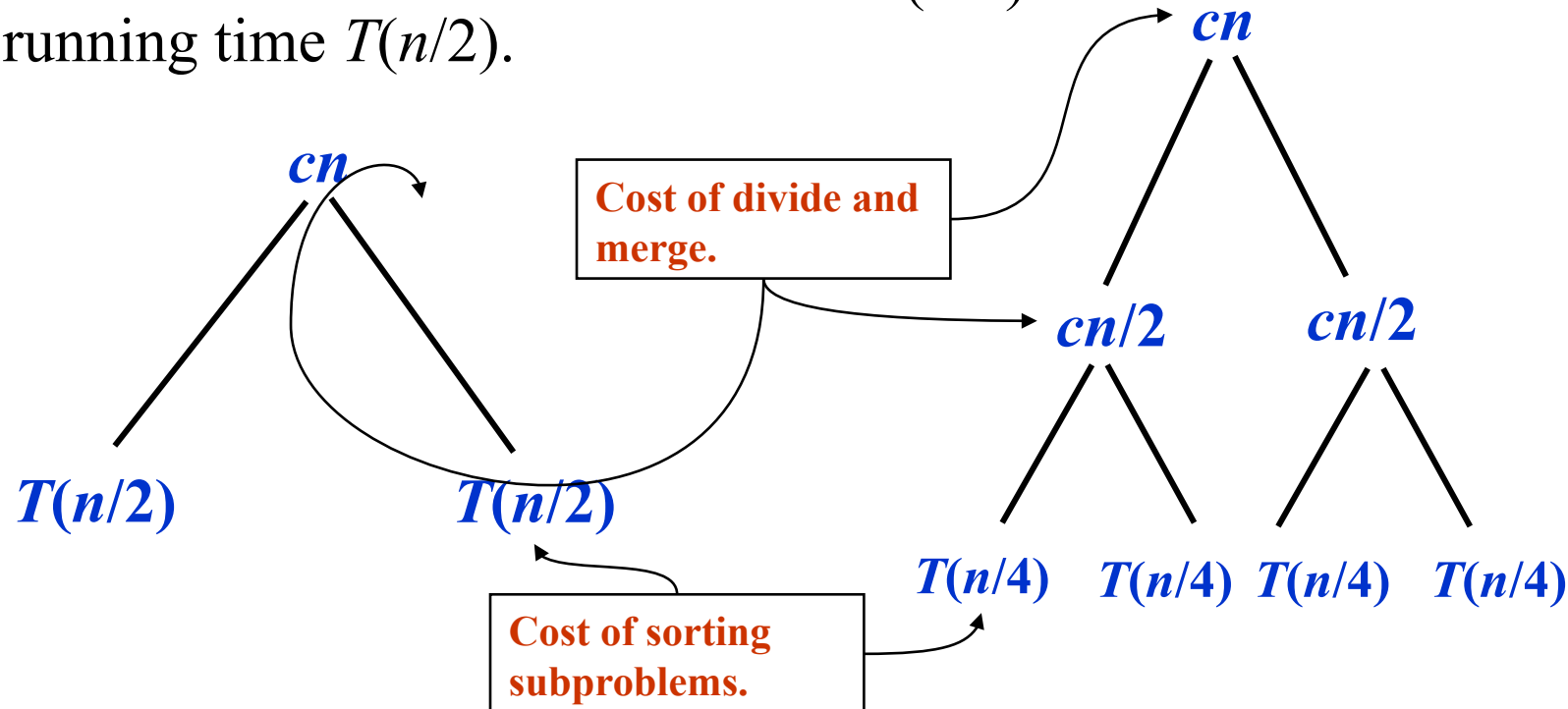
↳ Space requirement:  $\Theta(n)$  (not in-place)

# Recursion Tree for Merge Sort

Ref Book: Thomas Cormen

For the original problem, we have a cost of  $cn$ , plus two subproblems each of size  $(n/2)$  and running time  $T(n/2)$ .

Each of the size  $n/2$  problems has a cost of  $cn/2$  plus two subproblems, each costing  $T(n/4)$ .

