

Ad



CM (UNIT 3-4)

→ EXISTENCE OF SOLUTIONS

First we will find the Rank of the Matrix,



First apply Gauss Elimination Method steps (both) to matrix and then no. of completely non-zero rows is the Rank of matrix.

Now, if $P(A) \neq P(A|B) \Rightarrow$ No Solution
 $R = P(A) = P(A|B) \Rightarrow$ Solution

Rank of 'A' matrix \leftarrow $R = n$ \rightarrow Augmented Matrix $R < n$

\Rightarrow Unique Solution \Rightarrow Infinitely many solution

I. GAUSS ELIMINATION METHOD

Q. $x - y + 2z = 3$ — (1)

$x + 2y + 3z = 5$ — (2)

$3x - 4y - 5z = -13$ — (3)

A. Write it in form of matrix

$$\begin{bmatrix} 1 & -1 & 2 \\ 1 & 2 & 3 \\ 3 & -4 & -5 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 3 \\ 5 \\ -13 \end{bmatrix}$$

$\rightarrow AX = B$

$$(A : B) = \left[\begin{array}{ccc|c} 1 & -1 & 2 & 3 \\ 1 & 2 & 3 & 5 \\ 3 & -4 & -5 & -13 \end{array} \right]$$

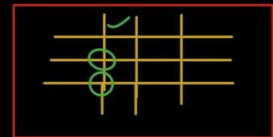
→ Now, we will apply row transformation converting '0' to zero using '1'.
 \therefore In above case we will convert 3 & 1 into 0 using '1'.

$$\begin{array}{l} R_2 \rightarrow R_2 - R_1 \\ R_3 \rightarrow R_3 - 3R_1 \end{array} \Rightarrow \left[\begin{array}{ccc|c} 1 & -1 & 2 & 3 \\ 0 & 3 & 1 & 2 \\ 0 & -1 & -11 & -22 \end{array} \right]$$

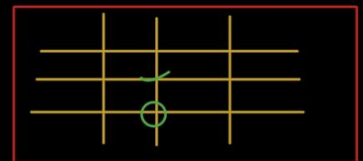
$$R_3 \rightarrow 3R_3 + R_2 \Rightarrow \left[\begin{array}{ccc|c} 1 & -1 & 2 & 3 \\ 0 & 3 & 1 & 2 \\ 0 & 0 & -32 & -64 \end{array} \right]$$

Now, we will write it again in eq. form $x - y + 2z = 3$ — (1)

Step 1 →



Step 2 →





Ad



Now, we will write it again in eq. form $\Rightarrow x - y + 2z = 3$ — (1)

$$\Rightarrow \boxed{z = 2} \Rightarrow \boxed{y = 0} \Rightarrow \boxed{x = -1}$$

$$3y + z = 2 \text{ — (2)}$$

$$-32z = -64 \text{ — (3)}$$

II. GAUSS JORDAN METHOD

$$\text{Q. } x + 4y + 9z = 16 \text{ — (1)}$$

$$2x + y + z = 10 \text{ — (2)}$$

$$3x + 2y + 3z = 18 \text{ — (3)}$$

A. Write it in form of matrix \Rightarrow

$$\begin{bmatrix} 1 & 4 & 9 \\ 2 & 1 & 1 \\ 3 & 2 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 16 \\ 10 \\ 18 \end{bmatrix}$$

$$\Rightarrow AX = B$$

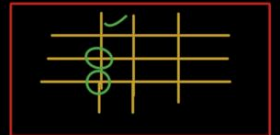
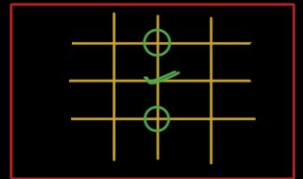
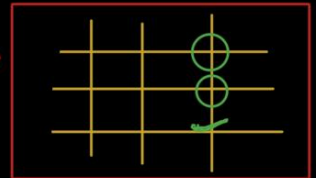
$$(A : B) = \left[\begin{array}{ccc|c} 1 & 4 & 9 & 16 \\ 2 & 1 & 1 & 10 \\ 3 & 2 & 3 & 18 \end{array} \right]$$

$$\begin{array}{l} R_2 \rightarrow R_2 - 2R_1 \\ R_3 \rightarrow R_3 - 3R_1 \end{array} = \left[\begin{array}{ccc|c} 1 & 4 & 9 & 16 \\ 0 & -7 & -17 & -22 \\ 0 & -10 & -24 & -30 \end{array} \right]$$

