

Optimization
Techniques

DUALITY AND SENSITIVITY ANALYSIS

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INTRODUCTION

- Given a constraint matrix \mathbf{A} , right hand side vector \mathbf{b} , and cost vector \mathbf{c} , we have a corresponding linear programming problem:

$$\begin{aligned} \text{Min} \quad & \mathbf{c}^T \mathbf{x} \\ \text{(LP)} \quad & \text{s. t. } \mathbf{Ax} = \mathbf{b} \quad \text{Primal Problem} \\ & \mathbf{x} \geq 0 \end{aligned}$$

- Questions:
 - Can we use the **same data** set of $(\mathbf{A}, \mathbf{b}, \mathbf{c})$ to construct **another linear programming problem**?
 - If so, how is this new linear program **related** to the original primal problem?

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THE ESSENCE

- Every linear program has another linear program associated with it: Its '**dual**'
- The dual complements the original linear program, the '**primal**'
- The theory of duality provides many insights into what is happening 'behind the scenes'
- Instead of primal, solving the dual LP problem is sometimes easier in following cases
 - The dual has fewer constraints than primal
Time required for solving LP problems is directly affected by the number of constraints, i.e., number of iterations necessary to converge to an optimum solution, which in Simplex method usually ranges from 1.5 to 3 times the number of structural constraints in the problem
 - The dual involves maximization of an objective function
It may be possible to avoid artificial variables that otherwise would be used in a primal minimization problem

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GUESSING

- \mathbf{A} is an m by n matrix, \mathbf{b} is an m -vector, \mathbf{c} is an n -vector.
- Can the roles of \mathbf{b} and \mathbf{c} can be switched?
 - If so, we'll have m variables and n constraints.
 - Correspondingly,
 - the transpose of matrix \mathbf{A} should be considered to accommodate rows for columns, and vice versa?
 - nonnegative variables for free variables?
 - equality constraints for inequality constraints?
 - minimizing objective for maximizing objective?

Optimization Techniques **PRIMAL AND DUAL**

Primal

Decision variables: \mathbf{x}

$\max Z = \mathbf{c}\mathbf{x}$

s.to $\mathbf{A}\mathbf{x} \leq \mathbf{b}$ n

$\mathbf{x} \geq 0$ m

Dual

Decision variables: \mathbf{y}

$\min W = \mathbf{y}\mathbf{b}$

s.to $\mathbf{y}\mathbf{A} \geq \mathbf{c}$ m

$\mathbf{y} \geq 0$ n

Optimization Techniques **PRIMAL AND DUAL - EXAMPLE**

Standard Algebraic Form

Primal

$\max Z = 3x_1 + 5x_2$

s. to $x_1 \leq 4$

$2x_2 \leq 12$

$3x_1 + 2x_2 \leq 18$

$x_1, x_2 \geq 0$

Dual

$\min W = 4y_1 + 12y_2 + 18y_3$

s. to $y_1 + 3y_3 \geq 3$

$2y_2 + 2y_3 \geq 5$

$y_1, y_2, y_3 \geq 0$

Optimization Techniques **PRIMAL AND DUAL - EXAMPLE**

Matrix Form

Primal

maximize $\begin{bmatrix} 3 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$

subject to $\begin{bmatrix} 1 & 0 \\ 0 & 2 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \leq \begin{bmatrix} 4 \\ 12 \\ 18 \end{bmatrix}$

$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \geq \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

Dual

minimize $\begin{bmatrix} y_1 & y_2 & y_3 \end{bmatrix} \begin{bmatrix} 4 \\ 12 \\ 18 \end{bmatrix}$

subject to $\begin{bmatrix} y_1 & y_2 & y_3 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 2 \\ 3 & 2 \end{bmatrix} \leq \begin{bmatrix} 3 & 5 \end{bmatrix}$

$\begin{bmatrix} y_1 & y_2 & y_3 \end{bmatrix} \geq \begin{bmatrix} 0 & 0 & 0 \end{bmatrix}$

Primal	Dual
Maximization	Minimization
Minimization	Maximization
i^{th} variable	i^{th} constraint
j^{th} constraint	j^{th} variable
$x_i > 0$	Inequality sign of i^{th} Constraint: \geq if dual is maximization \leq if dual is minimization
Primal	Dual
i^{th} variable unrestricted	i^{th} constraint with = sign
j^{th} constraint with = sign	j^{th} variable unrestricted
RHS of j^{th} constraint	Cost coefficient associated with j^{th} variable in the objective function
Cost coefficient associated with i^{th} variable in the objective function	RHS of i^{th} constraint constraints

Optimization Techniques FINDING DUAL OF A LP PROBLEM...CONTD

Note:

Before finding its dual, all the constraints should be transformed to 'less-than-equal-to' or 'equal-to' type for maximization problem and to 'greater-than-equal-to' or 'equal-to' type for minimization problem.

It can be done by multiplying with -1 both sides of the constraints, so that inequality sign gets reversed.

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Optimization Techniques SYMMETRY PROPERTY

➤ For any primal problem and its dual problem, all relationships between them must be symmetric because...

Optimization Techniques DUALITY THEOREM

The following are the *only* possible relationships between the primal and dual problems:

1. If one problem has *feasible solutions* and a *bounded* objective function (and so has an optimal solution), then so does the other problem, so both the weak and the strong duality properties are applicable
2. If one variable has *feasible solutions* but an *unbounded* objective function (no optimal solutions), then the other problem has *no feasible solutions*
3. If one variable has *no feasible solutions*, then the other problem either has *no feasible solutions* or an *unbounded* objective function

Optimization Techniques RELATIONSHIPS BETWEEN PRIMAL AND DUAL

➤ Weak duality property
If \mathbf{x} is a *feasible* solution to the primal, and \mathbf{y} is a *feasible* solution to the dual, then $\mathbf{cx} \leq \mathbf{yb}$

➤ Strong duality property
If \mathbf{x}^* is an *optimal* solution to the primal, and \mathbf{y}^* is an *optimal* solution to the dual, then $\mathbf{cx}^* = \mathbf{y}^*\mathbf{b}$

