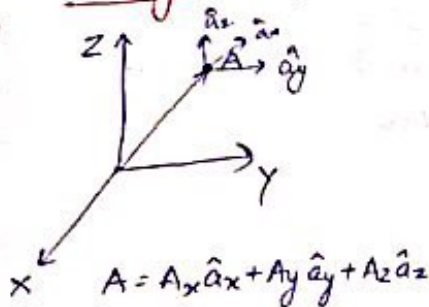


EMFT (unit-1) Coordinate System

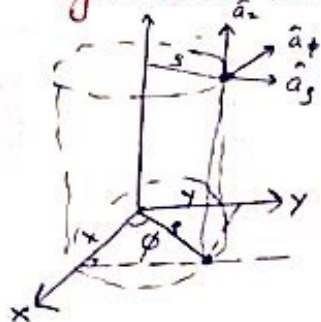
Rectangular (x, y, z)



$$A = A_x \hat{a}_x + A_y \hat{a}_y + A_z \hat{a}_z$$

$$\begin{cases} -\infty < x < \infty \\ -\infty < y < \infty \\ -\infty < z < \infty \end{cases}$$

Cylindrical (s, φ, z)



Spec - Range of 3 coordinates in cylindrical coordinate system
(2.5 m)
(2.08)

$$\begin{cases} 0 \leq s < \infty \\ 0 \leq \phi < 2\pi \\ -\infty < z < \infty \end{cases}$$

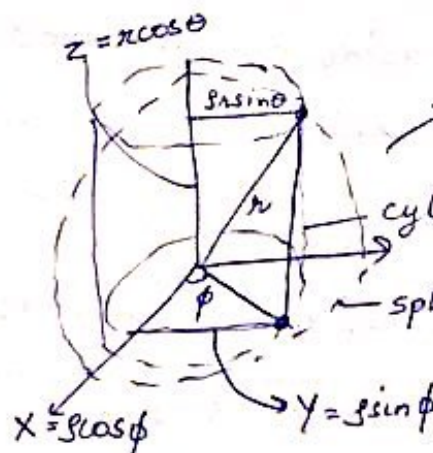
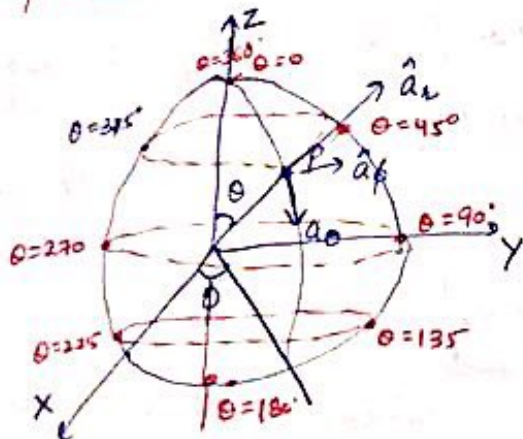
$$\begin{aligned} x &= s \cos \phi \\ y &= s \sin \phi \\ z &= z \end{aligned}$$

$$\begin{aligned} s &= \sqrt{x^2 + y^2} \\ \phi &= \tan^{-1} \frac{y}{x} \\ z &= z \end{aligned}$$

$$\begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} = \begin{bmatrix} \cos \phi & -\sin \phi & 0 \\ \sin \phi & \cos \phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} A_s \\ A_\phi \\ A_z \end{bmatrix}$$

For remembering
X comes before Y
and Y comes before Z
So X = s cos φ
Y = s sin φ

Spherical coordinate (r, θ, φ)



$$\begin{aligned} r &= \sqrt{s^2 + z^2} \\ &= \sqrt{x^2 + y^2 + z^2} \\ \theta &= \tan^{-1} \frac{s}{z} \\ \theta &= \tan^{-1} \frac{\sqrt{x^2 + y^2}}{z} \\ \phi &= \tan^{-1} \frac{y}{x} \end{aligned}$$

$$s = r \sin \theta$$

$$\begin{cases} 0 \leq r < \infty \\ 0 \leq \theta < \pi \\ 0 \leq \phi < 2\pi \end{cases}$$

$$\begin{aligned} x &= s \cos \phi = r \sin \theta \cos \phi \\ y &= s \sin \phi = r \sin \theta \sin \phi \\ z &= r \cos \theta \end{aligned}$$

$$\begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} = \begin{bmatrix} \sin \theta \cos \phi & \cos \theta \cos \phi & -\sin \phi \\ \sin \theta \sin \phi & \cos \theta \sin \phi & \cos \phi \\ r \cos \theta & -\sin \theta & 0 \end{bmatrix} \begin{bmatrix} A_r \\ A_\theta \\ A_\phi \end{bmatrix}$$

As angle 45° and 315° form the same cone in sphere,
θ = 45° and 225° form the same hemisphere &
θ = 135° & 225° form same cone. Hence 0 ≤ θ < π

Que: Transform the vector $A = 2\hat{a}_x + 3\hat{a}_\phi + 4\hat{a}_z$ into cartesian coordinates (March 2020) (2)

Solⁿ: Since the vector $A = 2\hat{a}_x + 3\hat{a}_\phi + 4\hat{a}_z$ is a (r, ϕ, z) i.e. cylindrical coordinate vector.

$$\begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} = \begin{bmatrix} \cos \phi & -\sin \phi & 0 \\ \sin \phi & \cos \phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} \Rightarrow \begin{aligned} A_x &= 2\cos \phi - 3\sin \phi \\ A_y &= 2\sin \phi + 3\cos \phi \\ A_z &= 4 \end{aligned}$$

We know $x = r \cos \phi$ and $y = r \sin \phi$

$$\text{So, } \cos \phi = \frac{x}{\sqrt{x^2+y^2}} \text{ and } \sin \phi = \frac{y}{\sqrt{x^2+y^2}}$$

$$A_x = 2 \cdot \frac{x}{\sqrt{x^2+y^2}} - 3 \cdot \frac{y}{\sqrt{x^2+y^2}} \hat{a}_x, A_y = \frac{2y}{\sqrt{x^2+y^2}} + \frac{3x}{\sqrt{x^2+y^2}} \hat{a}_y, A_z = 4\hat{a}_z$$

$$\boxed{A = \frac{2x-3y}{\sqrt{x^2+y^2}} \hat{a}_x + \frac{2y+3x}{\sqrt{x^2+y^2}} \hat{a}_y + 4\hat{a}_z}$$

Que: Transform the vector $A = y\hat{a}_x + x\hat{a}_y + \frac{x^2}{\sqrt{x^2+y^2}}\hat{a}_z$ into cylindrical coordinates (2019 session)

$$\text{Solⁿ: } \begin{bmatrix} A_r \\ A_\phi \\ A_z \end{bmatrix} = \begin{bmatrix} \cos \phi & \sin \phi & 0 \\ -\sin \phi & \cos \phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} \Rightarrow \begin{bmatrix} A_r \\ A_\phi \\ A_z \end{bmatrix} = \begin{bmatrix} \cos \phi & \sin \phi & 0 \\ -\sin \phi & \cos \phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} y \\ x \\ \frac{x^2}{\sqrt{x^2+y^2}} \end{bmatrix}$$

$$A_r = y \cos \phi + x \sin \phi = r \sin \phi \cos \phi + r \cos \phi \sin \phi = 2r \sin \phi \cos \phi = r \sin 2\phi$$

$$A_\phi = -y \sin \phi + x \cos \phi = -r \sin \phi \sin \phi + r \cos \phi \cos \phi = r(\cos^2 \phi - \sin^2 \phi) = r \cos 2\phi$$

$$A_z = \frac{x^2}{\sqrt{x^2+y^2}} = \frac{r^2 \cos^2 \phi}{r} = r \cos^2 \phi$$

$$\boxed{A(r, \phi, z) = r \sin 2\phi \hat{a}_r + r \cos 2\phi \hat{a}_\phi + r \cos^2 \phi \hat{a}_z}$$

$$\begin{aligned} x &= r \cos \phi \\ y &= r \sin \phi \\ z &= z \\ \cos \phi &= \frac{x}{\sqrt{x^2+y^2}} \\ \sin \phi &= \frac{y}{\sqrt{x^2+y^2}} \end{aligned}$$

Q: Convert the point $P(1, 3, 5)$ from Cartesian to cylindrical & spherical coordinate geometry (3 Marks, 2019) (end term)

Solⁿ: In cartesian $P(1, 3, 5) \Rightarrow x=1, y=3 \text{ \& } z=5$

For cylindrical coordinate $r = \sqrt{x^2+y^2} = \sqrt{1+9} = \sqrt{10} = 3.16$

$$\phi = \tan^{-1} \frac{y}{x} = \tan^{-1} \frac{3}{1} = 71.56^\circ$$

For spherical geometry $\rho = \sqrt{r^2+z^2} = \sqrt{10+25} = \sqrt{35} = 5.91$

$$\theta = \tan^{-1} \frac{\sqrt{x^2+y^2}}{z} = \tan^{-1} \frac{\sqrt{10}}{5} = 32.29^\circ$$

$$P(1, 3, 5) = P(3.16, 71.56^\circ, 5) = P(5.91, 32.29^\circ, 71.56^\circ)$$

Q:- Transform the vector $A = y\hat{a}_x - x\hat{a}_y + z\hat{a}_z$ into cylindrical coordinate. (End Term, 2019, 6 Marks)

Solⁿ:
$$\begin{bmatrix} A_r \\ A_\phi \\ A_z \end{bmatrix} = \begin{bmatrix} \cos\phi & \sin\phi & 0 \\ -\sin\phi & \cos\phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} y \\ -x \\ z \end{bmatrix}$$

$y = \rho \sin\phi$
 $x = \rho \cos\phi$

$A_r = (\cos\phi y - x \sin\phi)\hat{a}_r = (\rho \sin\phi \cos\phi - \rho \cos\phi \sin\phi)\hat{a}_r = 0$

$A_\phi = [-y \sin\phi + \cos\phi(-x)]\hat{a}_\phi = (-\rho \sin^2\phi - \rho \cos^2\phi)\hat{a}_\phi = -\rho\hat{a}_\phi$

$A_z = z\hat{a}_z$

$A(\rho, \phi, z) = -\rho\hat{a}_\phi + z\hat{a}_z$

(end term 2018)

Q:- Transform the vector $A = \hat{a}_\theta + \hat{a}_\phi$ to cartesian coordinate system (6.5).

