

# ‘Oumuamua, Pioneer anomaly and solar mass with Time Relativity

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**Abstract:** The theory of Time relativity explains well the weird behavior of the interstellar object ‘Oumuamua. I find that the real solar mass is slightly higher than today’s value, which caused the mysterious Speed Boost of which the value should be  $0.217 \text{ mm/s}$  above the prediction at perihelion. Time relativity confirms that ‘Oumuamua should slow down less than prediction, in proportion of which the difference is  $4.28 \times 10^{-8}$  near the Sun. For Pioneer anomaly I have computed the gap between real and predicted acceleration and found the value  $8.70 \times 10^{-10}$  which is very close to the observation  $(8.74 \pm 1.33) \times 10^{-10} \text{ m/s}^2$ .

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The mysterious behavior of the interstellar object ‘Oumuamua confuses scientists. In the past, the manmade Pioneer spacecrafts were also found to deviate from expected Newtonian trajectory. The theory of Time relativity that I develop provides a theoretical explanation to these phenomena.

In Time relativity the transformation of coordinates is the system (1) which is the adjunction of the system (12) given in « [Time relativity transformation of coordinates](#) » with the identity of y and z. The transformation of the x-component of velocity is the equation (2) which is the equation (19) given in « [Time relativity transformation of velocity](#) ». Below we will create the transformation of the velocity vector by deriving the transformation of the y and z components of velocity.

$$\begin{aligned} x_2 &= x_1 - ut_1 \\ y_2 &= y_1 \\ z_2 &= z_1 \quad (1) \\ t_2 &= t_1 \sqrt{1 - \frac{u^2}{c^2}} \\ v_{x,2} &= \frac{v_{x,1} - u}{\sqrt{1 - \frac{u^2}{c^2}}} \quad (2) \end{aligned}$$

## 1. Relativistic kinematics

### a) Y and Z components of velocity

Let frame 1 be a stationary frame of reference in which the inertial frame 2 moves at the velocity  $u$  in the x direction, see Figure 1. Let  $q$  be an object moving in the frame 2 at the velocity  $v_{y,2}$  in the y direction. During an infinitesimal time interval  $dt_2$ ,  $q$  has moved the infinitesimal distance  $dy_2$ , see Figure 2. So, the y-component of velocity in frame 2 equals  $dy_2/dt_2$ , see equation (3).

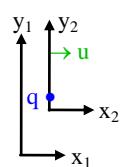


Figure 1

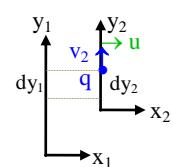


Figure 2

For the same motion, q has moved the infinitesimal distance  $dy_1$  during the time interval  $dt_1$  in frame 1. Because there is no length contraction in the y direction, we have  $dy_1 = dy_2$  (see Figure 2) and write equation (4) where the term  $dy_1/dt_1$  is the y-component of velocity in frame 1,  $v_{y,1}$ , see equation (5).

The ratio  $dt_1/dt_2$  is given in equation (6) which is obtained using the time equation of the system (1). We introduce equation (6) in to (4), which becomes equation (7), the relation between the y-components of velocity in frames 1 and 2.

The z-components of velocity in frame 1 and 2 are  $v_{z,1}$  and  $v_{z,2}$  and are related in the same way as for y-components, see equation (8).

### b) Velocity vector

Let  $\mathbf{i}$ ,  $\mathbf{j}$  and  $\mathbf{k}$  be the unit vectors in the x, y and z directions. By convention, vectors are written in boldface letters. The velocity vector of q in frame 2 is written in equations (9) in which we substitute equations (2), (7) and (8) for the x, y and z components and obtain equation (10). The velocity vector of q in frame 1 is written in equations (11), which we substitute for the corresponding terms in equation (10), in which we also substitute  $\mathbf{u}$  for  $ui$ , with  $\mathbf{u}$  being the velocity vector of the frame 2 in frame 1, see equation (12). Then, equation (10) becomes equation (13).

The velocity vectors of q in frame 1 and 2 are  $\mathbf{v}_1$  and  $\mathbf{v}_2$  and are related through equation (13).

### c) Acceleration vector

Suppose that the velocity of q is 0 at time  $t_2$  in frame 2 and is  $\mathbf{u}$  in frame 1. After an infinitesimal time interval  $dt_2$ , q's velocity becomes  $\mathbf{v}_2$  in frame 2. At the same moment, q's velocity becomes  $\mathbf{v}_1$  in frame 1.

Because  $dt_2$  is infinitesimal the vectors  $\mathbf{v}_2$  and  $\mathbf{v}_1 - \mathbf{u}$  are infinitesimal too and can be written in differential form as  $d\mathbf{v}_2$  and  $d\mathbf{v}_1$  in equations (14), which we introduce into equation (13) to obtain equation (15), of which both sides are divided by  $dt_2$  to make equation (16), in which the ratio  $dt_1/dt_2$  is substituted by equation (6) and then, equation (16) becomes equation (17), in which we substitute  $\alpha_1$  and  $\alpha_2$  for  $\frac{d\mathbf{v}_1}{dt_2}$  and  $\frac{d\mathbf{v}_2}{dt_2}$  to get equation (18), the relation between the accelerations of the object q in frame 1 and 2.

