Homework 5. Random Forests, OOBE

```
In [1]:
```

```
import matplotlib.pyplot as plt
import random

from matplotlib.colors import ListedColormap
from sklearn import datasets
from collections import Counter

import numpy as np
from sklearn.model_selection import train_test_split
```

Task 5

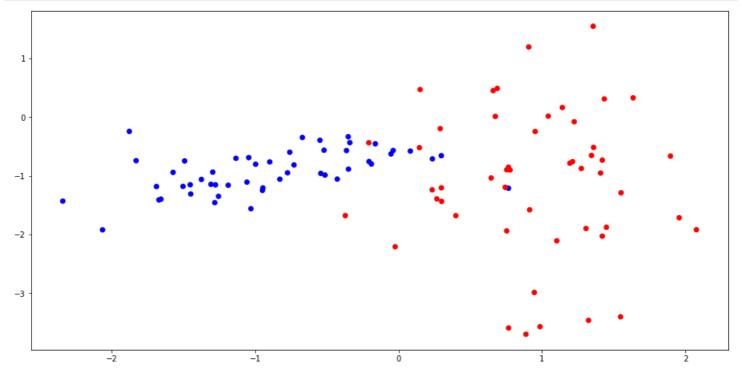
Сформировать с помощью sklearn.make_classification датасет из 100 объектов с двумя признаками,

обучить случайный лес из 1, 3, 10 и 50 деревьев и

визуализировать их разделяющие гиперплоскости на графиках (по подобию визуализации деревьев из предыдущего урока, необходимо только заменить вызов функции **predict** на **tree vote**).

Сделать выводы о получаемой сложности гиперплоскости и недообучении или переобучении случайного леса в зависимости от количества деревьев в нем.

In [2]:



```
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size = 0.3, random_state=4
2)
```

In [4]:

In [5]:

```
class DecisionTreeClassifier:
     класс узла
    class Node:
       def init (self, feature index, threshold, true branch, false branch):
            self.feature index = feature index
            self.threshold = threshold
            self.true branch = true branch
            self.false branch = false branch
     класс терминального узла
   class Leaf:
       def init (self, X, y):
            self.X = X
            self.y = y
            classes = Counter(self.y)
            self.prediction = max(classes, key=classes.get)
    def __init__(self, *, max_depth=None, max_features=None, min_gain=None, min_leaf_sampl
es=1):
        self.max depth = max depth
        self.max features = max features
        self.min gain = min gain
        self.min leaf samples = min leaf samples
        self.used features = set()
        self.tree = None
    def fit(self, X, y):
        self.tree = self.build_tree(np.array(X), np.array(y))
    def build_tree(self, X, y, current_depth=0):
        if (self.max_depth is not None) and (current_depth == self.max_depth):
            return self.Leaf(X, y)
        quality, threshold, feature index = self.find best split(X, y)
        if (quality == 0) or ((self.min gain is not None) and (quality < self.min gain)):</pre>
            return self.Leaf(X, y)
        true X, false X, true y, false y = self.split(X, y, feature index, threshold)
        if feature index not in self.used features:
            self.used features.add(feature index)
        true branch = self.build tree(true X, true y, current depth + 1)
        false branch = self.build tree(false X, false y, current depth + 1)
        return self.Node(feature index, threshold, true branch, false branch)
    def find best split(self, X, y):
        current gini = self.gini(y)
        best quality = 0
        best t = None
        best feature index = None
        n features = X.shape[1]
```

```
for feature index in range(n_features):
            if ((self.max features is not None)
                and (feature index not in self.used features)
                and (len(used features) == self.max features)):
                continue
            threshold values = np.unique(X[:, feature index])
            for t in threshold values:
                true X, false X, true y, false y = self.split(X, y, feature index, t)
                if min(len(true X), len(false X)) < self.min leaf samples:</pre>
                    continue
                current_quality = self.quality(true_y, false_y, current_gini)
                if current_quality > best_quality:
                    best quality, best t, best feature index = current quality, t, featur
e index
       return best quality, best t, best feature index
   def split(self, X, y, feature index, threshold):
        true indexes = np.where(X[:, feature index] <= threshold)</pre>
        false indexes = np.where(X[:, feature index] > threshold)
        return X[true indexes], X[false indexes], y[true indexes], y[false indexes]
   def quality(self, true_y, false_y, current_gini):
        true prob = float(true y.shape[0]) / (true y.shape[0] + false y.shape[0])
        return current gini - (true prob * self.gini(true y)) - ((1 - true prob) * self.g
ini(false y))
   def gini(self, y):
        impurity = 1
        for class count in Counter(y).values():
            p = class count / len(y)
            impurity = impurity - p ** 2
        return impurity
    def predict(self, X):
        return np.array([self.classify object(obj, self.tree) for obj in X])
    def classify object(self, obj, node):
        if isinstance(node, self.Leaf):
            return node.prediction
        if isinstance(obj, float):
            костыль из-за неспособности разобраться, почему возникает ошибка
            IndexError: invalid index to scalar variable.
            на строке
            --> 100
                            if (obj[node.feature index] <= node.threshold):</pre>
            в classify object(self, obj, node)
            if obj <= node.threshold:</pre>
               return self.classify object(obj, node.true branch)
            else:
               return self.classify object(obj, node.false branch)
        else:
            if (obj[node.feature index] <= node.threshold):</pre>
                return self.classify object(obj, node.true branch)
            else:
               return self.classify object(obj, node.false branch)
             """конец костыля"""
```

