

# ELECTRICAL SCIENCE

100

- 25 internal  
 → 15 internal ass  
 → 10 quis, assignment

75 external theory  
 + numericals.

## SYLLABUS

- # Unit-1 DC circuits
- # Unit-2 AC circuits
- # Unit-3 Transformers & Machines (motors + generators)
- # Unit-4 Measuring Instruments. (Analogue & Digital)

## UNIT-1 DC Circuits

### # BASIC TERMS

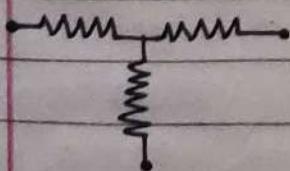
(a) Circuit :- Any energized (Sources of energy) network through which current flows is called a circuit.

OR

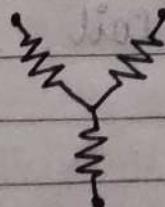
A closed network or loop in which current flows.

(b) Network :- Combination or interconnections of circuit elements or parameters

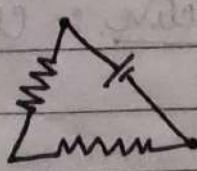
→ R, L and C, voltmeter, battery



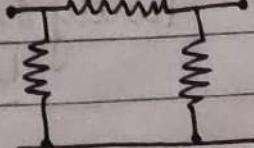
T network



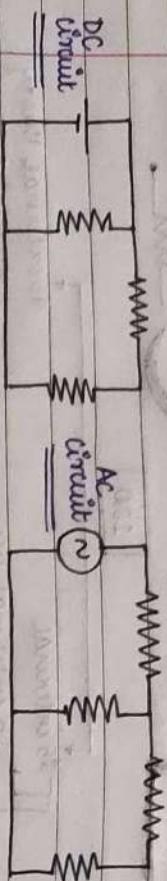
Star network



Delta Network

 $\pi$  network.

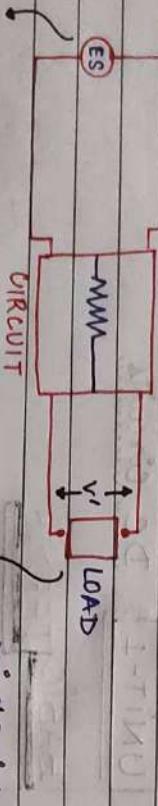
(c) Sources of Energy :- Battery, cell, solar cell, generator  
 much  $\rightarrow$  electricity



(d) Energy converter (LOAD) :- Anything which consumes electrical power. For eg: Fan, bulb.

For us:  $R, L, C$  for real life;  $C$  just enhances power factor.

### CIRCUIT REPRESENTATION



SOURCE OF EMF

$$\text{Open circuit voltage} \quad (\text{VI})$$

voltage

terminal

(point)

pair of 2 points

# QUESTIONS FOR VIVA :-

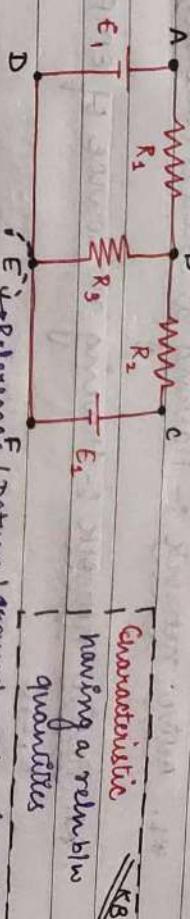
Q Purely Resistive :- Normal tungsten Load 0 watt bulb.

Purely Inductive :- Choke coil Load

\*5 Unilateral circuit :- characteristics of circuit changes with change in direction of current. Eg: Diode, rectifier.

\*6. Bilateral circuit :- characteristic remains same irrespective of direction of current. Eg: Transmission line.

# Circuit Diagram  
 A graphical representation of circuit elements



# TYPES OF CIRCUIT :-

\*1. DC circuit :- Voltage & current same with time.

\*2. AC circuit :- " " changes "

\*3. Linear circuit :- Which follows Ohm's law, i.e. purely resistive in nature.

Follows homo & superposition.  
St. line characteristic.

\*4. Non-linear circuit :- Does not follow Ohm's law. Eg:- Semiconductors. (Or) Which do not follow principle of superposition & homogeneity.

"Non linear

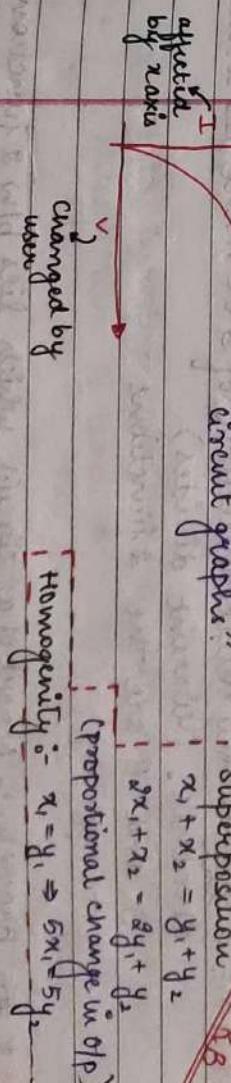
circuit graphs"

Superposition

$$x_1 + x_2 = y_1 + y_2$$

$$2x_1 + x_2 = 2y_1 + y_2$$

(proportional change in op.)



changed by

Homogeneity :-

$$x_1 = y_1 \Rightarrow 2x_1 = 2y_1$$

## # Types of Networks

\*1. Active network :- Having a source (attenuator) of EMF

\*2. Passive network :- Having no source of EMF. Eg:- only R, L, C

#1. Active elements :- Sources of EMF. Eg:- cell, battery

#2. Passive elements :- which stores, dissipates energy

Only R dissipates energy.

#3. Node :- A point or any interconnections of 2 or more elements.

A ( $E_1, R_1$ )      D & F are not Nodes

B ( $R_1, R_2, R_3$ )

C ( $R_2, E_2$ )

E ( $E_1, R_3, E_2$ )

\* \* #4. Junction :- Any interconnection of 3 or more circuit elements. (current divides)

B and E are the junctions  
(KCL applied)

\* \* #5. Branch :- A part of a circuit which lies b/w 2 junctions  
Fusing :- BADE, BE, BCFE Circuit diagram

#6. Loop :- Any closed path in a circuit is called loop

In which no element or node is encountered more than once. (KVL applied)

Fusing :- ABED, BCFE, ABCFED

★ ★ #7 Mesh :- Smallest loop which doesn't contain a loop

For eg :- BCFE, ABED

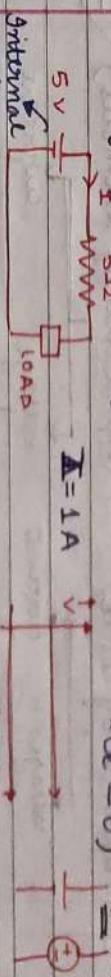
Ideal :- 100%.

# Type of Sources :-  
(Independent sources)

\*1. Voltage Source :- Provides EMF (const v. w.r.t.)

\*2. Constant current source :- provides constant current  
Eg:- Solar panels, Metadine generators, certain Transistors

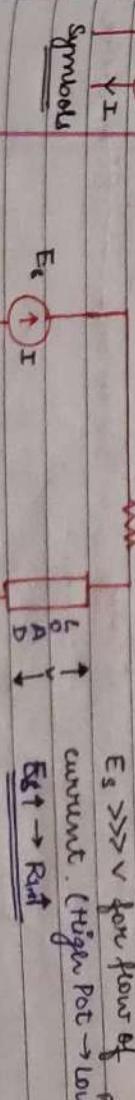
\*3. Ideal voltage source :- It should provide a constant  
designated voltage wrt time. (internal Resistance = 0)



internal  
Resis = 0

→ An ideal voltage source has zero internal resistance.  
A voltage source can be replaced by a short circuit because we need zero resistance & infinite current.

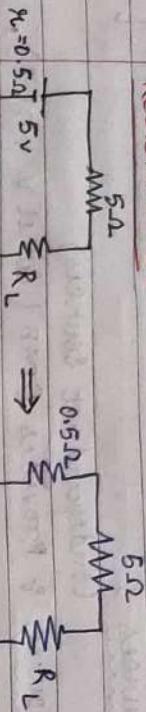
\*4. Ideal current source :- Provides constant current irrespective of load current.



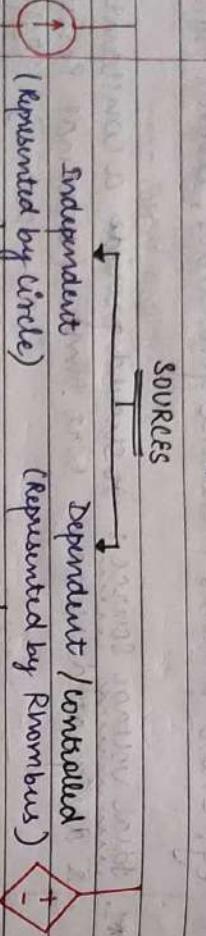
$E_s \ggg V$  for flow of current. (High Pot → Lower Pot)

An ideal current source which supply the same current to any resistive connected across its terminals. It has infinite internal resistance to provide constant current.

→ An ideal current source is replaced by an open circuit b/w infinite resistance (internal resistance) ~~whose are to be replaced by their internal resistances.~~



Replace battery ~~with~~ ~~independent~~  
(represented by circle)

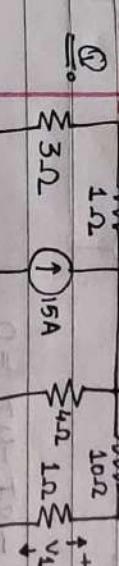


$$V = IR$$

$$= 5 \times 2 = 10V$$

$$I = \frac{V}{R} = \frac{10}{2} = 5 \text{ Ampere}$$

15 Nov, 2022

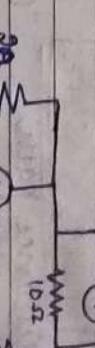


Find  $V_L$  using source conversion.

$$(3\Omega + 1\Omega) \parallel 4\Omega$$

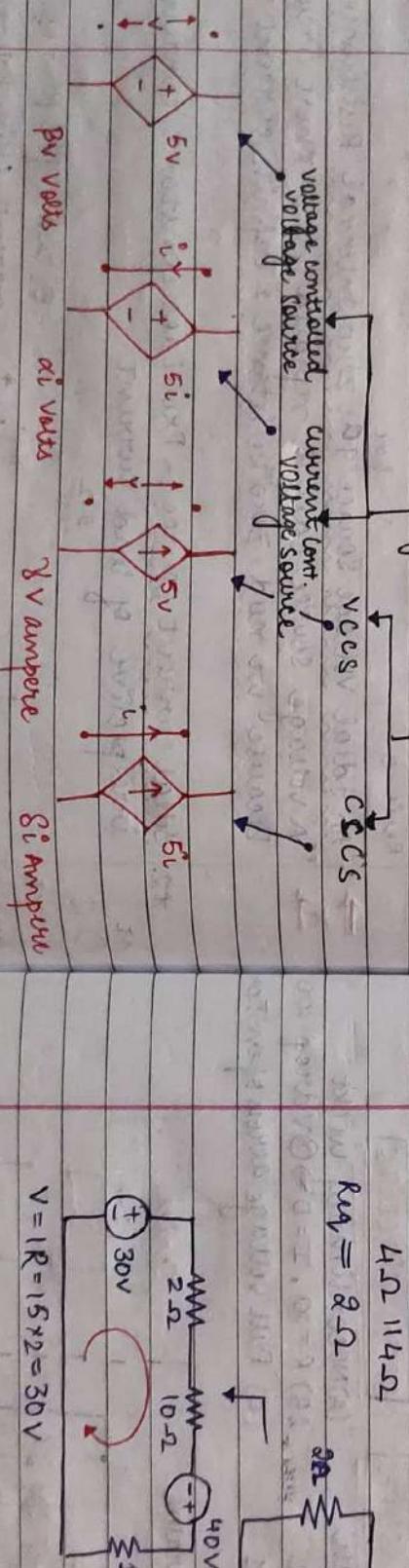
$$4\Omega \parallel 4\Omega$$

$$R_{eq} = 2\Omega$$



$$I = \frac{V}{R} = \frac{10}{2} = 5 \text{ Ampere}$$

15 Nov, 2022



$$V = IR = 15 \times 2 = 30V$$

$$30 - 12I + 40 - V_L = 0$$

$$30 - 12I + 40 - I(1\Omega) = 0$$

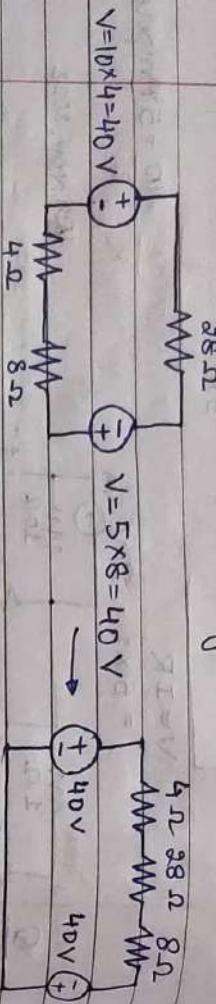
$$I = 5A \Rightarrow V = \frac{30}{13} \times 1\Omega = \frac{30}{13} V$$

# SOURCE CONVERSION :-  
(Independent sources)

$V_{source} \rightleftharpoons C_{source}$



Find the current in  $28\Omega$  using source converter.



$$+40V - 28I + 40 - 8I - 4I = 0$$

$$I = 8A$$

#

SHORT CIRCUITS vs OPEN CIRCUITS

- (A) zero resistance path
- (B) no continuity in ckt
- (C)  $R = \infty$ ,  $I = 0$   $\Rightarrow$  0V drop across R.
- (D) dangerous

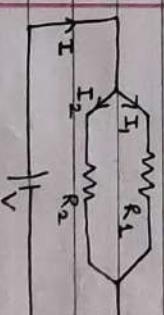
No current & no bulb will glow.

B. will glow.

Parallel ckt

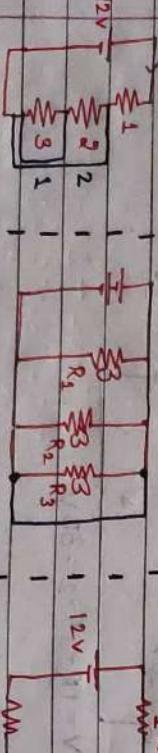
# Current Division Rule and Voltage Division Rule.

Series ckt



$$I_1 = I \cdot \left( \frac{R_2}{R_1 + R_2} \right)$$

$$V_1 = \frac{R_1 \cdot V}{R_{eq}} \Rightarrow V_2 = \frac{V \cdot R_2}{R_{eq}}$$



Step 1  $\Rightarrow$  short out  $3\Omega$

NO bulb will glow

Voltage across each component = 0

Step 2  $\Rightarrow$  short out  $2\Omega$  &  $3\Omega$

Current through 1Ω load

Final voltage

$$I_1 = \frac{12}{3} = 4A$$

$$\frac{1}{3}$$

Step 2  $\Rightarrow$  short out  $2\Omega$  &  $3\Omega$

Current through 1Ω load

Final voltage

$$I_2 = \frac{8}{6} = \frac{4}{3}A$$

$$\frac{1}{6}$$

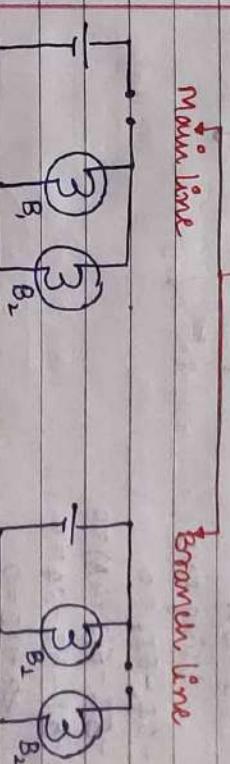
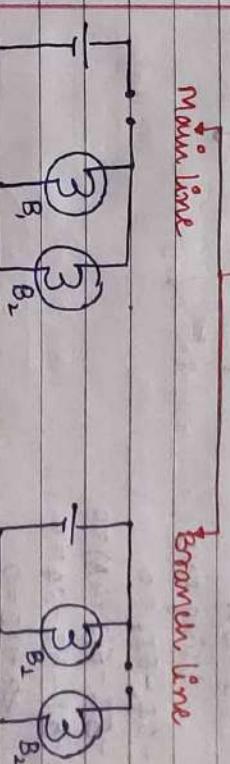
In short ckt (Ans)  
zero resistance  $\Rightarrow V = IR \Rightarrow V = 0$

zero voltage drop across terminals of short circuit.

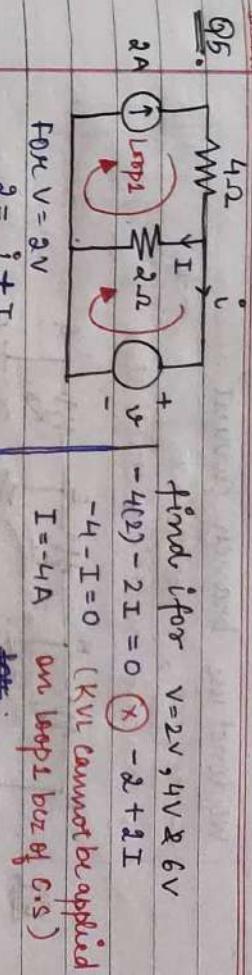
In parallel short ckt.

Short across one branch = Short across all branches.

Open ckt in parallel ckt.



Doubt.



Q3.

$I_1 = 6\Omega$        $2\Omega$   
 $24V$        $5\Omega$        $I$   
 $I$

KCL at A

$I_1 = I + 4A$

$I_1 = 24 = 4A$

$I = 0A$

Using KVL

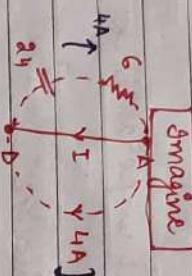
$24 - 6I - 5I = 0$

$24 - 5I - 5(I+4A) = 0$

$24 - 5I - 5I - 20 = 0$

$4I + 20 = 0$

$I = 0$



$\text{for } V = 4V$

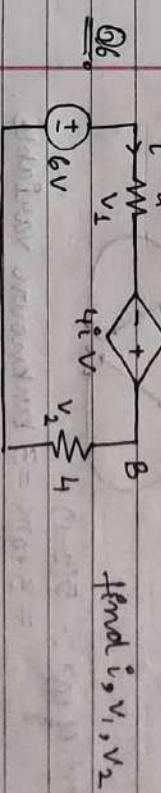
$-4V + 2I = 0$

$I = 2A \Rightarrow i = 4A$

$i = 2A$  for  $V = 2V$

$+2 = 2I \Rightarrow I = +1A$

After 3 pages :-



$-V_1 + 4i + V_2 + 6 = 0 \quad \text{I}$

$V_1 = 2i \quad V_2 = 4i \quad V_2 = 4 \times 3 = 12V$

$-2i + 4i - 4i + 6 = 0$

$i = +2i$

$i = +3A$

Apply KCL at A

$I = 0.5i + i = 1.5i$

Apply KVL

$6V - 2i - 1i - 5i = 0$

$6 - 8(1.5i) - 6i = 0$

$6 - 9i = 0$

$i = \frac{2}{9} A$

### # MESH ANALYSIS METHOD :-

We use mesh currents here based on KVL

Step-1 Count no of meshes.

Step-2 for each mesh, assign a mesh current preferably in C.W direction.

Step-3 Write down KVL for each mesh.

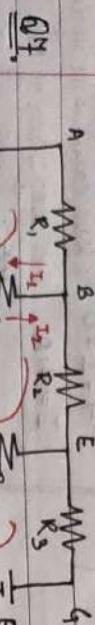
No. of eqns =  $(b - (j - 1))$   
 $b = \text{no. of branches}, j = \text{no. of junctions}$

Date : 26 Nov, 2022

We don't use branch current.

$\rightarrow$  less eqns, less tedious

$\rightarrow$  can use matrix method also.



Junctions :- B, E, C, F but C & F are at same potential. Hence

$$i := B, E, C = 3$$

Branch i-5 :-



$$\text{No. of eqn} := 5(3-1)$$

Using (i)

$$\text{Eqn } \textcircled{1} \quad E_1 - I_1 R_1 - R_4 (I_1 - I_2) = 0 + \begin{bmatrix} R_4 (\text{mesh no}_1 - \\ \text{mesh no}_2) \end{bmatrix}$$

$$E_1 - I_1 R_1 - R_4 I_1 + R_4 I_2 = 0$$

$$E_1 - I_1 (R_1 + R_4) + R_4 I_2 = 0$$

$$\text{Eqn } \textcircled{2} \quad - I_2 R_2 - R_5 (I_2 - I_3) - R_4 (I_2 - I_1) = 0$$

$$- I_2 R_2 - R_5 I_2 + R_5 I_3 - R_4 I_2 + R_4 I_1 = 0$$

$$- I_2 (R_2 + R_4 + R_5) + R_5 I_3 + R_4 I_1 = 0$$

$$\text{Eqn } \textcircled{3} \quad - I_3 R_3 - E_2 - R_5 (I_3 - I_2) = 0$$

$$- I_3 R_3 - E_2 - R_5 I_3 + R_5 I_2 = 0$$

$$- I_3 (R_3 + R_5) - E_2 + R_5 I_2 = 0$$



Find  $I_1, I_2, I_3$



$$\text{Formulation 1} : E_1 - I_1 R_1 - R_3 (I_1 - I_3) - R_2 (I_1 - I_2) = 0$$

$$E_1 - I_1 R_1 - R_3 I_1 + R_3 I_2 - R_2 I_1 + R_2 I_2 = 0$$

$$E_1 - I_1 (R_1 + R_2 + R_3) + R_3 I_3 + R_2 I_2 = 0 - \textcircled{1}$$

$$\text{For mesh 2} : E_2 - R_2 (I_2 - I_1) - R_5 (I_2 - I_3) - R_4 I_2 = 0$$

$$E_2 - I_2 (R_2 + R_5 + R_4) + R_2 I_1 + R_5 I_3 - \textcircled{2}$$

$$\text{For mesh 3} : - R_3 (I_3 - I_1) - R_6 I_3 - E_3 - R_4 I_3 - R_5 (I_3 - I_2) = 0$$

$$- E_3 - I_3 (R_3 + R_6 + R_7 + R_5) + R_3 I_1 + R_5 I_2 = 0 \quad \text{L} \textcircled{3}$$

L

$$E_1 = I_1 (R_1 + R_2 + R_3) - R_3 I_3 - R_2 I_2$$

$$\text{Using (ii)} \quad E_2 = I_2 (R_2 + R_5 + R_4) - R_2 I_1 - R_5 I_3$$

$$\text{Using (iii)} \quad E_3 = + I_3 (R_3 + R_6 + R_7 + R_5) - R_3 I_1 - R_5 I_2$$

$$\begin{bmatrix} E_1 \\ E_2 \\ E_3 \end{bmatrix} = \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix}$$

$$[E_m] = [R_m] [I_m] \rightarrow \text{Ohm's law in matrix form}$$

FOR CLOCKWISE DIR.

$$\begin{bmatrix} E_1 \\ E_2 \\ E_3 \end{bmatrix} = \begin{bmatrix} R_{12} & -R_3 & I_1 \\ R_1 + R_2 + R_3 & -R_2 & I_2 \\ R_{23} & R_2 + R_3 + R_5 & I_3 \end{bmatrix}^{-1} \begin{bmatrix} R_{12} \\ R_{23} \\ R_{23} \end{bmatrix}$$

For clockwise direction.

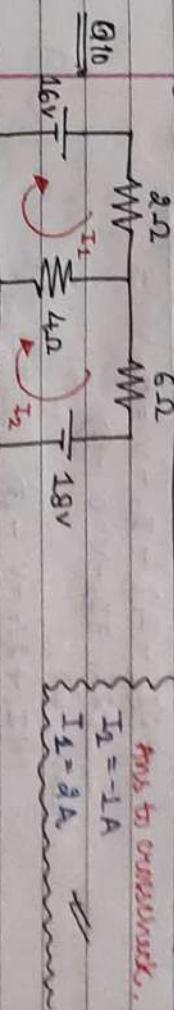
$$R_{11}, R_{22}, R_{33} = \text{sum of each mesh (+ve)}$$

$R_{ij}$  = Mutual Resistance b/w Mesh 3 & Mesh 1

All mutual resistances are -ve.

$$\frac{1}{147} \begin{bmatrix} 15 \times 5 \\ 23 \times 5 \end{bmatrix} = \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} \Rightarrow \begin{aligned} I_1 &= 2.05 \\ I_2 &= 7.5 \\ I_3 &= 11.5 \end{aligned}$$

$I_1 = 1.29A, I_2 = 0.51A, I_3 = 0.78A$  Ans



METHOD-1

$$\begin{bmatrix} 16 \\ -18 \end{bmatrix} = \begin{bmatrix} 6 & -4 \\ -4 & 10 \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \end{bmatrix}$$

$\rightarrow (i)$

$\rightarrow (ii)$

$16 - 2I_1 - 4(I_1 - I_2) = 0$

$\rightarrow (i)$

$-18 - 6(I_2) - 4(I_2 - I_1) = 0$

$\rightarrow (ii)$

$$\text{adj} = \begin{bmatrix} 10 & 4 \\ 4 & 6 \end{bmatrix}$$

$$(i) = 16 - 6I_1 + 4I_2 = 0$$

$$(ii) = -18 + 10I_2 + 4I_1 = 0$$

$$A = XB$$

from (i)

$$AX^{-1} = B = A \times \frac{1}{|X|} \text{adj} X = B$$

$$I_1 = \frac{6I_1 - 16}{4}$$

Put  $I_2$  in (ii)

$$\frac{1}{4} \begin{bmatrix} 16 \\ -18 \end{bmatrix} = \begin{bmatrix} I_1 \\ I_2 \end{bmatrix}$$

$$-18 - 10 \left( \frac{6I_1 - 16}{4} \right) + 4I_1 = 0$$

$$-72 - 60I_1 + 160 + 16I_1 = 0$$

$$88 - 44I_1 = 0$$

$$I_1 = 2A$$

$$I_2 = 6(2) - 16 = -\frac{4}{3}A$$

$$I_2 = -1A$$

Ans.

Ans.

Ans.

$$I_1 = 2A ; I_2 = -1A$$

Ans.

Ans.

Ans.