Optimization Technique **COMPLEMENTARY SOLUTIONS**

- At each iteration, the simplex method identifies
 - \mathbf{x} , a BFS for the primal, and
 - a complementary solution \mathbf{y} , a BS for the dual (which can be found from the row coefficients under slack variables)
- For any primal feasible (but suboptimal) \mathbf{x} , its complementary solution \mathbf{y} is dual infeasible, with $\mathbf{c}\mathbf{x} = \mathbf{y}\mathbf{b}$
- For any primal optimal \mathbf{x}^* , its complementary solution \mathbf{y}^* is dual optimal, with $\mathbf{c}\mathbf{x}^* = \mathbf{y}^*\mathbf{b}$

Optimization Technique **COMPLEMENTARY SLACKNESS**

- Associated variables between primal and dual

	Primal		Dual	
(original variable)	x_j	\longleftrightarrow	y_{m+j}^s	(surplus variable)
(slack variable)	x_{n+i}^s	\longleftrightarrow	y_i	(original variable)
- Complementary slackness property:
When one variable in primal is basic, its associated variable in dual is nonbasic

	Primal		Dual	
(m variables)	basic	\longleftrightarrow	nonbasic	(m variables)
(n variables)	nonbasic	\longleftrightarrow	basic	(n variables)

Optimization Technique **PRIMAL AND DUAL**

Primal: $Z = \mathbf{c}\mathbf{x}$

Dual: $W = \mathbf{y}\mathbf{b}$

Regions: suboptimal, superoptimal

Optimal values: $(\text{optimal}) Z^*$, $W^* (\text{optimal})$

TABLE 6.11 Relationships between complementary basic solutions

Primal Basic Solution	Complementary Dual Basic Solution	Both Basic Solutions	
		Primal Feasible?	Dual Feasible?
Suboptimal	Superoptimal	Yes	No
Optimal	Optimal	Yes	Yes
Superoptimal	Suboptimal	No	Yes
Neither feasible nor superoptimal	Neither feasible nor superoptimal	No	No

Primal problem: $\sum_{j=1}^n c_j x_j = Z$

Dual problem: $W = \sum_{i=1}^m b_i y_i$

Regions: Suboptimal, Superoptimal, Optimal

Optimal values: $(\text{optimal}) Z^*$, $W^* (\text{optimal})$

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DUAL OF THE DUAL=PRIMAL

• Rearrange the new dual

$$(D) \quad \begin{array}{ll} \text{Maximize} & c^T w \\ \text{s. t.} & \begin{bmatrix} A \\ -A \\ I \end{bmatrix} w \leq \begin{bmatrix} -b \\ b \\ 0 \end{bmatrix} \\ & w \text{ unrestricted} \in R^m \end{array}$$

• We have

$$\begin{array}{ll} \text{Maximize} & c^T w \\ \text{s. t.} & Aw \leq -b \\ & -Aw \leq b \\ & w \leq 0 \end{array}$$

For $x := -w$, we have

$$\begin{array}{ll} \text{Minimize} & c^T x \\ \text{s. t.} & Ax = b \\ & x \geq 0 \end{array}$$

Lemma 4.1 Dual of the Dual=Primal.

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TABLE 6.13 Constructing the dual of the dual problem

Dual Problem	Converted to Standard Form
Minimize $W = yb$, subject to $yA \geq c$ and $y \geq 0$.	Maximize $(-W) = -yb$, subject to $-yA \leq -c$ and $y \geq 0$.
Converted to Standard Form	Its Dual Problem
Maximize $Z = cx$, subject to $Ax \leq b$ and $x \geq 0$.	Minimize $(-Z) = -cx$, subject to $-Ax \geq -b$ and $x \geq 0$.

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TABLE 6.14 Corresponding primal-dual forms

Primal Problem (or Dual Problem)	Dual Problem (or Primal Problem)
Maximize Z (or W)	Minimize W (or Z)
Constraint i :	Variable y_i (or x_i):
\leq form \longleftrightarrow	$y_i \geq 0$
$=$ form \longleftrightarrow	Unconstrained
\geq form \longleftrightarrow	$y_i \leq 0$
Variable x_j (or y_j):	Constraint j :
$x_j \geq 0 \longleftrightarrow$	\geq form
Unconstrained \longleftrightarrow	$=$ form
$x_j \leq 0 \longleftrightarrow$	\leq form

Primal Problem	Dual Problem
Maximize $Z = \sum_{j=1}^n c_j x_j$ subject to $\sum_{j=1}^n a_{ij} x_j \leq b_i$ for $i = 1, 2, \dots, m$ and $x_j \geq 0$ for $j = 1, 2, \dots, n$	Minimize $W = \sum_{i=1}^m b_i y_i$ subject to $\sum_{i=1}^m a_{ij} y_i \geq c_j$ for $j = 1, 2, \dots, n$ and $y_i \geq 0$ for $i = 1, 2, \dots, m$

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$\max z = \sum_{j=1}^n c_j x_j$ subject to $\sum_{j=1}^n a_{ij} x_j = b_i, i = 1, 2, \dots, m$ $x_j \geq 0, j = 1, 2, \dots, n$	$\max z = \sum_{j=1}^n c_j x_j$ subject to $\sum_{j=1}^n a_{ij} x_j \leq b_i, i = 1, 2, \dots, m$ (1) $-\sum_{j=1}^n a_{ij} x_j \leq -b_i, i = 1, 2, \dots, m$ (2) $x_j \geq 0, j = 1, 2, \dots, n$
y_i' : dual variables corresponding to (1) y_i'' : dual variables corresponding to (2) $\min w = \sum_{i=1}^m b_i y_i' + \sum_{i=1}^m (-b_i y_i'')$ subject to $\sum_{i=1}^m a_{ij} y_i' + \sum_{i=1}^m (-a_{ij} y_i'') \geq c_j, j = 1, 2, \dots, n$ $y_i', y_i'' \geq 0, i = 1, 2, \dots, m$	$\min w = \sum_{i=1}^m b_i (y_i' - y_i'')$ $\sum_{i=1}^m a_{ij} (y_i' - y_i'') \geq c_j, j = 1, 2, \dots, n$ $y_i = y_i' - y_i''$ $\min w = \sum_{i=1}^m b_i y_i$ $\sum_{i=1}^m a_{ij} y_i \geq c_j, j = 1, 2, \dots, n$ y_i : unconstrained in sign

