

Лекция 7

Библиотека *thrust*

- Обобщенное программирование: *контейнеры, обобщенные алгоритмы, итераторы*.
- Контейнеры *host_vector* и *device_vector*.
- Алгоритмы *thrust*.
- Преобразование указателей и комбинированный код.
- Алгоритм *transform* и функторы.
- Кортежи и *zip*-итератор.

Контейнеры *host_vector* и *device_vector*

```
#include <thrust/host_vector.h>
#include <thrust/device_vector.h>
#include <thrust/generate.h>
#include <thrust/sort.h>
// #include <thrust/copy.h>

int main(void){
    thrust::host_vector<int> h(1 << 8);
    thrust::generate(h.begin(), h.end(), rand);
    thrust::device_vector<int> d=h;
    thrust::sort(d.begin(), d.end());

    //thrust::copy(d.begin(), d.end(), h.begin());
    h=d;

    for(int i=0;i<1<<8;i++)
        printf("%i\t%d\n",i, h[i]);

    return 0;
}
```

```
~> nvcc 0.cu -o 0
~> nvprof ./0 > tt
```

1.19%	1.7920us	1	1.7920us	1.7920us	1.7920us	[CUDA memcpy DtoD]
0.96%	1.4400us	1	1.4400us	1.4400us	1.4400us	[CUDA memcpy DtoH]
0.51%	768ns	1	768ns	768ns	768ns	[CUDA memcpy HtoD]

==7688== API calls:

Time(%)	Time	Calls	Avg	Min	Max	Name
98.77%	73.642ms	2	36.821ms	103.81us	73.539ms	cudaMalloc
0.49%	366.17us	83	4.4110us	210ns	158.99us	cuDeviceGetAttribute
0.24%	175.81us	21	8.3710us	7.0410us	21.062us	cudaLaunch
0.20%	151.87us	2	75.935us	70.339us	81.532us	cudaFree
0.07%	50.401us	1	50.401us	50.401us	50.401us	cuDeviceTotalMem
0.06%	48.446us	3	16.148us	14.660us	18.604us	cudaMemcpyAsync
0.05%	38.601us	1	38.601us	38.601us	38.601us	cuDeviceGetName
0.05%	35.354us	140	252ns	197ns	3.3320us	cudaSetupArgument
0.04%	28.573us	10	2.8570us	2.3560us	5.0370us	cudaFuncGetAttributes
0.01%	6.3730us	21	303ns	276ns	524ns	cudaPeekAtLastError
0.01%	6.0650us	21	288ns	227ns	1.1170us	cudaConfigureCall
0.00%	3.4010us	6	566ns	345ns	1.1120us	cudaDeviceGetAttribute
0.00%	2.4650us	2	1.2320us	942ns	1.5230us	cudaDeviceGetSharedMemConfig
0.00%	1.7510us	2	875ns	377ns	1.3740us	cuDeviceGetCount
0.00%	1.5600us	2	780ns	617ns	943ns	cudaGetDevice

Преобразование указателей и комбинированный код

```
#include <thrust/host_vector.h>
#include <thrust/device_vector.h>
#include <thrust/fill.h>
#include <thrust/copy.h>
#include <cstdio>

__global__ void gTest(float* d){
    int idx=threadIdx.x+blockDim.x*blockIdx.x;
    d[idx]+=(float)idx;
}
```

```

int main(void){
    float *raw_ptr;
#ifdef H2D
    thrust::host_vector<float> h(1 << 8);
    thrust::fill(h.begin(), h.end(), 3.1415f);
    thrust::device_vector<float> d = h;
    fprintf(stderr, "Host to device\n");
#else
    thrust::device_vector<float> d(1<<8);
    thrust::fill(d.begin(), d.end(), 3.1415f);
    thrust::host_vector<float> h;
    fprintf(stderr, "Just on device\n");
#endif

```

```

~> nvcc -D H2D 1n.cu -o 1n
~> 1n > tt

```

```

~> nvcc 1n.cu -o 1n
~> 1n > tt

```

```

    raw_ptr = thrust::raw_pointer_cast(&d[0]); //d.data());

```

```

    gTest<<<4,64>>>(raw_ptr);
    cudaDeviceSynchronize();

```

```

    h=d;           //thrust::copy(d.begin(), d.end(), h.begin());
    for(int i=0;i<(1<<8);i++)
        printf("%g\n",h[i]);

```

```

    cudaFree(raw_ptr);
    return 0;

