exam dokulil

June 20, 2023

1 Reduced units

 $\epsilon/k_b = 162.8K, \, \sigma = 3.627$

Reduced units: $T^* = 0.694$, $\rho_l^* = 0.84$

1.1 (a) Triple point formulas

$$T = 0.69\epsilon/k_b \quad \rho_l = 0.845\sigma^3$$

1.2 (b) Reduced units converted to SI

 $T = T^* \epsilon / k_b = 136.172 K, \, \rho_l = \rho_l^* \sigma^3 = 3.91251 \cdot 10^{-29} \, m^{-3}$

[]: 0.84 * 162.8, 0.82 * (3.627e-10)**3

[]: (136.752, 3.9125195364059994e-29)

2 Monte Carlo acceptance rules

2.1 The metropolis acceptance probability

Using the metropolis acceptance probability, $p_{acc}=\min(1,\exp(-\beta\Delta U))$, where $\Delta U=U_y-U_x$, the following holds.

If U(y) < U(x), then $\exp(-\beta \Delta U) > 1$, and $p_{acc} = 1$. Thus, the move is always accepted.

2.2 Using the symmetric acceptance probability

now, lets use the symmetric acceptance probability, $p_{acc}=\frac{1}{1+\exp(\beta\Delta U)}$. If the system loweres its energy, $\Delta U<0$, then if $\beta\Delta U\ll 1$, then $p_{acc}\approx 1$. So, if the change in energy is small, the move has high acceptance probability.

3 Programming a Monte Carlo simulation

The system contains one particle, and the potential is given by the equation

$$U(r) = x^4 + 3x^3 - 2.5x.$$

1

3.1 (a) Implementing the Monte Carlo simulation

The code is given below.

```
[]: from scipy import constants as const
import matplotlib.pyplot as plt
import numpy as np
from matplotlib import gridspec

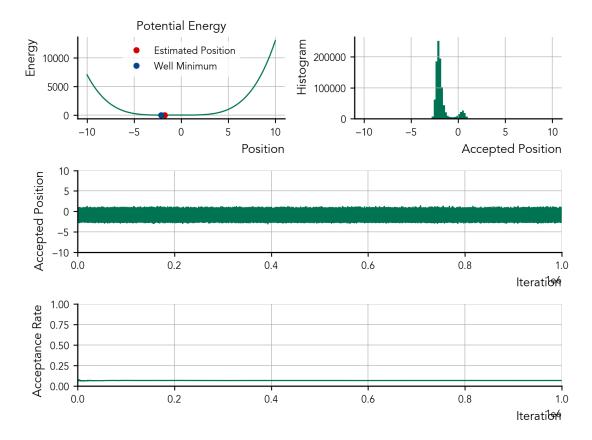
plt.style.use('scandic')
```

```
[]: def potential_energy(x):
         Potential energy of a particle in a 1D potential well.
         return x**4 + 3*x**3 - 2.5*x
     def monte_carlo_simulation(num_iterations, displacement_range, potential_energy_
      →= potential_energy, k_bT = 1, initial_position = None):
         111
         Monte Carlo simulation of a particle in a 1D potential well.
         if initial_position is None:
             current_position = np.random.uniform(*displacement_range)
         else:
             current_position = initial_position
         accepted_positions = []
         num_accepted = 0
         acc_rate = np.zeros(num_iterations)
         for i in range(num_iterations):
             current_energy = potential_energy(current_position)
             displacement = np.random.uniform(*displacement_range)
             new_position = current_position + displacement
             new_energy = potential_energy(new_position)
             acceptance_probability = np.exp(-(new_energy - current_energy) / k_bT)
             if np.random.rand() <= acceptance_probability: # this is not correct</pre>
                 current_position = new_position
                 num\_accepted += 1
             accepted_positions.append(current_position)
             acc_rate[i] = num_accepted / (i+1)
         estimated_position = np.mean(accepted_positions)
```

```
return estimated_position, accepted_positions, acc_rate
num_iterations = 1000000
displacement_range = (-10, 10)
estimated_position, accepted_positions, acc_rate =_
 →monte_carlo_simulation(num_iterations, displacement_range)
print("Estimated Particle Position:", estimated position)
# plotting
G = gridspec.GridSpec(3, 2)
ax = [plt.subplot(G[0, 0]), plt.subplot(G[1, :]), plt.subplot(G[0, 1]), plt.
 ⇒subplot(G[2, :])]
ax[0].set_title("Potential Energy")
ax[0].set_ylabel("Energy")
ax[0].set_xlabel("Position")
x = np.linspace(*displacement_range, 100)
ax[0].plot(x, potential_energy(x))
ax[0].plot(estimated_position, potential_energy(estimated_position), 'o',__
 ⇔label="Estimated Position")
ax[0].plot(x[np.argmin(potential_energy(x))], np.min(potential_energy(x)), 'o',__
 ⇔label="Well Minimum")
ax[0].legend()
ax[1].plot(accepted_positions)
ax[1].set_ylabel("Accepted Position")
ax[1].set_xlabel("Iteration")
ax[1].set_ylim(displacement_range)
ax[1].set_xlim(0, num_iterations)
# Plot a histogram of the accepted positions within the given range
ax[2].hist(accepted positions, bins=100, range=displacement range)
ax[2].set xlabel("Accepted Position")
ax[2].set_ylabel("Histogram")
ax[3].plot(acc_rate)
ax[3].set_xlabel("Iteration")
ax[3].set_ylabel("Acceptance Rate")
ax[3].set_ylim(0, 1)
ax[3].set_xlim(0, num_iterations)
# tight layout
plt.tight_layout()
```

```
/var/folders/xk/1__wtv4d77dg6j4_ypxwxc6m0000gp/T/ipykernel_48217/595094291.py:27
: RuntimeWarning: overflow encountered in exp
acceptance_probability = np.exp(-(new_energy - current_energy) / k_bT)
```