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$$\max z = \sum_{j=1}^n c_j x_j$$

subject to

$$\sum_{j=1}^n a_{ij} x_j \geq b_i, \quad i = 1, 2, \dots, m$$

$$x_j \geq 0, \quad j = 1, 2, \dots, n$$

$$\max z = \sum_{j=1}^n c_j x_j$$

subject to

$$-\sum_{j=1}^n a_{ij} x_j \leq -b_i, \quad i = 1, 2, \dots, m$$

$$x_j \geq 0, \quad j = 1, 2, \dots, n$$

y_i'' : dual variables corresponding to (2)

$$\min w = \sum_{i=1}^m (-b_i y_i'')$$

subject to

$$\sum_{i=1}^m (-a_{ij} y_i'') \geq c_j, \quad j = 1, 2, \dots, n$$

$$y_i'' \geq 0, \quad i = 1, 2, \dots, m$$

$y_i = -y_i''$

$$\min w = \sum_{i=1}^m b_i y_i$$

subject to

$$\sum_{i=1}^m a_{ij} y_i \geq c_j, \quad j = 1, 2, \dots, n$$

$$y_i \leq 0, \quad i = 1, 2, \dots, m$$

Optimization Technique

TABLE 6.15 One primal-dual form for the radiation therapy example

Primal Problem	Dual Problem
Maximize $-Z = -0.4x_1 - 0.5x_2$	Minimize $W = 2.7y_1 + 6y_2 + 6y_3$
subject to	subject to
$0.3x_1 + 0.1x_2 \leq 2.7$	$y_1 \geq 0$ (S)
$0.5x_1 + 0.5x_2 = 6$	y_2 unconstrained in sign (O)
$0.6x_1 + 0.4x_2 \geq 6$	$y_3 \leq 0$ (B)
and	and
$x_1 \geq 0$	$0.3y_1 + 0.5y_2 + 0.6y_3 \geq -0.4$ (S)
$x_2 \geq 0$	$0.1y_1 + 0.5y_2 + 0.4y_3 \geq -0.5$ (S)

TABLE 6.16 The other primal-dual form for the radiation therapy example

Primal Problem	Dual Problem
Minimize $Z = 0.4x_1 + 0.5x_2$	Maximize $W = 2.7y_1 + 6y_2 + 6y_3$
subject to	subject to
$0.3x_1 + 0.1x_2 \leq 2.7$	$y_1 \leq 0$
$0.5x_1 + 0.5x_2 = 6$	y_2 unconstrained in sign
$0.6x_1 + 0.4x_2 \geq 6$	$y_3 \geq 0$
and	and
$x_1 \geq 0$	$0.3y_1 + 0.5y_2 + 0.6y_3 \leq 0.4$
$x_2 \geq 0$	$0.1y_1 + 0.5y_2 + 0.4y_3 \leq 0.6$

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DUAL SIMPLEX METHOD

Simplex Method versus Dual Simplex Method

- Simplex method starts with a nonoptimal but feasible solution where as dual simplex method starts with an optimal but infeasible solution.
- Simplex method maintains the feasibility during successive iterations where as dual simplex method maintains the optimality.

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DUAL SIMPLEX METHOD: ITERATIVE STEPS

Steps involved in the dual simplex method are:

- All the constraints (except those with equality (=) sign) are modified to 'less-than-equal-to' sign. Constraints with greater-than-equal-to sign are multiplied by -1 through out so that inequality sign gets reversed. Finally, all these constraints are transformed to equality sign by introducing required slack variables.
- Modified problem, as in step one, is expressed in the form of a simplex tableau. If all the cost coefficients are positive (i.e., optimality condition is satisfied) and one or more basic variables have negative values (i.e., non-feasible solution), then dual simplex method is applicable.

Optimization Techniques **DUAL SIMPLEX METHOD: ITERATIVE STEPS...CONTD.**

3. **Selection of exiting variable:** The basic variable with the highest negative value is the exiting variable. If there are two candidates for exiting variable, any one is selected. The row of the selected exiting variable is marked as pivotal row.

4. **Selection of entering variable:** Cost coefficients, corresponding to all the negative elements of the pivotal row, are identified. Their ratios are calculated after changing the sign of the elements of pivotal row, i.e.,

The column corresponding to minimum ratio is identified as the pivotal column and associated decision variable is the entering variable.

$$\text{ratio} = \left| \frac{\text{cost coefficients}}{\text{elements of the pivotal row}} \right|$$

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Optimization Techniques **DUAL SIMPLEX METHOD: ITERATIVE STEPS...CONTD.**

5. **Pivotal operation:** Pivotal operation is exactly same as in the case of simplex method, considering the pivotal element as the element at the intersection of pivotal row and pivotal column.

6. **Check for optimality:** If all the basic variables have nonnegative values then the optimum solution is reached. Otherwise, Steps 3 to 5 are repeated until the optimum is reached.

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Optimization Techniques **DUAL SIMPLEX METHOD: AN EXAMPLE**

Consider the following problem:

$$\begin{array}{ll} \text{Minimize} & Z = 2x_1 + x_2 \\ \text{subject to} & x_1 \geq 2 \\ & 3x_1 + 4x_2 \leq 24 \\ & 4x_1 + 3x_2 \geq 12 \\ & -x_1 + 2x_2 \geq 1 \end{array}$$

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Optimization Techniques **DUAL SIMPLEX METHOD: AN EXAMPLE...CONTD.**

After introducing the surplus variables the problem is reformulated with equality constraints as follows:

$$\begin{array}{ll} \text{Minimize} & Z = 2x_1 + x_2 \\ \text{subject to} & -x_1 \quad \quad +x_3 = -2 \\ & 3x_1 \quad +4x_2 \quad +x_4 = 24 \\ & -4x_1 \quad -3x_2 \quad +x_5 = -12 \\ & x_1 \quad \quad -2x_2 \quad +x_6 = -1 \end{array}$$

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Optimization Technique DUAL SIMPLEX METHOD: AN EXAMPLE...CONTD.

Expressing the problem in the tableau form:

Iteration	Basis	Z	x_1	x_2	x_3	x_4	x_5	x_6	b_r
1	Z	1	-2	-1	0	0	0	0	0
	x_5	0	-1	0	1	0	0	0	-2
	x_4	0	3	4	0	1	0	0	24
	x_6	0	-4	-3	0	0	1	0	-12
	x_3	0	1	-2	0	0	0	1	-1
	Ratios \rightarrow	0.5	1/3	--	--	--	--	--	

Pivotal Row: Row 4 (Basis x_6)
Pivotal Column: Column 4 (Variable x_2)

Optimization Technique DUAL SIMPLEX METHOD: AN EXAMPLE...CONTD.