Solⁿ: Since the vector has θ and ϕ component, it is in spherical coordinate geometry. and in end term (2017) (6.5)

Solⁿ:
$$\begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} = \begin{bmatrix} \sin\theta \cos\phi & \cos\theta \cos\phi & -\sin\phi \\ \sin\theta \sin\phi & \cos\theta \sin\phi & \cos\phi \\ \cos\theta & -\sin\theta & 0 \end{bmatrix} \begin{bmatrix} A_r=0 \\ A_\theta=1 \\ A_\phi=1 \end{bmatrix}$$

$A_x = [\cos\theta \cos\phi - \sin\phi]\hat{a}_x =$

$A_y = [\cos\theta \sin\phi + \cos\theta]\hat{a}_y$

$A_z = [-\sin\theta]\hat{a}_z$

We know $z = r \cos\theta \Rightarrow \cos\theta = \frac{z}{r}$

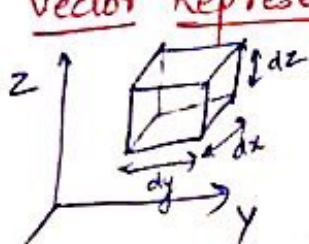
$= \frac{z}{\sqrt{x^2+y^2+z^2}}$

$\cos\phi = \frac{x}{\rho} = \frac{x}{\sqrt{x^2+y^2}}$, $\sin\theta = \frac{z}{\sqrt{x^2+y^2+z^2}}$
 $\sin\phi = \frac{y}{\rho} = \frac{y}{\sqrt{x^2+y^2}}$

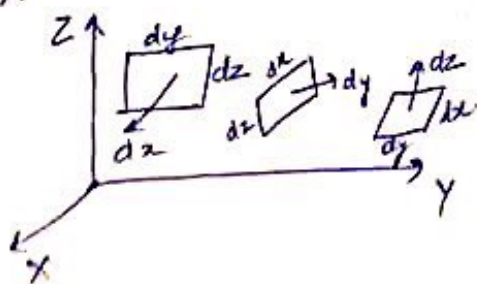
$$A = \left(\frac{z}{\sqrt{x^2+y^2+z^2}} \cdot \frac{x}{\sqrt{x^2+y^2}} - \frac{y}{\sqrt{x^2+y^2}} \right) \hat{a}_x + \left(\frac{z}{\sqrt{x^2+y^2+z^2}} \cdot \frac{y}{\sqrt{x^2+y^2}} + \frac{z}{\sqrt{x^2+y^2+z^2}} \right) \hat{a}_y - \frac{\sqrt{x^2+y^2}}{\sqrt{x^2+y^2+z^2}} \hat{a}_z$$

Q:- Determine the unit vector normal to the surface $xyz = 1$ at $(1, 1, 1)$. (end term 2018) (6M)

Vector Representation of Surfaces



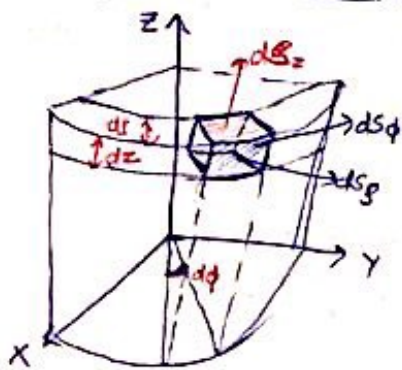
Differential displacement $\Rightarrow dl = dx\hat{a}_x + dy\hat{a}_y + dz\hat{a}_z$



Differential surface $ds = dydz\hat{a}_x$ or $dx dy\hat{a}_z$ or $dx dz\hat{a}_y$

Differential volume is given by $dV = dx dy dz$

In Cylindrical Coordinate Geometry

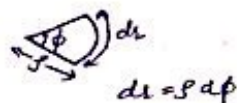


Differential displacement

$$dl = dr \hat{a}_r + r d\phi \hat{a}_\phi + dz \hat{a}_z$$

Differential normal surface

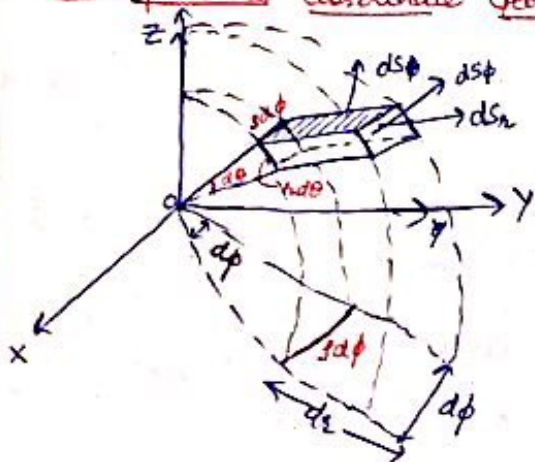
$$ds = r d\phi dz \hat{a}_r \quad \text{or} \quad dr dz \hat{a}_\phi \quad \text{or} \quad r dr d\phi \hat{a}_z$$



Differential volume

$$dV = r dr d\phi dz$$

In Spherical Coordinate Geometry



$$r = \rho \sin \theta$$

Differential displacement

$$dl = dr \hat{a}_r + r d\theta \hat{a}_\theta + r \sin \theta d\phi \hat{a}_\phi$$

Differential Surface Area

$$ds = r^2 \sin \theta d\theta d\phi \hat{a}_r \quad \text{or} \quad r \sin \theta dr d\phi \hat{a}_\theta \quad \text{or} \quad r dr d\theta \hat{a}_\phi$$

Differential volume $dV = r^2 \sin \theta dr d\theta d\phi$

Vector Analysis

Vector differential operator ∇ is defined as $\nabla = \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z}$. ∇ has direction but no magnitude but applies it to some vector or scalar.

∇ operator corresponding to each coordinate

Cartesian: $\nabla = \frac{\partial}{\partial x} \hat{a}_x + \frac{\partial}{\partial y} \hat{a}_y + \frac{\partial}{\partial z} \hat{a}_z$

Cylindrical: $\nabla = \frac{\partial}{\partial r} \hat{a}_r + \frac{1}{r} \frac{\partial}{\partial \phi} \hat{a}_\phi + \frac{\partial}{\partial z} \hat{a}_z$

Spherical: $\nabla = \frac{\partial}{\partial r} \hat{a}_r + \frac{1}{r} \frac{\partial}{\partial \theta} \hat{a}_\theta + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \hat{a}_\phi$

∇ scalar \rightarrow vector (gradient)
 $\nabla \cdot$ vector \rightarrow scalar (divergence)
 $\nabla \times$ vector \rightarrow vector (curl)

Gradient:- It represents the rate of change.

Cartesian: $\nabla V = \frac{\partial V}{\partial x} \hat{a}_x + \frac{\partial V}{\partial y} \hat{a}_y + \frac{\partial V}{\partial z} \hat{a}_z$

Cylindrical: $\nabla V = \frac{\partial V}{\partial r} \hat{a}_r + \frac{1}{r} \frac{\partial V}{\partial \phi} \hat{a}_\phi + \frac{\partial V}{\partial z} \hat{a}_z$

Spherical: $\nabla V = \frac{\partial V}{\partial r} \hat{a}_r + \frac{1}{r} \frac{\partial V}{\partial \theta} \hat{a}_\theta + \frac{1}{r \sin \theta} \frac{\partial V}{\partial \phi} \hat{a}_\phi$

$\rightarrow \nabla V$ points in the direction of maximum rate of change in V
 $\rightarrow \nabla V$ is normal to constant value surface at a given point.

(Q in 2018 (2.5M))

Divergence: It gives the rate per unit volume at which the physical entity is issuing from that point.

→ It is a measure of how much a field diverges at a given point

Cartesian: $\nabla \cdot \vec{V} = \frac{\partial V_x}{\partial x} + \frac{\partial V_y}{\partial y} + \frac{\partial V_z}{\partial z}$

Cylindrical: $\nabla \cdot \vec{V} = \frac{1}{r} \frac{\partial}{\partial r} (r V_r) + \frac{1}{r} \frac{\partial V_\phi}{\partial \phi} + \frac{\partial V_z}{\partial z}$

Spherical: $\nabla \cdot \vec{V} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 V_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta V_\theta) + \frac{1}{r \sin \theta} \frac{\partial V_\phi}{\partial \phi}$

Divergence Theorem: - Total outward flux through any closed surface of a vector is equal to volume integral of divergence of that vector.

$$\oint_S \vec{A} \cdot d\vec{s} = \int_V \nabla \cdot \vec{A} dV$$

A vector is said to be divergence less or solenoid if $\nabla \cdot \vec{A} = 0$

Curl: It is a measure of how much a field curl or rotates around a point.

