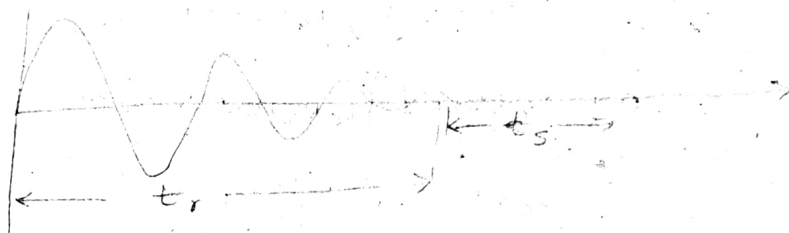


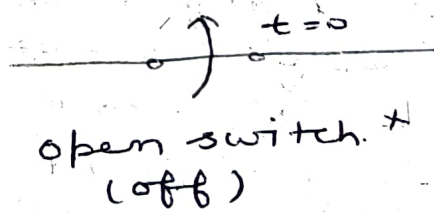
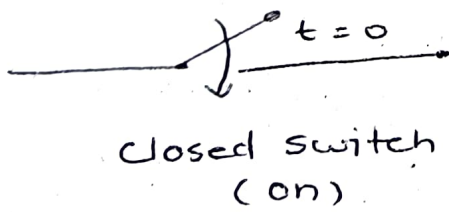
Whenever a ckt. is switched from one condition to another either by a change in the applied V_g or a change in ckt. element, there is a transition period during which branch current and element voltages change from their former value to new ones. This period is called Transient. After the transient has passed, the ckt. is said to be in steady state.



→ The linear diff. eqn that describes the ckt will have two parts to its solution.

- (i) Complementary fn. corresponds to transient
- (ii) Particular solution corresponds to steady state.

→ The ckt. changes are assumed to occur at time $t=0$ and represented by a switch.



$t = 0^-$ → Instant prior to $t=0$

$t = 0^+$ → Instant immediately after switching

→ Switching on or off an element or source in a ckt at $t=0$ will not disturb the storage element so that $i_L(0^-) = i_L(0^+)$, $V_C(0^-) = V_C(0^+)$.

Relationship for parameters:-

Parameter	Basic Relation	V-I Relation	Energy
1. R $G = 1/R$	$v(t) = Ri(t)$ or	$v_R(t) = Ri_R(t)$ $i_R(t) = Gv_R(t)$	$W_R(t) = \int_{-\infty}^t v_R(t) i_R(t) dt$
2. L	$\psi(t) = Li(t)$	$v_L(t) = L \frac{di_L(t)}{dt}$ $i_L(t) = \frac{1}{L} \int_{-\infty}^t v_L(t) dt$ or $i_L(t) = \frac{1}{L} \int_0^t v_L(t) dt + i_L(0^+)$	$W_L(t) = \frac{1}{2} Li_L^2(t)$
3. C	$q(t) = Cv(t)$	$v_C(t) = \frac{1}{C} \int_{-\infty}^t i_C(t) dt$ or $v_C(t) = \frac{1}{C} \int_0^t i_C(t) dt + v_C(0^+)$ $i_C(t) = C \frac{dv_C}{dt}$	$W_C(t) = \frac{1}{2} Cv_C^2(t)$

Differential equation →

1. I order Homogeneous diff. eqn →

$$\frac{dy(t)}{dt} + py(t) = 0$$

$p \rightarrow \text{const.}$

$$\frac{dy(t)}{y(t)} = -p dt$$

On Integration,

$$\ln y(t) = -pt + k'$$

$$\text{ie. } k' = \ln k$$

$$\ln y(t) = -pt + \ln k$$

$$= \ln(ke^{-pt})$$

$$y(t) = ke^{-pt}$$

If k is evaluated, the soln is a particular soln.

→ first order non homogeneous diff eqⁿ

$$\frac{dy(t)}{dt} + p y(t) = Q$$

$p \rightarrow \text{const}$

$Q \rightarrow \text{fn. of independent variable } t \text{ or const}$

$$e^{pt} \frac{dy(t)}{dt} + p e^{pt} y(t) = Q e^{pt}$$

$$\therefore d(x.y) = x dy + y dx$$

$$\Rightarrow \frac{d}{dt} (y(t) e^{pt}) = Q e^{pt}$$

On Integrating

$$y(t) e^{pt} = \int Q e^{pt} dt + k$$

$$y(t) = \underbrace{e^{-pt} \int Q e^{pt} dt}_{\text{P.I.}} + \underbrace{k e^{-pt}}_{\text{C.F.}}$$

