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#include <stdio.h>
#include <iostream>
#include <stddef.h>
#include <string>
#include <cstdlib>
#include <cstdarg>
#include <cmath>
#include <fstream>
#include <vector>
#include <cstdio>
#include <fstream>
#include <stdlib.h>
#include <sstream>

using std::cout;
using std::endl;
using std::ios;

// Function
prototypes=====
=====
double Evaluate_dUdy_Plus(double lmix_plus, double y_pl, double R_pl);

std::vector <double> getUplus(double R_pl, int filewrite);

std::vector <double> evalFunc(double R_plus_est, int filewrite);

//=====

// Main function
int main(){

    double U_ave=0.0;
    double tol = 1e-3; double toler = 1e-5;
    double Re_D = 40000;
    double R_plus_est = 0;
    double c = 0;
    double a= 1;
    double b = 10000;
    double root = 0;
    double ymax, Fmax, Udif;
    std::vector <double> f_a(4);
    std::vector <double> f_b(4);
    std::vector <double> f_c(4);
    std::vector <double> f_fin(4);
    double check_a, check_b, check_c;
    int iter=0;
    double Re_D_est;
    f_a = evalFunc(a, 0);
    f_b = evalFunc(b, 0);

    check_a = (2*f_a[3]*a - Re_D);
    check_b = (2*f_b[3]*b - Re_D);

    /* Check that that neither end-point is a root and if f(a) and f(b) have the same sign, throw an
exception. */
    if ( check_a == 0 ){
        root = a;
        std::cout<<"root is "<<root<<endl;
    } else if ( check_b == 0 ){
        root = b;
        std::cout<<"root is "<<root<<endl;
    } else if ( check_a * check_b > 0 ){
        std::cout<<"f(a) and f(b) do not have opposite signs"<<endl;
    }

    // Begin the iterations-----

    while ( fabs(Re_D_est - Re_D) > tol ){

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//   for (int i = 0; i<10; i++){
c = 0.5*(a + b);
R_plus_est = c;

f_a = evalFunc(a, 0);
f_b = evalFunc(b, 0);
f_c = evalFunc(c, 0);

check_a = (2*f_a[3]*a - Re_D);
check_b = (2*f_b[3]*b - Re_D);
check_c = (2*f_c[3]*c - Re_D);
U_ave = f_c[3];

std::cout<<" a is = "<<a<<endl;
std::cout<<" b is = "<<b<<endl;
std::cout<<" c is = "<<c<<endl;
std::cout<<" f(a) is = "<<check_a<<endl;
std::cout<<" f(b) is = "<<check_b<<endl;
std::cout<<" f(c) is = "<<check_c<<endl;
std::cout<<" -----U_ave is: "<<U_ave<<endl;
/* Check if we found a root or whether or not we should continue with:
* [a, c] if f(a) and f(c) have opposite signs, or
* [c, b] if f(c) and f(b) have opposite signs. */

if (check_c == 0){
    // break;
} else if (check_a * check_c < 0){
    b = c;
} else{
    a = c;
}

if ( b - a < tol ){
    if ( fabs(check_a) < fabs(check_b) && fabs(check_a) < tol ){
        root = a;
        std::cout<<"root is "<<root<<endl;
    }
    else if ( fabs(check_b) < tol ){
        root = b;
        std::cout<<"root is "<<root<<endl;
    }
}

// Break the iterations if convergence tolerance has been met
if (check_a < toler && check_b < toler && check_c < toler){
    break;
}

iter = iter + 1;

Re_D_est = 2*U_ave*c;
}
std::cout<<" Final results Re_D = "<<2*U_ave*R_plus_est<<endl;
std::cout<<" Final results R+ = "<<R_plus_est<<endl;
std::cout<<"Number of iterations = "<<iter<<endl;
f_fin = evalFunc(R_plus_est, 1);

ymax = f_c[0];
Fmax = f_c[1];
Udif = f_c[2];
U_ave = f_c[3];

std::cout<<" ymax = "<<ymax<<" Fmax = "<<Fmax<<" Udif = "<<Udif<<" U_ave = "<<U_ave<<endl;
return 0;
}

std::vector <double> evalFunc(double R_plus_est, int filewrite){

    std::vector <double> ResultsValue(4);
    //evaluate function!