Successive iterations:

Iteration	Basis	Z	x_1	x_2	x_3	x_4	x_5	x_6	b_r
	Z	1	-2/3	0	0	0	-1/3	0	4
	x_5	0	-1	0	1	0	0	0	-2
2	x_4	0	-7/3	0	0	1	4/3	0	8
	x_2	0	4/3	1	0	0	-1/3	0	4
	x_6	0	11/3	0	0	0	-2/3	1	7
	Ratios \rightarrow	2/3	--	--	--	--	--	--	

Optimization Technique DUAL SIMPLEX METHOD: AN EXAMPLE...CONTD.

Successive iterations:

Iteration	Basis	Z	x_1	x_2	x_3	x_4	x_5	x_6	b_r
	Z	1	0	0	-2/3	0	-1/3	0	16/3
	x_1	0	1	0	-1	0	0	0	2
3	x_4	0	0	0	-7/3	1	4/3	0	38/3
	x_2	0	0	1	4/3	0	-1/3	0	4/3
	x_6	0	0	0	11/3	0	-2/3	1	-1/3
	Ratios \rightarrow	--	--	--	--	0.5	--	--	

Optimization Technique DUAL SIMPLEX METHOD: AN EXAMPLE...CONTD.

Successive iterations:

Iteration	Basis	Z	x_1	x_2	x_3	x_4	x_5	x_6	b_r
	Z	1	0	0	2.5	0	0	-0.5	5.5
	x_1	0	1	0	-1	0	0	0	2
4	x_4	0	0	0	5	1	0	2	12
	x_2	0	0	1	-0.5	0	0	-0.5	1.5
	x_3	0	0	0	-5.5	0	1	-1.5	0.5
	Ratios \rightarrow								

As all the b_r are positive, optimum solution is reached.
Thus, the optimal solution is $Z = 5.5$ with $x_1 = 2$ and $x_2 = 1.5$

Optimization Techniques

SOLUTION OF DUAL FROM PRIMAL SIMPLEX

Primal
Maximize $Z = 4x_1 - x_2 + 2x_3$
subject to
 $2x_1 + x_2 + 2x_3 \leq 6$
 $x_1 - 4x_2 + 2x_3 \leq 0$
 $5x_1 - 2x_2 - 2x_3 \leq 4$
 $x_1, x_2, x_3 \geq 0$

Dual
Minimize $Z' = 6y_1 + 0y_2 + 4y_3$
subject to
 $2y_1 + y_2 + 5y_3 \geq 4$
 $y_1 - 4y_2 - 2y_3 \geq -1$
 $2y_1 + 2y_2 - 2y_3 \geq 2$
 $y_1, y_2, y_3 \geq 0$

Iteration	Basis	Z	x_1	x_2	x_3	s_1	s_2	s_3	b_i	$\frac{b_i}{a_{ij}}$
0		1	0	0	0	1	$\frac{1}{2}$	$-\frac{1}{2}$	$\frac{1}{2}$	22
	x_3	0	0	0	1	$\frac{1}{4}$	$\frac{1}{8}$	$-\frac{1}{8}$	1	
	s_1	0	1	0	0	$\frac{1}{6}$	$-\frac{1}{36}$	$\frac{2}{9}$	$\frac{11}{6}$	
	s_2	0	0	1	0	$\frac{1}{6}$	$-\frac{7}{36}$	$-\frac{1}{36}$	$\frac{5}{6}$	

Optimum value of Z = 22

All the coefficients are nonnegative. Thus optimum solution is achieved.

Value of s_1
Value of s_2
Value of s_3

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Optimization Techniques

Simplex Method: Keep the solution in any iteration suboptimal (not satisfying the condition for optimality, but the condition for feasibility).

Dual Simplex Method: Keep the solution in any iteration superoptimal (not satisfying the condition for feasibility, but the condition for optimality).

If a solution satisfies the condition for optimality, the coefficients in row (0) of the simplex tableau must nonnegative.

If a solution does not satisfy the condition for feasibility, one or more of the values of b in the right-side of simplex tableau must be negative.

Optimization Techniques

COMPLEXITY OF SIMPLEX METHOD PRIMAL VS. DUAL

- How long does it take to solve an LP using the simplex method?
 - Several factors but the **most important** one seems to be **the number of functional constraints**.
 - Computation tends to be **proportional to the cube** of the number of functional constraints in an LP.
 - The number of variables is a relatively minor factor (assuming revised simplex method)
 - The density of the matrix of technological coefficients is also a factor – the sparser the matrix (i.e., the larger the number of zeroes) the faster the simplex method; Real world problems tend to be sparse, i.e., “sparsity” of 5% or even 1%, which leads to fast runs.

Optimization Techniques

COMPLEXITY OF SIMPLEX METHOD PRIMAL VS. DUAL

- But the most important one seems to be **the number of functional constraints**.
 - Computation tends to be proportional to the cube of the number of functional constraints in an LP.

Question: So if problem A has twice as many constraints as problem B how much longer takes to solve problem A in comparison to problem B?

Problem A takes 8 times longer than problem B

Optimization Techniques

PRIMAL VS. DUAL?

So, the size of the problem, may determine whether to use the simplex method on the primal or dual problem.

If the primal has a large number of constraints and a small number of variables it is better to apply the simplex method to the dual (since it will have a small number of constraints).

Optimization Techniques

DUAL SIMPLEX METHOD

- This method is based on the duality results.
- It is a *mirror image of the simplex method*:
 - ❑ the simplex method deals with primal feasible solutions (but not dual feasible), moving toward a solution that is dual feasible;
 - ❑ the dual method deals with basic solutions in the primal problem that are dual feasible but not primal feasible. It moves toward an optimal solution by striving to achieve primal feasibility as well.

