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Example 5.3

`% SMD.m: Plots displacement of under damped spring-mass-damper system`

`% Inputs:`

`y0 = 3.0; % initial displacement, inches`

`dr = 0.10; % damping ratio`

`fr = 2*pi; % natural frequency, radians/second`

`T = 5.0; % total time to be plotted, seconds`

`N = 100; % number of time intervals to be plotted`

`% Calculate damped frequency, radians/second`

`fd = fr*sqrt(1-dr^2);`

`% Calculate time interval for displacement calculations`

`tinc = T/N;`

`for i = 1:N+1`

`t(i) = (i-1)*tinc;`

`c = cos(fd*t(i));`

`s = sin(fd*t(i));`

`e = exp(-dr*fr*t(i));`

`y(i) = (y0*c + y0*dr*fr/fd*s)*e;`

`end`

`figure`

`plot(t,y,'LineWidth',3,'Color','Red')`

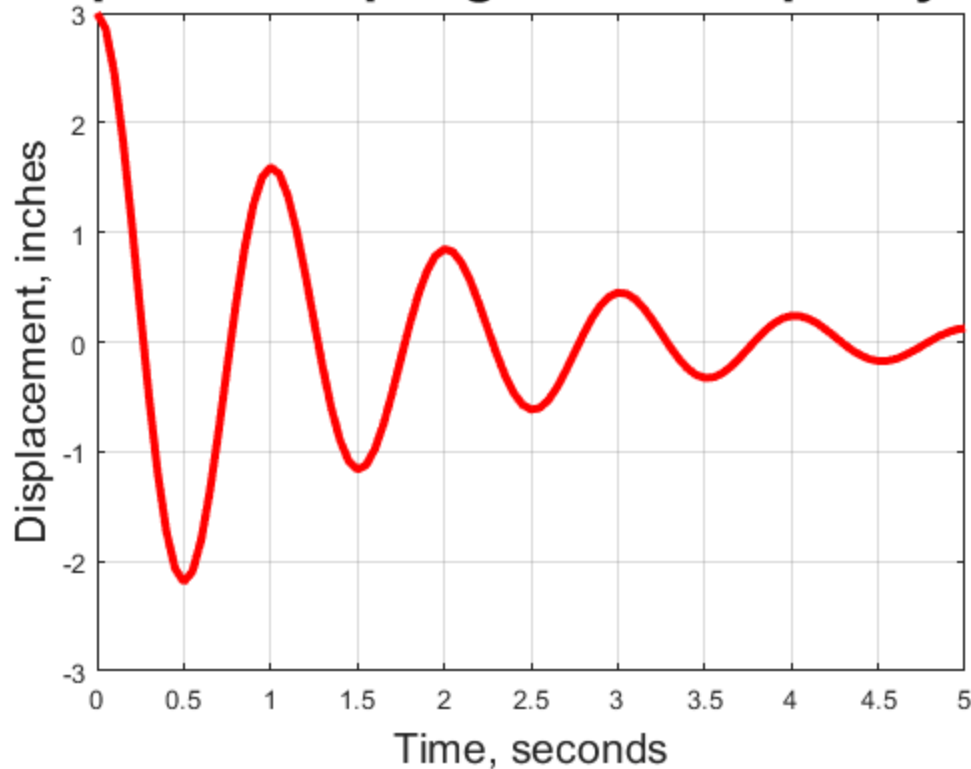
`grid on`