→ It is a measure of angular velocity of each point of the vector field.

Cartesian:

$$\nabla \times \vec{V} = \begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ V_x & V_y & V_z \end{vmatrix}$$

Cylindrical

$$\nabla \times \vec{V} = \frac{1}{r} \begin{vmatrix} \hat{a}_r & r \hat{a}_\phi & \hat{a}_z \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ V_r & r V_\phi & V_z \end{vmatrix}$$

Spherical

$$\nabla \times \vec{V} = \frac{1}{r \sin \theta} \begin{vmatrix} \hat{a}_r & r \hat{a}_\theta & r \sin \theta \hat{a}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ V_r & r V_\theta & r \sin \theta V_\phi \end{vmatrix}$$

Stokes Theorem: Circulation of a vector in closed path is equal to surface integral of curl of that vector bounded by that closed loop.

$$\oint_C \vec{A} \cdot d\vec{l} = \iint_S (\nabla \times \vec{A}) \cdot d\vec{s}$$

A vector is said to be conservative or irrotational if $\nabla \times \vec{A} = 0$

Second Derivative

Gradient (vector)

Divergence

Scalar Laplacian operator ($\nabla^2 V$)

Curl

$\nabla \times \vec{V} = 0$

Divergence (scalar)

Gradient

∇

Curl (vector)

Divergence ($\nabla \cdot \vec{V} = 0$)

Curl

vector Laplacian operator

Scalar Laplacian

Cartesian: $\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2}$

Cylindrical: $\nabla^2 V = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial V}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 V}{\partial \phi^2} + \frac{\partial^2 V}{\partial z^2}$

Spherical: $\nabla^2 V = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial V}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial V}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 V}{\partial \phi^2}$

Vector Laplacian
 $\nabla^2 \vec{V} = \nabla(\nabla \cdot \vec{V}) - \nabla \times (\nabla \times \vec{V})$

Que:- Determine the unit vector normal to the surface $S(x,y,z) = x^2 + y^2 - z$ at (1,3,0) (ET, 2018) (6M) (6)

Soln:- Unit vector normal to the surface is given by Gradient

$$\begin{aligned}\nabla S &= \frac{\partial S}{\partial x} \hat{a}_x + \frac{\partial S}{\partial y} \hat{a}_y + \frac{\partial S}{\partial z} \hat{a}_z \\ &= \frac{\partial (x^2 + y^2 - z)}{\partial x} \hat{a}_x + \frac{\partial (x^2 + y^2 - z)}{\partial y} \hat{a}_y + \frac{\partial (x^2 + y^2 - z)}{\partial z} \hat{a}_z \\ &= 2x \hat{a}_x + 2y \hat{a}_y + 2z \hat{a}_z\end{aligned}$$

$$\nabla S \text{ at } (1,3,0)$$

$$= 2\hat{a}_x + 6\hat{a}_y$$

$$\boxed{\nabla S = 2\hat{a}_x + 6\hat{a}_y}$$

Que:- Write Divergence & Stokes theorem in mathematical form (ET 2018, 2.5M)

Que:- Explain the condition when a field is solenoidal and when irrotational (ET, 2019, 2.5M)

Soln:- Define divergence & curl here, then

if divergence = 0 \rightarrow Field is solenoidal

if curl = 0 \rightarrow Field is irrotational

Que:- Give a vector function $A = (x + C_1 z) \hat{a}_x + (C_2 x + 3z) \hat{a}_y + (x + C_3 y + C_4 z) \hat{a}_z$ (ET, 2017, 6M)

a) Calculate C_1, C_2 and C_3 if A is irrotational

b) Determine the constant C_4 if A is solenoidal also

Solution:- To determine if its irrotational $\nabla \times A = 0$

$$\nabla \times A = \begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x + C_1 z & C_2 x + 3z & x + C_3 y + C_4 z \end{vmatrix} = 0$$

$$= \left[\frac{\partial}{\partial y} (x + C_3 y + C_4 z) - \frac{\partial}{\partial z} (C_2 x + 3z) \right] \hat{a}_x - \left[\frac{\partial}{\partial x} (x + C_3 y + C_4 z) - \frac{\partial}{\partial z} (x + C_1 z) \right] \hat{a}_y + \left[\frac{\partial}{\partial x} (C_2 x + 3z) - \frac{\partial}{\partial y} (x + C_1 z) \right] \hat{a}_z$$

$$= (C_3 - 3) \hat{a}_x + (C_1 - 1) \hat{a}_y + (C_2 - 0) \hat{a}_z = 0 \Rightarrow \begin{cases} C_3 = 0 \\ C_2 = 0 \\ C_1 = 1 \end{cases}$$

For solenoidal $\nabla \cdot A = 0$

$$\nabla \cdot A = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z} = \frac{\partial}{\partial x} (x + C_1 z) + \frac{\partial}{\partial y} (C_2 x + 3z) + \frac{\partial}{\partial z} (x + C_3 y + C_4 z) = 0$$

$$1 + 0 + C_4 = 0 \Rightarrow \boxed{C_4 = -1}$$

Que:- If $F = \text{grad} [x^2 + y^2 + z^2 - 3xyz]$ Find curl F ? (ET, 2017, 2.5M)

$$F = \text{grad} [x^2 + y^2 + z^2 - 3xyz]$$

$$\nabla F = \frac{\partial F}{\partial x} \hat{a}_x + \frac{\partial F}{\partial y} \hat{a}_y + \frac{\partial F}{\partial z} \hat{a}_z$$

$$= \frac{\partial}{\partial x} [x^2 + y^2 + z^2 - 3xyz] \hat{a}_x + \frac{\partial}{\partial y} [x^2 + y^2 + z^2 - 3xyz] \hat{a}_y + \frac{\partial}{\partial z} [x^2 + y^2 + z^2 - 3xyz] \hat{a}_z$$

$$= (2x - 3yz) \hat{a}_x + (2y - 3xz) \hat{a}_y + (2z - 3xy) \hat{a}_z$$

Curl of $F = \nabla \times F$

$$\begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2x - 3yz & 2y - 3xz & 2z - 3xy \end{vmatrix} = \hat{a}_x \left[\frac{\partial}{\partial y} (2z - 3xy) - \frac{\partial}{\partial z} (2y - 3xz) \right] + \hat{a}_y \left[\frac{\partial}{\partial x} (2z - 3xy) - \frac{\partial}{\partial z} (2x - 3yz) \right] + \hat{a}_z \left[\frac{\partial}{\partial x} (2y - 3xz) - \frac{\partial}{\partial y} (2x - 3xy) \right]$$

$$= (-3x + 3x) \hat{a}_x + (-3y + 3y) \hat{a}_y + (-3z + 3z) \hat{a}_z$$

$$= 0$$

Que:- Find the Laplacian of the scalar vector field $V = yz \sin \phi + z^2 \cos^2 \phi + y^2$ [ET, 2017, 6M] (7)

Soln: Laplacian \rightarrow Divergence of gradient

$$\begin{aligned}\nabla^2 V &= \frac{1}{x} \frac{\partial}{\partial x} \left(x \frac{\partial V}{\partial x} \right) + \frac{1}{y} \frac{\partial}{\partial y} \left(y \frac{\partial V}{\partial y} \right) + \frac{1}{z} \frac{\partial}{\partial z} \left(z \frac{\partial V}{\partial z} \right) \\&= \frac{1}{x} \frac{\partial}{\partial x} \left(y \frac{\partial}{\partial x} (yz \sin \phi + z^2 \cos^2 \phi + y^2) \right) + \frac{1}{y} \frac{\partial}{\partial y} \left(z \frac{\partial}{\partial y} (yz \sin \phi + z^2 \cos^2 \phi + y^2) \right) + \frac{1}{z} \frac{\partial}{\partial z} \left(z \frac{\partial}{\partial z} (yz \sin \phi + z^2 \cos^2 \phi + y^2) \right) \\&= \frac{1}{x} \frac{\partial}{\partial x} (y(z \sin \phi + 2z)) + \frac{1}{y} \frac{\partial}{\partial y} (z(z \cos \phi + z \cdot 2 \cdot \sin \phi)) + \frac{1}{z} \frac{\partial}{\partial z} (y \sin \phi + 2z \cos^2 \phi) \\&= \frac{1}{x} [z \sin \phi + 4y] + \frac{1}{y} [-yz \sin \phi - 2z^2 \cos \phi] + 2 \cos^2 \phi\end{aligned}$$

$$\boxed{\nabla^2 V = \frac{1}{x} [z \sin \phi + 4y] + \frac{1}{y} [-yz \sin \phi - 2z^2 \cos \phi] + 2 \cos^2 \phi}$$

Electrostatics

Coulomb's Law $\rightarrow F = \frac{k q_1 q_2}{R^2} \hat{a}_r$ or $F = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{R^2} \hat{a}_r$

where ϵ_0 = permittivity of free space

$\epsilon_0 = 8.854 \times 10^{-12}$ or $\frac{10^{-9}}{36\pi}$ F/m or $k = 9 \times 10^9$ N/m²

Electric Field: Force per unit charge when placed in an electric field.

