```
/st Check that that neither end-point is a root and if f(a) and f(b) have the same sign, throw an
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               double Evaluate_dUdy_Plus(double lmix_plus, double y_pl, double R_pl);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        std::vector <double> evalFunc(double R_plus_est, int filewrite);
(Selection of) num2.cpp
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            std::vector <double> getUplus(double R_pl, int filewrite);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              double U_ave=0.0;
double U_ave=0.0;
double Rol = 1e-3;
double Re D = 40000;
double R_Dlus_est = 0;
double a= 1;
double b = 10000;
double b = 10000;
double ymax, Fmax, Udif;
std::vector <double F ad 4);
std::vector <double F (c/4);
std::vector <doub
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          std::cout<<"root is "<croot<endl;
else if ( check_b == 0 ){
root = b;</pre>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              check_a = (2*f_a[3]*a - Re_D);
check_b = (2*f_b[3]*b - Re_D);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     double Re_D_est;
f_a = evalFunc(a, 0);
f_b = evalFunc(b, 0);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       exception. */
if (check_a == 0){
                                                                      #include cstdio.h>
#include ciostream>
#include cstring>
#include cstring>
#include cstdiib>
#include ccstdiib>
#include ccstdiarg>
#include cstdiarg>
#include cstcor>
#include cstdio>
#include cstdio>
#include cstdio>
#include cstdio>
#include cstdio>
#include cstdib.h>
#include cstdib.h>
#include cstdib.h>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       using std::cout;
using std::endl;
using std::ios;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 // Main function
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         // Function
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           int main(){
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         prototypes
2015-03-18
```

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(Selection of) /home/chris/Desktop/TurbHwork/num2/num2.cpp
```

std::cout<<"round"root is "<rroot</pre>celse if (check a * check b > 0){
std::cout<<"f(a) and f(b) do not have opposite signs"<<endl;

while (fabs(Re_D_est - Re_D) > tol){

// Begin the iterations--

```
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 std::cout<<" ymax = "<<ymax<<" Fmax = "<<fmax<<" Udif = "<<Udif<</rr>

return 0;

                                                                                                                                                                                                                                                                                                                                                                                     std::cout<< a is = "ccaccend1;
std::cout<< bis = "ccaccend1;
std::cout<< c is = "ccceend1;
std::cout<< f(a) is = "ccheck acend1;
std::cout<< f(b) is = "ccheck bccend1;
std::cout<< f(c) is = "ccheck bccend1;
std::cout</ f(c) is = "ccheck bccend1;
std::cout</pre>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    if ( b - a < tol ){
   if ( fabs(check_a) < fabs(check_b) && fabs(check_a) < tol ){</pre>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                // Break the iterations if convergence tolerance has been met
if (check_a < toler && check_b < toler && check_c < toler){
    break;</pre>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     std::cout<=" Final results Re_D = "<<2*U_ave*R_plus_est<=ndl;
std::cout<= Final results R+ = "<K plus_est<=ndl;
std::cout<="Winder of iterations = "<iter<=endl;
f_fin = evalFunc(R_plus_est, 1);</pre>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             std::vector <double> evalFunc(double R_plus_est, int filewrite){
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              std::cout<<"root is "<<root/
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               std::cout<<"root is "<<root</br>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    std::vector <double> ResultsValue(4);
//evaluate function!
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      } else if (check_a * check_c < 0){
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     else if ( fabs(check_b) < tol ){</pre>
// for (int i = 0; i<10; i++){ c = 0.5*(a + b); R_plus_est = c;
                                                                                                                                                                                                                                         check_a = (2*f_a[3]*a - Re_D);

check_b = (2*f_b[3]*b - Re_D);

check_c = (2*f_c[3]*c - Re_D);

U_ave = f_c[3];
                                                                                                                        f_a = evalFunc(a, 0);
f_b = evalFunc(b, 0);
f_c = evalFunc(c, 0);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              Re_D_est = 2*U_ave*c;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               if (check_c == 0){
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       iter = iter + 1;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        ymax = f_c[0];
Fmax = f_c[1];
Udif = f_c[2];
U_ave = f_c[3];
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      root = a;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       root = b;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        b = c;
else{
```

(Selection of) num2.cpp

```
Results/value = getUplus(R_plus_est, filewrite);

double ymax = Results/value[0];

double ymax = Results/value[1];

double udar = Results/value[1];

double U_ave = Results/value[1];

double U_ave = Results/value[1];

double U_ave = Results/value[2];

return Results/value;

}

double Evaluate_dudy_Plus(double lmix_plus, double y_pl, double R_pl){

double Evaluate_dudy_Plus(double lmix_plus*lmix_plus*lmix_plus*lmix_plus;

double du_av = 0.0;

if (y_pl < = 1){

du_dy = y_over_R + (y_over_R*y_over_R)*(lmix_plus*lmix_plus;

alv_dy = y_over_R + (y_over_R*y_over_R)*(lmix_plus*lmix_plus) +

alv_dy = v_over_R*y_over_R*y_over_R)*(lmix_plus*v_over_R) + 1) /(2*lmix_plus*lmix_plus);

also = (std::sqrt((4*lmix_plus*lmix_plus*y_over_R) + 1) /(2*lmix_plus);

return du_dy;

}
```

```
std::vector <double> getUplus(double R.pl., int filewrite){
double dU_dy0, dU_dy1, dU_dy2, dU_dy3, dU_dy3
```

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fprintf(fout, "%s", var2.c_str()); fprintf(fout, "\n");

FILE* fout = fopen(fileName1.c_str(), "w");

```
std::stringstream stream1, stream3, stream6, stream7;
stream1 <= "Up plus two-layer mixing_model.dat";
stream3 <= ""="<tream4" = "crum elem + 1;
stream4 <= "title = "<= ""<<stream4.rtile = "<= ""<<stream4.rtile = "<= "stream4.str();
std::string var2 = stream4.str();
std::string var2 = stream4.str();
std::string fileName1 = stream1.str();</pre>
                              Udif = U_pl_profile[counter-1]; // - U_pl_profile[counter * ymax/R_pl];
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      known and complete
(Selection of) num2.cpp
                                                                                                                                                                                                                        dU_dy = Evaluate_dddy_Plus(lmix_pl, y_pl, R_pl);
Reynolds_push, back(lmix_pl*mix_pl * dd dy*dd dy);
summ = summ + U n2 * (1 - y_pl/R_pl) * delta_ypl;
y_pl = y_pl + delta_ypl;
fr (fabs(y_pl - R_pl) < 1){
break;</pre>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    ===== now write results to file
                                                                                                                  // update vectors to store these values
Up_Lprofile.push back(U n2);
Y pl_profile.push_back(y pl);
ymax_profile.push_back(du_dy0 * lmix_pl);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         double num_elem = Reynolds.size();
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              ymax = i * delta_y_pl;
Fmax = (1/K)*val_max;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            }
if (Reynolds[i] > Rmax){
| Rmax = Reynolds[i];
                                                                                                                                                                                                                                                                                                                                                                                                           counter = counter + 1;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               U_ave = (2/R_pl) * summ;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     delta_y_pl = b;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      ReturnVals[0] = ymax;
ReturnVals[1] = Fmax;
ReturnVals[2] = Udif;
ReturnVals[3] = U_ave;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  if (filewrite == 1){
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              if (ypl > 1){
                                                                                                                                                                                                                                                                                                                                                                                                                                                      U_n1 = U_n2;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             (Tecplot!)=
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```

return ReturnVals;

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