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ResultsValue = getUplus(R_plus_est, filewrite);

double ymax = ResultsValue[0];
double Fmax = ResultsValue[1];
double Udif = ResultsValue[2];
double U_ave = ResultsValue[3];

return ResultsValue;
}

double Evaluate_dUdy_Plus(double lmix_plus, double y_pl, double R_pl){

double dU_dy = 0.0;
double lmix_plus_fourth = lmix_plus*lmix_plus*lmix_plus*lmix_plus;
double y_over_R = (1 - y_pl/R_pl);

if (y_pl <= 1){
    dU_dy = y_over_R - (y_over_R*y_over_R)*(lmix_plus*lmix_plus) +
    2*(y_over_R*y_over_R*y_over_R)*(lmix_plus_fourth);
}
else if (y_pl > 1){
    dU_dy = ( std::sqrt((4*lmix_plus*lmix_plus*y_over_R) + 1) - 1) / (2*lmix_plus*lmix_plus);
}
return dU_dy;
}

std::vector <double> getUplus(double R_pl, int filewrite){

double dU_dy0, dU_dy1, dU_dy2, dU_dy3, dU_dy;
std::vector <double> U_pl_profile;
std::vector <double> Y_pl_profile;
std::vector <double> ymax_profile;
std::vector <double> Reynolds;
std::vector <double> ReturnVals(4);

double summ = 0.0;
int counter = 0;
double A0_pl = 26.0;
double K = 0.41;
double lmix_pl=0, lmix_pl1=0, lmix_pl2=0;
double y_pl = 0;
double delta_y_pl=0, U_ave = 0;
double ymax=0, Fmax=0, Udif=0;

double a = 2e-1, b = 2e-1;

double U_n1 = 0, U_n2 = 0;

while (y_pl <= R_pl){

    lmix_pl1 = K*y_pl*(1 - exp(-y_pl/A0_pl) );
    lmix_pl2 = 0.09*R_pl;

    if (lmix_pl1 <= lmix_pl2){
        lmix_pl = lmix_pl1;
        delta_y_pl = a;
    }
    else if (lmix_pl1 > lmix_pl2){
        lmix_pl = lmix_pl2;
        delta_y_pl = b;
    }

    /* ===== RK4 Scheme ===== */
    dU_dy0 = Evaluate_dUdy_Plus(lmix_pl, y_pl, R_pl);
    dU_dy1 = Evaluate_dUdy_Plus(lmix_pl + 0.5*delta_y_pl*dU_dy0, y_pl + 0.5*delta_y_pl, R_pl);
    dU_dy2 = Evaluate_dUdy_Plus(lmix_pl + 0.5*delta_y_pl*dU_dy1, y_pl + 0.5*delta_y_pl, R_pl);
    dU_dy3 = Evaluate_dUdy_Plus(lmix_pl + 0.5*delta_y_pl*dU_dy2, y_pl + delta_y_pl, R_pl);
}

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    if (y_pl > 0){
        U_n2 = U_n1 + (delta_y_pl/6)*(dU_dy0 + 2*dU_dy1 + 2*dU_dy2 + dU_dy3);
    }

    // update vectors to store these values
    U_pl_profile.push_back(U_n2);
    Y_pl_profile.push_back(y_pl);
    ymax_profile.push_back(dU_dy0 * lmix_pl);

    dU_dy = Evaluate_dUdy_Plus(lmix_pl, y_pl, R_pl);
    Reynolds.push_back(lmix_pl*lmix_pl * dU_dy*dU_dy);
    summ = summ + U_n2 * (1 - y_pl/R_pl) * delta_y_pl;
    y_pl = y_pl + delta_y_pl;
    if (fabs(y_pl - R_pl) < 1){
        break;
    }

    counter = counter + 1;

