

Representation of the Earth Potential by Buried Masses

GEORGES BALMINO

*Groupe de Recherches de Géodésie Spatiale
Observatoire, 92 Meudon, France*

Abstract. Some ways of representing the earth potential by point masses are explored. The 1969 standard earth model of the Smithsonian Astrophysical Observatory is used as a reference. Points regularly distributed on a sphere inside the earth have been considered, as well as nonuniform configurations. The values of the masses are derived by a least-squares fit to the SAO field. The values of the different representations obtained have been checked by computing the geoid heights, gravity anomalies, and spherical harmonics associated with the field of the masses. The best model obtained consists of 126 points, mostly at a depth of 1300 km, tied to the important gravity anomalies derived from the reference field. The mean of the residuals is 6 mgal.

The main results obtained so far in dynamical geodesy have been based on the expansion of the earth potential in spherical harmonics. The methods of analysis are complex, for they have to process numerous observations made on different satellites from many stations; in addition, the determination of the potential coefficients and station coordinates, computed at the same time, involves very large matrices that cannot be handled easily on present computers.

In the near future, the technical progress in satellite geodesy, as well as great improvements in type and accuracy of observational methods, will make it necessary to use new representations of the potential of the earth. The series of harmonic coefficients converges very slowly, and too many terms must be taken into account in order to represent small, or short-wave, variations of the field (as measured by an altimeter or determined from gravity measurements). It is desirable that new representations satisfy as many as possible of the following conditions:

1. Discrete formulation (one 'detail' for one function), which leads to simple programming. (Recursive formulas lead to important errors, which occur, for example, if one computes the Legendre functions up to (180, 180) to represent details of 1 degree on the geoid.)

2. Homogeneous representation on both the surface and exterior of the earth.

3. Possibility of increasing locally the number of parameters without perturbing distant regions.

4. The same formulation of the potential and its derivative on and outside the earth, so as to facilitate the combination of observations from different sources (like gravity anomalies and satellite-to-ocean altimetry).

The representation of the gravity field by buried masses, which was suggested by *Weightmann* [1967] several years ago, can satisfy these conditions under some restrictions on the configuration and depth of the points.

Theoretically, any distribution of masses inside the earth that keeps the geoid fixed gives the same field outside the geoid. Consequently, it is reasonable to distribute the mass points regularly. Nevertheless, the anomalies of the gravity field already known make us think of putting the masses at the places where particular features exist.

Taking the last standard earth model determined by *Gaposchkin and Lambeck* [1970], we have tried in our approach to attain an equivalence between this model and a configuration of mass points, in order to represent the gravimetric geoid as well as possible. The values of differently obtained representations outside the earth have been checked by integrating satellite orbits.

METHOD

One has the choice of taking a regular distribution on a sphere inside the earth, or putting the points at places corresponding to large gravity anomalies. If the anomalies of the field are not known (they are to be determined through observations), only the first point of view is valid, and a large number of mass points close to the earth's surface must be considered. One can also take surface density values [Koch, 1970], but the expression for the external field is not convenient to use for satellite motion.

Starting from an a priori configuration of points $(\mathbf{P}_i)_0$, $i = 1, 2, \dots, N$, we determine parameters ϵ_i such that:

$$U_0 = \frac{GM}{r} \left[1 - \sum_{n=2}^{21} \left(\frac{a}{r} \right)^n J_n P_n(\sin \phi) + \sum_{n=2}^{22} \left(\frac{a}{r} \right)^n \sum_{k=1}^{n'} (C_{nk} \cos k\lambda + S_{nk} \sin k\lambda) P_{nk}(\sin \phi) \right] \tag{1}$$
$$n' = \min(n, 16)$$

$$U_M = E + T_M = E + \sum_{k=1}^N T_{Mk} = E + GM \sum_{k=1}^N \frac{\epsilon_k}{r_k}$$
$$\iiint_D |U_0 - U_M|^2 dv \text{ is a minimum} \tag{2}$$

where E is a reference potential included in U_m (because terms like

$$1/r \text{ or } (1/r) J_2(a/r)^2 P_2(\sin \phi)$$

cannot be easily represented otherwise, except by deep point masses, which are without physical meaning, and D is a region of space outside the earth (e.g., between 500- and 1500-km height).

