

# TransLink RTM3.3 Release Volume Delay Function Update October 28th, 2019





### **Outline**

- Volume Delay Function: What's New?
- Network Conversion Tools





### **Volume Delay Function (VDF)**

Volume Delay Function Output  $travel\ time = signal\ delay + freeflow\ time + volume\ delay$ Function of Function of Link Distance Link Volume Speed Limit Link Capacity per Lane Number of Lanes Link Type



### Volume Delay Function (VDF) Definitions in RTM

	VDF Code RTM3.2 → RTM3.3	RTM3.2	RTM3.3
Special Functions	VDF[1] → VDF[11] Connectors	SAME	
	VDF[2] → VDF[12] Bowen Island Ferry	SAME	
Merge Functions	VDF[3 to 7] → VDF[13] Highway Merge Sections	$\frac{length * 60}{speed} + 0.85 * \left(\frac{volume}{(600 to 1400) * lanes}\right)^{5}$	$\frac{length * 60}{speed} + 0.85 * \left(\frac{volume}{capacity * lanes}\right)^{5}$
Controlled Intersection Functions	VDF[25 to 75] → VDF[14] Stop Sign & Signals	$0.25 + \frac{length * 60}{speed} + 0.85 * \left(\frac{volume}{(400 to 1400) * lanes}\right)^{4}$	$\frac{signal\_delay}{speed} + \frac{length * 60}{speed} + 0.85 * \left(\frac{volume}{capacity * lanes}\right)^{4}$
Free-Flow Links	VDF[85] → VDF[15] Free-flow (< 80 km/hr)	$\frac{length * 60}{speed} * \left(1 + 0.6 * 0.85 * \left(\frac{volume}{1600 * lanes^{1.05}}\right)^{5}\right)$	$\frac{length * 60}{speed} * \left(1 + 0.6 * 0.85 * \left(\frac{volume}{capacity * lanes^{1.05}}\right)^{5}\right)$
	VDF[88] → VDF[16] Free-flow (≥ 80 km/hr)	$\frac{length * 60}{speed} * \left(1 + 0.6 * 0.43 * \left(\frac{volume}{1600 * lanes^{1.05}}\right)^{5.25}\right)$	$\frac{length * 60}{speed}* \left(1 + 0.6*0.43* \left(\frac{volume}{capacity*lanes^{1.05}}\right)^{5.25}\right)$



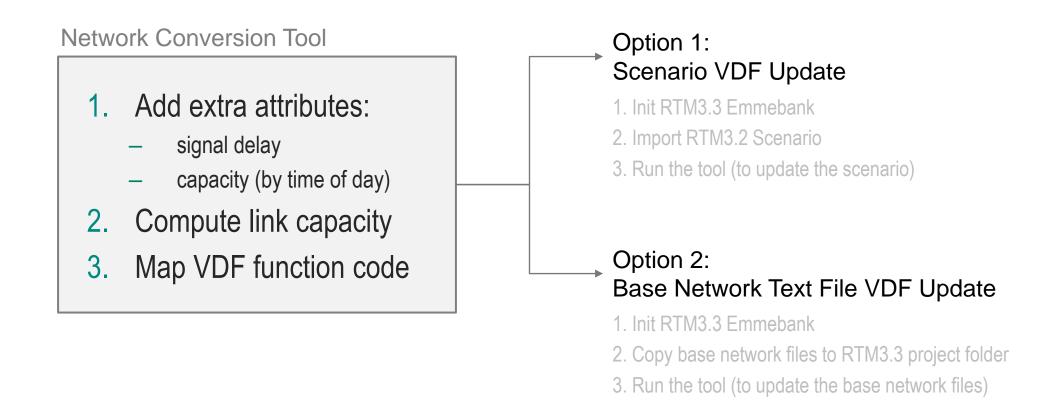
### **Modelling Enhancement**

- Calibrate to local conditions:
  - Signal coordination
  - Side street movement is minor
- Technology impact assessment:
  - Connected & autonomous vehicle