- If Q is a const

$$y(t) = e^{-pt} \frac{e^{pt}}{p} \cdot Q + k e^{-pt}$$

$$= \underbrace{\frac{Q}{p}}_{\text{P.I.}} + \underbrace{k e^{-pt}}_{\text{C.F.}}$$

3) Second order differential eqⁿ →

$$A \frac{d^2 y(t)}{dt^2} + B \frac{dy(t)}{dt} + C y(t) = 0$$

$$\boxed{y(t) = k_1 e^{p_1 t} + k_2 e^{p_2 t}} \rightarrow \text{general soln}$$

$k_1, k_2 \rightarrow \text{const}$

$p_1, p_2 \rightarrow \text{roots of quadratic eqⁿ}$

$$A p^2 + B p + C = 0$$

$$p_1, p_2 = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

If $p_1 = p_2$ then

$$y(t) = k_1 e^{p_1 t} + k_2 t e^{p_1 t}$$

Initial conditions in circuits \rightarrow

Initial conditions are required to evaluate arbitrary const. in general soln of diff. eqn.

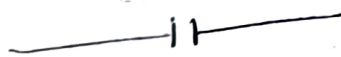
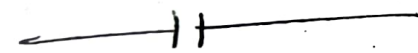
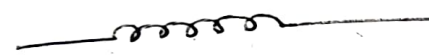
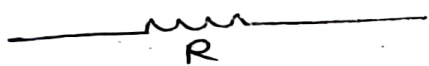
\rightarrow no. of initial conditions required is equal to the order of diff. eqn.

Steps to evaluate Initial conditions

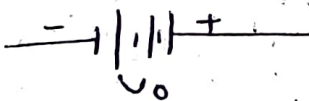
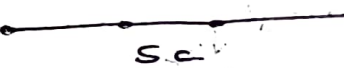
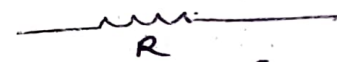
- 1) Draw the equivalent ckt. at $t = 0^+$
- 2) evaluate the initial values of V & i of all the branches.
- 3) Derivatives at $t = 0^+$ are evaluated.

Equivalent ckt. of the parameters

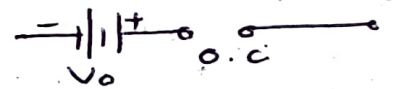
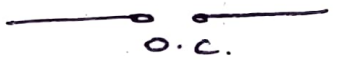
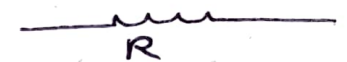
Element with Initial conditions



Equivalent ckt. at $t = 0^+$



Equivalent ckt. at $t = \infty$



Imp. char. of Inductor / Capacitor \rightarrow

1. There is no V / i across / through the L/C if the i / V through / across it is not changing with time. So L/C is short / open ckt. to d.c.
2. A finite amount of energy can be stored in the L/C even if the V / i across / through L/C is zero such as when i / V across / through it is const.
3. The L/C never dissipates energy but only store it. It is true only for mathematical model but not for physical model.

Various Responses \rightarrow

- ### Transient Response \rightarrow (means short lived)
- \rightarrow The value of V_g & ϕ during transient period are known as transient response
 - \rightarrow It is also defined as part of total response that goes to zero as time becomes large.
 - \rightarrow It depends upon N/w elements and independent of forcing fn. (source).
 - \rightarrow C.F. is the sol'n of diff. eq'n with forcing fn. set to zero.

- ### Steady state response \rightarrow
- \rightarrow The value of V_g & ϕ after the transient has died out are known as steady state response.
 - \rightarrow It is also defined as part of total time response which remains after transient has passed.
 - \rightarrow It depends on both N/w element and source.
 - \rightarrow P.I. represent the forced or steady state response

$$\text{Total time response} = T_t + T_{s.s.}$$

- ### 3. Zero Input Response \rightarrow
- \rightarrow Value of V_g & ϕ that result from initial conditions when the I/P or forcing fn is zero.

- ### 4. Zero state response \rightarrow
- \rightarrow Value of V_g & ϕ for an excitation which is applied when all initial conditions are zero.

