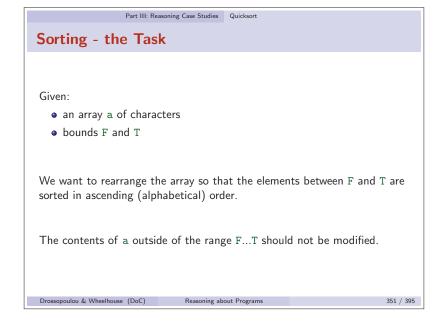
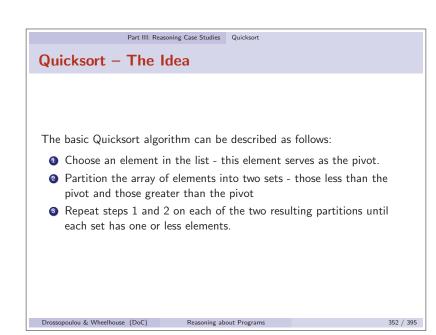


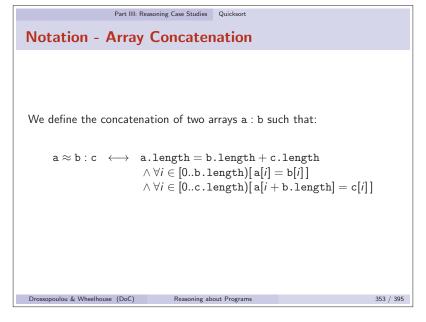
After serving at many institutions (including the University of Belfast, Oxford University,

Microsoft Research) Tony Hoare has now retired. However, he is still going to work every day and working on algebraic models of concurrency.



Note: The sorting task can actually be defined for an array of any type that has a less-then-or-equal relation \leq .





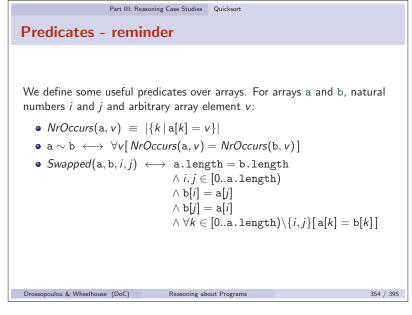
Using deep equality, array slices and concatenation we can describe many interesting

properties of arrays. For example:

$$a \approx a[0..1) : b : a[b.length + 1..a.length)$$

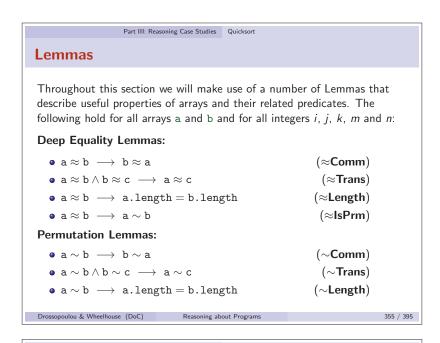
says that the contents of the array a from index 1 to index ${\tt b.length}$ is the same as the array ${\tt b.}$ It does not say anything about the other elements of the array ${\tt a.}$

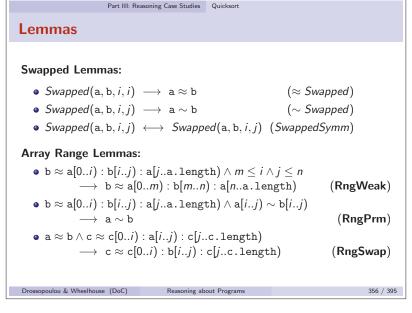
We will see later that this notation can be very useful for describing changes to just part of an array, or even for specifying that parts of an array are unmodified.



Using the notation developed on the previous slide an alternative representation of the Swapped predicate can be given as:

(note that some of the array slices in these last two conjuncts could be empty.)





In **RngWeak** the premise says a and b are identical except for the range [i..j), and the

conclusion says that a and b are identical except for the range [m..n). The lemma holds, since the range [m..n) includes the range [i..j).

Here is a proof of RngWeak.

