05/10/16. Realization of Digital & Filters. Difference equation specifies actual operations that are performed by digital System on input data in time domain. Advantages of representing degital feeting in Block dia

-> early to analyse I/o relationship

-> early to determine hardware requirements.

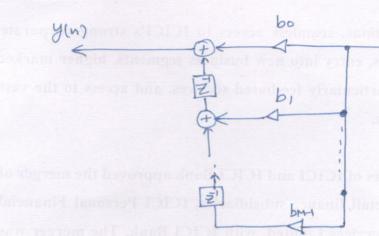
-> early to develop block dia from transfer function. FIR filter Structions H(Z) = M-1 bkZk A(W) = POX(W) + PIX(W-1) +--+ PW-X(W-WH) longth of filter = M = no. of weeks order = M-1. requires. 1 coefficients (6). actur-mat) Mmultiplies - M-1 additions.

I' Direct - Form D.F. Heureture of M-Dorder FIRfelter - M-1 memory locations to 2(11-1) Store M-1 perevious 1/p samples. -M memory locations to store x(n-142) 6m-2

III Polyphan Structure H(Z) = 5 bkZ-K = 5 A(K)Z-K. odd & even incleves. = M-1 MK) = 2K + M-1 R(2K+1) - Z(2K+1) = M-1 A(2K) = 2K + 100 = 1. M-1 A(2K+1) = (2Km) let • Eol2) = Stalok)2-K, E,(2) = My Alokan) = K

=) H(Z) = TO (Z2) + Z' E(Z2).

length = 7. H12) = (Q(0) + Q(2) Z2 + h(4) Z4 + h(6) Z6 (+ Z [A(1) + h(3) Z + h(5) Z - 4]+++ A10) X(2) X(2) 4(2) A(2) M(4) F1(23) Polyphase struct of FIR filter. h(5) n(3) hu) IIR filter structuras. For Ma7. TI I DEK



TV Cascade form structure.

also
$$H_{K}(Z) = \frac{Y_{K}(Z)}{X_{K}(Z)} = \frac{Y_{K}(Z)}{X_{K}(Z)} = \frac{Y_{K}(Z)}{X_{K}(Z)} + \frac{Y_{K}(Z)}{X_{K}(Z)} + \frac{Y_{K}(Z)}{X_{K}(Z)}$$

3) Yk(n) = pkox(n) + pkixk(n-1) + pkxk(n-2)

adders & vice versa.

cascade Realization x(n)

