# Kuangshi Ai

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Education

University of Notre Dame

Indiana, USA

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Ph.D. Student in Computer Science and Engineering

2024.08-Present

Research Interests: Scientific Visualization, Multi-modal LLMs, Human-Computer Interaction

**Fudan University** 

Shanghai, China

B.E. in Artificial Intelligence, School of Data Science

2020.09-2024.06

• Overall GPA: 3.71/4.0 Junior GPA: 4.0/4.0 Rank: 2/16

The University of Sydney

Sydney, Australia

Exchange Student in the Faculty of Engineering

2023.02-2023.06

• Overall Grade: HD (High Distinction) U.S. scale GPA: 4.0/4.0

#### **Publications**

- Kuangshi Ai, Kaiyuan Tang, Chaoli Wang. NLI4VolVis: Natural Language Interaction for Volume Visualization via Multi-LLM Agents and Editable 3D Gaussian Splatting. Submitted to 2025 IEEE VIS: Visualization and Visual Analytics
- Kaiyuan Tang, Kuangshi Ai, Jun Han, Chaoli Wang. TexGS-VolVis: Expressive Scene Editing for Volume Visualization via Textured Gaussian Splatting. Submitted to 2025 IEEE VIS: Visualization and Visual Analytics
- Simret Araya Gebreegziabher, Kuangshi Ai, Zheng Zhang, Elena Glassman, Toby Jia-Jun Li. Leveraging Variation Theory in Counterfactual Data Augmentation for Optimized Active Learning. Submitted to the 63rd Annual Meeting of the Association for Computational Linguistics (ACL 2025)

### Research Experience

# Natural Language Interaction for Volume Visualization

University of Notre Dame, USA

2024.08-Present

- Instructor: Prof. Chaoli Wang
  - Developed the first-ever framework enabling natural language interaction with complex 3D scenes using LLM agents and editable 3D Gaussian splatting
  - Integrated vision-language foundation models to achieve open-vocabulary querying of objects in 3D volumetric scenes, supporting intuitive scene manipulation with natural language
  - Work to be submitted to IEEE VIS2025 (TVCG)

## Counterfactual Data Augmentation for Active Learning Instructor: Prof. Toby Li

University of Notre Dame, USA 2023.07-2024.05

- Link: https://github.com/KuangshiAi/VariationTheory
- · Inspired by Variation Theory, proposed an Active Learning (AL) approach which synthesizes artificial datapoints that highlight key similarities and differences among labels
- Developed a neuro-symbolic pipeline combining large language models and rule-based models, which generates high-quality counterfactual examples
- · Achieved a comparable accuracy to prevalent AL strategies while necessitating fewer annotations

# **Data-Efficient Preprocessing of Vision Transformers**

The University of Sydney, Australia 2023.03-2023.06

Instructor: Prof. Chang Xu

- Link: https://github.com/KuangshiAi/vision\_transformer
- Proposed and implemented a method to preprocess and regenerate visual data input sequences, achieving minimal throughput loss and performance improvements on four small-scaled datasets
- · Pointed out potentials of ViTs and the limitation of our method on large-scaled datasets, and proposed a practical guideline for ViT training

### Bilevel Optimization with Special Forms of Lower-level Functions Instructor: Prof. Rujun Jiang

Fudan University, China 2022.12-2023.07

- Conducted experiments on IJCNN1 and corrupted MNIST datasets to evaluate stochastic and variance reduction algorithms for strongly convex lower-level functions
- Proposed case-specific algorithms for typical machine learning problems based on the structure of lower-level functions

**Quantitative Research** 

Beijing, China 2024.01-2024.05

Ningbo Lingjun Investment Management Partnership

- Participated in the development and optimization process of the combo model, maintaining and proficiently mastering the company's live trading model framework
- Based on the company's factor library and financial data, designed a graph transformer-based daily-frequency investment portfolio model, which demonstrated superior effectiveness and robustness compared to the existing live trading model through backtesting.

#### **Embodied AI Algorithm Research**

Shanghai, China 2023.10-2023.12

Shanghai Ziyan Intelligent Technology Co., Ltd.

- As an early member of the startup, developing autonomous control systems for humanoid robots to enhance their capabilities for everyday tasks
- Combined the structure of Swin ViT and Resformer to achieve robot vision focusing ability, and developed a Fast-ACVNet based stereo depth estimation pipeline for affordable environmental information capture
- Deployed and fine-tuned RT2 and Qwen locally as the high-level control unit of robot dogs, and leveraged GPT-4-vision to build navigation system in Meta's Habitat simulation environment

#### **Business Operations and Data Management**

Yunnan, China 2022.07-2022.08

YCIH Logistic Co., Ltd

- Utilized PostgreSQL database management system and Python web crawler technology to collect, analyze and manage data for the company's "INJA" Intelligent Supply Chain Platform
- Developed a backend system for data monitoring and control, real-time data visualization, and data analysis
  modeling

#### Honors & Awards

- Outstanding Graduate, Fudan University, 2024
- Second Prize (Top 2 in major), the Scholarship for Outstanding Students, Fudan University, 2024 & 2021
- Third Prize, the Scholarship for Outstanding Students, Fudan University, 2022
- Outstanding Student Leaders, Fudan University, 2020-2022
- Second Prize in Shanghai, Contemporary Undergraduate Mathematical Contest in Modeling, 2022
- Scholarship for Outstanding Freshmen, Fudan University, 2020

#### Professional Skills

Programming: Python, MATLAB, C/C++, SOL, R

Tools: Pytorch, TensorFlow, paddlepaddle, LaTeX, Numpy, Pandas, Linux

Language: English (TOEFL: 106/120), Chinese (native speaker)