Ans.

$$\frac{1}{6} \begin{bmatrix} 6 & -2 & -3 \\ -2 & 4+1+2 & -1 \\ 0 & -3 & -1 \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = 6(41) + 2(-15) - 3(23)$$

$$= 246 - 30 - 69 = 147$$

Summation of matrix

$$A_{31} = 2+21$$

$$A_{11} = 42 - 1$$

$$A_{21} = -12 - 3$$

$$A_{32} = -6 - 6$$

$$A_{12} = -12 - 3$$

$$A_{22} = 36 - 9$$

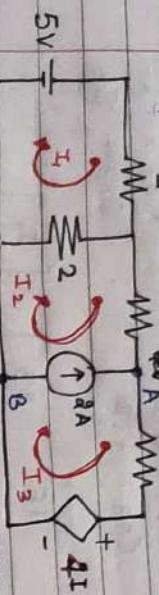
$$A_{33} = 42 - 4$$

$$A_{13} = 2+21$$

$$A_{23} = -6 - 6$$

$$\begin{aligned} C_1 &= 42 & C_4 &= +15 \\ C_{12} &= +15 & C_{22} &= 25 \\ C_{13} &= 23 & C_{23} &= +12 \\ C_{32} &= +12 & C_{33} &= 38 \end{aligned}$$

Q11 Supermesh \*\*



$$\text{Mesh 1: } 5 - I_1(4) - 2(I_1 - I_2) = 0$$

$$5 - I_1 - 2I_1 + 2I_2 = 0 \Rightarrow 5 - 3I_1 + 2I_2 = 0 \quad (1)$$

$$\text{Mesh 2: } I_3 - I_2 = 2 \Rightarrow I_3 = 2 + I_2 \quad (5)$$

$$-2(I_2 - I_1) - I_2 - V = 0$$

$$+2I_1 - 3I_2 - V = 0 \quad (2)$$

Assume voltage drop at A

To be +V & B = -V

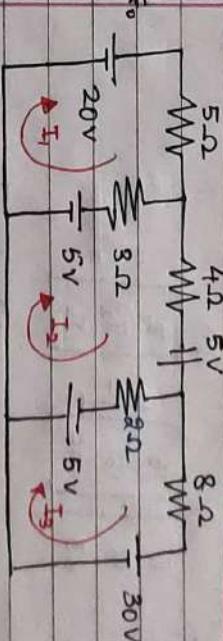
$$5 - 5 + I_1 - 44 = 0$$

$$51 - 57I_1 = 0$$

$$\frac{51}{57} = I_1 \Rightarrow I_1 = \frac{17}{19} A$$

$$I_3 = \frac{2 - 22}{19} = \frac{38 - 22}{19} = \frac{16}{19} = I_3$$

Q12.



must to measure

$$I_1 = \frac{1530}{598}$$

$$I_2 = \frac{1090}{598}$$

Mesh 1:

$$20 - 5I_1 - 3(I_1 - I_2) - 5 = 0$$

$$15 - 8I_1 + 3I_2 = 0$$

$$15 = 8I_1 - 3I_2$$

Mesh 2:

$$5 - 3(I_2 - I_1) - 4I_2 + 5 - 2(I_2 - I_3) + 5 = 0$$

$$15 - 9I_2 + 3I_1 + 2I_3 = 0$$

$$-15 = -9I_2 + 3I_1 + 2I_3$$

Mesh 3:

$$-5 - 2(I_3 - I_2) - 8I_3 - 30 = 0$$

$$-35 - 10I_3 + 2I_2 = 0$$

$\alpha$

$$5 - 3 \left( \frac{-5I_2 - 4}{2} \right) + 2I_2 = 0$$

$$10 + 15I_2 + 12 + 4I_2 = 0$$

$$19I_2 + 22 = 0 \Rightarrow -\frac{22}{19} = I_2$$

(acc to polarity)

$$\begin{bmatrix} 15 \\ 15 \\ -35 \end{bmatrix} = \begin{bmatrix} 8 & -3 & 0 \\ -3 & 9 & -2 \\ 0 & -2 & 10 \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix}$$

$$A = \begin{bmatrix} 8 & -3 & 0 \\ -3 & 4 & -2 \\ 0 & -2 & 10 \end{bmatrix} = 8(86) - 40 = 688 - 40 = 598$$

$$A_{11} = 90 - 4 = 86 \quad A_{21} = -30 \quad A_{31} = 6$$

$$A_{12} = -30 \quad A_{22} = 80 \quad A_{32} = -16$$

$$A_{13} = 6 \quad A_{23} = -16 \quad A_{33} = 42 - 9 = 33$$

$$C_{11} = 86 \quad C_{21} = +30 \quad C_{31} = 6$$

$$C_{12} = +30 \quad C_{22} = 80 \quad C_{32} = +16$$

$$C_{13} = 6 \quad C_{23} = +16 \quad C_{33} = 63$$

$$C_{11} = 136 - 9 \quad C_{21} = -96 - 3 \quad C_{31} = 53$$

$$C_{12} = 99 \quad C_{22} = 119 \quad C_{32} = 57$$

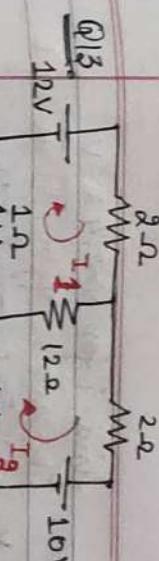
$$C_{13} = 53 \quad C_{23} = 57 \quad C_{33} = 111$$

$$\frac{1}{598} \begin{bmatrix} 86 & 30 & 6 \\ 30 & 80 & 16 \\ 6 & 16 & 63 \end{bmatrix} = \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix}$$

$$\frac{1}{598} \begin{bmatrix} (86)(15) + (30)(15) + (-35)(6) \\ (30)(15) + (80)(15) + (16)(-35) \\ (6)(15) + (16)(15) + (63)(-35) \end{bmatrix} = \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix}$$

$$\frac{1}{598} \begin{bmatrix} 1290 + 450 - 210 \\ 450 + 1200 - 560 \\ 90 + 240 - 2205 \end{bmatrix} = \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix}$$

Ans.  $\boxed{\frac{1530}{598} = I_1 ; \frac{1090}{598} = I_2 ; \frac{-1875}{598} = I_3}$



$$I_3 = 4.11 \text{ A} \\ I_2 = 2.05 \text{ A} \\ I_1 = 2.42 \text{ A}$$

$$I = 15(136 - 9) + 12(-96 - 3) - 1(36 + 17)$$

$$\begin{bmatrix} 12 \\ -10 \\ 24 \end{bmatrix} = \begin{bmatrix} 15 & -12 & -1 \\ -12 & 17 & -3 \\ -1 & -3 & 8 \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = 1905 - 1188 - 53 = 664$$

$$A_{11} = 136 - 9 \quad A_{21} = -96 - 3 \quad A_{31} = 36 + 17$$

$$A_{12} = 99 \quad A_{22} = 120 - 1 \quad A_{32} = -45 - 12$$

$$A_{13} = 53 \quad A_{23} = 57 \quad A_{33} = 255 - 144$$

$$\frac{1}{664} \begin{bmatrix} 127 & 99 & 53 \\ 99 & 119 & 57 \\ 53 & 57 & 111 \end{bmatrix} = \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix}$$

$$\frac{1}{664} \begin{bmatrix} (127)(12) - 10(99) + 24(53) \\ 99(12) - 10(119) + 24(57) \\ 53(12) - 10(57) + 24(111) \end{bmatrix} = \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix}$$

$$\frac{1}{664} \begin{bmatrix} 1524 - 990 + 1272 \\ 1188 - 1190 + 1368 \\ 636 - 570 + 2664 \end{bmatrix} = \begin{bmatrix} 1806 \\ 1366 \\ 2730 \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = \begin{bmatrix} I_1 = 2.42 \text{ A} \\ I_2 = 2.05 \text{ A} \\ I_3 = 4.11 \text{ A} \end{bmatrix}$$

Q6. find  $i$  for  $V=2, 4 \& 6V$   
 we cannot apply KVL in loop

$$2A$$

$$i = i + 1$$

$$I = 1 \quad \text{for } V=2$$

$$i = 2A$$

$$I = 0A$$

$$i = -3A$$

$$I = 1A$$

$$V = 4V$$

$$I = 2A$$

$$I = 3A$$

$$i = -2A$$

$$V = 6V$$

$$I = 3A$$

$$i = -3A$$

$$V = 6V$$

$$I = 3A$$

$$i = -3A$$

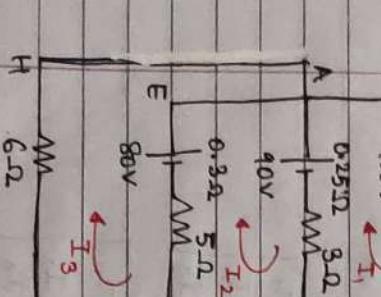
$$V = 6V$$

$$I = 2A$$

$$i = -2A$$

$$I_3 = AEFBGA$$

$$\begin{vmatrix} 1 & -685.2 & 36.72 & 17.22 & -10 & I_1 \\ -391.16 & 36.72 & 84.18 & 39.48 & -10 & I_2 \\ 17.22 & 39.48 & 53.19 & -80 & I_3 \end{vmatrix}$$



$$I_3 = -12.339A$$

$$\begin{aligned} C_{11} &= 68.52 & C_{21} &= 36.72 & C_{31} &= 17.22 \\ C_{12} &= 36.72 & C_{22} &= 84.18 & C_{32} &= 39.48 \\ C_{13} &= 17.22 & C_{23} &= 39.48 & C_{33} &= 53.19 \end{aligned}$$

$$A = 5.45 \begin{bmatrix} 8.55 & 11 & 5.3 \end{bmatrix}$$

$$+ 3.25 \begin{bmatrix} -3.25 & 11 \end{bmatrix}$$

$$= 5.45 [94.05 - 28.09]$$

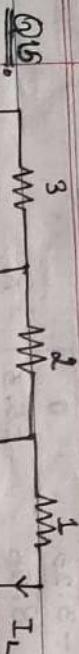
$$+ 3.25 (-35.75)$$

$$= 359.48 - 116.18 = 243.3$$

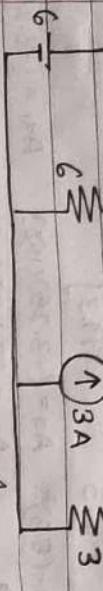
$$I_3 = AEFBGA$$

$$\begin{vmatrix} 1 & -685.2 & 36.72 & 17.22 & -10 & I_1 \\ -391.16 & 36.72 & 84.18 & 39.48 & -10 & I_2 \\ 17.22 & 39.48 & 53.19 & -80 & I_3 \end{vmatrix}$$

$$\begin{aligned} I_1 &= 243.3 + 0.25 & - (3 + 0.25) &= 0 \\ I_2 &= -(3 + 0.25) & 3 + 0.25 + 5 + 0.3 &= -(0.3 + 5) \\ I_3 &= 0 & -(0.3 + 5) &= 0.3 + 6 + 5 \end{aligned}$$



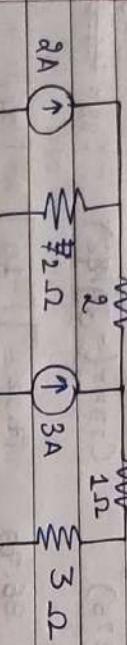
$$2A = I_L$$



$$\frac{1}{3} + \frac{1}{6} = \frac{6+3}{18} = \frac{9}{18} = \frac{1}{2}$$

$$V = IR$$

$$V_R = I$$



(a)

$$\Delta = \begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = a(ei-hf) - b(di-gf) + c(dh-ge)$$

(b) Determinant

$$\Delta = \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix}$$

*Sign ch. Interchange*

$$(c) \text{ adj } A = \frac{1}{\Delta} \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix}$$

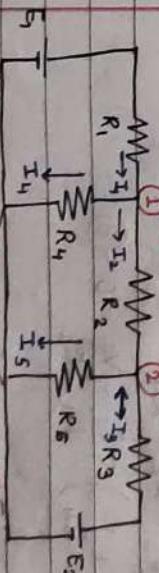
*Interchange*

$$A^{-1} = \frac{1}{|A|} \text{ adj } A$$

## NODAL ANALYSIS

(using KCL)

Date :- 1 Dec 2022



Step 1 :- find 'n' no. of junctions (node)

Step 2 :- no. of eqns =  $n-1$  ( $n$ =no. of junctions)

Hence  $n-1=2$

Step 3 :- Take one node as datum node (reference node)

Since total current is  $4A$  & resistance in both parallel branches is same,  $I$  in  $ABCD = 2A$ .

$$I_{ABCD} = 2A$$

# Methods of Matrix used in Numericals.

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, B = \begin{bmatrix} e & f & g \\ h & i & j \end{bmatrix} \Rightarrow AB = \begin{bmatrix} ae+bh & af+bi & ag+bj \\ ce+dh & cf+di & cg+dg \end{bmatrix}$$

Step 1 :- All other junctions, assign name & potential.

Step 2 :- find  $V_1$  &  $V_2$

Step 3 :- On each junction write KCL equations by marking branch currents.

At node 1 :-

$$I_1 = I_2 + I_4 \quad \text{--- (1)}$$

$$\text{At node 2} :- \quad I_5 = I_3 + I_2 \quad \text{--- (2)}$$

SOP 7 :- Write currents in the form of  $V/R$ .

$$I_1 = \frac{E_1 - V_1}{R_1} \quad I_5 = \frac{V_1 - V_6}{R_5} = \frac{V_2}{R_5}$$

$$I_2 = \frac{V_1 - V_2}{R_2} \quad I_3 = \frac{E_2 - V_2}{R_3} \quad I_4 = \frac{V_1 - V_6}{R_4} = \frac{V_1}{R_4}$$

Put these expressions in eq ① & ②

$$E_1 - V_1 = \frac{V_1 - V_2}{R_2} + V_1 \quad \text{--- (3)}$$

$$\frac{E_2 - V_2}{R_5} = E_2 - V_2 + \frac{V_1 - V_2}{R_2} \quad \text{--- (4)}$$

Simplifying ③

$$\frac{E_1 - V_1}{R_1} = \frac{V_1}{R_2} - \frac{V_2}{R_2} + \frac{V_1}{R_4}$$

$$V_1 \left( \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_4} \right) - \frac{V_2}{R_2} = 0 \quad \text{--- (5)}$$

Simplifying ④

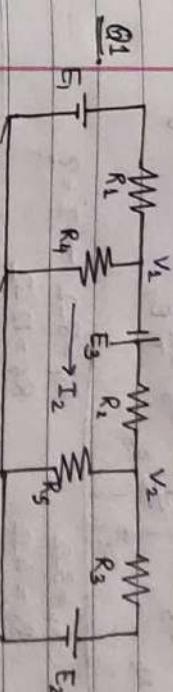
$$\frac{E_2 - V_2}{R_5} = E_2 - V_2 + \frac{V_1 - V_2}{R_2} - \frac{V_2}{R_2} \quad \text{--- (6)}$$

$$\frac{V_2}{R_5} = \frac{E_2 - V_2}{R_5} - \frac{V_2}{R_2} + V_1 - \frac{V_2}{R_2}$$

$$V_2 \left( \frac{1}{R_5} + \frac{1}{R_2} + \frac{1}{R_2} \right) - \frac{E_2 - V_2}{R_5} = 0 \quad \text{--- (6)}$$

### Application

(1) Where all the branches are connected at common ground



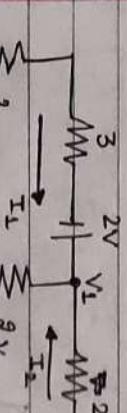
$$I_2 = \frac{(V_1 + E_3) - V_2}{R_2}$$

Rest all same

$$2 \quad V_1 \left( \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_5} \right) - \frac{V_2}{R_2} - \frac{E_1}{R_1} + \frac{E_3}{R_2} = 0$$

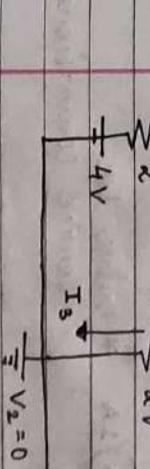
$$V_2 \left( \frac{1}{R_2} + \frac{1}{R_3} + \frac{1}{R_5} \right) - \frac{V_1}{R_2} - \frac{E_2}{R_3} - \frac{E_3}{R_2} = 0$$

Q2.



Find current in  
3 Ω resistance

$$V_1 = 8/3 V$$



$$I_3 = I_1 + I_2$$

$$I_3 = \frac{V_1 - V_2}{2} = \frac{V_1}{2} = \frac{4}{3}; \quad I_1 = \frac{4+2-V_1}{3+2} = \frac{6-V_1}{5} = \frac{6-8}{5} = \frac{-2}{5} = \frac{10}{15} = \frac{10}{15}$$

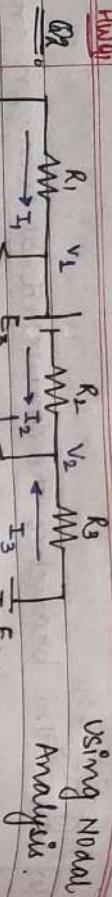
$$I_2 = \frac{4-V_1}{2}$$

$$= \frac{4-V_1}{2} = \frac{4-8}{2} = \frac{-4}{2} = -2$$

$$\frac{V_1}{2} = \frac{6-V_1}{5} + 2 - \frac{V_1}{2}$$

$$\frac{V_1 + V_1 + V_1}{2} = 6+2 \Rightarrow \frac{3V_1}{2} = 8 \Rightarrow V_1 = \frac{16}{3} V$$

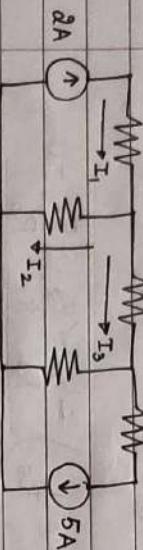
$$= 12V_1 = 32 \Rightarrow V_1 = \frac{8}{3} V$$



$$\begin{aligned} R_4 &= 8\Omega \rightarrow I = ? \\ E_1 &= 10V \quad R_1 = 3\Omega \quad R_5 = 12\Omega \\ E_3 &= 3V \quad R_2 = 4\Omega \quad R_3 = 14\Omega \\ E_2 &= 6V \end{aligned}$$

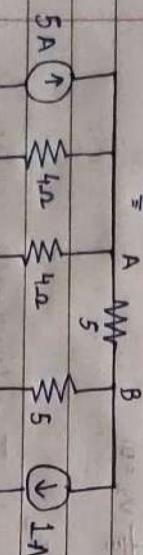
$$\begin{aligned} (use \text{ nodal } p \text{ mesh } \\ \text{analysis}) \\ I_4 &= 0.94A \end{aligned}$$

$\Rightarrow$  Nodal Analysis with current source.



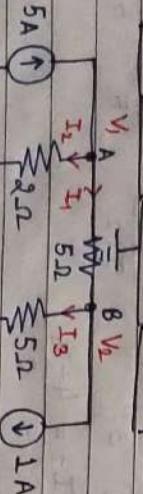
$$I_1 = I_2 + I_3$$

$$I_2 = I_3 + I_4$$

A.

$$I_1 = I_2 + I_3$$

$$I_2 = I_3 + I_4$$



$$I_1 = I_2 + I_3$$

$$I_2 = I_3 + I_4$$

$$I_4 = I_5 + I_6$$

$$I_5 = I_6 + I_7$$

$$I_7 = I_8 + I_9$$

$$I_9 = I_{10} + I_{11}$$

$$I_{11} = I_{12} + I_{13}$$

$$I_{12} = I_{13} + I_{14}$$

$$I_{14} = I_{15} + I_{16}$$

$$I_{15} = I_{16} + I_{17}$$

$$I_{17} = I_{18} + I_{19}$$

$$I_{19} = I_{20} + I_{21}$$

$$I_{21} = I_{22} + I_{23}$$

$$I_{23} = I_{24} + I_{25}$$

$$I_{25} = I_{26} + I_{27}$$

$$I_{27} = I_{28} + I_{29}$$

$$I_{29} = I_{30} + I_{31}$$

$$I_{31} = I_{32} + I_{33}$$

$$I_{33} = I_{34} + I_{35}$$

$$I_{35} = I_{36} + I_{37}$$

$$I_{37} = I_{38} + I_{39}$$

$$I_{39} = I_{40} + I_{41}$$

$$I_{41} = I_{42} + I_{43}$$

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$$I_{45} = I_{46} + I_{47}$$

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$$I_{335} = I_{336} + I_{337}$$

$$I_{337} = I_{338} + I_{339}$$

$$I_{339} = I_{340} + I_{341}$$

$$I_{341} = I_{342} + I_{343}$$

$$6I_2 - 3I_3 - 7 - I_3 = 0$$

$$6I_2 - 4I_3 - 7 = 0$$

$$7 + I_3 - 4I_2 + 4I_3 = 0 \quad \text{---} \quad (i)$$

$$7 + 5I_3 - 4I_2 = 7 \quad \text{---} \quad (ii)$$

$$\frac{I_3}{5} = I_2$$

$$6I_2 - 4\left(\frac{4I_2}{5}\right) - 7 = 0$$

$$36I_2 - 16I_2 - 35 = 0$$

$$48I_2, 14I_2 = 35$$

$$I_2 = 35 = \frac{5}{2} = 2.5 \text{ A}$$

14

$$I_3 = \frac{4}{5} \left(\frac{5}{2}\right) = 2 \text{ A}$$

14

$$I_2 = 35 = \frac{5}{2} = 2.5 \text{ A}$$

14

Simplification (ii)

$$-3 - 8 = 3V_2, 3V_1 - 3V_2 + 4V_1 - 4V_3 \\ - 11 = -V_1 - 3V_2 - 4V_3 \quad (iv)$$

From (i) Put  $V_2 + 22 = V_3$  in (iii) & (iv)

$$-V_1 - 4V_2 - 9(V_2 + 22) + 28 = 0$$

$$-V_1 - 13V_2 - 9(22) + 28 = 0$$

$$-V_1 - 13V_2 - 170 = 0 \quad \text{---} \quad (v)$$

$$-11 = -V_1 - 3V_2 - 4(V_2 + 22)$$

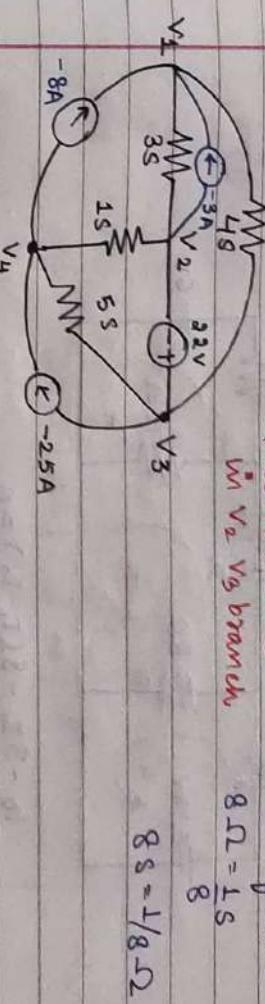
$$-11 = -V_1 - 3V_2 - 4V_2 - 88 \\ -11 = -V_1 - 7V_2 - 88 \\ -7 = -V_1 - 7V_2 \Rightarrow 11 = V_1 - V_2 \Rightarrow 11 + V_2 = V_1$$

$$7(11 + V_2) - 13V_2 = 170$$

$$77 + 7V_2 - 13V_2 = 170$$

$$-6V_2 = 93 \Rightarrow V_2 = -15.5$$

$$7V_1 = 170 + 13V_2 = 170 - 13(15.5) = -4.5 = V_1$$



## SUPER NODE

$\hookrightarrow$  no resistance  
in  $V_2$  vs branch.

\* Summation is  
inverse of Ohms

$$8\Omega = \frac{L}{S}$$

$$8S = 1/8\Omega$$

$$at \text{ node } V_2, apply \text{ KCL};$$

$$(-3) + (-8) = (V_2 - V_3)(3) + (V_1 - V_3)4 \quad -(iii)$$

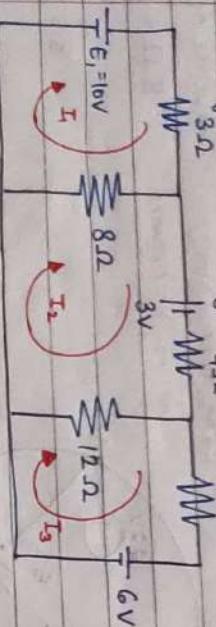
$$at \text{ node } V_3,$$

$$3(V_1 - V_2) + 3 - V_2 = 0 \quad (i) \quad 4(V_1 - V_3) = -25 + 5V_3$$

$$3V_1 + 4V_1 - 4V_2 + 3 - 4V_3 + 25 - 5V_3 = 0 \\ 7V_1 - 4V_2 - 9V_3 + 28 = 0 \quad -(iv)$$

$$V_2 + 22 - V_3 = 0 \quad -(v)$$

HW 01  
using mesh analysis



$$16 - 3I_1 - 8(I_1 - I_2) = 0 \\ -8(I_2 - I_1) - 3 - 4I_2 = 0 \\ -12(I_3 - I_2) - 14I_3 - 6 = 0$$

$$\begin{bmatrix} 10 & 3+8 & 0 \\ -3 & -8 & 0 \\ -6 & 0 & 0 \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = \begin{bmatrix} 16 \\ -3 \\ -6 \end{bmatrix}$$

→ A

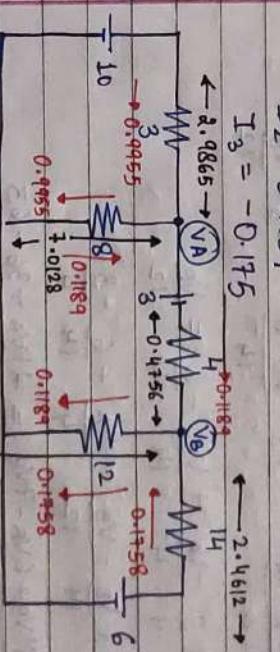
$$\begin{bmatrix} 10 & -8 & 0 \\ -3 & -8 & 24 \\ -6 & 0 & -12 \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = \begin{bmatrix} 16 \\ -3 \\ -6 \end{bmatrix}$$

$$|A| = 12 \left[ (24)(26) - (-12)(-12) \right] - (-8) \left[ (-8)(26) \right] \\ = 12(624 - 144) + 8(-8)(26) \\ = 12(480) - 1664 \\ = 5280 - 1664 = 4616 \text{ Amperes}$$

$$I_3 = -0.1189$$

$$I_1 = 0.4955$$

$$I_2 = 0.1189$$



$$V_A = 10 - 3.9865 = 7.0135 \text{ V}$$

$$V_B = 6 - 2.4612 = 3.635 \text{ V}$$

$$I_{R4} = 0.9955 - 0.1189 = 0.8766 \text{ A}$$

using Nodal Analysis

$$\begin{bmatrix} 10 & 480 & 208 & 96 & 0 & 0 \\ -3 & 208 & 286 & 132 & 1 & 0 \\ -6 & 96 & 132 & 200 & 0 & 1 \end{bmatrix} = \begin{bmatrix} I_1 \\ I_2 \\ I_3 \\ I_4 \\ I_5 \\ I_6 \end{bmatrix}$$

$$A_{11} = 624 - 144$$

$$A_{21} = (-8)(26)$$

$$A_{31} = (8)(12)$$

$$A_{12} = (26)(8)$$

$$A_{22} = (26)(11)$$

$$A_{32} = (11)(-12)$$

$$A_{13} = (8)(12)$$

$$A_{23} = (11)(-12)$$

$$A_{33} = 11(24) - (8)^2$$

$$C_{11} = 480$$

$$C_{21} = (+) 208$$

$$C_{31} = 96$$

$$C_{12} = (+) 208$$

$$C_{22} = 286$$

$$C_{32} = (+) 132$$

$$C_{13} = 96$$

$$C_{23} = (+) 132$$

$$C_{33} = 200$$

$$I_1 = I_2 + I_4$$

$$I_1 = \frac{10 - V_A}{3}, \quad I_2 = \frac{V_A - 3 - V_B}{4} =$$

$$I_4 = \frac{V_A}{8} = \frac{7.01}{8} = 0.876$$

$$\frac{10}{3} - \frac{V_A}{3} = \frac{V_A}{4} - \frac{3}{4} - \frac{V_B}{4} + \frac{V_A}{8}$$

$$\frac{V_B}{4} = \frac{V_A}{4} + \frac{V_A}{3} + \frac{V_A}{8} - \frac{10}{3} - \frac{3}{4}$$

$$\frac{V_B}{4} = \frac{6V_A + 8V_A + 3V_A}{24} - \frac{40 - 9}{12}$$

$$\frac{6V_B}{24} = \frac{17V_A}{24} - \frac{49}{12} \Rightarrow 6V_B = 17V_A - 98$$

$$\Rightarrow \frac{6V_B + 98}{17} = V_A$$

$$I_2 + I_3 = I_5$$

$$\frac{V_A - 3 - V_B}{4} = I_2 \quad ; \quad I_3 = \frac{6 - V_B}{14} \quad ; \quad I_5 = \frac{V_B}{12}$$

$$\frac{V_A}{4} - \frac{3}{4} - \frac{V_B}{4} + \frac{6}{14} - \frac{V_B}{14} = \frac{V_B}{12}$$

$$\frac{V_A}{4} - \frac{3}{4} + \frac{6}{14} = \frac{V_B}{12} + \frac{V_B}{14} + \frac{V_B}{4}$$

$$\frac{21V_A - 63 + 36}{84} = \frac{7V_B + 6V_B + 21V_B}{84}$$

$$21V_A - 27 = 13V_B + 21V_B = 34V_B$$

$$21V_A - 27 = 34V_B$$

$$21 \left( \frac{6V_B + 98}{17} \right) - 27(17) = 34V_B(17)$$

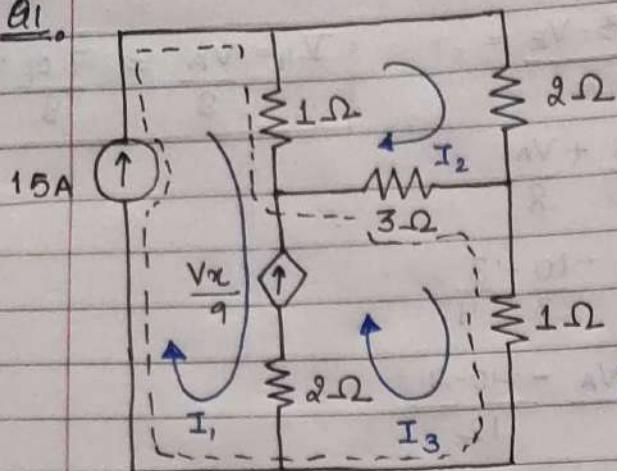
$$126V_B + 98(21) - 27(17) = 34(17)V_B$$

$$126V_B + 2058 - 459 = 578V_B$$

$$1599 = 452V_B$$

$$V_B = 3.53V$$

$$6(3.53) + 98 = V_A = 7.01V$$

Q1.