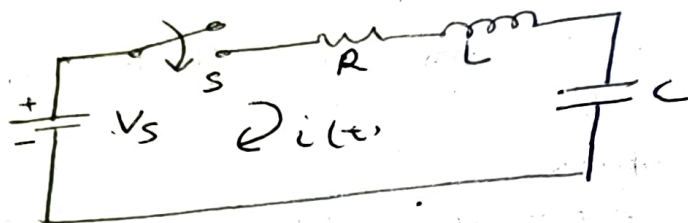
Transient Response of Series RLC circuit

d.c. excitation \rightarrow

Let us consider an eg.

$$V_s = 2V \quad R = 6\Omega \quad L = 2H \quad C = .25F$$

Determining $i(0^+)$, $\frac{di}{dt}(0^+)$, $\frac{d^2i}{dt^2}(0^+)$ and $i(t)$



By KVL

$$V_s = Ri(t) + L\frac{di(t)}{dt} + \frac{1}{C} \int i(t) dt \quad \text{--- (1)}$$

On differentiating

$$0 = R\frac{di(t)}{dt} + L\frac{d^2i(t)}{dt^2} + \frac{1}{C} i(t)$$

$$0 = 6\frac{di(t)}{dt} + 2\frac{d^2i(t)}{dt^2} + \frac{1}{.25} i(t)$$

$$0 = \frac{d^2i(t)}{dt^2} + 3\frac{di(t)}{dt} + 2i(t) \quad \text{--- (2)}$$

$$\text{Let } \frac{d^2i(t)}{dt^2} = p^2 \quad \frac{di(t)}{dt} = p$$

$$p^2 + 3p + 2 = 0$$

$$\Rightarrow P_1 = -1 \quad P_2 = -2$$

$$i(t) = K_1 e^{-t} + K_2 e^{-2t} \quad \text{--- (3)}$$

K_1, K_2 can be evaluated for a specific problem by the knowledge of initial conditions

If the switch is closed at $t=0$ then

$$\boxed{i(0^+) = 0} \quad \text{--- (4)}$$

[\because Inductor c.t. can't change instantaneously in inductor and C behave as o.c.]

In eq'n (1) 1 & 3 v/g terms are zero at the instant of switching. $Ri(0^+)$ being 0 b/c $i(0^+) = 0$ & $\frac{1}{C} \int_{-\infty}^{0^+} i dt$ b/c it is the initial v/g. a/c capacitor

hence $\frac{di}{dt}(0^+) = \frac{V_s}{L} - \frac{2}{2} = 1 \text{ A/sec.} \quad \text{--- (5)}$

from eqn (2)

$$\frac{d^2i}{dt^2}(0^+) + 3\frac{di}{dt}(0^+) + 2i(0^+) = 0$$

$$\begin{aligned} \frac{d^2i}{dt^2}(0^+) &= -3 \times 1 - 2 \times 0 \\ &= -3 \text{ A/sec}^2 \quad \text{--- (6)} \end{aligned}$$

The above two initial conditions (4) & (5) put into the general sol'n, eqn (3) gives

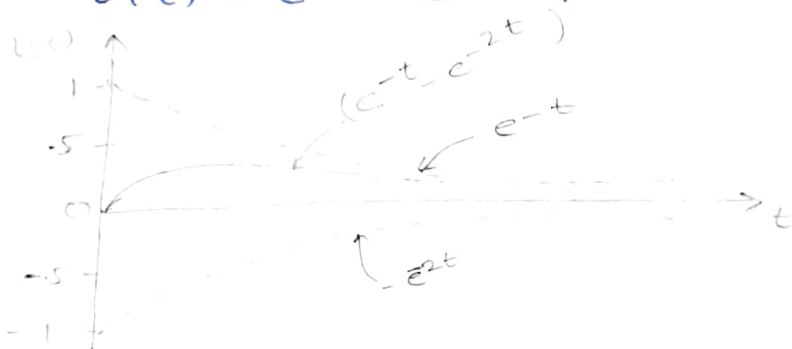
$$k_1 + k_2 = 0$$

$$-k_1 - 2k_2 = 1$$

$$\Rightarrow k_1 = 1, k_2 = -1$$

Hence Particular sol'n is

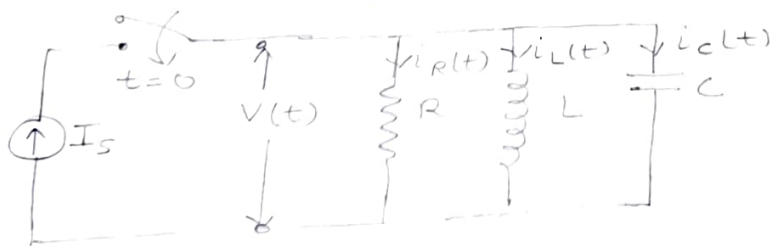
$$i(t) = e^t - e^{-2t} \text{ A}$$



RLC parallel circuit

Let $R = \frac{1}{16} \Omega$ $L = \frac{1}{16} \text{ H}$ $C = 4 \text{ F}$ $I_s = 2 \text{ A}$