$$\begin{array}{l} R_3 \rightarrow 7R_3 - 10R_2 \\ R_1 \rightarrow 7R_1 + 4R_2 \end{array} = \left[\begin{array}{ccc|c} 7 & 0 & -5 & 24 \\ 0 & -7 & -17 & -22 \\ 0 & 0 & 2 & 10 \end{array} \right]$$

$$\begin{array}{l} R_1 \rightarrow 2R_1 + 5R_3 \\ R_2 \rightarrow 2R_2 + 17R_3 \end{array} = \left[\begin{array}{ccc|c} 14 & 0 & 0 & 98 \\ 0 & -14 & 0 & 126 \\ 0 & 0 & 2 & 10 \end{array} \right]$$

$$\begin{array}{l} 14x = 98 \Rightarrow \boxed{x = 7} \\ -14y = 126 \Rightarrow \boxed{y = -9} \\ 2z = 10 \Rightarrow \boxed{z = 5} \end{array}$$

Step 1 \rightarrow Step 2 \rightarrow Step 3 \rightarrow 

LU DECOMPOSITION METHOD

Let

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

Here $AX = B$ — (1)

$$\Rightarrow A = LU = \begin{bmatrix} a & 0 & 0 \\ b & c & 0 \\ d & e & f \end{bmatrix} \begin{bmatrix} g & h & i \\ 0 & j & k \\ 0 & 0 & l \end{bmatrix}$$

Lower Δ \swarrow
Upper Δ \nwarrow



Aa



LU DECOMPOSITION METHOD

Let $\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$ Here $Ax = B$ — ①

$\Rightarrow A = LU = \begin{bmatrix} a & 0 & 0 \\ b & c & 0 \\ d & e & f \end{bmatrix} \begin{bmatrix} g & h & i \\ 0 & j & k \\ 0 & 0 & l \end{bmatrix}$

Lower Δ (pointing to the L matrix)
Upper Δ (pointing to the U matrix)

Putting $A = LU$ in ①, we get $L(UX) = B$
 $LY = B$

I. DOLITTLE'S METHOD

$A = LU$ where $L = \begin{bmatrix} 1 & 0 & 0 \\ a & 1 & 0 \\ b & c & 1 \end{bmatrix}$ and $U = \begin{bmatrix} d & e & f \\ 0 & g & h \\ 0 & 0 & i \end{bmatrix}$

II. CROUT'S FACTORISATION METHOD

$A = LU$ where $L = \begin{bmatrix} a & 0 & 0 \\ b & c & 0 \\ d & e & f \end{bmatrix}$ and $U = \begin{bmatrix} 1 & g & h \\ 0 & 1 & i \\ 0 & 0 & 1 \end{bmatrix}$

III. CHOLESKY METHOD \rightarrow only useful for symmetric method

$A = LL^T$ where $L = \begin{bmatrix} a & 0 & 0 \\ b & c & 0 \\ d & e & f \end{bmatrix}$ and $U = \begin{bmatrix} a & b & d \\ 0 & c & e \\ 0 & 0 & f \end{bmatrix}$
 (L^T)

POWER METHOD

Q. Find the numerically larger Eigen value of the matrix by power method.

$$A = \begin{bmatrix} 1 & -3 & 2 \\ 4 & 4 & -1 \\ 6 & 3 & 5 \end{bmatrix}$$

A. Let us take initial value as $X_0 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

Iteration 1 :- $AX_0 = \begin{bmatrix} 1 & -3 & 2 \\ 4 & 4 & -1 \\ 6 & 3 & 5 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 7 \\ 14 \end{bmatrix}$

\rightarrow Taking largest value common

\therefore At the end of iteration 1, the largest eigen value = 14 and

$$\Rightarrow 14 \begin{bmatrix} 0 \\ 0.5 \\ 1 \end{bmatrix}$$



Aa



iteration 1, the largest
eigen value = 14 and
eigen vector = $\begin{bmatrix} 0 \\ 0.5 \\ 1 \end{bmatrix}$

$$\Rightarrow 14 \begin{bmatrix} 0 \\ 0.5 \\ 1 \end{bmatrix}$$

Iteration 2 :-

$$AX_0 = \begin{bmatrix} 1 & -3 & 2 \\ 4 & 4 & -1 \\ 6 & 3 & 5 \end{bmatrix} \begin{bmatrix} 0 \\ 0.5 \\ 1 \end{bmatrix} = \begin{bmatrix} 0.5 \\ 1 \\ 6.5 \end{bmatrix} \Rightarrow 6.5 \begin{bmatrix} 0.07692 \\ 0.15384 \\ 1 \end{bmatrix}$$

