Zestaw 4 poprawa

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3N

Zbudowano wielomian interpolacyjny oparty na nastepujacych danych:

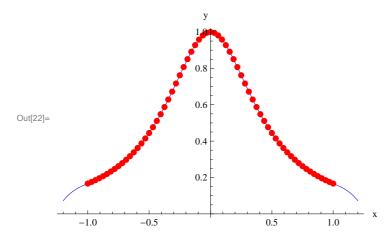
```
ln[1]:= x_0 = -1.2300;
                                             y_0 = 1.5129;
                                              x_1 = -1.1900;
                                              y_1 = 1.4161;
                                              x_2 = -0.7400;
                                              y_2 = 0.5476;
                                              x_3 = 0.1100;
                                              y_3 = 0.0121;
                                              x_4 = 2.5600;
                                               y_4 = 6.5536;
In[11]:= p[t_{-}] := N \left[ y_{0} \frac{(t-x_{1}) (t-x_{2}) (t-x_{3}) (t-x_{4})}{(x_{0}-x_{1}) (x_{0}-x_{2}) (x_{0}-x_{3}) (x_{0}-x_{4})} + y_{1} \frac{(t-x_{0}) (t-x_{2}) (t-x_{3}) (t-x_{4})}{(x_{1}-x_{0}) (x_{1}-x_{2}) (x_{1}-x_{3}) (x_{1}-x_{4})} + y_{1} \frac{(t-x_{0}) (t-x_{2}) (t-x_{3}) (t-x_{4})}{(x_{1}-x_{0}) (x_{1}-x_{2}) (x_{1}-x_{3}) (x_{1}-x_{4})} + y_{1} \frac{(t-x_{0}) (t-x_{2}) (t-x_{3}) (t-x_{4})}{(x_{1}-x_{0}) (x_{1}-x_{2}) (x_{1}-x_{3}) (x_{1}-x_{4})} + y_{1} \frac{(t-x_{0}) (t-x_{2}) (t-x_{3}) (t-x_{4})}{(x_{1}-x_{0}) (x_{1}-x_{2}) (x_{1}-x_{3}) (x_{1}-x_{4})} + y_{1} \frac{(t-x_{0}) (t-x_{2}) (t-x_{3}) (t-x_{4})}{(x_{1}-x_{2}) (x_{1}-x_{3}) (x_{1}-x_{4})} + y_{1} \frac{(t-x_{0}) (t-x_{2}) (t-x_{3}) (t-x_{4})}{(x_{1}-x_{2}) (x_{1}-x_{3}) (x_{1}-x_{4})} + y_{1} \frac{(t-x_{0}) (t-x_{3}) (t-x_{4})}{(x_{1}-x_{3}) (t-x_{4})} + y_{1} \frac{(t-x_{0}) (t-x_{3}) (t-x_{4})}{(x_{1}-x_{3}) (t-x_{4})} + y_{1} \frac{(t-x_{0}) (t-x_{3}) (t-x_{4})}{(x_{1}-x_{3}) (t-x_{4})} + y_{1} \frac{(t-x_{0}) (t-x_{4})}{(x_{1}-x_{4})} + y_{1} \frac{(t-x_{0}) (t-x_{4})}{(
                                                                                 y_{2} \frac{(t - x_{0}) (t - x_{1}) (x_{0} - x_{2}) (x_{0} - x_{3})}{(x_{2} - x_{0}) (x_{2} - x_{1}) (x_{2} - x_{3}) (x_{2} - x_{4})} + \\ y_{3} \frac{(t - x_{0}) (t - x_{1}) (t - x_{2}) (t - x_{4})}{(x_{3} - x_{0}) (x_{3} - x_{1}) (x_{3} - x_{2}) (x_{3} - x_{4})} + y_{4} \frac{(t - x_{0}) (t - x_{1}) (t - x_{2}) (t - x_{3})}{(x_{4} - x_{0}) (x_{4} - x_{1}) (x_{4} - x_{2}) (x_{4} - x_{3})} \right];
  In[12]:= p[t]
Out[12]= 15.1988 (-2.56 + t) (-0.11 + t) (0.74 + t) (1.19 + t) -
                                                          16.1379 \; (-2.56 + t) \; (-0.11 + t) \; (0.74 + t) \; (1.23 + t) \; + \; 0.885364 \; (-0.11 + t) \; (1.19 + t) \; (1.23 + t) \; - \; (-0.11 + t) \; (-0
                                                            0.00333543 (-2.56 + t) (0.74 + t) (1.19 + t) (1.23 + t) +
                                                            0.0570334 (-0.11 + t) (0.74 + t) (1.19 + t) (1.23 + t)
  In[13]:= Expand[p[t]]
Out[13]= -0.507477 + 3.91695 t + 7.22066 t^2 + 1.10671 t^3 - 0.885364 t^4
```