Optimization Techniques

Summary of Dual Simplex Method

Maximize $Z = -4y_1 - 12y_2 - 18y_3$
 subject to
 $y_1 + 3y_3 \geq 3$
 $2y_2 + 2y_3 \geq 5$
 $y_1 \geq 0, y_2 \geq 0, y_3 \geq 0.$

Iteration	Basic Variable	Eq.	Coefficient of:						Right Side
			Z	y_1	y_2	y_3	x_4	x_5	
0	Z	(0)	1	4	12	18	0	0	0
	y_1	(1)	0	-1	0	-3	1	0	-3
	y_2	(2)	0	0	-2	-2	0	1	-5
1	Z	(0)	1	4	0	6	0	6	-30
	y_1	(1)	0	-1	0	-3	1	0	-3
	y_2	(2)	0	0	1	1	0	-1	5
2	Z	(0)	1	2	0	0	2	6	-36
	y_1	(1)	0	1	3	0	1	-1	3
	y_2	(2)	0	-1	3	1	0	3	-2

1. **Initialization:** After converting any functional constraints in \geq form to \leq form (by multiplying through both sides by -1), introduce slack variables as needed to construct a set of equations describing the problem. Find a basic solution such that the coefficients in Eq. (0) are zero for basic variables and nonnegative for nonbasic variables (so the solution is optimal if it is feasible). Go to the feasibility test.

2. **Feasibility test:** Check to see whether all the basic variables are nonnegative. If they are, then this solution is feasible, and therefore optimal, so stop. Otherwise, go to an iteration.

3. **Iteration:**

Step 1 Determine the *leaving basic variable*: Select the negative basic variable that has the largest absolute value.

Step 2 Determine the *entering basic variable*: Select the nonbasic variable whose coefficient in Eq. (0) reaches zero first as an increasing multiple of the equation containing the leaving basic variable is added to Eq. (0). This selection is made by checking the nonbasic variables with negative coefficients in that equation (the one containing the leaving basic variable) and selecting the one with the smallest absolute value of the ratio of the Eq. (0) coefficient to the coefficient in that equation.

Step 3 Determine the *new basic solution*: Starting from the current set of equations, solve for the basic variables in terms of the nonbasic variables by Gaussian elimination. When we set the nonbasic variables equal to zero, each basic variable (and Z) equals the new right-hand side of the one equation in which it appears (with a coefficient of ± 1). Return to the feasibility test.

Optimization Techniques

A GRAPHICAL INTRODUCTION TO SENSITIVITY ANALYSIS

- Sensitivity analysis is concerned with how changes in an linear programming's parameters affect the optimal solution.

Optimization Techniques
CHANGES OF PARAMETERS

- Change objective function coefficient
- Change right-hand side of constraint
- Other change options
- Shadow price
- The Importance of sensitivity analysis

Optimization Techniques
EXAMPLE: GIAPETTO PROBLEM

Weekly profit (revenue - costs)

Profit generated by each soldier \$3

Profit generated by each train \$2

x_1 = number of soldiers produced each week
 x_2 = number of trains produced each week.

Optimization Techniques
A GRAPHICAL ILLUSTRATION OF SENSITIVITY ANALYSIS

Reconsider the Giapetto problem from Chapter 3:

Decision Variables: x_1 = number of soldiers produced each week
 x_2 = number of trains produced each week.

Max $z = 3x_1 + 2x_2$

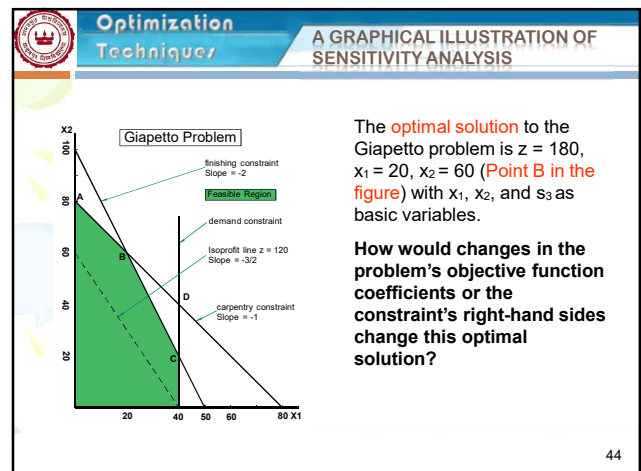
$2x_1 + x_2 \leq 100$ (finishing constraint)
 $x_1 + x_2 \leq 80$ (carpentry constraint)
 $x_1 \leq 40$ (demand constraint)
 $x_1, x_2 \geq 0$

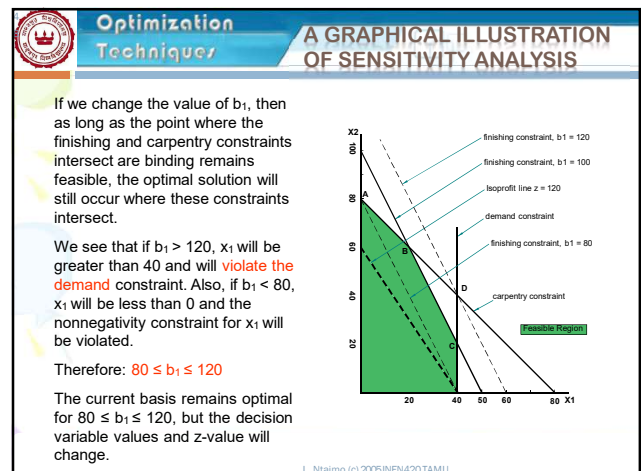
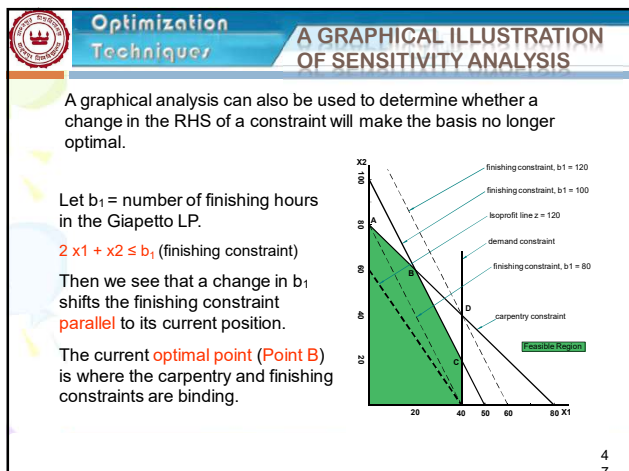
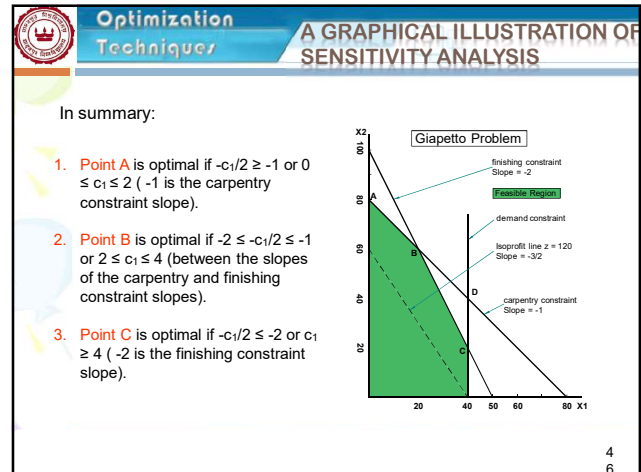
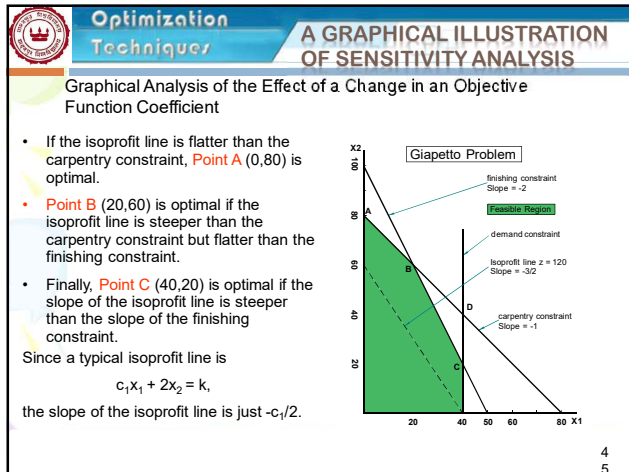
Standard Form:

