



Write something



Home(/) / Products(/products/) /

IMU286 Automotive Grade 6DoF (<https://www.skymems.com/products imu286-automotive-grade-6dof-mems-imu/>)



# IMU286 Automotive Grade 6DoF MEMS IMU

- Automotive Grade 6DoF IMU Sensor, Easy to Integrate
- Strictly Factory Calibrated at Full Temperature
- Pass 2000km All-Terrain Vehicles Tests
- Range (Typical): Gyro  $\pm 450^\circ/\text{s}$ , Acc  $\pm 16\text{g}$
- Bias Instability (Allan): Gyro  $1.2^\circ/\text{h}$ , Acc  $50\mu\text{g}$
- High Bandwidth (Typical): 200Hz
- Compact & Light Weight  $22.4 \times 22.4 \times 9\text{mm}$ , 20g
- Working Temperature:  $-40\text{~}+85^\circ\text{C}$



Contact



WhatsAPP  
(tel:+86-13372038516)



Skype  
(skype:+8613372038516?chat)

---

## Product Categories





# Brief Introduction

IMU286 inertial measurement unit is a high-performance, automotive grade, small-size and shock-proof 6DoF IMU sensor. It's composed of 3-axis gyroscope and 3-axis accelerometer, and it is strictly factory calibrated at full temperature, which trims the parameter errors such as offset drift over temperature, orthogonality error, and sensitivity. This ensures the consistency of module performance, allowing it to provide continuous, stable and accurate sensor measurement values across a wide temperature range.

IMU286 enjoys high accuracy with gyro-bias instability of better than  $1.2^\circ/\text{h}$ , which can be used for accurate navigation, control, and dynamic measurement of motion carriers. It offers a simple and cost-effective solution for unmanned vehicle, unmanned aircraft, unmanned surface vessel and platform stability, etc., and it has been successfully widely used in these fields.

# Technical Specifications

| Parameter                    | Test Condition   | Min. | Typical   | Max. | Unit                     |
|------------------------------|--|------|-----------|------|--------------------------|
| <b>Gyroscopes</b>            |  |      |           |      |                          |
| Range <sup>①</sup>           |  |      | $\pm 450$ |      | $^\circ/\text{s}$        |
| Bias Instability             | Allan variance   |      | 1.2       |      | $^\circ/\text{h}$        |
| Bias Stability               | 10s average( $-40\sim+85^\circ\text{C}$ , fixed temp.) |      | 5         |      | $^\circ/\text{h}$        |
| Bias Repeatability           |  |      | 3         |      | $^\circ/\text{h}$        |
| Full Temperature Bias (peak) |  |      | 0.03      |      | $^\circ/\text{s}$        |
| Random Walk                  |  |      | 0.2       |      | $^\circ/\sqrt{\text{h}}$ |

|                                     |                |        |        |        |            |
|-------------------------------------|----------------|--------|--------|--------|------------|
| Non-linearity                       |                |        | 100    |        | ppm        |
| Axial Coupling Coefficient          |                |        |        | 1%     |            |
| Linear Acceleration Effect on Bias  |                |        | 0.002  |        | °/s/g      |
| Bandwidth                           |                |        | 200    |        | Hz         |
| <b>Accelerometers</b>               |                |        |        |        |            |
| Range <sup>①</sup>                  |                |        | ±16    |        | g          |
| Bias Instability                    | Allan variance | 25     | 50     | 75     | ug         |
| Initial Bias Error                  |                | 3      | 4      | 5      | mg         |
| Resolution                          |                |        | 0.01   |        | mg         |
| Scale Factor Accuracy               |                |        | 0.1    |        | %          |
| Non-linearity                       |                |        | 0.01   |        | %FS        |
| Random Walk                         |                | 0.01   | 0.015  | 0.02   | m/s/<br>√h |
| Bandwidth                           |                |        | 150    |        | Hz         |
| <b>Interface<sup>②</sup> (UART)</b> |                |        |        |        |            |
| Baud Rate                           |                | 115200 | 460800 | 921600 | bps        |
| Output Rate                         |                | 200    | 1000   | 2000   | Hz         |
| <b>Reliability</b>                  |                |        |        |        |            |
| MTBF                                | 20000h         |        |        |        |            |
| Continuous Working Time             | 120h           |        |        |        |            |

### **Electrical Features**

|                   |           |
|-------------------|-----------|
| Supply Voltage    | 3.2 – 6 V |
| Power Consumption | < 0.5 W   |

### **Environment Conditions**

|                       |                   |
|-----------------------|-------------------|
| Operating Temperature | -40°C ~ 85°C      |
| Storage Temperature   | -55°C ~ 105°C     |
| Vibration Resistance  | 20-2000Hz, 20grms |
| Shock Resistance      | 2000g, 0.5ms      |

### **Physical Parameter**

|           |                                    |
|-----------|------------------------------------|
| Size      | 22.4 × 22.4 × 9 mm                 |
| Weight    | 20 grams                           |
| Connector | molex connector, model: 5015680607 |

Note:

- ①: The range of Gyroscopes and Accelerometers can be configured in our factory.
- ②: The baud rate and output rate can be configured in our factory.