    U_n1 = U_n2;
}
//===== known and complete
=====
U_ave = (2/R_pl) * summ;

double val_max = 0, Rmax = 0;
// now evaluate the new max values: these can only be evaluated once we know the entire velocity
// profile, hence why we initialize at start
for (int i=0; i< counter; i++){
    double ypl = Y_pl_profile[i];
    if (ymax_profile[i] > val_max){
        val_max = ymax_profile[i];
        if (ypl <= 1){
            delta_y_pl = a;
        }
        if (ypl > 1){
            delta_y_pl = b;
        }
        ymax = i * delta_y_pl;
        Fmax = (1/K)*val_max;
    }
    if (Reynolds[i] > Rmax){
        Rmax = Reynolds[i];
    }
}

Udif = U_pl_profile[counter-1]; // - U_pl_profile[counter * ymax/R_pl];

ReturnVals[0] = ymax;
ReturnVals[1] = Fmax;
ReturnVals[2] = Udif;
ReturnVals[3] = U_ave;

// //===== now write results to file
// (Tecplot!)=====

double num_elem = Reynolds.size();

if (fwrite == 1){
    std::stringstream stream1, stream3, stream4, stream5, stream6, stream7;
    stream1 << "U_plus_two-layer_mixing_model.dat";
    stream3 << "i="<<num_elem + 1;
    stream4<<"title = "<<" "<<stream1.str()<<" ";
    std::string var1 = stream3.str();
    std::string var2 = stream4.str();
    std::string fileName1 = stream1.str();

    FILE* fout = fopen(fileName1.c_str(), "w");

    fprintf(fout, "%s", var2.c_str() ); fprintf(fout, "\n");
}

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fprintf(fout, "%s", "variables = 'U+/U+max' 'y+/R+' 'y+' 'U+' 'normalized_Reynolds_Shear_Stress' ");
fprintf(fout, "\n"); // 'Reynolds Shear Stress'
fprintf(fout, "%s %s %s", "zone", var1.c_str(), "f=point"); fprintf(fout, "\n"); //

summ = 0;
for (int j = 0; j <= num_elem; j++){
    fprintf(fout, "%e\t %e\t %e\t %e\t %e\t", U_pl_profile[j]/U_pl_profile[num_elem], Y_pl_profile[j]/
    Y_pl_profile[num_elem], Y_pl_profile[j], U_pl_profile[j], Reynolds[j]/Rmax);
    fprintf(fout, "\n");
}
fclose(fout);
std::cout<<" "<<endl; std::cout<<"U_plus results file successfully written"<<endl;

//=====

stream5 << "Laufer Experimental Data.dat";
stream6 <<"i="<<11;
stream7<<"title = "<<" "<<stream5.str()<<" ";
var1 = stream6.str();
var2 = stream7.str();
std::string fileName2 = stream5.str();
fout = fopen(fileName2.c_str(), "w");
fprintf(fout, "%s", var2.c_str() ); fprintf(fout, "\n");
fprintf(fout, "%s", "variables = 'U+/U+max' 'y+/R+' "); fprintf(fout, "\n");
fprintf(fout, "%s %s %s", "zone", var1.c_str(), "f=point"); fprintf(fout, "\n"); //
fprintf(fout, "%e\t %e\t ", 0.333, 0.010); fprintf(fout, "\n");
fprintf(fout, "%e\t %e\t ", 0.696, 0.095); fprintf(fout, "\n");
fprintf(fout, "%e\t %e\t ", 0.789, 0.210); fprintf(fout, "\n");
fprintf(fout, "%e\t %e\t ", 0.833, 0.280); fprintf(fout, "\n");
fprintf(fout, "%e\t %e\t ", 0.868, 0.390); fprintf(fout, "\n");
fprintf(fout, "%e\t %e\t ", 0.902, 0.490); fprintf(fout, "\n");
fprintf(fout, "%e\t %e\t ", 0.931, 0.590); fprintf(fout, "\n");
fprintf(fout, "%e\t %e\t ", 0.961, 0.690); fprintf(fout, "\n");
fprintf(fout, "%e\t %e\t ", 0.975, 0.800); fprintf(fout, "\n");
fprintf(fout, "%e\t %e\t ", 0.999, 0.900); fprintf(fout, "\n");
fprintf(fout, "%e\t %e\t ", 1.000, 1.000); fprintf(fout, "\n");
fclose(fout);
std::cout<<"Laufer results successfully written"<<endl;
}

return ReturnVals;

}

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