## rotated\_Sprint\_04500001\_grf\_raw.mot ground\_force\_1\_vx ground\_force\_1\_vy ground\_force\_1\_vz 1e3 force (N) force (N) force (N) -200 **-**500 2.0 time (s) 0.0 1.0 2.0 3.0 0.0 1.0 2.0 0.0 1.0 3.0 time (s) time (s) ground\_force\_1\_py ground\_force\_1\_px ground\_force\_1\_pz 0.05 -0.200 position (m) position (m) position (m) -0.2250.00 -0.250-0.275 **L** -0.05 0.0 0.0 1.0 2.0 1.0 2.0 3.0 1.0 2.0 3.0 time (s) time (s) time (s) ground\_force\_1\_mx ground\_force\_1\_my ground\_force\_1\_mz 0.05 0.05 50 torque (N-m) torque (N-m) torque (N-m) 0 0.00 0.00 **-**50 -0.05 -0.05 0.0 1.0 2.0 3.0 0.0 1.0 2.0 3.0 2.0 3.0 0.0 time (s) time (s) time (s) ground\_force\_2\_vy ground\_force\_2\_vx ground\_force\_2\_vz 1e3 200 force (N) force (N) force (N) -200 L 0.0 **-**500 2.0 time (s) 2.0 time (s) 2.0 time (s) 0.0 0.0 1.0 ground\_force\_2\_px ground\_force\_2\_py ground\_force\_2\_pz 0.05 -0.30position (m) position (m) position (m) 1.0 -0.35 0.00

-0.05

0.0

1.0

2.0

time (s)

3.0

2.0

time (s)

0.0

2.0

time (s)

## rotated\_Sprint\_04500001\_grf\_raw.mot