### d) Derivative of vectors

The velocity vector of q is the time derivative of its position vector, which is  $\mathbf{X}_2$  in frame 2, see equation (19). The derivative of  $\mathbf{X}_2$  is derived in equation (20), where the coordinates  $(x_2, y_2, z_2)$  are written in terms of  $(x_1, y_1, z_1)$  the coordinates of q in frame 1 using system (1).

The position vector of q in frame 1 is  $\mathbf{X}_1$ , which is given in equation (21), which we substitute for the corresponding terms in equation (20), which then becomes equation (22). Since the derivatives of  $\mathbf{X}_1$  and  $\mathbf{X}_2$  are the velocity vectors in frame 1 and 2, we write equation (22) into equation (25) which is the equation (13).

$$v_{y,2} = \frac{dy_2}{dt_2} \quad (3)$$

$$\begin{aligned} \frac{dy_2}{dt_2} &= \frac{dy_1}{dt_2} \\ &= \frac{dy_1}{dt_1} \frac{dt_1}{dt_2} \end{aligned} \quad (4)$$

$$\frac{dy_1}{dt_1} = v_{y,1} \quad (5)$$

$$\frac{dt_1}{dt_2} = \frac{1}{\sqrt{1 - \frac{u^2}{c^2}}} \quad (6)$$

$$v_{y,2} = \frac{v_{y,1}}{\sqrt{1 - \frac{u^2}{c^2}}} \quad (7)$$

$$v_{z,2} = \frac{v_{z,1}}{\sqrt{1 - \frac{u^2}{c^2}}} \quad (8)$$

$$\mathbf{v}_2 = v_{x,2}\mathbf{i} + v_{y,2}\mathbf{j} + v_{z,2}\mathbf{k} \quad (9)$$

$$\begin{aligned} \mathbf{v}_2 &= \frac{v_{x,1} - u}{\sqrt{1 - \frac{u^2}{c^2}}}\mathbf{i} + \frac{v_{y,1}}{\sqrt{1 - \frac{u^2}{c^2}}}\mathbf{j} + \frac{v_{z,1}}{\sqrt{1 - \frac{u^2}{c^2}}}\mathbf{k} \\ &= \frac{1}{\sqrt{1 - \frac{u^2}{c^2}}} (v_{x,1}\mathbf{i} + v_{y,1}\mathbf{j} + v_{z,1}\mathbf{k} - u\mathbf{i}) \end{aligned} \quad (10)$$

$$\mathbf{v}_1 = v_{x,1}\mathbf{i} + v_{y,1}\mathbf{j} + v_{z,1}\mathbf{k} \quad (11)$$

$$\mathbf{u} = u \cdot \mathbf{i} \quad (12)$$

$$\mathbf{v}_2 = \frac{\mathbf{v}_1 - \mathbf{u}}{\sqrt{1 - \frac{u^2}{c^2}}} \quad (13)$$

$$d\mathbf{v}_2 = \mathbf{v}_2 - 0 \quad (14)$$

$$d\mathbf{v}_1 = \mathbf{v}_1 - \mathbf{u}$$

$$d\mathbf{v}_2 = \frac{d\mathbf{v}_1}{\sqrt{1 - \frac{u^2}{c^2}}} \quad (15)$$

$$\frac{d\mathbf{v}_2}{dt_2} = \frac{1}{\sqrt{1 - \frac{u^2}{c^2}}} \frac{d\mathbf{v}_1}{dt_1} \frac{dt_1}{dt_2} \quad (16)$$

$$\frac{d\mathbf{v}_2}{dt_2} = \frac{1}{1 - \frac{u^2}{c^2}} \frac{d\mathbf{v}_1}{dt_1} \quad (17)$$

$$\alpha_2 = \frac{\alpha_1}{1 - \frac{u^2}{c^2}} \quad (18)$$

$$\mathbf{X}_2 = x_2\mathbf{i} + y_2\mathbf{j} + z_2\mathbf{k} \quad (19)$$

$$\begin{aligned} \frac{d\mathbf{X}_2}{dt_2} &= \frac{d(x_2\mathbf{i} + y_2\mathbf{j} + z_2\mathbf{k})}{dt_2} \\ &= \frac{d((x_1 - ut_1)\mathbf{i} + y_1\mathbf{j} + z_1\mathbf{k})}{dt_2} \frac{dt_1}{dt_2} \\ &= \frac{1}{\sqrt{1 - \frac{u^2}{c^2}}} \frac{d(x_1\mathbf{i} + y_1\mathbf{j} + z_1\mathbf{k} - ut_1\mathbf{i})}{dt_1} \end{aligned} \quad (20)$$

$$\mathbf{X}_1 = x_1\mathbf{i} + y_1\mathbf{j} + z_1\mathbf{k} \quad (21)$$

$$\frac{d\mathbf{X}_2}{dt_2} = \frac{1}{\sqrt{1 - \frac{u^2}{c^2}}} \left( \frac{d\mathbf{X}_1}{dt_1} - \mathbf{u} \right) \quad (22)$$

We can derive the acceleration vector also by taking the time derivative of the velocity vector of  $\mathbf{q}$ , see equation (23). Because frame 2 is inertial,  $\mathbf{u}$  is constant. The derivative of  $\mathbf{v}_1$  and  $\mathbf{v}_2$  are the acceleration vector  $\boldsymbol{\alpha}_1$  and  $\boldsymbol{\alpha}_2$ , then, equation (23) becomes (26), which is the equation (18).