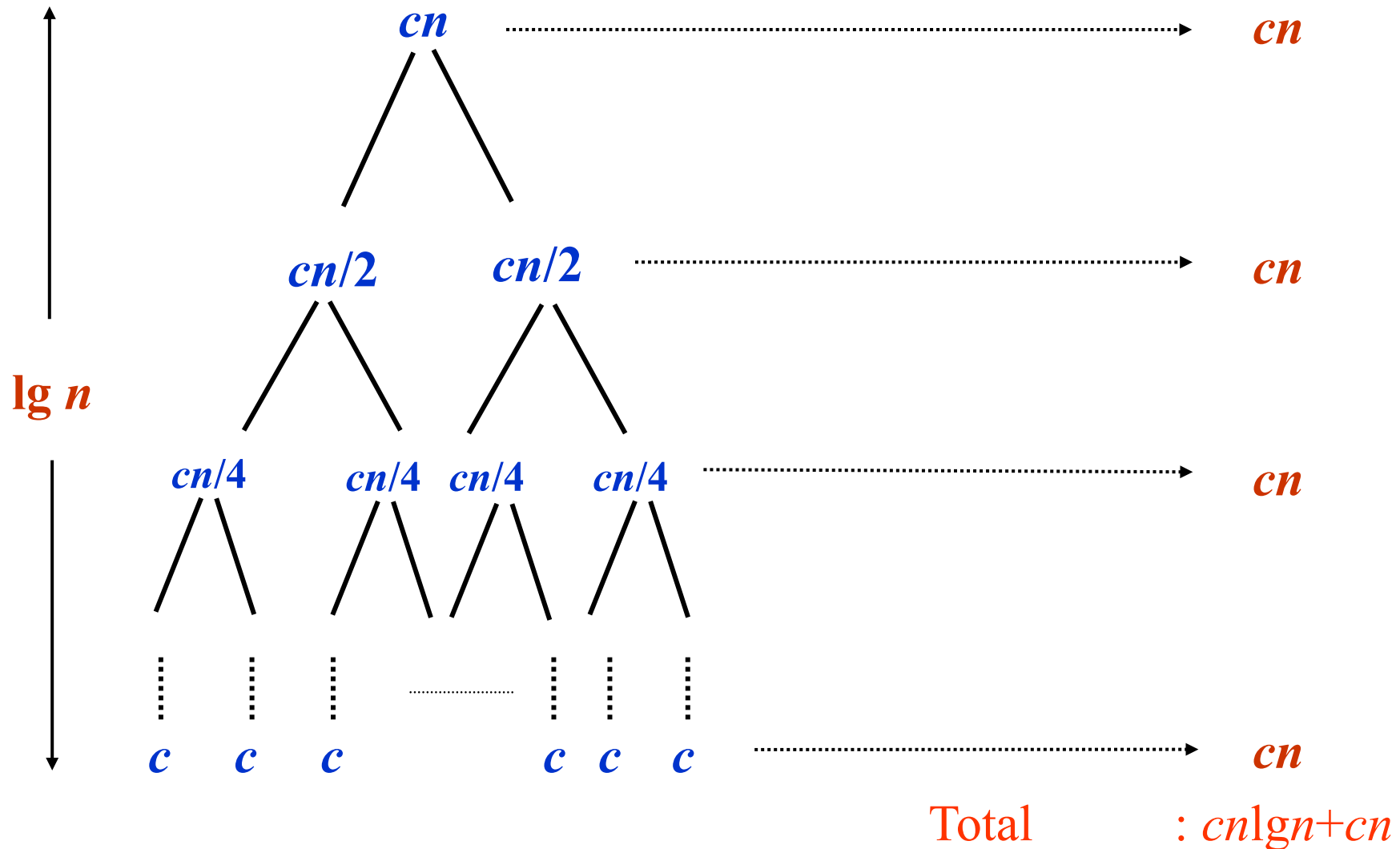




# Recursion Tree for Merge Sort

Ref Book: Thomas Cormen

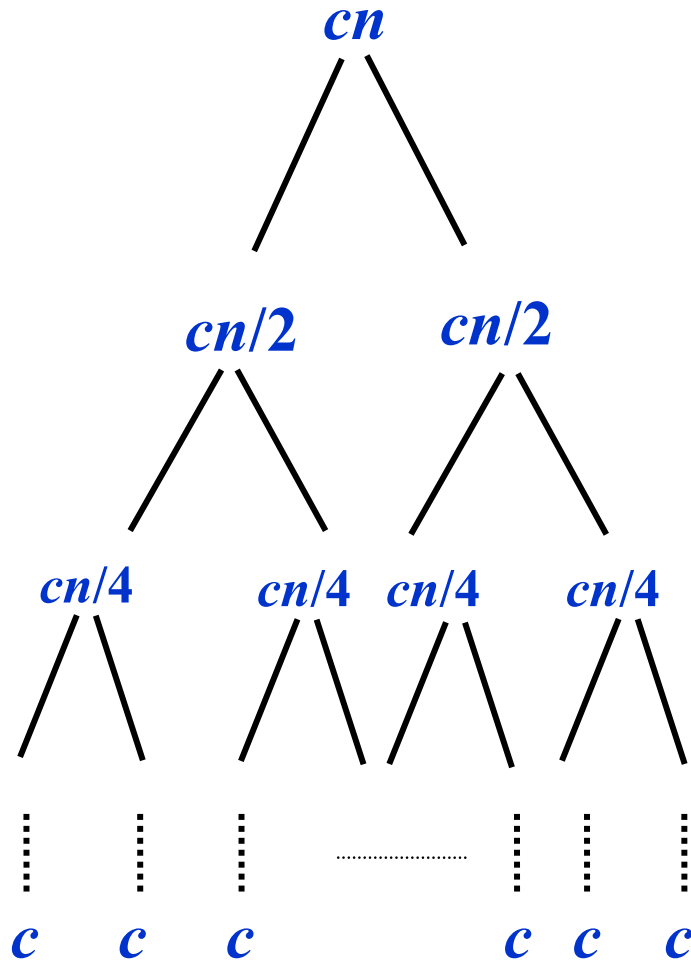
Continue expanding until the problem size reduces to 1.



# Recursion Tree for Merge Sort

Ref Book: Thomas Cormen

Continue expanding until the problem size reduces to 1.

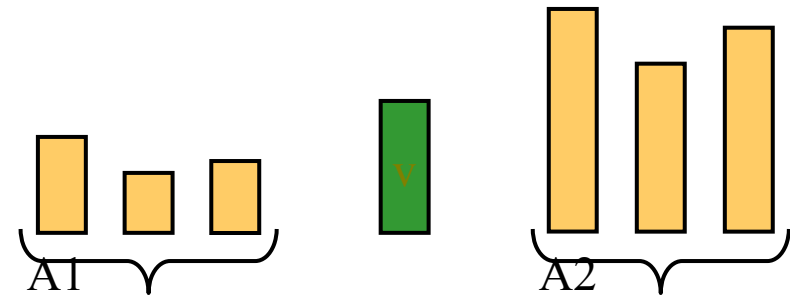
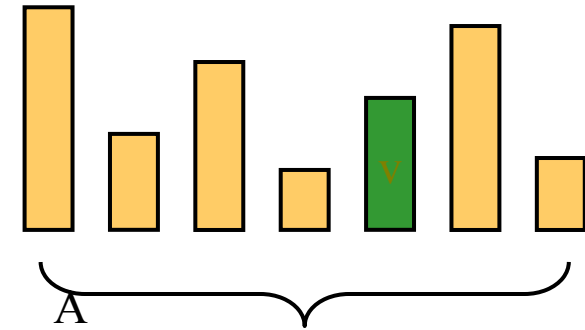


- Each level has total cost  $cn$ .
- Each time we go down one level, the number of subproblems doubles, but the cost per subproblem halves  $\Rightarrow$  *cost per level remains the same.*
- There are  $\lg n + 1$  levels, height is  $\lg n$ . (Assuming  $n$  is a power of 2.)
  - Can be proved by induction.
- Total cost = sum of costs at each level =  $(\lg n + 1)cn = cn \lg n + cn = \Theta(n \lg n)$ .

# Quicksort

Ref Book: Thomas Cormen

- ◆ Divide :
  - ◆ Pick any element (*pivot*)  $v$  in array  $A[p \dots r]$
  - ◆ Partition array  $A$  into two groups  
 $A1[p \dots q-1]$ ,  $A2[q+1 \dots r]$  Compute the index  $q$   
 $A1 \text{ element} < A[q] < A2 \text{ element}$
- ◆ Conquer step: recursively sort  $A1$  and  $A2$
- ◆ Combine step: the sorted  $A1$  (by the time returned from recursion), followed by  $A[q]$ , followed by the sorted  $A2$  (i.e., nothing extra needs to be done)

