



ITAR
FREE

STANDARD
MIL-STD
810G



INERTIAL MEASUREMENT UNITS

PRODUCT CATALOG

PIONEERING PRECISION IN INERTIAL NAVIGATION AND SENSOR FUSION FOR OVER 20 YEARS

About VIAVI Solutions

VIAVI (NASDAQ: VIAV) is a global provider of network test, monitoring and assurance solutions for telecommunications, cloud, enterprises, first responders, military, aerospace and railway. VIAVI is also a leader in light management technologies for 3D sensing, anti-counterfeiting, consumer electronics, industrial, automotive, government and aerospace applications.

Learn more about VIAVI at www.viavisolutions.com.

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About Inertial Labs, a VIAVI Solutions Company

With over 20 years of industry experience, Inertial Labs, a VIAVI Solutions Company, is a leading designer, integrator, and manufacturer of cutting-edge Inertial Measurement Units (IMUs), GPS-Aided Inertial Navigation Systems (INSs), and Attitude & Heading Reference Systems (AHRSs), as well as sensor fusion products and solutions ranging from Inertial Sensing, Assured Position Navigation and Timing (APNT) and GNSS Tracking to LiDAR Scanning, Alternative Navigation (ALTNAV), Visual Navigation, and Programmable Navigation Solutions.

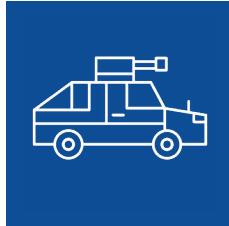
As experts in sensor fusion, Inertial Labs designs and develops quality products at the best price-performance ratio. Our team provides solutions capable of utilizing data from an array of sources, including air data computers (ADCs), ToF Mesh-Based Software Defined Radios (SDRs), Visual Odometry, Air Speed Sensors, Odometers, Encoders, and Standalone Magnetic Compasses (SAMCs).

APPLICATIONS



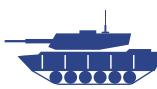
AEROSPACE

Navigation, Stabilization and Pointing



LAND

Commercial and Military



INDUSTRIAL

Small to Large Scale Operations



MARITIME

Dynamic Position, Heave, Surge and Sway



2001

Founded

150+

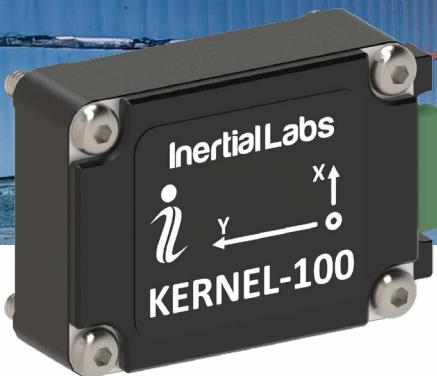
Highly Technical Staff

400+

Customers WorldWide

100,000+

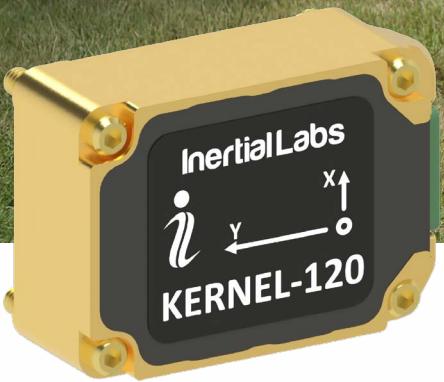
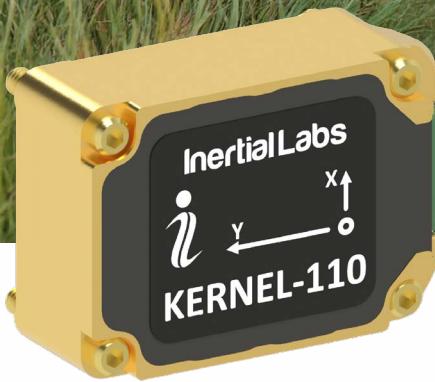
Devices in Operation



KERNEL-100

Gyro Bias in-run Stability (RMS)	2°/h
Gyro Noise (ARW)	0.38°/√h
Accel Bias in-run Stability	0.01 mg (RMS, 8 g)
Pitch & Roll Accuracy	0.05° (Static,RMS)
Accel SF Accuracy (over temp. range)500 ppm
Size	28.5 x 19.5 x 8.5 mm
Weight	7 g