In summary, the transformation of position vector is equation (24) (see system (1)). The derivative of the transformation of position vector is the transformation of velocity vector equation (25); the derivative of the transformation of velocity vector is the transformation of acceleration vector equation (26). We see that the transformations in Time relativity form a consistent vector system. In the contrary, the transformations in Special relativity do not. For example, the velocity-addition formula cannot be directly derived in vector form, neither can give acceleration vector.

## 2. Gravitation

### a) Relativistic orbit

The gravitation of a mass  $M$  transfers impulse to other mass. According to Newton's gravitational law, the impulse that  $M$  transfers to the mass  $m_0$  during an infinitesimal time interval  $dt_1$  in frame 1 is the  $d\mathbf{P}_1$  defined by equation (27), with  $M$  and  $m_0$  being the respective rest masses,  $r_M$  the distance from  $M$  to  $m_0$ ,  $\mathbf{e}_r$  the unit vector pointing from  $M$  to  $m_0$  and  $g$  the gravitational constant.

Let frame 2 be an inertial frame which moves momentarily with  $m_0$ . The impulse that  $m_0$  feels in frame 2 equals  $m_0 d\mathbf{v}_2$  with  $d\mathbf{v}_2$  being the change of velocity of  $m_0$  in frame 2 and is the  $d\mathbf{P}_2$  in equation (28) where we have substituted equation (15) for  $d\mathbf{v}_2$ .

The impulse on  $m_0$  in frames 1 and 2 refer to the same impulse. So,  $d\mathbf{P}_1 = d\mathbf{P}_2$ , see equation (29). Then, we equate equation (27) with (28) and obtain equation (30) which we transform into equation (31).

$\frac{d\mathbf{v}_1}{dt_1}$  is the acceleration of  $m_0$  in frames 1 of which the magnitude is  $-\alpha_R$ , see equation (32). Combining Equations (31) and (32) we obtain the expression of  $\alpha_R$  in equation (33).

The theoretical orbit of  $m_0$  in the gravitational field of  $M$  that obeys Newtonian law is called Newtonian orbit. The one that obeys Time relativity is called relativistic orbit. The orbital acceleration of the relativistic orbit is  $\alpha_R$ , that of the Newtonian orbit is  $\alpha_N$  given in equation (34), which we introduce in to equation (33) to express  $\alpha_R$  in terms of  $\alpha_N$  in equation (35).

Notice the coefficient  $\sqrt{1 - \frac{u^2}{c^2}}$  in equation (35), it comes from the conversion of time from frame 1 to 2 and has nothing to do with relativistic mass.

### b) Pericenter of orbit

Pericenter is the point of an orbit that is closest to the attracting body. The center and radius of curvature of the orbit at the pericenter are  $C$  and  $r_c$  which equal that of the circle of curvature at the pericenter, see Figure 3.

$$\begin{aligned} \frac{d\mathbf{v}_2}{dt_2} &= \frac{d}{dt_2} \left( \frac{\mathbf{v}_1 - \mathbf{u}}{\sqrt{1 - \frac{u^2}{c^2}}} \right) \\ &= \frac{1}{\sqrt{1 - \frac{u^2}{c^2}}} \frac{d\mathbf{v}_1}{dt_1} \frac{dt_1}{dt_2} \\ &= \frac{1}{1 - \frac{u^2}{c^2}} \frac{d\mathbf{v}_1}{dt_1} \end{aligned} \quad (23)$$

$$X_2 = X_1 - \mathbf{u}t_1 \quad (24)$$

$$\begin{cases} \frac{dX_1}{dt_1} = \mathbf{v}_1 \\ \frac{dX_2}{dt_2} = \mathbf{v}_2 \end{cases} \Rightarrow \mathbf{v}_2 = \frac{\mathbf{v}_1 - \mathbf{u}}{\sqrt{1 - \frac{u^2}{c^2}}} \quad (25)$$

$$\begin{cases} \frac{d\mathbf{v}_1}{dt_1} = \boldsymbol{\alpha}_1 \\ \frac{d\mathbf{v}_2}{dt_2} = \boldsymbol{\alpha}_2 \end{cases} \Rightarrow \boldsymbol{\alpha}_2 = \frac{\boldsymbol{\alpha}_1}{1 - \frac{u^2}{c^2}} \quad (26)$$

$$d\mathbf{P}_1 = \left( -\frac{gM \cdot m_0}{r_M^2} \mathbf{e}_r \right) dt_1 \quad (27)$$

$$d\mathbf{P}_2 = m_0 d\mathbf{v}_2 = \frac{m_0 d\mathbf{v}_1}{\sqrt{1 - \frac{u^2}{c^2}}} \quad (28)$$

$$d\mathbf{P}_1 = d\mathbf{P}_2 \quad (29)$$

$$-\frac{gM \cdot m_0 \cdot dt_1}{r_M^2} \mathbf{e}_r = \frac{m_0 d\mathbf{v}_1}{\sqrt{1 - \frac{u^2}{c^2}}} \quad (30)$$