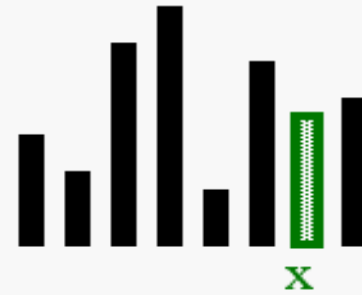




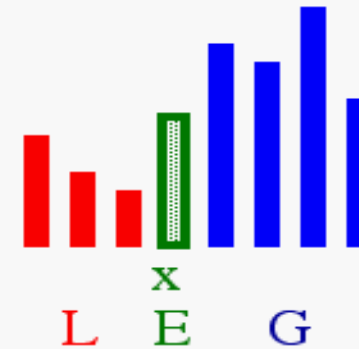
# *Idea of Quick Sort*

Ref Book: Internet

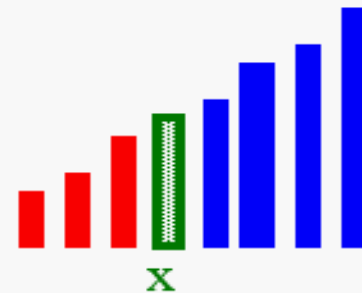
1) **Select:** pick an element



2) **Divide:** rearrange elements so that **x** goes to its final position **E**



3) **Recurse and Conquer:** recursively sort



# Quicksort Pseudo-code

**INPUT:** a sequence of  $n$  numbers stored in array  $A$

**OUTPUT:** an ordered sequence of  $n$  numbers

```
QuickSort ( $A, p, r$ ) // sort  $A[p..r]$  by divide & conquer
1  if  $p < r$ 
2      then  $q = \text{Partition}(A, p, r)$ 
3           QuickSort ( $A, p, q-1$ )
4           QuickSort ( $A, q+1, r$ )
```

**Initial Call:** *QuickSort*( $A, 1, n$ )

# Procedure Partitioning the array

Ref Book: Thomas  
Cormen

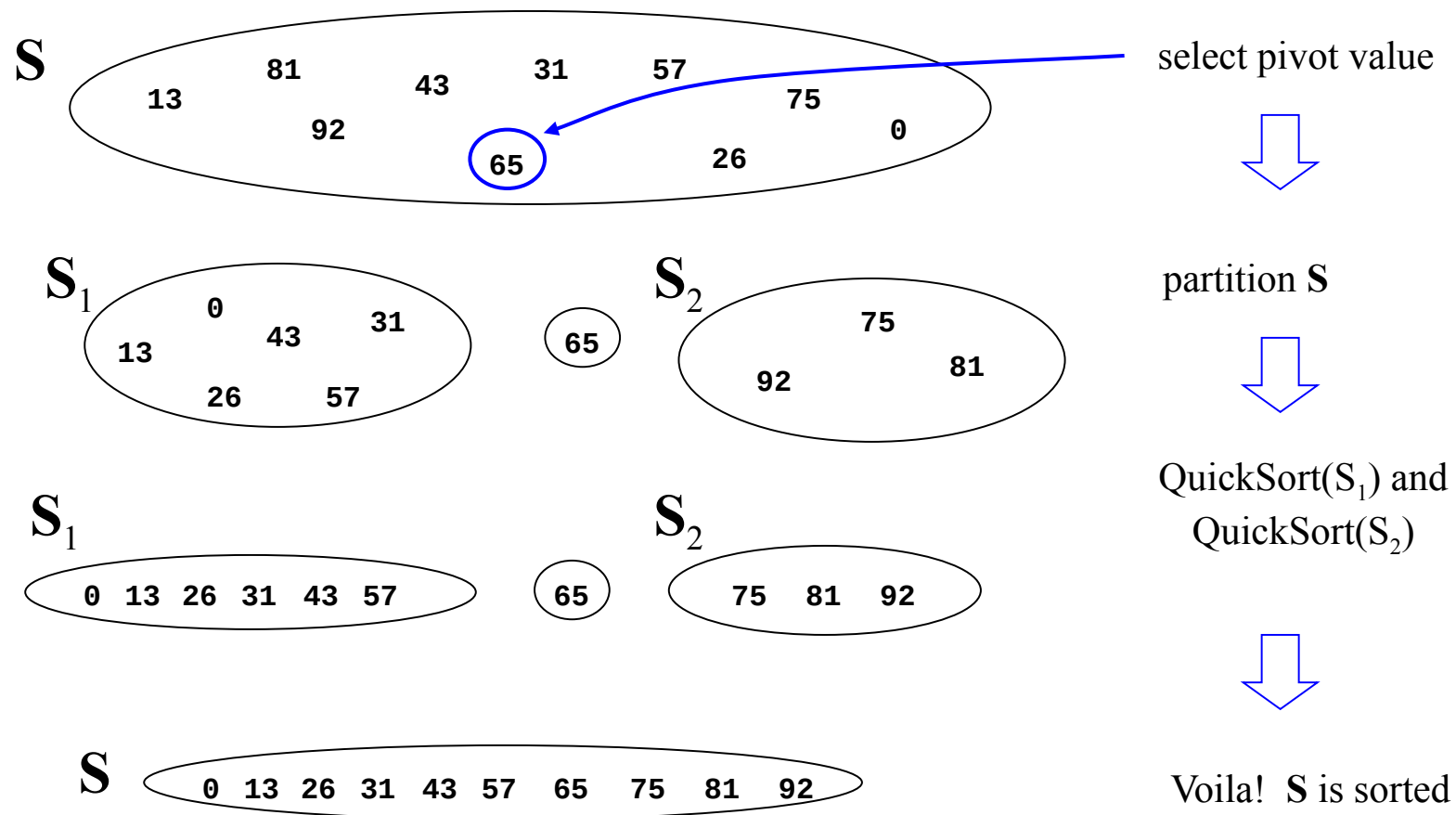
## **Partition( $A, p, r$ )**

```
1  $x = A[r]$ 
2  $i = p - 1$ 
3   for  $j \leftarrow p$  to  $r-1$ 
4     if  $A[j] \leq x$ 
5        $i = i + 1$ 
6     exchange  $A[i]$  with  $A[j]$ 
7   exchange  $A[i]$  with  $A[r]$ 
8   Return  $i + 1$ 
```