Estimated Particle Position: -1.7485941830563672



Based on the simulation the position of the particle is estimated to be at x = -1.7 (mean of the accepted positions).

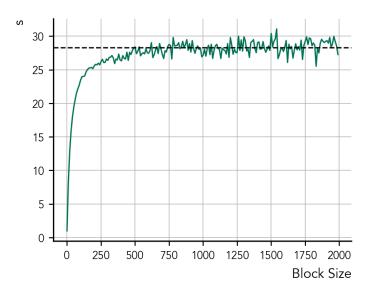
3.2 (b) Error estimate for $\langle x \rangle$

Using the block averaging method.

```
[]: def block_average(sample, block_sizes):
    """Returns variances of block means for different block sizes."""
    variances = []
    for size in block_sizes:
        n_blocks = int(np.floor(len(sample) / size))
```

```
block_averages = []
        for i in range(n_blocks):
            block = sample[i * size : (i+1) * size]
            block_averages.append(np.average(block))
        variances.append(np.var(block_averages))
   return variances
acc_pos_var_correlated = np.var(accepted_positions)
block_sizes = np.arange(1,2000,10)
# Block averaging
block_variances = block_average(accepted_positions, block_sizes)
# average samples 500 to 2000
get_plateau = block_sizes * block_variances/acc_pos_var_correlated
plateau_avg = np.mean(get_plateau[50:])
plt.figure(figsize=(4, 3))
plt.plot(block_sizes, get_plateau, label="Block Averaging")
# Mark plateau value
plt.axhline(plateau_avg, color="0", ls = "--")
plt.xlabel("Block Size")
plt.ylabel("s")
```

[]: Text(0, 1, 's')



Plateau value: 28.29 Chosen block size: 861 Position is estimated to be -1.75 +/- 0.02

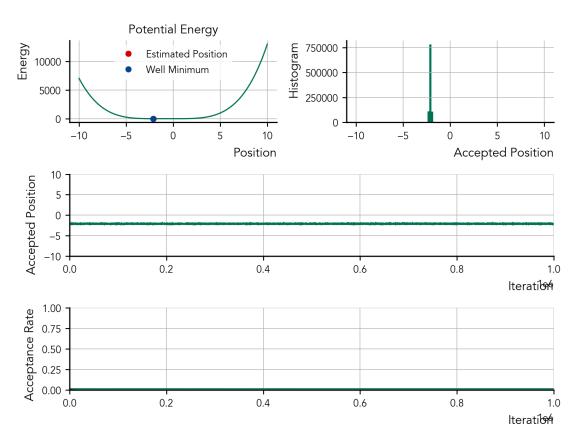
3.3 (c) Behaviour at higher temperatures