$$-\frac{gM}{r_M^2} \mathbf{e}_r = \frac{1}{\sqrt{1 - \frac{u^2}{c^2}}} \frac{d\mathbf{v}_1}{dt_1} \quad (31)$$

$$\frac{d\mathbf{v}_1}{dt_1} = \boldsymbol{\alpha}_r = -\alpha_R \mathbf{e}_r \quad (32)$$

$$\alpha_R = \frac{gM}{r_M^2} \sqrt{1 - \frac{u^2}{c^2}} \quad (33)$$

$$\alpha_N = \frac{gM}{r_M^2} \quad (34)$$

$$\alpha_R = \alpha_N \sqrt{1 - \frac{u^2}{c^2}} \quad (35)$$

$m_0$  follows momentarily the circle of curvature at the pericenter. On a relativistic orbit,  $m_0$ 's velocity and acceleration are  $u_R$  and  $\alpha_R$  which are related by equation (36). On a Newtonian orbit,  $m_0$ 's velocity and acceleration are  $u_N$  and  $\alpha_N$  which are related by equation (37). Introducing equations (36) and (37) in to (35), we obtain equation (38), which is then transformed into equation (39) then (40). The solution of equation (40) is given in equation (41), with the negative solution been dropped off because  $\frac{u_R^2}{c^2}$  is always positive. Equation (41) expresses the velocity of  $m_0$  at the pericenter of its relativistic orbit in the gravitational field of  $M$ .

- Large  $r_M$

When  $\left(\frac{2c^2 r_M^2}{gM r_c}\right)^2$  is much larger than 1, the square root can be simplified as in equation (42), which makes equation (41) to become (43). We see that, when  $r_M \rightarrow \infty$ ,  $u_R^2$  reduces to the Newtonian solution while being always smaller than it, see equation (44).

- Small  $r_M$

When  $\left(\frac{2c^2 r_M^2}{gM r_c}\right)^2$  is much smaller than 1, the square root can be simplified as in equation (45), which makes equation (41) to become equation (46), which shows that, when  $r_M \rightarrow 0$ ,  $\frac{u_R^2}{c^2}$  reduces to nearly 1 while being always smaller than 1. So, when  $r_M$  the distance between  $M$  and  $m_0$  decreases towards zero, the orbital velocity of  $m_0$  tends to the speed of light  $c$  without ever reaching it, see equation (47).

- Circular orbit

$M$  coincides with  $C$  in Figure 3 and  $r_c = r_M$  in the above solutions.

### 3. Solar mass

The mass of the Sun is not measured by weighting, but derived from the parameters of Earth's orbit which is nearly circular. Let  $r_M$  be the radius of the Earth's orbit and  $u_E$  its orbital velocity. By equating the orbital acceleration of the Earth (see equation (36)) with its Newtonian gravitational acceleration (see equation (34)), we obtain equation (48) which gives the today's used value of the mass of the Sun,  $M_0$ , in equation (49).

According to Time relativity, the orbital acceleration of the Earth is given by equation (33). So, by equating equation (36) with (33), we obtain equation (50) which gives the mass of the Sun  $M_R$  in equation (51), which is derived using Time relativity.

$$\frac{u_E^2}{r_M} = \frac{gM_0}{r_M^2} \quad (48)$$

$$M_0 = \frac{r_M u_E^2}{g} \quad (49)$$

$$\frac{u_E^2}{r_M} = \frac{gM_R}{r_M^2} \sqrt{1 - \frac{u_E^2}{c^2}} \quad (50)$$

$$M_R = \frac{r_M u_E^2}{g \sqrt{1 - \frac{u_E^2}{c^2}}} \quad (51)$$

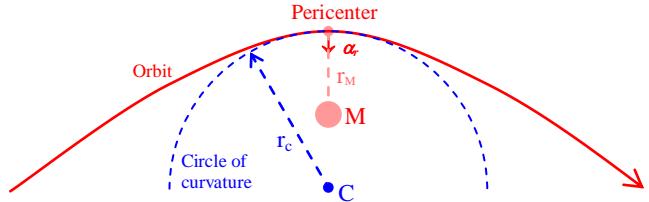


Figure 3

$$\frac{u_R^2}{r_c} = \alpha_R \quad (36)$$

$$\frac{u_N^2}{r_c} = \alpha_N = \frac{gM}{r_M^2} \quad (37)$$

$$\frac{u_R^2}{r_c} = \frac{u_N^2}{r_c} \sqrt{1 - \frac{u_R^2}{c^2}} \quad (38)$$

$$\left(\frac{u_R^2}{c^2}\right)^2 = \left(\frac{u_N^2}{c^2}\right)^2 \left(1 - \frac{u_R^2}{c^2}\right) \quad (39)$$

$$\left(\frac{c^2}{u_N^2}\right)^2 \left(\frac{u_R^2}{c^2}\right)^2 + \frac{u_R^2}{c^2} - 1 = 0 \quad (40)$$

$$\frac{u_R^2}{c^2} = \frac{\sqrt{1 + 4 \left(\frac{c^2}{u_N^2}\right)^2} - 1}{2 \left(\frac{c^2}{u_N^2}\right)} \quad (41)$$

