

## Assignment 2: Policy Gradient

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NOTE: Please do NOT change the sizes of the answer blocks or plots.

### 5 Small-Scale Experiments

#### 5.1 Experiment 1 (Cartpole) – [25 points total]

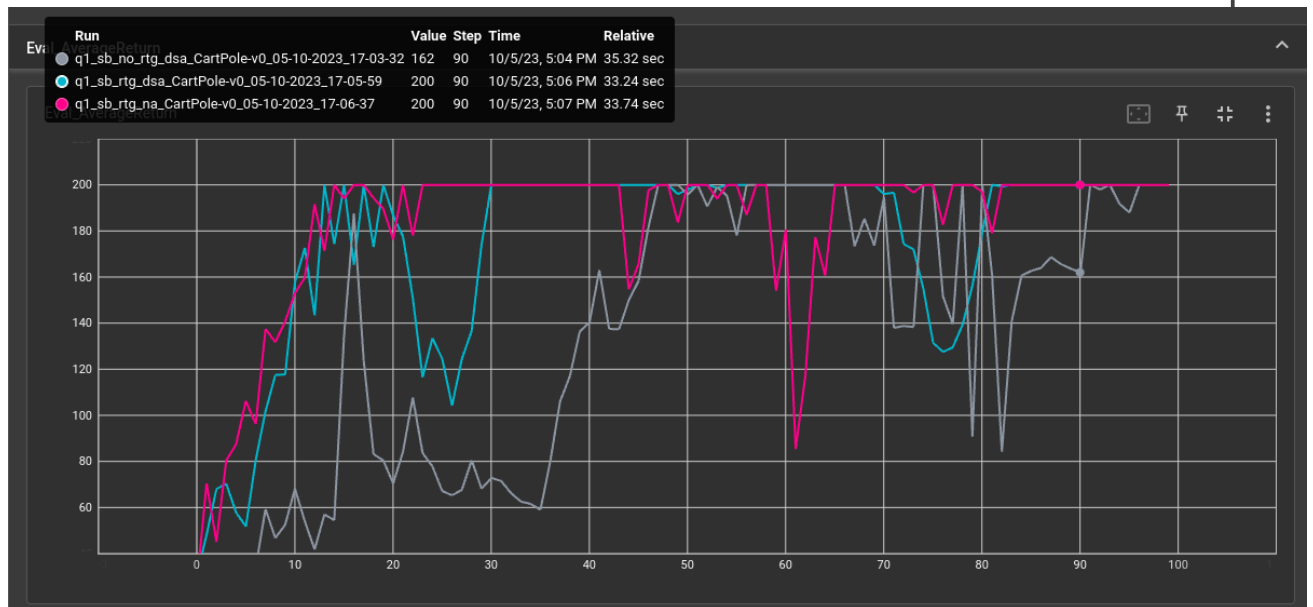
