rotated_Sprint_08550001_grf.mot ground_force_calcn_r_vz $ground_force_calcn_r_vx$ $ground_force_calcn_r_vy$ 1e3 500 3 250 force (N) force (N) force (N) -250 -500 0.5 1.5 2.0 0.5 1.5 0.5 1.5 2.0 time (s) time (s) time (s) ground_force_calcn_r_px $ground_force_calcn_r_py$ $ground_force_calcn_r_pz$ 0.05 0.00 1.5 position (m) position (m) position (m) -0.250.00 -0.50 -0.750.0 -0.05 0.5 2.0 0.5 2.0 time (s) time (s) time (s) ground_force_calcn_r_mx $ground_force_calcn_r_mz$ ground_force_calcn_r_my torque (N-m) torque (N-m) torque (N-m) -20 0.5 1.5 0.5 1.5 0.5 2.0 time (s) time (s) time (s) ground_force_calcn_l_vz ground_force_calcn_l_vx ground_force_calcn_l_vy 1e3 500 force (N) force (N) force (N) -200 -500 0.5 time (s) time (s) time (s) ground_force_calcn_l_pz ground_force_calcn_l_py ground_force_calcn_l_px 0.05 position (m) position (m) position (m) 0.00 2.5 0.0 -0.05 time (s) time (s) time (s)

rotated_Sprint_08550001_grf.mot