D is represented by a large number $M(>N)$ of points S , and we thus have

$$\sum_{i=1}^N \left[\left(\frac{\partial T_M}{\partial \epsilon_i} \right)_S \Delta \epsilon_i + (\nabla T_{Mi})_S \cdot \Delta \mathbf{P}_i \right] = (U_0 - U_M)_S$$

with

REPRESENTING EARTH POTENTIAL

$$\Delta \mathbf{P}_i = \mathbf{P}_i - (\mathbf{P}_i)_0$$
$$\Delta \epsilon_i = \epsilon_i - (\epsilon_i)_0$$
$$(\epsilon_i)_0 = 0$$

at the first iteration.
Different weights according to the heights of S can be chosen. In addition, we add the following constraints:

$$\sum_{i=1}^N \epsilon_i = 0$$

i.e., the total mass of the earth is unchanged, and

$$\sum_{i=1}^N \epsilon_i \mathbf{p}_i = 0$$

i.e., the center of inertia is not modified.
In the above,

$$\mathbf{p}_k = \mathbf{r} - \mathbf{r}_k$$

where \mathbf{r} is the geocentric vector to S , the point at which the potential is being computed, and \mathbf{r}_k is the vector from mass point P_k to S .
Finally, we solve

$$\begin{pmatrix} [\mathbf{A}^T \mathbf{\Pi} \mathbf{A}] & \mathbf{J}^T \\ \mathbf{J} & 0 \end{pmatrix} \begin{pmatrix} \mathbf{Y} \\ \mathbf{\Lambda} \end{pmatrix} = \begin{pmatrix} [\mathbf{A}^T \mathbf{\Pi}] & \mathbf{\Delta} \\ 0 & 0 \end{pmatrix} \tag{3}$$

where

- \mathbf{A} is the matrix of equations of condition.
- \mathbf{J} is the jacobian of constraints.
- \mathbf{y} is the vector of unknowns.
- $\mathbf{\Lambda}$ is the vector of Lagrange multipliers.
- $\mathbf{\Pi}$ is the matrix of weights.
- $\mathbf{\Delta}$ is the vector of the quantities $(U_0 - U_M)$.

Results obtained using (3) in conjunction with (1) and (2) did not yield a satisfactory representation of the field on the earth's surface. Hence, condition (2) was replaced by:

$$\iint_{\Phi} |\Delta g_0 - \Delta g_M|^2 ds \text{ is a minimum} \tag{4}$$

where Δg_0 is the field of the gravity anomalies derived from U_0 , and

$$\Delta g_M = \frac{\partial T_M}{\partial n} - \frac{2T}{a}$$

n being the normal at the surface Φ of the reference ellipsoid whose potential here is exactly E and whose mean radius is a .

GEORGES BALMINO

A natural weighting is obtained by writing the condition equations on the level curves of the gravity anomalies, which gives more importance to the large anomalies. Local studies have been made to determine optimal values ϵ_i, ρ_i for large anomalies.

The adequacy of a mass-point representation obtained via (2) or (4) can be checked in the following ways:

- 1. Computation of the residuals $U_o - U_M$ in D .
- 2. Calculation of gravity anomalies on ϕ from the formula:

$$\Delta g_Q = GM \sum_{k=1}^N \frac{\epsilon_k}{r_k^3} (a - \rho_k \cos \psi_k)$$

where Q is a point on Φ , a is the geocentric radius to Q , and ψ_k is the geocentric angle between \mathbf{g}_i and \mathbf{a} ; Δg_Q can then be compared with the actual anomaly at Q .

- 3. Determination of a harmonic coefficient set

$$\langle \gamma_{lm} \rangle = \sum_{k=1}^N \epsilon_k \left(\frac{\rho_k}{a} \right)^l \bar{P}_{lm}(\sin \phi_k) \cdot \left(\frac{(2 - \delta_0^m)(l - m)!}{(2l + 1)(l + m)!} \right)^{1/2} \cos m \lambda_k$$

$$\langle \sigma_{lm} \rangle = \sum_{k=1}^N \epsilon_k \left(\frac{\rho_k}{a} \right)^l \bar{P}_{lm}(\sin \phi_k) \cdot \left(\frac{(2 - \delta_0^m)(l - m)!}{(2l + 1)(l + m)!} \right)^{1/2} \sin m \lambda_k$$

where the bar denotes normalization; these can be compared with the SAO coefficients [Gaposchkin and Lambeck, 1970].

- 4. Comparison of numerical integration of a given orbit of a satellite in the SAO field and in the field U_M .