Given:

1. $b \approx a[0..i) : b[i..j) : a[j..a.length)$ 2. $m \le i \land j \le n$

To Show:

 α . $b \approx a[0..m) : b[m..n) : a[n..a.length)$

Proof:

From 1., and the definition of concatenation we have:

- 3. b.length=i+(j-i)+(a.length-j)
- 4. $\forall k \in [0..i)$. b[k] = a[k]
- 5. $\forall k \in [j..a.length)$. b[k] = a[k]

From 3. we obtain by arithmetic:

6. b.length = a.length

From 4., and 2., (since $m \le i \land k \le m \longrightarrow k \le i$) we obtain:

7. $\forall k \in [0..m)$. b[k] = a[k]

Similarly, from 5., and 2., we obtain:

8. $\forall k \in [n..a.length)$. b[k] = a[k]

From 6., 7., and 8., and definition of concatenation (:), we obtain α

```
 \begin{array}{c} \textbf{Quicksort} & \textbf{-Formal Specification} \\ \\ \textbf{1} & \textbf{void quicksort(char[] a, int F, int T)} \\ \textbf{2} & \textit{//PRE: } \textbf{a} \neq \textbf{null } \land \textbf{0} \leq \textbf{F} \leq \textbf{T} \leq \textbf{a.length}} \\ \textbf{3} & \textit{//POST: } \textbf{a} \approx \textbf{a_0}[0..F): \textbf{a[F..T)}: \textbf{a_0}[\textbf{T..a.length})} \\ \textbf{4} & \land \textbf{a} \sim \textbf{a_0} \land \textit{Sorted(a[F..T))} \\ \end{array}
```

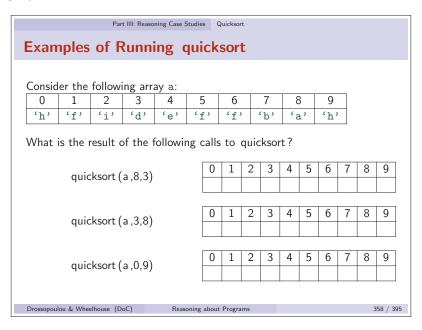
We do not need to distinguish between F and F_0 , nor between T and T_0 , because they are of primitive type and are passed by value - Java methods cannot modify the contents of value parameters. We do distinguish between a and a_0 because arrays are passed by reference in Java.

An alternative specification of the postcondition that explicitly states that F and T are unmodified by the code is:

The alternative version presented above requires us to carry the assertion $F = F_0 \wedge T = T_0$ with us throughout the Midconditions of the program and also forbids us from modifying these variables (unless we also later restore them to their original values).

We prefer the version in the slides as this leads to less notational overheads.

Note that the condition $a \sim a_0$ implies that $a.length = a_0.length$ by ($\sim Length$), so we can use the two lengths interchangeably in our assertions so long as this permutation property holds.



quicksort(a,8,3)	0	1	2	3	4	5	6	7	8	9
quicksort(a,8,3)	'W'	'h'	'a'	't'	()	'e'	΄ν'	'e'	'r'	'!'

Slide 359

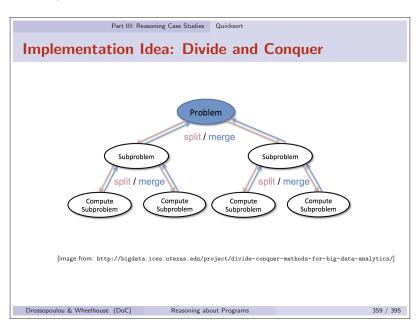
In this case the precondition of the method is violated $(8 \leq 3)$, so there is no guarantee that the postcondition will hold, i.e. anything can happen that satisfies the typing and call by value constraints of Java!