Max $z = 3x_1 + 2x_2$

$2x_1 + x_2 + s_1 = 100$
 $x_1 + x_2 + s_2 = 80$
 $x_1 + s_3 = 40$
 $x_1, x_2, s_1, s_2, s_3 \geq 0$

4
3





Optimization Technique **A GRAPHICAL ILLUSTRATION OF SENSITIVITY ANALYSIS**

In Summary:

In a constraint with a positive slack (or positive excess) in an LPs optimal solution, if we change the RHS of the constraint to a value in the range where the basis remains optimal, the optimal solution to the LP remains the same.

L. Ntamo (c) 2005 INEN420 TAMU

Optimization Technique **CHANGES OF PARAMETERS**

- Change objective function coefficient
- Change right-hand side of constraint
- Other change options
- Shadow price
- The Importance of sensitivity analysis

Optimization Technique **CHANGE RHS**

b_1

➤ $\max z = 3x_1 + 2x_2$ (weekly profit)

s.t. $2x_1 + x_2 \leq 100$ (finishing constraint)

$x_1 + x_2 \leq 80$ (carpentry constraint)

$x_1 \leq 40$ (demand constraint)

$x_1, x_2 \geq 0$ (sign restriction)

x_1 = number of soldiers produced each week

x_2 = number of trains produced each week.

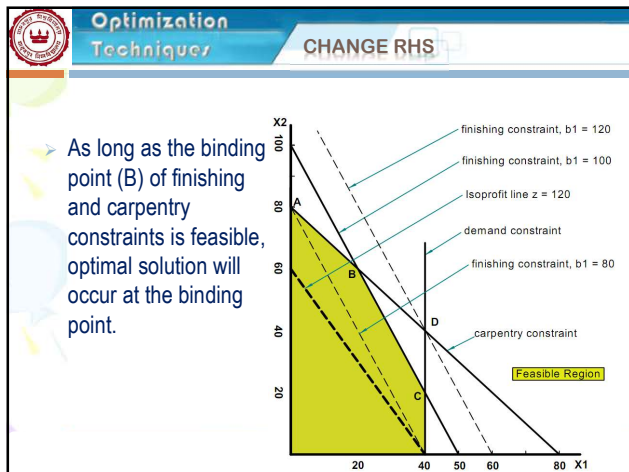
Optimization Technique **CHANGE RHS**

➤ b_1 is the number of finishing hours.

➤ Change in b_1 shifts the finishing constraint parallel to its current position.

➤ Current optimal point (B) is where the carpentry and finishing constraints are binding.

Feasible Region



Optimization Technique **CHANGE RHS**

$x_1 \leq 40$ (demand constraint)
 $x_1, x_2 \geq 0$ (sign restriction)

- If $b_1 > 120$, $x_1 > 40$ at the binding point.
- If $b_1 < 80$, $x_1 < 0$ at the binding point.
- So, in order to keep the basic solution, we need:
 $80 \leq b_1 \leq 120$
 (z is changed)

- If $b_1 > 120$, $x_1 > 40$ at the binding point.
- If $b_1 < 80$, $x_1 < 0$ at the binding point.
- So, in order to keep the basic solution, we need:
 $80 \leq b_1 \leq 120$
 (z is changed)

Optimization Technique **CHANGES OF PARAMETERS**

- Change objective function coefficient
- Change right-hand side of constraint
- Other change options
- Shadow price
- The Importance of sensitivity analysis

Optimization Technique **OTHER CHANGE OPTIONS**


max $z = 3x_1 + 2x_2$ (weekly profit)
 s.t. $2x_1 + x_2 \leq 100$ (finishing constraint)
 $x_1 + x_2 \leq 80$ (carpentry constraint)
 $x_1 \leq 40$ (demand constraint)
 $x_1, x_2 \geq 0$ (sign restriction)

The constraints are represented by the matrix:

$$\begin{pmatrix} 2 & 1 \\ 1 & 1 \\ 1 & 0 \end{pmatrix}$$

Optimization Techniques **OTHER CHANGE OPTIONS**

- $\max z = 3x_1 + 2x_2$ (weekly profit)
- s.t. $2x_1 + x_2 \leq 100$ (finishing constraint)
- $x_1 + x_2 \leq 80$ (carpentry constraint)
- $x_1 \leq 40$ (demand constraint)
- $x_1, x_2 \geq 0$ (sign restriction)



Optimization Techniques **CHANGES OF PARAMETERS**

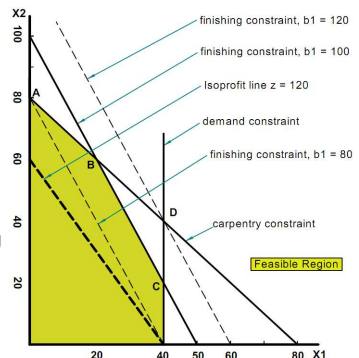
- Change objective function coefficient
- Change right-hand side of constraint
- Other change options
- Shadow price
- The Importance of sensitivity analysis

Optimization Techniques **SHADOW PRICES**

- To determine how a constraint's rhs changes the optimal z-value.
- The **shadow price** for the i th constraint of an LP is the amount by which the optimal z-value is changed when making marginal increase of the right hand side (increased in a max problem or decreased in a min problem).