RESULTS

Various tests using regular distributions of mass points and condition 2 proved unsatisfactory. A model that gave a good representation of the gravity anomalies on the ellipsoid was obtained in the following manner. The reference potential E in (1) was taken to be the earth ellipsoid harmonics. Ninety-two points were positioned at the extreme values of a map of gravity anomalies based on the SAO

standard earth. Constraining the points to lie at the same depth, the best representation was obtained at a depth of 1300 km. This preliminary model was improved by adding additional points up to a total of 126 and individually adjusting the depths of the 20 largest anomalies. The results are given in Table 1. For this model,

TABLE 1. Model for 126 Mass Points

| <i>N</i> | Lat. ϕ , deg | Long. λ , deg | Depth, km | Mass ϵ , 10^{-6} mass of earth |
|----------|----------------------|--------------------------|--------------|--|
| 1 | 59 | -152 | -1100 | 1.753 |
| 2 | 3 | -176 | -1300 | -0.511 |
| 3 | -66 | -177 | -1300 | -1.667 |
| 4 | 20 | -160 | -1300 | 0.810 |
| 5 | -31 | -159 | -1300 | 1.176 |
| 6 | -15 | -158 | -1300 | -0.499 |
| 7 | -2 | -155 | -1300 | 0.912 |
| 8 | 22 | -143 | -1300 | -1.233 |
| 9 | -27 | -140 | -1300 | -1.734 |
| 10 | 32 | -126 | -1300 | -1.603 |
| 11 | 3 | -125 | -1300 | -1.159 |
| 12 | -19 | -121 | -1300 | 0.762 |
| 13 | -46 | -121 | -1500 | 2.122 |
| 14 | 47 | -115 | -1100 | 0.667 |
| 15 | -12 | -101 | -1300 | 0.699 |
| 16 | -49 | -99 | -1300 | -1.632 |
| 17 | 38 | -98 | -1300 | -1.334 |
| 18 | -76 | -95 | -1300 | -1.265 |
| 19 | -35 | -85 | -1300 | 0.579 |
| 20 | -15 | -85 | -1000 | -1.507 |
| 21 | 60 | -89 | -1300 | -2.065 |
| 22 | 39 | -71 | -1300 | -0.645 |
| 23 | 0 | -71 | -1300 | 1.868 |
| 24 | -19 | -69 | -1300 | 1.667 |
| 25 | -54 | -69 | -1500 | 1.048 |
| 26 | 19 | -64 | -1300 | -1.713 |
| 27 | 24 | -28 | -1300 | -0.175 |
| 28 | 9 | -49 | -1300 | -1.275 |
| 29 | -14 | -52 | -1300 | -1.015 |
| 30 | -36 | -42 | -2000 | -0.646 |
| 31 | 42 | -32 | -1100 | 1.876 |
| 32 | -18 | -24 | -1200 | -1.061 |
| 33 | 69 | -20 | -1300 | 0.977 |
| 34 | 60 | -175 | -1300 | -0.933 |
| 35 | 9 | -11 | -1300 | 0.974 |
| 36 | 22 | -4 | -1300 | -0.665 |
| 37 | -64 | -25 | -1500 | 0.753 |
| 38 | 39 | -3 | -1000 | 1.218 |
| 39 | -39 | 2 | -1000 | -0.616 |
| 40 | -50 | 15 | -1300 | 0.987 |
| 41 | -66 | 21 | -1300 | -1.337 |
| 42 | -42 | 24 | -1300 | -0.848 |
| 43 | 4 | 25 | -1000 | -1.482 |
| 44 | 18 | 29 | -1300 | 1.940 |
| 45 | 30 | 25 | -1300 | -2.460 |
| 46 | 45 | 26 | -1000 | 1.498 |

TABLE 1. (continued)