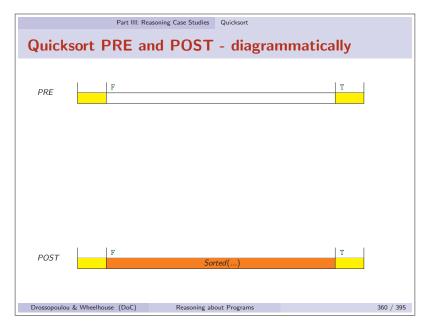
Notice that the range of the sorted slice of array a in the postcondition is closed-open, so while array element F is sorted, array element T is not.

quicksort(a,0,9)

0	1	2	3	4	5	6	7	8	9
'a'	ʻb'	'd'	'e'	'f'	'f'	'f'	'h'	'i'	'h'

Recursive Quicksort





```
Part III: Reasoning Case Studies Quicksort
Sketching the Midconditions - 1
  void quicksort(char[] a, int F, int T)
  <sup>2</sup> //PRE: a \neq null \land 0 \leq F \leq T \leq a.length
  ^{3} //POST: a \approx a_0[0..F) : a[F..T) : a_0[T..a.length)
                \land \ a \sim a_0 \land \textit{Sorted}(a[F..T))
        if ( sometest ) {
             ... somecode ...
 12
          //Mid: a \approx a_0[0..F) : a[F..T) : a_0[T..a.length)
                   \land \ a \sim a_0 \land \textit{Sorted}(a[F..T))
 15
 16
 17 }
Drossopoulou & Wheelhouse (DoC)
                                      Reasoning about Programs
```

Slide 362

Part III: Reasoning Case Studies Quicksort

Knowing When to Stop - working out sometest

With any recursive algorithm, one of the first things you need to do is to work out when to stop recursing.

Let's take a closer look at the postcondition of quicksort:

$$\mathbf{a} \approx \mathbf{a_0}[0..F) : \mathbf{a_0}[F..T) : \mathbf{a_0}[T..a.length)$$
$$\wedge \mathbf{a} \sim \mathbf{a_0} \wedge Sorted(\mathbf{a[F..T)})$$

Observe that if the array slice a[F..T) is empty (i.e. F = T), then there is nothing to do. The empty array is vacuously sorted.

This leads to an initial suggestion of an if test of the form:

if
$$(F < T)$$

Drossopoulou & Wheelhouse (DoC)

Reasoning about Programs

Part III: Reasoning Case Studies Quicksort

Knowing When to Stop - working out sometest - 2

However, we can do better than this.

Let's look again at the postcondition of quicksort:

$$\begin{split} \textbf{a} \approx \textbf{a}_0[0..F): \textbf{a}[F..T): \textbf{a}_0[T..\textbf{a}.\texttt{length}) \\ \wedge \textbf{a} \sim \textbf{a}_0 \wedge \textit{Sorted}(\textbf{a}[F..T)) \end{split}$$

We have already noted that the empty array is vacuously sorted, but an array of just one element is also trivially sorted.

So an improved suggestion for the if-test is:

if (
$$F + 1 < T$$
)

Drossopoulou & Wheelhouse (DoC)

Reasoning about Programs

363 / 395

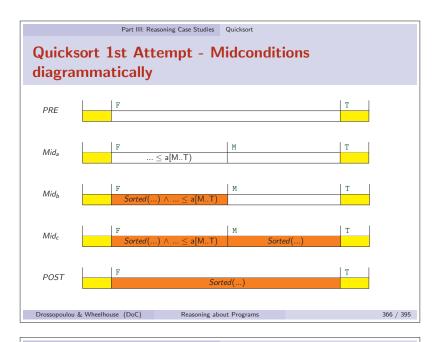
Slide 363

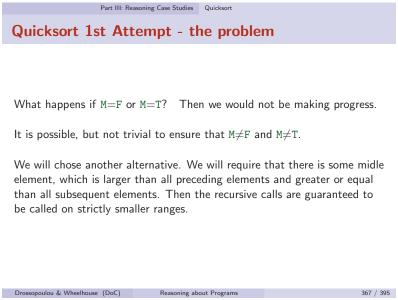
```
Part III: Reasoning Case Studies Quicksort
Quicksort - when to stop
  void quicksort(char[] a, int F, int T)
  <sup>2</sup> //PRE: a \neq null \land 0 \leq F \leq T \leq a.length
  _3 //POST: a \approx a_0[0..F) : a[F..T) : a_0[T..a.length)
                \land \ a \sim a_0 \land \textit{Sorted}(a[F..T))
       if (F + 1 < T) {
            ... somecode ...
 13
            //Mid: a \approx a_0[0..F) : a[F..T) : a_0[T..a.length)
                    \land a \sim a<sub>0</sub> \land Sorted(a[F..T))
 15
 16 }
 17 }
Drossopoulou & Wheelhouse (DoC)
                                      Reasoning about Programs
```