Inertial Measurement Units



KERNEL-110 | KERNEL-120

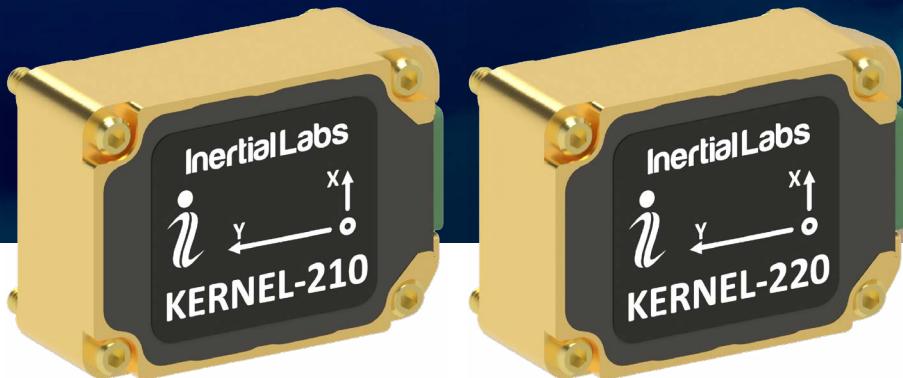
Gyro Bias in-run Stability (RMS)	2°/h
Gyro Noise (ARW)	0.3°/√h
Accel Bias in-run Stability	0.01 mg (RMS, 8 g)
Pitch & Roll Accuracy	0.05° (Static,RMS)
Accel SF Accuracy (over temp. range)500 ppm
Size	28.38 x 19.5 x 10.5 mm
Weight	10 g



KERNEL-201

Gyro Bias in-run Stability (RMS).....	0.7%/h
Gyro Noise (ARW)	0.065%/h
Accel Bias in-run Stability	0.015 mg (RMS, 8 g)
Accel SF Accuracy (over temp. range).....	.500 ppm
Size	28.5 x 19.5 x 11.2 mm
Weight.....	10 g

Inertial Measurement Units



KERNEL-210 | KERNEL-220

Gyro Bias in-run Stability (RMS)	1%/h
Gyro Noise (ARW)	0.2%/h
Accel Bias in-run Stability	0.005 mg (RMS, 8 g)
Pitch & Roll Accuracy	0.05° (Static,RMS)
Accel SF Accuracy (over temp. range)	150 ppm
Size	28.38 x 19.5 x 10.5 mm
Weight	17 g

Inertial Measurement Units



IMU-P TACTICAL / INDUSTRIAL A, S

	Tactical A	Industrial A	Tactical S	Industrial S
Gyro Bias in-run Stability (RMS).....	.1%/h.....	.3%/h.....	.05%/h.....	.2%/h.....
Gyro Noise (ARW)	0.2%/h.....	0.3%/h.....	0.06%/h.....	0.1%/h.....
Accel Bias in-run Stability	0.005 mg (RMS,8g).....	0.01 mg (RMS,8g).....	0.005 mg (RMS,8g).....	0.01 mg (RMS,8g).....
Pitch & Roll Accuracy	0.05° (Static,RMS).....	0.05° (Static,RMS).....	0.05° (Static,RMS).....	0.05° (Static,RMS).....
Accel SF Accuracy (over temp. range).....	150 ppm.....	500 ppm.....	150 ppm.....	500 ppm.....
Size39 x 45 x 22 mm.....			
Weight70 g.....	.70 g.....	.70 g.....	.70 g.....

Inertial Measurement Units



IMU-NAV-100 TACTICAL A, S

	Tactical A	Tactical S
Gyro Bias in-run Stability (RMS).....	0.5%/h.....	1%/h
Gyro Noise (ARW)	0.1%/h.....	0.04%/h
Accel Bias in-run Stability	0.003 mg (RMS, 8g).....	0.003 mg (RMS, 8g)
Pitch & Roll Accuracy	0.03° (Static, RMS).....	0.03° (Static, RMS)
Accel SF Accuracy (over temp. range).....	150 ppm.....	150 ppm
Size	59.2 x 47.0 x 43.2 mm.....	59.2 x 47.0 x 43.2 mm
Weight	155 g.....	155 g



