# Slate Recommendation Systems: A Reinforcement Learning Problem

#### **Introduction to Problem Statement:**

The PS here deals with building a Recommender System that optimally chooses and places C=9 items on a grid out of a total dataset of T=350 items. This should consider some basic features of the users, expected to be single-use, as well as interaction and correlation amongst the chosen items. We also wish to incorporate features such as seasonality and trends.

# What a Multi Arm Bandit Approach would look like:

A simple bandit approach would treat every slate as one item, i.e. one action set. This would create 350P9, i.e. 7\*10^22 items. Finding enough data to exploit the best actions from this set would be near impossible. This makes it intractable to use on such a dataset. This leads to the need to look at alternate methods of solving this problem

## SlateQ:

A recent approach to the slate recommendation problem is an MDP model called SlateQ. SlateQ looks at building a two-part solution to this problem as follows:

- 1. A User Choice Model:
  - a. Input:
    - Interaction Data from users
  - b. Output:
    - The user choice model outputs a relative probability of selecting each item for every grid. For example, this probability would be 1/10 for each item before training. (The 10th item being a null item)
    - After that, it would then train to calculate relative probability.
  - c. How
    - SlateQ does not explain this model. Here we are looking to ideate and create an alternate model.
  - d. Diagram:

While Training: All data regarding slates and action taken While Evaluation : A 3x3 slate User Choice Model

While Evaluation : A 3x3 matrix with probabilities of selection of each item (+an additional probability of no selection)

#### 2. A Slate Building Model:

a. Input:

The relative probabilities of selection, and the rewards associated with each item

b. Output:

The best slate out of the 7\*10^22 items.

c. How:

SlateQ uses mixed integer programming to solve a combinatorial problem in linear time.

d. Diagram:



## Approach to the problem:

This problem can be approached in two stages:

- 1. Stage 1: Looking for alternate slate recommendation solutions
  - a. This includes looking at SlateQ and exploring alternatives such as off-policy evaluation, SEO models, and CMAB models.
- 2. Stage 2: Proceeding with SlateQ and looking at possible User Choice models
  - a. If we proceed with SlateQ, it still leaves uncertainty about how the user choice will be modelled.
  - b. This could include looking at Multinomial Logit models, CTR models or building a model from scratch.

## Stages of solution:

- 1. Literature Review:
  - a. This is the current step of the process that I am at, which involves reading both about possible alternate models as well as possible options for user choice and understanding their pros and cons
  - b. I have reviewed the papers listed below and am still trying to find evidence that interaction data is modelled at any stage of this process.
  - c. I have found papers that take into account the positioning of the items
- 2. Database selection:
  - a. We worked initially n setting up the Finn.no database, however, since it could not be fixed up, we moved to the Google RecSim database.
  - b. The Recsim database has now been installed and set up.
- 3. Proposed Alternative Models:
  - a. Proposed Model Type 1

- i. The first proposal is to consider 350C2 interactions. This would involve learning all 350C2 interactions, then choosing the k items with the highest correlation magnitude will be factored in, while creating the final slate.
- ii. This reduces complexity by eliminating all interaction terms above 350C3, for which we need significantly more data. It also brings us down from 350C2 to 350\*k interaction terms to consider. k could be 1,2,5,10, depending on the data.
- iii. The alternative could be to initially reduce ur action space from 350 to around 50 based on the popularity of the singular items (i.e level 1 terms) itself
- b. Proposed Model Type 2
  - i. We could look at non-linearising the action space based on suggestions from Prof.Ravi. This could include building the following.
    - 1. A neural network-based Contextual Bandit
    - 2. Relational Boosted Bandits
    - 3. GP-UCB (Gaussian Process optimizer with upper confidence bounds)

### References:

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- 12. Cluster Bandits: https://github.com/google-research/recsim/tree/master/recsim /colab (Pasted as text due to format issues)