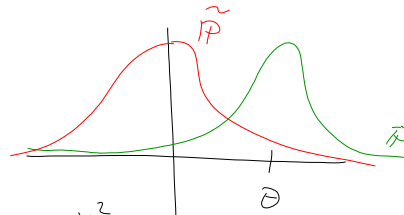


$$\mathbb{P}: X \sim N(0, 1)$$

$$Y = X + \theta \Rightarrow Y \sim N(\theta, 1)$$

$$\tilde{\mathbb{P}}: Y \sim N(0, 1)$$



$$Z = \frac{d\tilde{\mathbb{P}}}{d\mathbb{P}} = \frac{\frac{1}{\sqrt{2\pi}} e^{-\frac{y^2}{2}}}{\frac{1}{\sqrt{2\pi}} e^{-\frac{(y-\theta)^2}{2}}}$$

$$= e^{-y\theta + \frac{\theta^2}{2}}$$

$$\begin{aligned} \tilde{\mathbb{P}}(Y \leq a) &= \int_{Y \leq a} Z d\mathbb{P} \\ &= \int_{-\infty}^a \underbrace{e^{-y\theta + \frac{\theta^2}{2}}}_{Z} \underbrace{\frac{1}{\sqrt{2\pi}} e^{-\frac{(y-\theta)^2}{2}}}_{d\mathbb{P}} dy \\ &= \int_{-\infty}^a \frac{1}{\sqrt{2\pi}} e^{-\frac{(y^2 - 2y\theta + \theta^2)}{2} - y\theta + \frac{\theta^2}{2}} dy \\ &= \int_{-\infty}^a \frac{1}{\sqrt{2\pi}} e^{-\frac{y^2}{2}} dy \end{aligned}$$

$$Z = \frac{d\tilde{\mathbb{P}}}{d\mathbb{P}} = \frac{\frac{1}{\sqrt{2\pi}} e^{-\frac{(x+\theta)^2}{2}}}{\frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}}} \quad X = Y - \theta$$

$$= e^{-x\theta - \frac{\theta^2}{2}}$$

$$\begin{aligned} \tilde{\mathbb{P}}(Y \leq a) &= \int_{Y \leq a} Z d\mathbb{P} \\ &= \int_{X+\theta \leq a} e^{-x\theta - \frac{\theta^2}{2}} \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} dx \\ &= \int_{-\infty}^{a-\theta} \frac{1}{\sqrt{2\pi}} e^{-\frac{(x+\theta)^2}{2}} dx \\ &\quad y = x + \theta \\ &\quad dy = dx \\ &= \int_{-\infty}^a \frac{1}{\sqrt{2\pi}} e^{-\frac{y^2}{2}} dy \end{aligned}$$

$$\begin{aligned}
& \int_A \frac{1}{z(s)} E[Y z(t) | \mathcal{H}(s)] d\tilde{P} \\
&= \int_{\Omega} \frac{1_{\{A\}}}{z(s)} E[Y z(t) | \mathcal{H}(s)] d\tilde{P} \\
&= \tilde{E} \left[\frac{1}{z(s)} E[1_{\{A\}} Y z(t) | \mathcal{H}(s)] \right] \\
&\quad X = \frac{1}{z(s)} E[1_{\{A\}} Y z(t) | \mathcal{H}(s)] \\
&\quad \tilde{E}[X] = E[X z(s)] \\
&= E[E[1_{\{A\}} Y z(t) | \mathcal{H}(s)]] \\
&= E[1_{\{A\}} Y z(t)] \\
&= \tilde{E}[1_{\{A\}} Y] \\
&= \int_{\Omega} 1_{\{A\}} Y d\tilde{P} = \int_A Y d\tilde{P}
\end{aligned}$$

$$Z(t) = e^{-\frac{1}{2} \int_0^t \theta^2(u) du - \int_0^t \theta(u) dW(u)}$$

$$dZ(t) = ?$$

$$X(t) = X(0) + \int_0^t \Delta(u) dW(u) + \int_0^t \Gamma(u) du$$

$$dX(t) = \Delta(t) dW(t) + \cancel{\Gamma(t) dt}$$

$$\begin{aligned} E[X(t) | \mathcal{H}(s)] &= X(0) + \int_0^s \Delta(u) dW(u) \\ &\quad + E\left[\int_0^t \Gamma(u) du \mid \mathcal{H}(s)\right] \\ &= X(s) \quad \text{if } \Gamma(t) = 0 \end{aligned}$$

$$dY(t) = \frac{Y(t)^2}{(t+1)^2} \cos(Y(t)) dM(t)$$

$$Y(t) - Y(0) = \int_0^t \frac{Y(u)^2}{(u+1)^2} \cos(Y(u)) dM(u)$$

$$Y(t) = Y(0) + \int_0^t \frac{Y(u)^2}{(u+1)^2} \cos(Y(u)) dM(u)$$

$$E[Y(t) | \mathcal{H}(s)] = Y(s)$$

$$Z(t) = e^{X(t)} \quad \text{where } X(t) = -\int_0^t \theta(u) dW(u) - \frac{1}{2} \int_0^t \theta^2(u) du$$