Iteration 3 :-

$$AX_0 = \begin{bmatrix} 1 & -3 & 2 \\ 4 & 4 & -1 \\ 6 & 3 & 5 \end{bmatrix} \begin{bmatrix} 0.07692 \\ 0.15384 \\ 1 \end{bmatrix} = \begin{bmatrix} 1.6454 \\ -0.07696 \\ 5.92304 \end{bmatrix} \Rightarrow 5.92304 \begin{bmatrix} 0.07692 \\ 0.15384 \\ 1 \end{bmatrix}$$

\therefore Largest Eigen Value = 5.92304

$$\text{Eigen Vector} = \begin{bmatrix} 0.07692 \\ 0.15384 \\ 1 \end{bmatrix}$$

And solve so on!

* We will solve till the given iteration (if mentioned) or if not given then will solve till 2 consecutive readings of Eigen value.

PICARD METHOD

$$y_{n+1} = y_0 + \int_{x_0}^x f(x, y_n) dx$$

Q. Solve by picard method (upto 3rd approximation) $\frac{dy}{dx} = x + y^2$; $y(0) = 0$

Also find $y(0.1)$.

A. $f(x, y) = x + y^2$ | $\frac{x_0 = 0 \quad y_0 = 0}{\text{①}}$

$$\left[\begin{array}{l} \because y(0) = 0 \\ \Rightarrow \text{whole } y \text{ value} = 0 \\ \text{and } y \text{ of } x \text{ value} = 0 \end{array} \right]$$

Now, in Picard formula, put $n=0$

we have, $y_1 = y_0 + \int_{x_0}^x f(x, y_0) dx$

$$= y_0 + \int_0^x (x + y_0^2) dx \Rightarrow y_1 = 0 + \int_0^x (x + 0) dx \text{ [using ①]}$$



Aa



$$= y_0 + \int_{x_0}^x (x+y_0)^2 dx \Rightarrow y_1 = 0 + \int_0^x (x+0) dx \text{ [using ①]}$$

$$\Rightarrow y_1 = \left(\frac{x^2}{2} \right)_0^x = \frac{x^2}{2}$$

Now, Put $n=1$, we have $y_2 = y_0 + \int_{x_0}^x f(x, y_1) dx$

$$= y_0 + \int_{x_0}^x (x+y_1)^2 dx = 0 + \int_0^x \left(x + \left[\frac{x^2}{2} \right] \right)^2 dx$$

$$= \frac{x^2}{2} + \frac{x^5}{20}$$

Put $n=2$ and solve further till mentioned no. of approximations.

TAYLOR SERIES METHOD

$$y_{n+1} = y_n + h y'_n + \frac{h^2}{2!} y''_n + \frac{h^3}{3!} y'''_n + \dots$$

Q. Solve $\frac{dy}{dx} = x+y$ by Taylor Series Method. Start from $x=1$, $y=0$ and carry to $x=1.2$ with $h=0.1$.

A. $\frac{dy}{dx} = f(x, y) = x+y$

Also, $x_0 = 1$, $y_0 = 0$, $h = 0.1$

$\therefore x_1 = x_0 + h = 1.1$ and $y' = x+y$ (given)

$$\begin{array}{l|l} \because y' = x+y & y'_0 = 1+0 = 1 \\ \Rightarrow y'' = 1+y' & y''_0 = 1+1 = 2 \\ \Rightarrow y''' = y'' & y'''_0 = 2 \\ \Rightarrow y^{(4)} = y''' \text{ and so on} & y^{(4)}_0 = 2 \end{array}$$

By Taylor Series, $y_1 = y(x_1) = y_0 + h y'_0 + \frac{h^2}{2!} y''_0 + \frac{h^3}{3!} y'''_0 + \dots$

$$y(1.1) = 0 + (0.1)(1) + \frac{(0.1)^2}{2}(2) + \frac{(0.1)^3}{6}(2) + \frac{(0.1)^4}{24}(2) + \dots$$

$$y(1.1) = 0.11034 \approx \boxed{0.1103} = y_1$$

$$y(1.1) = 0 + (0.1)(1) + \frac{(0.1)^2}{2}(2) + \frac{(0.1)^3}{6}(2) + \frac{(0.1)^4}{24}(2) + \dots$$