$$\left(\frac{2c^2}{u_N^2}\right)^2 = \left(\frac{2c^2 r_M^2}{gM r_c}\right)^2 \gg 1 \Rightarrow \sqrt{\left(\frac{2c^2}{u_N^2}\right)^2 + 1} \approx \frac{2c^2}{u_N^2} \quad (42)$$

$$\begin{aligned} \frac{u_R^2}{c^2} &\approx \frac{\frac{2c^2}{u_N^2} - 1}{2 \left(\frac{c^2}{u_N^2}\right)^2} \\ &= \frac{u_N^2}{c^2} - \frac{1}{2} \left(\frac{u_N^2}{c^2}\right)^2 \end{aligned} \quad (43)$$

$$u_R \xrightarrow[r_M \rightarrow \infty]{} u_N \quad (44)$$

$$\begin{aligned} \left(\frac{2c^2}{u_N^2}\right)^2 &= \left(\frac{2c^2 r_M^2}{gM r_c}\right)^2 \ll 1 \Rightarrow \\ \sqrt{1 + \left(\frac{2c^2}{u_N^2}\right)^2} & \end{aligned} \quad (45)$$

$$\begin{aligned} &\approx 1 + \frac{1}{2} \left(\frac{2c^2}{u_N^2}\right)^2 - \frac{1}{8} \left(\frac{2c^2}{u_N^2}\right)^4 \\ \frac{u_R^2}{c^2} &\approx \frac{\frac{1}{2} \left(\frac{2c^2}{u_N^2}\right)^2 - \frac{1}{8} \left(\frac{2c^2}{u_N^2}\right)^4}{2 \left(\frac{c^2}{u_N^2}\right)^2} \\ &= 1 - \left(\frac{c^2}{u_N^2}\right)^2 < 1 \end{aligned} \quad (46)$$

$$u_R < c, \quad u_R \xrightarrow[r_M \rightarrow 0]{} c \quad (47)$$

The ratio  $M_R/M_0$  is given in equation (52), which shows that  $M_R$  is bigger than  $M_0$ , that is, the mass of the Sun derived using Time relativity is bigger than its today's value. The relative gap between  $M_R$  and  $M_0$  is defined as  $\frac{M_R}{M_0} - 1$  of which the numerical value is

computed in equation (53) using the orbital velocity of the Earth 29.8 km/s, which gives  $4.94 \times 10^{-9}$ .

$$\frac{M_R}{M_0} = \frac{1}{\sqrt{1 - \frac{u_E^2}{c^2}}} \approx 1 + \frac{u_E^2}{2c^2} > 1$$

$$u_E = 29.8 \text{ km/s} \Rightarrow$$

#### 4. Anomalies in space

##### a) 'Oumuamua

###### • Speed Boost

The interstellar object '[Oumuamua](#)' was discovered on Oct. 19, 2017, which is 40 days after it has passed the perihelion on Sept. 9, 2017 at the velocity [87.71 km/s](#). It goes a [tiny bit faster](#) than it should have if the only effect on its motion was the Sun's gravity, which is not predicted by current theory [1][2][3][4][5][6]. But this [Speed Boost](#) is predicted by Time relativity.

Let  $u_R$  be the real orbital velocity of 'Oumuamua caused by  $M_R$ , which is expressed in equation (54) in terms of the real orbital acceleration  $\alpha_R$  and  $r_c$  the radius of curvature of its orbit at the perihelion. With  $M_0$ , the orbital velocity would be  $u_0$  which is expressed in equation (55) in terms of the corresponding orbital acceleration  $\alpha_0$ . We divide equation (54) with (55) to obtain the ratio of the 2 velocities squared in equation (56).

$$u_R^2 = \alpha_R r_c \quad (54)$$

$$u_0^2 = \alpha_0 r_c \quad (55)$$

$$\frac{u_R^2}{u_0^2} = \frac{\alpha_R}{\alpha_0} \quad (56)$$

$$\alpha_R = kM_R \quad (57)$$

$$\alpha_0 = kM_0 \quad (58)$$

$$\frac{u_R^2}{u_0^2} = \frac{M_R}{M_0} \quad (59)$$

The gravitational acceleration is proportional to the mass, so,  $\alpha_R$  and  $\alpha_0$  can be written as in equations (57) and (58). Introducing equations (57) and (58) in to (56), we get equation (59).

The difference of velocity  $u_R - u_0$  is derived in equation (60). Because the values of  $u_R$  and  $u_0$  are very close, we can write  $u_R + u_0 \approx 2u_0$  in equation (61), which is introduced along with equation (59) in to equation (60) to get equation (62). Using the numerical values of  $u_0$  and  $\frac{M_R}{M_0} - 1$ , we find the value of difference of velocity  $u_R - u_0 = 0.217 \text{ mm/s}$  in equation (63).

$$u_R - u_0 = \frac{u_R^2 - u_0^2}{u_R + u_0} = \frac{u_0^2}{u_R + u_0} \left( \frac{u_R^2}{u_0^2} - 1 \right) \quad (60)$$

$$u_R \approx u_0 \Rightarrow u_R + u_0 = 2u_0 \quad (61)$$

$$u_R - u_0 \approx \frac{u_0}{2} \left( \frac{M_R}{M_0} - 1 \right) \quad (62)$$

$$\begin{aligned} &\text{Perihelion} \\ &u_0 = 87.71 \text{ km/s} \Rightarrow \end{aligned} \quad (63)$$

$$u_R - u_0 = 0.217 \text{ mm/s}$$

###### • Resistance to slowdown

'Oumuamua slows down under the Sun's gravity, but not as fast as predicted by celestial mechanics [1][2][3][4][5][6]. I call this phenomenon Resistance to slowdown effect, which is predicted by Time relativity.

