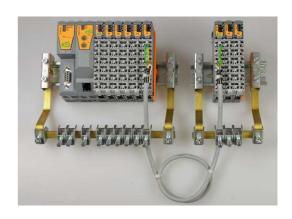
**T2** 











### \*\*\* SAFETY REGULATIONS \*\*\*

Being under voltage the device must not be opened. Danger of electric shock exists. Service works at the weighing equipment are permitted only for qualified personnel. In case of works at conveying lines, all relevant drives have to be switched-off and secured against reengaging.

The related device/system may only be set-up and operated in connection with this documentation. Start-up and operation of a devices/system may only be carried out by **qualified personnel**. Qualified personnel in terms of safety notes of this documentation are persons being authorized to take into operation, to ground and to label the devices, systems and circuits in accordance with the standards of safety engineering.



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### **Revision list**

Revision	Date	Author	Chapter	Description
T2_DWC7A_V0_4_d	16.09.2014	Ratzinger		Preliminary edition
T2_DWC7A_V1_23_en	05.04.2016	Ratzinger	all	Description of new functions and parameters based on technological progress
T2_DWC7A_V1_29_en	24.08.2017	Ratzinger Jungwirth	all	Description of new functions and parameters based on technological progress Translation Check

### **Software indication**

These instruction is based on following Software versions:

W.00.01.29 (Weighing system) P.00.01.29 (Operating unit)

In course of the technical progress changes can be carried out at the software. At subsequent software versions therefore deviations are possible compared to these instructions.

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# 1 General description

This part of the service instructions describes the possibilities of parameterisation of the DWC-7A Weighing system.

It is an extension of the T1-Service instructions, but is no separate manual.

It does not include details and parameters affecting the fieldbus interface. These have been transferred to the T3-Manual.

## 1.1 Symbols

This manual is using the following symbols for special indications:



#### **IMPORTANT INDICATION!**

Marks an important indication.



#### WARNING!

Marks a general warning.



#### **DANGER!**

Means that death or severe personal injury might occur if the corresponding precautions are not taken.

\* marks KUKLA - factory settings



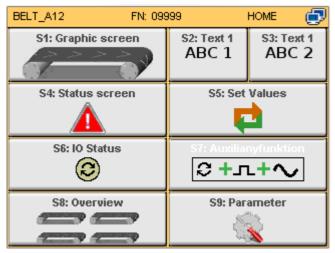
# 1.2 Access into Parameter-system



Via one single operator panel OP-7A several different weighing units can be operated and parameterized under certain circumstances. It ABSOLUTELY must be observed which physical weighing unit is selected currently.

Name and fabrication number of the currently active weighing unit is always shown in the TOP LEFT CORNER of the display.

Within one scale the main selection can be opened with key "MODE".



"S9: Parameter" opens the input window for parameterisation.

Only if a parameter password (P1060) was set, the following screen appears. For entering the password click the red password-number and change it to the number indicated in your parameter printout.

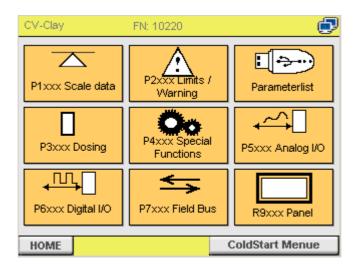


Then, the parameter menu can be opened by pressing the button in the centre of the display.



### 1.3 Parameter - Main selection

All parameters are divided into logically related blocks of thousands. Some parameters or even complete parameter blocks could be omitted (e.g. Block P7xxx if no Fieldbus interface is installed).



The main selection permits quick access to all parameters.

### 1.4 Navigation within the parameter pages

All parameters are divided into logically related blocks of thousands. Some parameters or even complete parameter blocks could be omitted (e.g. Block P7xxx if no Fieldbus interface is installed).



Key serves for fast scrolling back (in blocks) within the parameter pages.

Key A scrolls back one single parameter page.

Key × changes into main selection.

Key scrolls forward one single parameter page.

Key serves for rapid scrolling forward (in blocks) within the parameter pages.



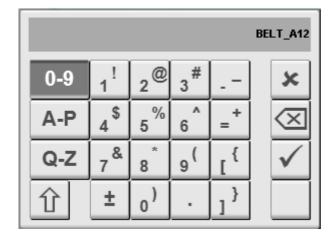
Parameters are only transferred into the weighing unit as a complete data package if key has been pressed!



# 1.5 Operating elements in the parameter level



Since the selection fields in the parameter level sometimes are relatively small, KUKLA recommends operation with a special Touchscreen- pen (in case of need an upturned ball point pen or similar).



Onscreen keyboard for entering text:

Due to the small screen size for entering text the desired page has to be selected with the three character set keys.



The active page appears dark.



leaves the input window WITHOUT CHANGE



deletes ONE character



takes over the data and leaves the picture WITH THE CHANGE

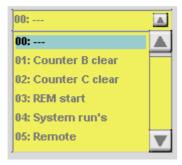


Corresponds to SHIFT-key, this selection always only applies for the next character.

Onscreen keyboard for entering numbers:







Selection menu:

By means of the arrow-keys in case of need navigation within the selection is possible.

The first line as well as the green coded area selects the actual selection.



It absolutely has to be observed that the picture has to be left with correct selection.

## 1.6 Leaving the parameter level

All parameters are divided into logically related blocks of thousands. Some parameters or even complete parameter blocks could be omitted (e.g. Block P7xxx if no Fieldbus interface is installed).





With key X the change to main selection is possible at any time.

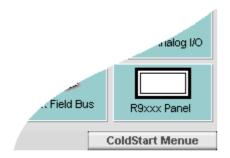
Parameters are only transferred into the weighing unit as a complete data package if key  $\times$  and the button "Accept change" have been pressed!

Exception is parameter P1070 (Language), which immediately affects the display screen internally.

With key "HOME" the parameter mode is left in direction main selection.



## 1.7 Factory settings / Cold start

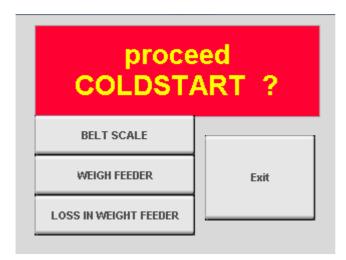


The main menu allows a reset of all parameters to factory settings.



#### With a reset to factory settings all previously set parameters will be deleted!

A previous backup of the old parameters is strongly recommended if these data must be available later.



It is advised to select those scale type, which most closely corresponds to the future use.

This reduces the number of parameters, which must be modified subsequently according to the detail requirements.

After a cold start, it is essential to switch to the parameter group P1xxx to apply the data also in the base unit.

# 1.8 Parameter mode at several operating units in the same network

Several operating units can control a single base unit in normal operation.

But always just ONE SINGLE OPERATOR PANEL is allowed to work in the PARAMETER MODE of a particular weighing computer. Therefore, a mutual overwriting of parameters is avoided.

## 1.9 Automatic exit from parameter mode



In case of about 10 minutes of inactivity (page change) on the panel, the parameter mode is left automatically.

This allows other panels in the network to take control over a particular weighing computer.