$$y(1.1) = 0.11034 \approx \boxed{0.1103} = y_1$$

Now, $x_1 = 1.1$, $y_1 = 0.1103$, $h = 0.1$

$$\therefore x_2 = x_1 + h = 1.1 + 0.1 = 1.2$$

$$y'_1 = x_1 + y_1 = 1.1 + 0.1103 = 1.2103$$

$$y''_1 = 1 + y'_1 = 1 + 1.2103 = 2.2103$$

$$y'''_1 = y''_1 = 2.2103$$

$$y^{(4)}_1 = y'''_1 = 2.2103$$

By Taylor Series, $y_2 = y(x_2) = y_1 + h y'_1 + \frac{h^2}{2!} y''_1 + \frac{h^3}{3!} y'''_1 + \frac{h^4}{4!} y^{(4)}_1 + \dots$

$$= 0.24276 \approx \boxed{0.2428} = y_2$$

EULER METHOD

Euler's Method is also called Runge Kutta method of first order whereas

Euler's Modified Method is called Runge Kutta method of second order.

$$y_{n+1} = y_n + h f(x_n, y_n)$$

Q. Solve $\frac{dy}{dx} = x+y$; $y=1$ at $x=0$. Find approx. value of y for $x=0.1$

A.

$$\begin{aligned} x_0 &= 0 \\ x_1 &= 0.02 \\ x_2 &= 0.04 \\ x_3 &= 0.06 \\ x_4 &= 0.08 \\ x_5 &= 0.10 \end{aligned}$$

$$x_0 = 0$$

$$y_0 = 1$$

$$f(x, y) = x + y$$

$$y_{n+1} = y_n + h(x_n + y_n)$$

Put $n=0$,

$$y_1 = y_0 + h(x_0 + y_0) = 1 + 0.02(0 + 1) = \boxed{1.02}$$

$$\text{Put } n=1, \Rightarrow y_2 = 1.0408$$

$$\text{Put } n=2, \Rightarrow y_3 =$$

And so on, we will calculate all 'y' corresponding to x means in this case till y_5 ($\because x_5$ is last iteration).

EULER'S MODIFIED METHOD



Aa



EULER'S MODIFIED METHOD

$$y_{n+1}^* = y_n + h f(x_n, y_n)$$

$$y_{n+1} = y_n + \frac{h}{2} \left[f(x_n, y_n) + f(x_{n+1}, y_{n+1}^*) \right]$$

Q. Given $\frac{dy}{dx} = x^2 + y$ with $y(0) = 1$, find $y(0.02)$ and $y(0.04)$.

A. $f(x, y) = x^2 + y$

$\Rightarrow x_0 = 0, y_0 = 1$ $x_1 = 0.02$ $x_2 = 0.04$

$\Rightarrow h = x_2 - x_1 = 0.02$

Put $n=0$, we have

$$\begin{aligned} y_1^* &= y_0 + h f(x_0, y_0) \\ &= y_0 + h (x_0^2 + y_0) = 1 + 0.02 (0^2 + 1) \\ &= 1.02 \end{aligned}$$

$$\begin{aligned} \Rightarrow y_1 &= y_0 + \frac{h}{2} (f(x_0, y_0) + f(x_1, y_1^*)) \\ &= y_0 + \frac{h}{2} (x_0^2 + y_0 + x_1^2 + y_1^*) \\ &= 1 + 0.01 (0^2 + 1 + (0.02)^2 + 1.02) = \boxed{1.0202} \end{aligned}$$

Similarly, we will calculate y_2 as well and then question complete!!

RUNGE KUTTA METHOD OF FOURTH ORDER

$$K_1 = h f(x_n, y_n)$$

$$K_2 = h f\left(x_n + \frac{h}{2}, y_n + \frac{K_1}{2}\right)$$

$$K_3 = h f\left(x_n + \frac{h}{2}, y_n + \frac{K_2}{2}\right)$$

$$K_4 = h f(x_n + h, y_n + K_3)$$

$$K = \frac{1}{6} (K_1 + 2K_2 + 2K_3 + K_4)$$

$$\Rightarrow y_{n+1} = y_n + K$$

Q. Given $\frac{dy}{dx} = x + y^2$, $y(0) = 1$, Find $y(0.2)$ where $h = 0.1$.

A. $f(x, y) = x + y^2$

$\Rightarrow x_0 = 0, y_0 = 1$ $\therefore h = 0.1 \Rightarrow x_1 = 0.1$

Q. Given $\frac{dy}{dx} = x + y^2$, $y(0) = 1$, Find $y(0.2)$ where $h = 0.1$.

A. $f(x, y) = x + y^2$

Put $n=0$,

$$K_1 = h f(x_0, y_0) = h(x_0 + y_0^2) = 0.1(0 + 1) = 0.1$$

$$K_2 = h f\left(x_0 + \frac{h}{2}, y_0 + \frac{K_1}{2}\right) = h\left[\left(x_0 + \frac{h}{2}\right) + \left(y_0 + \frac{K_1}{2}\right)^2\right]$$