Part III: Reasoning Case Studies Quicksort

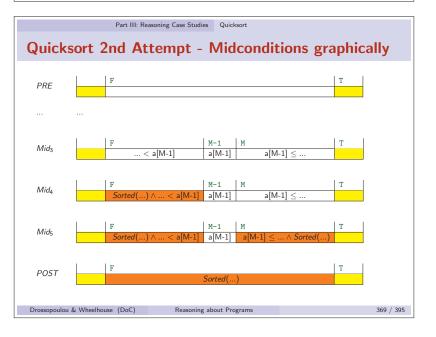
Quicksort 1st Attempt

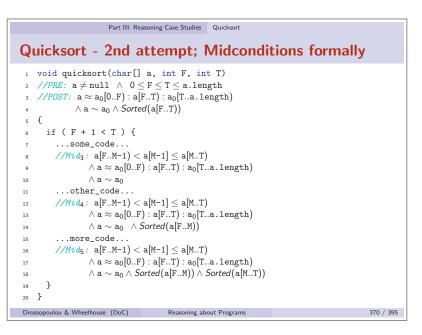
Permute the array slice a[F..T), in such a way that there exists an index M∈[F..T) such that the elements a a from M onwards are larger or equal to the elements in the array before M.
Then sort the subarrays a[F..M) and a[M..T), separately.





Part III: Reasoning Case Studies Quicksort 2nd Attempt Rough idea: Permute the array slice a[F..T), in such a way that there exists an index M-1∈[F..T), such that a[M-1] is strictly larger than all preceding elements, and smaller equal to all subsequent elements. Then sort the subarrays separately.





A remaining question is whether such a value M can always be found. Consider for example the following array b, and values F=3, T=7.

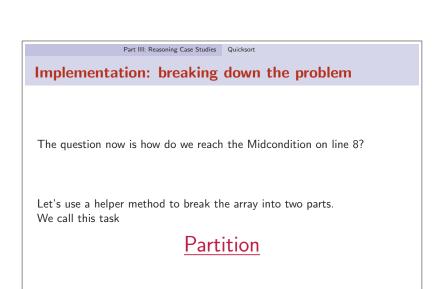
b

0	1	2	3	4	5	6	7	8	9
g,	'd'	'i'	'h'	'h'	'h'	'h'	'd'	'i'	'A'

We are looking for a M such that $3 \le M \le 7$, such that

$$a[3..{\tt M-1}) < a[{\tt M-1}] \le a[{\tt M..7})$$

Even though all of the elements of the array-slice are equal, we can still choose $\mathtt{M}=4$ to satisfy the above assertion.



Drossopoulou & Wheelhouse (DoC) Reasoning about Programs 371 / 3

Implementing Quicksort - 2nd attempt

Part III: Reasoning Case Studies Quicksort

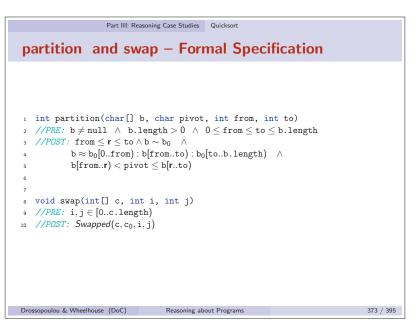
We will use the methods partition and swap to construct the quicksort method.

We can implement partition and swap later.

For now we will assume that these methods are *totally correct* with respect to their corresponding specifications.

This technique is known as *top-down* program development.