# Parameter file / Parameter printout via USB flash drive

### Parameter - list

S9: Parameter

After calling the menu point

Parameter list

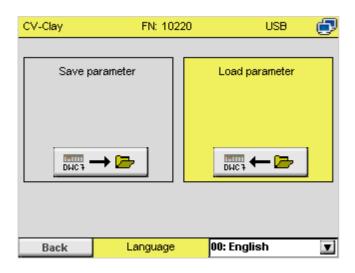
the gate to the parameter menu opens by the key

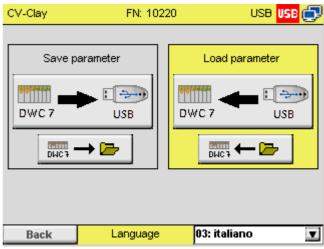
### Administration of sets of parameters

Basically, the system generates parameter files in a .CSV-format. This format can be read from word processing programs or common spreadsheet programs without problems. Also further processing and back reading are possible.

The system can store these CSV-files on an internal partition of the service module (archive 📂 ) as well as on a connected USB-stick usual in trade.

If an USB-Stick was detected, the following screens can appear:





In this case only the internal archive in the service module is accessible.



With one service module several basic devices can be controlled, therefore it has to be noted that IN THE ARCHIVE ALSO PARAMETER FILES OF OTHER SCLAES ARE EXISTENT, NOT ONLY THE FILES OF THE PRESENTLY ACTIVE SCALE!

The red symbol in the right top corner displays that an active USB-memory was detected. Additionally, both large buttons appear, which permit storing and loading from the USB-memory.



## 2.3 Saving of an actual set of parameters

In the top line the actually on the service module active scale is displayed.

The gray coded rectangle displays that an unintentional erroneous programming is impossible.

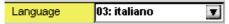


The establishment of a .CSV-parameter file is initiated. After the progress bar has been ran out, usually a success report follows, which has to be confirmed with the key "OK".



The same process occurs here, but in this case the file is not dropped in the USB-memory but in the internal memory.

For the improvement of the readability the parameter list also gets inserted in plain text. In order that the plain texts are also readable, the desired language can manually be selected via a DropDown-selection.



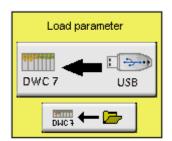
The plain texts are irrelevant for a later back loading of the parameter file because in this case only the received numbers are scanned by the computer system.

## 2.4 Loading of a saved set of parameters

In the top line, the actually on the service module active scale is displayed.



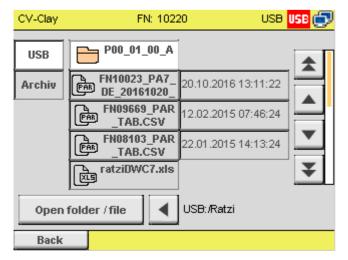
IT IS EXTREMLY IMPORTANT THAT THE RIGHT SCALE IS SELECTED, otherwise an UNINTENED OVERWRITING OF AN ERRORNEOUSLY SELECTED SYSTEM COULD OCCUR!



The yellow coded rectangle displays that an unintentional erroneous programming is possible!

Through the corresponding keys it can be selected from WHERE the parameters should be downloaded

The integrated browser should display the desired medium.



Besides the .CSV-files also other files and folders are displayed, if existing.

DWC-7 parameter files are represented with the symbol.



The file name usually starts with FNxxxxx PA7 yy date time.

xxxxx in this case stands for the 5-digits fabrication number and yy for the plain text language selected during the storing.

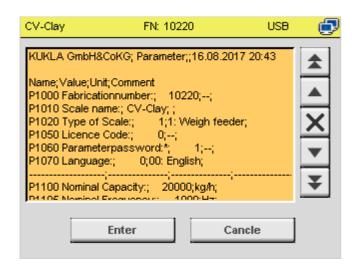


Whichever a folder or a file was selected, this is opened with the key

Open folder / file

The key permits the exiting of the actual folder.

The plain texts are irrelevant for a later back loading of the parameter file because in this case only the received numbers are scanned by the computer system.



After few seconds (Loading...) the values read off from the storage medium are represented again to permit a visual control.

Only with the key the parameters are taken into the service module (still not into the basic device/scale).

In the service module they can be edited further.

Only during exiting the parameter mode the user decides, if the changes should be rejected or uploaded into the basic device.

CSV-Data file can be edited by a plain text editor.

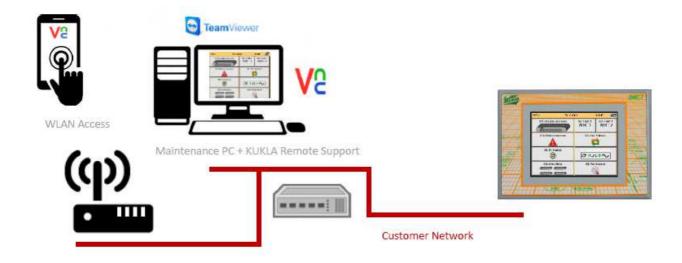
```
FN00001_PAR_TAB.CSV - Editor
Datei Bearbeiten Format Ansicht ?
KUKLA GmbH&CoKG; Parameter;;19.04.2016 09:41
Name; Value; Unit; Comment
P1000 Fabricationnumber:;
P1010 Scale name:; DBW; ;
P1020 Type of Scale:;
P1050 Licence Code:;
                                                    1; --;
                                              1;1: Weigh feeder;
                                            0;--;
P1060 Parameterpassword:*;
P1070 Language:;
                                      0;00: English;
P1100 Nominal Capacity:;
P1105 Nominal Frequency:
                                            20000; kg/h;
1000; Hz;
P1120 Belt Length:;
P1124 Nominal Speed:;
P1130 g3 - length:;
P1132 g2 - length:;
P1150 Test weight:;
                                      ,
6000; mm;
                                      250,0; mm/s;
                                        650; mm;
                                          O; mm;
                                    75,00;%;
P1160 Measuring distance:; 1000;mm;
P1200 Tara mode:; 0;0: Mean Tare Mode;
```



# 3 Connection to a local IT - network

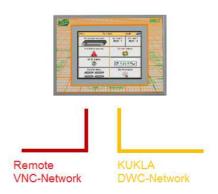
## 3.1 Remote access via Ethernet or WiFi - Access

The operating unit OP7 provides a visualization as a VNC server ("Virtual Network Computing") via its own Ethernet interface. This can be connected to an external Ethernet network if desired. In this way, a wireless access on tablets or mobile phones via an optional WiFi adapter can also be realized.



It is essential to ensure that each of the two RJ45 ports is assigned to the correct network.

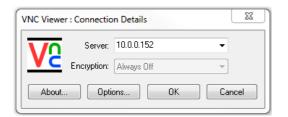






### 3.2 Parameterisation via VNC-Client

If a network connection to a terminal device is available, a VNC client can be obtained free from the manufacturer. VNC Viewer are also available as apps in the corresponding app stores. The network setup is made with the parameters R992x on the operator panel.



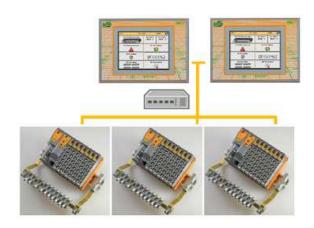
After starting the VNC-Viewer, the IP-address of the service module to be remote-controlled has to be entered.

OK establishes the connection.

In case of problems with the connection build-up, the network connection always should be checked first. This is done with the usual ICMP-Functions (e.g. PING-command).

### 3.3 KUKLA DWC-Network

The internal network is used for communication of all DWC-7 scale computers with the operator panels. In every single network only a maximum of 8 scale computers and 8 control units is allowed due to performance reasons. External devices must not be connected.



This IP-Address always corresponds to the basic range 10.0.1.xx.

The last digit corresponds to the node number, which is set on the rear of the operator panel.