$$= 0.1\left[\left(0 + \frac{0.1}{2}\right) + \left(1 + \frac{0.1}{2}\right)^2\right] = 0.11525$$

$$K_3 = h f\left(x_0 + \frac{h}{2}, y_0 + \frac{K_2}{2}\right) = h\left[\left(x_0 + \frac{h}{2}\right) + \left(y_0 + \frac{K_2}{2}\right)^2\right] = 0.1169$$

$$K_4 = h f(x_0 + h, y_0 + K_3) = h[(x_0 + h) + (y_0 + K_3)^2] = 0.1347$$

$$\Rightarrow K = \frac{1}{6}[K_1 + 2K_2 + 2K_3 + K_4] = 0.1165$$

$$\Rightarrow y_1 = y_0 + K = 1 + 0.1165 = 1.1165$$

Similarly, we will find y_2 value and that'll be ans $[y(0.2)]$.

MILNE'S PREDICTOR AND CORRECTOR METHOD

Consider $\frac{dy}{dx} = f(x, y)$; $y(x_0) = y_0$; $y(x_1) = y_1$; $y(x_2) = y_2$; $y(x_3) = y_3$

where x_0, x_1, x_2 & x_3 are equi-distant values of x with step size h .

$$\therefore \text{Milne's Predictor Formula} \rightarrow y_4^p = y_0 + \frac{4h}{3}(2f_1 - f_2 + 2f_3)$$

$$\text{Milne's Corrector Formula} \rightarrow y_4^c = y_2 + \frac{h}{3}(f_2 + 4f_3 + f_4^p)$$

Q. Using Milne's Predictor Corrector Method, find y when $x = 0.8$, given

$$\frac{dy}{dx} = x - y^2; \quad y(0) = 0; \quad y(0.2) = 0.02; \quad y(0.4) = 0.0795;$$

$$y(0.6) = 0.1762.$$

$$\text{A. } f(x, y) = x - y^2$$

x	y	$f = x - y^2$	Here $h = 0.2$. on Applying Milne's Predictor Formula, we have $y_4^p = y_0 + \frac{4h}{3}(2f_1 - f_2 + 2f_3)$
$x_0 = 0$	$y_0 = 0$	$f_0 = 0$	
$x_1 = 0.2$	$y_1 = 0.02$	$f_1 = 0.1996$	



Aa



Q. Using Milne's Predictor Corrector Method, find y when $x=0.8$, given

$$\frac{dy}{dx} = x - y^2 ; y(0) = 0 ; y(0.2) = 0.02 ; y(0.4) = 0.0795 ;$$

$$y(0.6) = 0.1762.$$

A: $f(x, y) = x - y^2$

x	y	$f = x - y^2$
$x_0 = 0$	$y_0 = 0$	$f_0 = 0$
$x_1 = 0.2$	$y_1 = 0.02$	$f_1 = 0.1996$
$x_2 = 0.4$	$y_2 = 0.0795$	$f_2 = 0.3937$
$x_3 = 0.6$	$y_3 = 0.1762$	$f_3 = 0.5689$
$x_4 = 0.8$	$y_4^p = 0.3049$	$f_4^p = 0.707$
	$y_4^c = 0.3046$	

Here $h = 0.2$.

On Applying Milne's Predictor Formula, we have

$$y_4^p = y_0 + \frac{4h}{3} (2f_1 - f_2 + 2f_3)$$

$$= 0 + \frac{4 \times 0.2}{3} (2 \times 0.1996 - 0.3937 + 2 \times 0.5689)$$

$$\Rightarrow y_4^p = 0.3049$$

* After this put this value in table & find f_4^p .

Now, using Milne's Corrector Formula, we have

$$y_4^c = 0.3046$$

ADAM BASHFORTH PREDICTOR & CORRECTOR FORMULA

$$y_4^p = y_3 + \frac{h}{24} (55f_3 - 59f_2 + 37f_1 - 9f_0)$$

$$y_4^c = y_3 + \frac{h}{24} (9f_4^p + 19f_3 - f_2 + f_1)$$