$$\text{Here } 15A = I_1$$

$$(2) - I_3 - I_1 = \frac{V_x}{9} \quad (\text{Dependent source})$$

$$(3) - 2I_2 - 3(I_2 - I_3) - 1(I_2 - 15) = 0$$

$$(4) -1(15 - I_2) - 3(I_3 - I_2) - 1I_3 = 0$$

$$(2) = I_3 - 15 = \frac{V_x}{9}$$

$$(3) - 2I_2 - 3I_2 + 3I_3 - I_2 + 15 = 0$$

$$-6I_2 + 3I_3 + 15 = 0 \Rightarrow 3I_3 + 15 = 6I_2$$

$$(4) -15 + 15I_2 - 3I_3 + 3I_2 - I_3 = 0$$

$$-15 + 18I_2 - 4I_3 = 0$$

$$-15 + 3(3I_3 + 15) - 4I_3 = 0$$

$$-15 + 9I_3 + 45 - 4I_3 = 0$$

$$30 + 5I_3 = 0$$

$$I_3 = -6$$

$$\frac{3(-6) + 15}{6} = I_2 = \frac{21 + 15}{6} = \frac{36}{6} = 6 = I_2$$

Since we have dependent source, so we can't use super mesh

$$15A = I_1 - \dot{\psi}$$

$$\frac{1}{9}V_x = I_3 - I_1 \Rightarrow V_x = 9I_3 - 9I_1 \Rightarrow V_x = 9I_3 - 9(15)$$

$$V_x = 3(I_3 - I_2) \Rightarrow V_x = 3I_3 - 3I_2 \Rightarrow 9I_3 - 9(15) = 3I_2$$

$$2 - 2I_2 - 3(I_2 - I_3) - 1(I_2 - 15) = 0$$

$$3I_3 + 15 = 6I_2 + \dot{\psi}$$

$$-3I_2 - \dot{\psi}$$

$$9I_3 - 9(15) = 3I_2 - 3I_2$$

$$3I_3 + 15 = 6I_2$$

$$3I_3 = 6I_2 - 15$$

$$3(6I_2 - 15) - 9(15) = 6I_2 - 15 - 3I_2$$

$$18I_2 - 45 - 135 = 6I_2 - 15 - 3I_2$$

$$18I_2 - 3I_2 = 135 + 45 - 15$$

$$15I_2 = 165$$

$$\boxed{I_2 = 11A}$$

$$\boxed{I_2 = 11A}$$

$$3I_3 = 6(11) - 15$$

$$3I_3 = 66 - 15$$

$$I_3 = \frac{51}{3} = 17A$$

$$\boxed{I_3 = 17A}$$

$$V_x = 3(17 - 11) = 18V$$

$$\boxed{V_x = 18V}$$

-3I<sub>2</sub> - 15

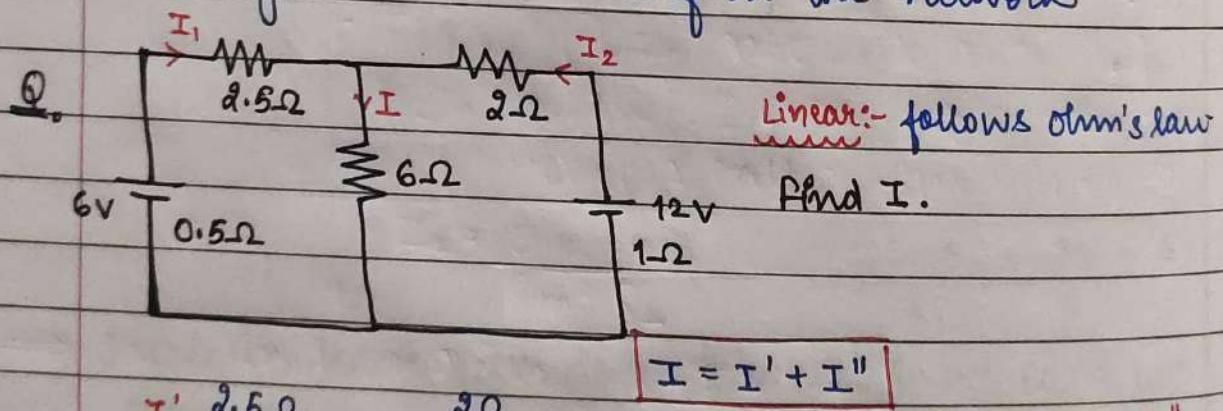
# NETWORK THEOREMS

- Superposition theorem
  - Reciprocity
  - Thvenin
  - Norton
  - Max power transfer theorem (proof → 5 marks)
- } linear bilateral  
Active network.  
(more than 1 source of emf)  
\* Only dependent sources ~~can~~ cannot use.  
\* used for voltage

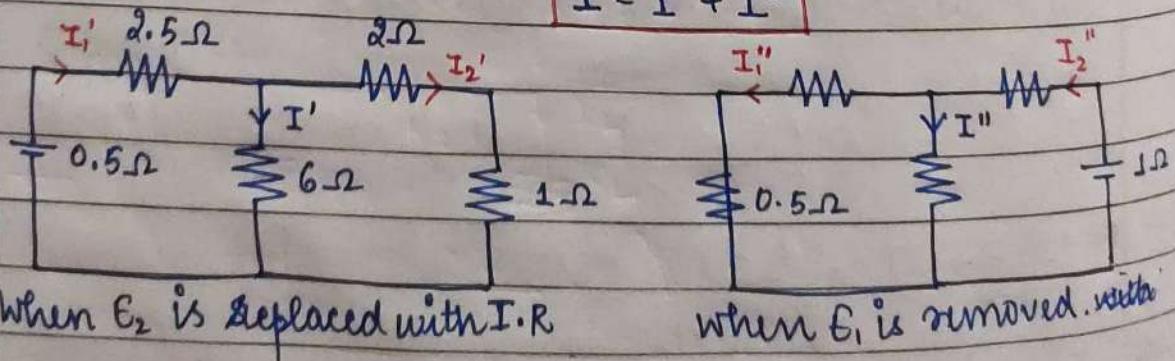
## A. Superposition theorem

"according to this theorem, if there are no. of sources of EMF acting simultaneously in any linear bilateral network then each emf acts independently of the others i.e. as if other emfs did not exist."

In other words, current or voltage across any conductor of network is obtained by superimposing the currents & voltages due to each emf in the network.



$$I = I' + I''$$



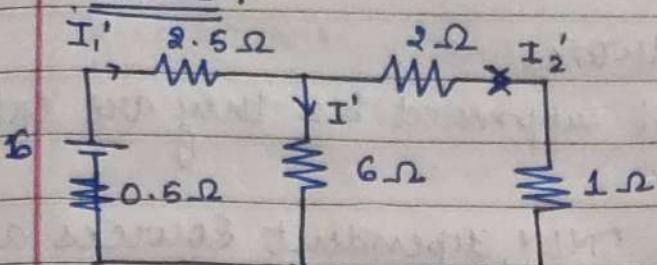
$$I_2 = -I_2' + I_2''$$

\* Dependent sources can never be deactivated / killed.

CLASSTIME Pg. No.

Date / /

Case 1 :-



$$I_1' = \frac{6}{(3||6) + (2.5 + 0.5)} = \frac{6}{5} \text{ A}$$

Apply current div.

$$I' = (I_1') \frac{(2+1)}{(6+2+1)}$$

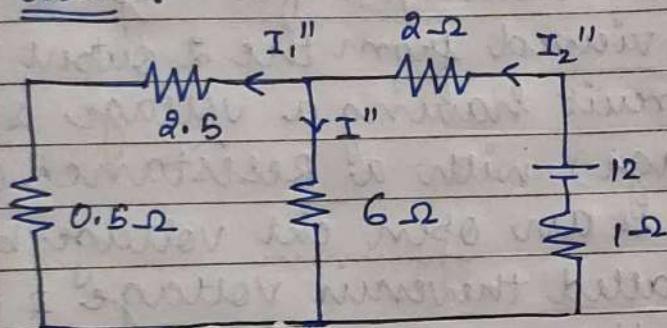
$$I' = \frac{2}{5} \left( \frac{3}{9} \right) = \frac{2}{5} \text{ A}$$

$$I = I_T \frac{( \text{II Resist}(+) )}{( \text{Sum of } R + \text{II } R )}$$

$$I_1' = I' + I_2'$$

$$\frac{2}{5} = \frac{6}{5} + I_2' \Rightarrow I_2' = -\frac{4}{5} \text{ A}$$

Case 2 :-



$$\text{Req} = \left\{ (0.5 + (2.5)) || (6) \right\} + (2+1)$$

$$I_2'' = \frac{12}{5} \text{ A}$$

for I''

Apply current div rule

$$I'' = (I_2'') \frac{(2.5 + 0.5)}{(6 + 2.5 + 0.5)} = \frac{12}{5} \times \left( \frac{3}{9} \right) = \frac{4}{5} \text{ A}$$

$$I_2'' = I_1'' + I''$$

$$\frac{12}{5} = I_1'' + \frac{4}{5} \text{ A} \Rightarrow I_1'' = \frac{8}{5} \text{ A}$$

$$I = I' + I'' = \frac{4}{5} + \frac{2}{5} = \frac{6}{5} \text{ A.}$$

## Limitations

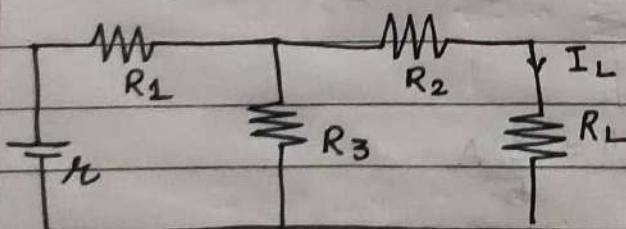
- applied only in linear networks
- Dependent sources are not suppressed bcz they are externally controlled.
- It can't be applied where ONLY dependent sources are there.
- Power can't be determined ~~directly~~ by superposition.  
(bcz Power is non linear quantity, it is not linearly related with V or I)

Date = 10 Dec, 2022

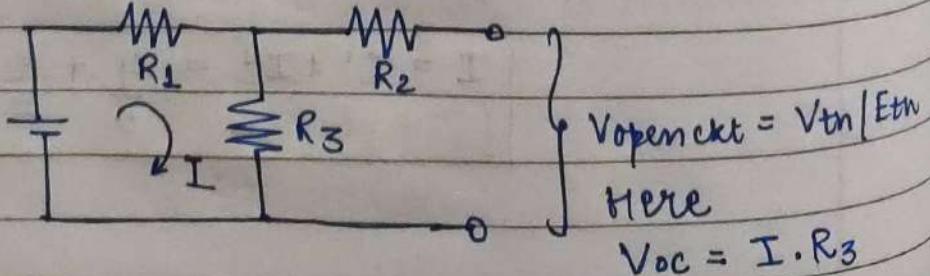
\* \* (B) THEVENIN THEOREM:- (only independent sources are given)  
It is a mathematical technique for replacing a given network ~~as~~ viewed from the 2 output terminals by an equivalent circuit having a voltage source  $E_{th}$  (thevenin's voltage) with a resistance ( $R_{th}$ ) in series where  $E_{th}$  is an open ckt voltage b/w the req. 2 terminals & called thevenin voltage &  $R_{th}$  is equivalent Resis. of the network as seen from the 2 terminals with all <sup>other</sup> sources replaced by their internal resistances, & called thevenin's Resistan

$$I_L = \frac{E_{th}}{R_{th} + R_L}$$

⇒ How to find  $V_{th}$  &  $R_{th}$



(a) Remove  $R_L$   
& find  $V_{th}$

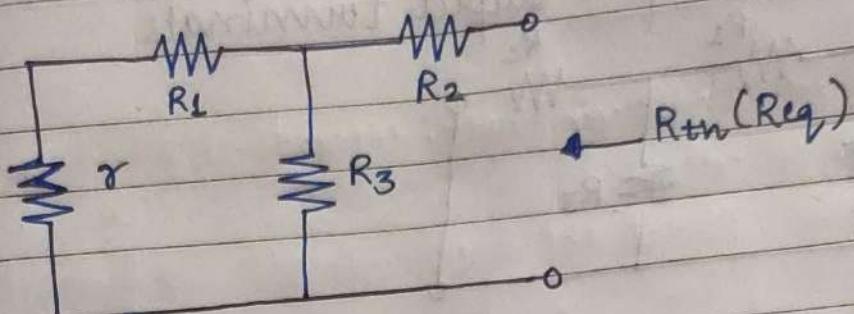


Date / /

(b) for  $R_{th}$ , replace all sources of emf by their internal resistances ( $\infty$ )

$$V_{\text{source}} = \text{S.C}$$

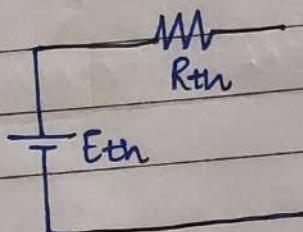
$$\text{C. source} = 0 \cdot \text{C}$$



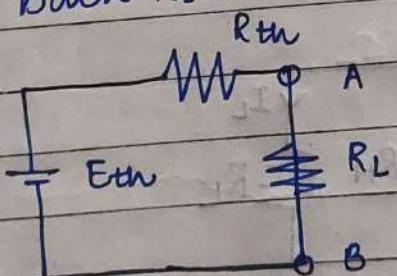
(c) find  $R_{th}$  from terminals  
Here

$$((\infty + R_1) \parallel R_3) + R_2 = R_{th}$$

(d) draw thevenin ckt



(e) connect back  $R_t$



(f) Find  $I_L = \frac{V_{th}}{R_{th} + R_L}$

(g) **NORTON THEOREM**:- (Dual to Thevenin theorem)  
It is a mathematical tech. for ---- having a current source in || of an eq. Resis  $R_N$  ( $I_N$ ) with

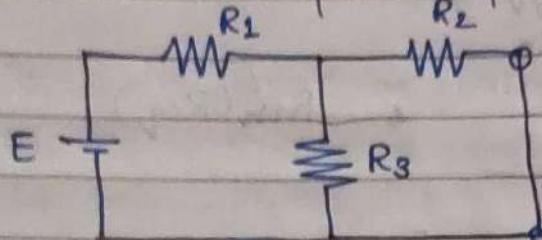
$R_{TH} \rightarrow R_N$

### HOW TO NORTANISE GIVEN CKT

Steps

(1) Remove  $R_L$

(2) Short ckt 2 open output terminals



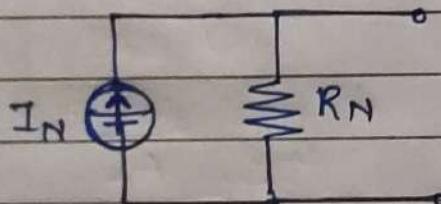
(3) find out short ckt current  $I_N$

$$R_{eq} = (R_2 || R_3) + R_1 ; I = E/R_{eq}$$

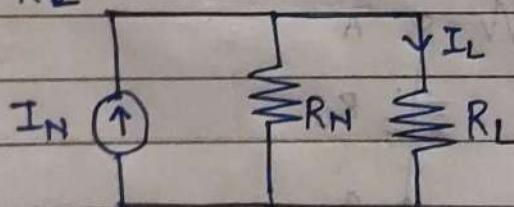
$$I_N = \frac{I \cdot R_3}{R_2 + R_3}$$

(4)  $R_{TH} = R_N$

(5) Draw nortanised ckt

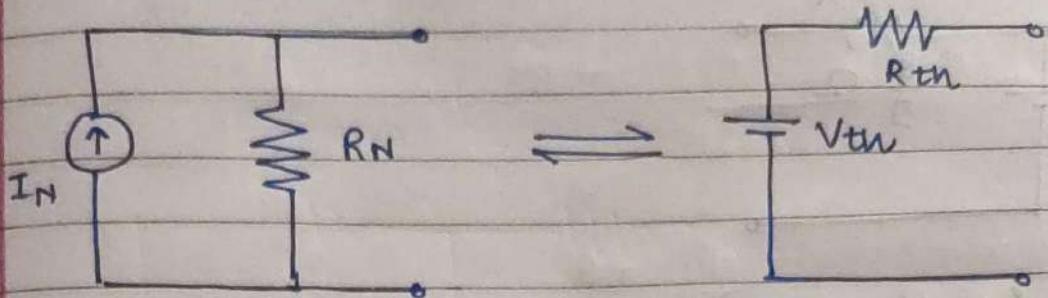


(6) Connect  $R_L$



$$I_L = I_N \cdot \left( \frac{R_N}{R_N + R_L} \right)$$

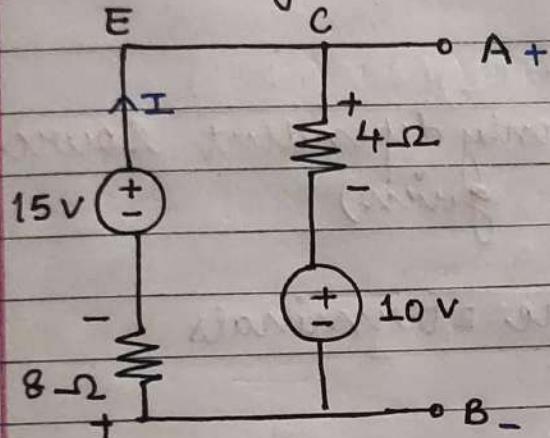
Q. How thevenin & Norton are Dual to each other



Source conversion

$$I_N = \frac{E_{th}}{R_{th}}, \quad R_N = R_{th}$$

Q1. Solve using thevenin, thenenise the ckt



Ans.  $V_{th} = \text{Voltage across } 4\Omega \text{ or } 8\Omega \text{ branch}$

$$-4I - 10 - 8I + 15 = 0$$

$$-12I + 5 = 0$$

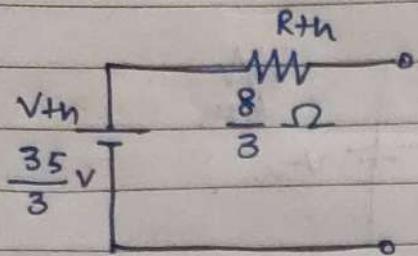
$$\boxed{I = \frac{5}{12} \text{ A}}$$

for  $V_{th}$ ,  $V_{th} = 4I + 10$

$$= 4\left(\frac{5}{12}\right) + 10 = \frac{35}{3} \text{ V}$$

$$R_{th} = \frac{8}{3} \Omega$$

Theveninised ckt



# Thevenin theorem (both dependent & independent sources)

(1)  $V_{th}$  as usual

(2) for  $R_{th}$ , short ckt & terminals, & find  $I_{short}$

$$R_{th} = \frac{V_{th}}{I_{sh}}$$

Same for Nortans

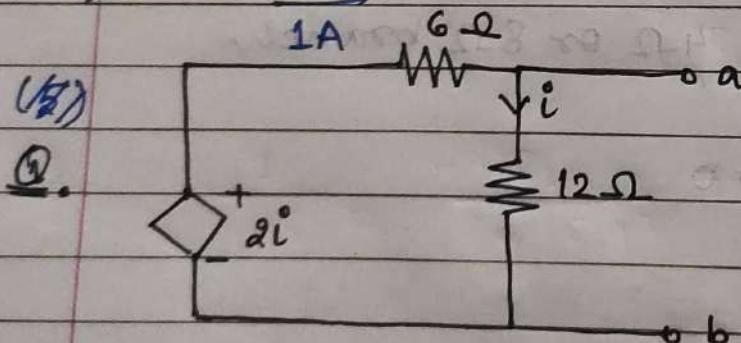
# Thevenin Theorem (when only dependent sources are given)

(1)  $V_{oc} = 0$  /  $V_{th} = 0$

(2) Connect 1A source to the 2 terminals

(3) calculate  $V_{ab}$

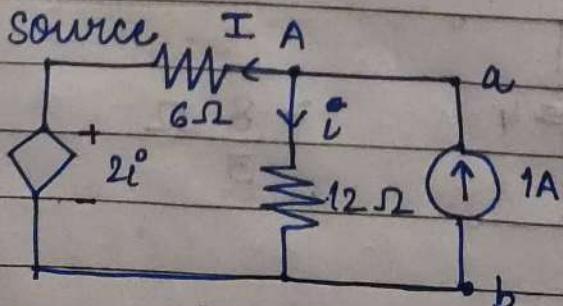
(4)  $R_{th} = \frac{V_{ab}}{I}$



$i = 0$  b/c no independent source

$$\Rightarrow V_{th} = 12i = 0 \quad | \quad V_{oc} = 0V$$

Connect 1A source



$$I + i = 1 \text{ A}$$

(Nodal analysis)

$$\frac{2i - V_{ab}}{6} - \frac{V_{ab}}{12} + 1 = 0 \quad \rightarrow$$

$$4i - 3V_{ab} = -12$$

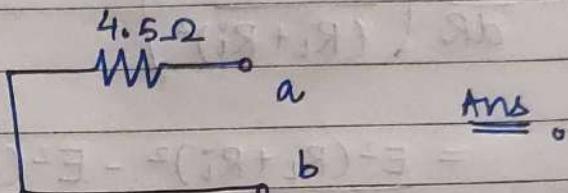
$$i = \frac{V_{ab}}{12} \quad \text{---(ii)}$$

Put (ii) in (i)

$$V_{ab} = 4.5$$

$$R_{th} = \frac{V_{ab}}{1} = 4.5 \text{ V}$$

Thvenin ckt

Ans.

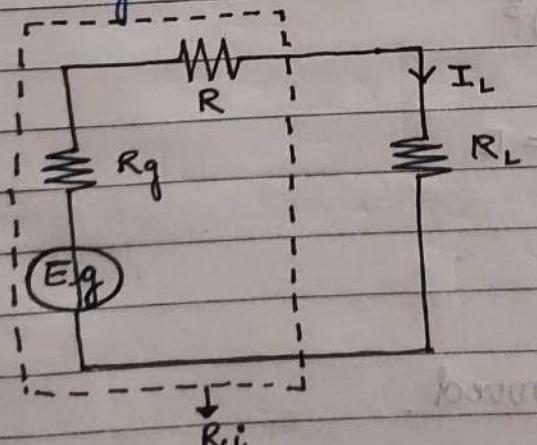
Date = 12 Dec, 2022

(D) MAXIMUM POWER TRANSFER THEOREM :-

(application or extension of Thvenin theorem)

# 5 Marks important ques (Derivation + graph)

A resistive load will abstract max power from a network when the load resistance is equal to the resistance of the network as viewed from the output terminals with all energy sources removed leaving behind their internal Resistances.



$$\text{Let } R_i = R_g + R$$

then  $R_L = R_i$  for max power transfer.

(Transfer efficiency  $\eta$ ) = 50%.

$$I = \frac{E}{R_L + R_i}$$

$$P_L = I^2 R_L = \frac{E^2 \cdot (R_L)}{(R_L + R_i)^2} \quad \text{--- (i)}$$

for maxima  $\frac{dP_L}{dR_L} = 0$

Put P from (i)

$$\frac{d}{dR} \left( \frac{E^2 (R_L)}{(R_L + R_i)^2} \right)$$

$$= \frac{E^2 (R_L + R_i)^2 - E^2 (R_L) (2(R_L + R_i))}{(R_L + R_i)^4}$$

$$\frac{dP}{dR} = E^2 \left[ \frac{1}{(R_L + R_i)^2} - \frac{2(R_L)}{(R_L + R_i)^3} \right]$$

either  $E^2 = 0$  or  $\left[ \frac{1}{(R_L + R_i)^2} - \frac{2R_L}{(R_L + R_i)^3} \right] = 0$

$$\frac{1}{(R_L + R_i)^2} - \frac{2R_L}{(R_L + R_i)^3} = 0$$

$$\frac{R_L + R_i - 2R_L}{(R_L + R_i)^3} = 0$$

$$R_i = R_L$$

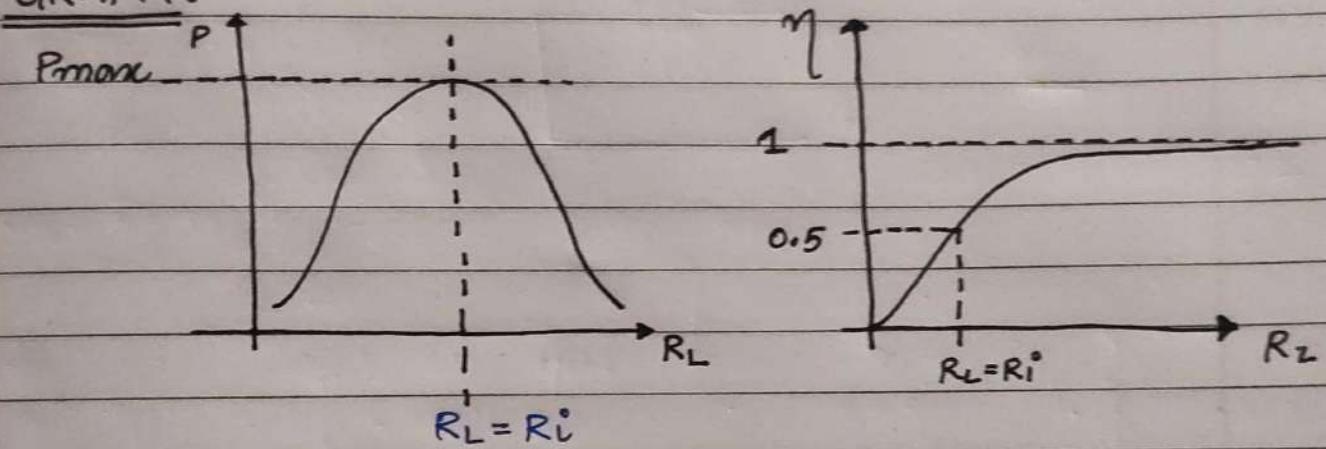
Hence Proved.