##### 5.1.1 Configurations

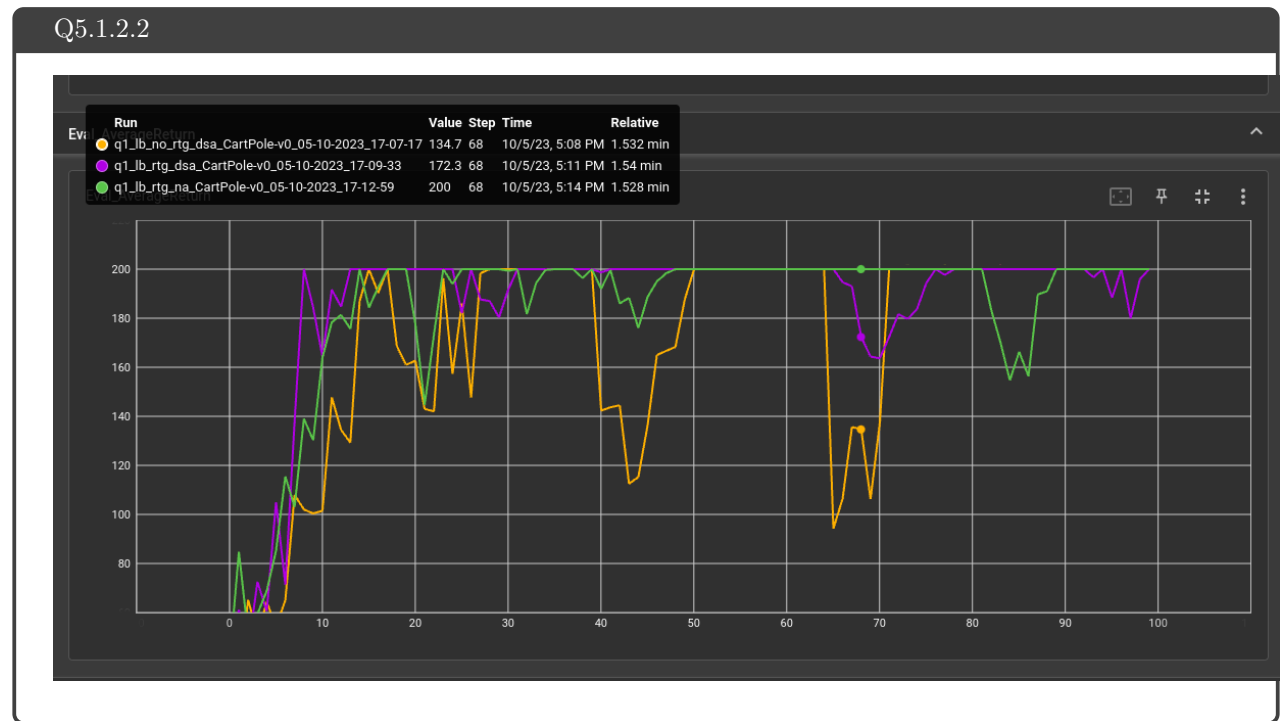
Q5.1.1

##### 5.1.2 Plots

##### 5.1.2.1 Small batch – [5 points]

Q5.1.2.1



**5.1.2.2 Large batch – [5 points]****5.1.3 Analysis****5.1.3.1 Value estimator – [5 points]****5.1.3.2 Advantage standardization – [5 points]**