In fact, as relativistic mass is bigger than rest mass, the fast moving 'Oumuamua carries more kinetic energy than Newtonian theory predicts. So, 'Oumuamua looks moving slower when carrying the kinetic energy that Newtonian theory predicts.

Let  $u_N$  and  $E_N$  be the Newtonian velocity and kinetic energy of 'Oumuamua.  $E_N$  is expressed in equation (64). When it slows down to the velocity  $u_N^*$ , its kinetic energy is  $E_N^*$  and the decrease of velocity squared is expressed in equation (65).

$$E_N = \frac{m_0 u_N^2}{2} \quad (64)$$

$$u_N^* - u_N^2 = \frac{2}{m_0} (E_N^* - E_N) \quad (65)$$

$$E_R = m_0 c^2 \left( 1 - \sqrt{1 - \frac{u_R^2}{c^2}} \right) \quad (66)$$

$$\left( 1 - \frac{E_R}{m_0 c^2} \right)^2 = 1 - \frac{u_R^2}{c^2} \quad (67)$$

The real kinetic energy carried by 'Oumuamua moving at the real velocity  $u_R$  is  $E_R$ . According to Time relativity,  $E_R$  is given in equation (66), which is the equation (44) in « [Velocity, mass, momentum and energy of an accelerated object](#) » in relativity ». When 'Oumuamua slows down to the velocity  $u_N^*$ , its kinetic energy is  $E_N^*$ .

Equation (66) is transformed into equation (67) for deriving the decrease of velocity squared, see equations (68) to (70).

$$\left(1 - \frac{E_R^*}{m_0 c^2}\right)^2 - \left(1 - \frac{E_R}{m_0 c^2}\right)^2 = \left(1 - \frac{u_R^{*2}}{c^2}\right) - \left(1 - \frac{u_R^2}{c^2}\right) \quad (68)$$

$$c^2 \left(1 - \frac{E_R^*}{m_0 c^2} - 1 + \frac{E_R}{m_0 c^2}\right) \left(1 - \frac{E_R^*}{m_0 c^2} + 1 - \frac{E_R}{m_0 c^2}\right) \\ = -u_R^{*2} + u_R^2 \quad (69)$$

$$u_R^{*2} - u_R^2 = \frac{E_R^* - E_R}{m_0} \left(2 - \frac{E_R^* + E_R}{m_0 c^2}\right) \quad (70)$$

Let us denote the differences of velocity squared in the form  $\Delta(u^2)$ , see equation (71). We compute the ratio of these differences by dividing equation (70) with equation (65), which gives equation (72).

Suppose that, when going from one point to another, 'Oumuamua gains the quantity of potential energy  $\Delta U$ , which equals the loss of kinetic energy,  $E_R^* - E_R$  for Time relativity and  $E_N^* - E_N$  for Newtonian theory. Because  $\Delta U$  is the same for the 2 cases, we have  $E_R^* - E_R = E_N^* - E_N$ , see equation (73). Also, the values of  $E_R^*$  and  $E_R$  equal nearly the Newtonian kinetic energy, so we can write equation (74). Introducing equations (73) and (74) in to (72) we get equation (75) which is smaller than 1. So, the decrease of velocity for Time relativity is smaller than the Newtonian one, that is, 'Oumuamua "resists to slowdown".

We compute this effect when the decrease of velocity is very small, so we write equation (75) into (76). We differentiate  $\Delta(u_R^2)$  and  $\Delta(u_N^2)$  and simplify the ratio  $\frac{\Delta(u_R^2)}{\Delta(u_N^2)}$  into  $\frac{\Delta u_R}{\Delta u_N}$  because the orbital velocity for Time relativity is very close to the Newtonian one, see equation (77). Then, equation (76) becomes equation (78), which quantifies the relative gap of decrease of velocity between Time relativity and Newtonian predictions.

Let us call  $\frac{\Delta u_R}{\Delta u_N} - 1$  Resistance to slowdown and compute its value in equation (79). It equals  $-4.28 \times 10^{-8}$  at perihelion where the velocity of 'Oumuamua is 87.71 km/s. In outer space where the Sun's gravity is very weak, the velocity of 'Oumuamua is [26.33 km/s](#)<sup>[1]</sup> and its Resistance to slowdown is  $-3.86 \times 10^{-9}$ . It will be interesting to compare the theoretical value  $-4.28 \times 10^{-8}$  with the observation at perihelion<sup>[1][2][3][4][5][6]</sup>.