The network range used by KUKLA is 10.0.1.x. This range cannot be changed and must be separated from other networks through appropriate gateways if necessary.



# 4 Parameter description

The parameter description has the following appearance (principle):

Parameter number	Parameter text:		Data type
	Unit: / Selection:	Range:	
Cold start:	0		
Description:			
Dependency:			

#### Parameter number

Indicates the respective parameter number. The numbers used consist of four digits in the range of 0000 up to 9999. Numbers prefixed with "r" or "R" indicate that this parameter is "read-only" and shows a certain value, but cannot be changed directly by specifying a different value via this parameter number. All other parameters are prefixed with "P". The values of these parameters can be changed directly in the area, which is indicated by the adjustments "Min" and "Max" in the heading line. If these values have a physical unit, the unit is indicated in square brackets.

#### Parameter text

Indicates the name of the respective parameter.

#### Data type

The available data types are listed in the following table.

Character	Meaning
String[x]	String [number of characters]
INT	32 Bit integer

#### **Description**

Explanations to the function of a parameter.

#### **Values**

Listing of possible values of a parameter.

#### Indication

Indications concerning recommended adjustments.

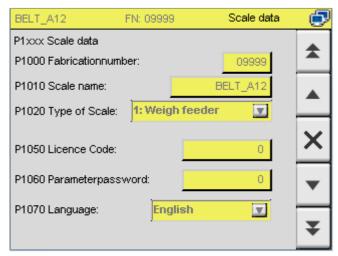
#### Dependency

Conditions, which have to be fulfilled in conjunction with this parameter.

Also, special influences of these parameters to others and vice versa.



# 4.1 Parameter group P1xxx / Scale data



The parameter group "Scale data" describes the nominal data and the basic structure of the weighing system.

Nominal data is usually defined at design and rating of the complete system and is limited with the physical limits of the used components.

P1000	Fabricationnumber:			INT
	Unit:	Absolute	Range:	1-99999
Cold start:	1			
Description:	descri	bes the serial number of the weighing	system	
Indication:	numbe	number identifies the entire system at er at any communication with manufa arly identified.		

P1010	Scale name:		String[16]
	Unit:	Range:	A-Z,a-z,0-9, Special character
Cold start:	RBW (Belt scale), DBW (Weigh feeder)		
Description:	describes the client's designation of the scale		
Indication:	The name should be selected to be possibly significant added to the text. This parameter is especially importational several weighing electronics. This text is always operating steps.	ant, since one ope	erating unit is able to

P1020	Type of scale:				
	Selection: 0: Belt scale 1: Weigh feeder 2: Flowmeter 3: Loss-in-weight-feeder	Range:	0-3		
Cold start:	0 to 3, depending on the selected Cold start				
Description:	describes the basic type of scale A belt scale is a pure registration system, which speed and the current material load. A weigh feeder can additionally regulate the ma setpoint dependent dosing.	·			



An impact flow meter (also called impact plate scale) detects the impact force of a bulk material and calculates an actual capacity thereof.
A loss-in-weight-feeder calculates the actual capacity from the loss of weight in a weighing bin.

Based on this parameter other parameters are connected or disconnected. For example, all dosing parameters (P3xxx) are no longer relevant if 0 has been selected.

P1050	Licence Code:		INT
	Unit: Absolute	Range:	0-4294967295
Cold start:	0 / Emergency licence for 30 days		
Description:	The license code ensures that the weighing system and scope of functions has been acquired regularly at the manufacturer.		
Indication:	In case of changing important hardware components, it might be necessary to request a ne license code from the manufacturer in writing. It has to be noted that KUKLA will only issue new license if the scope of functions has been acquired officially.		

P1060	Paran	neterpassword:		INT
	Unit:	Absolute	Range:	0-9999
Cold start:	0			
Description:		arameter password permits a lock is not desired, 0 has to b	a lock of the parameterisation level for not autoe adjusted.	thorized users.
Indication:		ccess lock can also be put on. This can be connected wit	on a digital input for reasons of compatibility han external switch.	to a previous

P1070	Language:
	Selection: 0: English Range: 0- 1: Deutsch 2: francaise 3: italiano 4: espanol 5: русский 6: العربية
Cold start:	0: English
Description:	This parameter defines the operating language.
Indication:	In case of change of this parameter, the changeover immediately affects the displayed language if spressed. The parameter itself will be stored to the base unit after leaving the

P1100	Nomina	al Capacity:		INT
	Unit:	kg/h	Range:	0-99999999
Cold start:	50000 (	Belt scale), 20000 (Weigh feeder)		
Description:	This parameter describes the nominal conveying capacity of the weighing systems.			

parameter mode like any other parameter.



Indication: The nominal capacity of a continuous conveying system always results from the product of conveying weight times conveying speed. Thus, in case of a change of capacity also the conveying speed and/or the material load have to be changed correspondingly.

P1105	Nominal Frequency:		INT
	Unit: Hz	Range:	0-9999
Cold start:	100 (Belt scale), 1000 (Weigh feeder)		
Description:	The nominal frequency describes at how man weighing system calculates the nominal speed		nput DI0) the
Indication:	Usually the system also can correctly measure	actual speeds of up to 150%.	

P1120	Belt Length:		INT
	Unit: mm	Range:	0-9999999
Cold start:	20000 (Belt scale), 6000 (Weigh feeder)		
Description:	The belt length describes the endless length of the conveyor belt (including lower belt). For weighing screws the length of the screw has to be entered here.		
Indication:	This parameter's meaning is primarily for calculating	ng the duration of taring and	I test.

P1124	Nominal Speed:		INT
	Unit: mm/s	Range:	0-9999,9
Cold start:	500,0 (Belt scale), 250,0 (Weigh feeder)		
Description:	This parameter describes the nominal spe	eed of the material at 100 speed.	
Indication:	In case of conveyor belts this correspond material speed in the screw.  This parameter's meaning is primarily for	,	

P1130	g3 - length:		INT
	Unit: mm	Range:	0-9999999
Cold start:	8000 (Belt scale), 650 (Weigh feeder)		
Description:	This parameter describes the distance betw the material leaves the weighing system. At		
Indication:	Since at a weigh feeder the material load of design, an exact input of this parameter is n for the entire process, this parameter should	ecessary. If the short-term accura	

P1132	g2 - length:		INT
	Unit: mm	Range:	0-9999999
Cold start:	4000 (Belt scale), 0 (Weigh feeder)		



Description:	This parameter describes the distance between measuring length and dosing point. This point is important for special applications, at which an additive or a liquid is added to the weighing material. The supply has to be done between measuring length and discharge point.
Indication:	
Dependency:	The parameter value may never be higher than parameter P1130.

P1150	Test weight:		INT
	Unit: %	Range:	0-150,00
Cold start:	75,00		
Description:	This parameter describes how high the load in for calculating the result of a test with test wei		weight. It is used
Indication:	This parameter is automatically converted by the percentage utilization changes inversely parea.		