**5.1.3.3 Batch size – [5 points]**

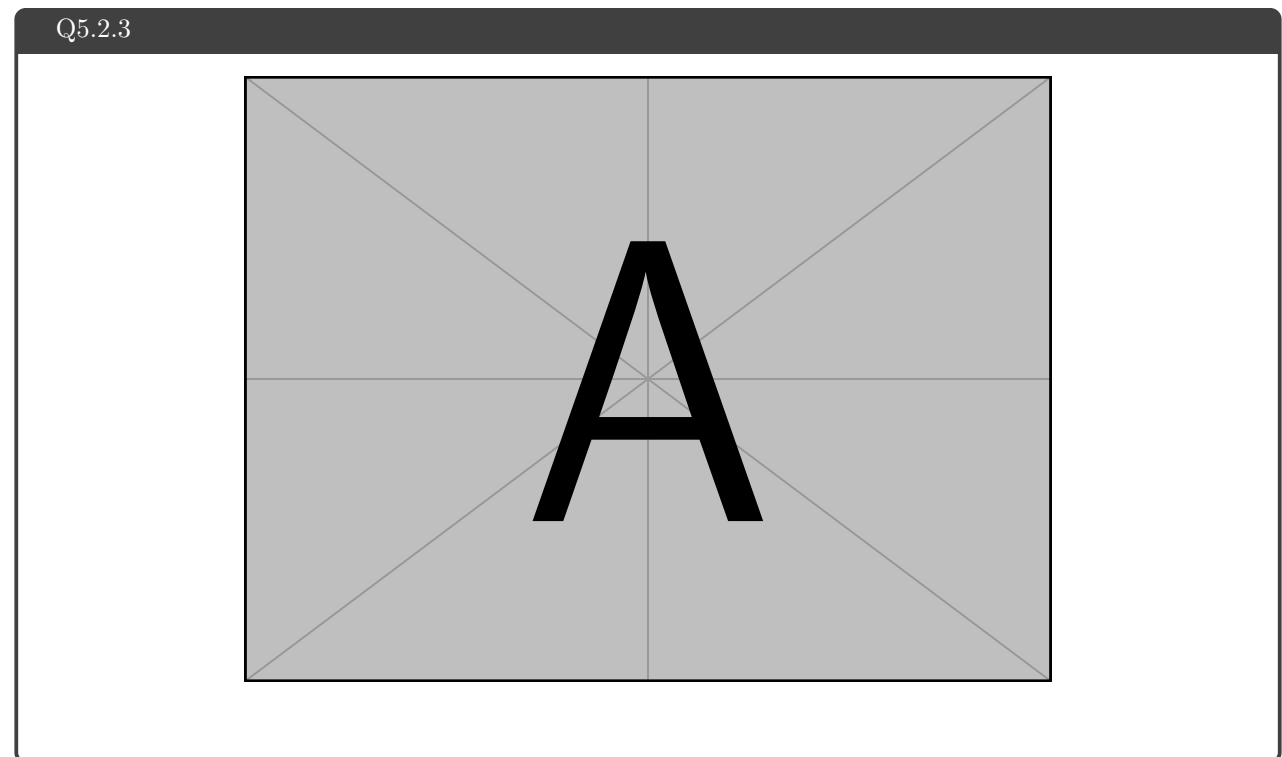
Q5.1.3.1

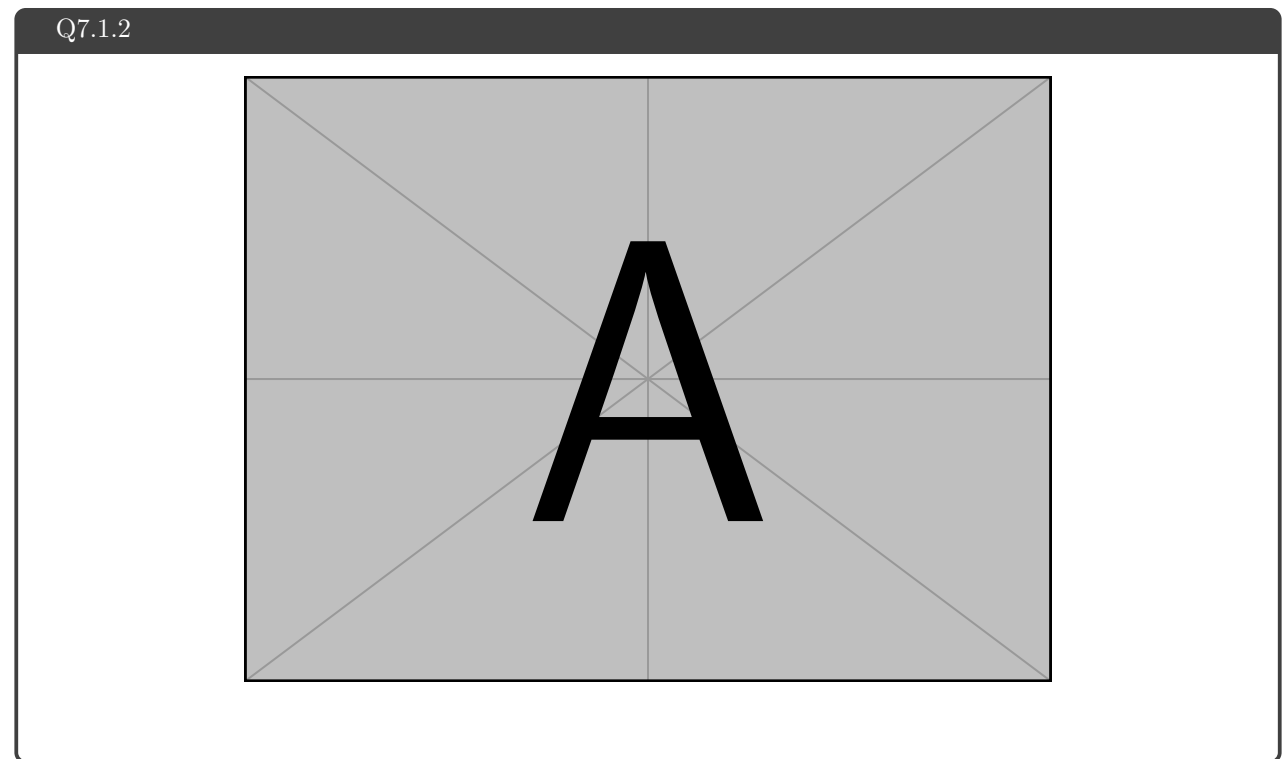