`title('Response of Spring-Mass-Damper System','FontSize',20)`

`xlabel('Time, seconds','FontSize',16)`

`ylabel('Displacement, inches','FontSize',16)`

Response of Spring-Mass-Damper System



Example 5.4

```
% SMD.m: Plots displacement of under damped spring-mass-damper system
```

```
% Inputs:
```

```
y0 = 3.0; % initial displacement, inches
```

```
dr = 0.10; % damping ratio
```

```
fr = 2*pi; % natural frequency, radians/second
```

```
T = 5.0; % total time to be plotted, seconds
```

```
N = 100; % number of time intervals to be plotted
```

```
% Calculate damped frequency, radians/second
```

```
fd = fr*sqrt(1-dr^2);
```

```
% Calculate time interval for displacement calculations
```

```
tinc = T/N;
```

```
for i = 1:N+1
```

```
    t(i) = (i-1)*tinc;
```

```
    c = cos(fd*t(i));
```

```
    s = sin(fd*t(i));
```

```
    e = exp(-dr*fr*t(i));
```

```
    y(i) = (y0*c + y0*dr*fr/fd*s)*e;
```

```
end
```

```
figure
```

```
plot(t,y,'LineWidth',3,'Color','Red')
grid on
title('Response of Spring-Mass-Damper System','FontSize',20)
xlabel('Time, seconds','FontSize',16)
ylabel('Displacement, inches','FontSize',16)

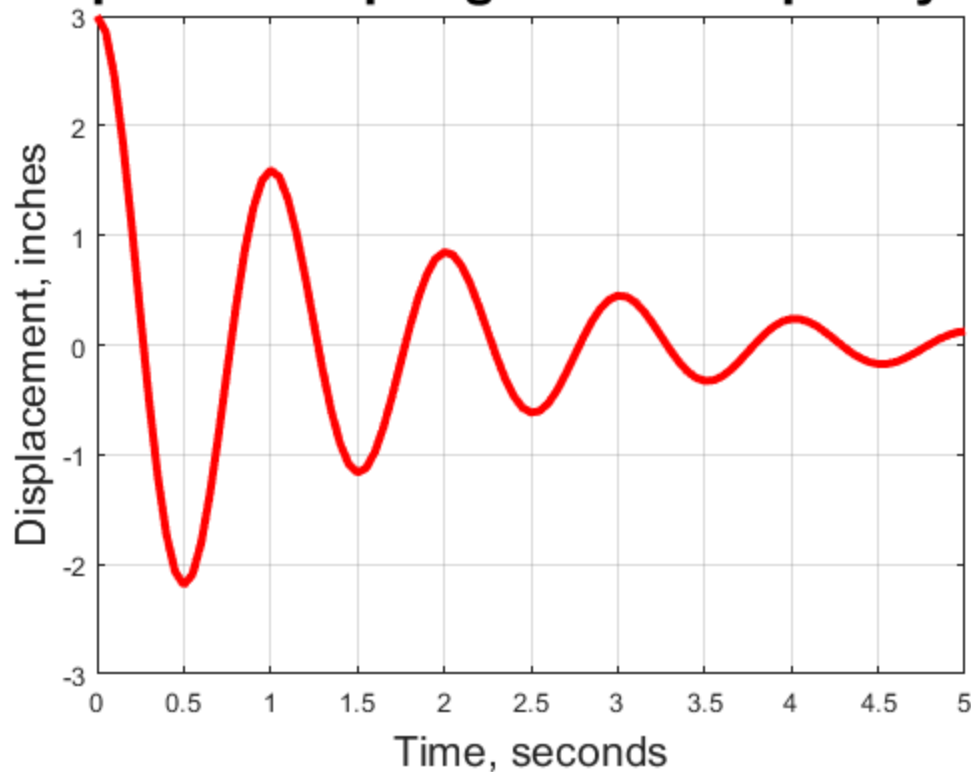
% Compute and plot displacements for a different damping ratio

dr2 = 0.20; % new damping ratio

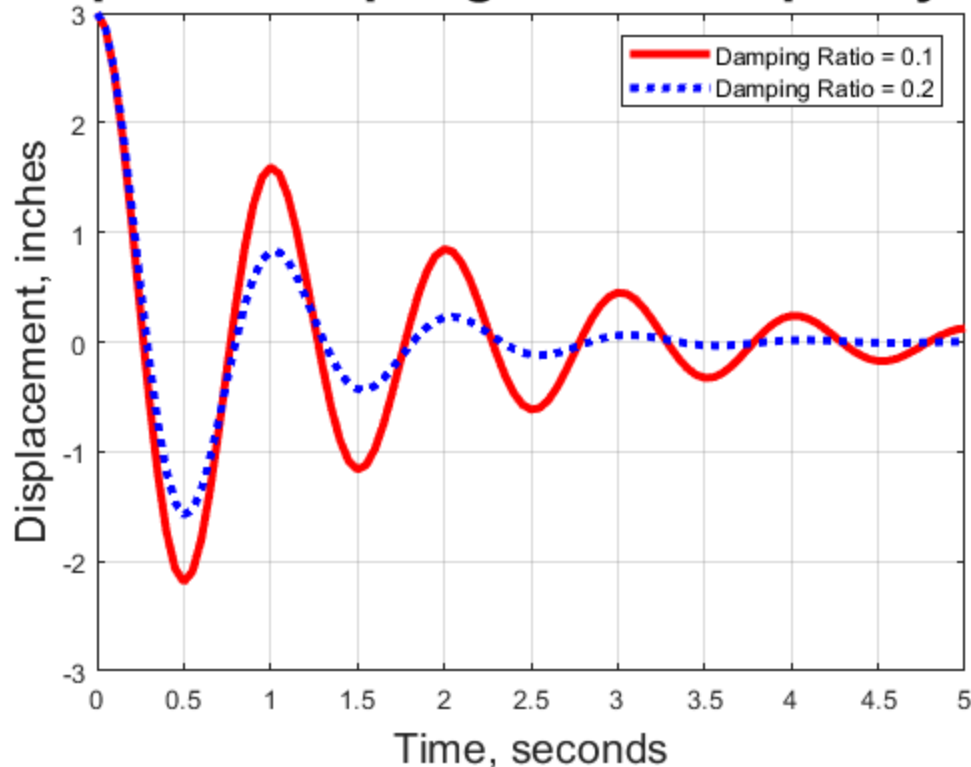
% Calculate new damped frequency fd
fd2 = fr*sqrt(1-dr2^2);

for i = 1:N+1
    c = cos(fd2*t(i));
    s = sin(fd2*t(i));
    e = exp(-dr2*fr*t(i));
    y2(i) = (y0*c + y0*dr2*fr/fd2*s)*e;
end
hold on
plot(t,y2,'LineWidth',3,'LineStyle',':', 'Color','Blue')
legend('Damping Ratio = 0.1','Damping Ratio = 0.2')
```