P1160	Measuring distance:		INT
	Unit: mm	Range:	0-9999
Cold start:	1000		
Description:	This parameter describes the length of the by the mechanical design of the measuring		value is defined
Indication:			

P1200	Tara mode:		INT
	Selection: 0: Mean Tare Mode 1: Absolute Tare Mode	Range:	0-1
Cold start:	0: Mean Tare Mode		
Description:	At "0: Mean Tare Mode" via one belt revolution the input signal. However, if the conveyor belt he lead to short-term deviations of load measuring against ZERO after one belt revolution at the last of high short-term accuracy is necessary, the activated. In this case the weighing computer of more than 1000 belt sections and subtracts always the correct net weight is displayed and	has a different weight at several poing. But these deviations cancel of atest.  The variant "1: Absolute Tare Modestores during the tare process the this later always at the right time,	nts, this could ut each other de" has to be exact weight
Indication:	For the adjustment "1: Absolute Tare Mode" it conveyor belt an additional mark, which can sensor. This mark corresponds to the logical be	be detected by the weighing elec	

P1300	Display unit:		INT
	Selection: 0: 0,1 kg/h 1: 1 kg/h 2: 0,010 t/h 3: 0,100 t/h 4: 1,000 t/h 5:	Range:	0-12



```
6: 0,001 kg/min
                       7: 0,01 kg/min
                           0,1 kg/min
                       8:
                       9:
                             1 kg/min
                       10: ---
                             1 g/m<sup>2</sup>
                       11:
                             1 g/h
                       12:
Cold start:
Description:
              The display unit shows the interpretation of capacity values on the display and on paper
              printouts.
Indication:
              Recommendation for the adjustment:
                         999.9 \text{ kg/h} = 0:
                                                0.1 \text{ kg/h}
              up to
              1000 -
                          9999 kg/h = 1:
                                                   1 kg/h
              10.00 - 99.99 t/h = 2: 0.010 t/h
              100.00 - 999.9 t/h = 3: 0.100 t/h
              1000.0 - 10000 t/h = 4: 1.000 t/h
                           Set to standard!
              Via key
                                               P1300 and P1310 are calculated automatically.
```

P1310	Counter Unit:
	Selection: 00: 0,1 kg Range: 0-1
	01: 1 kg 02: 0,010 t
	03: 0,100 t
	04: 1,000 t
	05:
	06: 0,2 kg
	07: 2 kg
	08: 0,020 t
	09: 0,200 t 10: 2,000 t
	11:
	12: 0,5 kg
	13: 5 kg
	14: 0,050 t
	15: 0,500 t 16: 5,000 t
	17: 1 g
Cold start:	
Description:	The counter unit shows the resolutioon of counter data (quantity indications) at the display. The adjustment defines at the same time also the counting pulse output for the digital pulse output in case of its use.
Indication:	Recommendation for the adjustment:
	up to 2999 kg/h = 00: 0.1 kg
	3.00 - 29.99  t/h = 01: 1 kg 30.00 - 299.9  t/h = 02: 0,010  t
	30.00 - 299.9  t/h = 02: 0,010  t 300 - 2999  t/h = 03: 0,100  t
	3000 - 10000 t/h = 04: 1,000 t
	Set to standard!
	Via key P1300 and P1310 are calculated automatically.



P1315	Impulslength:		INT
	Unit: ms	Range:	20-2000
Cold start:	100		
Description:	The pulse length describes the pulse output.	length of a counting pulse at the digital	al counting pulse
Indication:	For internal reasons only values divida The system rounds the value automat	•	

P1320	Home:		INT
	Selection: 00: Chart 01: Mode 02: Text screen 03: Set values 04: Trend 05: Chart 2	Range:	0-5
Cold start:	0		
Description:	This parameter determines which visualizat a restart of the CPU.	ion image will be loaded at this scale by	default after
Indication:	Because this parameter is stored at the bas to this scale, will use this setup too!	e unit, other operator panels, which mig	ht be linked

P1400	Speed averaging:	Range:	
	Unit: Tacho pulses Range:		
Cold start:	24		
Description:	The speed measurement is averaged through the number of Tacho pulses set here.		
Indication:	Use always multiple numbers of the pulses per revolution of the measuring unit. (etachometer wheel with 12 pulses per revolution -> 2 revolutions in total = 24 pulse averaging		

P1410	Integration precision regulator:	INT
	Unit: Tacho pulses	Range:
Cold start:	12	
Description:	This parameter determines after how many tac capacity control is retriggered.	chometer pulses the Capacity fine tuner for the
Indication:	The regulation time varies thereby proportional	to the drive velocity.

P1440	ITG- Display:		INT
	Unit:	Range:	
Cold start:	0		
Description:	An averaging of the display output of t	he actual load at g1, g3 and P3 is done.	

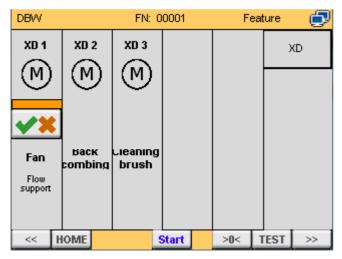


Indication: ---

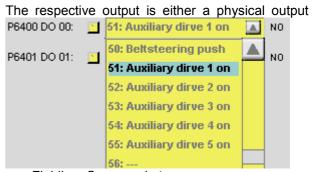
P1450	ITG- Set value:		INT	
	Unit:	Tacho pulses	Range:	
Cold start:	0			
Description:	An ave	eraging of the display output of	the nominal value is done.	
Indication:				_



### 4.1.1 P15xx Auxiliary Drives (XD1-XD5)



Auxiliary drives are support systems, which are necessary for the process and are functionally associated with the weighing system.



or a Fieldbus Command at "BusControlBits2" Register.

P1501 P1502 P1503 P1504 P1505	Auxiliary drive 1: Auxiliary drive 2: Auxiliary drive 3: Auxiliary drive 4: Auxiliary drive 5:	Т
	Selection: 00: not active Range: 0-1 01: Feeder 02: Fan 03: Slide gate 04: Back combing 05: Combing brush 06: Cleaning brush 07: DischargerDevice LiW 08: DischargerDevice PreBin 09: Loosening injector 10: Flow support 11: Cleaning device 12: 13: Loosening device 14: STD drive	4
Cold start:	00: not active	
Linz (LNZ)Description:	It is determined which auxiliary drives are controlled by the system and how their function defined.	is
Indication:	Detailed settings of the P15xx group are hidden if a channel is parametrized to "00: not active	

P1510 P1520 P1530 P1540 P1550	Release on: (Auxiliary drive 1) Release on: (Auxiliary drive 2) Release on: (Auxiliary drive 3) Release on: (Auxiliary drive 4) Release on: (Auxiliary drive 5)		Range: 0x01 / 0x02 / 0x04	
	Unit: Bitfield	Range:	0x01 / 0x02 / 0x04	
Cold start:	0x00			



Description:

The line "Remote" describes which status signals are mandatory to release the selected auxiliary drive for the operation.

The line "Panel" describes the signals needed for manual operation.

The line "Local" describes the signals needed for local mode operation. Local- Mode must be enabled with Parameter P3021 previously.

MEM stores the ON/OFF status in the PANel mode at operation mode changes until the return at next time.

Caution: Danger of an automatic drive start when switching to PAN!

RDY means "release only if the entire system is ready/RDY".

RUN only releases the auxiliary drive if the main conveyor system (belt or screw) is running.

Indication:

P1510 Release on:

Remote:

Panel:

Local:

auxiliary drives in REMote mode.

P1511 P1521 P1531 P1541 P1551	Release via Panel 1: Release via Panel 2: Release via Panel 3: Release via Panel 4: Release via Panel 5:		INT
	Selection: 00: not Active 01: Active	Range:	0-1
Cold start:	00: not Active		
Description:	This parameter determines whether the co- functions" are displayed and thus a manual r		7: Auxiliary
Indication:			

P1512 P1522 P1532 P1542 P1552	REM channel: (for Auxiliary drive 1) REM channel: (for Auxiliary drive 2)		INT
	Selection: 00: Not active 01: Channel 1 02: Channel 2 03: Channel 3 04: Channel 4 05: Channel 5 06: 07: 08: Always active	Range:	0-8
Cold start:	00: Not active		
Description:	This parameter determines which digital inputs or	Fieldbusbits lead the general	release of the

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Indication:	Also see digital inputs P60xx / 64,65 etc. or bus command 3 "CHANNEL x START" and "STOP
	CHANNEL x".