Put  $R_L = R_i$  in ④

$$\begin{aligned} P_{\max} &= \left( \frac{E}{2R_L} \right)^2 (R_L) \\ &= \frac{E^2}{4R_L^2} \cdot R_L \end{aligned}$$

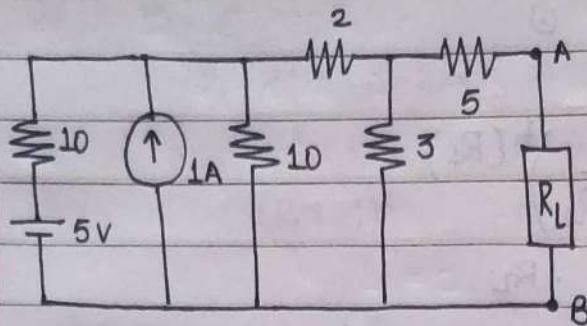
$$P_{\max} = \frac{E^2}{4R_L} = \frac{(V_{TH})^2}{4R_L}$$

GRAPH:-

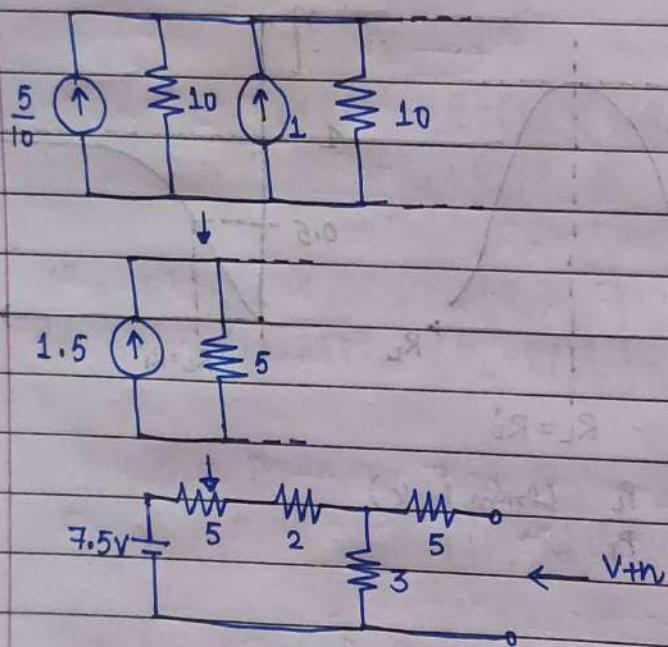


# Proof of  $\eta = \frac{P_L}{P_T}$  (from book)

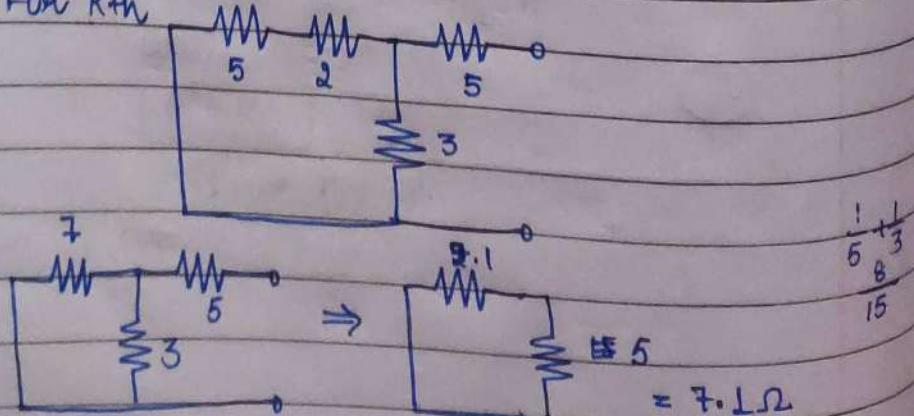
Date :- 14 Dec, 2022

Q1.Find  $R_L$  for Max powerAns. For Max power  $R_L = R_{th}$ 

$$P_{max} = \frac{V_{th}^2}{4R_L}$$



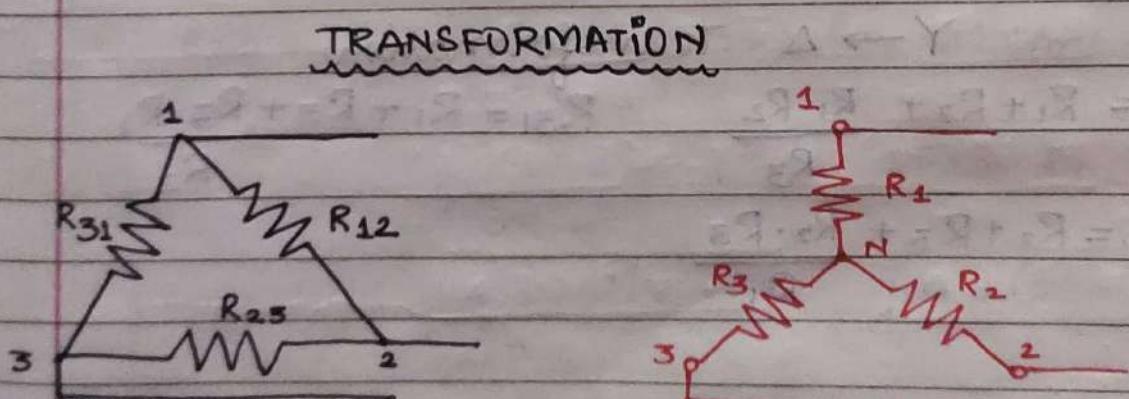
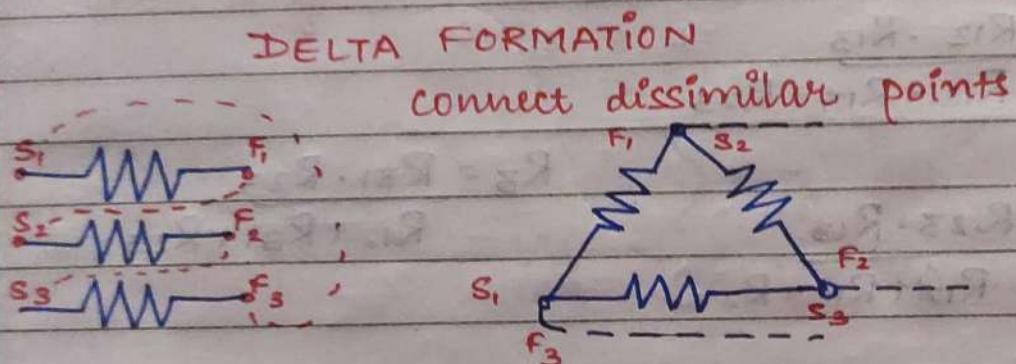
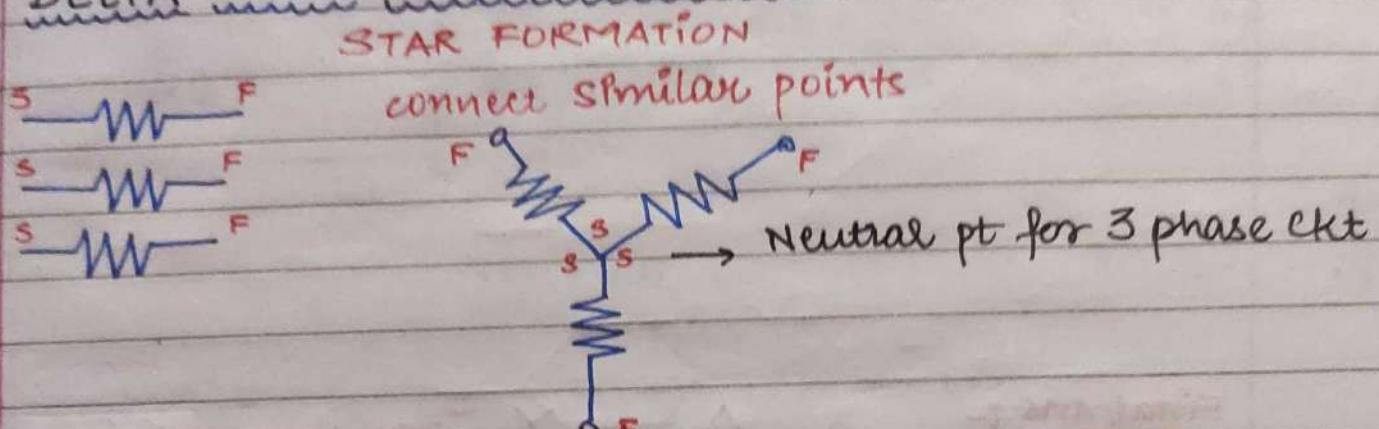
$V_{th}$  = Voltage drop across  $3\Omega$  resistance  
 Voltage division =  $\frac{3(5+5)}{10} = 2.25V$

For  $R_{th}$ 

$$P_{\max} = \frac{(2.25)^2}{4(7.1)} = \frac{5.0625}{28.4} = 0.178 \text{ W}$$

$$R_m = R_L = 7.1 \Omega$$

## # DELTA - STAR TRANSFORMATION :-



For electrically equivalent  
 $\Rightarrow$  Resistance b/w any pair of terminals is same

for S connection :- Resist b/w 1 & 2  $\Rightarrow R_{12} || (R_{31} + R_{23})$

$$= \frac{R_{12}(R_{23} + R_{31})}{R_{12} + R_{23} + R_{31}}$$

Q

for star connection

$$\text{Res b/w } 1 \& 2 = R_1 + R_2 \rightarrow ①$$

for electrically equivalent

$$1 = 2$$

Final ans :-

$\Delta \rightarrow Y$  Transformation.

$$R_1 = \frac{R_{12} \cdot R_{13}}{R_{12} + R_{13} + R_{23}}$$

$$R_2 = \frac{R_{23} \cdot R_{13}}{R_{12} + R_{13} + R_{23}}$$

$$R_3 = \frac{R_{31} \cdot R_{23}}{R_{12} + R_{31} + R_{23}}$$

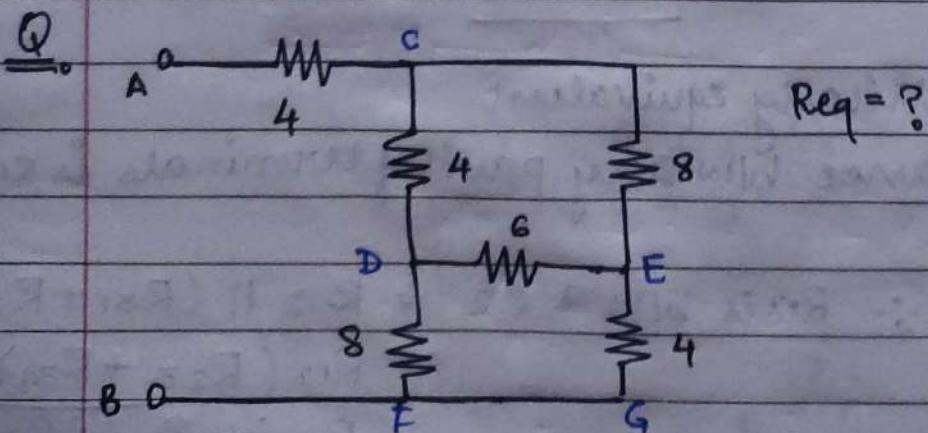
$$R_3 = \frac{R_{31} \cdot R_{23}}{R_{12} + R_{31} + R_{23}}$$

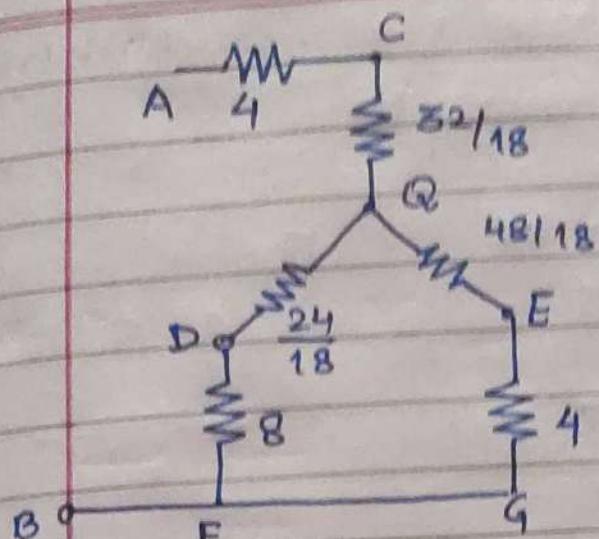
$Y \rightarrow \Delta$  Transformation

$$R_{12} = R_1 + R_2 + \frac{R_1 \cdot R_2}{R_3}$$

$$R_{31} = R_1 + R_3 + \frac{R_3 \cdot R_1}{R_2}$$

$$R_{23} = R_2 + R_3 + \frac{R_2 \cdot R_3}{R_1}$$



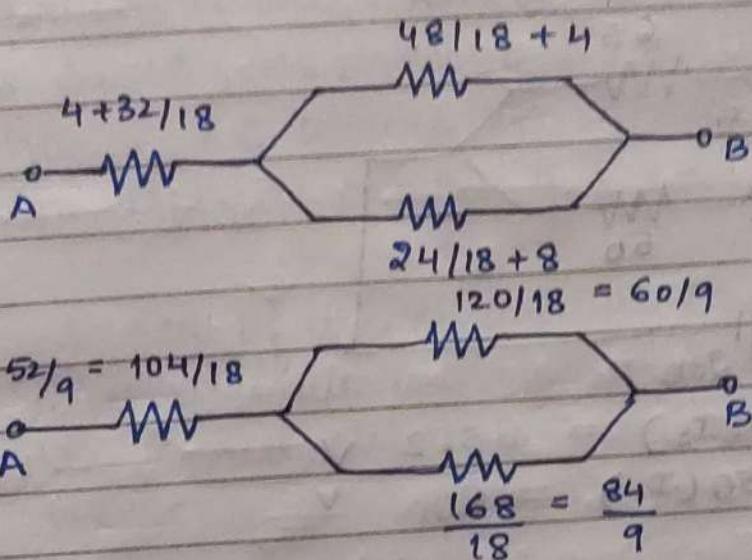


$$R_C = \frac{R_{CD} \cdot R_{CE}}{R_{CD} + R_{CE} + R_{DE}}$$

$$= \frac{32}{18}$$

$$R_D = \frac{24}{18} \quad R_E = \frac{48}{18}$$

$$\frac{72}{18} + \frac{32}{18} = \frac{104}{18}$$

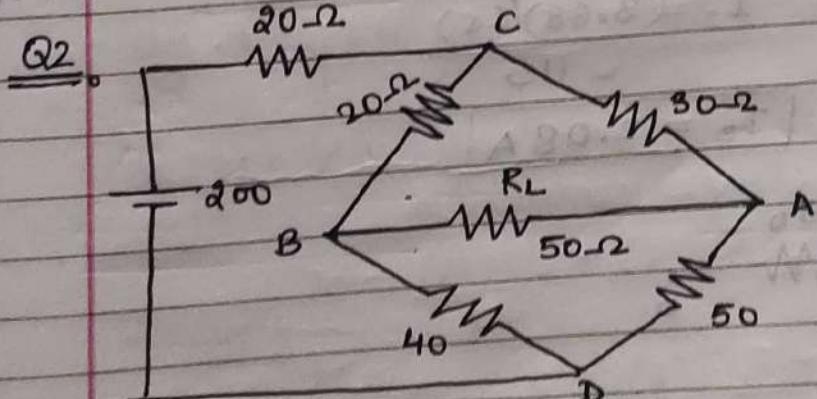


$$R_{AB} = \frac{87}{9} \Omega$$

$$\frac{118}{18} \quad \frac{48}{18}$$

$$\frac{144}{168} \quad \frac{24}{168}$$

$$R_{AB} = \frac{52}{9} + \left( \frac{60}{9} + \frac{84}{9} \right) = \frac{87}{9} \Omega \text{ Ans.}$$



Find  $I_{RL}$

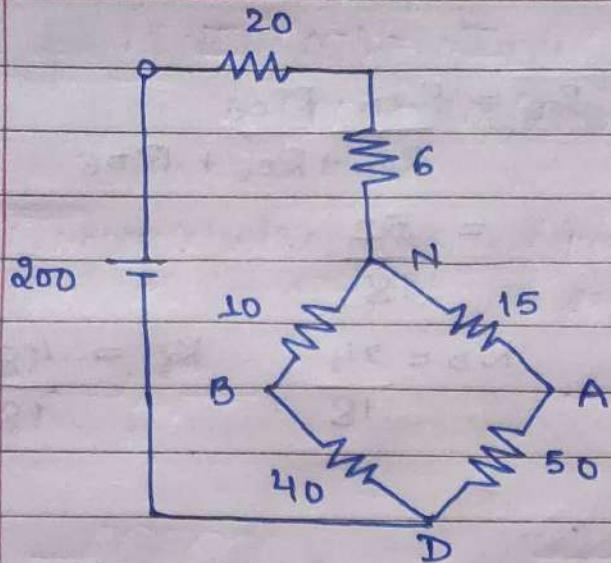
$$I_{RL} = (50)(V_{AB}) / (50)$$

$$x = \frac{20 \cdot 30}{100} = 6 \Omega$$

$$z = 15 \Omega$$

$$y = \frac{1000}{100} = 10 \Omega$$

Ans: - 0.65V



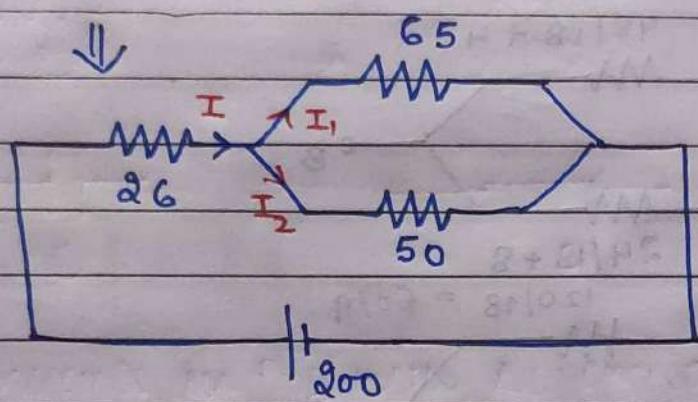
$$\frac{1}{65} + \frac{1}{50}$$

$$10 + 13$$

$$650$$

$$\frac{650}{23}$$

$$= 28.26$$



$$I = \frac{200}{26 + 28.26}$$

$$= 200$$

$$54.26$$

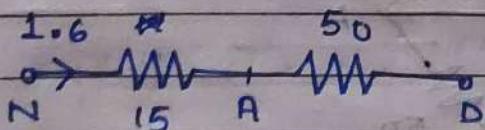
$$= 3.68$$

$$I_1 = \frac{I(50)}{65 + 50} \quad I_2 = \frac{I(65)}{65 + 50}$$

$$I_1 = \frac{3.68(50)}{115} \quad I_2 = \frac{(3.68)(65)}{115}$$

$$I_1 = 1.6 \text{ A}$$

$$I_2 = 2.08 \text{ A}$$



\*\* Pot diff b/w A & B is 3.2 V

$$I_{RL} = 50 \times 3.2 = 160 \text{ A} \quad 15.625 \text{ V}$$

# AC FUNDAMENTAL

AC :- Magnitude & direction changes w.r.t time.

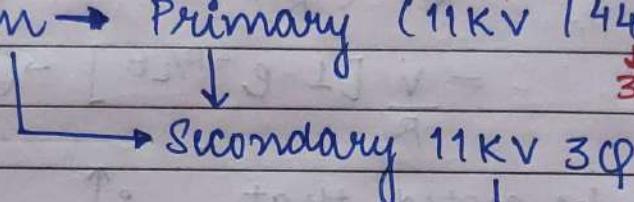
(d)

# IMPORTANCE OF AC

# Power System :-

Generation  $\rightarrow$  11 KVTransmission  $\rightarrow$  132 KV, 66 KVDistribution  $\rightarrow$  Primary (11 KV  $\downarrow$  440 V)  $\rightarrow$  output

3φ



#

(a)

(b)

(c)

(d)

$$(a) P = VI \cos \theta$$

 $\downarrow$   
 $\downarrow$   
 Const
 

vary

 $I \propto$  load

$$P = \text{const} \Rightarrow V \propto \frac{1}{I}$$

$$V \uparrow \rightarrow I \downarrow \rightarrow \boxed{\text{LOSSES} \downarrow}$$

#

(a)

(b)

(b) less cost & wt of wire bcs these quantities  $\propto \frac{1}{I}$   
 wt of wire  $\propto$  tower size  $\propto$  ckt breaker  $\propto \frac{1}{I}$   
 Rating of appliances.

 $I \downarrow$  hence these things are less.

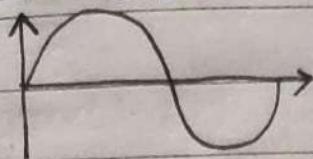
(c) Induction motor works on AC as DC motors cannot do heavy work. Induction motors are robust (no heating on heavy work)

(c)

(d)

(d)

Natural zero break :- shock prevention.



# Adv of choosing sinusoidal wave form over other produces less losses

(a) ↓ Harmonics :- less Freq (undesirable)

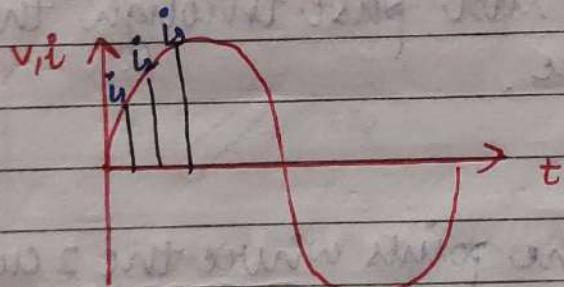
(b) ↓ Interferences with communication ckt.

(c) ↓ Noise

# Important Terms.

(a) Waveform :- shape of the curve ( $V$  or  $I$ ) when plotted against time.

(b) Instantaneous value :- value of quantity at any particular instant is called Instantaneous value



all instantaneous values are written in small letters

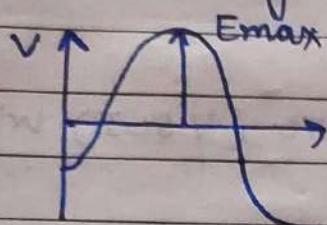
(c) Frequency (Hz) :- NO. of cycles in 1 sec.

$$f = \frac{1}{T}$$

(d) Time Period (sec) :-

Time taken to complete one cycle

- (e) Cycle :- Set of all +ve & -ve instantaneous values in 1 cycle.
- (f) Half Cycle / Alternation :- Set of all +ve values  $\rightarrow$  +ve half cycle  
Set of all -ve values  $\rightarrow$  -ve half cycle.
- (g) Amplitude / Peak value / Crest value / Max value :-  
The max mag (+ve/-ve) which an alternating qty attains during one cycle.

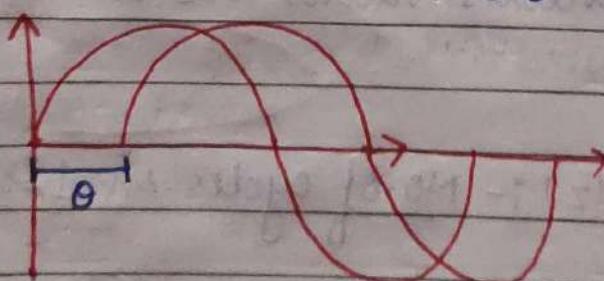


- (h) Phase / Phase Angle :-

Fraction of T.P of alternating qty that has elapsed since the current last past through the zero position of reference.

- (i) Phase difference :-

Angular dis b/w the points where the 2 curves cross the reference value in the same dir.



- (j) Avg value :-

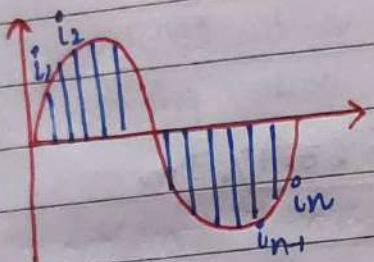
Sum of all instantaneous

Arithmatic avg of all inst. values considered of an alternating qty over one cycle.

$I_{av}, V_{av} \rightarrow \text{Representation}$

(k) Symmetrical Alt. q'ty :-  
wave +ve half cycle = -ve half cycle.

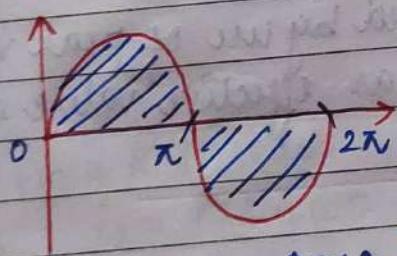
For sym. alt. q'ty, avg value = 0.



$$\text{avg} = \frac{i_1 + i_2 + \dots + i_{n-1} - i_n}{n} = 0$$

For unsymmetrical alt. q'ty, avg value  $\neq 0$

$\Rightarrow$  Integral Calculus Method for Avg value.



= Area under graph  
 $\theta 2\pi = \text{base}$

$I_{av} = \frac{\text{Area of alternation}}{\text{base}}$

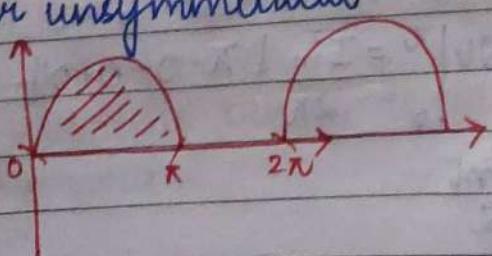
Integration at home

For pure wave form :- we take for half cycle.

$I_{av} = \frac{\int_0^\pi I_m \sin \theta}{\pi} = \frac{2I_m}{\pi}$

$\therefore I_{av} = 0.637 I_m$

For unsymmetrical



$$I_{av} = \frac{\int_0^\pi I_m (\text{wave eqn})}{2\pi}$$

limit :- where we see actual waveform  
base :- when next cycle start.

Q. Derivation of avg value of current

$$\begin{aligned} I_{av} &= \frac{1}{\pi} \int_0^{\pi} I_0 \sin \theta \, d\theta \\ &= \left[ I_0 (-\cos \theta) \right]_0^{\pi} \\ &= \frac{2 I_0}{\pi} = 0.637 I_m = 63.7\% I_m \end{aligned}$$

Date 24 Dec, 2022

(L) Root mean square value :

(written in capital letters)

$$V = V_m \sin \theta$$

All instruments, Ammeter, Voltmeter measure RMS value. It is used for calculations.

- (1) Protective devices are calculated by use of peak values.
- (2) RMS values are also known as effective value & virtual value.

$$I_{rms} = \sqrt{\frac{1}{\pi} \int_0^{\pi} i^2 \, d\theta}$$

$$I_{rms}^2 = \frac{1}{\pi} \int_0^{\pi} I_m^2 \sin^2 \theta \, d\theta = \frac{I_m^2}{\pi} \int_0^{\pi} \sin^2 \theta \, d\theta$$

$$= \frac{I_m^2}{\pi} \int_0^{\pi} \left( \frac{1 - \cos 2\theta}{2} \right) \, d\theta = \frac{I_m^2}{2\pi} \int_0^{\pi} (1 - \cos 2\theta) \, d\theta$$

$$= \frac{I_m^2}{2\pi} \left| \theta - \frac{1}{2} \sin 2\theta \right|_0^{\pi} = \frac{I_m^2}{2\pi} | \pi - 0 - 0 + 0 |$$

$$I_{rms} = \frac{I_m}{\sqrt{2}}$$

Q1

Ans

Q2

(2)

(3)

(4)

$$\therefore I_{\text{rms}} = \frac{I_m}{\sqrt{2}} = 0.707 I_m$$

(m) Form factor :-

It is the ratio of RMS value of AC to Avg value of AC for pure sinusoidal wave.

$$F.F = \frac{\text{RMS value}}{\text{Avg value}} = \frac{0.707 I_m}{0.637 I_m}$$

$$K_f = F.F = 1.1$$

(n) Peak factor / crest factor / Amplitude factor :-

It is the ratio of peak value of AC qty to RMS value of AC qty

$$K_p = \frac{\text{Peak value}}{\text{RMS value}} = \sqrt{2} = 1.414$$

Q1. Find RMS value

$$i_2 = 12 \sin \omega t + 5(\sin \omega t - 3\pi/2) + 8 + 24 (\sin \omega t - 5\pi/2)$$

Ans.

$$I_{\text{rms}} = \sqrt{\left(\frac{12}{\sqrt{2}}\right)^2 + \left(\frac{5}{\sqrt{2}}\right)^2 + 8^2 + \left(\frac{24}{\sqrt{2}}\right)^2}$$

$$= \sqrt{\frac{973}{2}} = \sqrt{486.5}$$

Q2. A sinusoidal varying current AC of 50 Hz max value of 15A. Write eqn for instantaneous value.

(1) Current after 1200 sec.

(2) Find time taken to reach 10A for 1st time.

(3) Avg value.

A2:-

$$V = 60 \text{ Hz}$$

$$I_m = 15 \text{ A}$$

$$\omega = 2\pi V = 120 \pi$$

(ii)  $I_{t=0} = I_m \sin \omega t = 15 \sin(120\pi) \left(\frac{1}{200}\right) = 15 \sin\left(\frac{3}{5}\right)$   
 $= 15 \sin(0.6) = 14.266$

(iii)  $I_t = 10 = 15 \sin 120\pi t$

$$\sin^{-1}\left(\frac{2}{5}\right) = 120\pi t = \frac{\sin^{-1}(2/5)}{120\pi} = t$$

(iv) Avg value  $= \frac{2(15)}{\pi} = 9.55 \text{ A}$

(v) Instantaneous current  $= i = 15 \sin 120\pi t$

Q3. An AC source sinusoidal has current RMS value of 40A at 50Hz frequency. Write the expression of

(i) Instantaneous Current

(ii) current at 0.02 sec after passing through max +ve value.

A3.  $I_{RMS} = 40 \text{ A} ; V = 50 \text{ Hz}$

$$\frac{I_m}{\sqrt{2}} = I_{RMS} \Rightarrow I_m = \sqrt{2} I_{RMS} = \sqrt{2}(40) = 40\sqrt{2} \text{ A}$$

$$\omega = 2\pi V = 100\pi$$

$$i = I_m \sin \omega t \\ = 40\sqrt{2} \sin 100\pi t$$

HW ques  
 Q1. Half wave Rectifier form factor.  $1.57$  (Derivation)  
 Q2. Peak form factor for half wave.