In [6]:

```
class RandomForestClassifier:
    def __init__(self, *args, n_trees, random_state=None, oob_metric=False, **kwargs):
```

```
self.n trees = n trees
        self.args = args
        self.kwargs = kwargs
        self.forest = []
        self.oob metric = oob metric
        if self.oob metric:
            self.oob accuracy = None
        if random state:
            np.random.seed(random state)
    def fit(self, X, y):
       X, y = np.array(X), np.array(y)
        preds = []
        for in range(y.shape[0]):
            preds.append([])
       bootstraps = self.get bootstrap indexes(X, y, n trees=self.n trees)
        for obs indexes, feat indexes in bootstraps:
            tree = DecisionTreeClassifier(*self.args, **self.kwargs)
            tree.fit(X[obs_indexes][:, feat_indexes], y[obs_indexes])
            self.forest.append(tree)
        if self.oob metric:
            oob indexes = (i for i in range(X.shape[0]) if i not in obs indexes)
            for i in oob indexes:
                preds[i].append(tree.predict(X[i])[0])
            oob preds = []
            y copy = np.copy(y)
            for obj_preds in preds:
                avg_pred = max(set(obj_preds), key=obj_preds.count) if len(obj_preds) > 0
else None
                oob preds.append(avg pred)
            oob indexes = [i for i , value in enumerate(oob preds) if value is not None]
            self.oob_accuracy = accuracy_metric(y[oob_indexes], np.array(oob_preds)[oob_i
ndexes])
    def get_bootstrap_indexes(self, X, y, *, n_trees, subsample=True):
        len subsample = int(np.sqrt(X.shape[1]))
        for i in range(n trees):
            n obs, n feat = X.shape
            obs indexes = np.random.choice(np.arange(n obs), size=n obs, replace=True)
            feat indexes = np.arange(n feat)
            if subsample:
                feat indexes = np.random.choice(feat indexes, size=len subsample, replace
=True)
       yield obs indexes, feat indexes
    def predict(self, X):
       X = np.array(X)
        y pred = []
        for classes in zip(*[tree.predict(X) for tree in self.forest]):
            y pred.append(max(set(classes), key=classes.count))
       return y pred
```

```
In [7]:
```

```
rf_oob = RandomForestClassifier(n_trees=100, max_depth=3, random_state=123, oob_metric=Tr
ue)
rf_oob.fit(X, y)
rf_oob.oob_accuracy
```

Out[7]:

83.33333333333334

In [8]:

```
from sklearn.model_selection import train_test_split
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size = 0.3, random_state=4
2)
```