Thus $E = \lim_{q \rightarrow 0} \frac{F}{q}$ or $E = \frac{q_1}{4\pi\epsilon_0 R^2} \hat{a}_r$

Continuous Charge Distribution:

Line charge density ρ_L $Q = \int \rho_L dl$

Surface charge density ρ_S $Q = \int \rho_S ds$

Volume charge density ρ_V $Q = \int \rho_V dv$

Electric Field Intensity

1. Due to line charge, $\vec{E} = \frac{\rho_L}{2\pi\epsilon_0 r} \hat{a}_r$

2. Due to surface charge $\vec{E} = \frac{\rho_S}{2\epsilon_0} \hat{a}_n$

3. Due to volume charge $\vec{E} = \frac{\rho}{4\pi\epsilon_0 z^2} \hat{a}_z$

Electric Flux: It is a measure of electric field lines passing through any surface $\psi = \int \vec{E} \cdot d\vec{s}$

and electric flux density is given by $\vec{D} = \epsilon_0 \vec{E}$

\hookrightarrow also called electric displacement.

Gauss Law: The total electric flux passing through any closed surface is equal to charge enclosed by that surface. (ET 2018, 2.5M)

$\psi = \oint \vec{E} \cdot d\vec{s} = \frac{Q_{\text{enclosed}}}{\epsilon_0}$

$\oint \epsilon_0 \vec{E} \cdot d\vec{s} = Q_{\text{enclosed}}$

$\oint \vec{D} \cdot d\vec{s} = Q_{\text{enclosed}}$

Gaussian surface \vec{E} is \perp to the surface and moving outward from the surface.

2. \vec{E} is equal at all points on the surface.

If charge is distributed over volume V which contains an surface ds

$$Q = \int \rho_v dv$$

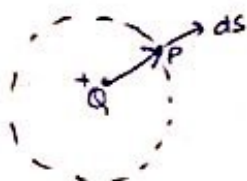
$$\oint_S \vec{D} \cdot d\vec{s} = Q_{\text{enclosed}} = \int \rho_v dv$$

$$\oint_S \vec{D} \cdot d\vec{s} = \int \rho_v dv \quad \text{Maxwell's first equation}$$

Applying divergence theorem $\rightarrow \oint_S \vec{D} \cdot d\vec{s} = \int \nabla \cdot \vec{D} dv$

$$\Rightarrow \boxed{\nabla \cdot \vec{D} = \rho_v} \rightarrow \text{Maxwell's first equation in differential form.}$$

\vec{E} due to point charge



$$\oint_S \vec{D} \cdot d\vec{s} = Q_{\text{enclosed}}$$

$$\oint_S \vec{D} \cdot d\vec{s} = Q_{\text{enclosed}}$$

$$\vec{D} \cdot 4\pi R^2 \hat{a}_r = Q$$

$$\vec{D} = \frac{Q}{4\pi R^2} \hat{a}_r$$

$$\epsilon_0 \vec{E} = \frac{Q}{4\pi R^2} \hat{a}_r$$

$$\boxed{\vec{E} = \frac{Q}{4\pi\epsilon_0 R^2} \hat{a}_r}$$

\vec{E} due to line charge



$$Q = \int \rho_L dl$$

$$\oint_S \vec{D} \cdot d\vec{s} = US + LS + \text{Round surface}$$

For US & LS angle b/w \vec{D} & $d\vec{s}$ is 90° so $\vec{D} \cdot d\vec{s} = 0$

$$\oint_{\text{round}} \vec{D} \cdot d\vec{s} = \oint \vec{D} \cdot d\vec{s} = \rho_L \cdot L$$

$$\vec{D} \oint ds = \rho_L L$$

$$\epsilon_0 \vec{E} \cdot 2\pi R L = \rho_L L$$

$$\boxed{\vec{E} = \frac{\rho_L}{2\pi\epsilon_0 R} \hat{a}_r}$$

Electric Potential \rightarrow It is a scalar quantity and is used to defined electric field.

Work done in moving a charge is

$$dW = -\vec{F} \cdot d\vec{l}$$

$$= -\vec{E} \cdot q \cdot d\vec{l}$$

$$\text{or } \boxed{W = -q \int_A^B \vec{E} \cdot d\vec{l}}$$

-ve sign indicates that the work is done by an external agent.

$$\boxed{V = -\int \vec{E} \cdot d\vec{l}}$$

$$\text{or } \boxed{\vec{E} = -\nabla V}$$

$$V_{AB} = \frac{W}{Q} = -\int_A^B \vec{E} \cdot d\vec{l} = -\int_A^B \frac{Q}{4\pi\epsilon_0 r^2} \hat{a}_r \cdot d\vec{l} = -\int_{r_A}^{r_B} \frac{Q}{4\pi\epsilon_0 r^2} dr = \frac{Q}{4\pi\epsilon_0} \left[\frac{1}{r_B} - \frac{1}{r_A} \right]$$

potential energy per unit charge

$$\boxed{V_{AB} = V_B - V_A}$$

$$V_{AB} = -V_{BA}$$

$$V_{AB} = -\int_A^B \vec{E} \cdot d\vec{l}$$

$$-V_{AB} = -\int_A^B \vec{E} \cdot d\vec{l} = -\int_B^A \vec{E} \cdot d\vec{l} = V_{BA}$$

$$-V_{AB} = V_{BA}$$

$$V_{AB} + V_{BA} = 0 \Rightarrow -\int_A^B \vec{E} \cdot d\vec{l} - \int_B^A \vec{E} \cdot d\vec{l} = 0 \Rightarrow \boxed{\oint \vec{E} \cdot d\vec{l} = 0} \quad \text{Maxwell's 2nd equation}$$

It states that the net work done in moving a point charge in a closed loop in presence of \vec{E} is zero.

Apply Stokes's theorem $\oint \vec{E} \cdot d\vec{l} = \int (\nabla \times \vec{E}) \cdot d\vec{s}$

$$\therefore \oint \vec{E} \cdot d\vec{l} = 0$$

$$\boxed{\nabla \times \vec{E} = 0}$$

Q: Given that the field $E = \frac{100}{r^2} \hat{r}$ Volt/meter in cylindrical coordinate. Show that the work needed to move a point charge Q from any radial distance r to a point twice the radial distance is independent of r .

Solⁿ: $W = -Q \int_{r_1}^{r_2} \vec{E} \cdot d\vec{l}$ $dl = dr \hat{r}$

$$= -Q \int_{r_1}^{r_2} \frac{100}{r^2} \hat{r} \cdot dr \hat{r}$$

$$= -Q \int_{r_1}^{r_2} \frac{100}{r^2} dr = -100Q \left[\ln(r) \right]_{r_1}^{2r} = -100Q \left[\ln\left(\frac{2r}{r}\right) \right]$$

$$= -100Q \ln(2) \quad \ln(2) = 0.6931$$

$$\boxed{W = -69.31Q}$$

Q: Given that the field $V = \frac{10}{r^2} \sin\theta \cos\phi$. Find the electric flux density D at $(10, 0, 0)$ and work done in moving a charge of $100 \mu C$ from point $A(2, 60^\circ, 60^\circ)$ to $B(4, 30^\circ, 30^\circ)$.

Solⁿ: $D = \epsilon_0 E$
 and $E = -\nabla V$
 Since V is given in spherical coordinates

$$E = -\nabla V = -\left[\frac{\partial V}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial V}{\partial \theta} \hat{\theta} + \frac{1}{r \sin\theta} \frac{\partial V}{\partial \phi} \hat{\phi} \right]$$

$$= -\left[\frac{-20}{r^3} \sin\theta \cos\phi \hat{r} - \frac{10}{r^3} \cos\theta \cos\phi \hat{\theta} + \frac{10}{r^3} \sin\phi \hat{\phi} \right]$$

At $(10, 0, 0) \rightarrow D = \epsilon_0 E$

$$D = \epsilon_0 \left[\frac{20}{(10)^3} \sin 0 \cos 0 \hat{r} - \frac{10}{(10)^3} \cos 0 \cos 0 \hat{\theta} + \frac{10}{(10)^3} \sin 0 \hat{\phi} \right]$$

$$= \epsilon_0 \left[0 - 0 + \frac{1}{10^2} \hat{\phi} \right] = -\frac{8.854 \times 10^{-12}}{10^2} = -8.854 \times 10^{-14} \hat{\phi}$$

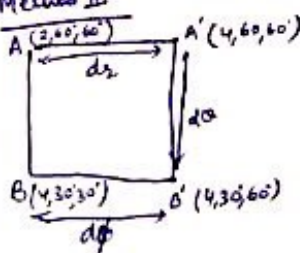
Work done in moving a charge of $100 \mu C$ from $A(2, 60^\circ, 60^\circ)$ to $B(4, 30^\circ, 30^\circ)$

Method I: $V_A = \frac{10}{r^2} \sin\theta \cos\phi = \frac{10}{4} \sin 60^\circ \cos 60^\circ = \frac{10}{4} \times \frac{\sqrt{3}}{2} \times \frac{1}{2} = \frac{10\sqrt{3}}{16}$

$V_B = \frac{10}{r^2} \sin\theta \cos\phi = \frac{10}{16} \cdot \frac{\sqrt{3}}{2} \cdot \frac{1}{2} = \frac{10\sqrt{3}}{64}$