Response of Spring-Mass-Damper System



Response of Spring-Mass-Damper System



Example 5.4 Function `displace` & `displace2` section

```
out = displace(2)
out2 = displace2(3,.1,2*pi,2)

figure
fplot(@(t)displace2(3,.1,2*pi,t),[0 5])
hold on
fplot(@(t)displace2(3,.2,2*pi,t),[0 5])
```

`out =`

`0.8467`

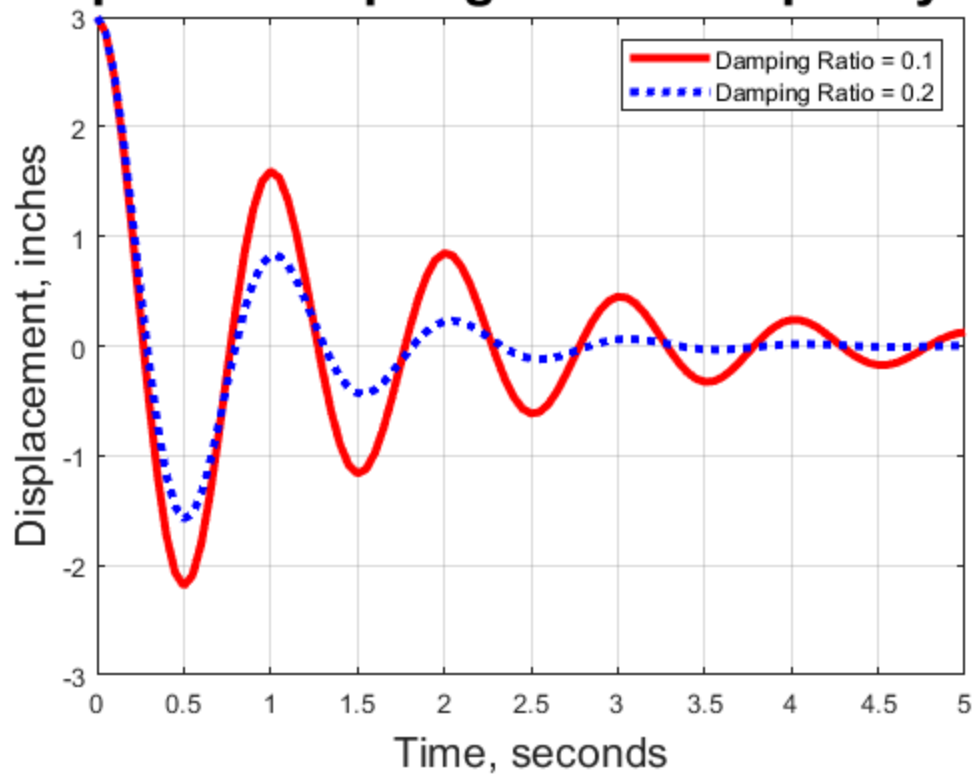
`out2 =`

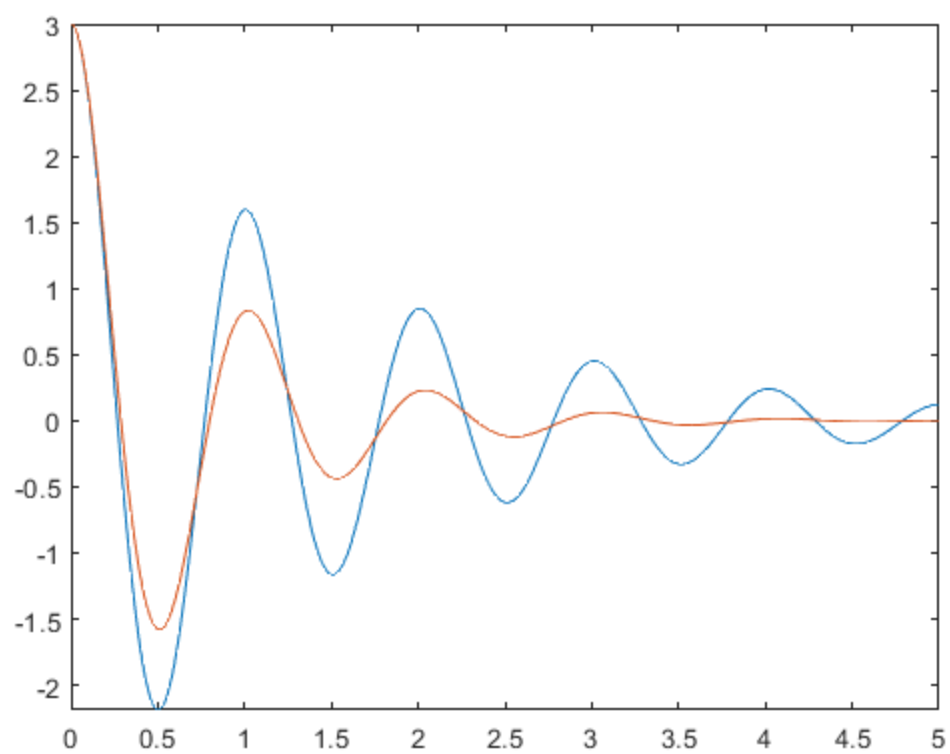
`0.8467`

Warning: Function behaves unexpectedly on array inputs. To improve performance, properly vectorize your function to return an output with the same size and shape as the input arguments.

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Response of Spring-Mass-Damper System





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