# **Network Conversion Tool**



### **Update Existing RTM3.2 Networks**



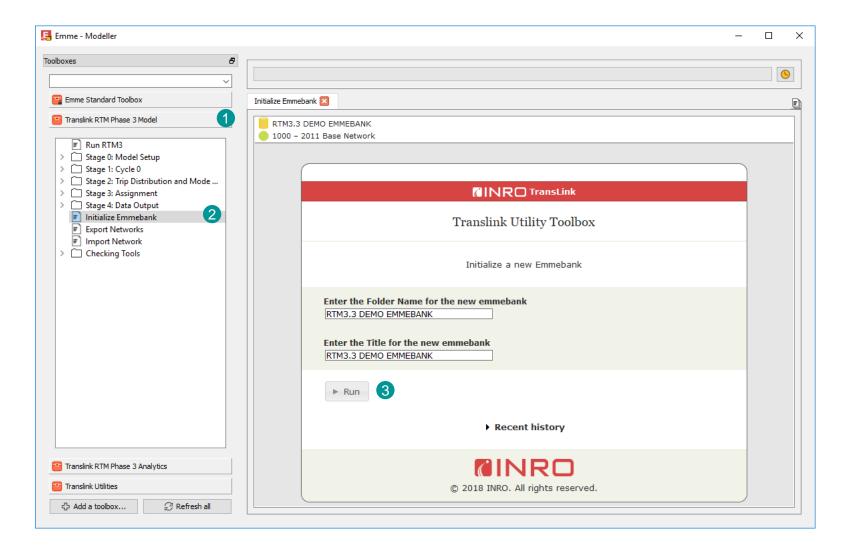
### Option 1: Scenario VDF Update



### **Scenario VDF Update**

- 1. Init RTM3.3 Emmebank
- 2. Import RTM3.2 Scenario
- 3. Run the tool

- Navigate to RTM Model Toolbox
- Launch "Initialize Emmebank" Tool
- 3 Enter Emmebank Name and Run

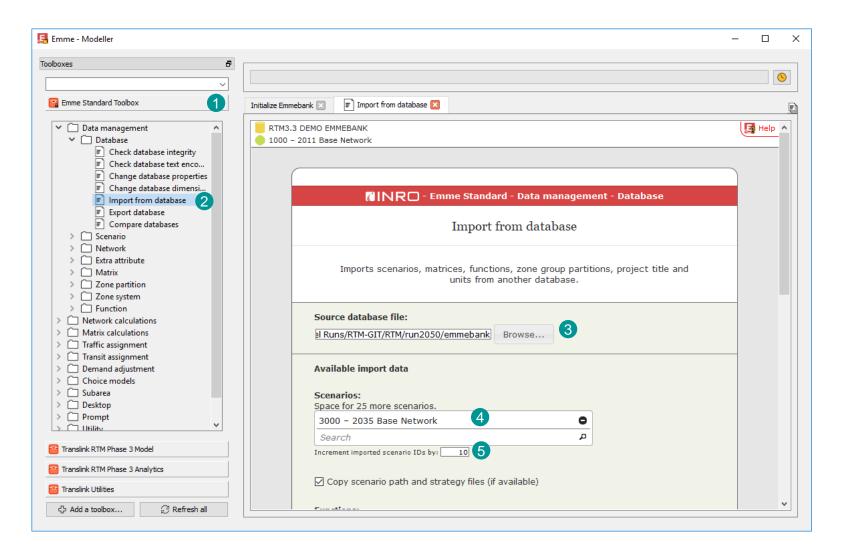




### **Scenario VDF Update**

- 1. Init RTM3.3 Emmebank
- 2. Import RTM3.2 Scenario
- 3. Run the tool

- Navigate to Standard Toolbox
- Launch "Import from database" Tool
- Select Source Emmehank file
- 4 Select RTM3.2 Scenarios
- **6** Enter Increment to Scenario IDs and Run

