CSE 379 Lab #3 Part 1 Spring 2020

Objective

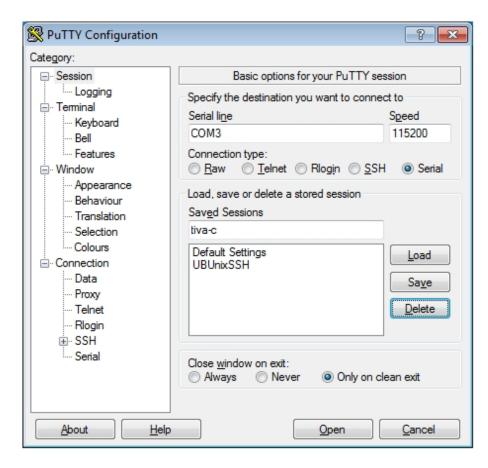
In this lab, you will learn how to communicate with the ARM processor via a serial connection using the UART (universal asynchronous receiver transmitter). In doing so, you will also learn how to write and use assembly language subroutines.

Description

Write two (2) ARM assembly language subroutines, called *output_character* and *read_character*. These subroutines will allow a user to enter a character and display the character in *PuTTy* via the UART. All user input should be echoed back to the display.

PuTTy Setup

Open PuTTy ($Start \rightarrow All\ Programs \rightarrow PuTTy \rightarrow PuTTy$) to communicate with the board. Select Serial as the connection type. To determine which COM port the board is connected to, go to Start, and in the search bar type cmd and press Enter. In the command line, type mode and press Enter. Typically, the highest numbered COM port corresponds to the ARM board. In PuTTy enter COMx as the serial line, where x is the number of the COM port you determined using mode command in the previous step. Set the baud rate to 115,200 in the speed field. Save the session by entering Tiva-c under $Saved\ Sessions$ and then hit Save. Load the session called Tiva-c by selecting Tiva-c from the list and clicking on the Load button. The figures below will help you navigate the setup.



```
Command Prompt
C:∖>mode
                                                                                                                                                Ξ
Status for device COM3:
                                     115207
None
8
       Baud:
       Parity:
Data Bits:
Stop Bits:
        imeout:
                                      OFF
                                     OFF
OFF
OFF
OFF
       XON/XOFF:
      DSR handshaking:
DSR handshaking:
DSR sensitivity:
DTR circuit:
RTS circuit:
Status for device CON:
                                   300
80
31
1
437
       Lines:
      Columns:
Keyboard rate:
Keyboard delay:
Code page:
```

Testing

The following C program can be used to test your code. The program first initializes the UART by calling *serial_init*, and then calls *lab3*, which is the assembly language subroutine that contains your code. This code is available on the *Labs* page of the course website. The routine *lab3* should call *read_character* followed by *output_character* to allow the user to enter a character and then echo that character back to the display.

```
#include <stdint.h>
extern int lab3 (void);
void serial_init(void);
void serial_init(void)
   /* Provide clock to UARTO */
   (*((volatile uint32_t *)(0x400FE618))) = 1;
   /* Enable clock to PortA */
   (*((volatile uint32_t *)(0x400FE608))) = 1;
   /* Disable UARTO Control */
   (*((volatile uint32_t *)(0x4000C030))) = 0;
   /* Set UARTO_IBRD_R for 115,200 baud */
   (*((volatile uint32_t *)(0x4000C024))) = 8;
   /* Set UARTO_FBRD_R for 115,200 baud */
   (*((volatile uint32_t *)(0x4000C028))) = 44;
   /* Use System Clock */
   (*((volatile uint32_t *)(0x4000CFC8))) | = 0;
   /* Use 8-bit word length, 1 stop bit, no parity */
   (*((volatile uint32_t *)(0x4000C02C))) = 0x60;
   /* Enable UARTO Control */
   (*((volatile uint32_t *)(0x4000C030))) = 0x301;
   /* Make PAO and PA1 as Digital Ports */
   (*((volatile uint32_t *)(0x4000451C))) = 0x03;
   /* Change PAO, PA1 to Use an Alternate Function */
   (*((volatile uint32_t *)(0x40004420))) = 0x03;
   /* Configure PAO and PA1 for UART */
   (*((volatile uint32_t *)(0x4000452C))) = 0x11;
}
int main()
  serial_init();
  lab3();
```

Skeleton Code

The following ARM assembly language skeleton code can be used to get you started. It is available online on the *Labs* page of the course website.

```
.text
.global lab3

U0LSR: .equ 0x18  ; UARTO Line Status Register

lab3:
   STMFD SP!,{lr}; Store register lr on stack

; Your code is placed here

   LDMFD sp!, {lr}
   mov pc, lr
   .end
```

Partners

You will work with a partner in this lab. Your partner MUST be the partner you signed up to work with online. One partner is responsible for writing output_character and the other is responsible for writing read_character. They must be done individually! It is recommended that you test output_character first, and then use output_character to echo the character back when testing read_character. When testing, both partners should be present and participate in the debugging process.

Demonstrations & Submissions

You MUST demonstrate to your TA that your *output_character* and *read_character* routines work properly before starting the second part of this lab. The due date for getting *output_character* and *read_character* working is the end of your lab session on February 17 or 18 (depending upon which day you have lab).