rotated\_Sprint\_07200001\_grf.mot  $ground\_force\_calcn\_r\_vy$ ground\_force\_calcn\_r\_vx ground\_force\_calcn\_r\_vz 1e3 500 3 200 force (N) force (N) force (N) -200 <del>-</del>500 0 0.0 1.0 2.0 3.0 0.0 2.0 0.0 1.0 2.0 3.0 time (s) time (s) time (s) ground\_force\_calcn\_r\_px ground\_force\_calcn\_r\_py ground\_force\_calcn\_r\_pz 0.05 0.0 position (m) position (m) position (m) 0.00 0.0 -0.05 0.0 0.0 1.0 3.0 0.0 1.0 3.0 time (s) time (s) time (s)  $ground\_force\_calcn\_r\_mx$ ground\_force\_calcn\_r\_my ground\_force\_calcn\_r\_mz 50 torque (N-m) torque (N-m) torque (N-m) **-**50 **-**50 3.0 2.0 3.0 0.0 2.0 0.0 1.0 2.0 3.0 0.0 time (s) time (s) time (s) ground\_force\_calcn\_l\_vy ground\_force\_calcn\_l\_vz ground\_force\_calcn\_l\_vx 1e3 500 force (N) force (N) force (N) <del>-</del>200 0.0 1.0 0.0 1.0 2.0 time (s) time (s) time (s) ground\_force\_calcn\_l\_py ground\_force\_calcn\_l\_pz ground\_force\_calcn\_l\_px 0.05 position (m) position (m) position (m) 0.00 0.0 0.0 -0.05 0.0 1.0 2.0 3.0

time (s)

time (s)

time (s)

## rotated\_Sprint\_07200001\_grf.mot

