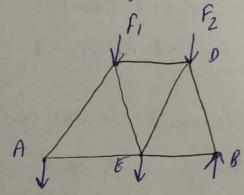
Trees and frame ;

A framed structure is an assemblage of a no. of bour on nods joined together in such a way to farm a rigid framewark Structure is designed to resist geometrical distortion

The engineering structures may be broadly divided into a) Trusses b) Frames c) Machines

Towns: The structure is called thus when the loods are applied only at joints. They are joined together at their ends by suiveting on welding.

Every member of a trum is a two face system.



Frame - It is the Stuncture Consisting of several bars of members pinned together and in which one or more than one of its members is subjected to more than two farces.

machine: The merchines are the structures that have some movable parts and are used to transmit power.

Perfect, deficient and redundant frames-The steucture is said to be perfect if the no. of members is just sufficient to prevent distoction of shape when subjected to external loads. m=7, j=5 (Pertect truss) $\int m = 2j - 3$ A B c O Here no of joint = 6 = 2x6-3(Imperfect / deficient trum) Since there are only eight members. Such a ference cannot prevent geometrical distortion when loaded. Hence it is called imperfect un déficient frame. A stellecture is termed hed and frame if the no. of members in it is more than that beguired feel a perfect frame. j: 7 m=12 m: 2x7-3Statically determinate and statically indeterminate frama A trus is statically determinate if the equations of static equilibrium alone are sufficient to determine the axial faces in the members without the need of counidarity their deformation Equations of Static Equilibrium are not sufficient to determine the forces in statically inderminate frame, their is held of Considering their deformation also

1) The joints of a simple trum are assumed to be pin connections and frictionless. The joints, therefore, cannot resist moments.

2) The loads on the terms are applied at the joints only.

3) The members of a town are straight two face members

4) The weight of the members are negligibly small.

1) The terms is statically determinate.

3) The members are slender and of uniform Cross section

Methods of Determination of axial forces in the members

1) Method of joints

2) Method of sections

3) Greephical method.

Every joint is treated seperately as a FBD i) Method of joint Efn=0; Efy=0

· Celetain direction of forces acting on the joints is assumed It the magnitude of a particular tarce comes out positive, the assumption in respect to its direction is correct.

· Start from a joint where not more than two unknown

force appear.

. The force in the member will be tensile if the member pull the joint (fance is directed away from the pin.)

· For compression, farce is towards the pin.

Tension: Pulling at each end

Compellation: Pushing at each end.

Special condition

If A single face cannot farm a system in equilibrium. It implies, if there is only one face acting at a joint,

Then for equilibrium it should be equal to zero. Fi=0

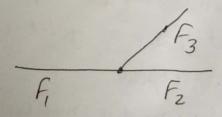
and there is no external fasce acting at the joint, then
the farce in both the members are zero.

F, = F2 = 0

F

joint and out of them two are collinear, then the force in the third member will be zero.