5N

Skonstruowano funckje, jak w zadaniu 4N:

```
In[18]:= SplajnNat[XY0_] := Module {XY = XY0},
              Dd = Module \{k\}, n = Length[XY] - 1; X = Transpose[XY]_{[1]};
                  Y = Transpose[XY]_{[2]}; h = d = Table[0, {n}]; m = Table[0, {n+1}];
                  a = b = c = v = Table[0, {n-1}]; s = Table[0, {n}, {4}];
                  h_{[1]} = X_{[2]} - X_{[1]};
                  \mathbf{d}_{\llbracket 1 \rrbracket} = \frac{\mathbf{Y}_{\llbracket 2 \rrbracket} - \mathbf{Y}_{\llbracket 1 \rrbracket}}{\mathbf{h}_{\llbracket 1 \rrbracket}};
                  For k = 2, k \le n, k++
                    h_{[\![k]\!]} = X_{[\![k+1]\!]} - X_{[\![k]\!]};
                    d_{[k]} = \frac{Y_{[k+1]} - Y_{[k]}}{h_{[k]}};
                    \mathbf{a}_{[\![k-1]\!]} = \mathbf{h}_{[\![k]\!]};
                    b_{[k-1]} = 2 (h_{[k-1]} + h_{[k]});
                    c_{[k-1]} = h_{[k]};
                    v_{[k-1]} = 6 (d_{[k]} - d_{[k-1]});
          TrD := Module [\{k, t\},
                  m_{\parallel 1 \parallel} = 0;
                  m_{[n+1]} = 0;
                  For k = 2, k \le n - 1, k++,
                    t = \frac{a_{[k-1]}}{b_{[k-1]}};
                    b_{[k]} = b_{[k]} - t c_{[k-1]};
                    v_{[k]} = v_{[k]} - t v_{[k-1]};
                  \mathbf{m}_{\llbracket \mathbf{n} \rrbracket} = \frac{\mathbf{v}_{\llbracket \mathbf{n}-1 \rrbracket}}{\mathbf{b}_{\llbracket \mathbf{n}-1 \rrbracket}};
                  For k = n - 2, 1 \le k, k - -,
                    m_{[\![k+1]\!]} \ = \ \frac{v_{[\![k]\!]} \ - \ c_{[\![k]\!]} \ m_{[\![k+2]\!]}}{b_{[\![k]\!]}} \, ; \, \Big] \, ; \, \Big] \, ; \, \Big] \, ; \, \\
          Pol := Module [\{k\}],
                  For k = 1, k \le n, k++,
                      s_{[k,1]} = Y_{[k]};
                      s_{[k,2]} = d_{[k]} - \frac{1}{6}h_{[k]} (2m_{[k]} + m_{[k+1]});
                      \mathbf{s}_{[k,3]} = \frac{\mathbf{m}_{[k]}}{2};
                      s_{[k,4]} = \frac{m_{[k+1]} - m_{[k]}}{6 h_{[k]}}; ]; 
          CS[t_] := Module[{j},
                  For [j=1, j \le n, j++,
                    If [X_{[j]} \le t \&\& t < X_{[j+1]}, k = j];;
                  If [t < X_{[1]}, k = 1];
                  If [X_{[n+1]} \le t, k = n];
                  w = t - X_{\lceil k \rceil};
                  Return [ ((s_{[k,4]} w + s_{[k,3]}) w + s_{[k,2]}) w + s_{[k,1]} ];];
              Dd;
              TrD;
              Pol;
```

```
In[19]:= SplajnNat[XY];
         \texttt{dots} = \texttt{ListPlot}[\texttt{XY}, \texttt{PlotStyle} \rightarrow \{\texttt{Red}, \texttt{PointSize}[\texttt{0.02}]\}, \texttt{DisplayFunction} \rightarrow \texttt{Identity}];
          \texttt{gr} = \texttt{Plot}[\texttt{CS}[\texttt{x}], \{\texttt{x}, -1.2, 1.2\}, \texttt{PlotStyle} \rightarrow \{\texttt{Blue}\}, \texttt{DisplayFunction} \rightarrow \texttt{Identity}];
          Show[gr, dots, AxesLabel \rightarrow {"x", "y
          Print["Splajn y = ", Expand[CS[x]]];
```



Splajn y = $5.15425 - 14.3955 x + 14.1119 x^2 - 4.70397 x^3$