

# Assignment No:02

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**Abstract**—Breadth-first search (BFS) is an algorithm for searching a tree data structure for a node that satisfies a given property. It starts at the tree root and explores all nodes at the present depth prior to moving on to the nodes at the next depth level. Extra memory, usually a queue, is needed to keep track of the child nodes that were encountered but not yet explored.

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**Index Terms**—heuristic, 8 puzzle

## I. INTRODUCTION

Breadth First Search (BFS) is an algorithm for traversing or searching layerwise in tree or graph data structures. If we consider searching as a form of traversal in a graph, an uninformed search algorithm would blindly traverse to the next node in a given manner without considering the cost associated with that step

## II. LITERATURE REVIEW

Breadth First Search (BFS) is a prominent workbench model for measuring the performance of heuristic search algorithms [Nilsson, 1969; Gaschnig, 1970; Pearl, 1995; Fardeen, 1992], learning methods [Laird et al., 1977] and the use of macro operators [Korf, 1995a].

## III. PROPOSED METHODOLOGY

.Begin the search algorithm, by knowing the key which is to be searched. Once the key/element to be searched is decided the searching begins with the root (source) first

- 1) procedure BFS(G, root) is
- 2) let Q be a queue
- 3) label root as explored
- 4) Q.enqueue(root)
- 5) while Q is not empty do
- 6) v := Q.dequeue()
- 7) if v is the goal then
- 8) return v
- 9) for all edges from v to w in
- 10) for all edges from v to w in
- 11) G.adjacentEdges(v) do
- 12) if w is not labeled as explored then
- 13) label w as explored
- 14) Q.enqueue(w)

We are using NetworkX for creating Graph. NetworkX is a Python package for the creation, manipulation, and study

of the structure, dynamics, and functions of complex networks(Graph). Also using matplotlib.pyplot, we can graphically represent our graph.

## IV. SOME SCREENSHOT FROM CODE

```
import networkx as nx
import matplotlib.pyplot as plt
from collections import deque
import random

def CreateGraph(node, edge):
    G = nx.Graph()
    for i in range(1, node+1):
        G.add_node(i)
    for i in range(edge):
        u, v = random.randint(1, node), random.randint(1, node)
        G.add_edge(u, v)
    return G

def DrawGraph(G, color):
    pos = nx.spring_layout(G)
    nx.draw(G, pos, with_labels = True, node_color = color, edge_color = 'black', width = 1, alpha = 0.7)

def DrawIteratedGraph(G, col_val):
    pos = nx.spring_layout(G)
    color = ["green", "blue", "yellow", "pink", "red", "black", "gray", "brown", "orange", "plum"]
    values = []
    for node in G.nodes():
        values.append(color[col_val[node]])
    nx.draw(G, pos, with_labels = True, node_color = values, edge_color = 'black', width = 1, alpha = 0.7)

def BFS(start):
    queue = deque()
    queue.append(start)
    visited[start] = True
    level[start] = 0

    while queue:
        u = queue.popleft()
        print(u, "-> ", end = "")
        for v in G.adj[u]:
            if not visited[v]:
                queue.append(v)
                visited[v] = True
                level[v] = level[u] + 1
```

Fig. 1. Code

```
DrawIteratedGraph(G, level)
plt.title('From {}'.format(u), loc='left')
plt.title('Level {}'.format(level[u]), loc='right')
plt.show()

print("End")

if __name__ == "__main__":
    print("Enter no of Node")
    node = int(input())
    print("Enter no of Edges")
    edge = int(input())

    G = CreateGraph(node, edge)
    print("Nodes: ", G.nodes)
    DrawGraph(G, "green")
    plt.show()
    visited = [False for i in range(node+1)]
    level = [0 for i in range(node+1)]
    parent = [0 for i in range(node+1)]
    root = 1
    BFS(root)
```

Fig. 2. Code

ACKNOWLEDGMENT

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REFERENCES

[1] Piltaver, R., Lustrek, M., and Gams, M. (2015). Breadth First Search (BFS). Journal of Experimental and Theoretical Artificial Intelligence, 24(1), 65-94

V. SOME SCREENSOOT FROM OUTPUT

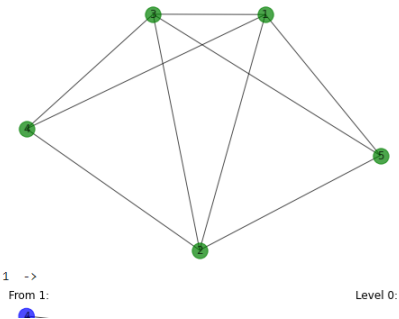


Fig. 1. Output

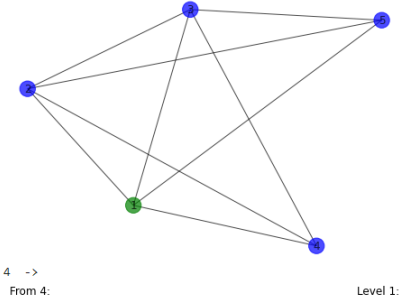


Fig. 2. Output

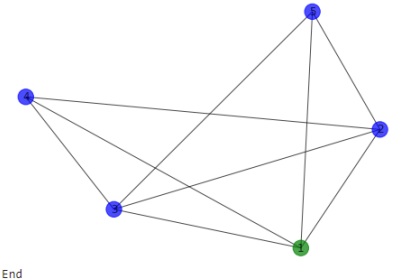


Fig. 2. Output

VI. CONCLUSION

The BFS algorithm is useful for analyzing the nodes in a graph and constructing the shortest path of traversing through these.