Optimization Techniques **SHADOW PRICES – EXAMPLE**

- Finishing constraint
- Basic variable: 100
- Current value
 - $b_1 = 100 + \Delta$
- New optimal solution
 - $(20 + \Delta, 60 - \Delta)$
- $z = 3x_1 + 2x_2 = 180 + \Delta$
- Current basis is optimal
 - one increase in finishing hours increase optimal z-value by \$1
- The shadow price for the finishing constraint is \$1



Optimization Techniques **CHANGES OF PARAMETERS**

- Change objective function coefficient
- Change right-hand side of constraint
- Other change options
- Shadow price
- The Importance of sensitivity analysis

Optimization Techniques **THE IMPORTANCE OF SENSITIVITY ANALYSIS**

- If LP parameters change, whether we have to solve the problem again?
 - ❑ In previous example: sensitivity analysis shows it is unnecessary as long as: $80 \leq b_1 \leq 120$
 - ❑ **z is changed**

Optimization Techniques **THE IMPORTANCE OF SENSITIVITY ANALYSIS**

- Deal with the uncertainty about LP parameters

Giapetto Problem

The graph shows the feasible region for the Giapetto Problem in the x_1 - x_2 plane. The feasible region is a yellow-shaded area bounded by the following constraints:

- finishing constraint: Slope = -2
- demand constraint: vertical line at $x_1 = 40$
- carpentry constraint: Slope = -1
- isoprofit line $z = 120$: Slope = -3/2

Key points on the graph include A (0, 80), B (40, 60), C (40, 20), and D (0, 0). The optimal solution is at point B.

- Example:
- The weekly demand for soldiers is 40.
- Optimal solution B
- If the weekly demand is uncertain. $x_1 \leq ?$
- As long as the demand is at least 20, B is still the optimal solution.

Optimization Techniques **A MORE DETAILED LOOK AT SENSITIVITY**

- We are interested in the optimal solution sensitivity to changes in model parameters
 - ❑ Coefficients a_{ij} , c_j
 - ❑ Right hand sides b_i
- If we change the model parameters, how does it affect
 - ❑ **Feasibility?**
 - If violated, then primal infeasible, but may be dual feasible
 - ❑ **Optimality?**
 - If violated, then dual infeasible, but may be primal feasible

Optimization Technique **GENERAL PROCEDURE FOR SENSITIVITY ANALYSIS**

- Revise the model
- Calculate changes to the original final tableau
- Convert to the proper form using Gaussian elimination
- **Feasibility Test:** Is the new right-hand-sides ≥ 0 ?
- **Optimality Test:** Is the new row-0 coefficients ≥ 0 ?
- Reoptimization
 - ❑ If feasible, but not optimal, continue solving with the primal simplex method
 - ❑ If not feasible, but satisfies optimality, continue solving with the dual simplex method
 - ❑ If feasible and satisfies optimality, then calculate new x^* and Z^*

Optimization Technique **EXAMPLE OF SENSITIVITY ANALYSIS**

Original model
 Max $Z = 3x_1 + 5x_2$
 s. to $x_1 \leq 4$
 $2x_2 \leq 12$
 $3x_1 + 2x_2 \leq 18$
 $x_1, x_2 \geq 0$

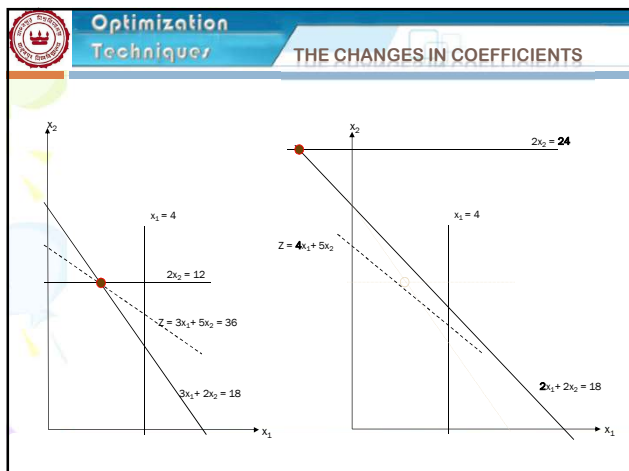
Revised model
 Max $Z = 4x_1 + 5x_2$
 s. to $x_1 \leq 4$
 $2x_2 \leq 24$
 $2x_1 + 2x_2 \leq 18$
 $x_1, x_2 \geq 0$

Original final simplex tableau

Basic variable	Z	x_1	x_2	s_1	s_2	s_3	r.h.s.
Z	1	0	0	0	3/2	1	36
s_1	0	0	0	1	1/3	-1/3	2
x_2	0	0	1	0	1/2	0	6
x_1	0	1	0	0	-1/3	1/3	2

$C_B B^{-1} A - C$ $C_B B^{-1}$ $B^{-1} A$ $B^{-1} b$

What happens when A, b, c changes?



Optimization Technique **EXAMPLE OF SENSITIVITY ANALYSIS**

- Calculate changes to the original final tableau from original final tableau

$B_{old}^{-1} =$ $C_B B_{old}^{-1} = y^* =$

use new coefficients $\bar{A}_{new}, \bar{b}_{new}, \bar{C}_{new}$:

$B_{old}^{-1} \bar{b}_{new} =$ $C_B B_{old}^{-1} \bar{b}_{new} = y^* \bar{b}_{new} =$

$C_B B_{old}^{-1} \bar{A}_{new} - \bar{C}_{new} =$

Duality/Sensitivity-68

Optimization Technique **EXAMPLE OF SENSITIVITY ANALYSIS**

Basic variable	Z	x_1	x_2	s_1	s_2	s_3	r.h.s.
Z	1	0	0	0	$\frac{1}{2}$	1	48
s_1	0	0	0	1	$\frac{1}{2}$	$-\frac{1}{2}$	7
x_2	0	0	1	0	$\frac{1}{2}$	0	12
x_1	0	1	0	0	$-\frac{1}{2}$	$\frac{1}{2}$	-3

- Feasible?
- Satisfies optimality criterion?