3.3.1 $k_B T = 0.1$

```
[]: # for
     estimated_position, accepted_positions, acc_rate =_
      ⇒monte_carlo_simulation(num_iterations, displacement_range, k_bT = 0.1, __
      \rightarrowinitial_position = -2.1)
     print("Estimated Particle Position:", estimated_position)
     # plotting
     G = gridspec.GridSpec(3, 2)
     ax = [plt.subplot(G[0, 0]), plt.subplot(G[1, :]), plt.subplot(G[0, 1]), plt.
      ⇒subplot(G[2, :])]
     ax[0].set_title("Potential Energy")
     ax[0].set_ylabel("Energy")
     ax[0].set_xlabel("Position")
     x = np.linspace(*displacement_range, 100)
     ax[0].plot(x, potential_energy(x))
     ax[0].plot(estimated_position, potential_energy(estimated_position), 'o', u
      ⇔label="Estimated Position")
     ax[0].plot(x[np.argmin(potential_energy(x))], np.min(potential_energy(x)), 'o',__
      ⇔label="Well Minimum")
     ax[0].legend()
```

```
ax[1].plot(accepted_positions)
ax[1].set_ylabel("Accepted Position")
ax[1].set_xlabel("Iteration")
ax[1].set_ylim(displacement_range)
ax[1].set_xlim(0, num_iterations)
# Plot a histogram of the accepted positions within the given range
ax[2].hist(accepted_positions, bins=100, range=displacement_range)
ax[2].set_xlabel("Accepted Position")
ax[2].set_ylabel("Histogram")
ax[3].plot(acc_rate)
ax[3].set_xlabel("Iteration")
ax[3].set_ylabel("Acceptance Rate")
ax[3].set_ylim(0, 1)
ax[3].set_xlim(0, num_iterations)
# tight layout
plt.tight_layout()
```

Estimated Particle Position: -2.102491980521195



```
[]: acc_pos_var_correlated = np.var(accepted_positions)
block_sizes = np.arange(1,2000,10)

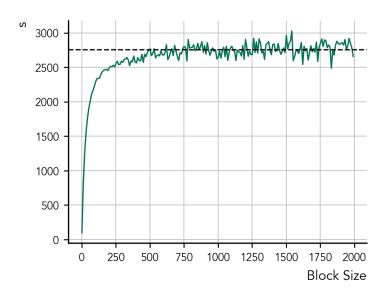
# average samples 500 to 2000
get_plateau = block_sizes * block_variances/acc_pos_var_correlated
plateau_avg = np.mean(get_plateau[50:])
# Block averaging
block_variances = block_average(accepted_positions, block_sizes)

plt.figure(figsize=(4, 3))
plt.plot(block_sizes, get_plateau, label="Block Averaging")

# Mark plateau value
plt.axhline(plateau_avg, color="0", ls = "--")

plt.xlabel("Block Size")
plt.ylabel("s")
```

[]: Text(0, 1, 's')



```
[]: block_size = block_sizes[np.abs(get_plateau - plateau_avg).argmin()]

print(f"Simulation temperature {0.1}")
print("-----")
print(f"Plateau value: \t\t {plateau_avg:.2f}")
print(f"Chosen block size: \t {block_size}")
```

```
acc_pos_std_corrected = np.sqrt(acc_pos_var_correlated / __
  →len(accepted_positions) * block_size)
print(f"\nPosition is estimated to be {estimated_position:.5f} +/-u

√{acc pos std corrected:.5f}")
est_0_1 = estimated_position
est_0_1_err = acc_pos_std_corrected
Simulation temperature 0.1
```

Plateau value: 2756.47 Chosen block size: 861

Position is estimated to be -2.10249 +/- 0.00239

3.3.2 $k_B T = 0.5$

```
[]: # for
     estimated_position, accepted_positions, acc_rate =_
      monte_carlo_simulation(num_iterations, displacement_range, k_bT = 0.5,__
      \hookrightarrowinitial_position = -2.1)
     print("Estimated Particle Position:", estimated_position)
     # plotting
     G = gridspec.GridSpec(3, 2)
     ax = [plt.subplot(G[0, 0]), plt.subplot(G[1, :]), plt.subplot(G[0, 1]), plt.
      ⇒subplot(G[2, :])]
     ax[0].set_title("Potential Energy")
     ax[0].set_ylabel("Energy")
     ax[0].set_xlabel("Position")
     x = np.linspace(*displacement_range, 100)
     ax[0].plot(x, potential_energy(x))
     ax[0].plot(estimated_position, potential_energy(estimated_position), 'o', __
      ⇔label="Estimated Position")
     ax[0].plot(x[np.argmin(potential_energy(x))], np.min(potential_energy(x)), 'o', __
      ⇔label="Well Minimum")
     ax[0].legend()
     ax[1].plot(accepted_positions)
     ax[1].set_ylabel("Accepted Position")
     ax[1].set_xlabel("Iteration")
     ax[1].set_ylim(displacement_range)
```