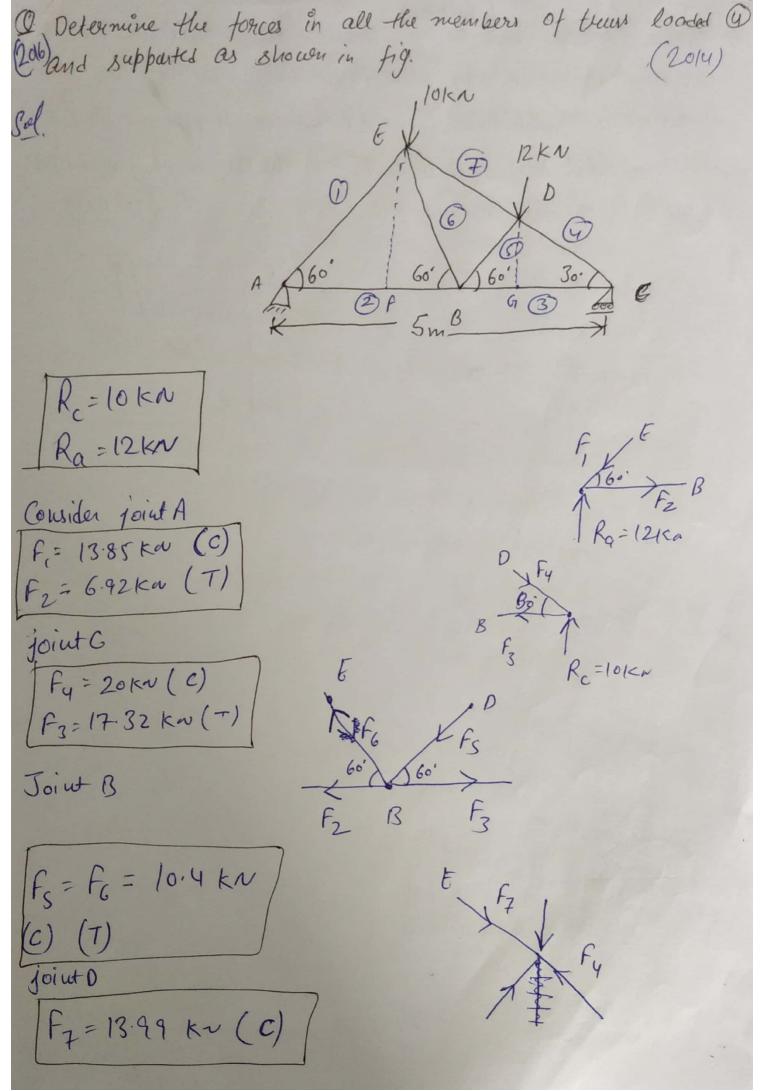
F3 =0



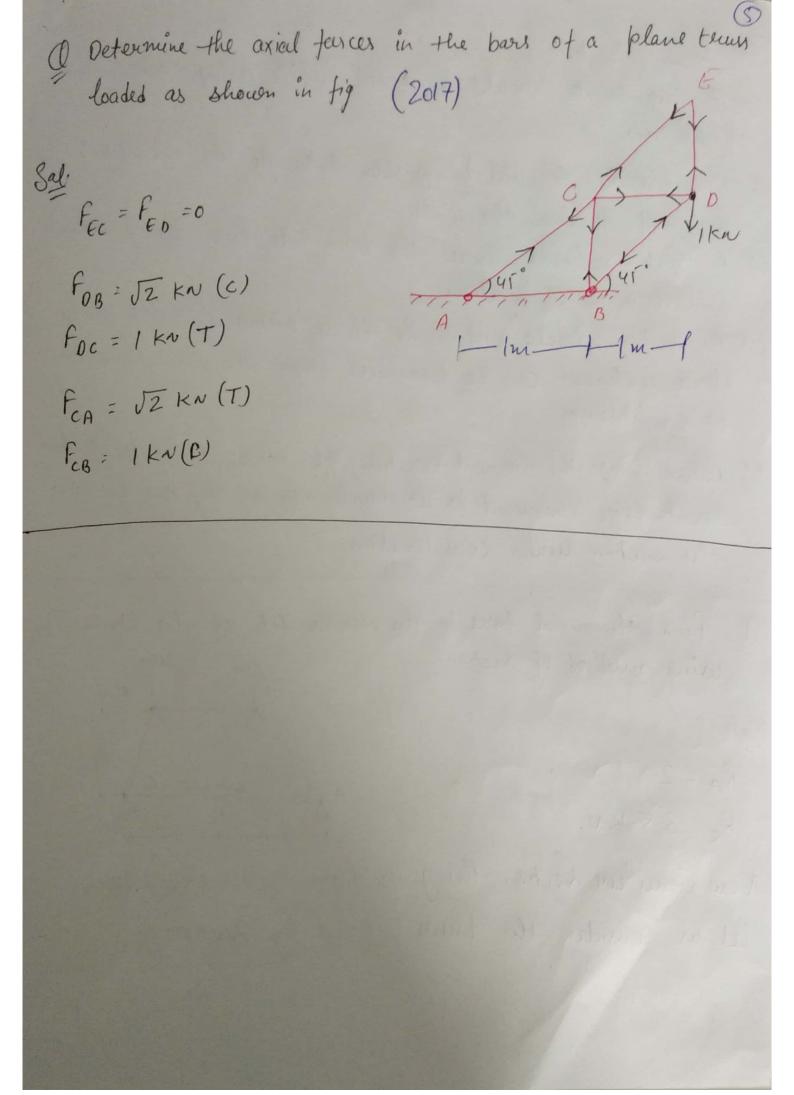
a Determine the forces in all the members of a trus with the loading and support system as show in fig Sal Ac = 2. FW An = 1.25 w Ra = 22.5 KeN Rb= 7.5 KN Joint A F_ = F, cos 60. Fros Fisinbo = -Ra [F,=-25.97 KN](0) Our assumption is wrong. 97 is compressive in nature $F_2 = -12.99 \, \mathrm{kN}$ (7) This assumption is also wrong. It is tensile in neuture. Consider joint B. \$ fn = f3 (0130 - f2 - 6)