P1513 P1523 P1533 P1543 P1553	Channeloption REM: (for Auxiliary drive 1 Channeloption REM: (for Auxiliary drive 2 Channeloption REM: (for Auxiliary drive 3 Channeloption REM: (for Auxiliary drive 4 Channeloption REM: (for Auxiliary drive 5	) ) )	INT
	Selection: 00: Meaningless 01: Button 02: Switch 03: Wiping contact	Range:	0-3
Cold start:	00: Meaningless		
Description:	This parameter describes which digital input of (only valid for the REMote mode).  When selecting "01: Button" the corresponding the input for "CHANNEL x STOP" must be converted by the correspondence of the correspondenc	ng digital input for "CHANNEL X STA onnected. onding digital input for "CHANNEL X	ART" and also
Indication:			

P1514 P1524 P1534 P1544 P1554	PAN channel: (for Auxiliary drive 1) PAN channel: (for Auxiliary drive 2) PAN channel: (for Auxiliary drive 3) PAN channel: (for Auxiliary drive 4) PAN channel: (for Auxiliary drive 5)		INT
	Selection: 00: Not active 01: Channel 1 02: Channel 2 03: Channel 3 04: Channel 4 05: Channel 5 06: 07: 08: Always active	Range:	0-8
	•		

Cold start:	00: Not active
Description:	This parameter determines which digital inputs or Fieldbusbits lead the general release of the auxiliary drives in PANel mode.
Indication:	Also see digital inputs P60xx / 64,65 etc. or bus command 3 "CHANNEL x START" and "CHANNEL x STOP ".

P1515 P1525 P1535 P1545 P1555	Channeloption PAN: (for Auxiliary drive 1) Channeloption PAN: (for Auxiliary drive 2) Channeloption PAN: (for Auxiliary drive 3) Channeloption PAN: (for Auxiliary drive 4) Channeloption PAN: (for Auxiliary drive 5)		
	Selection: 00: Meaningless 01: Button 02: Switch 03: Wiping contact	Range:	0-3



Cold start:	00: Meaningless
Description:	This parameter describes which digital input channel / Fieldbusbit will release the auxiliary drive. (only valid for the PANel mode).  When selecting "01: Button" the corresponding digital input for "CHANNEL x START" and also the input for "CHANNEL x STOP" must be connected.  When selecting "02: Switch" just the corresponding digital input for "CHANNEL x START" must be activated. (see P60xx / 64,65 etc. or bus command 3)
Indication:	It has to be noted that one channel is able to release several auxiliary drives (see P60xx / $64,65$ etc.).

P1516 P1526 P1536 P1546 P1556	LOC channel: (for Auxiliary drive 1) LOC channel: (for Auxiliary drive 2)		INT
	Selection: 00: Not active 01: Channel 1 02: Channel 2 03: Channel 3 04: Channel 4 05: Channel 5 06: 07: 08: Always active	Range:	0-8
Cold start:	00: Not active		
Description:	This parameter determines which digital inputs o auxiliary drives in LOCal mode.	r Fieldbusbits lead the general	release of the
Indication:	Also see digital inputs P60xx / 64,65 etc. or bus c CHANNEL x".	ommand 3 "CHANNEL x STAR	T" and "STOP

P1517 P1527 P1537 P1547 P1557	Channeloption LOC: (for Auxiliary drive 1) Channeloption LOC: (for Auxiliary drive 2) Channeloption LOC: (for Auxiliary drive 3) Channeloption LOC: (for Auxiliary drive 4) Channeloption LOC: (for Auxiliary drive 5)		INT
	Selection: 00: Meaningless 01: Button 02: Switch 03: Wiping contact	Range:	0-3
Cold start:	00: Meaningless		
Description:	This parameter describes which digital input chanr (only valid for the LOCal mode).  When selecting "01: Button" the corresponding dithe input for "CHANNEL x STOP" must be connect When selecting "02: Switch" just the correspondin be activated. (see P60xx / 64,65 etc. or bus comnections)	gital input for "CHANNEL x STAF cted. ig digital input for "CHANNEL x S	RT" and also
Indication:	It has to be noted that one channel is able to relea etc.).	se several auxiliary drives (see P	60xx / 64,65



P1528 P1538 P1548 P1558	Parallel function 2: (for Auxiliary drive 1) Parallel function 2: (for Auxiliary drive 2) Parallel function 2: (for Auxiliary drive 3) Parallel function 2: (for Auxiliary drive 4) Parallel function 2: (for Auxiliary drive 5)		INT
	Selection: 00: not active 01: Feeder 02: Fan 03: Slide gate 04: Back combing 05: Combing brush 06: Cleaning brush 07: DischargerDevice LiW 08: DischargerDevice PreBin 09: Loosening injector 10: Flow support 11: Cleaning device 12: 13: Loosening device 14: STD drive	Range:	0-14
Cold start:	00: not active		
Description:	Sometimes several auxiliary drives are connect operating screen "S7: Auxiliary functions" is able permits a parallel display of several texts.		
Indication:			
P1519 P1529 P1539 P1549 P1559	Parallel function 3: (for Auxiliary drive 1) Parallel function 3: (for Auxiliary drive 2) Parallel function 3: (for Auxiliary drive 3) Parallel function 3: (for Auxiliary drive 4) Parallel function 3: (for Auxiliary drive 5)		INT
i			
Description:	2nd parallel text, for functionality see descriptio	n of P15x8.	
P1561 P1562 P1563 P1564 P1565	2nd parallel text, for functionality see description  XD1 Pulse time at v min:  XD2 Pulse time at v min:  XD3 Pulse time at v min:  XD4 Pulse time at v min:  XD5 Pulse time at v min:	n of P15x8.	INT
P1561 P1562 P1563 P1564	XD1 Pulse time at v min: XD2 Pulse time at v min: XD3 Pulse time at v min: XD4 Pulse time at v min:	n of P15x8.	INT
P1561 P1562 P1563 P1564	XD1 Pulse time at v min: XD2 Pulse time at v min: XD3 Pulse time at v min: XD4 Pulse time at v min: XD5 Pulse time at v min:		INT
P1561 P1562 P1563 P1564 P1565	XD1 Pulse time at v min: XD2 Pulse time at v min: XD3 Pulse time at v min: XD4 Pulse time at v min: XD5 Pulse time at v min:	Range:  of a speed monitor for each individua time a positive edge at the input red. If this control pulse does not appear.	I additional must occur





## 4.1.2 P19xx Loss-In-Weight-Feeder Systems LiW / Nominal parameters

P1020 Type of Scale: 3: Loss in weight feed

The parameter group P19xx is active only if the operation mode is "Loss in weight" or if a level measurement is activated.

