rotated_Sprint_05400001_grf.mot $ground_force_calcn_r_vy$ ground_force_calcn_r_vx ground_force_calcn_r_vz 1e3 500 force (N) force (N) force (N) -500 -200 0.0 1.0 2.0 3.0 0.0 1.0 3.0 0.0 1.0 2.0 3.0 time (s) time (s) time (s) ground_force_calcn_r_px ground_force_calcn_r_py ground_force_calcn_r_pz 0.05 0.0 position (m) position (m) position (m) 0.00 0.5 -0.6 0.0 -0.05 0.0 1.0 0.0 1.0 2.0 3.0 0.0 3.0 3.0 time (s) time (s) time (s) ground_force_calcn_r_my ground_force_calcn_r_mx ground_force_calcn_r_mz 50 torque (N-m) torque (N-m) torque (N-m) 0 1.0 2.0 3.0 0.0 2.0 3.0 0.0 2.0 3.0 0.0 1.0 time (s) time (s) time (s) ground_force_calcn_l_vy ground_force_calcn_l_vx ground_force_calcn_l_vz 1e3 500 force (N) force (N) force (N) -200 -500 2.0 time (s) 0.0 0.0 time (s) time (s) ground_force_calcn_l_px ground_force_calcn_l_py ground_force_calcn_l_pz 0.05 position (m) position (m) position (m) -0.2 0.00 -0.6 0.0 -0.05 0.0 0.0 2.0 0.0 time (s) time (s) time (s)

rotated_Sprint_05400001_grf.mot