| <i>N</i> | Lat. ϕ , deg | Long. λ , deg | Depth, km | Mass ϵ , 10^{-6} mass of earth |
|----------|----------------------|--------------------------|--------------|--|
| 47 | 35 | 46 | -1300 | 2.707 |
| 48 | 21 | 50 | -1300 | -2.213 |
| 49 | -6 | 48 | -1100 | -1.360 |
| 50 | -43 | 43 | -1300 | 2.359 |
| 51 | -44 | 61 | -1300 | -1.681 |
| 52 | -67 | 73 | -1300 | 1.682 |
| 53 | -36 | 74 | -1300 | 1.603 |
| 54 | 4 | 79 | -1000 | -2.143 |
| 55 | 41 | 68 | -1300 | -1.807 |
| 56 | 69 | 76 | -1300 | -1.792 |
| 57 | 35 | 90 | -1300 | 1.308 |
| 58 | -49 | 99 | -1300 | 1.380 |
| 59 | -25 | 98 | -1300 | -1.575 |
| 60 | -1 | 112 | -1300 | 1.590 |
| 61 | 47 | 100 | -1300 | -1.931 |
| 62 | 62 | 109 | -1300 | 2.080 |
| 63 | 12 | 124 | -1300 | 1.110 |
| 64 | -21 | 121 | -1300 | 0.808 |
| 65 | -38 | 122 | -1300 | -2.029 |
| 66 | -63 | 120 | -1300 | -1.442 |
| 67 | -4 | 142 | -1100 | 1.224 |
| 68 | 31 | 141 | -1300 | 1.625 |
| 69 | -42 | 152 | -1500 | -2.374 |
| 70 | 1 | 159 | -1300 | -0.434 |
| 71 | 39 | 160 | -1300 | -1.755 |
| 72 | 57 | 158 | -1300 | 2.384 |
| 73 | -47 | 135 | -1300 | -0.178 |
| 74 | -25 | 174 | -1300 | 0.766 |
| 75 | 22 | 101 | -1300 | -0.895 |
| 76 | 68 | 133 | -1300 | -1.734 |
| 77 | -9 | 30 | -1300 | 0.498 |
| 78 | 16 | -94 | -1300 | 0.707 |
| 79 | 10 | 50 | -1300 | 1.573 |
| 80 | 40 | -112 | -1300 | 1.519 |
| 81 | 58 | -40 | -1300 | -0.578 |
| 82 | 58 | 53 | -1300 | 1.700 |
| 83 | -18 | -40 | -1300 | 1.284 |
| 84 | -46 | 167 | -1300 | 1.113 |
| 85 | 85 | 100 | -1100 | 1.052 |
| 86 | -42 | -35 | -2000 | -2.932 |
| 87 | -42 | -16 | -1300 | 1.248 |
| 88 | 26 | 126 | -1300 | -1.006 |
| 89 | 40 | 131 | -1300 | 0.942 |
| 90 | -19 | 160 | -1200 | 0.684 |
| 91 | 39 | -163 | -1300 | -0.595 |
| 92 | 42 | -17 | -1100 | -1.040 |
| 93 | 43 | -135 | -1300 | -1.365 |
| 94 | 33 | -144 | -1300 | 0.933 |
| 95 | 17 | -134 | -1300 | 1.106 |
| 96 | -51 | -142 | -1300 | -0.318 |
| 97 | -34 | -108 | -1300 | -0.378 |

REPRESENTING EARTH POTENTIAL

TABLE 1. (continued)

| <i>N</i> | Lat. ϕ , deg | Long. λ , deg | Depth, km | Mass ϵ , 10^{-6} mass of earth |
|----------|----------------------|--------------------------|--------------|--|
| 98 | 44 | -89 | -1300 | 1.252 |
| 99 | 77 | -121 | -1300 | -0.334 |
| 100 | 82 | -78 | -1300 | -0.857 |
| 101 | 85 | -20 | -1300 | 0.048 |
| 102 | 71 | -52 | -1300 | 1.519 |
| 103 | 37 | -53 | -1300 | -0.470 |
| 104 | 27 | -44 | -1300 | 1.064 |
| 105 | 58 | -5 | -1300 | 0.667 |
| 106 | -85 | 100 | -1300 | -0.010 |
| 107 | 4 | -28 | -1300 | 0.333 |
| 108 | -6 | -11 | -1300 | -0.127 |
| 109 | -27 | -16 | -1300 | -0.133 |
| 110 | -73 | -15 | -1300 | 0.625 |
| 111 | -61 | -81 | -1300 | 0.622 |
| 112 | -33 | -70 | -1300 | 0.064 |
| 113 | -23 | -4 | -1300 | 1.177 |
| 114 | -10 | 4 | -1300 | -0.403 |
| 115 | -19 | 30 | -1300 | 0.091 |
| 116 | 28 | 65 | -1300 | 0.961 |
| 117 | 48 | 43 | -1300 | -2.070 |
| 118 | 58 | 13 | -1300 | -1.057 |
| 119 | 16 | 145 | -1300 | -0.561 |
| 120 | -47 | 137 | -1300 | 0.899 |
| 121 | -16 | 69 | -1300 | 0.336 |
| 122 | -15 | 112 | -1300 | -0.598 |
| 123 | -29 | 145 | -1300 | 0.153 |
| 124 | 23 | 165 | -1300 | -0.164 |
| 125 | 55 | 131 | -1300 | -0.872 |
| 126 | 15 | 14 | -1300 | 0.990 |

the mean of the residuals is 6 mgal and the largest differences are of the order of 10 mgal, which is the estimated accuracy of the SAO standard earth.

REFERENCES

Gaposchkin, E. M., and K. Lambeck, 1969 Smithsonian standard earth (II), *Smithson. Astrophys. Observ. Spec. Rep. 315*, 1970.
Koch, K. R., Surface density values for the earth from satellite and gravity observations, *Geophys. J. Roy. Astron. Soc.*, 21, 1-12, 1970.
Weightman, J. A., Gravity, geodesy, and artificial satellites: A unified analytical approach, in *The Use of Artificial Satellites for Geodesy*, vol. 2, edited by G. Veis, pp. 467-486, National Technical University, Athens, Greece, 1967.