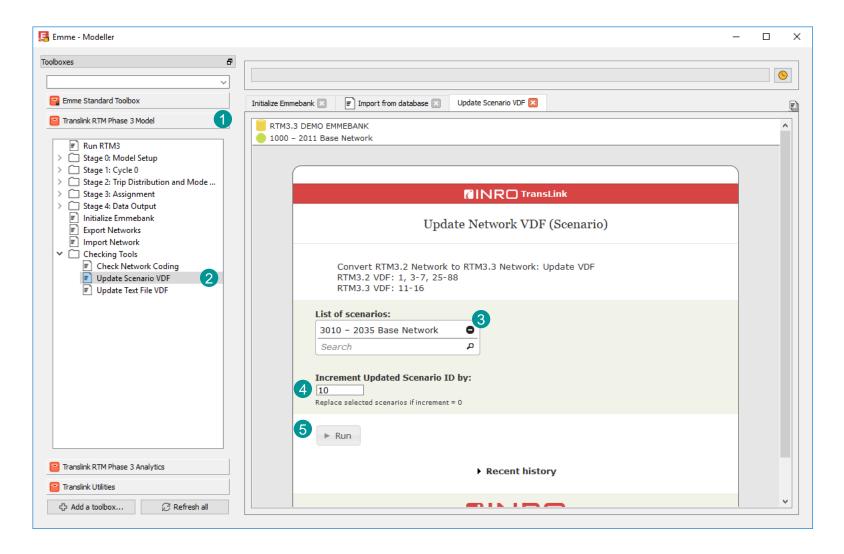




### **Scenario VDF Update**

- 1. Init RTM3.3 Emmebank
- 2. Import RTM3.2 Scenario
- 3. Run the tool

- Navigate to RTM Toolbox
- Launch "Update Scenario VDF" Tool
- 3 Select RTM3.2 Scenarios
- Enter Increment to Scenario IDs
- Run



# Option 2: Base Network Text File VDF Update

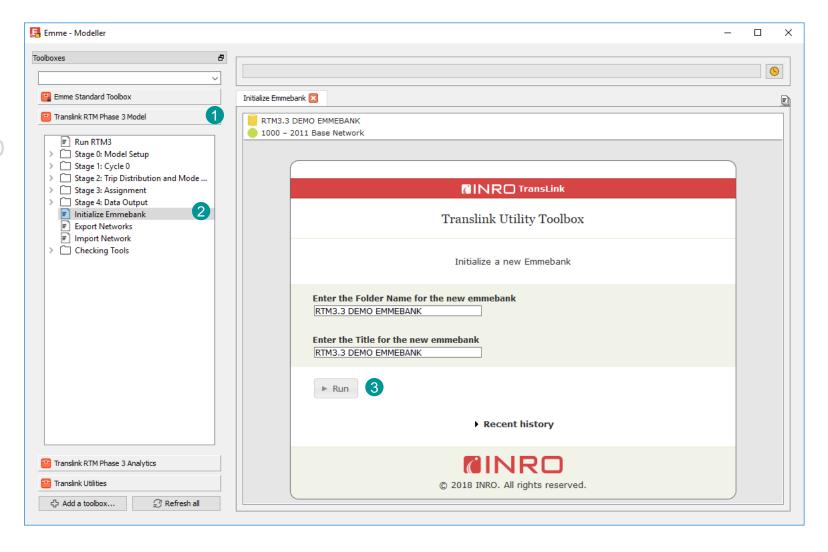


### **Base Network Text File VDF Update**

### 1. Init RTM3.3 Emmebank

- 2. Copy base network files to RTM3.3 project folder
- 3. Run the tool

- Navigate to RTM Model Toolbox
- Launch "Initialize Emmebank" Tool
- 3 Enter Emmebank Name and Run

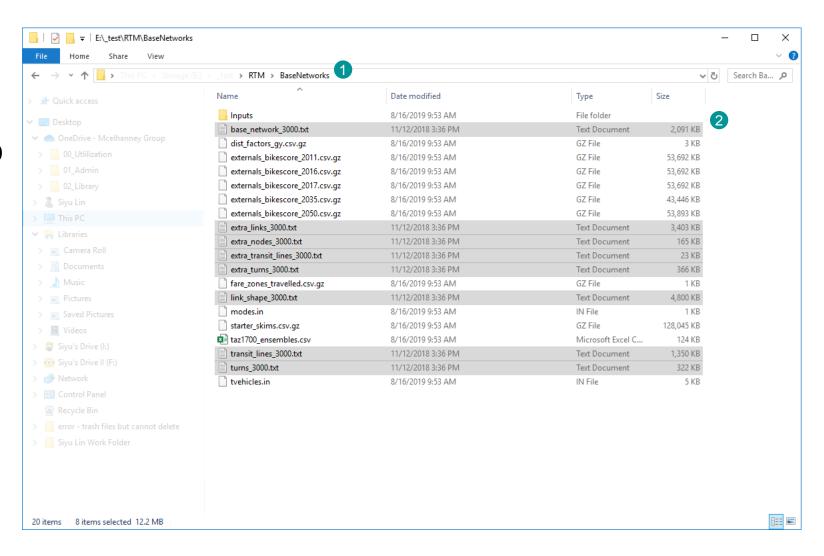




### **Base Network Text File VDF Update**

- 1. Init RTM3.3 Emmebank
- 2. Copy base network files to RTM3.3 project folder
- 3. Run the tool