$$\text{Equation (75)} \Rightarrow \Delta(u_R^2) - \Delta(u_N^2) \approx -\frac{u_R^{*2} + u_R^2}{4c^2} \Delta(u_N^2) \quad (80)$$

$$= -\frac{u_R^{*2} + u_R^2}{4c^2} (u_N^{*2} - u_N^2)$$

$$u_R = u_N \Rightarrow \Delta(u_R^2) - \Delta(u_N^2) = (u_R^{*2} - u_R^2) - (u_N^{*2} - u_N^2)$$

$$= u_R^{*2} - u_N^{*2} = (u_R^* - u_N^*)(u_R^* + u_N^*)$$

Equations (80) = (81)  $\Rightarrow$

$$u_R^* - u_N^* \approx -\frac{u_R^{*2} + u_R^2}{4c^2} \frac{u_N^{*2} - u_N^2}{u_R^* + u_N^*} \quad (82)$$

$$u_N \approx u_R \approx 87.71 \text{ km/s} \quad u_N^* \approx u_R^* \approx 26.33 \text{ km/s} \quad (83)$$

In outer space  
 $u_R^* - u_N^* \approx 3.1 \text{ mm/s}$

I have also computed the gap between the total decreases of velocity for Time relativity and Newtonian theory, see equations (80) to (83), which shows that changing its velocity from 87.71 km/s to 26.33 km/s, 'Oumuamua would move 3.1 mm/s faster than predicted in outer space.

### b) Pioneer anomaly

The Wikipedia page [Pioneer anomaly](#)<sup>[7]</sup> explains that while the spacecrafts [Pioneer 10](#) and [Pioneer 11](#) are escaping the Solar System, their navigational data show that they are slowing slightly more than expected, they get an additional extremely small acceleration towards the Sun which is  $\Delta\alpha = (8.74 \pm 1.33) \times 10^{-10} \text{ m/s}^2$ <sup>[7][8][9][10][11][12][13][14][15][16]</sup>.

Let us compute the Resistance to slowdown for Pioneer by using the

$$u_R^{*2} - u_R^2 = \Delta(u_R^2) \quad (71)$$

$$u_N^{*2} - u_N^2 = \Delta(u_N^2)$$

$$\frac{\Delta(u_R^2)}{\Delta(u_N^2)} = \frac{E_R^* - E_R}{E_N^* - E_N} \left(1 - \frac{E_R^* + E_R}{2m_0 c^2}\right) \quad (72)$$

$$\text{Gain in potential energy } \Delta U \quad (73)$$

$$\Delta U = E_R^* - E_R \Rightarrow \frac{E_R^* - E_R}{E_N^* - E_N} = 1$$

$$= E_N^* - E_N$$

$$E_R \approx m_0 \frac{u_R^{*2}}{2}, E_R^* \approx m_0 \frac{u_R^2}{2} \Rightarrow \frac{E_R^* + E_R}{2m_0 c^2} \approx \frac{u_R^{*2} + u_R^2}{4c^2} \quad (74)$$

$$\frac{\Delta(u_R^2)}{\Delta(u_N^2)} \approx 1 - \frac{u_R^{*2} + u_R^2}{4c^2} < 1 \quad (75)$$

$$\Delta u_R \text{ small } u_R^{*2} \approx u_R^2 \Rightarrow \frac{\Delta(u_R^2)}{\Delta(u_N^2)} - 1 \approx -\frac{u_R^2}{2c^2} \quad (76)$$

$$u_R \approx u_N \Rightarrow \frac{\Delta(u_R^2)}{\Delta(u_N^2)} \approx \frac{2u_R \Delta u_R}{2u_N \Delta u_N} \approx \frac{\Delta u_R}{\Delta u_N} \quad (77)$$

$$\frac{\Delta u_R}{\Delta u_N} - 1 \approx -\frac{u_R^2}{2c^2} \quad (78)$$

$$\text{Perihelion}$$

$$u_R = 87.71 \text{ km/s} \Rightarrow \frac{\Delta u_R}{\Delta u_N} - 1 = -4.28 \times 10^{-8}$$

$$\frac{\Delta u_R}{\Delta u_N} \quad (79)$$

$$\text{Outer space}$$

$$u_R = 26.33 \text{ km/s} \Rightarrow \frac{\Delta u_R}{\Delta u_N} - 1 = -3.86 \times 10^{-9}$$

tangential orbital acceleration which equals the change of magnitude of velocity  $\Delta u$  divided by time interval  $\Delta t$ , see equation (84) where the index R and N indicate Time relativity and Newtonian theory. We divide  $\alpha_R$  with  $\alpha_N$  in equation (85) which shows that the ratio of acceleration equals that of the change of velocity. Introducing equation (85) in to equation (78), we get equation (86).

Using the velocity of [Pioneer 10](#) on December, 30, 2005 which is [12.51 km/s](#), equation (86) gives the Resistance to slowdown for Pioneer:  $-8.70 \times 10^{-10}$ , see equation (87), which is amazingly close to the value of  $\Delta\alpha$  given in the Wikipedia page [Pioneer anomaly](#) [7]:  $(8.74 \pm 1.33) \times 10^{-10} \text{ m/s}^2$ .

However, there is a glitch: the quantity  $\frac{\alpha_R}{\alpha_N} - 1$  is dimensionless while  $\Delta\alpha$  has the dimension  $\text{m/s}^2$ . I suspect that there may be more than a pure coincidence.