determine $v(0^+)$, $\frac{dv}{dt}(0^+)$, $\frac{d^2v}{dt^2}(0^+)$, $v(t)$



By KCL

$$\begin{aligned} I_s &= i_R(t) + i_L(t) + i_C(t) \\ &= \frac{v(t)}{R} + \frac{1}{L} \int v(t) dt + C \frac{dv(t)}{dt} \quad \text{--- (1)} \end{aligned}$$

differentiate & using numerical value of RLC

$$0 = 16 \frac{dv(t)}{dt} + 16 v(t) + 4 \frac{d^2v(t)}{dt^2}$$

$$\Rightarrow \frac{d^2 v(t)}{dt^2} + 4 \frac{dv(t)}{dt} + 4 v(t) = 0 \quad \text{--- (2)}$$

$$\Rightarrow p^2 + 4p + 4 = 0$$

on solving $p = -2, -2$

$$\boxed{v(t) = K_1 e^{-2t} + K_2 t e^{-2t}} \rightarrow \text{general sol'n} \quad \text{--- (3)}$$

To obtain a particular sol'n for this problem will require knowledge of two initial conditions from ckt. $v(0^+)$ must equal zero, since Capacitor acts as a s.c at initial instant i.e.

$$\boxed{v(0^+) = 0} \quad \text{--- (4)}$$

In eqn (1) the I & II c.t. terms are zero at the instant of switching, b/c $v(0^+) = 0$ and there is no c.t. in the inductor at initial instant. Hence

$$\frac{dv}{dt}(0^+) = \frac{I_s}{C} = \frac{2}{4} = \frac{1}{2} \text{ V/sec.} \quad \text{--- (5)}$$

from eqn (2)

$$\frac{d^2 v}{dt^2}(0^+) + 4 \cdot \frac{1}{2} + 4 \cdot 0 = 0$$

$$\frac{d^2 v}{dt^2}(0^+) = -2 \text{ V/sec}^2 \quad \text{--- (6)}$$

above two initial conditions (4) & (5) are put into eqn (3)

$$K_1 = 0 \quad \& \quad -2K_1 + K_2 = \frac{1}{2}$$

$$\Rightarrow K_2 = \frac{1}{2}$$

So particular sol'n is

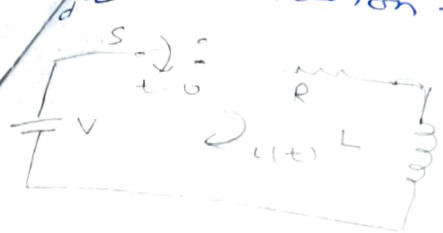
$$v(t) = \frac{1}{2} t e^{-2t} \text{ V.}$$



$$t=0 \rightarrow v(t) = 0$$

$$t=\frac{1}{2} \rightarrow v(t) =$$

Transient Response of Series RL ckt. having d.c. excitation \rightarrow at the instant when switch is closed



at the instant when switch is closed

$$i(t) = \frac{V}{R} (1 - e^{-R/Lt})$$

$$v_R(t) = i(t) R$$

$$v_L(t) = L \frac{di(t)}{dt} = V e^{-R/Lt}$$

at $t=0 \Rightarrow i(t)=0$
 at $t=\infty \Rightarrow i(t)=V/R$
 at $t = \frac{L}{R} = T \Rightarrow i(t) = \frac{V}{R} (1 - e^{-1}) = .632 V/R$

$$v_L(t) = V$$

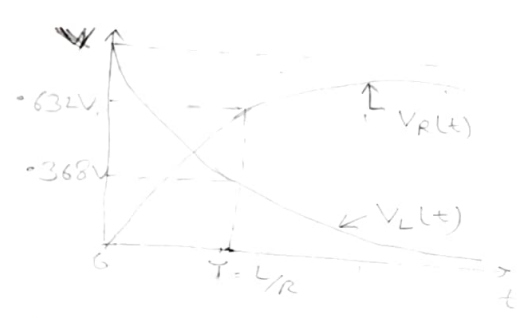
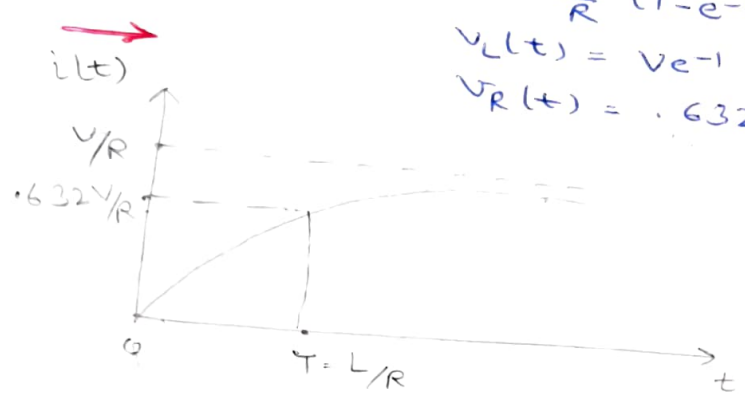
$$v_L(t) = 0$$