$W = q(V_B - V_A) = 100 \times \left(\frac{10\sqrt{3}}{64} - \frac{10\sqrt{3}}{16} \right) = 100 \times \frac{10\sqrt{3}}{64} (1-4) = \boxed{-8.10 \mu J}$

Method II



$AA' = dr = dr \hat{r}$
 $AB' = d\theta = r d\theta \hat{\theta}$
 $BB' = d\phi = r \sin\theta d\phi \hat{\phi}$

$$W = -Q \int \vec{E} \cdot d\vec{l} = -Q \left[\int_{A'A} \vec{E} \cdot d\vec{l} + \int_{A'B'} \vec{E} \cdot d\vec{l} + \int_{B'B} \vec{E} \cdot d\vec{l} \right]$$

$$= -Q \left[\int_{r=2}^4 \frac{10}{r^3} \sin\theta \cos\phi dr + \int_{\theta=60}^{30} \frac{-10 \cos\theta \cos\phi}{r^3} r d\theta + \int_{\phi=60}^{30} \frac{10 \sin\phi}{r^3} r \sin\theta d\phi \right]$$

$$= -Q \left[\frac{10}{2} \sin\theta \cos\phi \left[\frac{-1}{2r^2} \right]_{r=2}^4 - \frac{10}{2} \left[\sin\theta \right]_{60}^{30} \cos\phi + \frac{10}{2} \sin\theta \left[-\cos\phi \right]_{60}^{30} \right]$$

$$= -Q \left[\frac{10\sqrt{3}}{2} \cdot \frac{1}{2} \left[\frac{-1}{16} - \frac{-1}{4} \right] - \frac{10}{2} \left[\sin 30^\circ - \sin 60^\circ \right] \cos 60^\circ + \frac{10}{2} \cdot \frac{1}{2} \left[\cos 60^\circ - \cos 30^\circ \right] \right]$$

$$= -Q \left[\frac{15\sqrt{3}}{32} - \frac{5}{32} + \frac{5\sqrt{3}}{32} - \frac{5\sqrt{3}}{32} + \frac{5}{32} \right]$$

$\frac{-W}{Q} = 0.810$

$$\boxed{W = -0.810 \times Q = -8.10 \mu J}$$

③

Que:- Define the terms Electric field intensity (E) and Electric flux density (D). Also give the relationship b/w E & D . (ET 2019, 2.5M)

Que: Potential is given by $V = 2(x+1)^2(y+2)^2(z+3)^2$ Volt in free space. At a point $P(2, -1, 4)$. Calculate (a) Potential at point P (b) Electric field intensity \vec{E} at point P (c) Electric flux density \vec{D} at point P (d) Volumetric charge density ρ_v at P (ET 2019, 11-8)

Solⁿ: $V = 2(x+1)^2(y+2)^2(z+3)^2$
 $P(2, -1, 4)$

1) $V = 2(2+1)^2(-1+2)^2(4+3)^2 = 2(3)^2(1)^2(7)^2 = 2 \times 9 \times 1 \times 49 = 882 \text{ V}$

2) $E = -\nabla V = -\left(\frac{\partial V}{\partial x} \hat{a}_x + \frac{\partial V}{\partial y} \hat{a}_y + \frac{\partial V}{\partial z} \hat{a}_z\right)$
 $= -4(x+1)(y+2)^2(z+3)^2 \hat{a}_x - 4(x+1)^2(y+2)(z+3)^2 \hat{a}_y - 4(x+1)^2(y+2)^2(z+3) \hat{a}_z$

At $P(2, -1, 4)$

$\vec{E} = 4(3)(1)^2(7)^2 \hat{a}_x - 4(3)^2(1)(7)^2 \hat{a}_y - 4(3)^2(1)^2(7) \hat{a}_z$

$\vec{E} = -588 \hat{a}_x - 1764 \hat{a}_y - 252 \hat{a}_z$

(iii) $D = \epsilon_0 \vec{E} = 8.854 \times 10^{-12} [-588 \hat{a}_x - 1764 \hat{a}_y - 252 \hat{a}_z]$
 $= -5.21 \hat{a}_x - 15.62 \hat{a}_y - 2.23 \hat{a}_z \text{ nC/m}^2$

(iv) $\rho_v = \nabla \cdot D = \epsilon_0 \left[\frac{\partial E_x}{\partial x} + \frac{\partial E_y}{\partial y} + \frac{\partial E_z}{\partial z} \right]$
 $= \epsilon_0 [-4(y+2)^2(z+3)^2 - 4(x+1)^2(z+3)^2 - 4(x+1)^2(y+2)^2]$
 $\rho_v = -17.67 \text{ nC/m}^3$

Electric field is usually determined using Coulomb's law or Gauss law when the charge distribution is known or using $E = -\nabla V$ when the potential distribution is known.

However in most practical situations, when neither the charge distribution nor the potential distribution is known but only electrostatic conditions (charge & potential) at some boundaries are known & it is desired to find \vec{E} and \vec{V} through the region. Such problems are tackled using Poisson, Laplace or method of images.

Poisson and Laplace Equation

From Gauss law $\nabla \cdot D = \rho_v \Rightarrow \epsilon_0 \nabla \cdot E = \rho_v$ (1)

$E = -\nabla V$ (2)

Put (2) in (1) $\nabla \cdot (\epsilon_0 (-\nabla V)) = \rho_v$

For homogeneous medium i.e. when ϵ is constant

$\epsilon \nabla^2 V = -\rho_v$ or $\nabla^2 V = -\frac{\rho_v}{\epsilon} \rightarrow$ Poisson equation

For a charge free region

$\nabla^2 V = 0$

\rightarrow Laplace Equation \rightarrow

Laplace eqⁿ is all different geometries is given on 2nd derivatives page.

(May 2017)

M-6.5

(May 2018) M-4.5

Uniqueness Theorem states that if a solution to a Laplace equation can be found that satisfies the boundary conditions, then the solution is unique i.e. it is the only solution regardless of the method used. (10)

Que: In cylindrical coordinate, two $\phi = \text{constant}$ planes are insulated along Z-axis. Find the expression for \vec{E} b/w the planes assuming a potential of 100V for $\phi = \alpha$ and zero at $\phi = 0$. (Sessional 2018)

Soln: Since the potential is constant with r & z , Laplace eqn is given by

$$\nabla^2 V = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial V}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 V}{\partial \phi^2} + \frac{\partial^2 V}{\partial z^2} = 0 \Rightarrow \frac{1}{r^2} \frac{\partial^2 V}{\partial \phi^2} = 0$$

Integrating $\frac{1}{r^2} \frac{\partial^2 V}{\partial \phi^2} = 0$

$$\frac{\partial^2 V}{\partial \phi^2} = 0 \quad \frac{\partial V}{\partial \phi} = A = \text{constant}$$

$$V = A\phi + B$$

Apply Boundary conditions

At $\phi = 0 \rightarrow A(0) + B = 0 \Rightarrow B = 0$

At $\phi = \alpha \quad A(\alpha) + B = 100 \Rightarrow A = \frac{100}{\alpha}$

$$\rightarrow V = \frac{100}{\alpha} \phi$$

$$\begin{aligned} \vec{E} = -\nabla V &= -\left[\frac{\partial V}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial V}{\partial \phi} \hat{\phi} + \frac{\partial V}{\partial z} \hat{z} \right] = -\left[\frac{1}{r} \frac{\partial V}{\partial \phi} \hat{\phi} + 0 + 0 \right] \\ &= -\frac{1}{r} \frac{\partial V}{\partial \phi} \hat{\phi} = -\frac{1}{r} \frac{\partial}{\partial \phi} \left[\frac{100}{\alpha} \phi \right] \hat{\phi} = -\frac{100}{r\alpha} \hat{\phi} \text{ V/m} \end{aligned}$$

$$|E| = \left| \frac{100}{r\alpha} \right|$$

Que: Two conducting cones ($\theta = \frac{\pi}{6}$ and $\theta = \frac{5\pi}{10}$) of infinite extent are separated by a very small gap at $r=0$. If V at $\theta = \frac{\pi}{10} = 0$ and V at $\theta = \frac{\pi}{6}$ is 50V. Find \vec{E} . (Sessional 2020)

Soln: The Laplacian eqn in spherical coordinates is

$$\nabla^2 V = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial V}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial V}{\partial \theta} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial^2 V}{\partial \phi^2} \text{ reduces to}$$

$$\nabla^2 V = 0 = \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial V}{\partial \theta} \right) = 0 \Rightarrow \frac{\partial}{\partial \theta} \left[\sin \theta \frac{\partial V}{\partial \theta} \right] = 0$$

Integration $\sin \theta \frac{\partial V}{\partial \theta} = A \quad \text{or} \quad \frac{\partial V}{\partial \theta} = \frac{A}{\sin \theta} \quad \text{--- (1)}$

Integrating $V = A \int \frac{1}{\sin \theta} d\theta = A \int \frac{1}{2 \sin \theta/2 \cos \theta/2} d\theta = A \int \frac{1}{2} \frac{\sec^2 \theta/2}{\tan \theta/2} d\theta$
 $= A \int \frac{d(\tan \theta/2)}{\tan \theta/2} = A \ln(\tan \theta/2) + B$

Apply Boundary conditions to determine A & B

$V(\theta = \theta_1) = 0 = A \ln(\tan \theta_1/2) + B \Rightarrow B = -A \ln(\tan \theta_1/2)$