There is a second glitch.  $\frac{\alpha_R}{\alpha_N} - 1 < 0$  means that  $\alpha_R$  is smaller than  $\alpha_N$  in magnitude. Because the tangential acceleration points towards the Sun while the velocity away from the Sun, a smaller acceleration means that the spacecrafts are less pulled towards the Sun. So, the resistance to slowdown effect makes the spacecrafts to slow less than expected rather than “*slowing slightly more than expected*”. Also, because the thermal radiation pressure proposed by the cited papers [7][8][9][10][11][12][13][14][15][16] pushes towards the Sun it acts against the resistance to slowdown effect.

Anyway, because the resistance to slowdown effect is observed with ‘Oumuamua and the theoretical value  $-8.70 \times 10^{-10}$  is so close to the observational value  $(8.74 \pm 1.33) \times 10^{-10} \text{ m/s}^2$ , it will be very interesting to look again into the navigational data of [Pioneer 10](#) and [Pioneer 11](#).

Just for comparison, the total acceleration due to the Sun is  $7.37 \times 10^{-7} \text{ m/s}^2$ , see equation (88). Due to Speed Boost effect (bigger solar mass, see section 4. a) ‘Oumuamua •Speed Boost) the relative increase of gravitational acceleration is  $4.94 \times 10^{-9}$ , see equation (90). The increased of acceleration is  $3.64 \times 10^{-15} \text{ m/s}^2$  towards the Sun, see equation (91).

### c) Flyby anomaly

Flyby is a common gravity assist maneuver to accelerate a spacecraft using the gravity of the Earth. It was noticed that in multiple cases, spacecrafts have been observed to gain more speed than scientists had predicted. This phenomenon is called [flyby anomaly](#) [17][18][19][20][21].

This gain in speed may have the same origin than the Speed Boost of ‘Oumuamua, except that the attracting body is the Earth. And indeed, the mass of the Earth was derived using the orbit of the Moon of which the velocity is  $1.022 \text{ km/s}$ , which makes the mass of the Earth ( $1 + 5.81 \times 10^{-12}$ ) times more massive than the today’s used value, see section 3 “Solar mass”.

## 5. Planets and Parker Solar Probe

The above cases of speed boost make reevaluating the mass of the Sun important. For doing so, we can compute the quantity  $\mu = \alpha \cdot r_M^2$  for all the planets, with  $\alpha$  being the orbital acceleration of the planet and  $r_M$  its distance from the Sun,  $\alpha$  and  $r_M$  being instantaneous values.

$$\text{Tangential acceleration } \alpha_R = \frac{\Delta u_R}{\Delta t}, \alpha_N = \frac{\Delta u_N}{\Delta t} \quad (84)$$

$$\text{Equation (77)} \Rightarrow \frac{\alpha_R}{\alpha_N} = \frac{\Delta u_R}{\Delta u_N} \quad (85)$$

$$\text{Equation (76)} \Rightarrow \frac{\alpha_R}{\alpha_N} - 1 \approx -\frac{u_R^2}{2c^2} \quad (86)$$

$$u_R = 12.51 \text{ km/s} \\ \frac{\alpha_R}{\alpha_N} - 1 \approx -8.70 \times 10^{-10} \quad (87)$$

$$M = 1.99 \times 10^{30} \text{ kg} \\ g = 6.67 \times 10^{-11} \text{ m}^3/\text{kg s}^2 \\ u_E = 29.8 \text{ km/s} \\ r_M = 89.7 \text{ AU}$$

$$|\alpha_0| = \frac{gM}{r_M^2} \\ = 7.37 \times 10^{-7} \text{ m/s}^2 \quad (88)$$

$$\text{Equation (57) and (58)} \Rightarrow \frac{\alpha_R}{\alpha_0} = \frac{M_R}{M_0} \quad (89)$$

$$\frac{\alpha_R}{\alpha_0} - 1 \approx 4.94 \times 10^{-9} \quad (90)$$

$$|\alpha_R| - |\alpha_0| \\ \approx 4.94 \times 10^{-9} |\alpha_0| \\ = 3.64 \times 10^{-15} \text{ m/s}^2 \quad (91)$$

If  $\mu$  is the same for all the planets, then the mass of the Sun is consistent with Newtonian theory as given in equation (92). If  $\mu$  varies according to equation (93) (see equation (33)), with  $i$  indicating instantaneous orbital values for the  $i^{\text{th}}$  planet, then the mass of the Sun is now undervalued and  $\mu$  will give the real mass of the Sun.

$$\begin{aligned} &\text{Newtonian} \\ &\mu = \alpha \cdot r_M^{-2} = gM \end{aligned} \quad (92)$$

Time relativity

$$\mu = \alpha \cdot r_{M,i}^{-2} = gM \sqrt{1 - \frac{u_i^2}{c^2}} \quad (93)$$

The orbital data of Mercury, Venus, Earth, Mars, Jupiter, Saturn, Uranus, Neptune exist in the archives, but I doubt that they are sufficiently precise for this work. So, new measurement is necessary. To quickly obtain high precision orbital data around the Sun, the navigation data of the [Parker Solar Probe](#) are a good source because they are precise measurement and its orbit is very elongated, which makes the value of  $r_M$  and  $u$  to vary in a large range.

Also, the orbit of the Parker Solar Probe is suitable for verifying the Resistance to slowdown effect. Indeed, its orbital velocity and tangential acceleration vary in a large range.

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