Optimization Technique **EXAMPLE OF SENSITIVITY ANALYSIS**

Simple dual simplex iteration

Basic variable	Z	x_1	x_2	s_1	s_2	s_3	r.h.s.
Z	1	0	0	0	$\frac{1}{2}$	1	48
s_1	0	0	0	1	$\frac{1}{2}$	$-\frac{1}{2}$	7
x_2	0	0	1	0	$\frac{1}{2}$	0	12
x_1	0	1	0	0	$-\frac{1}{2}$	$\frac{1}{2}$	-3

Basic variable	Z	x_1	x_2	s_1	s_2	s_3	r.h.s.
Z	1						
	0						
	0						
	0						

Optimization Technique **CHANGES IN B_i ONLY (CASE 1)**

B.V.	Z	Original Variables	Slack Variables	r.h.s.
		x_1 x_2 ... x_n	x_{n+1}^s ... x_{n+m}^s	
Z	1	$c_B B^{-1} A - c$	$c_B B^{-1}$	$c_B B^{-1} b$
x_B	0	$B^{-1} A$	B^{-1}	$B^{-1} b$

- What is affected when only b changes?
- Optimality criterion will always be satisfied
- Feasibility might not

Optimization Technique **CHANGES IN B_i ONLY EXAMPLE A**

Change $b = \begin{bmatrix} 4 \\ 12 \\ 18 \end{bmatrix}$ to $\bar{b} = \begin{bmatrix} 4 \\ 24 \\ 18 \end{bmatrix} \rightarrow B^{-1}b =$

$c_B B^{-1}b =$

Basic variable	Z	x_1	x_2	s_1	s_2	s_3	r.h.s.
Z	1	0	0	0	$\frac{3}{2}$	1	
s_1	0	0	0	1	$\frac{1}{3}$	$-\frac{1}{3}$	
x_2	0	0	1	0	$\frac{1}{2}$	0	
x_1	0	1	0	0	$-\frac{1}{3}$	$\frac{1}{3}$	

Optimization Technique CHANGES IN B_1 ONLY EXAMPLE A

Simple dual simplex iteration

Basic variable	Z	x_1	x_2	s_1	s_2	s_3	r.h.s.
Z	1	0	0	0	3/2	1	54
s_1	0	0	0	1	1/3	-1/3	6
x_2	0	0	1	0	1/2	0	12
x_1	0	1	0	0	-1/3	1/3	-2

Basic variable	Z	x_1	x_2	s_1	s_2	s_3	r.h.s.
Z	1						
	0						
	0						
	0						

Optimization Technique CHANGES IN B_1 ONLY REPRESENTING AS DIFFERENCES

Change $b = \begin{bmatrix} 4 \\ 12 \\ 18 \end{bmatrix}$ to $\bar{b} = \begin{bmatrix} 4 \\ 24 \\ 18 \end{bmatrix}$

Can represent as $\bar{b} = b + \begin{bmatrix} \Delta b_1 \\ \Delta b_2 \\ \Delta b_3 \end{bmatrix}$
 Δb

Then we can find $B^{-1}\Delta b$ = change in r.h.s. of optimal tableau
 $c_B B^{-1}\Delta b$ = change in optimal Z value

Optimization Technique CHANGES IN B_1 ONLY ALLOWABLE RANGES

- Assume only b_2 changes
- The current basis stays feasible (and optimal) as long as
 $B^{-1}(b + \Delta b) \geq 0$

Optimization Technique CHANGES IN COEFFICIENTS OF NONBASIC VARIABLES (CASE 2A)

B.V.	Z	Original Variables				Slack Variables				r.h.s.
		x_1	x_2	...	x_n	x_{n+1}^s	...	x_{n+m}^s		
Z	1	$c_B B^{-1}A - c$				$c_B B^{-1}$				$c_B B^{-1}b$
x_B	0	$B^{-1}A$				B^{-1}				$B^{-1}b$

- What is affected when only c and A columns for a nonbasic variable change?
- Feasibility criterion will always be satisfied
- Optimality might not

Optimization Technique CHANGES IN COEFFICIENTS OF NONBASIC VARIABLES EXAMPLE A CONTINUED

➤ From Example A, we had

Basic variable	Z	x_1	x_2	s_1	s_2	s_3	r.h.s.
Z	1	9/2	0	0	0	5/2	45
s_1	0	1	0	1	0	0	4
x_2	0	3/2	1	0	0	1/2	9
s_2	0	-3	0	0	1	-1	6

Change $c_1 = 3$ to $\bar{c}_1 = 4 \rightarrow (c_B B^{-1} \bar{A} - \bar{c})_1 = y^* \bar{A} - \bar{c} =$

$$A_1 = \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix} \quad \bar{A}_1 = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} \quad (B^{-1} \bar{A})_1 =$$

Optimization Technique CHANGES IN COEFFICIENTS OF NONBASIC VARIABLES ALLOWABLE RANGES

- Assume only c_1 changes
- The current basis stays optimal (and feasible) as long as $(C_B B^{-1} \bar{A} - \bar{c}) \geq 0$

Optimization Technique INTRODUCTION OF A NEW VARIABLE (CASE 2B)

➤ Assume the variable was always there, with $c_1=0$, $A_{1j}=0$

➤ Can now assume it is a nonbasic variable at the original optimal, and apply the same approach as Case 2a

Example A

Max $Z = 3x_1 + 5x_2$

s. to $x_1 \leq 4$

$2x_2 \leq 24$

$3x_1 + 2x_2 \leq 18$

$x_1, x_2 \geq 0$

Example A with new variable

Max $Z = 3x_1 + 5x_2 + 2x_6$

s. to $x_1 + x_6 \leq 4$

$2x_2 \leq 24$

$3x_1 + 2x_2 + 2x_6 \leq 18$

$x_1, x_2 \geq 0$

Optimization Technique OTHER POSSIBLE ANALYSES

- Changes to the coefficients of a basic variable
 - ❑ Utilize same approach as initial example, not much of a 'special case'
- Introduction of a new constraint
 - ❑ Would optimality criterion be satisfied?
 - ❑ Would feasibility criterion be satisfied?
- Parametric analysis