P1900	Nominal Bin Load:		INT
	Unit: kg	Range:	10-99999
Cold start:	10.0		
Description:	The nominal weighing area of the bin, very serves as buffer for a level measurement		lone. The bin also
Indication:	The source of actual values has to be several sources can be selected. (e.g.		ardware structure

P1910	Difference Register Cells:		INT
	Unit:	Range:	0-1999
Cold start:	200		
Description:	It can be determined how many cells the syster Generally, more cells provide a more stable displathe system only responds sluggishly to rapid chan	ay. However, this has the di	sadvantage that
Indication:			

P1912	G Settling:		INT
	Unit:	Range:	-9999 -9999
Cold start:			
Description:	This parameter allows the smoothing of the direction Positive numbers smooth the signal by means With negative numbers, the steepness of the signare completely controlled and larger changes a	of an additive averaging. gnal change can be limited. Th	nus, small changes
Indication:			

P1914	PG Mem:	ī
	Selection: 00: average value Range: 00-0 01: PG mem 02: Last value	2
Cold start:	00: average value	_
Description:	The firmware is able to store a characteristic curve of the product properties during the dosin step. In the next refilling step, the system can then control the drive according to the characteristic, which can lead to an improvement in the accuracy.	_
Indication:	In the active state, the system fills with an average value of the last dosing cycle.	

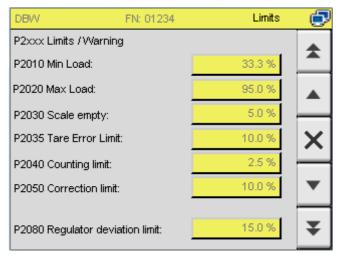


P1920	Max R	efillingtime:		INT
	Unit:	S	Range:	0-9999
Cold start:	12			
Description:	The ma	aximal permitted time, which a	refilling (step 1) may last, is defined here.	
Indication:				

P1922	LiW Settling Time:		INT
	Unit: s	Range:	0-9999
Cold start:			
Description:	The settling time is active after filling the be fluctuations by delayed dropping product duri		ion of weight
Indication:			



# 4.2 Parameter group P2xxx / Limits-warnings



The parameter group "**limits/warnings**" permits the adaption of various limit values to client's requirements.

Additionally, operational errors and warnings can be adapted individually.

P2010	Min Load:		INT
	Unit: %	Range:	0 - 90,00
Cold start:	33.3		
Description:	message "S09: Min Load" is set. This message is part of the status me	t g3 goes below the limit value adjusted essage system and can be used via the	
Indication:	P23xx also for warnings and shut-offs  Also a digital output can be parameter		

P2020	Max Load:		INT
	Unit: %	Range:	20,00 - 200,00
Cold start:	95,00		
Description:	If the material load at discharge point g3 message "S10: Max Load" is set. This message is part of the status message P23xx also for warnings and shut-offs.	•	
Indication:	Also a digital output can be parameterized	to this status. (see P64xx)	

P2030	Scale empty:		
	Unit: %	Range:	0,00 - 50,00
Cold start:	5,00		
Description:	message "S08: Scale empty" is set. This message is part of the status m P23xx also for warnings. Shut-offs an	essage system and can be used via the only reasonable to a limited extent.  or a threshold value during taring and te	e parameter group
Indication:	Also a digital output can be paramete	erized to this status. (see P64xx)	



P2035	Tare Error Limit:		
	Unit: %	Range:	0,00 - 50,00
Cold start:	10,00		
Description:	Usually at taring at the weighchannel always a zero point is measured, which is similar to that deposited at the start-up in the Offset-parameter (see P50x4). If now the tare deviates more than by the value adjusted here, the status message "S24: Tare error" is activated.		
Indication:	Also a digital output can be parameterized to this	status (see P64xx)	

P2040	Counting limit:		INT
	Unit: %	Range:	0,00 - 20,00
Cold start:	2,50		
Description:	This parameter prevents phantom weight counti period. Minor weight values can be faded out with this parameter value, all counters are locked. Or	th this parameter. In case of a lo	ad value below
Indication:	This value should not be selected too high, o quantity will not be counted.	therwise at each drive start or	stop a certain

P2050	Correction limit:		INT
	Unit: %	Range:	5,00 - 80,00
Cold start:	10,00		
Description:	This parameter permits a limiting of an automatic test weight/test load only corrections within the ar		
Indication:			

P2080	Regulator deviation limit:		INT
	Unit: %	Range:	2,00 - 20,00
Cold start:	10,00		
Description:	With the help of this parameter linearity errors of the n If the main drive receives a nominal value of 90% from measured via tacho only 88% come back, the weig nominal value by this factor maximally (set point increally get back the 90% nevertheless.	n the weighing electronic ghing electronics can in	s, however, really ternally raise the
Indication:	Basically, the dosing main drive should be adjusted as The actual factor (linearity) can be read in Text scree		weighing system.



### 4.2.1 P22xx Error periods / General lock of status and error messages

Details as well as additional information to status- and error messages are included in the T1-service instructions.



P2208

Cold start:

If the time is set to -1, the corresponding error message of the following P22xx - group can be completely blocked.



S08 Scale empty:

s

Unit:

0

The following time parameters permit an adjustment of an activation delay of the respective status message.

Range:

S00 WC 0 error:		INT
S01 WC 1 error:		INT
S02 WC 2 error:		INT
S03 WC 3 error:		INT
S04 WC 4 error:		INT
S05 WC 5 error:		INT
Unit: s	Range:	-1 - 600
3		
		gnal at the first
The number -1 deactivates the status me in the entire system.	essage completely, so that it is not ava	ailable anymore
SOE Alarm 6:		INT
S07 Alarm 7:		INT
currently not used / deactivated with -1		
	S01 WC 1 error: S02 WC 2 error: S03 WC 3 error: S04 WC 4 error: S05 WC 5 error: Unit: s  3  This status message is activated after the Weighchannel input is not within the plause of the number -1 deactivates the status mesin the entire system.  S06 Alarm 6: S07 Alarm 7:	S01 WC 1 error:  S02 WC 2 error:  S03 WC 3 error:  S04 WC 4 error:  Unit: s Range:  3  This status message is activated after the period adjusted here, if the input si Weighchannel input is not within the plausible area.  The number -1 deactivates the status message completely, so that it is not avain the entire system.  S06 Alarm 6:  S07 Alarm 7:

INT

-1 - 600



Description:	This status message is activated if the load value at the measuring length goes below the limit value deposited in P2030.
Indication:	This status message should not be delayed. The recommended adjustment is 0s.

P2209	S09 M	in Load:		INT
	Unit:	S	Range:	-1 - 600
Cold start:	0			
Description:		tatus message is deposited in P20	e at the discharge point goe	s below the limit
Indication:		tatus message ment 0s is usual	ary, however, an immediat	e activation with

P2210	S10 Max Load:		INT
	Unit: s	Range:	-1 - 600
Cold start:	0		
Description:	This status message is activated if the deposited in P2020.	load value at the discharge point exceed	ls the limit value
Indication:	This status message can be delayed adjustment 0s is usual.	d if necessary, however, an immediate	activation with

P2211	S11 Alarm 11:	INT
Indication:	currently not used / deactivated with -1	

P2212	S12 Drive / Tacho error:			
	Unit: s	Range:	-1 - 600	
Cold start:	0			
Description:	This status message is activated if a motor failure is detected via a digital input or if at a running drive no tacho pulses are measured.			
Indication:	This status message can be delayed if necessary, however, an immediate activation with adjustment 0s is usual.			

P2213	S13 Not recog. belt start mark:		INT
	Unit: S	Range:	-1 - 600
Cold start:	0		
Description:	This status message gets activated if the Absolute Tare Mode (P1200 Tara mode) is selected and the synchronization mark, which is typically incorporated into the fabric of the belt, is not detected correct or not in time.		
Indication:	Never glue metal strips ONTO the belt, usually these quickly cause this error due to loss of belt marker. If this error occurs, the sensor and the detection distance between sensor and marke should be checked too.		



