## I2-TD4 (Linear Transformations)

- 1. Determine if the following mappings are linear transformations.
  - (a)  $L: \mathbb{R}^2 \to \mathbb{R}^2, L(x_1, x_2) = (x_1 2x_2, 3 + x_1 + 3x_2)$
  - (b)  $L: \mathbb{R}^3 \to \mathbb{R}^2, L(x_1, x_2, x_3) = (x_1 + 2x_2 + x_3, x_1 x_2)$
  - (c)  $L: \mathbb{R}^2 \to \mathbb{R}^2, L(x_1, x_2) = (x_1 + 2x_2, x_1x_2)$
  - (d) Let  $A \in \mathbb{R}^{n \times n}$  and  $L : \mathbb{R}^n \to \mathbb{R}^n$ , L(x) = Ax
  - (e)  $\varphi: \mathcal{C}^2(\mathbb{R}) \to \mathcal{C}^0(\mathbb{R}), \varphi(f) = 2tf''(t) + \cos tf'(t) (t^2 1)f(t).$
  - (f)  $\varphi: \mathcal{C}^0(\mathbb{R}) \to \mathbb{R}, \ \varphi(f) = \int_0^1 (f(x) + 3f'(x)) dx$
- 2. Let  $L \in \mathcal{L}(V, W)$ . Show that
  - (a) if  $v_1, v_2, \ldots, v_n$  span a vector space V, then  $L(v_1), L(v_2), \ldots, L(v_n)$  span Im(L).
  - (b) if  $L(v_1), L(v_2), \ldots, L(v_n)$  are linearly independent, then  $v_1, v_2, \ldots, v_n$  linearly independent.
- 3. Let  $L \in \mathcal{L}(V, W)$ . Show that
  - (a) Ker(L) is a subspace of V.
  - (b) Im(L) is a subspace of W.
  - (c) if dim  $V < \infty$ , then null $(L) + \operatorname{rank}(L) = \dim V$ .
- 4. Let  $L \in \mathcal{L}(V, W)$ .
  - (a) Show that L is one-to-one if and only if  $Ker(L) = \{0\}$ .
  - (b) Show that L is onto if and only if Im(L) = W.
  - (c) Suppose dim  $V = \dim W < \infty$ . Show that L is one-to-one if and only if it is onto.
- 5. Let U, V and W be vector spaces over the same field. Let f be a linear transformation from U to V and g be a linear transformation from V to W. Show that
  - (a)  $g \circ f$  is also a linear transforation.
  - (b)  $\operatorname{rank}(g \circ f) \leq \min\{\operatorname{rank}(f); \operatorname{rank}(g)\}$
  - (c) if f is surjective then  $rank(g \circ f) = rank(g)$
  - (d) if g is injective then  $rank(g \circ f) = rank(f)$
- 6. Let  $f: \mathbb{R}^3 \to \mathbb{R}^3$ , f(x,y,z) = (z,x-y,y+z). Show that f is an automorphism.
- 7. Let  $L: \mathbb{R}^4 \to \mathbb{R}^3$  be a linear transformation defined by

$$L \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 0 & -1 \\ 2 & 1 & 0 & -1 \\ 1 & 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix}.$$

(a) Find the kernel of L and one of its bases. Is L one-to-one?

- (b) Find the range of L and one of its bases. Is L onto?
- 8. Let  $L: \mathbb{R}^2 \to \mathbb{R}^3$  be a linear transformation defined by

$$L\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}.$$

- (a) Find the kernel of L and one of its bases. Is L one-to-one?
- (b) Find the range of L and one of its bases. Is L onto?
- 9. Let  $L: \mathbb{R}^3 \to \mathbb{R}^3$  be a linear transformation defined by

$$L\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 2 & 0 & -1 \\ 1 & 1 & 0 \\ 2 & -1 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}.$$

- (a) Find the kernel of L and one of its bases. Is L one-to-one?
- (b) Find the range of L and one of its bases. Is L onto?
- 10. Let T be the mapping from  $\mathbb{R}^4$  into  $\mathbb{R}_3[X]$  defined by, for  $x=(x_1,x_2,x_3,x_4)\in\mathbb{R}^4$ ,

$$T(x) = x_1 + 2x_2 + x_3 + (x_2 - x_4)t + (x_1 - 3x_3)t^2 + (x_1 + x_2 + x_3 - x_4)t^3.$$

- (a) Determine a basis and the dimension of Ker(T) and Im(T).
- (b) Is T an isomorphism from  $\mathbb{R}^4$  into  $\mathbb{R}_3[X]$ ?
- 11. Let  $T: \mathcal{C}^2(\mathbb{R}) \to \mathcal{C}^2(\mathbb{R})$ ; T(f) = 2f'' 5f' + 3f. Show that T is an endomorphism and determine its kernel.
- 12. Let  $n \geq 2$  and  $f: \mathbb{R}_n[X] \to \mathbb{R}_2[X]$  defined by

$$f(P) = x^2 P(0) + (x - 2)P(1)$$

- (a) Show that f is linear.
- (b) Find the kernel and image of f.
- 13. Let  $\varphi : \mathbb{R}_n[X] \to \mathbb{R}_n[X]$  defined by