IMU-NAV-200

Gyro Bias in-run Stability (RMS)	0.3°/h
Gyro Noise (ARW)	0.04°/v/h
Accel Bias in-run Stability	0.003 mg (RMS, 8g)
Pitch & Roll Accuracy	0.03° (Static, RMS)
Accel SF Accuracy (over temp. range)	150 ppm
Size	47.0 x 62.6 x 43.5 mm
Weight	155 g

Inertial Measurement Units



IMU-FI-200T

Gyro Noise (ARW)	0.025%/h (typical)
Accel Bias in-run Stability	0.02 mg (RMS)
Accel SF Accuracy (over temp. range).....	500 ppm (over temp. range)
Size	D88.90 x H84.50 mm
Weight.....	790 g



IMU-H100

Gyro Bias in-run Stability (RMS).....	1 °/h
Gyroscopes Measurement range	±2000 deg/sec
Accel Bias in-run Stability	0.03 mg
Accel Bias Repeatability	1.2 mg
Accelerometers Noise (VRW)	0.045 m/sec./√hr
Size	50.8 x 64.8 x 35.6 mm
Weight.....	160 g

INERTIAL MEASUREMENT UNITS

							
	Kernel-100	Kernel-110, 120	Kernel-210, 220	Kernel-201	IMU-H100	IMU-P Industrial A	IMU-P Industrial S
Gyro Bias in-run Stability (RMS) (/h)	2	2	1	0.7	1	3	2
Gyro Noise (ARW)(%/h)	0.38	0.3	0.2	0.065	0.2	0.3	0.1
Accel Bias in-run Stability (mg) (RMS, 8g)	0.01	0.01	0.005	0.015	0.03	0.01	0.01
Pitch & Roll Accuracy (Static,RMS)	0.05°	0.05° (Static,RMS)	0.05° (Static,RMS)	N/A	N/A	0.05°	0.05°
Accel SF Accuracy (over temp. range)(ppm)	500	500	150	500	150	150	500
Size (mm)	28.5 x 19.5 x 8.5	28.38 x 19.5 x 10.5	28.38 x 19.5 x 10.5	28.5 x 19.5 x 11.2	50.8 x 64.8 x 35.6	39 x 45 x 22	39 x 45 x 22
Weight (g)	7	10	17	10	160	70	70
Applications	Autonomous Vehicles, LoS Stabilization, Micro-UAV Systems	Autonomous Vehicles, LoS Stabilization, Micro-UAV Systems	Autonomous Vehicles, Guidance and Nav, LoS Stabilization, Micro-UAV Systems	Autonomous Vehicles, LoS Stabilization, Micro-UAV Systems	Autonomous Vehicles, LoS Stabilization, Micro-UAV Systems	Anti-Roll Systems, Gimbals, Motion Control Sensors	Anti-Roll Systems, Gimbals, Motion Control Sensors

						
	IMU-P Tactical S	IMU-P Tactical A	IMU-NAV-100-S	IMU-NAV-100-A	IMU-NAV-200	IMU-FI-200T
Gyro Bias in-run Stability (RMS) (%/h)	0.5	1	1	0.5	0.3	N/A
Gyro Noise (ARW) (%/h)	0.06	0.2	0.04	0.1	0.04	0.025
Accel Bias in-run Stability (RMS, 8g) (mg)	0.005	0.005	0.003	0.003	0.003	0.02
Pitch & Roll Accuracy (Static, RMS)	0.05°	0.05°	0.03°	0.03°	0.03°	N/A
Accel SF Accuracy (over temp. range) (ppm)	150	150	150	150	150	500
Size (mm)	39 x 45 x 22	39 x 45 x 22	59.2 x 47.0 x 43.2	59.2 x 47.0 x 43.2	47.0 x 62.6 x 43.5	D88.90 x H84.50
Weight (g)	70	70	155	155	155	790
Applications	Anti-Roll Systems, Gimbals, Motion Control Sensors	Electro-Optical Components (EOC/IR), Orientation Control, Platform Stabilization	Antenna and Line of Sight Stabilization Systems, Motion Control Sensors	Land vehicle navigation and motion analysis, UAV & AUV/ROV navigation	Guidance & Navigation in GPS-denied environments	Tactical Navigation. Medium accuracy gyrocompassing