P2214	S14 Feeder in limits:				
	Unit:	s		Range:	-1 - 600
Cold start:	10				
Description:	limits ar	nd a further auveying capacit erroneous em	tomatic readjustment is a y externally to the correct	g factor of the feeder has achieven not possible anymore. It has to be direction. Large changes in bulk seeders or conveyor screws mig	be tried to adapt material density
Indication:					

P2215	S15 Belt misrun:				
	Unit:	S		Range:	-1 - 600
Cold start:	10				
Description:	An exte		ignalled a belt misrun. Usi	ually this signal serves for s	witching off the
Indication:	separat LEFT" a This sta	te sensor on each and "S22: Belt mis atus message sho	side and belt misrun is srun RIGHT" should be use	-30s, in order to enable a re	21: Belt misrun

P2216	S16 Belt-Slip error:			INT	
	Unit:	s		Range:	-1 - 600
Cold start:	0				
Description:			ected a slip at the main co		ally this sensor is
Indication:	This m	essage can also be tr	iggered by a belt crack or l	by a screw blocking.	

P2217	S17 Drive stopped:			
	Unit: 8	Range:	-1 - 600	
Cold start:	0			
Description:	This is a pure status message signalling the standstill of the main drive is signalled		sured and, thus,	
Indication:	A delay of this message is not reasonable			

P2218	S18 Setvalue error:		
	Unit: s	Range:	-1 - 600
Cold start:	10		
Description:	This message signals an erroneous nominal value.		
Indication:	A delay of this message is not reasonable.		



P2219	S19 Deviation:		INT		
	Unit: s	Range:	-1 - 600		
Cold start:	10				
Description:	If the current actual capacity value deviate set nominal value, this status message is		lue from the pre-		
Indication:	A delay of this message is only reasonab	le to a limited extent.			
P2220	S20 Alarm 20:		INT		
Indication:	currently not used / deactivated with -1				
P2221	S21 Belt misrun LEFT:		INT		
	Unit: s	Range:	-1 - 600		
Cold start:	10				
Description:	An external sensor has signalled a belt misrun on the LEFT side in conveying direction. Usually this signal serves for switching off the belt drive.				
Indication:	This message should be used if on each	side a separate sensor is installed. If	there is only one		
	single input signal and a belt misrun is signal. This status message should usually be dinto normal working area after correction.	gnalled, message "S15: Belt misrun" ( lelayed 10-30s, in order to enable a r	shall be used.		
P2222	single input signal and a belt misrun is signal. This status message should usually be d	gnalled, message "S15: Belt misrun" ( lelayed 10-30s, in order to enable a r	shall be used.		
P2222	single input signal and a belt misrun is signal. This status message should usually be dinto normal working area after correction.	gnalled, message "S15: Belt misrun" ( lelayed 10-30s, in order to enable a r	shall be used. ewind of the belt		
P2222 Cold start:	single input signal and a belt misrun is signal and a belt misrun is signal and a belt misru	gnalled, message "S15: Belt misrun" elayed 10-30s, in order to enable a roof error and quitting.	shall be used. ewind of the belt		
	single input signal and a belt misrun is signal and a belt misrun is signal and a belt misru	gnalled, message "S15: Belt misrun" glelayed 10-30s, in order to enable a reof error and quitting.  Range:	shall be used. ewind of the belt INT -1 - 600		
Cold start:	single input signal and a belt misrun is signally be do into normal working area after correction  S22 Belt misrun RIGHT:  Unit: s  10  An external sensor has signalled a belt	gnalled, message "S15: Belt misrun" gnalled, message "S15: Belt misrun" gnalled and of error and quitting.  Range:  t misrun on the RIGHT side in confit the belt drive. side a separate sensor is installed. If gnalled, message "S15: Belt misrun" gnalled and one of the enable and elayed 10-30s, in order to enable a response to the enable and elayed the elayed the enable and elayed the enable and elayed the enable and elayed the elayed the enable and elayed the elayed the enable and elayed the	INT -1 - 600 weying direction. there is only one shall be used.		
Cold start: Description:	single input signal and a belt misrun is signal status message should usually be do into normal working area after correction  S22 Belt misrun RIGHT:  Unit: s  10  An external sensor has signalled a belt Usually this signal serves for switching of This message should be used if on each single input signal and a belt misrun is signal status message should usually be do	gnalled, message "S15: Belt misrun" gnalled, message "S15: Belt misrun" gnalled and of error and quitting.  Range:  t misrun on the RIGHT side in confit the belt drive. side a separate sensor is installed. If gnalled, message "S15: Belt misrun" gnalled and one of the enable and elayed 10-30s, in order to enable a response to the enable and elayed the elayed the enable and elayed the enable and elayed the enable and elayed the elayed the enable and elayed the elayed the enable and elayed the	INT -1 - 600 weying direction. there is only one shall be used.		
Cold start: Description: Indication:	single input signal and a belt misrun is signal status message should usually be do into normal working area after correction.  S22 Belt misrun RIGHT:  Unit: s  10  An external sensor has signalled a belt Usually this signal serves for switching of This message should be used if on each single input signal and a belt misrun is signal input signal and a belt misrun is signal status message should usually be do into normal working area after correction	gnalled, message "S15: Belt misrun" gnalled, message "S15: Belt misrun" gnalled and of error and quitting.  Range:  t misrun on the RIGHT side in confit the belt drive. side a separate sensor is installed. If gnalled, message "S15: Belt misrun" gnalled and one of the enable and elayed 10-30s, in order to enable a response to the enable and elayed the elayed the enable and elayed the enable and elayed the enable and elayed the elayed the enable and elayed the elayed the enable and elayed the	INT -1 - 600  veying direction. there is only one shall be used. ewind of the belt		
Cold start: Description: Indication:	single input signal and a belt misrun is signal status message should usually be do into normal working area after correction.  S22 Belt misrun RIGHT:  Unit: s  10  An external sensor has signalled a belt Usually this signal serves for switching of This message should be used if on each single input signal and a belt misrun is signal input signal and a belt misrun is signal input signal and a belt misrun is signal input signal and a self misrun is signal input s	gnalled, message "S15: Belt misrun" glelayed 10-30s, in order to enable a reof error and quitting.  Range:  Range:  t misrun on the RIGHT side in confit the belt drive. side a separate sensor is installed. If gnalled, message "S15: Belt misrun" glelayed 10-30s, in order to enable a reof error and quitting.	INT -1 - 600 veying direction. there is only one shall be used. ewind of the belt		
Cold start:  Description:  Indication:	single input signal and a belt misrun is signal status message should usually be dinto normal working area after correction  S22 Belt misrun RIGHT:  Unit: S  10  An external sensor has signalled a belt Usually this signal serves for switching of This message should be used if on each single input signal and a belt misrun is signal input signal and a belt misrun is signal status message should usually be dinto normal working area after correction  S23 Chain Tension error:  Unit: S	gnalled, message "S15: Belt misrun" gelayed 10-30s, in order to enable a reof error and quitting.  Range:  Range:  t misrun on the RIGHT side in confit the belt drive.  side a separate sensor is installed. If gnalled, message "S15: Belt misrun" gelayed 10-30s, in order to enable a reof error and quitting.  Range:	INT -1 - 600 weying direction. there is only one shall be used. ewind of the belt INT -1 - 600		
Cold start:  Description:  Indication:  P2223  Cold start:	single input signal and a belt misrun is signal status message should usually be do into normal working area after correction  S22 Belt misrun RIGHT:  Unit: s  10  An external sensor has signalled a belicusually this signal serves for switching of this message should be used if on each single input signal and a belt misrun is signal into normal working area after correction  S23 Chain Tension error:  Unit: s  10  This message is used for systems with in	gnalled, message "S15: Belt misrun" glelayed 10-30s, in order to enable a reof error and quitting.  Range:  Range:  t misrun on the RIGHT side in confit the belt drive.  side a separate sensor is installed. If gnalled, message "S15: Belt misrun" glelayed 10-30s, in order to enable a reof error and quitting.  Range:  Range:	INT -1 - 600 weying direction. there is only one shall be used. ewind of the belt INT -1 - 600 type ying direction.		
Cold start: Description: Indication:  P2223  Cold start: Description:	single input signal and a belt misrun is signal status message should usually be do into normal working area after correction.  S22 Belt misrun RIGHT:  Unit: s  10  An external sensor has signalled a belt Usually this signal serves for switching of This message should be used if on each single input signal and a belt misrun is signal status message should usually be do into normal working area after correction.  S23 Chain Tension error:  Unit: s  10  This message is used for systems with inthat the chain(s) for the cleaning scraper.  A delay time of 5-30s is recommended, in	gnalled, message "S15: Belt misrun" glelayed 10-30s, in order to enable a reof error and quitting.  Range:  Range:  t misrun on the RIGHT side in confit the belt drive.  side a separate sensor is installed. If gnalled, message "S15: Belt misrun" glelayed 10-30s, in order to enable a reof error and quitting.  Range:  Range:	INT -1 - 600 weying direction. there is only one shall be used. ewind of the belt INT -1 - 600 type ying direction.		