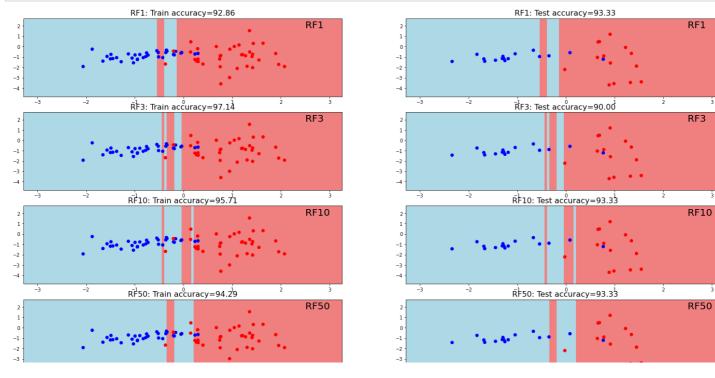
In [9]:

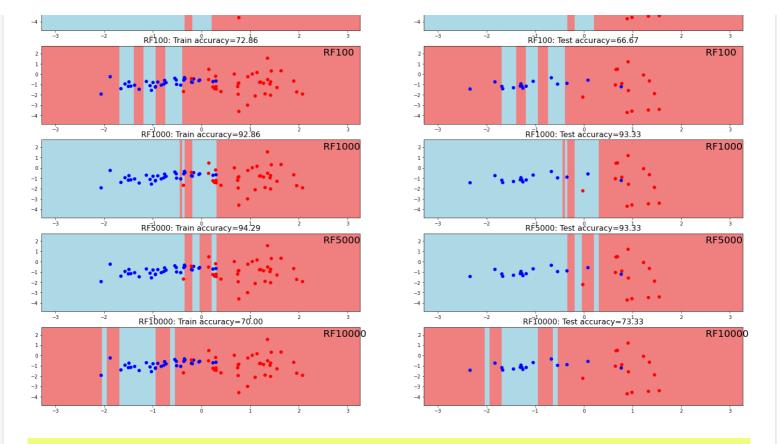
```
# Визуализируем дерево на графике

def get_meshgrid(data, step=.05, border=1.2):
    x_min, x_max = data[:, 0].min() - border, data[:, 0].max() + border
    y_min, y_max = data[:, 1].min() - border, data[:, 1].max() + border
    return np.meshgrid(np.arange(x_min, x_max, step), np.arange(y_min, y_max, step))
```

In [116]:

```
colors = ListedColormap(['red', 'blue'])
light colors = ListedColormap(['lightcoral', 'lightblue'])
tree counts = [1, 3, 10, 50, 100, 1000, 5000, 10000]
accuracy values = {'train': [], 'test': []}
fig, axes = plt.subplots(len(tree counts), 2, figsize = (26, 28))
for i, n trees in enumerate(tree counts):
   rf model = RandomForestClassifier(n trees=n trees, random state=56, max depth=5)
    rf_model.fit(X_train, y_train)
    train preds = rf model.predict(X train)
    test preds = rf model.predict(X test)
    xx, yy = get meshgrid(X train)
   mesh predictions = np.array(rf model.predict(np.c [xx.ravel(), yy.ravel()])).reshape(
xx.shape)
    train_accuracy = accuracy_metric(y_train, train_preds)
    test_accuracy = accuracy_metric(y_test, test_preds)
      график обучающей выборки
   axes[i][0].pcolormesh(xx, yy, mesh predictions, cmap = light colors, shading='auto')
    axes[i][0].scatter(X train[:, 0], X train[:, 1], c = y train, cmap = colors)
   axes[i][0].set title(f'RF{n trees}: Train accuracy={train accuracy:.2f}', fontsize=16
);
   axes[i][0].text(2.5, 1.8, f'RF{n trees}', fontsize = 20)
   accuracy values['train'].append(train accuracy)
    # график тестовой выборки
   axes[i][1].pcolormesh(xx, yy, mesh_predictions, cmap = light_colors, shading='auto')
   axes[i][1].scatter(X test[:, 0], X test[:, 1], c = y test, cmap = colors);
    axes[i][1].set title(f'RF{n trees}: Test accuracy={test accuracy:.2f}', fontsize=16);
    axes[i][1].text(2.5, 1.8, f'RF{n trees}', fontsize = 20);
    accuracy values['test'].append(test accuracy)
plt.show()
```





Самую низкую точность предсказаний получил ансамбль из ста деревьев, к этому добавим явное переобучение. Интересно, что точность на **train** и **test** леса из одного дерева равна точности леса из тысячи деревьев.