$$v_R(t) = 0$$

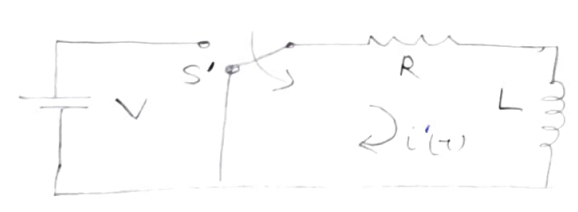
$$v_R(t) = V$$

$$v_L(t) = V e^{-1} = .368 V$$

$$v_R(t) = .632 V$$



when RL ckt. reaches at steady state ($t=\infty$) and suddenly V_g is withdrawn by opening the switch S and throwing it to S'



$$L \frac{di'(t)}{dt} + Ri'(t) = 0$$

$$i'(t) = K e^{-R/Lt}$$

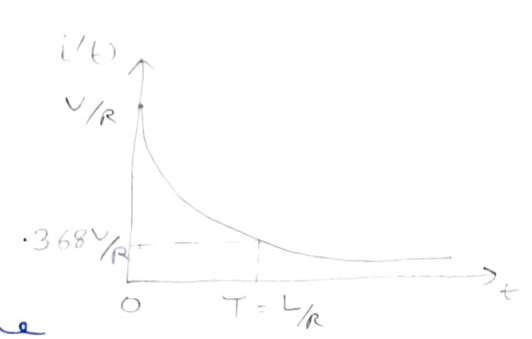
at $t=0^+$ inductor keep the S.S. of $i(0^+) = i(\infty) = V/R$

$$\frac{V}{R} = K e^0 \Rightarrow K' = \frac{V}{R}$$

$$i'(t) = \frac{V}{R} e^{-R/Lt}$$

$$v_R'(t) = i'(t) R = V e^{-R/Lt}$$

$$v_L'(t) = L \frac{di'(t)}{dt} = -V e^{-R/Lt}$$

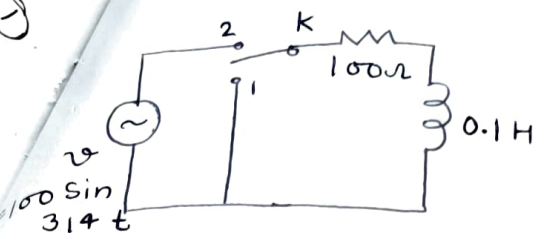


$\rightarrow T = L/R$ is known as the time constant of the circuit

It is defined as the time taken for the current to reach 63% of its value final value. Thus it is a measure of rapidity with which steady state is reached

0.5
x
8

①



find the current at $t > 0$ if a.c v.g. is applied when switch K is moved to 2 from 1 at $t = 0$.

Assume a steady state current of 1 A in R-L circuit when the switch was at position 1.

Sol. at $t = 0^-$ $i(0^-) = 1 \text{ A}$

also $i(0^-) = i(0^+) = 1$

$$Z = R + jX_L = 100 + j(2\pi \times 50 \times 0.1) = 104.8 \angle 17.47^\circ \Omega$$

by KVL in R-L circuit

$$v = Ri + L \frac{di}{dt}$$

$$100 \sin 314t = 100i + 0.1 \frac{di}{dt}$$

$$\frac{di}{dt} + 1000i = 1000 \sin 314t$$

$$(p + 10^3)i = 10^3 \sin 314t$$

$$i_c = Ke^{-R/Lt} = Ke^{-\frac{1000}{0.1}t}$$

$$i_p = \frac{V_m}{Z} \sin(\omega t + \phi - \tan^{-1} \frac{\omega L}{R})$$

$$= \frac{100\sqrt{2}}{104.8} \sin(314t - 17.47^\circ) \quad [\because \phi = 0^\circ]$$

$$= 1.345 \sin(314t - 0.304)$$

$$i = i_c + i_p$$

$$= Ke^{-R/Lt} + 1.345 \sin(314t - 0.304)$$

$$\text{at } t = 0^+ \quad i(0^+) = 1$$

$$1 = K + 1.345 \sin(-0.304)$$

$$1 = K + (-0.3)$$

$$K = 1.3$$

$$i = 1.3 e^{-1000t} + 1.345 \sin(314t - 0.304)$$