At $\theta = \theta_2$, $V = 50$, $V = A \ln \tan \theta_2/2 - A \ln(\tan \theta_1/2)$

$$V = A \ln \left[\frac{\tan \theta_2/2}{\tan \theta_1/2} \right] \quad \text{--- (2)}$$

At $V(\theta=0_2) = V_0 = A \ln \left[\frac{\tan \theta_2/2}{\tan \theta_1/2} \right]$ or $A = \frac{V_0}{\ln \left[\frac{\tan \theta_2/2}{\tan \theta_1/2} \right]}$ (11)

Put A & B value in (2)

$$V = \frac{V_0 \ln \left[\frac{\tan \theta/2}{\tan \theta_1/2} \right]}{\ln \left[\frac{\tan \theta_2/2}{\tan \theta_1/2} \right]}$$

from eq (1)

$$E = -\nabla V = -\frac{1}{r} \frac{\partial V}{\partial \theta} \hat{a}_\theta = -\frac{A}{r \sin \theta} \hat{a}_\theta = \frac{-V_0}{r \sin \theta \ln \left[\frac{\tan \theta_2/2}{\tan \theta_1/2} \right]} \hat{a}_\theta$$

Putting value of $\theta_1 = \frac{\pi}{10}$, $\theta_2 = \frac{\pi}{6}$ and $V_0 = 50$

$$V = 50 \ln \left[\frac{\tan \theta/2}{\tan \pi/20} \right] = 95.1 \ln \left[\frac{\tan \theta/2}{0.1584} \right] \quad (3)$$

Comparing (2) & (3) $A = 95.1$

and $E = -\frac{95.1}{r \sin \theta} \hat{a}_\theta \text{ V/m}$

Ques: Derive the poisson eq? State the conditions when the equation becomes the Laplace equation. In spherical coordinate geometry $V=0$ at $r=0.2\text{m}$ and $V=200$ at $r=4\text{m}$ then calculate E and D assuming free space b/w the shells. (ET may 2018, 6.5M)

Ans:- Laplace eqⁿ spherical coordinate geometry

$$\nabla^2 V = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial V}{\partial r} \right) = 0 \quad (\text{since variation is only in } r)$$

$$\frac{\partial}{\partial r} \left(r^2 \frac{\partial V}{\partial r} \right) = 0 \rightarrow r^2 \frac{\partial V}{\partial r} = A \quad dV = \frac{A}{r^2} dr \quad V = -\frac{A}{r} + B$$

Applying Boundary conditions

$$V=0 \text{ at } r=0.2$$

$$0 = -\frac{A}{0.2} + B$$

$$-A + 0.2B = 0 \quad \boxed{A = 0.2B}$$

$$V=200 \text{ at } r=4$$

$$200 = -\frac{A}{4} + B$$

$$200 = -\frac{0.2B}{4} + B \Rightarrow \boxed{B = \frac{4000}{19} \text{ and } A = \frac{800}{19}}$$

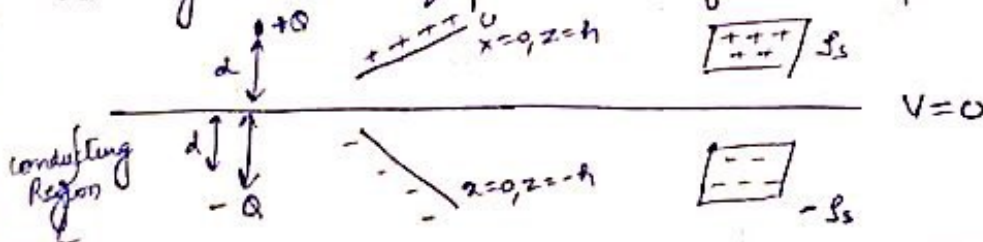
$$V = -\frac{800}{19r} + \frac{4000}{19}$$

$$E = -\nabla V = -\left(+\frac{800}{19r^2} \hat{a}_r \right) = -\frac{800}{19r^2} \hat{a}_r$$

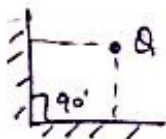
$$\vec{D} = -\epsilon_0 \cdot \frac{800}{19r^2} \hat{a}_r$$

Method of Images

If any charge configuration placed above infinite grounded perfect conducting plane then the charge is replaced by the charge configuration itself and its image and its equipotential surface in place of grounded plane.

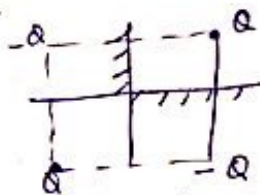


The number of images formed is $N = \frac{360^\circ}{\phi} - 1$
 where $\phi =$ angle b/w conducting planes.



$$\phi = 90^\circ$$

$$N = \frac{360^\circ}{90^\circ} - 1 = 3$$

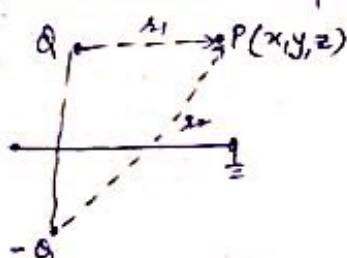


(12)

For applying method of images, two conditions must always be satisfied

- 1) The image charge(s) must be located in the conducting region \rightarrow to satisfy Poisson Equation
- 2) The image charge(s) must be located such that on the conducting surface(s) the potential is zero or constant. \rightarrow this condition ensures that boundary conditions are satisfied.

\vec{E} and V due to point charge placed above grounded conducting plane



$$\vec{E} = \frac{Q}{4\pi\epsilon_0} \frac{\hat{a}_1}{r_1^2} + \frac{-Q}{4\pi\epsilon_0} \frac{\hat{a}_2}{r_2^2}$$

$$= \frac{Q}{4\pi\epsilon_0} \frac{\vec{r}_1}{r_1^3} - \frac{Q}{4\pi\epsilon_0} \frac{\vec{r}_2}{r_2^3}$$

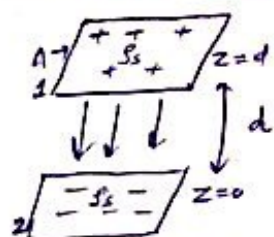
$$r_1 = x\hat{a}_x + y\hat{a}_y + (z-h)\hat{a}_z$$

$$|r_1| = \sqrt{x^2 + y^2 + (z-h)^2} \quad |r_2| = \sqrt{x^2 + y^2 + (z+h)^2}$$

$$V = \frac{Q}{4\pi\epsilon_0 r_1} - \frac{Q}{4\pi\epsilon_0 r_2} = \frac{Q}{4\pi\epsilon_0} \left[\frac{1}{r_1} - \frac{1}{r_2} \right]$$

Capacitance: When two conductors of equal and opposite charges are placed at a distance they exhibit capacitance.

Parallel Plate Capacitor



$$C = \frac{Q}{V_{21}}$$

$$Q = \int \vec{S}_s \cdot d\vec{s} = \vec{S}_s \cdot \vec{A}$$

$$V_{21} = -\int_z \vec{E} \cdot d\vec{l}$$

$$\vec{E} = \frac{\vec{S}_s}{\epsilon_0} (-\hat{a}_z) - \frac{\vec{S}_s}{\epsilon_0} (\hat{a}_z) = -\frac{\vec{S}_s}{\epsilon_0} \hat{a}_z = -\frac{Q}{A\epsilon_0} \hat{a}_z$$

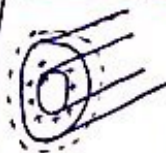
$$V_{21} = -\int_z \vec{E} \cdot d\vec{l} = -\int_z -\frac{Q}{A\epsilon_0} \hat{a}_z \cdot dz \hat{a}_z$$

$$= -\int_0^d -\frac{Q}{A\epsilon_0} dz = \frac{Q}{A\epsilon_0} [d-0] = \frac{Qd}{A\epsilon_0}$$

$$C = \frac{Q}{V_{21}} = \frac{Q}{\frac{Qd}{A\epsilon_0}} = \frac{A\epsilon_0}{d}$$

$$C = \frac{A\epsilon_0}{d}$$

Coaxial / Cylindrical Capacitor



$$V_{21} = -\int \vec{E} \cdot d\vec{l} \quad \oint \vec{E} \cdot d\vec{s} = \frac{Q_{\text{enclosed}}}{\epsilon_0} \quad \text{Gauss Law}$$

$$E \oint ds = \frac{Q}{\epsilon_0}$$

$$\vec{E} \cdot 2\pi r L = \frac{Q}{\epsilon_0} \quad \vec{E} = \frac{Q}{2\pi\epsilon_0 r L} \hat{a}_r$$

$$V_{21} = -\int_a^b \frac{Q}{2\pi\epsilon_0 r L} \cdot \hat{a}_r \cdot dr \hat{a}_r$$

$$= -\int_a^b \frac{Q}{2\pi\epsilon_0 r L} dr = -\frac{Q}{2\pi\epsilon_0 L} \ln\left(\frac{b}{a}\right)$$

$$= -\frac{Q}{2\pi\epsilon_0 L} \ln\left(\frac{b}{a}\right)$$

$$C = \frac{Q}{V_{21}} = \frac{Q}{-\frac{Q}{2\pi\epsilon_0 L} \ln(b/a)} = \frac{2\pi\epsilon_0 L}{\ln(b/a)}$$

