MIT CSAIL 6.819/6.869 Advances in Computer Vision Fall 2021

Problem Set 5: Texture Synthesis and Style Transfer

Posted: Wednesday, April 21, 2021 Due: Midnight, Wednesday, April 28, 2021

6.869 and 6.819 students are expected to finish all problems unless there is an additional instruction.

We provide a python notebook with the code to be completed. You can run it locally or in Colab (upload it to Google Drive and select 'open in colab') to avoid setting up your own environment. Once you finish, run the cells and download the notebook to be submitted.

Submission Instructions: Please submit a .zip file named <your kerberos>.zip. The zip file should contain two separate files: 1) a report named <your kerberos>.pdf, including your responses to all required questions with images and/or plots showing your results, 2) a file named <your kerberos>.ipynb of the python notebook you filled in with the cells run.

Late Submission Policy: If your pset is submitted within 7 days (rounding up) of the original deadline, you will receive partial credit. Such submissions will be penalized by a multiplicative coefficient that linearly decreases from 1 to 0.5.

Problem 1 Texture synthesis (5pts)

In this problem you will implement the Efros and Leung algorithm for texture synthesis [1] discussed in Section 9.3 of Forsyth and Ponce [2]. In addition to reading the textbook you may also find it helpful to visit Efros' texture synthesis website: http://graphics.cs.cmu.edu/people/efros/research/synthesis.html, in which many of the implementation details described below can be found.

As discussed in class, the Efros and Leung algorithm synthesizes a new texture by performing an exhaustive search of a source texture for each synthesized pixel in the target image, in which sum-of-squared differences (SSD) is used to associate similar image patches in the source image with that of the target. The algorithm is initialized by randomly selecting a 3×3 patch from the source texture and placing it in the center of the target texture. The boundaries of this patch are then recursively filled until all pixels in the target image have been considered. Implement the Efros and Leung algorithm as the following Python function:

synthIm = SynthTexture(sample, w, s)

where sample is the source texture image, w is the width of the search window, and s=(ht, wt) specifies the height and width of the target image synthIm. As described above, this

algorithm will create a new target texture image, initialized with a 3x3 patch from the source image. It will then grow this patch to fill the entire image. As discussed in the textbook, when growing the image, un-filled pixels along the boundary of the block of synthesized values are considered at each iteration of the algorithm. A useful technique for recovering the location of these pixels is dilation, a morphological operation that expands image regions. Specifically, one could use scipy.ndimage.binary dilation, numpy.nonzero, numpy.ix_routines to recover the un-filled pixel locations along the boundary of the synthesized block in the target image. We have provided the sample code for this part, you are encouraged to take a look and play with it.

In addition to the above function, we ask you to write a subroutine that for a given pixel in the target image, returns a list of possible candidate matches in the source texture along with their corresponding SSD errors. This function should have the following syntax:

where bestMatches is the list of possible candidate matches with corresponding SSD errors specified by errors. template is the $w \times w$ image template associated with a pixel of the target image, sample is the source texture image, and G is a 2D Gaussian mask discussed below. This routine is called by SynthTexture and a pixel value is randomly selected from bestMatches to synthesize a pixel of the target image. To form bestMatches accept all pixel locations whose SSD error values are less than the minimum SSD value times $(1 + \epsilon)$. To avoid randomly selecting a match with unusually large error, also check that the error of the randomly selected match is below a threshold δ . Efros and Leung use threshold values of $\epsilon = 0.1$ and $\delta = 0.3$.

Note that template can have values that have not yet been filled in by the image growing routine. Mask the template image such that these values are not considered when computing SSD. Efros and Leung suggest using the following image mask:

where validMask is a square mask of width w that is 1 where the template is filled, 0 otherwise and G is a 2D zero-mean Gaussian with standard deviation $\sigma = w/6.4$ sampled on a $w \times w$ grid centered about its mean. G can be pre-computed using scipy.ndimage.gaussian filter routine or one can computed theselves following the Gaussian equation. The purpose of the Gaussian is to down-weight pixels that are farther from the center of the template. Also, make sure to normalize the mask such that its elements sum to 1.

To summarize, you will need to complete the follow three tasks in texture-synthesis.ipynb: (i) compute the Gaussian kernel, (ii) complete the Find matches function, and (iii) sample from the output of Find matches function and update the image.

Test and run your implementation using the grayscale source texture image rings.jpg available in the pset, with window widths of w = 5, 7, 13, s = [100, 100] and an initial starting seed of (x, y) = (4, 32). Explain the algorithm's performance with respect to window size. For a given window size, if you re-run the algorithm with the same starting seed do you get the same result? Why or why not? Is this true for all window sizes?

In your report, include the synthesized textures that correspond to each window size along with answers to the above questions.



Figure 1: Screaming Taipei 101.

Problem 2 Neural Style Transfer (3pts)

In the second part of the assignment, we will walk you through Neural Style Transfer, an algorithm presented by Gatys *et al.* [3]. Neural Style Transfer allows one to turn an input image into a new artistic style. For instance, Fig. 1 shows the magnifacent Taipei-101¹ with the art style from The Scream². The algorithm takes as inputs the content-image and the style-image, and generates an output that looks similar to the content of the content-image and the artistic style of the style-image.

Please follow the step-by-step instructions within style-transfer.ipynb and answer the following questions:

- (1) Implement the code for computing the gram matrix.
- (2) Different from the content-loss which computes the mean square error of the feature maps of the optimized image and the content image, we computed the gram_matrix for the style-loss because.
 - (a) style-loss should encode the spatial correspondence between the optimized image and the style-image.
 - (b) style-loss shouldn't encode the spatial correspondence between the optimized image and the style-image.
 - (c) style-loss should match the distribution of features found in the optimized image and the style-image.
 - (d) style-loss shouldn't match the distribution of features found in the optimized image and the style-image.
- (3) Using conv_5 or conv_1 as the content-loss layer produces different results because _____.
 - (a) conv_5 features care more about the exact pixel values reconstruction of the content-image.
 - (b) conv_1 features care more about the exact pixel values reconstruction of the content-image.

¹https://en.wikipedia.org/wiki/Taipei_101

²https://en.wikipedia.org/wiki/The_Scream

- (c) conv_5 features care more about the semantic content of the content-image.
- (d) conv_1 features care more about the semantic content of the content-image.
- (4) The style transfer algorithm presented here is cool, but we can do better! Notably, the iterative optimization process is slow, which limits its real-world application. Below, we attached several papers on speeding up the style transfer process. Briefly summarize one of the papers in your report:
 - (a) Perceptual Losses for Real-Time Style Transfer and Super-Resolution, Johnson et al. [5]
 - (b) Arbitrary Style Transfer in Real-time with Adaptive Instance Normalization, Huang and Belongie [4].

References

- [1] Alexei A Efros and Thomas K Leung. Texture synthesis by non-parametric sampling. In ICCV, 1999.
- [2] David A Forsyth and Jean Ponce. Computer vision: a modern approach. Pearson, 2012.
- [3] Leon A Gatys, Alexander S Ecker, and Matthias Bethge. Image style transfer using convolutional neural networks. In *CVPR*, 2016.
- [4] Xun Huang and Serge Belongie. Arbitrary style transfer in real-time with adaptive instance normalization. In *ICCV*, 2017.
- [5] Justin Johnson, Alexandre Alahi, and Li Fei-Fei. Perceptual losses for real-time style transfer and super-resolution. In *ECCV*, 2016.