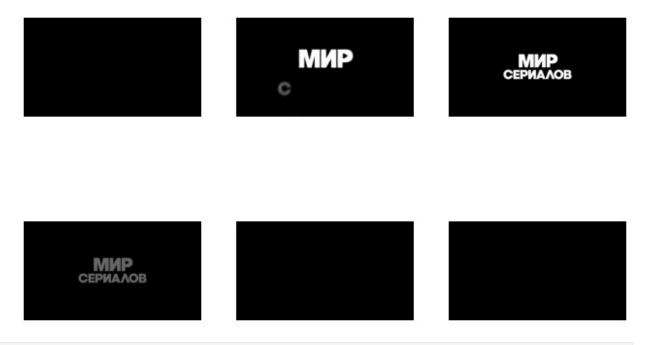
Для поиска интро я предлагаю следующий подход: Аудио и видео разбивается на фреймы определенного интервала, из этих фреймов получаем эмбеддинги (по отдельности), эти эмбеддинги объединяются и подаются в предиктор, например, простую CNN. В итоге, получаем вероятности быть интро для всех кадров.

```
import cv2
import torch
import torch.nn as nn
import numpy as np
import librosa
from transformers import AutoProcessor, AutoModel
import torchvision.transforms as T
from PIL import Image
```

## Функция для получения фреймов

```
def extract video frames(video path, frame duration=1.0):
    cap = cv2.VideoCapture(video path)
    fps = cap.get(cv2.CAP PROP FPS)
    total_frames = int(cap.get(cv2.CAP_PROP_FRAME_COUNT))
    video duration = total frames / fps
    frames = []
    timestamps = []
    current time = 0.0
    while current time < video duration:
        cap.set(cv2.CAP PROP POS MSEC, current time * 1000)
        ret, frame = cap.read()
        if not ret:
            break
        frames.append(frame)
        timestamps.append(current time)
        current time += frame duration
    cap.release()
    audio, sr = librosa.load(video path, sr=16000)
    audio chunks = []
    for ts in timestamps:
        start sample = int(ts * sr)
        end sample = int((ts + frame duration) * sr)
        chunk = audio[start sample:end sample]
        chunk = librosa.util.fix length(chunk, size=int(frame duration
* sr))
        audio chunks.append(chunk)
    return frames, audio_chunks, timestamps
```

```
frames, audio chunks, timestamps = extract video frames("/content/-
220020068 456249220.mp4")
<ipython-input-39-302975361>:22: UserWarning: PySoundFile failed.
Trying audioread instead.
  audio, sr = librosa.load(video path, sr=16000)
/usr/local/lib/python3.11/dist-packages/librosa/core/audio.py:184:
FutureWarning: librosa.core.audio. audioread load
     Deprecated as of librosa version 0.10.0.
     It will be removed in librosa version 1.0.
 y, sr_native = __audioread load(path, offset, duration, dtvpe)
import matplotlib.pyplot as plt
fig, axs = plt.subplots(\frac{2}{3}, figsize=(\frac{8}{5}))
for i, ax in enumerate(axs.flat):
    ax.imshow(frames[i])
    ax.axis('off')
plt.show()
```



device = torch.device("cuda" if torch.cuda.is\_available() else "cpu")

Получение видео эмбеддингов с помощью dinov2, аудио - MFCC

```
processor = AutoProcessor.from_pretrained("facebook/dinov2-base")
model = AutoModel.from_pretrained("facebook/dinov2-
base").to(device).eval()

transform = T.Compose([
```

```
T.Resize(224),
    T.CenterCrop(224),
    T.ToTensor(),
    T.Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
])
def get video embedding(frame: np.ndarray) -> np.ndarray:
    image = Image.fromarray(cv2.cvtColor(frame, cv2.COLOR BGR2RGB))
    inputs = transform(image).unsqueeze(0).to(device)
    with torch.no grad():
        outputs = model(inputs)
        embedding = outputs.last hidden state.mean(dim=1).squeeze()
    return embedding.cpu().numpy()
def get audio embedding(audio, sr=16000):
    mfcc = librosa.feature.mfcc(y=audio, sr=sr, n mfcc=20)
    return np.mean(mfcc, axis=1)
video embs = [get video embedding(frame) for frame in frames]
audio embs = [get audio embedding(audio) for audio in audio chunks]
video embs[0].shape, audio embs[0].shape
((768,),(20,))
```

## Конкатенирую эмбеддинги

```
features = []
for v_emb, a_emb in zip(video_embs, audio_embs):
         vec = np.concatenate([v_emb, a_emb])
         features.append(vec)
features = torch.tensor(np.array(features),
dtype=torch.float32).unsqueeze(0)
features.shape
torch.Size([1, 1002, 788])
```

## Простая сверточная нейронная сеть

```
def forward(self, x):
    x = x.transpose(1, 2)
    x = self.net(x)
    return x.squeeze(1)
```

Датасет не маленький, так что для примера я проинференсила полученную фичу

```
model = IntroPredictor(features.shape[2])
model.eval()
with torch.no_grad():
    out = model(features)
out
tensor([[0.6250, 0.5934, 0.8102, ..., 0.6557, 0.6861, 0.6970]])
```