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 100  
 264

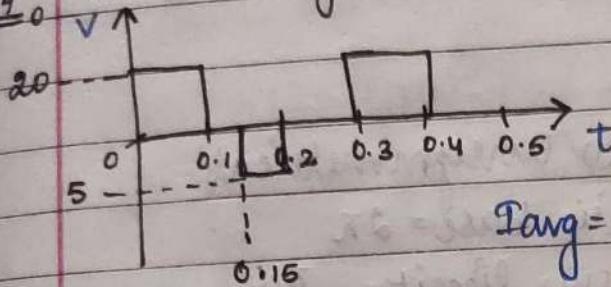
$$40\sqrt{2} = 40\sqrt{2} \sin 100\pi t$$

$$t/2 = 100\pi t \quad t = 1/200$$

$$t = 1/200 + 0.02 = 0.07$$

$$40\sqrt{2} \sin 7\pi = I_{avg} = 0$$

Q4. Find Average & RMS value.



$$I_{avg} = \frac{1}{0.2} \left[ \int_0^{0.1} 20 dt + \int_{0.1}^{0.2} -5 dt \right]$$

$$I_{avg} = \frac{1}{0.2} \left[ [20t]_0^{0.1} + [-5t]_{0.1}^{0.2} \right]$$

$$= \frac{10}{3} \left[ 20 \cdot (0.1) - (5 \cdot 0.2 - 5 \cdot 0.15) \right]$$

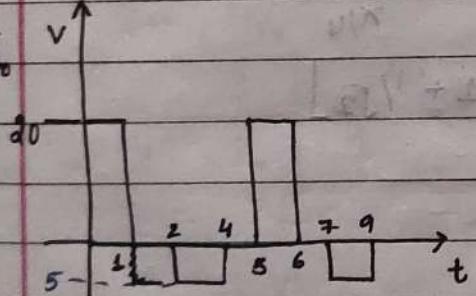
$$= \frac{10}{3} \left[ 2 - (1 - 0.75) \right] = \frac{10}{3} \times 1.75 = \frac{17.5}{3} = I_{avg}$$

-: I rms at end :-

Date :- 28 Dec, 2022

Q5. find Avg. & RMS value.

$$V_{avg} = \frac{1}{5} \int V(t) dt$$



$$= \frac{1}{5} \left[ \int_0^1 (20 \cdot dt) + \int_2^4 (-5 \cdot dt) \right]$$

$$= \frac{1}{5} \left[ [20t]_0^1 - [5t]_2^4 \right]$$

$$= \frac{1}{5} [20(1) - 20(0) - (5(4) - 5(2))]$$

$$= \frac{1}{5} [20 - 10] = 2$$

$$RMS = \sqrt{(V_{avg})^2} = \sqrt{\frac{1}{5} \left[ \int V(t)^2 dt \right]}$$

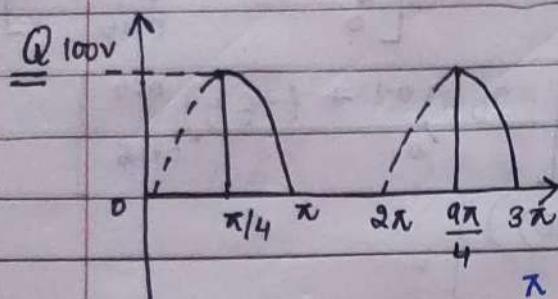
$$= \sqrt{\frac{1}{5} \left[ \int_0^1 (20^2 dt) + \int_2^4 (5^2 dt) \right]}$$

$$\frac{\theta}{t} = \omega$$

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$$\sqrt{\frac{1}{5} \left( \int_0^1 400(t) + 25t \right)^2}$$

$$= \sqrt{\frac{1}{5} (400 + 50)} = \sqrt{\frac{450}{5}} = \sqrt{90}$$



i) unsymmetrical

ii) base =  $2\pi$

iii) limit =  $\pi/4 \rightarrow \pi$

$$V_{avg} = \frac{1}{2\pi} \int_{\pi/4}^{\pi} 100 \sin(\omega t) dt$$

$\omega t \rightarrow \theta$   
 $dt \rightarrow d\theta$

$$= \frac{1}{2\pi} (100) (-\cos \theta) \Big|_{\pi/4}^{\pi}$$

$$= \frac{100 - 50}{\pi} [-1 + 1/\sqrt{2}]$$

$$= 27.018$$

$$V_{rms} = \sqrt{\frac{1}{2\pi} \int (100)^2 (\sin \theta)^2 d\theta}$$

$$2\sin^2 \theta = 1 - \cos 2\theta$$

$$= \sqrt{\frac{10000}{2\pi} \int_{\pi/4}^{\pi} \sin^2 \theta d\theta}$$

$$= \sqrt{\frac{10000}{4\pi} \int_{\pi/4}^{\pi} (1 - \cos 2\theta) d\theta}$$

$$= \sqrt{\frac{2500}{\pi} \left[ \theta - \frac{\sin 2\theta}{2} \right]_{\pi/4}^{\pi}}$$

put  $\pi = 3.14$

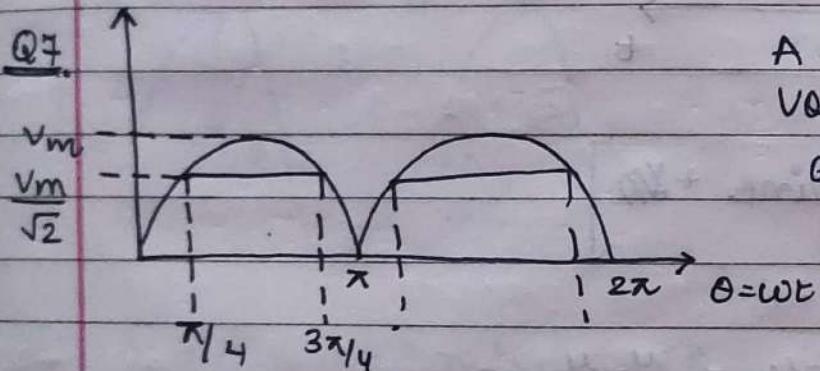
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$$= \sqrt{\frac{2500}{\pi}} \left[ \frac{\pi - \sin \frac{\pi}{2}}{2} - \frac{\pi}{4} + \frac{\sin 2(\pi/4)}{2} \right]$$

$$= \sqrt{\frac{2500}{\pi}} \left[ \frac{3\pi}{4} + \frac{1}{2} \right]$$

$$= \sqrt{\frac{3(25)(100)^2}{4} + \left( \frac{2500}{\pi} \right) \left( \frac{1}{2} \right)}$$

$$= \sqrt{1875 + 398.08} = \sqrt{2,273.08} = 47.67$$



A full Rectified Sinusoidal Voltage clipped at  $1/\sqrt{2}$  of its max value.

$$V_{avg} = \frac{1}{\pi} \left[ \int_0^{\pi/4} V_m \sin \theta d\theta + \int_{\pi/4}^{3\pi/4} V_m d\theta + \int_{3\pi/4}^{\pi} V_m \sin \theta d\theta \right]$$

$$= \frac{1}{\pi} \left[ V_m \left[ -\cos \theta \right]_0^{\pi/4} + \frac{V_m}{\sqrt{2}} \left[ \theta \right]_{\pi/4}^{3\pi/4} + V_m \left[ -\cos \theta \right]_{3\pi/4}^{\pi} \right]$$

$$= \frac{1}{\pi} \left[ -V_m \left[ \cos \frac{\pi}{4} - \cos 0 \right] + \frac{V_m}{\sqrt{2}} \left[ \frac{3\pi}{4} - \frac{\pi}{4} \right] + V_m \left[ \cos \pi - \cos \frac{3\pi}{4} \right] \right]$$

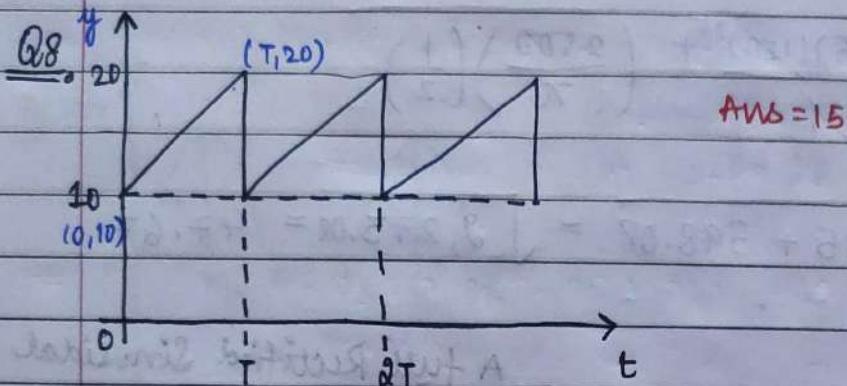
$$= \frac{1}{\pi} \left[ -V_m \left[ \frac{1 - \frac{\sqrt{2}}{2}}{\sqrt{2}} \right] + \frac{V_m \pi}{\sqrt{2}} - V_m \left[ -1 - \left( -\frac{1}{\sqrt{2}} \right) \right] \right]$$

$$= \frac{1}{\pi} \left[ -V_m \left[ \frac{1 - \sqrt{2}}{\sqrt{2}} \right] - V_m \left[ \frac{-1 + 1}{\sqrt{2}} \right] + \frac{V_m \pi}{2\sqrt{2}} \right]$$

$$= \frac{1}{\pi} \left[ -2V_m \left[ \frac{1 - \sqrt{2}}{\sqrt{2}} \right] + \frac{V_m \pi}{2\sqrt{2}} \right] = V_m \left[ -\frac{2}{\pi} \left( \frac{1 - \sqrt{2}}{\sqrt{2}} \right) + \frac{\pi}{2\sqrt{2}} \right]$$

$$V_m \left( \frac{(-0.636)(-0.414)}{1.414} + 0.353 \right)$$

$$V_m (0.186 + 0.353) = V_m (0.54)$$



$$y_{avg} = \frac{1}{T} \int_0^T [y_{line} + k_1]$$

$$\text{eqn of line} \Rightarrow \frac{y_2 - y_1}{x_2 - x_1} = \frac{y - y_1}{x - x_1}$$

$$\frac{20 - 10}{T - 0} = \frac{y - 10}{x - 0}$$

$$\frac{10}{T} = \frac{y - 10}{x}$$

$$10x = yT - 10T$$

$$10(t) = yT - 10T \quad (x=t)$$

$$\frac{10(t) + 10(T)}{T} = y$$

$$y = \frac{10t}{T} + 10$$

$$y_{avg} = \frac{1}{T} \int_0^T \left[ \frac{10t}{T} + 10 \right] dt + \int_0^T 10 dt$$

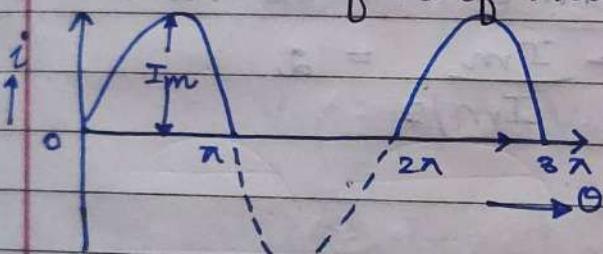
$$\frac{1}{T} \left[ \int_0^T \left( \frac{10t}{T} \right)^2 dt + \int_0^T 10 dt \right]$$

$$\frac{1}{T} \left[ \frac{10}{T} \left( \frac{t^2}{2} \right)_0^T + 10T \right]$$

$$\frac{1}{T} \left[ \frac{10}{T} \left( \frac{T^2}{2} \right) + 10T \right]$$

$$5 + 10 = 15$$

# RMS value of Half Wave Rectifier



$$I_{RMS} = \sqrt{\frac{1}{2\pi} \int_0^\pi I_m^2 \sin^2 \theta d\theta}$$

$$= \sqrt{\frac{I_m^2}{2\pi} \int_0^\pi \left[ \frac{1 - \cos 2\theta}{2} \right] d\theta}$$

$$= \sqrt{\frac{I_m^2}{2\pi} \left( \frac{\theta}{2} + \frac{\sin 2\theta}{4} \right)_0^\pi}$$

$$= \frac{I_m}{2} \sqrt{\frac{1}{\pi} \left( \pi - \cancel{\sin \frac{2\pi}{2}} - 0 - \cancel{\sin 0} \right)}$$

$$I_{RMS} = \frac{I_m}{2}$$

## # AVERAGE VALUE OF HALF WAVE RECTIFIER :-

$$I_{av} = \frac{1}{2\pi} \int_0^{\pi} I_m \sin \theta d\theta$$

$$= \frac{I_m}{2\pi} \left[ -\cos \theta \right]_0^\pi = \frac{I_m}{\pi}$$

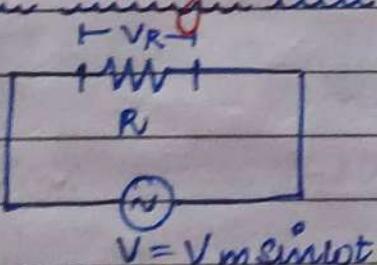
## # FORM FACTOR OF HALF WAVE RECTIFIER :-

$$F.F = \frac{\text{RMS value}}{\text{Peak Avg value}} = \frac{I_m/2}{I_m/\pi} = \frac{\pi}{2} = 1.57$$

## # PEAK FORM FACTOR OF HALF WAVE RECTIFIER

$$P.F = \frac{\text{Peak value}}{\text{RMS value}} = \frac{I_m}{I_m/2} = 2$$

Date :- 29 Dec, 2022.

AC through Pure RESISTIVE CIRCUIT

$$\text{Voltage} = V_m \sin \omega t = v - 2$$

$$\text{instantaneous current} = i$$

$$\text{V drop across } R \text{ is } V_R = iR - 3$$

$$\text{for equilibrium } i = 2$$

$$V_R = iR = V_m \sin \omega t$$

$$i = \frac{V_m}{R} \sin \omega t$$

$$\text{for } \sin \omega t = 1 \quad i = \frac{V_m}{R} = \frac{I_m}{R}$$

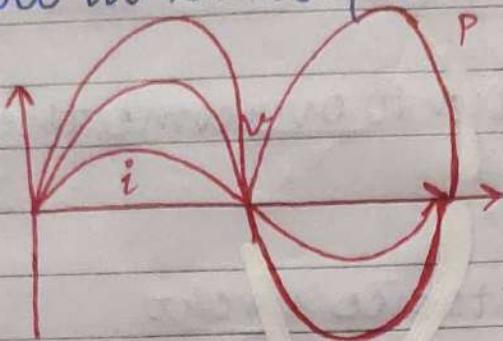
$$i = I_m \sin \omega t - 3$$

comparing ② & ③

$$\text{for } v = V_m \sin \omega t$$

$$I = i = I_m \sin \omega t$$

$v, i$  are in same phase. for only R ckt



$$\begin{aligned}
 \text{Instantaneous power} &= vi = P \\
 &= (V_m \sin \omega t)(I_m \sin \omega t) \\
 &= V_m I_m \sin^2 \omega t \\
 &= V_m I_m \left( \frac{1 - \cos 2\omega t}{2} \right) \\
 &= \frac{V_m I_m}{2} - \frac{V_m I_m \cos 2\omega t}{2} \quad \text{variable.} \quad (4)
 \end{aligned}$$

For average power.

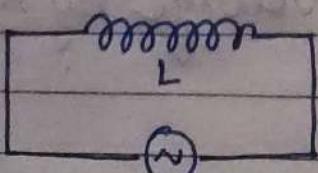
over complete cycle, the variable part in 4 is zero. we are left with only  $\frac{V_m I_m}{2}$

$$P = \frac{V_m I_m}{2} = \frac{V_m}{\sqrt{2}} \frac{I_m}{\sqrt{2}} = V_{rms} \cdot I_{rms}$$

$$P_{avg} = V \cdot I$$

- (a) Power is always +ve and the expression of power is  $V_{rms} I_{rms}$ . Unit = Watts
- (b) NO part of power cycle becomes -ve at any time and power is never zero in purely resistive ckt.

# AC through purely INDUCTIVE CIRCUIT



$V = V_m \sin \omega t$   
when an alternating voltage

all this voltage is used to overcome the self induced emf.  $e = -L \frac{di}{dt}$

As there is no resistance in ckt.

$$\text{Hence applied voltage } V = -e = -\left(-L \frac{di}{dt}\right) = L \frac{di}{dt}$$

$$V_m \sin \omega t = L \frac{di}{dt}$$

$$\int di = \frac{V_m}{L} \sin \omega t dt$$

$$I = \frac{V_m}{WL} \sin(\omega t - \pi/2)$$

$$I = \frac{V_m}{X_L} \sin(\omega t - \pi/2)$$

$$\omega L = X_L = \text{Inductive reactance} = \Omega$$

Inductive reactance is the resistance offered by inductor to alternating current

for  $\sin(\omega t - \pi/2)$

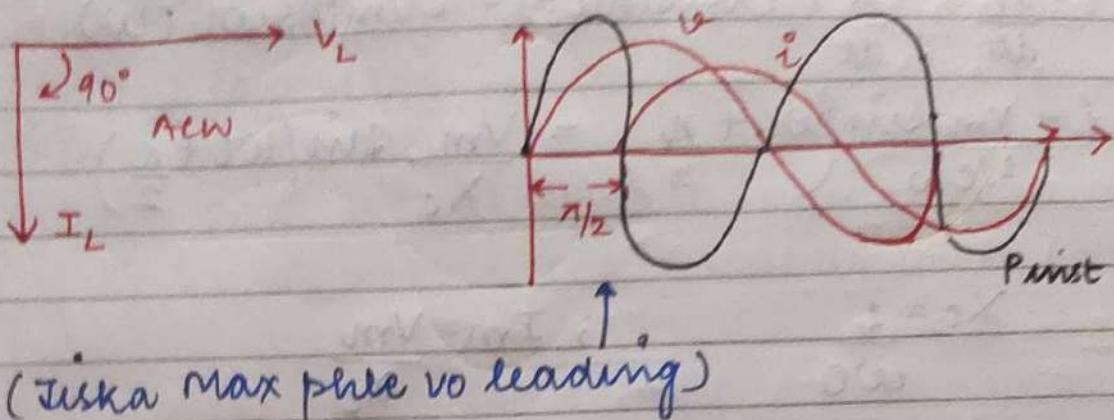
$$i = \frac{V_m}{X_L} = I_m$$

In a L ckt

$$V = V_m \sin \omega t$$

$$i = I_m \sin(\omega t - \pi/2)$$

current lags the applied voltage by  $\pi/2$



$$\text{Instantaneous Power} = v \cdot i$$

$$= (V_m \sin \omega t) (I_m (\sin \omega t - \pi/2))$$

$$= -V_m I_m \sin \omega t \cos \omega t$$

$$= -\frac{V_m I_m}{2} \sin 2\omega t \rightarrow \text{fluctuating (variable)}$$

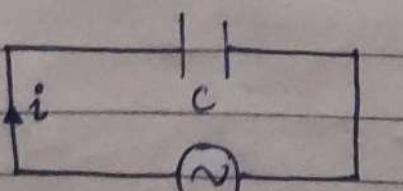
$$\text{Avg Power} = 0$$

In a pure Inductive & capacitive ckt, average power across full cycle is zero.

(NO consumption of Power in pure L & C in avg but at instant it consumes power).

### Power system :-

## # AC through Pure Capacitive Alone



$$V = V_m \sin \omega t$$

$$\text{Let } V = V_m \sin \omega t$$

$$V = \text{pot diff across plates}$$

$$q = \text{charge on plates}$$

$$q = CV$$

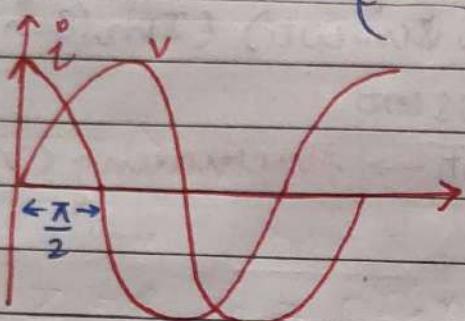
$$= C V_m \sin \omega t$$

$$i = \frac{dq}{dt} = \frac{d}{dt} (C V_m \sin(\omega t)) = C V_m \cos(\omega t)$$

$$i = \frac{V_m \cdot \sin(\omega t + \frac{\pi}{2})}{Z_c} = \frac{V_m}{X_c} \sin(\omega t + \frac{\pi}{2})$$

$$X_c = \frac{1}{\omega C} ; I_m = \frac{V_m}{X_c}$$

$$i = I_m \sin(\omega t + \frac{\pi}{2})$$



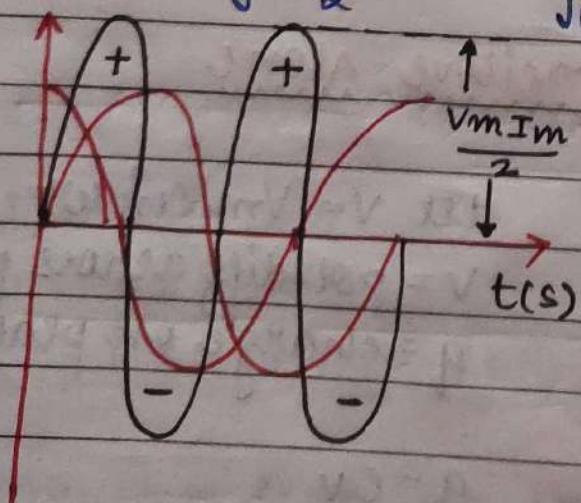
Instantaneous Power

$$P = Vi = (V_m \sin \omega t) (I_m \sin (\omega t + 90^\circ))$$

$$= V_m I_m \sin \omega t \cos \omega t$$

$$= \frac{1}{2} V_m I_m \sin 2\omega t$$

$$\text{Power avg} = \frac{1}{2} V_m I_m \int_0^{2\pi} \sin 2\omega t dt = 0$$



## POWER SYSTEM

### (i) Apparent Power (S)

It is given by the product of rms values of applied voltage and circuit current.

$$\therefore S = VI = (IZ) \cdot I = I^2 Z = \text{volt amperes (VA)}$$

### (ii) Active / Real Power (P)

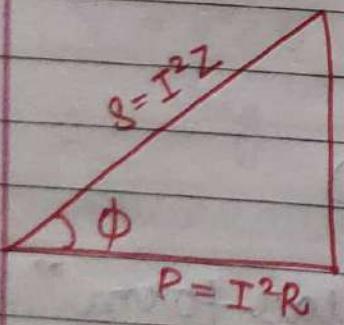
It is the power which is actually dissipated by circuit Resistance.

$$P = I^2 R = VI \cos \phi = \text{Watt}$$

### (iii) Reactive Power (Q)

It is the power developed in the inductive reactance of the circuit / capacitance reactance (consuming in one half cycle, give back in other half cycle).

$$Q = I^2 X_L = I^2 \cdot Z \sin \phi = I \cdot (IZ) \sin \phi = VI \sin \phi \\ = \text{volt-amperes - reactive.}$$



$$S^2 = P^2 + Q^2$$

$$S = \sqrt{P^2 + Q^2}$$

$$\cos \phi = \frac{P}{S}$$

### Q4. continue

$$I_{rms} = \frac{10}{\sqrt{3}} \left[ \int_0^{0.1} 400 dt + \int_{0.15}^{0.2} 25 dt \right]$$

$$= \sqrt{\frac{10}{3}} \left( 400 \times \frac{0.1}{10} + 25 \left( \frac{0.2}{10} - \frac{0.15}{100} \right) \right) \\ = \sqrt{\frac{10}{3}} (40 + 5 - 3.75) = \sqrt{137.5} A$$

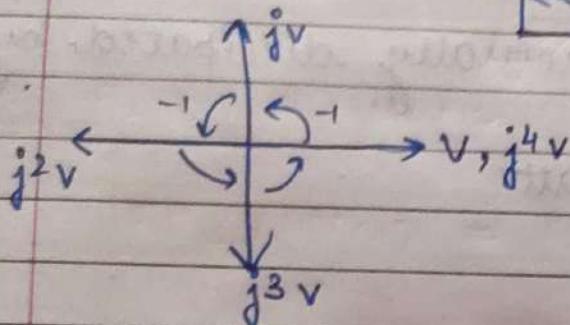
## Mathematical Representation of phasors

### (A) Rectangular form

$$j^2 = -1$$

$$j = \sqrt{-1}$$

$$Z = R + jX$$



$$Z = a + jb = R + jX$$

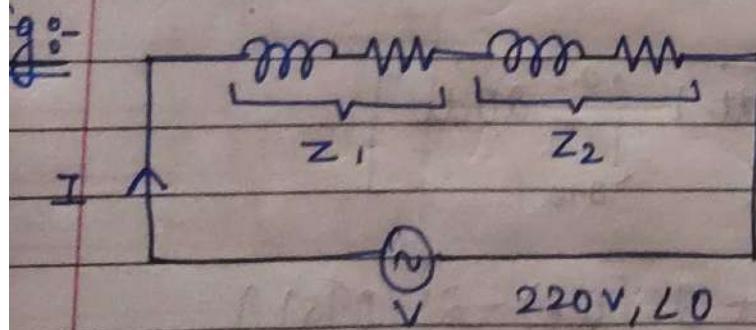
a = Real part

b = Imaginary part

$$Z_1 = R_1 + jX_1 ; Z_2 = R_2 + jX_2$$

$$Z_1 + Z_2 = (R_1 + R_2) + j(X_1 + X_2)$$

"Add / Sub we go it in Rectangular form"



$$\text{net impedance} = Z_1 + Z_2$$

$$|Z| = \sqrt{R^2 + X^2}$$

$$\tan \phi = \frac{X}{R}$$

## (B) TRIGONOMETRICAL FORM

$$\text{Real part} = a = V \cos \phi$$

$$\text{Imag. part} = b = V \sin \phi$$

$$\vec{V} = V \cos \phi + V j \sin \phi$$

$$\vec{V} = V (\cos \phi + j \sin \phi)$$

## (C) EXPONENTIAL FORM

$$e^{j\phi} = \cos \phi + j \sin \phi$$

$$e^{-j\phi} = \cos \phi - j \sin \phi$$

$$e^{j(\theta+\phi)} = \cos(\theta+\phi) + j \sin(\theta+\phi)$$

## (D) POLAR FORM

$$\vec{V} = V \angle \theta = V \angle -\theta$$

↓  
mag      ↗ Phase L.

"Multiplication of phasors" "Divide of phasors"

$$A \angle \theta, B \angle \alpha$$

$$A \cdot B = AB \angle (\theta + \alpha)$$

$$\frac{A}{B} = \frac{A}{B} \angle (\theta - \alpha)$$

Q.  $Z = 3 + j5 ; V = 220V, \angle 0 ; I = ?$

Ans.  $I = \frac{V}{Z}$

$$|Z| = \sqrt{3^2 + 5^2} = 4Y \quad \theta = \tan^{-1} \left( \frac{5}{3} \right)$$

$$Z = 4Y \angle 0, V = 220 \angle 0$$

coil =  $R + jX_L$   
lead & lag

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Date / /

$$I = \frac{220}{\sqrt{R^2 + X_L^2}} \angle (0 - \theta)$$

#  $A \angle \theta \rightarrow n^{\text{th}} \text{ power}$

$$A^n \angle n\theta$$

$$n^{\text{th}} \text{ root } A^{1/n} \angle \frac{\theta}{n}$$

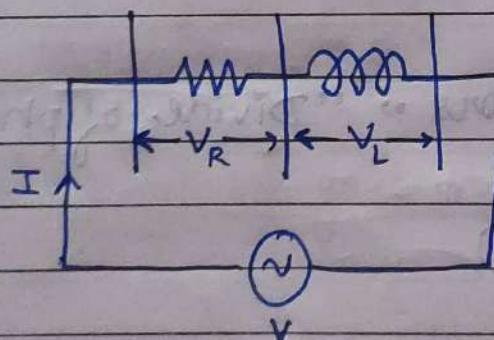
Eg:-  $5 \angle 60^\circ, 4^{\text{th}} \text{ power}$

$$5^4 \angle (4)(60) = 625 \angle 240^\circ$$

$$4^{\text{th}} \text{ root} = (5)^{1/4} \angle \sqrt[4]{\frac{60}{4}} = \sqrt{5} \angle 15^\circ$$

# R-L Series Circuit :-

R-L Series :- coil



$$V = \sqrt{V_R^2 + V_L^2} = \sqrt{(IR)^2 + (IX_L)^2}$$

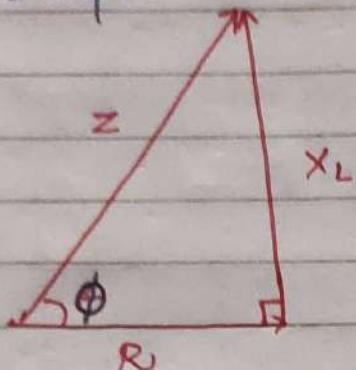
$$V = I \sqrt{R^2 + X_L^2}$$

$$\frac{V}{I} = Z = \sqrt{R^2 + X_L^2}$$

$$\text{Impedance} = \sqrt{R^2 + X_L^2}$$

$$\tan \theta = \frac{X_L}{R} = \frac{\omega L}{R}$$

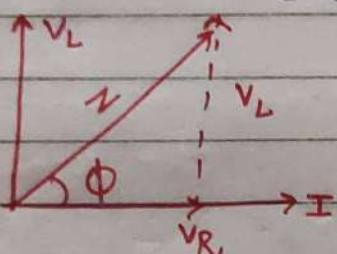
Impedance  $\Delta$ ,



$$\cos \phi = \frac{R}{Z} = \frac{\text{Resistance}}{\text{Impedance}}$$

$$0 \leq \cos \phi \leq 1$$

bcs base ckt's are pure Resistive ( $\cos \phi = 1$ ) and pure Inductive/Capacitive ( $\cos \phi = 0$ )



Applied  $V$  &  $I$  are not in phase  
 $I$  is lagging  $V$  by  $\phi$  with  $V$ .

$$\text{If } V_{\text{m}} \sin \theta = V \\ I = I_{\text{m}} \sin (\theta - \phi)$$

$$P = VI = V_{\text{m}} \sin \theta \times I_{\text{m}} \sin (\theta - \phi) \\ = V_{\text{m}} I_{\text{m}} \sin \theta \sin (\theta - \phi)$$

$$= \frac{V_{\text{m}}}{\sqrt{2}} \underbrace{\frac{I_{\text{m}}}{\sqrt{2}} \cos \phi}_{\text{constt}} - \frac{V_{\text{m}}}{\sqrt{2}} \underbrace{\frac{I_{\text{m}}}{\sqrt{2}} \cos (\omega t - \phi)}_{\text{fluctuating}}$$

$$P = P_{\text{avg}} = \frac{V_{\text{m}}}{\sqrt{2}} \frac{I_{\text{m}}}{\sqrt{2}} \cos \phi = V_{\text{rms}} I_{\text{rms}} \cos \phi$$

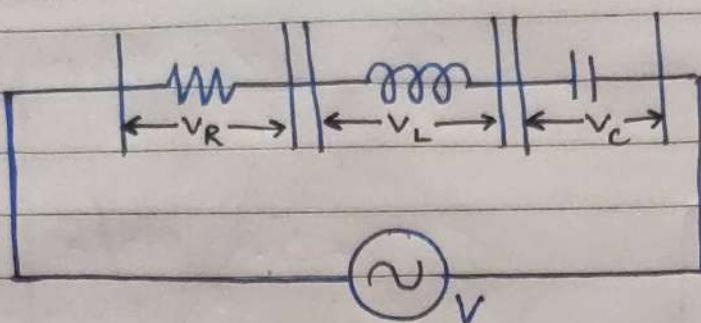
$$P = VI \cos\phi = VI \cdot \frac{R}{Z} = \frac{V}{Z} \cdot I \cdot R = I^2 R, \text{ Watt}$$

Power is only consumed by ckt.