[F3 = 15 KN (Compressive)]

Q Determine the seactions and the farces in each member of a thurs as shown in fig. 4KN Ra = 3.5 KN Consider joint A F.= 4.04 KN (C) F2= 2.02 (T) Consider joint C Fy= 2.88 Kv (C) F3=1.44 K2 (T) R=2.5 KA Consider joint B $f_S = f_6 = 1.16 = 0.58 \text{ km}$ Fz = 1.73 KN (C)



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following points should be noted while using the method Method of section:

i) The Section should be passed through the members

and not thorough the joints.

1) A Section should divide the trues into two clearly separate

and unconnected positions.

(iii) A section should cut only three members since only three unknown can be determined from the three equations of equilibrium.

iv) when using the moment equation, the moment can be taken about any convenient point which may us may not lie on

the section under consideration.

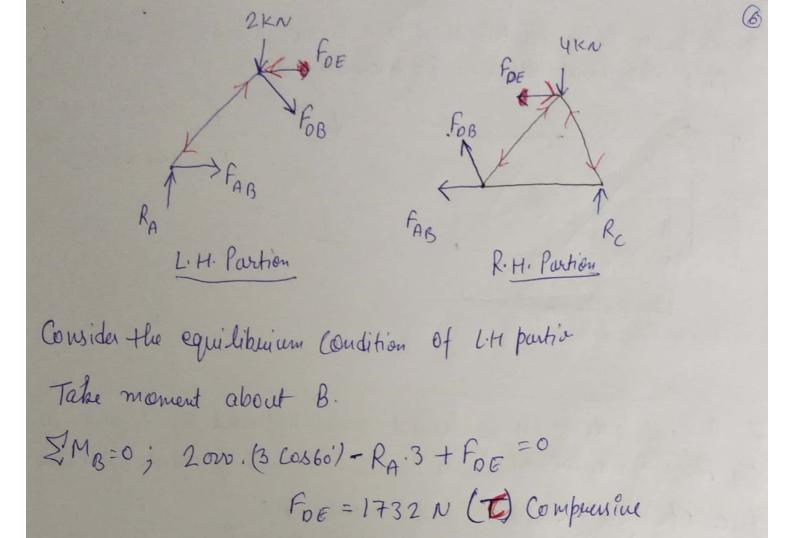
I find the axial force in the member DE of the trum wing method of section. 2KN Q UKN

