

# Krissy (Dahl) Gianforte

Seattle, WA

Krissy.Gianforte@gmail.com

(484) 744 1203

## **Career Summary**

*Engineer out of Caltech, currently pursuing a Master of Information and Data Science degree from UC Berkeley. Looking for a role focused on data science. Known for fast learning, self-motivated research, and unrelenting quality.*

I am a Data Scientist and Mechanical Engineer with over 5 years of experience in the healthcare industry. I have driven product testing as a Verification/Quality Engineer, and relished every opportunity to reduce test time and cost by applying innovative data analysis techniques. This year, I will complete a Masters in Data Science from UC Berkeley and hope to move fully into a Data Science role, where I can continue to creatively solve real-world problems. As part of the UC Berkeley program, I have gained practical skills in data manipulation, machine learning, statistical methods, and data visualization.

Building my career in the medical industry helped me build solid habits of clear communication and defendable, data-driven decisions. I am known by those I have worked with for diligent documentation, clear rationale, and reliable follow-through. My analyses and reports have withstood FDA scrutiny, and I have defended my work both internally and to the agency. I am excited to apply such signature care and creativity to new and interesting problems.

## **Technical Skills**

### **Data Science Software and Tools**

R (statistical computing)

Python

SQL

Command Line Interface (git, etc)

Machine Learning (including sklearn)

Natural Language Processing (TensorFlow)

Visualization (html, D3.js, Tableau)

### **Engineering Software**

PLC logic (Direct Soft 5)

SmartMotor control (Animatics SMI)

GUI/Interface design (Matlab, C-More HMI)

3D Printing (MendelMax, Repetier-Host)

Instron Material Testing

Solidworks 2012 & Inventor 2011

### **Medical Device Regulation & Standards**

ISO 13485 and 21 CFR 820 understanding and experience

Fluency in IEC 60601-1 and associated standards

Familiarity with IEC 14971, MIL-STD 810, RTCA DO-160, ISO 10993

## **Education**

### **UC Berkeley: School of Information**

### **Master of Information and Data Science (MIDS), 2019**

Coursework includes research design and applications for data analysis, statistical methods, experiments and causality, machine learning, and data visualization

### **Project Highlights:** (Demos at [people.ischool.berkeley.edu/~krissy](http://people.ischool.berkeley.edu/~krissy))

- Board Game Design: Machine learning analysis of board games using python and sklearn
- Ford GoBike Analysis: SQL exploration of GoBike data resulting in business recommendations
- Fitness Data Dashboard: User-oriented design of a fitness data visualization, implemented in D3
- Propaganda Experiment: Study designed to evaluate propaganda's effects on politics, analyzed in R

### **California Institute of Technology**

### **B.S. in Mechanical Engineering, 2012**

Coursework included engineering design, kinematics and robotics, control theory, learning systems, and programming methods

# Krissy (Dahl) Gianforte

Krissy.Gianforte@gmail.com

## **Professional Experience**

### **Product Creation Studio (2/2018-6/2018)**

Quality Engineer

Seattle, WA

- Responsible for all quality engineering project tasks and deliverables at PCS, including requirements development, risk analysis, and verification planning, execution, and reporting

### **Philips Healthcare, AED Business (4/2015-12/2017)**

Verification Lead, V&V Engineering

Bothell, WA

- Authored hardware verification test plans, sampling plans, protocols, tool packages, and test reports (including compliance testing and certifications)
- Performed statistical analysis on test data to determine test sample sizes and prove product reliability
- Interpreted medical device standards for their application to AED devices and accessories
- Participated in design reviews for input specifications, specifically for testability and consistency
- Developed test tools in C#, including a timing tool for interval testing and an equipment tracking program
- Provided mentorship and guidance to the team as a senior engineer; serves as a process expert to ensure that V&V work aligns with the Philips Quality System and applicable standards & regulations
- CAPA owner – performed root cause analysis; created action plan including correction, corrective action, and preventive action; documented progress and effectiveness
- Back-room reference for verification matters during audits; front-room experience as subject matter expert

### **Weyerhaeuser (7/2013-12/2014)**

Mechanical Engineer, Scale and Development Engineering, Timberlands Technology

Federal Way, WA

- Programmed control logic and interfaces for multiple PLC automated systems using DirectSoft5
- Developed image analysis program in Matlab (including GUI) for inspection of cellulose fibers products
- Designed and installed custom mechanical equipment for use in lumber mills and development labs

### **Medtronic Diabetes (7/2012-7/2013)**

Associate Mechanical Design Engineer, Research and Development

Northridge, CA

- Wrote design verification test plans and oversaw their execution. Authored corresponding verification reports for product approval and release
- Performed Minitab statistical analyses on test data to quantify design performance
- Constructed Matlab program to standardize a previously subjective visual test method for detecting material stress in injection molded plastic components

## **Research Experience**

### **Monticello Internship (6/2011-8/2011)**

Robotics Institute, Carnegie Mellon University

Pittsburgh, PA

Mentor: Dr. David Wettergreen

*Bucket Wheel Design for a Lightweight Robotic Lunar Excavator*

- Designed and constructed prototype digging tools for inclusion on a lunar rover
- Balanced project restrictions (power draw, launch weight) with excavation efficiency
- Executed tests in sandbox and performed analyses using Matlab to determine optimal tool design

### **Summer Undergraduate Research Fellowship (SURF) (6/2010-8/2010)**

Jet Propulsion Laboratory (JPL)

Pasadena, CA

Mentor: David R. Thompson, PhD

*Current-Sensitive Path Planning for an Underactuated Free-floating Ocean Sensorweb*

- Developed Matlab program to simulate motion of 3000 floating ocean sensors
- Implemented various algorithms to optimize movement of a large-scale system
- First author and presenter of paper at the IROS International Robotics Conference (9/2011)