## R-C series circuit

#

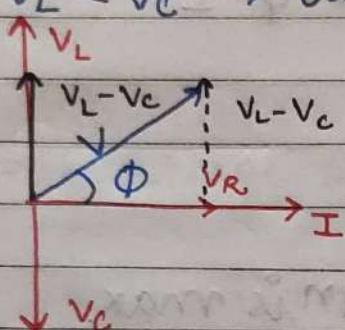
## R-L-C Series Circuit



$v_L > v_c \Rightarrow$  Inductive ckt

$v_L < v_c \Rightarrow$  Capacitive ckt

FOR  $v_L > v_c$



I lags applied voltage by  $\phi$  angle

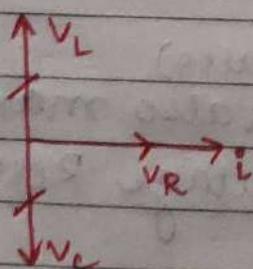
$$Z = \sqrt{R^2 + (X_L - X_C)^2}$$

### # SERIES RESONANCE :-

Condition :-  $X_L = X_C$  or  $v_L = v_c$

Resonance :- Any ac circuit which behaves like purely resistive circuit i.e.  $V$  &  $I$  are in same phase, i.e. net reactive component of circuit is zero.

$$v_L - v_c = 0$$



Total voltage is around resistive part of ckt.

Vis in phase with I.  
 $v_R = V$

At Resonance

$$v_L = v_c$$

$$I X_L = I X_C$$

$$X_L = X_C$$

$$\omega L = \frac{1}{\omega C}$$

$$\omega^2 = \frac{1}{LC}$$

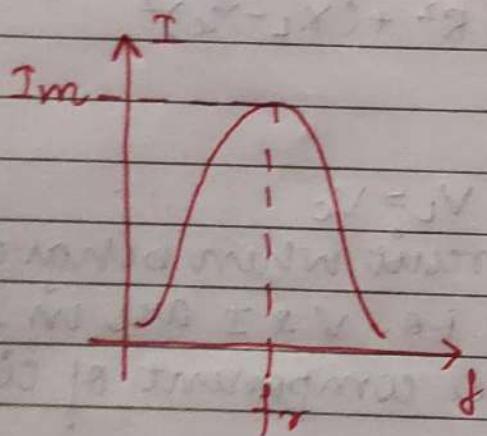
$$f = \frac{1}{2\pi\sqrt{LC}}$$

→ As VR is in phase with  $\vec{I}$   $\Rightarrow \cos \phi = 1$

$$Z = \sqrt{R^2 + (X_L - X_C)^2}$$

$$Z = R$$

→ Current at Resonating cond'n is max.



Radio & Communication  
ckt Applications.

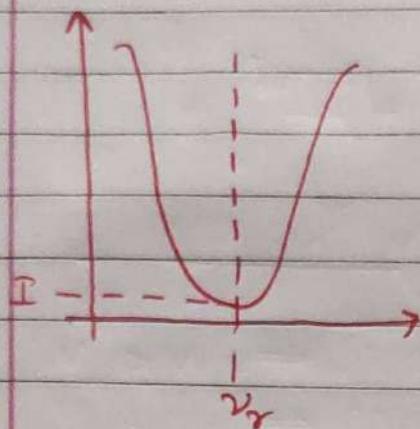
Series Resonance is also called Voltage Resonance  
& acceptor circuit.

(Voltage Magnification ckt)

Voltage across each component is also maximum  
with current hence called Voltage Resonance  
(L, C also)

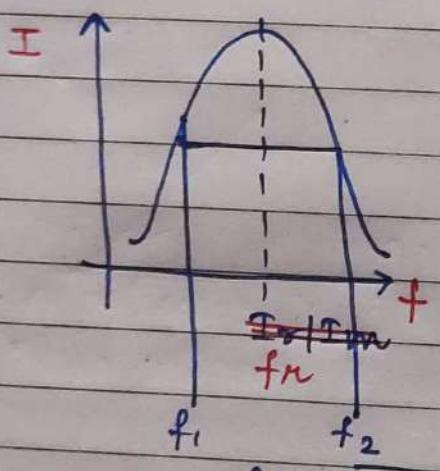
As ~~the~~ it accepts max current from the ckt  
It is acceptor circuit.

## Parallel Resonance. (current / reductor resonance)



### # BANDWIDTH :-

The range of freq where  $I = \pm 0.7\% \text{ of } I_{max}$



$$BW = f_2 - f_1$$

$f_1$  &  $f_2$  are half power points  
Power drawn is half at these points.

$$f_r = \sqrt{f_1 f_2}$$

# Q-factor (Quality factor of coil) :-

V developed across L or C

Applied voltage

$$= \frac{I_r X_L}{I_r R} = \frac{1}{R} \sqrt{\frac{L}{C}}$$

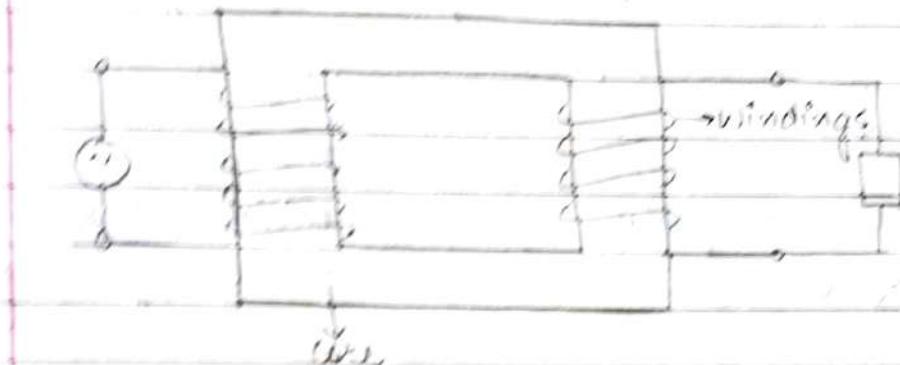
(Qr.)

Resonating frequency  
Bandwidth

Q factor decides designing of coil  
It does not depend upon frequency.

unit-3

# TRANSFORMER



(the two magnetically coupled core  
connected)

(Electrical)

Transformer (Transfer) :- E. Energy from one core to another core w/o changing V.

- Static device :- no rotating part as in motors.
- Device :- no effective work, hence it's not a machine
- Machine :- effective work using power.

Power is transferred from primary to secondary.

- No rotating part → No change in frequency.

# Uses of Transformer,

- (a) Voltage up down (potential transformers)
- (b) Same voltage transfer
- (c) Current up down (current transformers)
- (d) Same Power transfer

$$\text{P}_{\text{NP}} = \text{P}_{\text{OP}}$$

$$V_1 I_1 \cos \phi = V_2 I_2 \cos \phi$$

$$\frac{V_1}{V_2} = \frac{I_2}{I_1}$$

if  $V_1 \uparrow$ ,  $I_1 \downarrow$

## # Types of transformer

(A)

### INSTRUMENT TRANSFORMERS

(connected before measuring inst.)

CT

current transformer  
(step up of voltage)

PT

Potential Transformer  
(stepdown of voltage)

## (B) Basis of Rating of transformer

Power transformer  
(3- $\Phi$ )

Distribution transformer  
(3- $\Phi$ )

Electronics Transformer  
(5-10 V)

## (C) Step-up - Stepdown transformer

Stepup VT

Stepdown VT

## (D) Phase

### PHASE

1- $\Phi$

3- $\Phi$

Primary, Secondary  
or tertiary windings

Input

Y / A

A / A

A / Y

Y / Y

output



10 34



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Primary side :- Input side ( $1^{\circ}$ )

Secondary side :- Output side ( $2^{\circ}$ )

$V_1, I_1, N_1, E$ ,  $\rightarrow$  Primary       $V_2, I_2 \rightarrow$  Secondary

$V_o, I_o \rightarrow$  No load  $\Rightarrow$  Secondary current = 0

(G) 11 KV

(T) 132 KV (Distribution / Transmission)

## # CONSTRUCTION OF TRANSFORMER (Power transformer)

- i) core :- Mag material  $\Rightarrow$  flux transfer (soft iron) CRGO  
Silicon steel
- ii) Winding :- Cu  $\Rightarrow$  current transfer
- iii) Tank & conservator (vi) conservator tank
- iv) Coolant / insulating coil
- v) Bushings

## Electronics Transformer

- i) core
- ii) winding

### (A) CORE :- In core

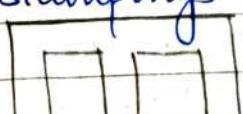
Q why not cast iron  $\rightarrow$  hysteresis losses.

core losses  $\Rightarrow$  hysteresis & ~~iron losses~~ Eddy losses

CRGO  $\rightarrow$  Manufacturing Process

(cooled Rolled Oriented)  $\Rightarrow$  leakage flux  $\downarrow$   
hysteresis losses  $\downarrow$

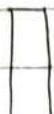
Stampings :- Shape of core



E



L



I

Silicon sheet

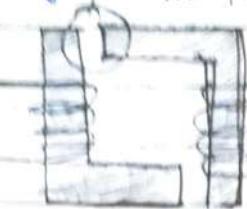
shape.

MOTOR 80%  $\eta$   
(i) 60-70%  $\eta$

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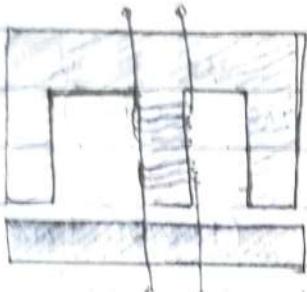
Q. Why E, L, I  $\rightarrow$  ↓ Eddy current losses

→ air/vacuum  $\rightarrow$  do not allow current



(no joints, only pressed together)  
 $\hookrightarrow$  break the ckt of Eddy current

core type transformer



Q. Why transformer is highly efficient device?

Less losses  $\rightarrow$  friction losses  $\times$

$\rightarrow$  core construction

$\rightarrow$  Hysteresis loss  $\downarrow$ , due to Silicon.

# Hysteresis :- To lag behind (Greek word)

B lags H  $\rightarrow$  Number of turns  $\times$  I ( $n \times I$ )  $\Rightarrow$  sets up  $\phi$   
Mag field

$H \times I \Rightarrow$  magnetism force

Q. Eddy losses & Hysteresis losses are const <sup>in</sup> nature.  
Explain. How to reduce

Date :- 27 Jan 2023

### CONSTRUCTION OF TRANSFORMER :-

(i) Core :- Core loss  $\rightarrow$  eddy + hysteresis loss

$\rightarrow$  constant core  
 $\rightarrow$  depend upon  $V, V$  } O.C Test

(ii) Winding :- Copper (conductor)  $\rightarrow$  copper losses  $\rightarrow I^2 R$  losses

S.C { load depends  
Test variable losses } on current

Formula for Eddy losses :-

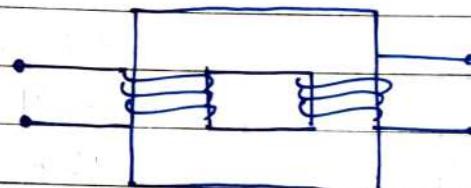
Hysteresis losses :-

CLASSTIME Pg. No.

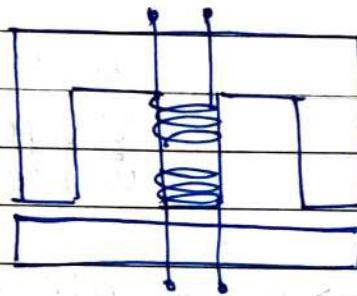
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Q. On the basis of construction, classify ~~core~~ transformer.

A:- core type :-



shell type :-



Q. Eddy losses are constant

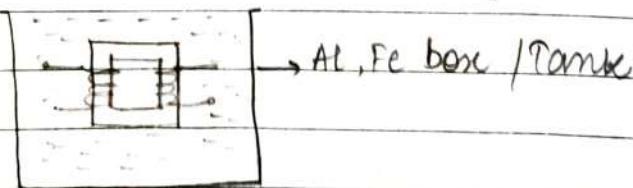
It depends upon input supply  $V \propto v \Rightarrow \phi$ .

which is constant hence  $v$  &  $\nu$  are constant in nature.

Stampings enhance Eddy losses.

open ckt test (No load test)

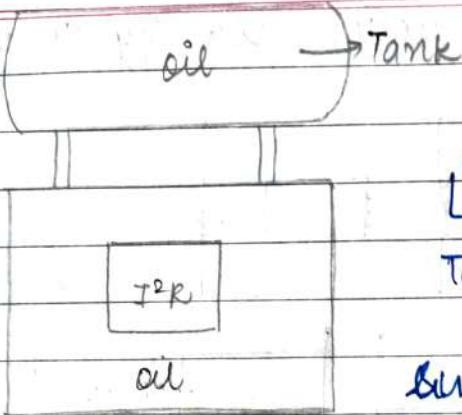
→ Conservator Tank (insulating oil)



Insulation b/w Tank & TRM is req bcz eddy loss will transfer to Tank and hence loss ↑.

We use TRM oil (insulating oil)  $\Rightarrow$  also provide cooling property

Heat losses  
Turbine losses



oil heatup through  $I^2R$  lossy  
 ↳ vapours → go to conservator  
 Tank ( $T \downarrow$  than tank) → liquify

Since  $V$  is same

$V_{(\text{vapour})} = V_{(\text{liq. into tank})}$   
 into conservator

tank.

In hot region  $\Rightarrow$  forced cooling  $\Rightarrow$  fan (forced draw cooling)

54°C  $\Rightarrow$  water sprinkler on fan.

Bushings

connecting insulating rings in output wires

no. of rings  $\times 11\text{ KV} =$  output voltage.

Breathers (Dehydrator)

Contains Si Gel (originally Blue colour) in duct to take oil samples (Blue  $\rightarrow$  Pink either change oil or change oil).

### Losses

The wattmeter reading gives total losses

but at no load, current losses are negligible

b/c  $I_0 = 0.2\%$  of full load ckt.

$I \downarrow \Rightarrow$  SC losses  $\downarrow \Rightarrow$  neglect them.  
 i.e. open ckt test.

(W)

$\rightarrow$  core + Cu

O.C cond'n  $\rightarrow$  Cu losses  $\approx$  zero  $\rightarrow$  core losses measure

short  
core  
loss.

# EMF

flux ↑

$\frac{1}{4}f$

Avg M

indu

Avg e

for si

RMS v

of N<sub>1</sub>

RMS v

of N<sub>2</sub> +

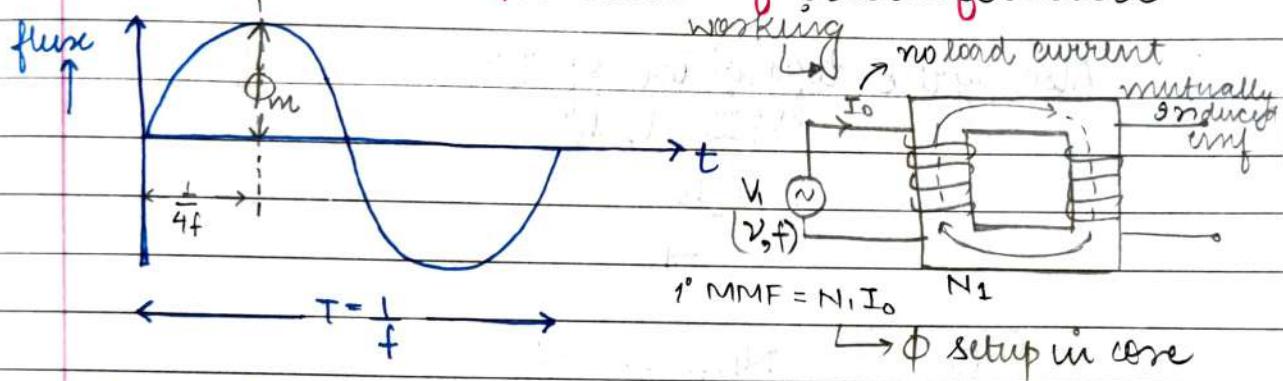
# Transfor

short ckt  $\Rightarrow$  max I  $\Rightarrow$  min voltage  
 core losses depends upon voltage  $\approx$  negligible loss.

## # EMF

Derivation & Ques 5-marks

## Equation of Transformers.



$$\text{Avg rate of change of flux} = \frac{0 - \Phi_m}{0 - \frac{1}{4}f} \rightarrow 4f\Phi_m \text{ wb/s}$$

$$\text{induced emf} = \text{Rate of change of flux} = N \frac{d\Phi}{dt}$$

$$\text{Avg emf induced per turn} = 4f\Phi_m$$

$$\text{for sinusoidal flux} \rightarrow \text{RMS value per turn} = 1.11 \times 4f\Phi_m \\ - 4.44 f\Phi_m \text{ Volt.}$$

RMS value of induced emf in primary winding  
of  $N_1$  turns

$$E_1 = 4.44 f N_1 \Phi_m \quad \text{(i)}$$

RMS value of induced emf in secondary winding  
of  $N_2$  turns

$$E_2 = 4.44 f N_2 \Phi_m \quad \text{(ii)}$$

## # Transformation Ratio (K)

$$\frac{E_1}{E_2} = \frac{N_1}{N_2} = \frac{1}{K} \Rightarrow \frac{E_2}{E_1} = \frac{N_2}{N_1} = K$$

for ideal transformer  $\rightarrow 100\% \eta \rightarrow$  zero losses  
 $V_1$  supplied  $\Rightarrow E_1$  generated  $\propto E_2$  generated  $= V_2$   
 output

$$\frac{E_1}{E_2} = \frac{V_1}{V_2} = \frac{N_1}{N_2} = \frac{1}{K}$$

Also by the definition of TFM  
 $V_1 I_1 = V_2 I_2$

$$\frac{V_1}{V_2} = \frac{I_2}{I_1}$$

$$\boxed{\frac{E_1}{E_2} = \frac{V_1}{V_2} = \frac{N_1}{N_2} = \frac{I_2}{I_1} = \frac{1}{K}}$$

$K > 1 \Rightarrow N_2 > N_1 \Rightarrow$  Step Up transformer.

- Q. A 25 KVA 1-Φ TFM has  $250 = N_1$  &  $40 = N_2$ . The primary is connected 1500 V, 50 Hz mains supply. Cal  $I_1$ ,  $I_2$ ,  $E_2$ , Max  $\phi$  in core.

A1. Power  $= V_1 I_1 = V_2 I_2 = 25 \text{ KVA} = 25000 \text{ VA}$

$$N_1 = 250, N_2 = 40$$

$$E_1 = 1500, V_1 = 50$$

$$\frac{N_1}{N_2} = \frac{I_2}{I_1} = \frac{V_1}{V_2} \Rightarrow \frac{N_1}{N_2} = \frac{V_1}{V_2} \left( \frac{E_1}{E_2} \right)$$

$$\frac{250}{40} = \frac{1500}{E_2}$$

$$E_2 = \frac{1500 \times 40}{250} = \frac{15 \times 4 \times 4}{25} = 240 \text{ V}$$

$$25000 = 240 \times I_2 = 1500 \times I_1$$

$$I_2 = \frac{25000}{240} = 104.16 \text{ A}$$

$$I_1 = \frac{25000}{1500} = 16.6 \text{ A}$$

$$E_1 = 4.44 f N_1 \Phi_m$$

$$\frac{1500}{4.44 \times 50 \times 250} = \Phi_m = 0.027 \text{ Wb} = 27 \text{ mWb.}$$

- Q. Max flux density in the core of a 250/3000V 50Hz 1Φ transformer is 1.2 wb/m<sup>2</sup>. If the emf per turn is 8V. Det secondary & primary turns & Area of core.

$$4f\Phi_m \times 1.11 = 8V$$

$$4.44 \times 50 \times \Phi_m = 8$$

$$\Phi_m = \frac{8}{4.44 \times 50} = 36 \text{ mwb.}$$

$$\frac{\Phi}{\text{Area}} = \frac{36 \times 10^{-3}}{\text{Area}} = 1.2$$

$$\text{Area} = 30 \times 10^{-3} \text{ m}^2 \Rightarrow 3 \times 10^{-2} \text{ m}^2$$

$$250/8000 \Rightarrow E_1 = 250, E_2 = 83000$$

$$\frac{\Phi}{\text{Area}} = B_m \Rightarrow \Phi = B_m \text{Area}$$

$$\text{Area} \quad E_1 = 4.44 f N_1 \Phi_m$$

$$250 = 4.44 \times 50 \times 36 \times 10^{-3} \times N_1$$

$$N_1 = \frac{250 \times 10^3}{4.44 \times 50 \times 36} = 0.03128 \times 10^3 = 31.28 \text{ } \cancel{\text{#}}$$

$$N_1 \approx 32$$

$$E_1 = 250 \quad E_2 = 3000$$

$$N_1 = 32 \quad N_2 = ?$$

$$\frac{E_1}{E_2} = \frac{N_1}{N_2} \Rightarrow N_2 = \frac{N_1 \times E_2}{E_1} = 384 \text{ turns.}$$

$$\frac{Z_2}{Z_1} =$$

- Q. What will happen if TFM 1° is supplied by DC supply.  
 flux will be setup but not alternating in nature  $\Rightarrow$  MMF DC in nature  $\Rightarrow$  no  $E_2$ .  
 Eventually primary winding will burn with heat losses.

(a)

(b)

(c)

(d)

$$Z_1 = R_1 + jX_1$$

$$Z_2 = R_2 + jX_2$$

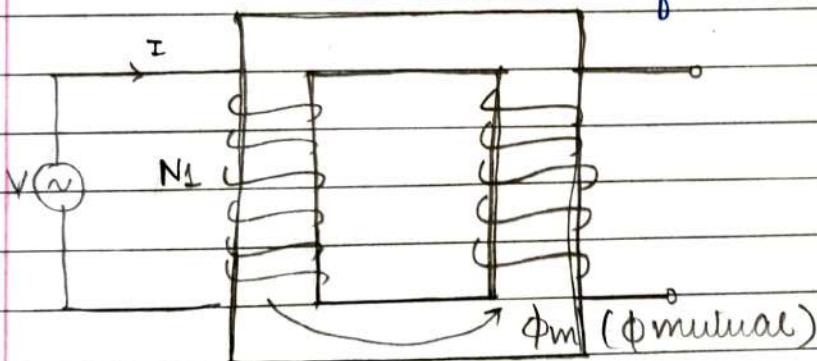
# EQUIVALENT CIRCUIT

Ideal transformer 100% zero losses assumptions

- core losses (Hysteresis & Eddy)
- Ohmic losses (cu losses,  $I^2R$  losses)
- NO leakage flux
- 100% permeability  $B = \mu H$

$$H = N \times I \quad (\text{No. of turns} \times \text{current})$$

all current  $\rightarrow$  flux setup (no wastage)



$$\text{MMF} = N \cdot I$$

$\rightarrow$  Flux linking  $\Rightarrow$  no contribution in emf

Practical Transformer

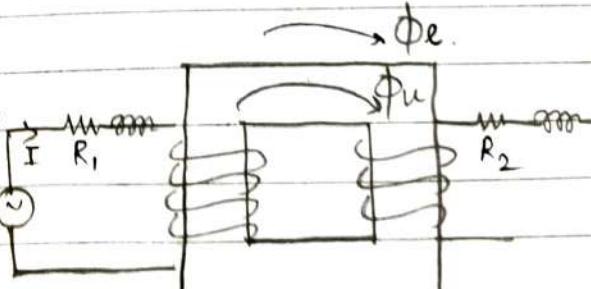
$$\eta = 95\% \quad \text{time} = 50 \text{ years}$$

- core losses

- Ohmic losses ( $I^2R_1 + I^2R_2$ )

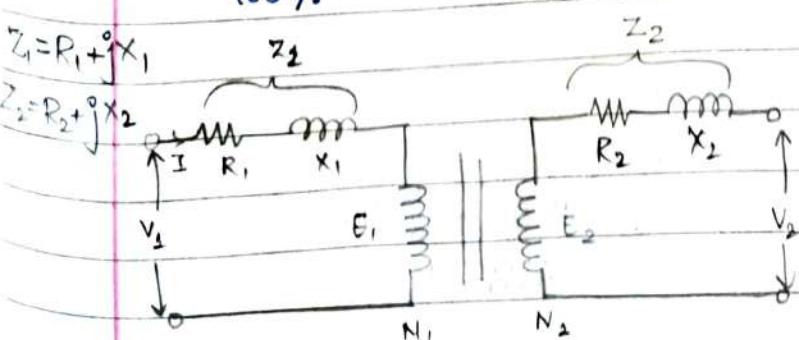
- Leakage  $\phi$

$$\begin{aligned} \phi_{\text{Total}} &= \phi_{\text{useful}} + \phi_{\text{leakage}} \\ 100\% &= 95\% + 5\% \end{aligned}$$



$Z_1 = R_1 + jX_1$   
 $Z_2 = R_2 + jX_2$   
 $V_1$   $V_2$   
 $N_1$   $N_2$

leakage Voltage drop  
or leakage reactance.