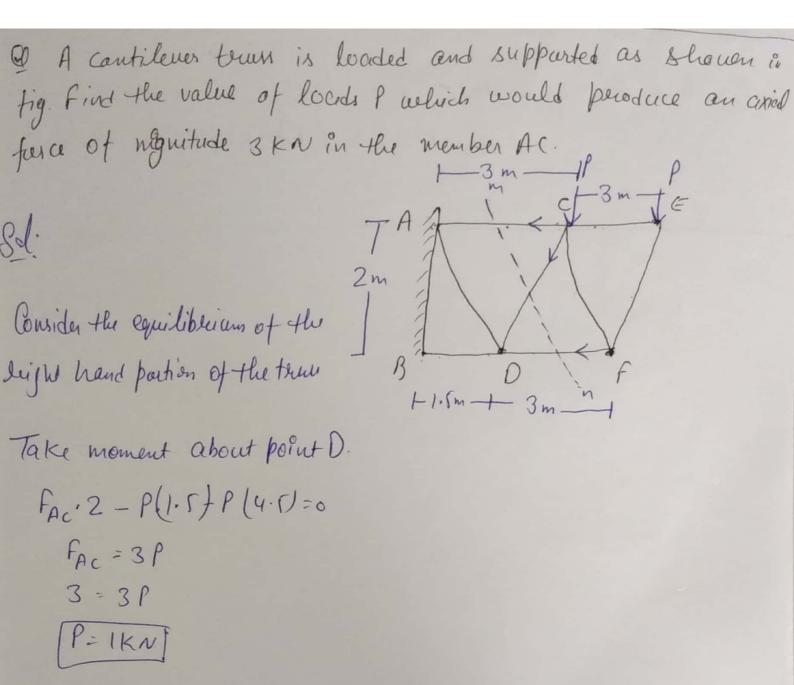
RA = 2.5 KN

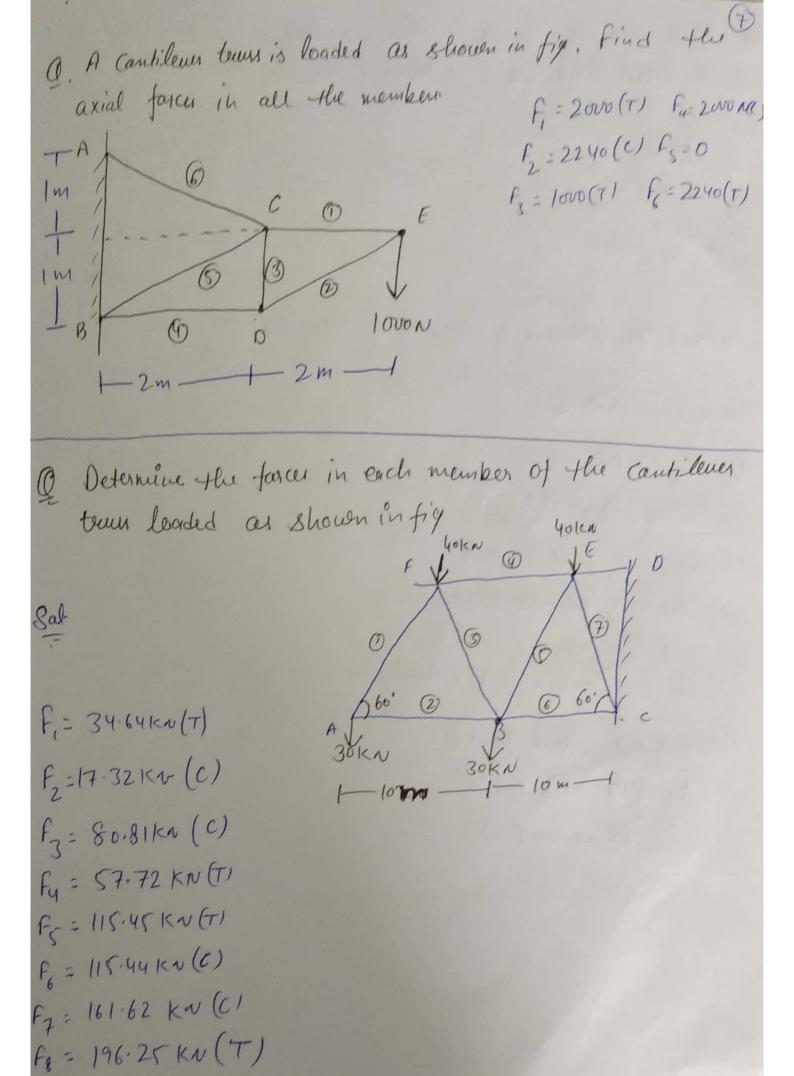
Rc = 3.5 KN

2KN G BY E

Now either we section the given town by 1-1 on 2-2 plans. Let us consider the thus is cut by section 1-1.

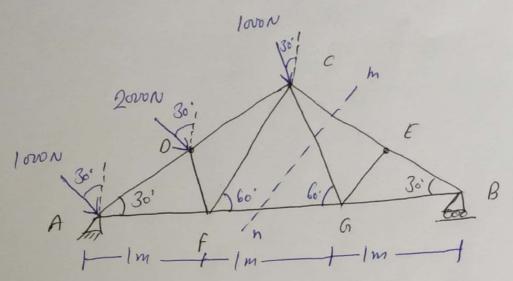






Determine the forces in the members (1), (2) and (3) of the trues loaded and supported as shown in fig. Sal Ra = 12KN Re=10 Ka BD=1-2 (M CD = 2-16 [14 Considering Quilibeium Conditions of right part of the terms, Take moment about C. F2. CO - 12 DG = 0 F2=10.39KN(C) Take moment about point B. F. BD+Rc. BC-12.BG=0 F = -14KN = 14KN (C) [Assumption is wrong] Take moment about point D. F3.06- Rc. 6600 FJ: 17.32 KN (T)

A thuss is loaded and supported as shown. Determine the axial forces in the members CE, CG and FG.



Taking moment about point A

Taking moment about
$$C - F_{G} = 2000 \text{ m(T)}$$

1. Gi - $f_{CE} = 2309 \text{ (C)}$

1. B $f_{CG} = 0$