- Open RTM > BaseNetworks folder
- 2 Copy Base Network Files (8/scenario)
  - base network ####.txt
  - extra links ####.txt
  - extra nodes ####.txt
  - extra\_transit\_lines \_####.txt
  - extra turns ####.txt
  - link shape ####.txt
  - transit lines ####.txt
  - truns ####.txt

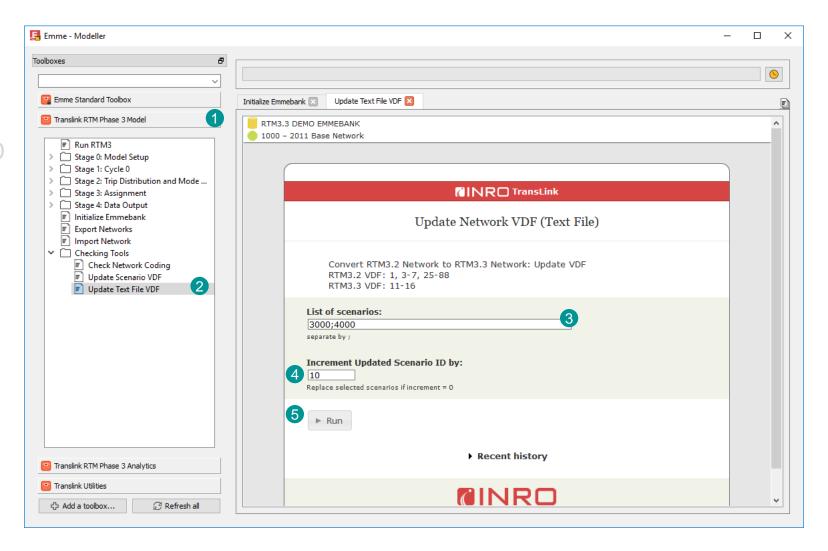




### **Base Network Text File VDF Update**

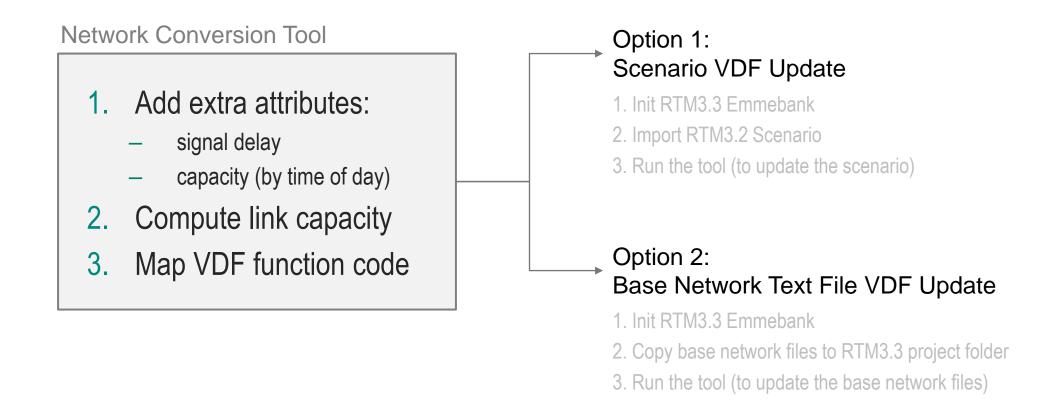
- 1. Init RTM3.3 Emmebank
- 2. Copy base network files to RTM3.3 project folder
- 3. Run the tool

- Navigate to RTM Toolbox
- Launch "Update Scenario VDF" Tool
- 3 Enter Scenario IDs (separated by ;)
- 4 Enter Increment to Scenario IDs
- Run





### **Update Existing RTM3.2 Networks**



## VDF Update

- 1. SIGNAL DELAY AND LINK CAPACITY ARE EXPLICITLY CODED.
- 2 IMPROVED FORMULATION FOR TRAVEL TIME CALIBRATION.
- 3. CONVERSION TOOLS UPDATE THE EXISTING NETWORKS.