Drossopoulou & Wheelhouse (DoC) Reasoning about Programs



As for the specification of quicksort, we implicitly also assume that $b \neq null$

Similarly we do not distinguish between from and from₀, nor between to and to₀, because they are of primitive type, and the method cannot modify their values. But we do distinguish between b and b_0 because the array is passed by reference.

Part III: Reasoning Case Studies Quicksort

Examples of Running partition

Consider the following array a:

0	1	2	3	4
'е'	ʻp'	'd'	ʻq'	'с'

What is a possible result of the following calls to partition?

0	1	2	3	4	

Drossopoulou & Wheelhouse (DoC)

Reasoning about Programs

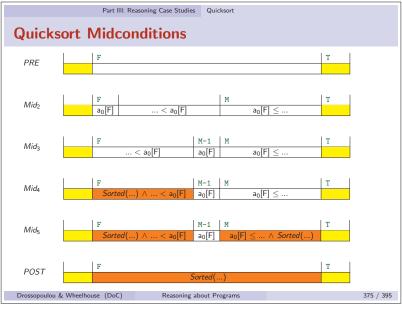
374 / 395

$$r=2$$
 a'=

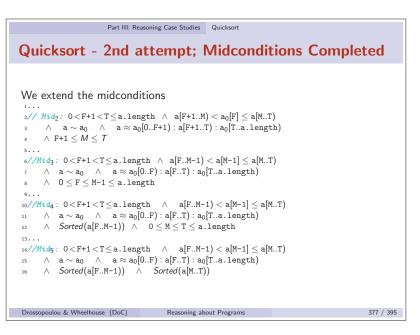
$$r = 0$$
 a'=

$$r=5$$
 a'

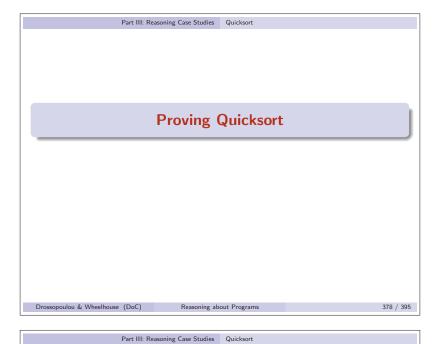




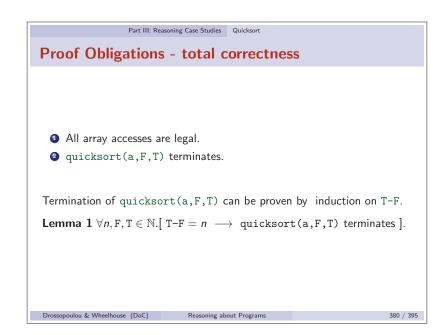
```
Part III: Reasoning Case Studies Quicksort
Quicksort - 2nd attempt; Midconditions and Code
 void quicksort(char[] a, int F, int T)
 2 //PRE: a \neq null \land 0 \leq F \leq T \leq a.length
 3 //POST:
            \texttt{a} \approx \texttt{a}_0[\texttt{0}..\texttt{F}) : \texttt{a}[\texttt{F}..\texttt{T}) : \texttt{a}_0[\texttt{T}..\texttt{a}.\texttt{length}) \land \quad \texttt{a} \sim \texttt{a}_0 \quad \land \quad \textit{Sorted}(\texttt{a}[\texttt{F}..\texttt{T}))
        if (F+1<T) {
            int M = partition(a,a[F],F+1,T);
             /\!/\!\textit{Mid}_2: \ a[\text{F+1..M}) < a_0[\text{F}] \leq a[\text{M..T}) \quad \land \quad a \sim a_0 \quad \land
                          a \approx a_0[0..F+1) : a[F+1..T) : a_0[T..a.length)
            swap(a,F,M-1);
            \label{eq:mid_a:a[F..M-1)} \textit{//Mid_a:} \ a[F..M-1) < a[M-1] \leq a[M..T) \quad \land \quad a \sim a_0 \quad \land
                          \mathtt{a} \approx \mathtt{a_0} \mathtt{[0..F)} : \mathtt{a[F..T)} : \mathtt{a_0[T..a.length)}
            quicksort(a,F,M-1);
            //Mid<sub>4</sub>: a[F..M-1) < a[M-1] \le a[M..T) \land a \sim a_0 \land
                          a \approx a_0[0..F) : a[F..T) : a_0[T..a.length) \land
                           Sorted(a[F..M-1))
            quicksort(a,M,T);
            \label{eq:mid_5:a} \mbox{$/$/Mid_5:} \ \ a[\text{F..M-1}) < a[\text{M-1}] \leq a[\text{M..T}) \quad \land \quad a \sim a_0 \quad \land
                          a \approx a_0[0..F) : a[F..T) : a_0[T..a.length) \land
                           Sorted(a[F..M-1)) \land Sorted(a[M..T))
Drossopoulou & Wheelhouse (DoC)
                                                     Reasoning about Programs
```