In [122]:

```
plt.figure(figsize=(26, 8))

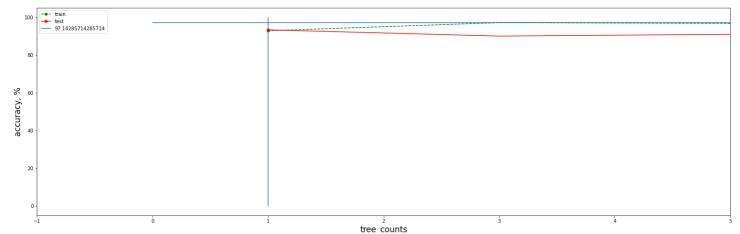
markers_train = max(accuracy_values['train'])
plt.plot(tree_counts, accuracy_values['train'], '--gp', label='train', markevery=markers_
train);

markers_test = max(accuracy_values['test'])
plt.plot(tree_counts, accuracy_values['test'], '-rp', label='test', markevery=markers_test);

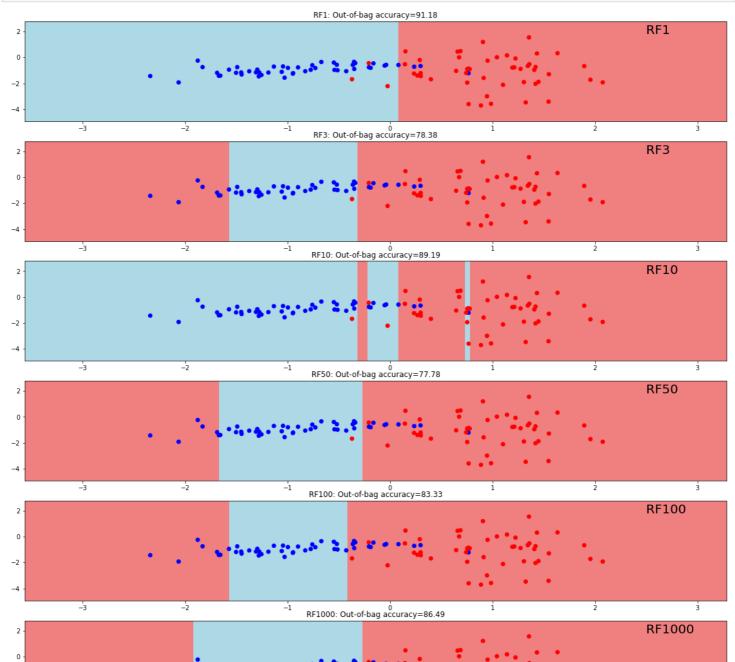
plt.xlabel('tree_counts', fontdict={'fontsize': 17})
plt.ylabel('accuracy, %', fontdict={'fontsize': 17})

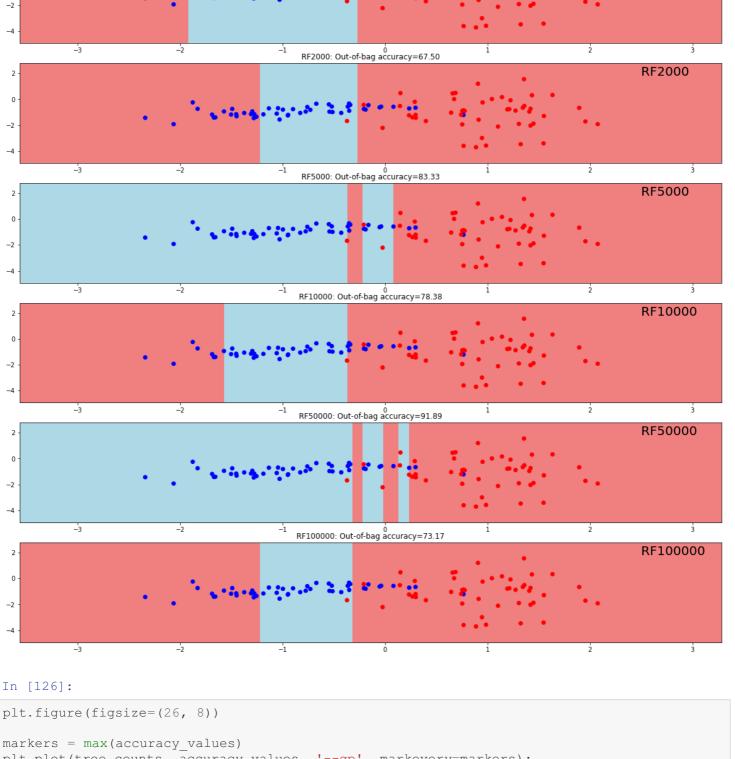
plt.vlines(x=1, ymin=0, ymax=100)
plt.hlines(y=max( max(accuracy_values['train']), max(accuracy_values['test']) ), xmin=0, xmax=max(tree_counts), label=f"{max( max(accuracy_values['train']), max(accuracy_values['test']) }");

plt.xlim(-1, 5)
plt.legend();
```



```
# с использованием out-of-bag error
colors = ListedColormap(['red', 'blue'])
light_colors = ListedColormap(['lightcoral', 'lightblue'])
tree_counts = [1, 3, 10, 50, 100, 1000, 2000, 5000, 10000, 50000, 100000]
accuracy values = []
fig, axes = plt.subplots(len(tree counts), 1, figsize = (20, 38))
for i, n trees in enumerate(tree counts):
    rf oob = RandomForestClassifier(n trees=n trees, max depth=3, random state=123, oob m
etric=True)
   rf oob.fit(X, y)
    preds = rf_oob.predict(X)
    xx, yy = get meshgrid(X)
   mesh predictions = np.array(rf oob.predict(np.c [xx.ravel(), yy.ravel()])).reshape(xx
.shape)
   oob accuracy = rf oob.oob accuracy
      график обучающей выборки
    axes[i].pcolormesh(xx, yy, mesh_predictions, cmap = light_colors, shading='auto')
   axes[i].scatter(X[:, 0], X[:, 1], c = y, cmap = colors)
   axes[i].set_title(f'RF{n_trees}: Out-of-bag accuracy={oob_accuracy:.2f}');
    axes[i].text(2.5, 1.8, f'RF{n_trees}', fontsize = 20)
    accuracy_values.append(oob_accuracy)
plt.show()
```