Spherical Capacitance



$$\oint \vec{E} \cdot d\vec{s} = \frac{Q_{\text{enclosed}}}{\epsilon_0}$$

$$V_{21} = -\int_a^b \frac{Q}{4\pi\epsilon_0 r^2} \hat{r} \cdot d\vec{s} \hat{r} = -\int_a^b \frac{Q}{4\pi\epsilon_0 r^2} ds = -\frac{Q}{4\pi\epsilon_0} \left[-\frac{1}{r} \right]_a^b$$

$$V_{21} = \frac{Q}{4\pi\epsilon_0} \left[\frac{1}{a} - \frac{1}{b} \right]$$

$$C = \frac{Q}{V_{21}} = \frac{Q}{\frac{Q}{4\pi\epsilon_0} \left[\frac{1}{a} - \frac{1}{b} \right]}$$

$$C = \frac{4\pi\epsilon_0}{\frac{1}{a} - \frac{1}{b}}$$

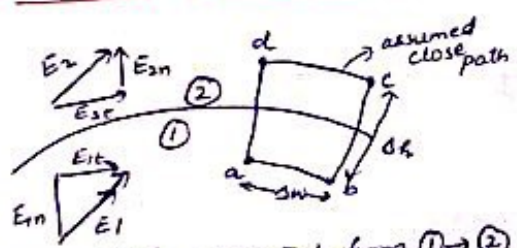
If $b = \infty$ $C = 4\pi\epsilon_0 a$

Boundary Conditions

When \vec{E} exists in a region consisting of two different media, the condition that the field must satisfy at the interface separating the medium is called boundary condition.

To determine boundary conditions Maxwell's equation are used
 1. $\oint \vec{E} \cdot d\vec{l} = 0$
 2. $\oint \vec{D} \cdot d\vec{s} = Q$
 Decompose \vec{E} and \vec{D} into normal and tangential components i.e. \vec{E}_n and \vec{E}_t , \vec{D}_n and \vec{D}_t .

Dielectric - Dielectric Boundary Condition



When \vec{E} is directed from ① → ②

Apply $\oint \vec{E} \cdot d\vec{l} = 0$

$$= \int_a^b \vec{E}_1 \cdot d\vec{l} + \int_b^c \vec{E}_2 \cdot d\vec{l} + \int_c^d \vec{E}_2 \cdot d\vec{l} + \int_d^a \vec{E}_1 \cdot d\vec{l}$$

$$E_{1t} \Delta w + E_{1n} \frac{\Delta h}{2} + E_{2n} \frac{\Delta h}{2} - E_{2t} \Delta w - E_{1n} \frac{\Delta h}{2} = 0$$

$$(E_{1t} - E_{2t}) \Delta w = 0$$

$$\text{as } \Delta w \neq 0 \Rightarrow E_{1t} = E_{2t}$$

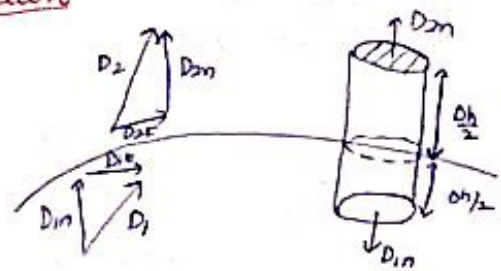
i.e. tangential component of \vec{E} i.e. \vec{E}_t is said to be continuous (constant) across the boundary.

$$D = \epsilon E \therefore D_{1t} = \epsilon_1 E_{1t}$$

$$E_{1t} = \frac{D_{1t}}{\epsilon_1} \quad E_{2t} = \frac{D_{2t}}{\epsilon_2}$$

$$\frac{D_{1t}}{\epsilon_1} = \frac{D_{2t}}{\epsilon_2}$$

Tangential comp



$$\oint \vec{D} \cdot d\vec{s} = Q_{\text{enclosed}}$$

top: $\int \vec{D}_2 \cdot d\vec{s}$
 curved: cancelled due to symmetry
 bottom: $\int \vec{D}_1 \cdot d\vec{s}$

$$D_{2n} \Delta S - D_{1n} \Delta S = \rho_s \Delta S$$

$$D_{2n} - D_{1n} = \rho_s$$

If the surface has no charge i.e. $\rho_s = 0$

$$D_{1n} = D_{2n}$$

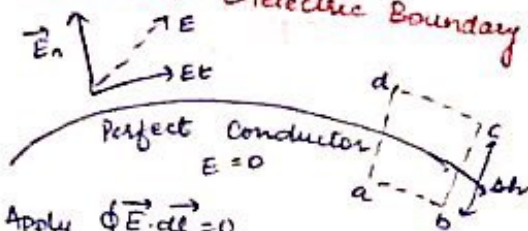
normal component of \vec{D} is continuous across interface.

Since $D = \epsilon E$

$$\epsilon_1 \vec{E}_{1n} = \epsilon_2 \vec{E}_{2n}$$

\vec{E}_n is not continuous across interface.

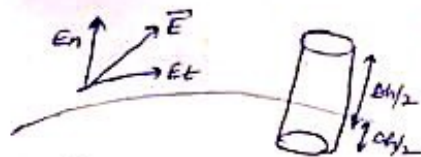
Conductor - Dielectric Boundary condition



Apply $\oint \vec{E} \cdot d\vec{l} = 0$

$$\underbrace{0 \cdot \Delta w}_{a-b} + \underbrace{0 \cdot \frac{\Delta h}{2} + E_n \cdot \frac{\Delta h}{2}}_{b-c \text{ path}} - \underbrace{E_t \cdot \Delta w}_{c-d} - \underbrace{E_n \cdot \frac{\Delta h}{2} + 0 \cdot \frac{\Delta h}{2}}_{d-a} = 0$$

$$E_t \cdot \Delta w = 0 \quad \text{or} \quad \boxed{E_t = 0}$$



$$\int_{\text{top}} \vec{D} \cdot d\vec{s} + \int_{\text{bottom}} \vec{D} \cdot d\vec{s} + \int_{\text{surface}} \vec{D} \cdot d\vec{s} = Q_{\text{enclosed}}$$

zero due to symmetry

$$D_n \cdot \Delta s - 0 \cdot \Delta s = \epsilon_s \cdot \Delta s$$

$$\boxed{D_n = \epsilon_s}$$

Que:- The region 1 ($z < 0$) is free space while region 2 ($z > 0$) is dielectric for which relative permittivity is equal to 4. Given that $D_1 = 2\hat{a}_x - 3\hat{a}_y + 4\hat{a}_z$ C/m². Find E_2 and angles θ_1 and θ_2 . (Sessional 2020)

Sol:- $D_1 = 2\hat{a}_x - 3\hat{a}_y + 4\hat{a}_z$

Boundary condition for dielectric-dielectric medium are $\epsilon = 4$ dielectric
 $E_{1t} = E_{2t}$ and $D_{1n} = D_{2n}$ $\epsilon = 1$ free space

$$D_{1n} = 4\hat{a}_z = D_{2n}$$

$$D_{1t} = 2\hat{a}_x - 3\hat{a}_y$$

$$E_{1t} = E_{2t}$$

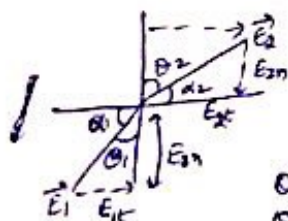
$$\frac{D_{1t}}{\epsilon_1} = \frac{D_{2t}}{\epsilon_2}$$

$$D_{2t} = \frac{\epsilon_2}{\epsilon_1} D_{1t} = 4(2\hat{a}_x - 3\hat{a}_y) = 8\hat{a}_x - 12\hat{a}_y$$

(since $z=0$ separates both the spaces.
So \hat{a}_n is in z -direction)

$$\vec{D}_2 = \vec{D}_{2t} + \vec{D}_{2n} = 8\hat{a}_x - 12\hat{a}_y + 4\hat{a}_z$$

$$\vec{E}_2 = \frac{\vec{D}_2}{\epsilon_0} = \frac{1}{10^{-9} \times 4} (8, -12, 4) \Rightarrow \boxed{\vec{E}_2 = 226.08\hat{a}_x - 339.12\hat{a}_y + 113.76\hat{a}_z}$$



$$\alpha_1 = 90^\circ - \theta_1$$

$$\alpha_2 = 90^\circ - \theta_2$$

$$\tan \alpha_1 = \frac{D_{1n}}{D_{1t}} \text{ or } \frac{E_{1n}}{E_{1t}} = \frac{4}{\sqrt{2^2 + 3^2}} = 1.11 \rightarrow \alpha = 47.98^\circ$$

$$\tan \alpha_2 = \left| \frac{D_{2n}}{D_{2t}} \right| = \frac{4}{\sqrt{8^2 + 12^2}} = 0.27 \rightarrow \alpha = 15.10^\circ$$

$$\theta_1 = 90^\circ - 47.98^\circ = 42.02^\circ$$

$$\theta_2 = 90^\circ - 15.10^\circ = 74.9^\circ$$

$$\frac{\tan \theta_2}{\tan \theta_1} = \frac{\tan 74.9^\circ}{\tan 42.02^\circ} = \frac{3.706}{0.901} = 4.11 \approx \frac{\epsilon_2}{\epsilon_1}$$

For verification only.