We complete the mid-conditions so as to be able to satisfy the preconditions for the recursive calls of quicksort and swap. We are allowed to do this, because in the ifbranch of the function quicksort we have that F+1 < T. Also, the range of the value of M is determined from the call on partition



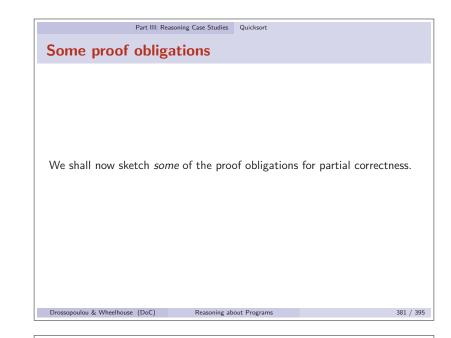
Proof Obligations - partial correctness ● F+1≥T implies POST. ● PRE and if-condition implies precondition of partition(a,a[F],F+1,T). ● Mid₂ holds at line 8. ● Mid₂ implies precondition of swap(a,F,M-1). ● Mid₃ holds at line 11. ● Mid₃ implies precondition of quicksort(a,F,M-1). ● Mid₄ holds at line 14. ● Mid₄ implies precondition of quicksort(a,M,T). ● Mid₅ holds at line 18. ● Mid₅ implies implies POST.

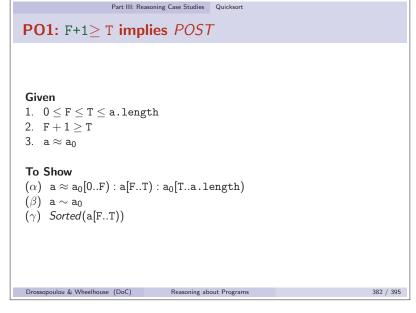


Lemma 1 can be proven by strong induction. That is, we shall prove

 $\mathbf{Lemma} \ \mathbf{2} \ \forall n, \mathtt{F}, \mathtt{T} \in \mathbb{N}. [\ \mathtt{T-F} \leq n \ \longrightarrow \ \mathtt{quicksort(a,F,T)} \ \mathrm{terminates} \].$

Then, Lemma 1 is a direct corollary of Lemma 2.





From the Givens, 1. comes from the precondition, 2. is the negation of the if-test, and

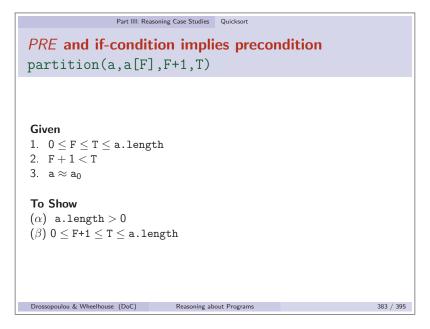
3. comes from the code (as we have not modified the array).

From the assertions to be shown, α , β and γ come directly from the post-condition of quicksort(a,F,T).

Proof

 α and β follow from 3.

From 1, and 2 we obtain that T=F, or T=F+1. Therefore, the array a[F..T) has length at most 1. This gives us γ .