$$dX(t) = -\theta(t) dW(t) - \frac{1}{2} \theta^2(t) dt$$

$$\begin{aligned} dZ(t) &= Z(t) dX(t) + \frac{1}{2} Z(t) (dX(t))^2 \\ &= -Z(t) \theta(t) dW(t) - \frac{1}{2} Z(t) \theta^2(t) dt \\ &\quad + \frac{1}{2} Z(t) \theta^2(t) dt \\ &= -Z(t) \theta(t) dW(t) \end{aligned}$$

$$Z = Z(T)$$

$$E\{Z\} = E\{Z(T)\} = E\{Z(T) | \mathcal{H}(0)\} = Z(0) = 1$$

$$\begin{aligned}
 \tilde{w}(0) &= 0 \\
 [\tilde{w}, \tilde{w}](t) &= t \\
 \text{cont. paths.} \\
 \tilde{E}[\tilde{w}(t) | \mathcal{H}(s)] &= \tilde{w}(s)
 \end{aligned}
 \quad
 \begin{aligned}
 \tilde{w}(0) &= w(0) + \int_0^0 \theta(u) du = 0 \\
 \tilde{w}(t) &= w(t) + \int_0^t \theta(u) du \\
 d\tilde{w}(t) &= dw(t) + \theta(t) dt \\
 (d\tilde{w}(t))^2 &= dt \\
 \int_0^t (d\tilde{w}(u))^2 &= t
 \end{aligned}$$

$$\tilde{E}[\tilde{w}(t) | \mathcal{H}(s)] = \frac{1}{z(s)} E[\tilde{w}(t) z(t) | \mathcal{H}(s)]$$

So $\tilde{w}(t)$ is \tilde{P} -Martingale if $\tilde{w}(t)z(t)$ is a P -Mart.

$$\begin{aligned}
 d(\tilde{w}(t)z(t)) &= z(t)d\tilde{w}(t) + \tilde{w}(t)dz(t) \\
 &\quad + dz(t)d\tilde{w}(t) \\
 &= z(t)(dw(t) + \theta(t)dt) \\
 &\quad - \tilde{w}(t)z(t)\theta(t)dw(t) \\
 &\quad + (-\theta(t)z(t)dw(t))(dw(t) + \theta(t)dt) \\
 &= z(t)dw(t) + z(t)\theta(t)dt \\
 &\quad - \tilde{w}(t)z(t)\theta(t)dw(t) \\
 &\quad - \theta(t)z(t)dt - 0 \\
 &= (z(t) - \tilde{w}(t)z(t)\theta(t))dw(t)
 \end{aligned}$$

$$D(t)S(t) = e^{-\int_0^t R(u) du} S(0) e^{\int_0^t (\alpha(u) - \frac{\sigma^2(u)}{2}) du + \int_0^t \sigma(u) dW(u)}$$

$$= S(0) e^{\int_0^t (\alpha(u) - R(u) - \frac{\sigma^2(u)}{2}) du + \int_0^t \sigma(u) dW(u)}$$

$$d(D(t)S(t)) = D(t)dS(t) + S(t)dD(t) + dD(t)dS(t)$$

$$= D(t)\alpha(t)S(t)dt + D(t)\sigma(t)S(t)dW(t) + -R(t)D(t)S(t)dt + 0$$

$$= D(t)S(t)(\alpha(t) - R(t))dt + D(t)S(t)\sigma(t)dW(t)$$

$$= D(t)S(t)\sigma(t) \left(dW(t) + \frac{(\alpha(t) - R(t))}{\sigma(t)} dt \right)$$

$$\Theta(t) = \frac{\alpha(t) - R(t)}{\sigma(t)} \Rightarrow dW(t) + \Theta(t)dt$$

$$d\tilde{W}(t)$$

GBM:

$$\Theta(t) = \frac{\alpha - r}{\sigma}$$

$$\tilde{W}(t) = W(t) + \int_0^t \frac{\alpha - r}{\sigma} du$$

$$= W(t) + \left(\frac{\alpha - r}{\sigma}\right)t$$

$$W(t) = \tilde{W}(t) - \left(\frac{\alpha - r}{\sigma}\right)t$$

$$S(t) = S(0) e^{(\alpha - \frac{\sigma^2}{2})t + \sigma W(t)}$$

$$= S(0) e^{(\alpha - \frac{\sigma^2}{2})t + \sigma(\tilde{W}(t) - (\frac{\alpha - r}{\sigma})t)}$$

$$= S(0) e^{(r - \frac{\sigma^2}{2})t + \sigma \tilde{W}(t)}$$

$$\tilde{\mathbb{E}} \left\{ e^{-rT} (S(T) - K)_+ \right\}$$

$$= \tilde{\mathbb{E}} \left\{ e^{-rT} \left(S(0) e^{(r - \frac{\sigma^2}{2})T + \sigma \tilde{W}(T)} - K \right)_+ \right\}$$