## **Typical Application**

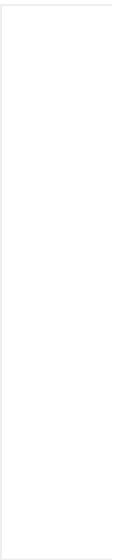
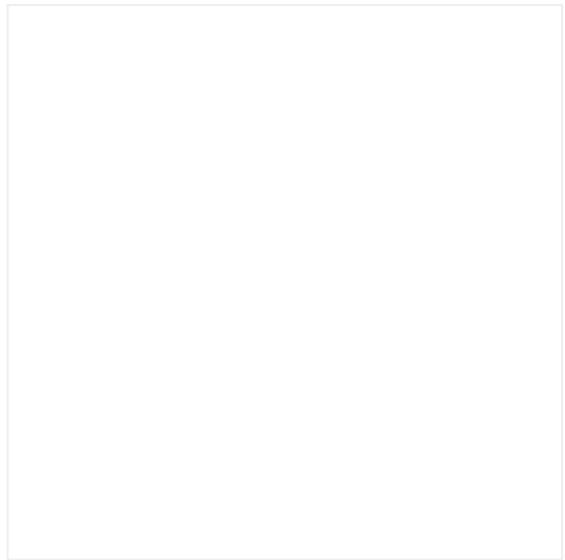
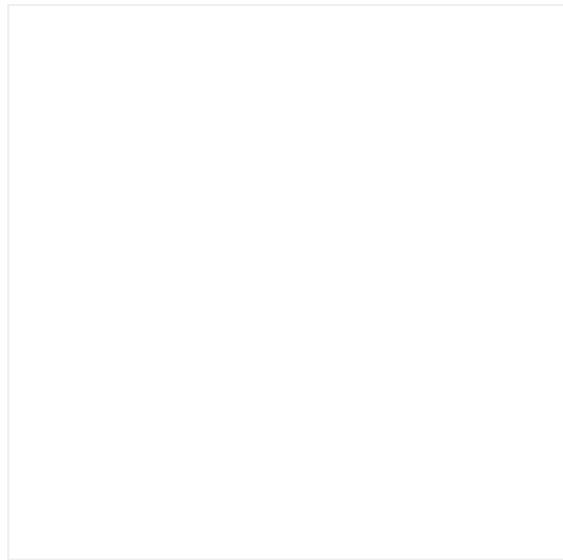
- Unmanned Aircraft
- Autonomous Vehicle
- Unmanned Surface Vessel

- Platform Stabilization

## Product Advantages

## FAQ

## Related Products



### IMU80 6DoF Mini IMU

(<https://www.skymems.com/products/imu80-6dof-mini-imu/>)

Read more

(<https://www.skymems.com/products/imu80-6dof-mini-imu/>)

### IMU90 High Precision 6DoF Mini IMU

(<https://www.skymems.com/products/imu90-high-precision-6dof-mini-imu/>)

Read more

(<https://www.skymems.com/products/imu90-high-precision-6dof-mini-imu/>)

### IMU188 I

(<https://www.skymems.com/products/imu188-i-miniaturized-imu/>)

Read more

(<https://www.skymems.com/products/imu188-i-miniaturized-imu/>)

## Join our newsletter

Sign up our newsletter and get more events & promotions!



[difference-between-mems-and-piezo-accelerometers/](#)

2026-01-23

**What is the difference between a fiber optic gyro and a ring laser gyro? (<https://www.skymems.com/what-is-the-difference-between-a-fiber-optic-gyro-and-a-ring-laser-gyro/>)**

2026-01-16

Copyright © 2025 SkyMEMS All rights reserved 苏ICP备16016974号-1 (<https://beian.miit.gov.cn/>)

[Privacy Policy](#) (<https://skymems.com/privacy-policy/>)

 [sitemap\(/sitemap\\_index.xml\)](#)