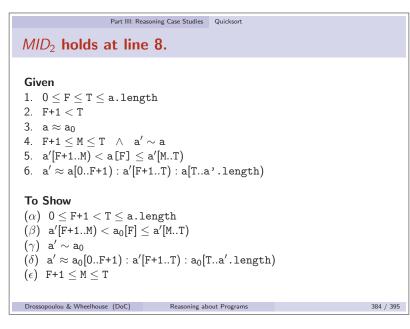
From the **Givens**, 1. comes from the precondition, 2. is the if-test, and 3. comes from the code (as we have not modified the array).

From the assertions **to be shown**, α and β are the precondition of partition(a,a[F],F+1,T), with the following replacements: $b \mapsto a$, pivot $\mapsto a[F]$, from $\mapsto F+1$, and $to \mapsto T$.

Proof

From 1 and 2 we obtain that T \geq 1, and with 2. we obtain that a.length \geq 1, which gives α .

Moreover, 1. and 2. give β .



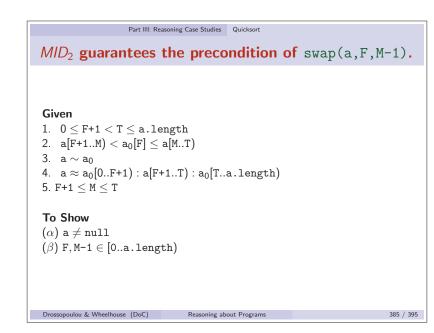
From the **Givens**, 1. comes from the precondition, 2. is the if-test, and 3. comes from the code (as we have not modified the array before calling partition).

Assertions 4.-6. come from the postcondition of partition(a,a[F],F+1,T), with the following replacements: $b_0 \mapsto a,b \mapsto a'$, pivot $\mapsto a[F]$, from $\mapsto F+1$, to $\mapsto T$, and $\mathbf{r} \mapsto M$. These lines describe the *effect* of the call partition(a,a[F],F+1,T) on the contents of the array a, hence we replace b_0 by a, ie the array before the call, and b by a', ie the array after the call.

The assertions **to be shown**, α - ϵ are the midcondition Mid_2 , with the replacement: $a \mapsto a'$. That is, we want to show that the assertion Mid_2 holds for the array *after* the call.

Proof

- α follows from 1.
- β follows from 5. and 3.
- γ follows from 3. and the second conjunct in 4., and lemmas ($\approx Prm$) and ($\sim Trans$).
- δ follows from 3. and 6.
- ϵ follows from 4.

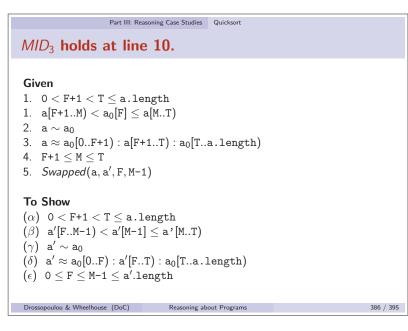


From the **Givens**, 1.-4. come from the Mid_2 .

Assertions $\alpha - \gamma$ come from the postcondition of swap(b,pivot,from,to), with the following replacements: $c \mapsto a$, $i \mapsto F$, $j \mapsto M-1$.

Proof α follows from the precondition of quicksort, and 3.

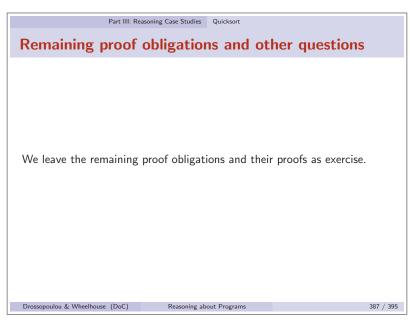
 β follows from the precondition of quicksort (0 \leq F) and 5, and 1. (M \leq a.length).



From the **Givens**, 1.-4. come from Mid_2 And **Given**.5. comes from the postcondition of sap, where we apply the the following replacements: $c \mapsto a, i \mapsto F, j \mapsto M-1$.