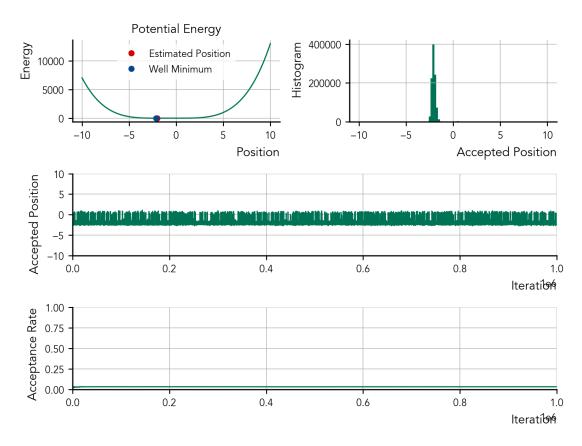
```
ax[1].set_xlim(0, num_iterations)

# Plot a histogram of the accepted positions within the given range
ax[2].hist(accepted_positions, bins=100, range=displacement_range)
ax[2].set_xlabel("Accepted Position")
ax[2].set_ylabel("Histogram")

ax[3].plot(acc_rate)
ax[3].set_xlabel("Iteration")
ax[3].set_ylabel("Acceptance Rate")
ax[3].set_ylim(0, 1)
ax[3].set_ylim(0, num_iterations)

# tight layout
plt.tight_layout()
```

Estimated Particle Position: -2.035623887549357



```
[]: acc_pos_var_correlated = np.var(accepted_positions)
block_sizes = np.arange(1,2000,10)
```

```
# Block averaging
block_variances = block_average(accepted_positions, block_sizes)

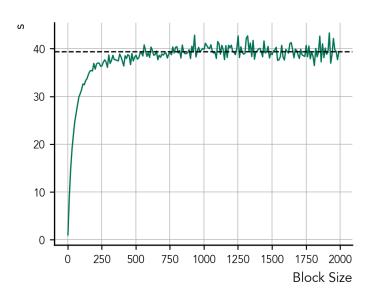
# average samples 500 to 2000
get_plateau = block_sizes * block_variances/acc_pos_var_correlated
plateau_avg = np.mean(get_plateau[50:])

plt.figure(figsize=(4, 3))
plt.plot(block_sizes, get_plateau, label="Block Averaging")

# Mark plateau value
plt.axhline(plateau_avg, color="0", ls = "--")

plt.xlabel("Block Size")
plt.ylabel("s")
```