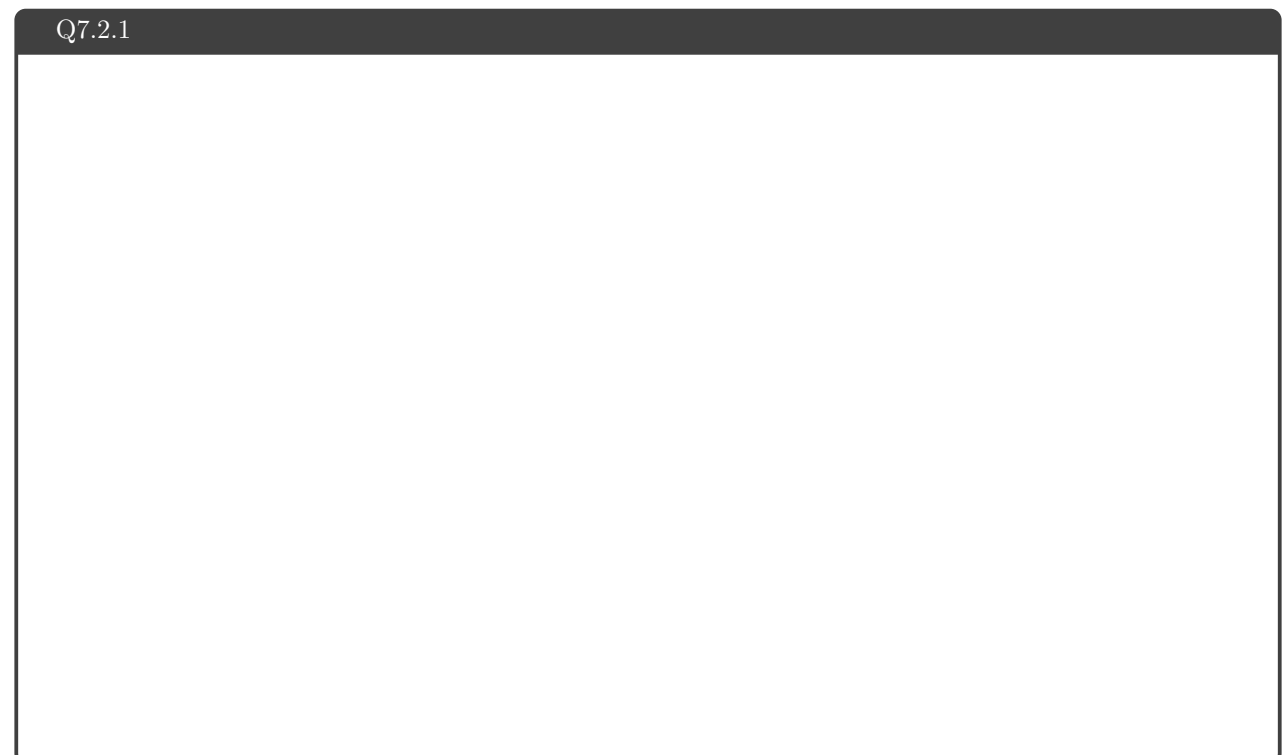
**5.2 Experiment 2 (InvertedPendulum) – [15 points total]****5.2.1 Configurations – [5 points]**