```

```

}

```

Алгоритм *transform* и функторы

```
#include <thrust/host_vector.h>
#include <thrust/device_vector.h>
#include <thrust/transform.h>
#include <thrust/sequence.h>
#include <cstdio>
#include <cmath>
```

```
struct range_functor{
    float h;
    range_functor(float _h):h(_h){}
    __host__ __device__
    float operator()(float x){
        return h*x;
    }
};
```

```
struct sin_functor
{
    __device__
    float operator()(float x){
        return __sinf(x);
    }
};
```

```
int main(){
    range_functor R(0.02);
    sin_functor Sin;

    fprintf(stderr, "%g\n", R(30.0f));
    //fprintf(stderr, "%g\n", Sin(3141592.0f/6.0f));

    thrust::host_vector<float> h1(1 << 8);
    thrust::host_vector<float> h2(1 << 8);
    thrust::device_vector<float> d1(1 << 8);
    thrust::device_vector<float> d2(1 << 8);
    thrust::sequence(thrust::device, d1.begin(), d1.end());
    thrust::transform(d1.begin(), d1.end(), d1.begin(), R);
    thrust::transform(d1.begin(), d1.end(), d2.begin(), Sin);

    h2=d2;
    h1=d1;

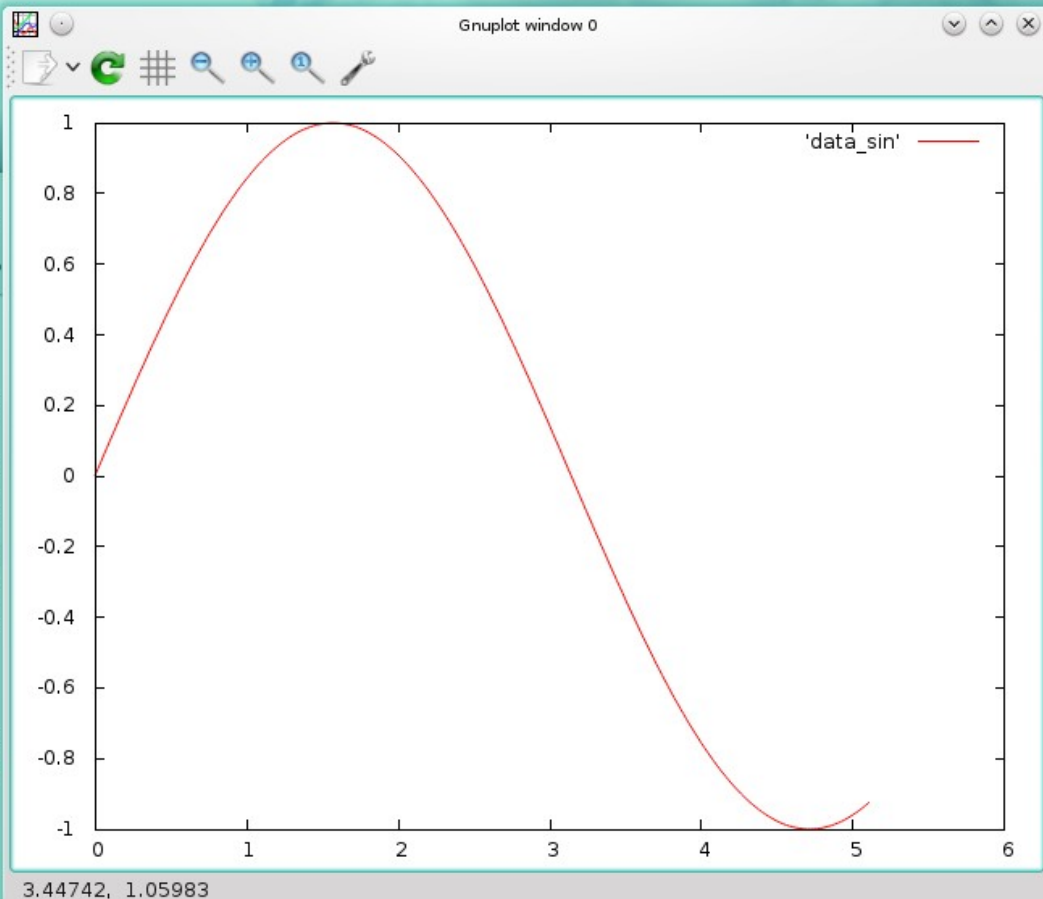
    for(int i=0;i<(1<<8);i++){
        printf("%g\t%g\n",h1[i], h2[i]);
    }

    return 0;
}
```

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```
//  
int main(){  
    range_func rfunc;  
    sin_func sfunc;  
  
    thrust::host_vector  
    thrust::host_vector  
    thrust::device_vect  
    thrust::device_vect  
    thrust::sequence(th  
    thrust::transform(d  
    thrust::transform(d  
    //thrust::fill(d2.b  
  
    h2=d2;  
    h1=d1;  
    //thrust::for_each(t  
    for(int i=0;i<(1<  
    printf("%g\t%g\n"  
    )  
  
    return 0;  
}
```



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func3.cu UTF-8