Que: The region ($x < 0$) is free space while region ($x > 0$) is a dielectric for which the relative permittivity is 2.5. Given that $D_1 = 3\hat{a}_x - 4\hat{a}_y + 6\hat{a}_z$. Find E_2 and angle θ_1 and θ_2 .

Sol:- $D_1 = 3\hat{a}_x - 4\hat{a}_y + 6\hat{a}_z$

The boundary is along \hat{a}_x and boundary conditions are

$$E_{1t} = E_{2t}$$

$$\text{and } D_{2n} = D_{1n}$$

$$D_{1n} = 3\hat{a}_x = D_{2n}$$

$$D_{1t} = -4\hat{a}_y + 6\hat{a}_z$$

$$E_{1t} = E_{2t} \quad \text{or} \quad \frac{D_{1t}}{\epsilon_1} = \frac{D_{2t}}{\epsilon_2} \quad \text{or} \quad D_{2t} = \frac{\epsilon_2}{\epsilon_1} D_{1t}$$

$$D_{2t} = 2.5(-4\hat{a}_y + 6\hat{a}_z) = -10\hat{a}_y + 15\hat{a}_z$$

$$D_2 = 3\hat{a}_x - 10\hat{a}_y + 15\hat{a}_z$$

$$\vec{E}_2 = \frac{\vec{D}_2}{\epsilon_2} = \frac{1}{\frac{10^{-9}}{36\pi} \times 2.5} (3, -10, 15) = 45.216 \times 10^{-9} (3, -10, 15)$$

$$\vec{E}_2 = 135.648\hat{a}_x - 452.16\hat{a}_y + 678.24\hat{a}_z \text{ V/m}$$

$$\tan \alpha_1 = \frac{3}{\sqrt{4^2 + 6^2}} = \frac{3}{\sqrt{36 + 16}} = \frac{3}{7.21} = 0.416 \quad \alpha_1 = 22.58^\circ$$

$$\theta_1 = 90^\circ - 22.58^\circ = 67.42^\circ$$

$$\tan \alpha_2 = \frac{3}{\sqrt{10^2 + 15^2}} = \frac{3}{\sqrt{325}} = \frac{3}{18.02} = 0.166 \quad \alpha_2 = 9.42^\circ$$

$$\theta_2 = 90^\circ - 9.42^\circ = 80.58^\circ$$

$$\frac{\tan \theta_2}{\tan \theta_1} = \frac{\tan 80.58^\circ}{\tan 67.42^\circ} = \frac{6.027}{2.4047} = 2.50 \rightarrow \text{Ratio of } \frac{\epsilon_2}{\epsilon_1} \rightarrow \text{for verification purpose only.}$$

Que: There exists a boundary b/w two dielectric medium at $z=0$, $\epsilon_1 = 2.5$ in region 1, $z < 0$ and $\epsilon_2 = 4$ in region 2, $z > 0$. If the field in the region 1 is $\vec{E}_1 = -30\hat{a}_x + 50\hat{a}_y + 70\hat{a}_z$ V/m. Find

- (i) Normal and tangential components of \vec{E}_1
- (ii) Normal and tangential components of \vec{D}_2
- (iii) Angle of incidence & angle of refraction (θ_1, θ_2)

Sol: $\vec{E}_1 = -30\hat{a}_x + 50\hat{a}_y + 70\hat{a}_z$

The boundary is defined at $z=0$ so $\hat{a}_n = \hat{a}_z$

Acc. to Boundary conditions

$$E_{1n} = 70\hat{a}_z$$

$$E_{1t} = E_{2t}$$

$$E_{1t} = -30\hat{a}_x + 50\hat{a}_y = E_{2t}$$

$$\text{and } D_{1n} = D_{2n}$$

$$D_{1n} = D_{2n}$$

$$\epsilon_1 E_{1n} = \epsilon_2 E_{2n}$$

$$E_{2n} = \frac{\epsilon_1}{\epsilon_2} E_{1n} = \frac{2.5}{4} (70\hat{a}_z) \quad \vec{E}_{2n} = 43.75\hat{a}_z$$

$$\vec{E}_2 = -30\hat{a}_x + 50\hat{a}_y + 43.75\hat{a}_z$$

$$\vec{D}_2 = \epsilon_2 \vec{E}_2 = 60\epsilon_0 \vec{E}_2 = \frac{10^{-9}}{36\pi} \times 4 \times (-30, 50, 43.75)$$

$$\vec{D}_2 = -1.061\hat{a}_x + 1.768\hat{a}_y + 1.547\hat{a}_z \text{ nC/m}^2$$

$$\tan \alpha_1 = \frac{E_{1n}}{E_{1t}} = \frac{70}{\sqrt{30^2 + 50^2}} = \frac{70}{65.57} = 1.067 = \alpha_1 = 46.85^\circ \rightarrow \theta_1 = 43.15^\circ$$

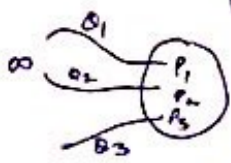
$$\tan \alpha_2 = \frac{E_{2n}}{E_{2t}} = \frac{43.75}{\sqrt{30^2 + 50^2}} = \frac{43.75}{65.57} = 0.667 \quad \alpha_2 = 33.70^\circ \rightarrow \theta_2 = 56.3^\circ$$

$$\frac{\tan \theta_2}{\tan \theta_1} = \frac{\tan 56.3^\circ}{\tan 43.15^\circ} = \frac{1.499}{0.9374} = 1.59 \rightarrow \text{Ratio of } \frac{\epsilon_2}{\epsilon_1}$$

$$\frac{\epsilon_2}{\epsilon_1} = \frac{4}{2.5} = 1.6$$

Electrostatic Energy / Energy density in Electrostatics [ET 2019, 6.5M] (16)

To determine the energy present in an assembly of charges, determine the amount of work done to assemble them.



No work is done to transfer q_1 from ∞ to P_1 , because the space is initially charge free & there is no electric field.

Work done in moving q_2 from ∞ to P_2 is equal to product of q_2 and potential V_{21} due to q_1 .

$$\text{Hly } W_3 = q_3(V_{32} + V_{31})$$

$$W_E = W_1 + W_2 + W_3 = 0 + q_2 V_{21} + q_3(V_{31} + V_{32}) \quad \text{--- (1)}$$

If the charges are positioned in reverse order i.e. $q_3 \rightarrow q_2 \rightarrow q_1$,

$$\text{So } W_E = W_3 + W_2 + W_1 = 0 + q_3 V_{32} + q_1(V_{12} + V_{13}) \quad \text{--- (2)}$$

$$\text{By (1) + (2) } 2W_E = q_1(V_{12} + V_{13}) + q_2(V_{21} + V_{23}) + q_3(V_{31} + V_{32})$$

$$= q_1 V_1 + q_2 V_2 + q_3 V_3$$

where V_1, V_2 and V_3 are total potential at P_1, P_2 and P_3 respectively.

$$W_E = \frac{1}{2}(q_1 V_1 + q_2 V_2 + q_3 V_3)$$

For n -charges $W_E = \frac{1}{2} \sum_{k=1}^n q_k V_k$ in Joules

$$Q = \int \rho \, dv$$

or $W_E = \frac{1}{2} \int V \cdot \rho \, dv$ for continuous charge distribution

Acc. to Gauss law $\nabla \cdot \vec{D} = \rho$

$$W_E = \frac{1}{2} \int_V V(\nabla \cdot \vec{D}) \, dv$$

Using vector identity $\nabla \cdot (V\vec{D}) = V(\nabla \cdot \vec{D}) + \vec{D} \cdot (\nabla V)$

$$\text{or } V(\nabla \cdot \vec{D}) = \nabla \cdot (V\vec{D}) - \vec{D} \cdot (\nabla V)$$

$$W_E = \frac{1}{2} \int_V \{ \nabla \cdot (V\vec{D}) - \vec{D} \cdot (\nabla V) \} \, dv$$

$$= \frac{1}{2} \int_V \nabla \cdot (V\vec{D}) \, dv - \frac{1}{2} \int_V \vec{D} \cdot (\nabla V) \, dv$$

$$\downarrow \text{divergence theorem}$$

$$\frac{1}{2} \oint_S V\vec{D} \cdot \vec{ds} - \frac{1}{2} \int_V \vec{D} \cdot (\nabla V) \, dv$$

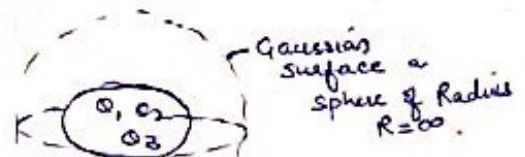
$$W_E = -\frac{1}{2} \int_V \vec{D} \cdot (\nabla V) \, dv$$

$$E = -\nabla V$$

$$W_E = \frac{1}{2} \int_V \vec{D} \cdot \vec{E} \, dv$$

$$W_E = \frac{1}{2} \int_V \epsilon_0 \vec{E} \cdot \vec{E} \, dv$$

$$\text{or } W_E = \frac{1}{2} \int_V \frac{D^2}{\epsilon_0} \, dv$$



$$\left. \begin{array}{l} V \propto \frac{1}{R} \\ D \propto \frac{1}{R^2} \end{array} \right\} \begin{array}{l} VD \propto \frac{1}{R^3} \\ \text{and } dS \propto R^2 \end{array}$$

$$\oint \vec{VD} \cdot \vec{ds} \propto \frac{R^2}{R^3} = \frac{1}{R} = \frac{1}{\infty} = 0$$