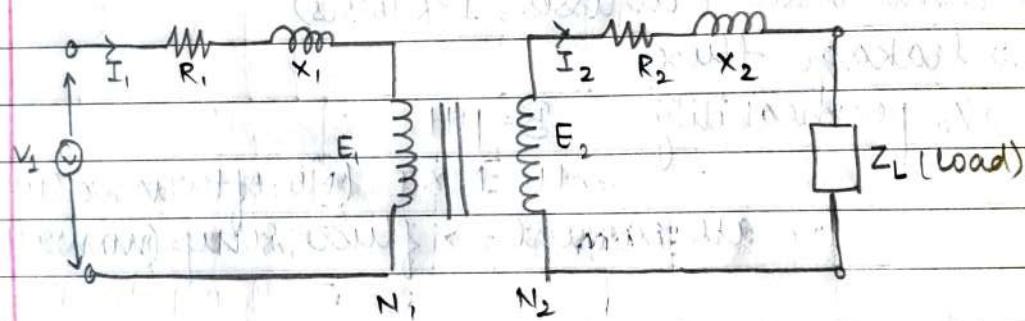
no load eq. ckt

$R_1$  = Primary winding resistance  
 $X_1$  = 1° leakage Reactance  
 $V_2$  = 2° Terminal V  
 $E_2$  = 2° Induced EMF

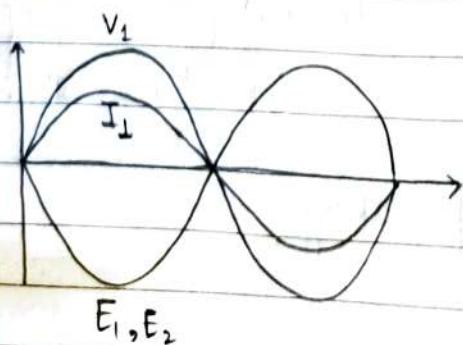
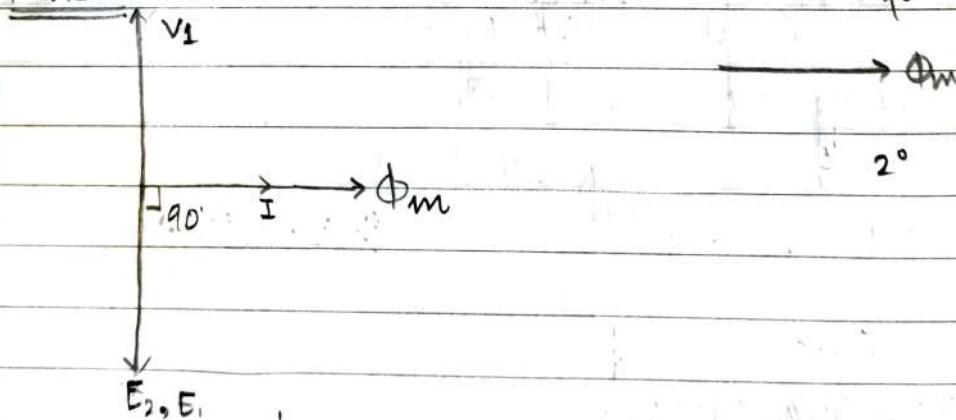
# Phasor Diagram

- on NO LOAD CONDITION

Equivalent ckt at LOAD CONDITION



PHASOR:- NO load



For Resistive Load

$$V_1 = -E_1$$

At no load

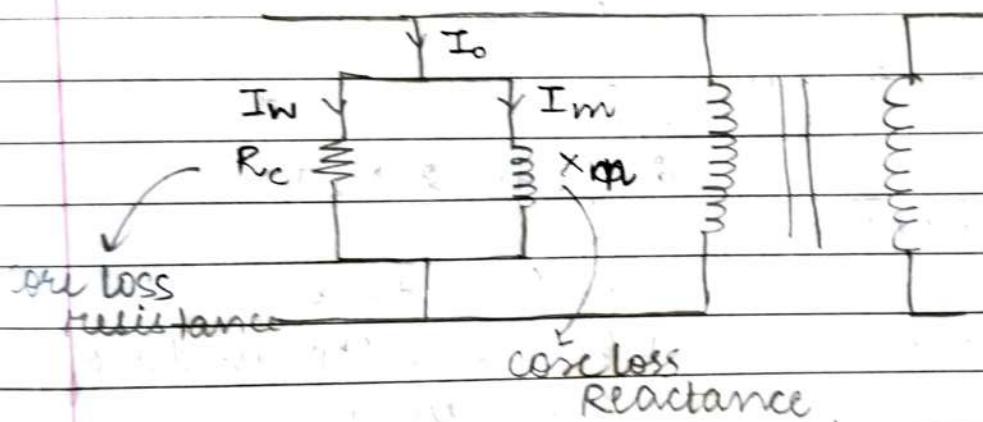
$$I_0 = 2-10\% \text{ of } I_{\text{full}}$$

→ neglect ohmic losses  
⇒  $X - \text{M} - R$

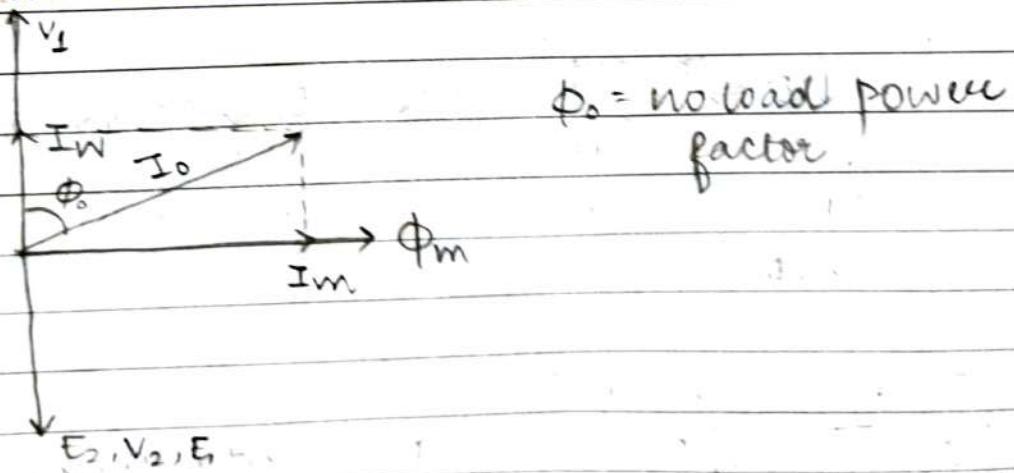
$I_o \rightarrow \phi_m$  mutual flux maintenance ( $I_m$ ) ✓  
 (magnetising component of no load current)

$\rightarrow$  ~~core~~ loss ( $I_w$ ) ✓  
 (core loss component)

$I_o = I_m + I_w$

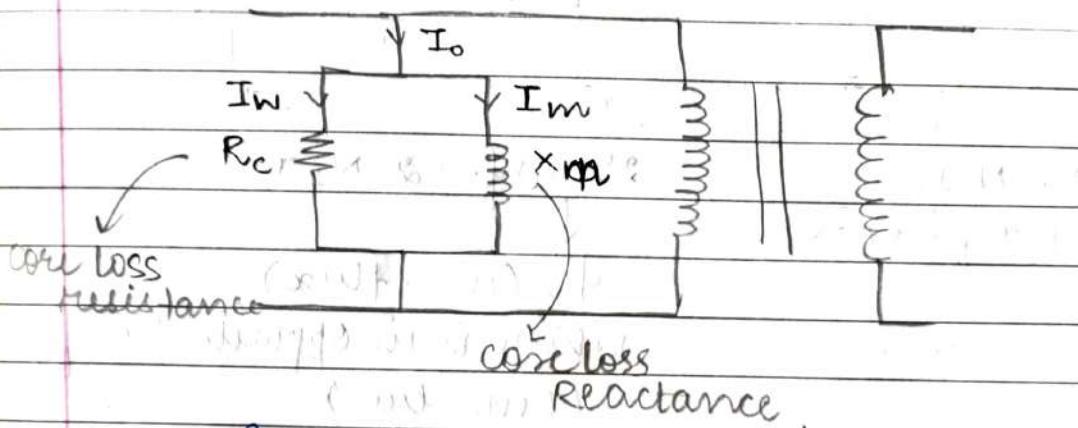


TFM with core loss at no load

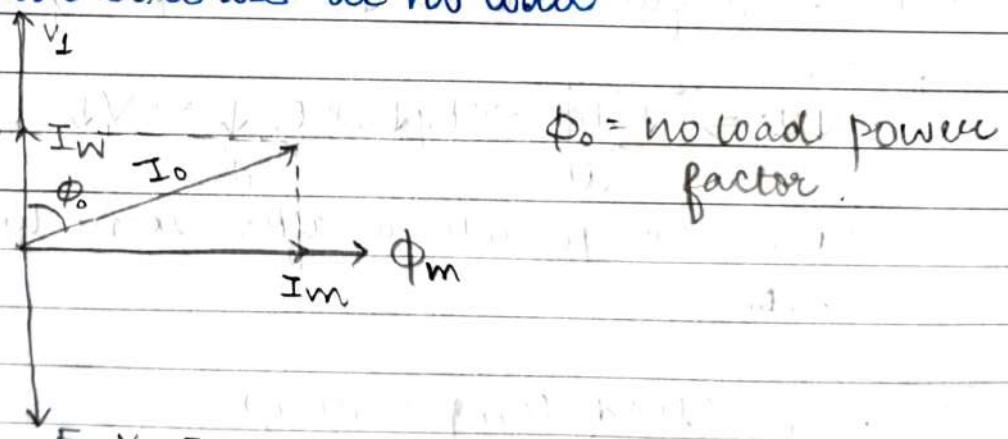


$I_o \rightarrow \Phi_m$  mutual flux maintenance ( $I_m$ )  
 core losses ( $I_w$ )  
 $I_o = I_m + I_w$

(magnetising component of no load current)  
 (core loss component)



TFM with core loss at no load

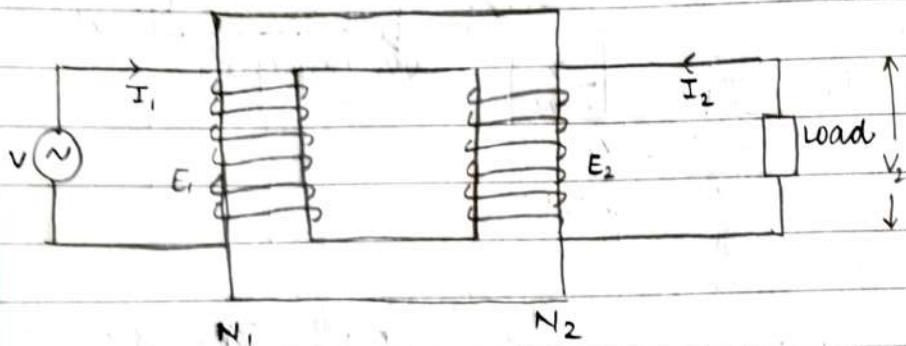


Date : 1 Feb 2023

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# TRANSFORMER ON LOAD



1° MMF =  $N_1 I_1$ ,  
(to setup a flux)

$$2^{\circ} \text{ mmf} = N_2 I_2$$

$\downarrow$   
 $\phi_2$  (own flux)

which is in opposite dir of  $\phi_m$   
(Lenz law)

Net  $\rightarrow$  less flux hence  $\phi_2$  is demagnetising flux.

$$\downarrow \phi \Rightarrow \downarrow \frac{d\phi}{dt} \Rightarrow E_1 \downarrow \& E_2 \downarrow \Rightarrow V_1 \downarrow = E_1 \downarrow$$

which is not possible as after some time  $E_1 = 0$

\* Loop hole \*

$$I_2 = I_1' \quad (\text{load compensator})$$

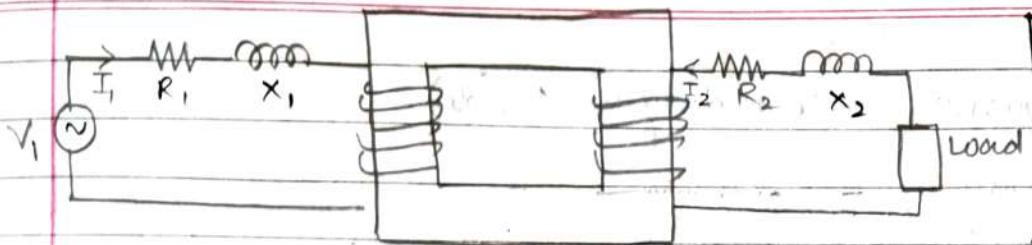
$$\vec{I}_0 + \vec{I}_1' = \vec{I}_1 \quad (I_1' = 1^{\circ} \text{ additional current})$$

$\downarrow$   
no load current

$$I_0 \rightarrow \phi_m \quad & I_1' \rightarrow \phi_2'$$

$$I_2 \rightarrow \phi_2$$

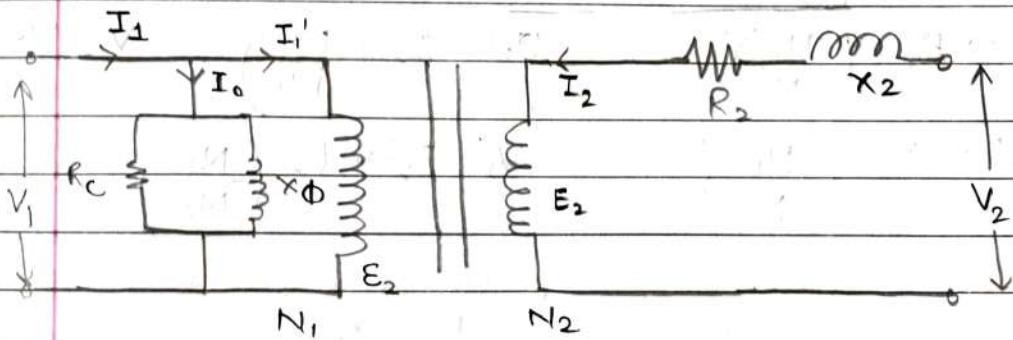
$$I_1' = I_2 \Rightarrow \phi_2' = \phi_2$$



const.  
Working  
EMF eqn  
Numerical  
Phasor

$X_C \rightarrow$  core reactance

$R_C \rightarrow$  core loss Resistant



Equivalent ckt for on load

condition

secondary terminal voltage

$$\vec{E}_2 = \vec{V}_2 + \vec{I}_2 (R_2 + jX_2) \quad \text{secondary voltage eqn}$$

$$\vec{V}_1 = \vec{I}_1 (R_1 + jX_1) + \vec{E}_1$$

1° ohmic loss

stray losses :- extra losses

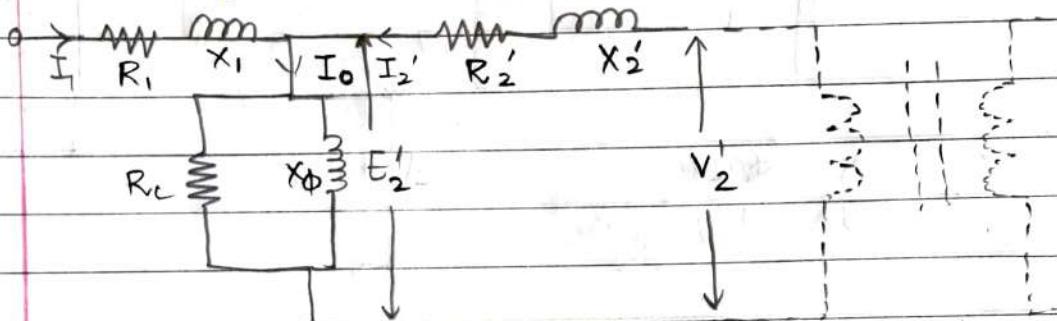
cu losses :-  $I_2$  dependent

flux leakage losses :-  $-R_2, X_2, X_1$  do compensate

core losses :-  $V, R$  losses dependent

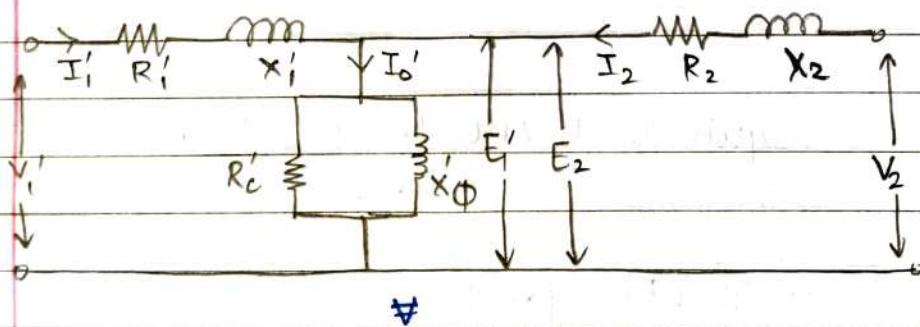
Referred to  $1^\circ$

(Primary & secondary in  $1^\circ$  side)



$$R_2' = R_2 \cdot \left( \frac{N_1}{N_2} \right)^2 \rightarrow \text{jiski side } I_2' = I_2 \left( \frac{N_2}{N_1} \right) \quad V_2' = V_2 \left( \frac{N_1}{N_2} \right)$$

$$X_2' = X_2 \cdot \left( \frac{N_1}{N_2} \right)^2 \quad E_2' = E_2 \left( \frac{N_1}{N_2} \right)$$



Referred to  $2^\circ$

$$V_1' = V_1 \cdot \left( \frac{N_2}{N_1} \right) ; \quad R_1' = R_1 \left( \frac{N_2}{N_1} \right)^2$$

$$I_1' = I_1 \left( \frac{N_1}{N_2} \right) ; \quad X_1' = X_1 \left( \frac{N_2}{N_1} \right)^2$$

Req<sub>1</sub> :- Equivalent  $1^\circ = R_1 + R_2'$

Req<sub>2</sub> :- Equivalent  $2^\circ = X_1 + X_2'$

# Voltage Regulation : (Ideal VR=0)

$$\vec{E}_2 - \vec{V}_2 = 0$$

no load  $\rightarrow$  on load

$$V_{\text{no load}} = V_{\text{on load}} \rightarrow \vec{V}_2 = \vec{E}_2$$

$$\vec{E}_2 = \vec{V}_2 + (I_2 (R_2 + jX_2))$$

$\underbrace{\qquad\qquad\qquad}_{=0}$  but not possible.

**Defn :-** At constant supply voltage, the change in 2<sup>o</sup> terminal voltage from no load to full load wrt no load voltage is called voltage Regulation of transformer.

$$\frac{E_2 - V_2}{E_2} = \text{voltage Reg}$$

$$\% VR = \frac{E_2 - V_2}{E_2} \times 100 \quad \left. \begin{array}{l} \text{Large VR} = \text{Poor VR} \\ \end{array} \right.$$

Date :- 3 Feb 2023

### PHASOR DIAGRAM

Actual Transformer on load :-

(with magnetic load and winding resistance)

$$\vec{I}_o = \vec{I}_c + \vec{I}_w$$

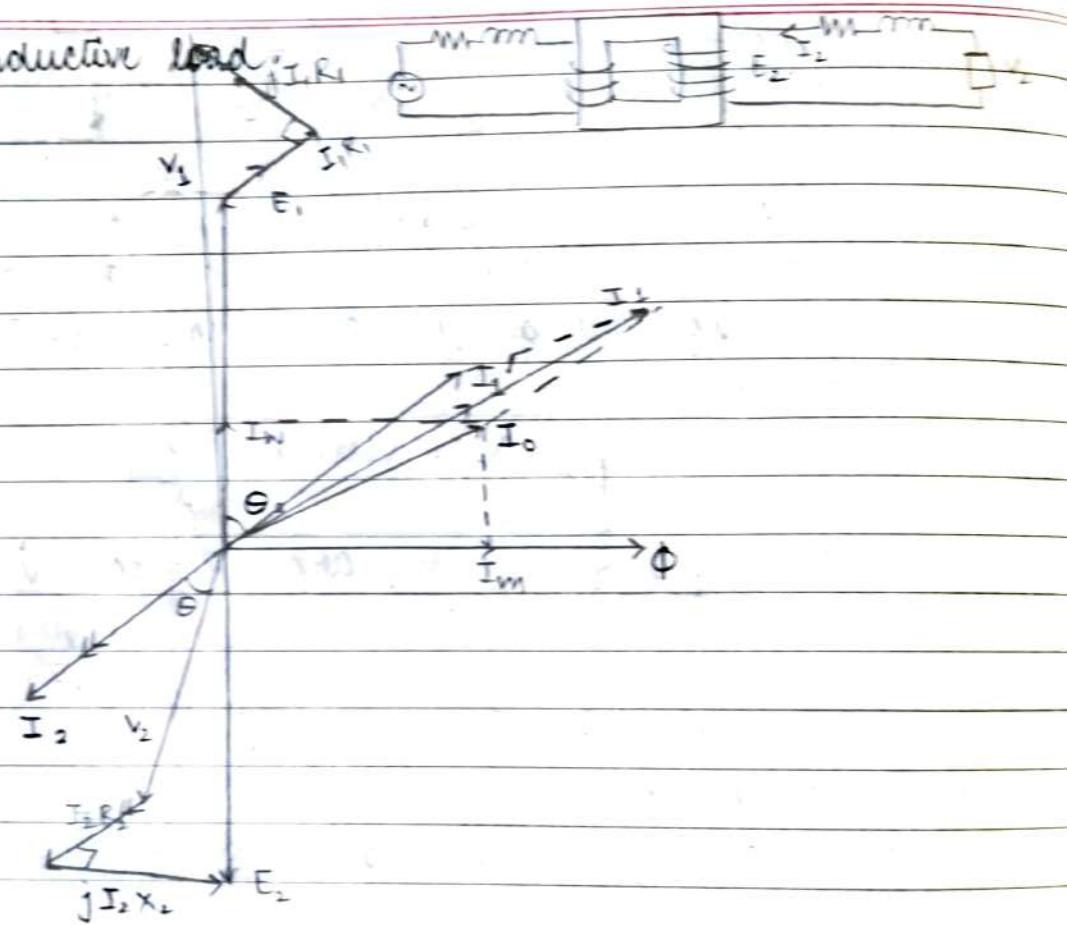
$$\vec{I}'_1 = \vec{I}_2$$

$$\vec{I}_1 = \vec{I}_o + \vec{I}'_1$$

$$E_2 = V_2 + I_2 Z_2 \quad (Z_2 = R_2 + jX_2)$$

$$V_1 = E_1 + I_1 (R_1 + jX_1)$$

:-

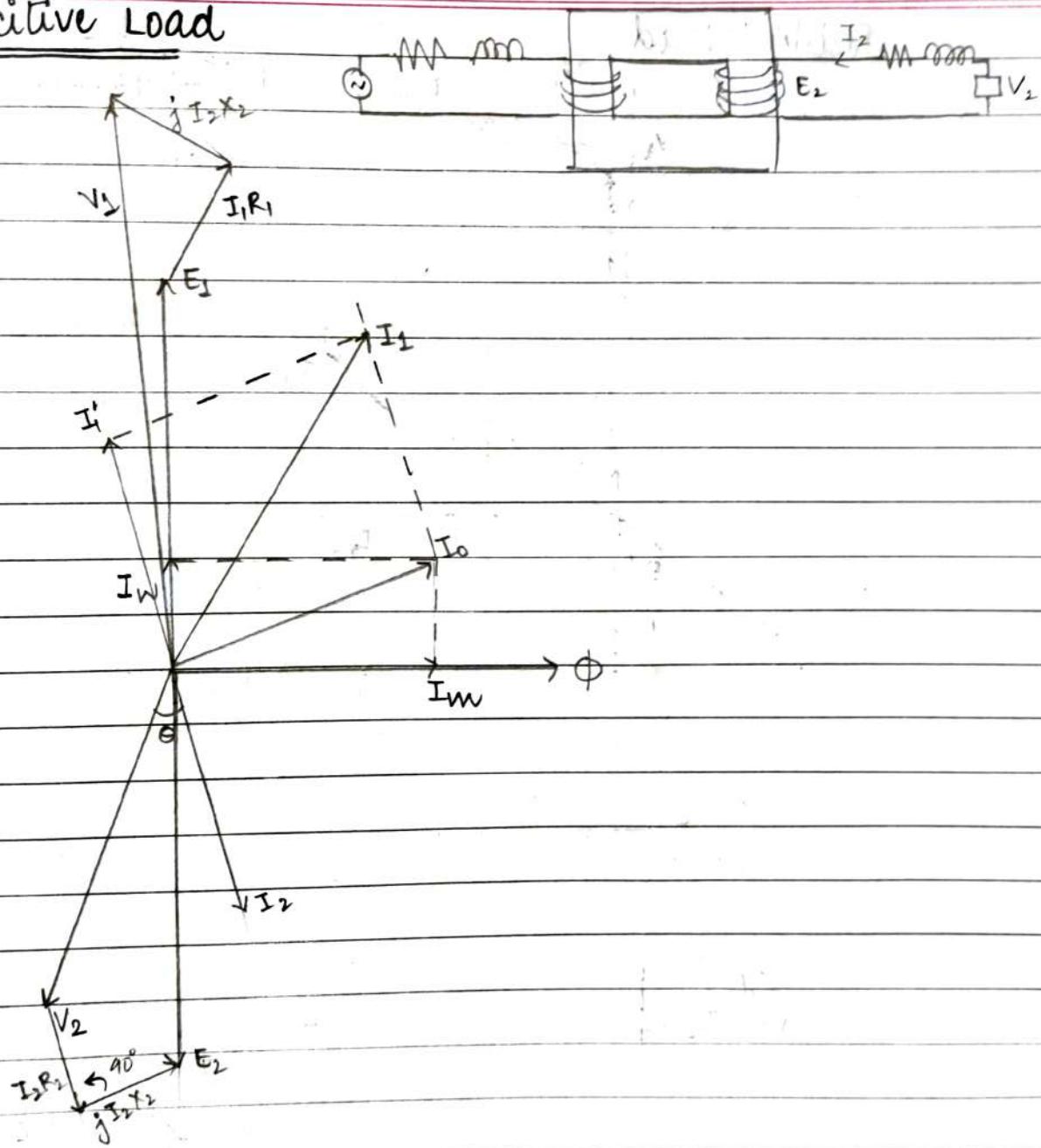
Inductive Load  $i_2, R_2$ 

→  $I_2$  large  $V_2$  for inductive load

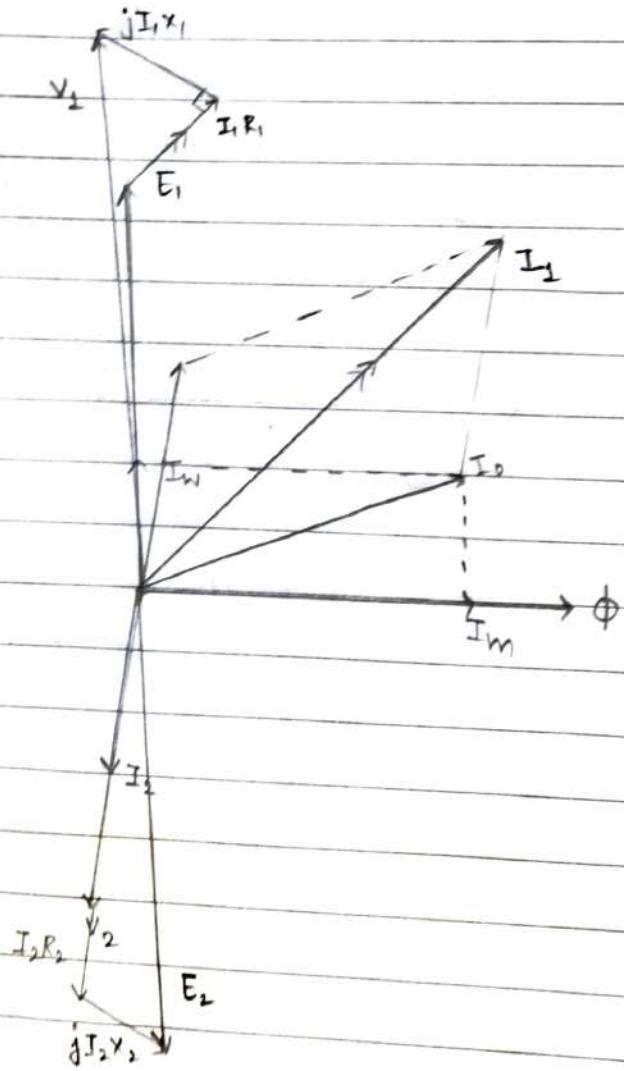
$$\rightarrow E_2 = V_2 + I_2 Z_2$$

Neglect leakage losses:- neglect  $x_1, x_2$

## Capacitive Load



## Resistive Load.



## Efficiency

$$\eta = \frac{\text{Output power}}{\text{Input power}} = \frac{\text{Output Power}}{\text{Output Power} + \text{losses}}$$

If  $x$  is fraction of full load ;  $\eta = \frac{\text{Output Power}}{\text{Output Power} + \text{Power loss}}$  (full load)

$$P_{cu} = I_2^2 R_{eq2}$$

$$P_{core} / P_{iron}$$

$$R_{eq2} = R_2 + R'_i$$

$$\text{Output Power} = V_2 I_2 \cos \phi_2$$

$\downarrow$  cu  $\downarrow$  core

$$\eta(x) = \frac{x V_2 I_2 \cos \phi_2}{x V_2 I_2 \cos \phi_2 + P_i + x^2 P_{cu}}$$

For  $\eta$  to be max

$$\frac{d\eta}{dI_2} = 0$$

at full load

$$P_i = P_{cu}$$

at  $x$  load

$$P_i = x^2 P_{cu}$$

IRON loss =  $x^2$  cu losses

$$x = \sqrt{\frac{P_i}{P_{cu}}}$$

$$\begin{aligned} \text{output KVA for max } \eta &= x \times \text{full load KVA} \\ &= \sqrt{\frac{P_i}{P_{cu}}} \times \text{full load KVA} \end{aligned}$$

OC & SC test:-

→ **All day efficiency**  
 It is the ratio of output power in KWh unit  
input power

### \* Voltage Regulation

$$E_2 - V_2 = I_2 R_{eq} \cos \theta_2 + I_2 X_{eq} \sin \theta_2$$

$\cos \theta$  → load power factor

$$\text{Per unit voltage } R = \frac{I_2 R_{eq} \cos \theta_2}{E_2} + \frac{I_2 X_{eq} \sin \theta_2}{E_2}$$

$$= E_R \cos \theta_2 \pm E_X \sin \theta_2$$

↓                          ↓

per unit resistive drop      per unit inductive drop

inductive +  
capacitive -  
reactance

$$E_R = \frac{I_2 R_{eq}}{E_2}$$

$$E_X = \frac{I_2 X_{eq}}{E_2}$$

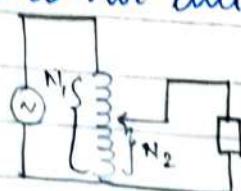
$$\% VR = (E_R \cos \theta_2 \pm E_X \sin \theta_2) \times 100$$

Condition for zero voltage regulation

(i) load power factor is leading (capacitive load)

### Auto-transformer (variac)

A transformer in which a part of the winding is common to both the primary & secondary circuit. In autotransformer two windings are not electrically isolated



On load, a part of the load current is obtained directly from the supply & remaining part is obtained by transformer action.

Autotransformer is Stepdown transformer.

3  
unit

# Measuring Instruments

- \* which measures Power, wattage, voltage, current, energy, etc.

- Wattmeter
  - Voltmeter
  - Ammeter
- } Analogue only.

## Q. Essential Req of Electrical Instruments

### Measuring Instruments

Absolute M.I

Measuring  $\propto$  constt  
qty

Eg:- Tangent Galvanometer  
 $V \propto \tan\theta$

Syllabus

Secondary M.I

Measured  $\propto$  Deflection  
, qty (moving part)

Indicating  
deflection of  
nude points  
measured qty

- Ammeter
- voltmeter

Syllabus

Integrating  
Integrating diff  
characteristic of  
ckt.

→ Energy meter  
(induction type)

Recording  
Recording the  
readings of  
indicating &  
integrating type  
devices

→ All indicating type  
can be converted into  
recording type.

Q. Essentials of Measuring Instrument (3-5 marks)

A1. (a) Deflecting Torque ( $T_d$ )

→ moving needle from stationary to measured value

→ Torque can be due to magnetic, chemical force, etc.

→ Magneto-type Ammeter  
→ using magnetic force

→ induction type Energy meter → using faraday law of induction.

(b) Controlling Torque ( $T_c$ )

when measured force is removed, pointer should

come back to zero & to stabilise the pointer at reading

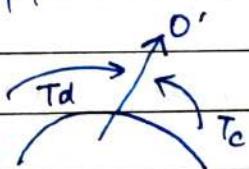
controlling Torque (Equal to deflection Torque but in opposite dir.)