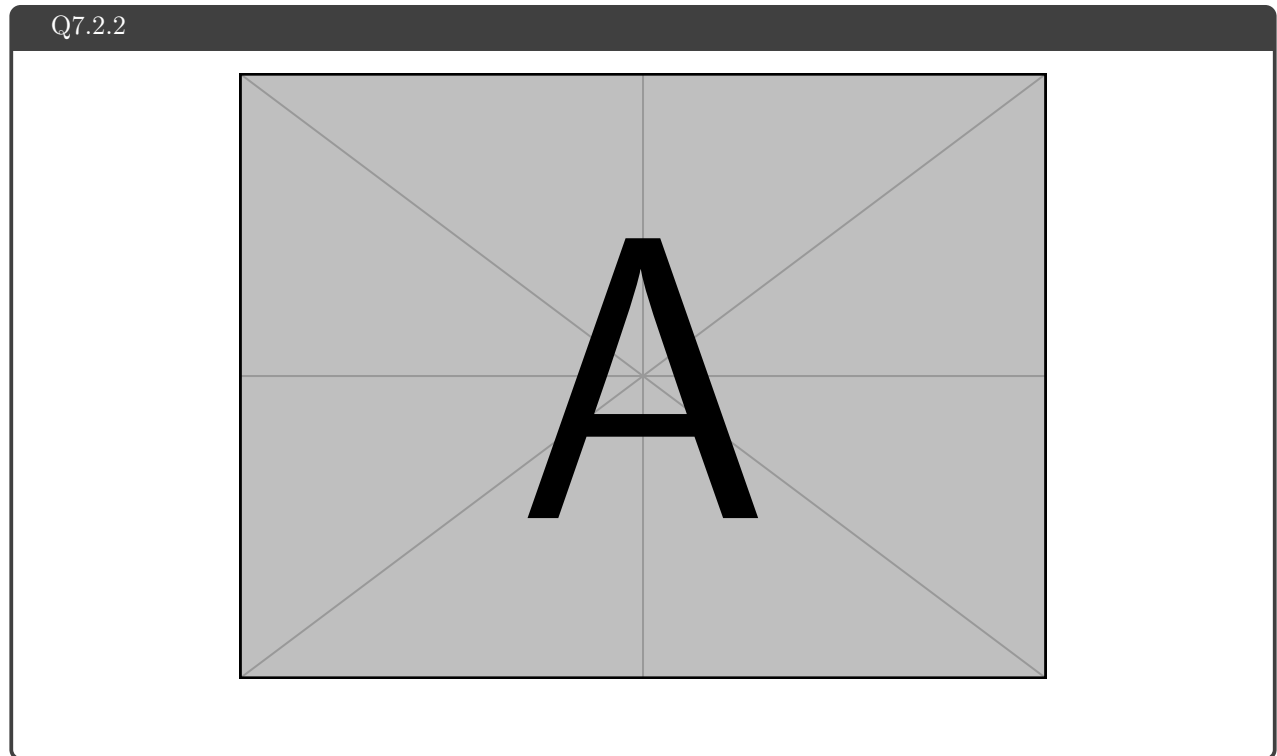
Q5.2.1

**5.2.2 smallest  $b^*$  and largest  $r^*$  (same run) – [5 points]**

Q5.2.2

**5.2.3 Plot – [5 points]****7 More Complex Experiments****7.1 Experiment 3 (LunarLander) – [10 points total]****7.1.1 Configurations**