```
malkov@linux-5002:~/WORKSHOP/CUDA EXERCISE/THRUST/tests> nvcc func3.cu -o func3  
malkov@linux-5002:~/WORKSHOP/CUDA EXERCISE/THRUST/tests> ./func3 > data_sin  
malkov@linux-5002:~/WORKSHOP/CUDA EXERCISE/THRUST/tests> gnuplot
```

```
GNUPLOT  
Version 4.6 patchlevel 5    last modified February 2014  
Build System: Linux x86_64  
  
Copyright (C) 1986-1993, 1998, 2004, 2007-2014  
Thomas Williams, Colin Kelley and many others  
  
gnuplot home:    http://www.gnuplot.info  
faq, bugs, etc:  type "help FAQ"  
immediate help:  type "help" (plot window: hit 'h')
```

```
Terminal type set to 'qt'  
gnuplot> plot 'data_sin' w l  
gnuplot>
```

Search and Replace Current Project Terminal Debug View

Реализация SAXPY

```
#include <thrust/host_vector.h>
#include <thrust/device_vector.h>
#include <thrust/transform.h>

struct saxpy_functor
{
    const float a;
    saxpy_functor(float _a) : a(_a) {}
    __host__ __device__
    float operator()(float x, float y){
        return a*x+y;
    }
};

void saxpy(float a, thrust::device_vector<float>& x,
           thrust::device_vector<float>& y){
    saxpy_functor func(a);

    thrust::transform(x.begin(), x.end(), y.begin(), y.begin(), func);
}
```

```

#include <thrust/fill.h>
#include <thrust/sequence.h>

int main(){
    thrust::host_vector<float> h1(1 << 24);
    thrust::host_vector<float> h2(1 << 24);
    thrust::sequence(h1.begin(), h1.end());
    thrust::fill(h2.begin(), h2.end(), 0.87);

    thrust::device_vector<float> d1 = h1;
    thrust::device_vector<float> d2 = h2;

    saxpy(3.0, d1, d2);

    h2=d2;
    h1=d1;

    for(int i=0;i<(1<<8);i++){
        printf("%d\t%g\t%g\n",i, h1[i], h2[i]);
    }

    return 0;
}

```

```

~> ./3n
0  0  0.87
1  1  3.87
2  2  6.87
3  3  9.87
4  4  12.87
5  5  15.87
6  6  18.87
7  7  21.87

```

```

.....
250250750.87
251251753.87
252252756.87
253253759.87
254254762.87
255255765.87

```

Кортежи

```
#include <thrust/tuple.h>
#include <cstdio>

int main(){
    thrust::tuple<int, float, const char *> test_tuple(23, 4.5, "thrust");
    printf("%d\t%f\t%s\n", thrust::get<0>(test_tuple),
        thrust::get<1>(test_tuple),
        thrust::get<2>(test_tuple));

    return 0;
}
```

```
~> ./tuple1
23    4.5    thrust
```

zip-итераторы

```
#include <thrust/tuple.h>
#include <thrust/device_vector.h>
#include <thrust/host_vector.h>
#include <thrust/transform.h>
#include <thrust/fill.h>
#include <thrust/iterator/zip_iterator.h>

#define N 32

struct rotate_tuple{
    __host__ __device__
    thrust::tuple<float,float,float> operator()(thrust::tuple<float&,float&,float&>& t){
        float x = thrust::get<0>(t);
        float y = thrust::get<1>(t);
        float z = thrust::get<2>(t);

        float rx=0.36*x+0.48*y-0.80*z;
        float ry=-0.80f*x+0.60*y+0.00f*z;
        float rz=0.48f*x+0.64f*y+0.60f*z;

        return thrust::make_tuple(rx,ry,rz);
    }
};
```

```
int main(){
    thrust::device_vector<float> x(N), y(N), z(N);

    thrust::fill(x.begin(), x.end(), 2.0);
    thrust::fill(y.begin(), y.end(), 3.0);
    thrust::fill(z.begin(), z.end(), 5.0);

    thrust::transform(
        thrust::make_zip_iterator(
            thrust::make_tuple(x.begin(), y.begin(), z.begin() )),
        thrust::make_zip_iterator(
            thrust::make_tuple(x.end(), y.end(), z.end() )),
        thrust::make_zip_iterator(
            thrust::make_tuple(x.begin(), y.begin(), z.begin() )),
        rotate_tuple() );

    thrust::host_vector<float> hx(N), hy(N), hz(N);
    hx=x; hy=y; hz=z;
    for(int i=0;i<N;i++)
        printf("%g\t%g\t%g\n",hx[i], hy[i], hz[i]);

    return 0;
}
```