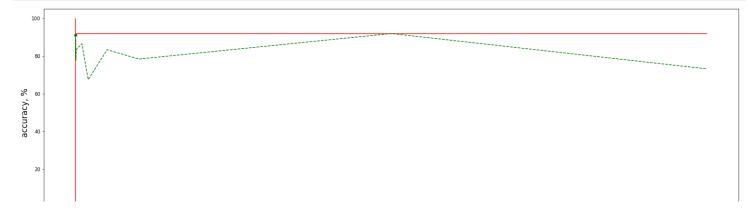


```
plt.figure(figsize=(26, 8))

markers = max(accuracy_values)
plt.plot(tree_counts, accuracy_values, '--gp', markevery=markers);

plt.xlabel('tree_counts', fontdict={'fontsize': 17})
plt.ylabel('accuracy, %', fontdict={'fontsize': 17})

plt.vlines(x=1, ymin=0, ymax=100, color='r')
plt.hlines(y=max(accuracy_values), xmin=0, xmax=max(tree_counts), color='r');
# plt.xlim(-100, 10)
```



Лучший результат в случае оценки методом **out-of-bag error** получился на модели, использующей всего одно дерево, пока в конец списка **trees_counts** не было добавлено большое число **5e4**. Скорее всего строить столько деревьев решений просто неэффективно.

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*эта задача несоизмеримо проста по сравнению с имплементацией out-of-bag-error

```
In []:

def gini(self, y):
    for class_count in Counter(y).values():
        p = class_count / len(y)
    return -(np.sum(p * np.log2(p)))
```