# BRYAN KRISTIONO

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★ kristinus.github.io/Portfolio

Waterloo Computer Science Student | 2B

## Skills

## Languages:

Java, C++, Javascript, C, HTML, SCSS, Python, Bash, Racket

#### Tools:

Angular, React Native, Expo Linux/Unix, AWS, Jenkins, **Google Cloud Services** Photoshop, Indesign

## Hardware:

Arduino, Roborio, Controller Area Network

## **Education**

## **University of Waterloo**

Candidate for Honours Bachelor of Computer Science | Co-op 2016 - 2021

GPA: 3.67

## **Awards**

#### **First Robotics Competition:**

2017 Durham District Winner 2016 North bay Regional Winner 2016 Waterloo Regional Winner 2016 Championship Division Finalist

### Activities

Fashion for Change	2018
<ul> <li>Web Developer</li> </ul>	
Party Games Club	2017 - 2018
<ul> <li>Executive</li> </ul>	
Acapella ACE	2017 - 2018
• Tenor 2	
Waterloo Math Faculty	2017 - 2018

Orientation Leader

**Ambassador** 

## **Work Experience**

# **Qualicom | Programmer Trainee**

Apr 2017 - Aug 2017

#### North York, ON

- Developed web applications using Angular and provided suitable user interface for customers.
- Designed and programmed mobile UI for ecommerce website with consideration to UX.
- Integrated Continuous Delivery by constructing a Unix build server with Jenkins capable of automating builds, tests, and deployment.

## **Projects**

## Alexa Skill | Animal Buzz (Javascript)

Jan 2018

Sept 2017

- Launched an Alexa app quiz game on US stores applying Amazon Web Services Lambda for development.
- Enhanced Voice User Interface specifically for young children, as per design for Alexa Skills Challenge.

## Injury Detector | BruiseClues (Javascript)

- Deployed a native app that uses Google cloud vision API to detect injuries and notify the user relevant treatment information.
- Developed with Javascript and React native on Expo.io to allow the app to run on both IOS and Android.

## FRC Robot | Black Mamba (Java)

Jan 2016 - Apr 2016

- Developed camera tracking for automatic targeting using Roborealm and retroreflective tape for a ball shooting robot.
- Utilized trigonometric analysis to integrate computer vision with motion control.
- Created over 30 autonomous sequences to achieve double the points during competition.

## **Volunteer Experience**

#### THEORY 6 | Robotics Mentor

Sept 2016 - Present

Mississauga, ON

- Teach students the process of integrating actuators and sensors to mechanical components.
- Guide students to produce mechanical movements with the use of libraries and sensors.

#### Hack the North | Volunteer

Sept 2017

University of Waterloo

 Spent over 20 hours volunteering for Canada's largest hackathon, including helping with set-up, registration and hardware lending.