The assertions **to be shown**, $\alpha - \epsilon$ are the midcondition Mid_3 , with the replacement: $a \mapsto a'$. That is, we want to show that the assertion Mid_3 holds for the array after the call of swap(a,F,M-1).

```
Proof \alpha follows from 1. \beta follows from 5. and 3. \gamma follows from 3. and the second conjunct in 4., and lemmas (\approxPrm) and (\simTrans). \delta follows from 3. and 6. \epsilon follows from 4.
```



For fun: Can you turn the recursive quicksort to an iterative one? Can you then optimize the iterative version?

... read on in

Razvan Certezeanu, Sophia Drossopoulou, Benjamin Egelund-Mller, K. Rustan M. Leino, Sinduran Sivarajan, Mark J. Wheelhouse:

Quicksort Revisited - Verifying Alternative Versions of Quicksort.

Theory and Practice of Formal Methods 2016: 407-426

This is one of the outcomes of UROP placements in 2015.

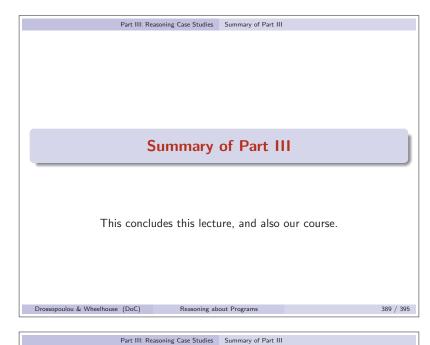
Summary of Part III

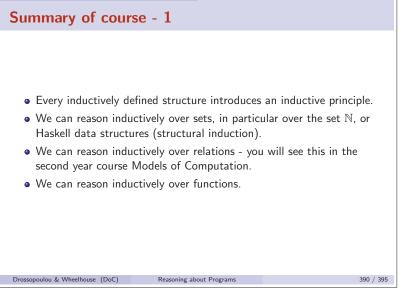
Part III - Conclusion

Midconditions can be used to develop a program
Before a method call, we must establish its precondition
We use the current midcondition to establish a method's precondition
After a method call, we may assume its postcondition
We use the postcondition to establish the next midcondition
We use the postcondition to establish the next midcondition

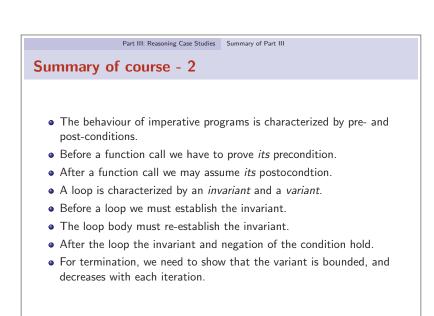
The steps outlined above reflect the mental process that underlies program development

In top-down development, functions call other functions whose specifications are known, but which have not yet been implemented





Drossopoulou & Wheelhouse (DoC)



Summary of course - 3

Be clear about what is given and what is to be shown.
Justify each step.
Vary size of steps according to task and your confidence.

Drossopoulou & Wheelhouse (DoC)

Reasoning about Programs

Summary of Part III

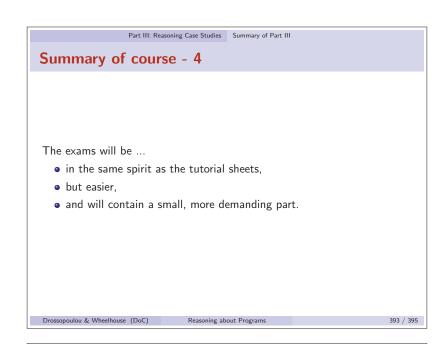
Summary of Part III

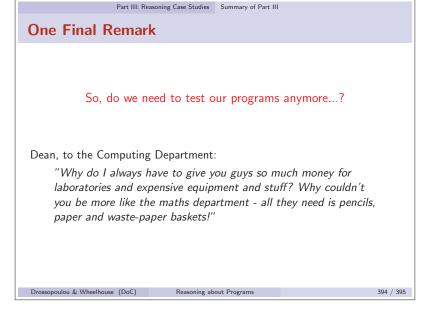
Reasoning about Programs

Summary of Part III

Summary of Part III

Reasoning about Programs





Thank you