[]: Text(0, 1, 's')



```
print(f"\nPosition is estimated to be {estimated_position:.5f} +/-u

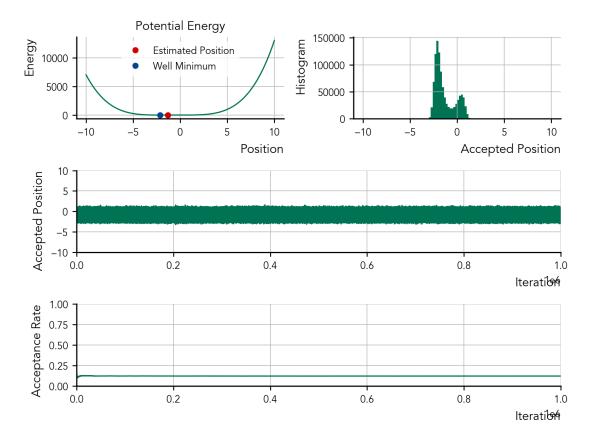
√{acc_pos_std_corrected:.5f}")
     est_0_5 = estimated_position
     est_0_5_err = acc_pos_std_corrected
    Simulation temperature 0.5
                             39.42
    Plateau value:
    Chosen block size:
                            1211
    Position is estimated to be -2.03562 +/- 0.01185
    3.3.3 k_BT = 2
[]: # for
     estimated_position, accepted_positions, acc_rate =__
      →monte_carlo_simulation(num_iterations, displacement_range, k_bT = 2, ___
     \rightarrowinitial_position = -2.1)
     print("Estimated Particle Position:", estimated_position)
     # plotting
     G = gridspec.GridSpec(3, 2)
     ax = [plt.subplot(G[0, 0]), plt.subplot(G[1, :]), plt.subplot(G[0, 1]), plt.
      ⇒subplot(G[2, :])]
     ax[0].set_title("Potential Energy")
     ax[0].set_ylabel("Energy")
     ax[0].set_xlabel("Position")
     x = np.linspace(*displacement_range, 100)
     ax[0].plot(x, potential_energy(x))
     ax[0].plot(estimated_position, potential_energy(estimated_position), 'o', u
      ⇔label="Estimated Position")
     ax[0].plot(x[np.argmin(potential_energy(x))], np.min(potential_energy(x)), 'o', __
      ⇔label="Well Minimum")
     ax[0].legend()
     ax[1].plot(accepted_positions)
     ax[1].set_ylabel("Accepted Position")
     ax[1].set_xlabel("Iteration")
     ax[1].set_ylim(displacement_range)
     ax[1].set_xlim(0, num_iterations)
     # Plot a histogram of the accepted positions within the given range
     ax[2].hist(accepted_positions, bins=100, range=displacement_range)
```

```
ax[2].set_xlabel("Accepted Position")
ax[2].set_ylabel("Histogram")

ax[3].plot(acc_rate)
ax[3].set_xlabel("Iteration")
ax[3].set_ylabel("Acceptance Rate")
ax[3].set_ylim(0, 1)
ax[3].set_ylim(0, num_iterations)

# tight layout
plt.tight_layout()
```

Estimated Particle Position: -1.324025680342521



```
[]: acc_pos_var_correlated = np.var(accepted_positions)

block_sizes = np.arange(1,2000,10)

# Block averaging
block_variances = block_average(accepted_positions, block_sizes)
# average samples 500 to 2000
```

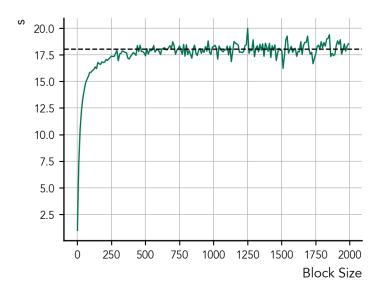
```
get_plateau = block_sizes * block_variances/acc_pos_var_correlated
plateau_avg = np.mean(get_plateau[50:])

plt.figure(figsize=(4, 3))
plt.plot(block_sizes, get_plateau, label="Block Averaging")

# Mark plateau value
plt.axhline(plateau_avg, color="0", ls = "--")

plt.xlabel("Block Size")
plt.ylabel("s")
```

[]: Text(0, 1, 's')



est_2_err = acc_pos_std_corrected

Simulation temperature 2

Plateau value: 18.04 Chosen block size: 851

Position is estimated to be -1.32403 +/- 0.03142

Temperature	Estimated Position	Error
0.1	-2.10249	0.00239
0.5	-2.03562	0.01185
1	-1.74859	0.02363
2	-1.32403	0.03142

Based on the previous results one can see that with increasing temperature the particle is more likely to be located further from the well minimum as the particle has more energy to move around.

One can Also see that the acceptance rate is higher at higher temperatures. As the cold particle has less energy, thus it is less likely to move around, and the acceptance rate is lower.

4 Uncoupled spins

Considering system of N independent spins $s_i \in \{-1, 1\}$ coupled to external magnetic field H with the energy state $\nu = \{s_1, s_2, \dots, s_N\}$.

$$E_{\nu} = -\sum_{i=1}^{N} s_i H$$

With canonical partition function

$$Z=2^N\cosh^N(\beta H)$$

and the mean magnetization with all the intermediate steps

$$\begin{split} m &= \frac{1}{N} \sum_{i=1}^{N} s_i = -\frac{1}{N} \frac{\partial \ln Z}{\partial H} = \frac{1}{N} \frac{\partial \ln \cosh^N(\beta H)}{\partial H} = -\frac{1}{N} \frac{N \partial \ln \cosh(\beta H)}{\partial H} \\ &= \frac{\beta}{N} \frac{N \sinh(\beta H)}{\cosh(\beta H)} = \beta \tanh(\beta H) \end{split}$$