Input: Array containing  
sorted subarrays  $A[p..q]$  and  
 $A[q+1..r]$ .

Output: sorted subarray in  
 $A[p..r]$ .

# The steps of QuickSort



# Quicksort Analysis

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Assumptions:

- A random pivot (no median-of-three partitioning)
- No cutoff for small arrays

Running time

- pivot selection: constant time, i.e.  $O(1)$
- partitioning: linear time, i.e.  $O(N)$
- running time of the two recursive calls

$T(N)=T(i)+T(N-i-1)+cN$  where  $c$  is a constant

- $i$ : number of elements in  $S_1$



# Worst-Case Analysis

---

worst case Partition?

- The pivot is the smallest element, all the time
- Partition is always unbalanced

$$T(N) = T(N - 1) + cN$$

$$T(N - 1) = T(N - 2) + c(N - 1)$$

$$T(N - 2) = T(N - 3) + c(N - 2)$$

$$\vdots$$

$$T(2) = T(1) + c(2)$$

$$T(N) = T(1) + c \sum_{i=2}^N i = O(N^2)$$

# Best-case Analysis

---

best case Partitioning?

- Partition is perfectly balanced.
- Pivot is always in the middle (median of the array)

$$\begin{aligned}
 T(N) &= 2T(N/2) + cN \\
 \frac{T(N)}{N} &= \frac{T(N/2)}{N/2} + c \\
 \frac{T(N/2)}{N/2} &= \frac{T(N/4)}{N/4} + c \\
 \frac{T(N/4)}{N/4} &= \frac{T(N/8)}{N/8} + c \\
 &\vdots \\
 \frac{T(2)}{2} &= \frac{T(1)}{1} + c \\
 \frac{T(N)}{N} &= \frac{T(1)}{1} + c \log N \\
 T(N) &= cN \log N + N = O(N \log N)
 \end{aligned}$$

# Average-Case Analysis

---

Intution for Average Case

On average, the running time is  $O(N \log N)$

# Summary Analysis of Quicksort

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Best case: split in the middle —  $\Theta(n \log n)$

Worst case: sorted array! —  $\Theta(n^2)$

Average case: random arrays —  $\Theta(n \log n)$

Improvements:

- better pivot selection: median of three partitioning
- switch to insertion sort on small subfiles
- elimination of recursion

# Large Integer multiplication

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# References

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1. Thomas H Cormen and Charles E.L Leiserson, "Introduction to Algorithm" PHI Third Edition
2. Horowitz and Sahani, "Fundamentals of Computer Algorithms", 2ND Edition. University Press, ISBN: 978 81 7371 6126, 81 7371 61262.