$$\varphi(P) = P(x+1) - P(x)$$

- (a) Show that  $\varphi$  is an endomorphism.
- (b) Find the kernel and image of  $\varphi$ .
- 14. Let f be an endomorphism on vector space V satisfies  $f^2 5f + 6 \text{Id} = 0$ . Show that  $V = \text{Ker}(f 2 \text{Id}) \oplus \text{Ker}(f 3 \text{Id})$ . (Note:  $f^2 = f \circ f$ )
- 15. Show that there is a unique linear transformation f such that f(1,2) = 2 and f(-2,1) = 5. Find the nullity and image of f.
- 16. Let  $L \in \mathcal{L}(\mathbb{R}^3)$  verifies

$$L\begin{pmatrix} 1\\-1\\0\end{pmatrix} = \begin{pmatrix} 0\\1\\2\end{pmatrix}, \quad L\begin{pmatrix} 1\\1\\1\end{pmatrix} = \begin{pmatrix} 1\\1\\0\end{pmatrix}, \quad L\begin{pmatrix} 0\\0\\1\end{pmatrix} = \begin{pmatrix} 0\\1\\1\end{pmatrix}$$

- (a) Find the image of  $e_1 = (1,0,0)$  under the linear transformation L.
- (b) Find the linear transformation L.
- 17. Consider  $L \in \mathcal{L}(\mathbb{R}^3), L(x, y, z) = (x + y + z; x y, 2z)$ . Let

$$B_1 = \{(1,1,1); (1,1,0), (1,0,0)\}$$
 and  $B_2 = \{(-1,0,1); (0,1,0), (1,2,3)\}$ 

- (a) Find the matrix representation L relative to the standard basis.
- (b) Find the transition matrix from  $B_2$  to  $B_1$ , denoted by S.
- (c) Find the matrix representation L relative to bases  $B_1$  and  $B_2$ .
- (d) Verify that  $[L]_{B_1}[v]_{B_1} = [L(v)]_{B_1}$  for any vector  $v \in \mathbb{R}^3$ .
- (e) Verify that  $[L]_{B_2} = S^{-1}[L]_{B_1}S$ .
- 18. Let T be a linear transformation from  $\mathbb{R}^4$  into  $\mathbb{R}^3$  defined by, for  $x=(x_1,x_2,x_3,x_4)$ ,

$$T(x) = (x_1 + x_2 + x_3 + x_4, 2x_1 + 3x_2 - x_3 + 3x_4, x_1 + 2x_2 - 2x_3 + 2x_4).$$

- (a) Let  $B_1$  and  $B_2$  be the standard basis for  $\mathbb{R}^4$  and  $\mathbb{R}^3$ , respectively. Find the matrix representation of T with respect to the bases  $B_1$  and  $B_2$ .
- (b) Let  $B_3 = \{(1,1,1,1), (1,2,1,3), (1,1,1,2), (1,3,2,2)\}$  be a subset of  $\mathbb{R}^4$  and  $B_4 = \{(1,1,2), (0,1,2), (1,1,3)\}$  be a subset of  $\mathbb{R}^3$ . Show that  $B_3$  is a basis for  $\mathbb{R}^4$  and  $B_4$  is a basis for  $\mathbb{R}^3$ . Find the matrix representation of T with respect to the bases  $B_3$  and  $B_4$ .
- (c) Verify that for any  $v \in \mathbb{R}^4$ , we have  $[T]_{B_3}^{B_4}[v]_{B_4} = [T(v)]_{B_3}$ .
- 19. The set  $S = \{e^{2t}, te^{2t}, t^2e^{2t}\}$  is a basis of a vector space V of functions  $f : \mathbb{R} \to \mathbb{R}$ . Let D be the differential operator on V; that is D(f) = df/dt. Find the matrix representation of D relative to the basis S.
- 20. Let  $L: \mathcal{M}_2(\mathbb{R}) \to \mathbb{R}_1[X], \ L\begin{pmatrix} a & b \\ c & d \end{pmatrix} = (a+d)x + b + c.$ 
  - (a) Show that L is a linear transformation.
  - (b) Determine the matrix represents L in the canonical bases of  $\mathcal{M}_2(\mathbb{R})$  and  $\mathbb{R}_1[X]$ .
  - (c) Find Ker(L) and Im(L).
- 21. Let  $f: \mathbb{R}_n[X] \to \mathbb{R}_n[X]$ ; f(P) = xP' P.
  - (a) Show that  $f \in \mathcal{L}(\mathbb{R}_n[X])$
  - (b) Determine the matrix represents f in the canonical bases of  $\mathbb{R}_n[X]$ .
  - (c) Find Ker(f) and Im(f).
- 22. Let  $T: \mathbb{R}_3[X] \to \mathbb{R}_3[X]$  defined by T(f) = xf'' 2xf' + f. Show that T is a linear transformation and then find the matrix represents T with respect to the standard basis of  $\mathbb{R}_3[X]$ .
- 23. Let  $f: \mathbb{R}_n[X] \to \mathbb{R}_{n+1}[X]; f(P) = e^{x^2} \left(Pe^{-x^2}\right)'$ .
  - (a) Show that  $f \in \mathcal{L}(\mathbb{R}_n[X], \mathbb{R}_{n+1}[X])$
  - (b) Determine the matrix represents f in the canonical bases of  $\mathbb{R}_n[X]$  and  $\mathbb{R}_{n+1}[X]$ .
  - (c) Find Ker(f) and Im(f).