**7.1.2 Plot – [10 points]****7.2 Experiment 4 (HalfCheetah) – [30 points]****7.2.1 Configurations**

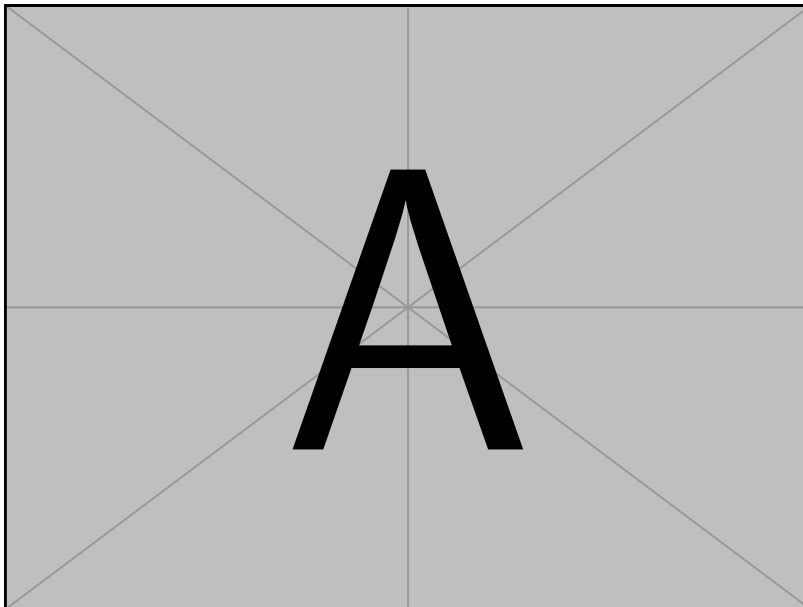
**7.2.2 Plot – [10 points]****7.2.3 Optimal  $b^*$  and  $r^*$  – [3 points]****7.2.4 Describe how  $b^*$  and  $r^*$  affect task performance – [7 points]**

**7.2.5 Configurations with optimal  $b^*$  and  $r^*$  – [3 points]**

Q7.2.5

**7.2.6 Plot for four runs with optimal  $b^*$  and  $r^*$  – [7 points]**

Q7.2.6

**8 Implementing Generalized Advantage Estimation**

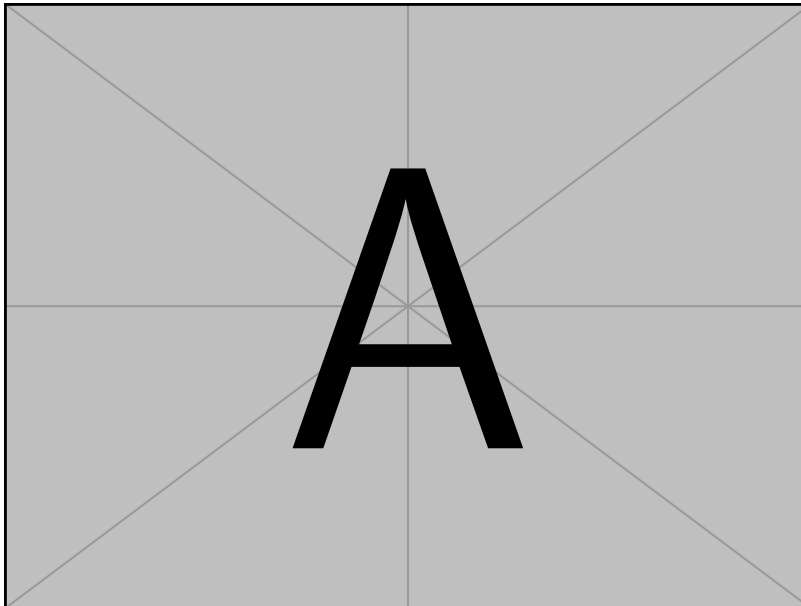
## 8.1 Experiment 5 (Hopper) – [20 points]

### 8.1.1 Configurations

Q8.1.1

### 8.1.2 Plot – [13 points]

Q8.1.2



### 8.1.3 Describe how $\lambda$ affects task performance – [7 points]

Q8.1.3



## 9 Bonus! (optional)

### 9.1 Parallelization – [15 points]

Q9.1

Difference in training time:

### 9.2 Multiple gradient steps – [5 points]

Q9.1