(c) Damping Torque

vibration/ oscillations at measuring value

which is due to inertia hence Damping Torque

minimises this oscillation



methods to produce controlling torque

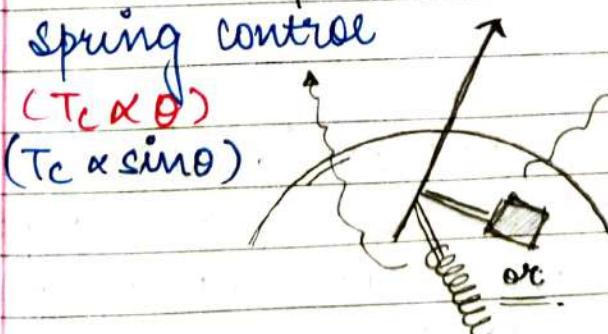
(a) Spring control

$$(T_c \propto \theta)$$

$$(T_c \propto \sin\theta)$$

(b) Weight Control

$$(T_c \propto mg)$$



Types of Damping Torque

(a) Eddy current

opposite eddy current to

absorb vibrations/ oscillations. Placed near metal

(b) Fluid friction

Instrument kept in air in chamber

(c) Oil damping

chamber placed in oil

Q. Essentials of measuring Instrument (3-5 marks)

A1. (a) Deflecting Torque ( $T_d$ )

→ moving needle from stationary to measured value

→ Torque can be due to magnetic, chemical force, etc.

→ Magneto-type Ammeter  
→ using magnetic force

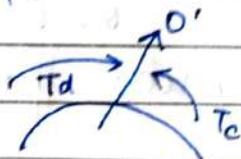
→ induction type Energy meter → using faraday law of induction.

(b) Controlling Torque ( $T_c$ )

when measured force is removed, pointer should

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controlling Torque (Equal to deflection Torque but in opposite dir)



(c) Damping Torque

vibration/ oscillations at measuring value

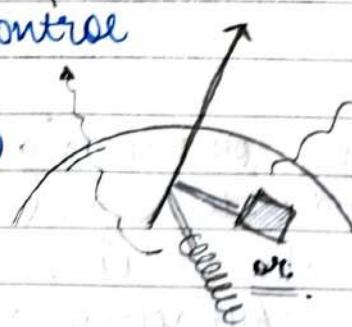
which is due to inertia hence Damping Torque minimises this oscillation

Methods to produce Controlling torque

(a) Spring control

$$(T_c \propto \theta)$$

$$(T_c \propto \sin\theta)$$



(b) Weight Control

$$(T_c \propto mg)$$

Types of Damping Torque

(a) Eddy current

opposite eddy

current to absorb vibrations/ oscillations. Placed on spirals.

(b) Fluid friction

Instrument kept in air in chamber

(c) Oil damping

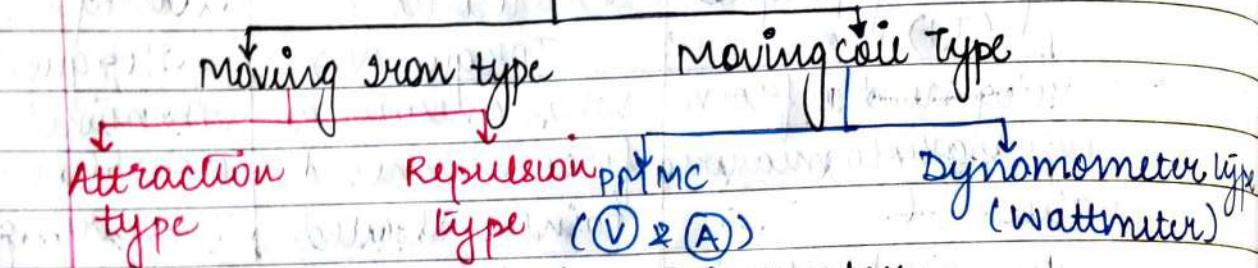
chamber placed in oil

Vehicle  
position

horizontal position

Date :- 10 Feb 2023  
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# MEASURING INSTRUMENTS



Q Difference b/w voltmeter & Ammeter.

→ coil 50mA & 50mV → extend the range.  
multiplier not series

Voltage → connect ~~Shunt~~ in ~~parallel~~ <sup>multiplier</sup> Series

Voltage → connect shunt in parallel  
Ammeter → connected multiplier in series || w/  
shunt

## LOGIC :-

more current we need to measure  $\rightarrow R \downarrow \rightarrow$

Connect in parallel (FORMULA)  
or thick wire

Shunt ~~is~~ means parallel.

## Principle

More voltage  $\rightarrow$  More R  $\rightarrow$  In series  
or thin wire.

Deflecting Torque is due to current

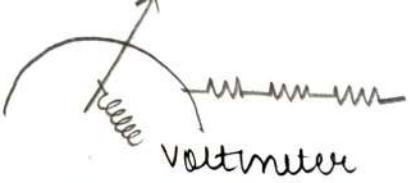
~~Current~~

Q. Diff b/w moving iron or moving coil

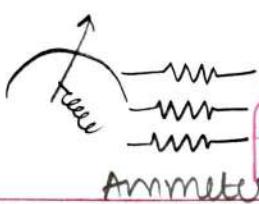
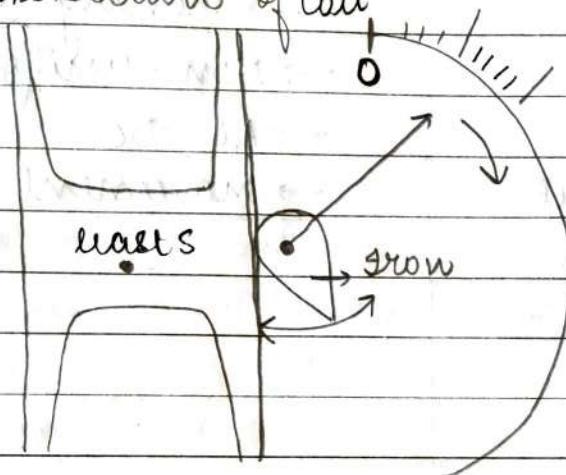
Iron  $\rightarrow$  Magnetism  $\rightarrow$  Attractive & Repulsive force.

## MOVING COIL TYPE:-

Attraction type :-



Cross section of coil



Ammeter

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current carrying  
coil produces  
magnetism

Moving iron attracts  
towards the center  
of coil.

deflection  $\rightarrow$  iron  $\rightarrow$  attraction  $\rightarrow$  magnetism  $\rightarrow$  current  
( $B \propto I$ )

Reluctance  $\sim$  Resistance

(S)  $\hookrightarrow$  Opposition to the flow of magnetism

Principle When a soft iron piece is placed in the M.F. of a current carrying coil it is attracted towards center of the coil because center of coil is the point of min Reluctance.

Advantage :-

- (a) cheap
- (b) simple
- (c) Both AC & DC.  $\approx$

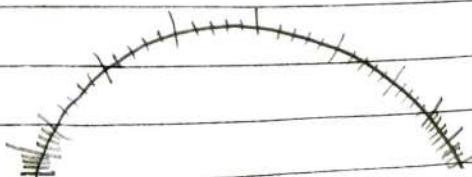
$$\begin{aligned} \theta &\propto I^2 \\ T_d &\propto I^2 \end{aligned}$$

$$T_c = T_d$$

$$T_c \propto \theta$$

$\theta \rightarrow$  deflection

$\rightarrow$  non-uniform scale.



Moving coil

→ Uniform scale

→ Only DC

→ Movement due to coil

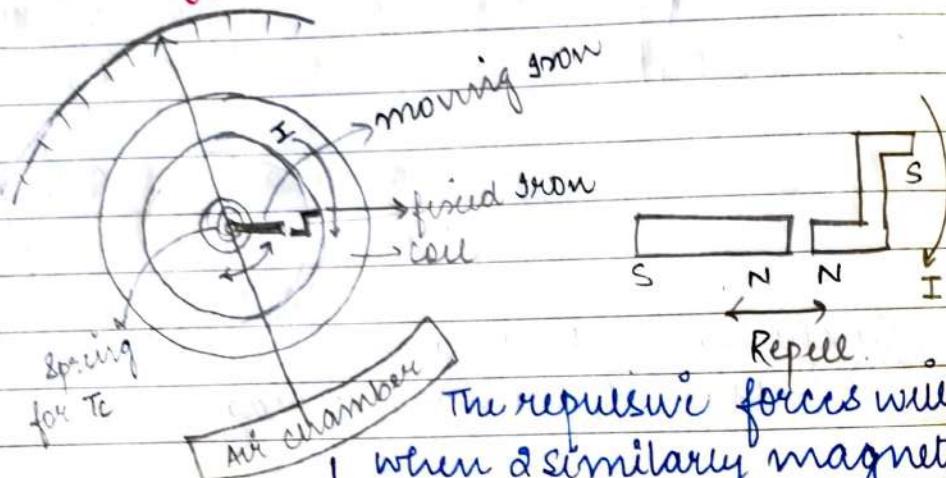
Moving iron

→ Non-uniform scale.

→ AC - DC

→ Movement due to iron

### # Repulsion type :-



The repulsive forces will act

when 2 similarly magnetised iron pieces are placed near to each other.

### # PMMC Type :-

### Permanent Magnet Moving Coil Type :-

Characteristics

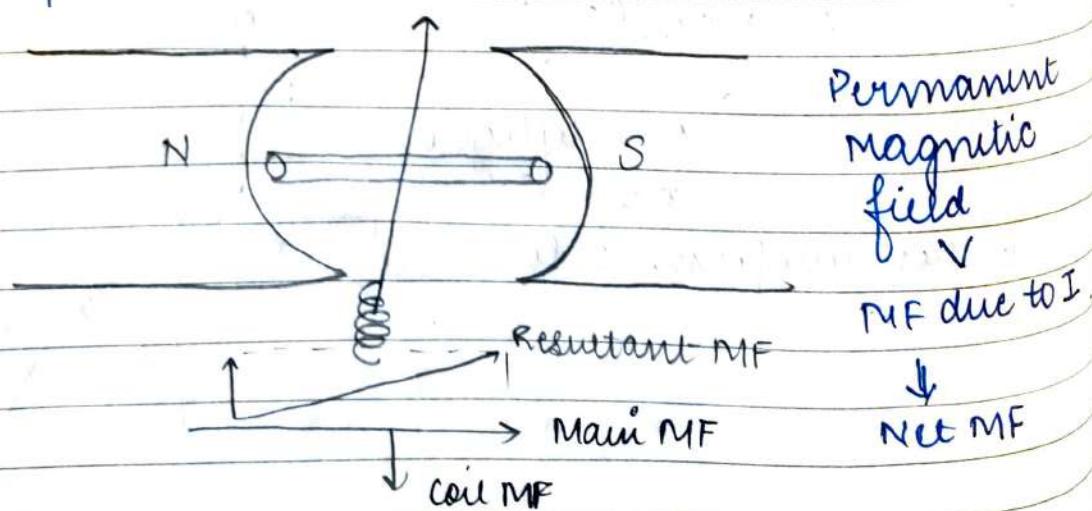
(a) Sensitive & accurate

(b) Only on DC.

(c) Voltmeter & Ammeter.



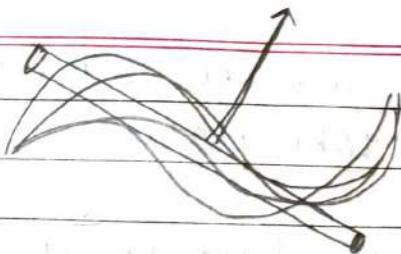
(d) Uniform scale.



Speed  $\propto$  poles

CLASSTIME Pg. No.

Date / /



Pointer  $\rightarrow$  coil  $\rightarrow$  Resultant  
MF  $\rightarrow \Delta$  MF  $\rightarrow$  Field due to  
coil  $\rightarrow I$

when a current carrying coil is placed in a uniform MF, it experiences a MForce  $\rightarrow T$

Magnetic field N  $\rightarrow$  S }  
 $\textcircled{\sim}$  S  $\rightarrow$  N & N  $\rightarrow$  S }  $\Rightarrow$

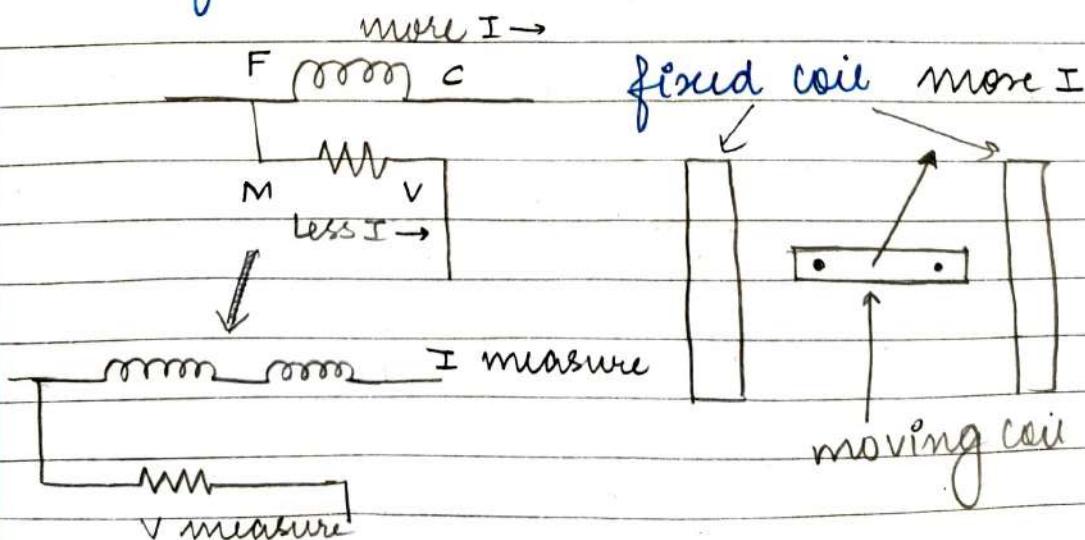
If current in the coil is reversed, the dir of deflecting Torque will be reversed bcz field produced by permanent Magnet doesn't change. This will give wrong dir of rotation.

$$\Theta \propto I$$

## # DYNAMOMETER TYPE:-

(moving coil type)

(used for wattmeter only).



when a current carrying coil is placed in MF produced by the current carrying fixed

coil, A force is exerted on the coil sides of the moving coil & deflection takes place.

In other words, when the field produced by the current carrying moving coil tries to come in line with the field produced by the current carrying fixed coil. A deflecting torque is exerted on the moving sys & deflection takes place.

The fixed coil is connected in series with the load & carries ckt current . therefore it is called current coil .

The moving coil is placed b/w the 2 parts of fixed coil & is mounted on spindle . The moving coil is connected in ||<sup>th</sup> with load & carries the current proportional to voltage . therefore it is called potential coil .

# DC MACHINES

an added battery  
CLASSTIME Board  
Date:

E<sub>c</sub> incoming I<sub>a</sub>

→ Motor (E<sub>c</sub> → Mech)

→ Generator Eg

(Mech → E<sub>c</sub>) autonomy  
I<sub>a</sub>

construction

Principle

Working

Speed Control of Shunt / Service Motor.

## DC Machines

separately excited  
DC machine

self Excited DC machi-  
nes

series  
source  
series

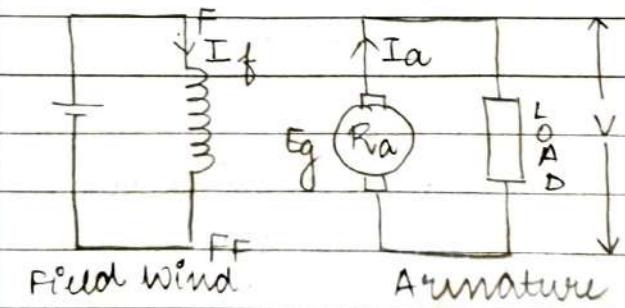
shunt

compound

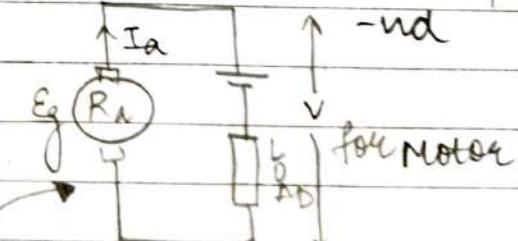
→ long  
shunt

→ short  
shunt

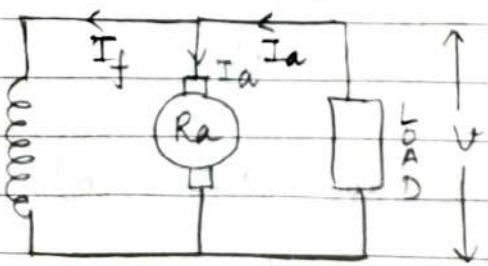
Field winding (generate flux)  
Armature part (rotating part)



Field wind.  
current carrying coil  $\rightarrow$  M Flux

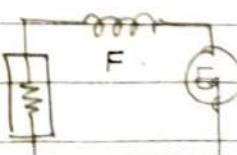


v terminal voltage (Motor  $\rightarrow$  Input, Generator  $\rightarrow$  output)

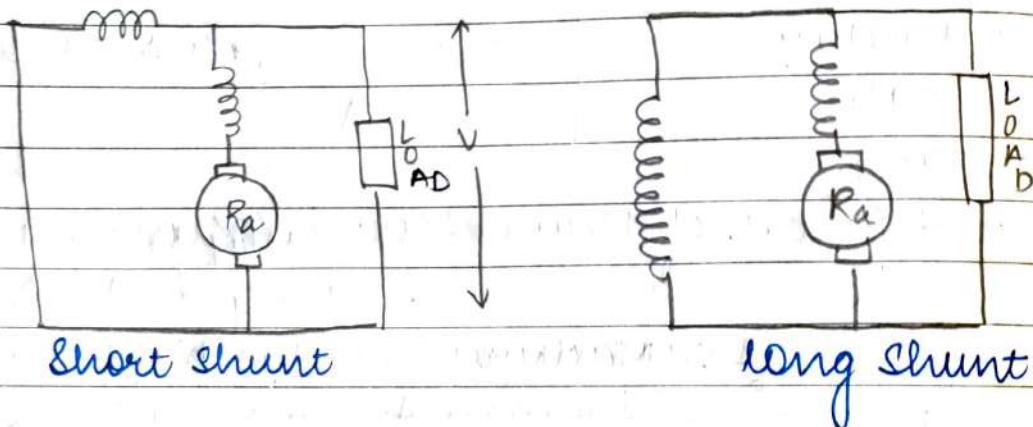


Self Excited (shunt)

Series :-



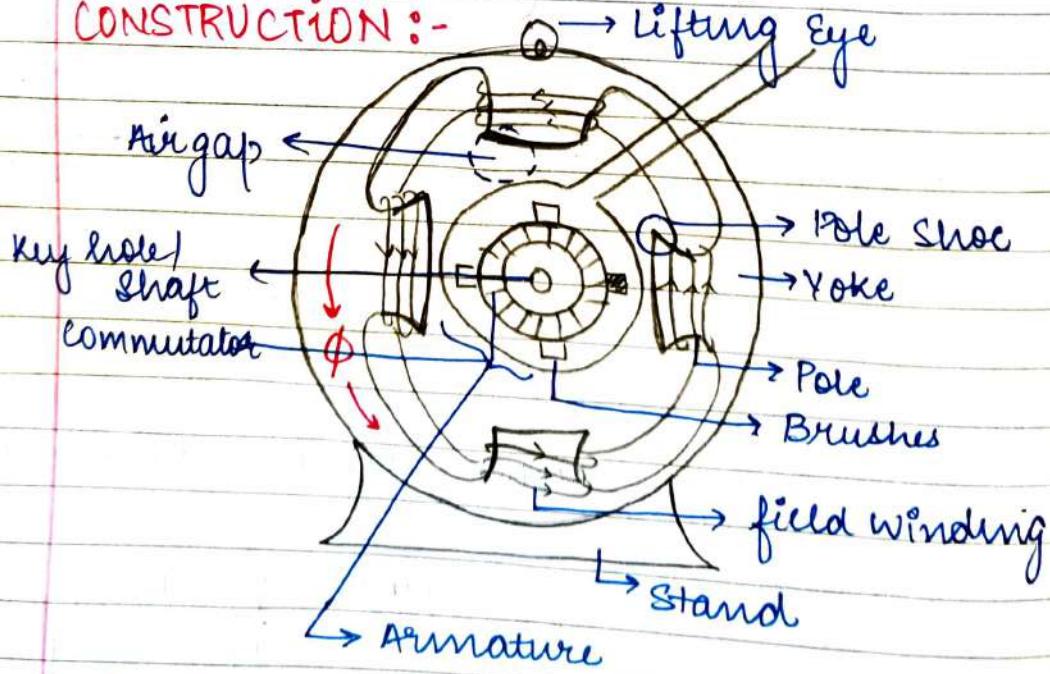
## Compound



→ Differentially compound :- Net flux of both coils is subtraction of each flux (joined in opposite direction)

→ Cumulative :- Both coil has supporting field so net field is addition of both.

## CONSTRUCTION :-



4 pole :- 4 pole DC machine (even no.)

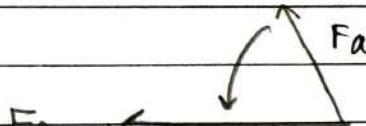
Yoke :- carry flux (magnetic material)

Made up of soft iron, frame of DC machine,

Field winding (in series) is connected on pole & supply  $\phi$  in air gap.

Current carrying coil  $\rightarrow$  produces MF  $\rightarrow$  experience a force.

(Armature :- own MF, field winding :- own MF  
 $F_W > A \rightarrow$  Subtract)

 Farm Armature will try to align with MF  $\rightarrow$  Armature Rotate  $\rightarrow$  cut flux  $\rightarrow d\phi/dt \rightarrow$  emf  $\rightarrow$  produces current  $\rightarrow$  own MF  $\rightarrow$  interlace with field winding MF  $\rightarrow$  try to align & so on.

commutator :- ~~split~~ slip rings + brushes (Rectifier for DC machine)

$\rightarrow$  Residual magnetism  
 Retentivity

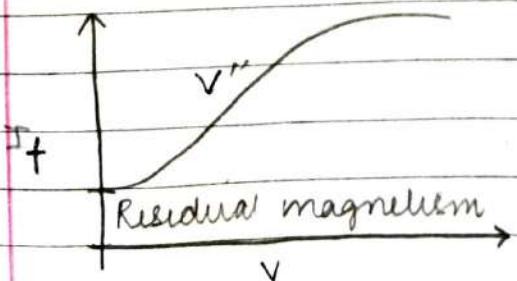
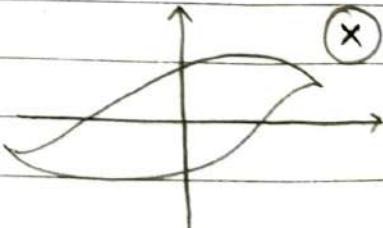
$$H = NI = 0$$

But  $B \neq 0$



for core of DC Generator

Used to start DC generator.



by commutator  $\rightarrow$  EMF  $\rightarrow$  AC  
 $\rightarrow$  Current  $\rightarrow$  DC

## EMF equation for DC generator

$$= \frac{\Phi Z N}{60} \frac{P}{A} \text{ Volts}$$

P = NO. of poles

$\Phi$  = flux produced by each pole. (Wb/Pole)

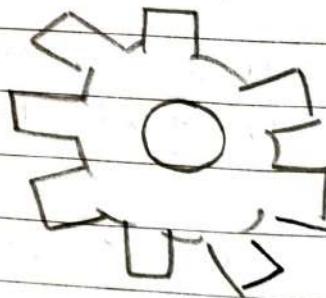
N = Speed of Armature in RPM

Z = Total no. of Armature conductors

A = No. of parallel paths

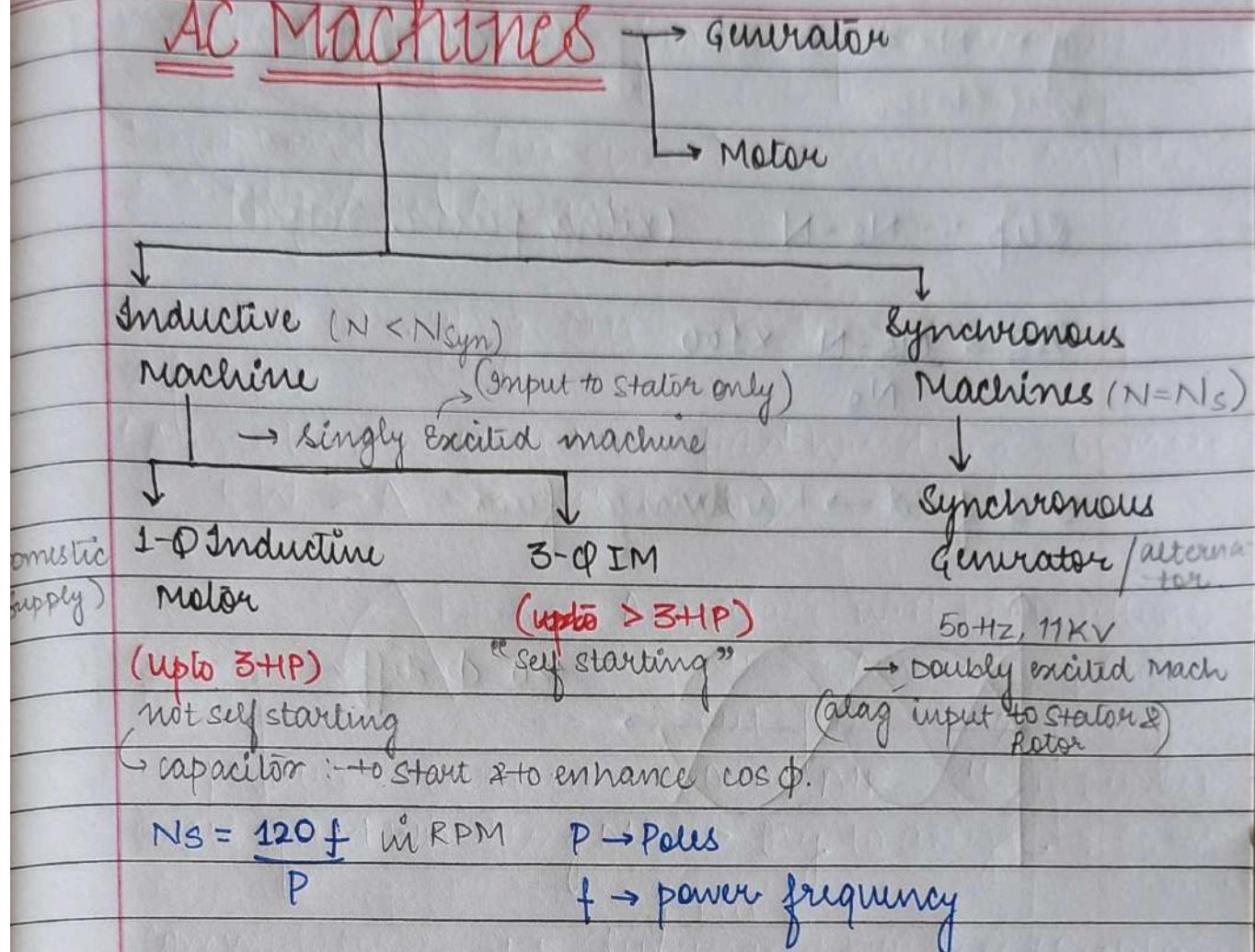
A = P (Lap winding)

A = 2 (wave winding)

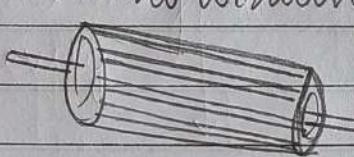


Inside Armature.

# AC Machines



1-Φ I.M → construction Rotor → squirrel cage



no winding  $\Rightarrow$  Al/Cu bars

type

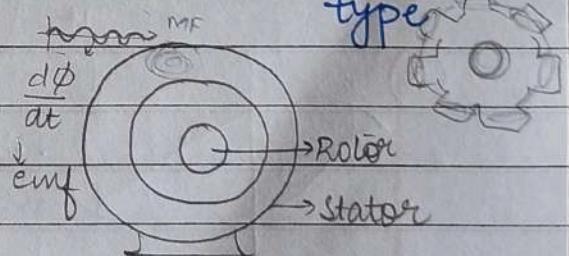
(slant - reduce  
humming)

Round wound

type

3-Φ I.M → Rotor  
Stator

Induction 3Φ



MF in stator  $\rightarrow \frac{d\phi}{dt} \rightarrow \text{emf} \rightarrow$  current in Rotor  $\rightarrow$

own MF  $\rightarrow$  resultant (main field > Rotor field)  $\rightarrow$   
try to align w main field.

Stator is running at  $N_s$  ( $f$  is 50Hz)

- Rotor (w capacitor)  $N < N_s$

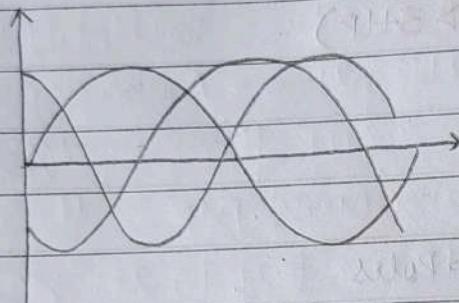
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If  $N = N_s \Rightarrow$  relatively stationary  $\rightarrow$  motor  
wrt stator

Slip  $\dots N_s - N$  (kitna parche rotor)

$$\%S = \frac{N_s - N}{N_s} \times 100$$

3-Ø field  $\rightarrow$  Revolving field



120°  $\phi$  diff