Cold start:	0		
Description:	During the taring process an unpermitted mea bridge(s).	asuring value was measured o	n the weighing
Indication:	A delay of this message is not reasonable.		
P2225	S25 Test error:		INT
	Unit: s	Range:	-1 - 600
Cold start:	0		
Description:	At the test with test weight the nominal numb permitted tolerance (+/- 1,0%).	er 1000 was not achieved by	more than the
Indication:	A delay of this message is not reasonable.		
P2226	S26 Filling error:		INT
	Unit: s	Range:	-1 - 600
Cold start:	0		
Description:	The refilling process (loss-in-weight-dosing) in the adjusted parameter.  Lack of material or poorly flowing material might		nitted by the
Indication:	A delay of this message is only reasonable to a	limited extent.	
P2227	S27 BinMovement error:		INT
	Unit: s	Range:	-1 - 600
Cold start:	1		
Cold start:  Description:	1 During emptying the loss-in-weight-feeder an imbeing larger than the limit value adjusted was m		of weight
	During emptying the loss-in-weight-feeder an im	easured.	of weight
Description:	During emptying the loss-in-weight-feeder an imbeing larger than the limit value adjusted was m	easured.	of weight
Description:	During emptying the loss-in-weight-feeder an imbeing larger than the limit value adjusted was made and the limit value and the limit value adjusted was made and the limit value and the	easured.	
Description:	During emptying the loss-in-weight-feeder an imbeing larger than the limit value adjusted was made A delay of this message is only reasonable to a S28 Decentral IO offline:	easured.  limited extent.	INT
Description: Indication:	During emptying the loss-in-weight-feeder an imbeing larger than the limit value adjusted was made and limit value adjuste	easured.  limited extent.  Range:	INT -1 - 600
Description: Indication: P2228 Cold start:	During emptying the loss-in-weight-feeder an imbeing larger than the limit value adjusted was made A delay of this message is only reasonable to a second se	easured.  limited extent.  Range:  ed cable reduction package) di	INT -1 - 600
Description: Indication:  P2228  Cold start: Description:	During emptying the loss-in-weight-feeder an imbeing larger than the limit value adjusted was made A delay of this message is only reasonable to a second se	easured.  limited extent.  Range:  ed cable reduction package) di	INT -1 - 600
Description: Indication:  P2228  Cold start: Description: Indication:	During emptying the loss-in-weight-feeder an imbeing larger than the limit value adjusted was made and the larger than the limit value adjusted was made and the larger than the limit value adjusted was made and the larger than the limit value adjusted was made and the larger than the l	easured.  limited extent.  Range:  ed cable reduction package) di	INI -1 - 600 rectly at the
Description: Indication:  P2228  Cold start: Description: Indication:	During emptying the loss-in-weight-feeder an imbeing larger than the limit value adjusted was made and the larger than the limit value adjusted was made and the larger than the limit value adjusted was made and the larger than the limit value adjusted was made and the larger than the l	easured.  limited extent.  Range:  ed cable reduction package) di	INI -1 - 600 rectly at the



Cold start:	0		
Description:	Via a digital input or a fieldbus signal the syste safety switch-off. Thus, a clear text display wit status screen.		
Indication:	A delay of this message is only reasonable to	a limited extent	
P2231	S31 Fieldbus Offline:		INT
	Unit: s	Range:	-1 - 600
Cold start:	0		
Description:	A Fieldbus module is installed in the weighing s system.	system, but is currently not conne	ected to a Maste
Indication:	A delay of this message is only reasonable to	a limited extent.	
P2232	S32 MM00 Error:		INT
P2236	S36 MM01 Error:		INT
P2240	S40 MM10 Error:		INT
P2244	S44 MM11 Error:		IN
	Unit: s	Range:	-1 - 600
Cold start:	0 s		
Description:	The connected MoviMot frequency inverter (chaif the error is active longer than the paramindication. As far as this is useful, short-term e	eterised number of seconds it	will trigger the
Indication:	The transmission of this status message is pDWC-7 MM module and the MoviMot invertional manuals.		
P2233	S33 MM00 Inverter failure:		INT
P2237	S37 MM01 Inverter failure:		INT
P2241	S41 MM10 Inverter failure:		INT
P2245	S45 MM11 Inverter failure:		INT
	Unit: s	Range:	-1 - 600
Cold start:	0 s		
Description:	The connected MoviMot frequency inverter (chaif the error is active longer than the paramindication. As far as this is useful, short-term expressions.	eterised number of seconds it	
Indication:	The transmission of this status message is p DWC-7 MM module and the MoviMot inverte manuals.		
P2234	S34 MM00 offline:		INT
P2238	S38 MM01 offline:		INT
P2242	S42 MM10 offline:		INT



P2246	S46 MM11 offline:		INT
	Unit: S	Range:	-1 - 600
Cold start:	0 s		
Description:	The connected MoviMot frequency inverter of the error is active longer than the paraindication. As far as this is useful, short-term	meterised number of seconds it will	trigger the
Indication:	Communication via RS-485 data telegrams	are currently not successfully.	
P2235	S35 Alarm 35:		INT
P2239	S39 Alarm 39:		INT
P2243	S43 Alarm 43:		INT
P2247	S47 Alarm 47:		INT
Indication:	currently not used / deactivated with -1		
P2248	S48 XD1 speed monitoring:		INT
P2251	S51 XD2 speed monitoring:		INT
P2254	S54 XD3 speed monitoring:		INT
P2257	S57 XD4 speed monitoring:		INT
P2260	S60 XD5 speed monitoring:		INT
	Unit: S	Range:	-1 - 600
Cold start:	0 s		
Description:	With this parameter, the "run monitoring erro by n-seconds after the physical trigger.	" of the additional drive can be addition	ally delayed
Indication:	Typically, with this parameter, unwanted sho	ort faults can be blocked out.	
P2249	S49 XD1 fault:		INT
P2252	S52 XD2 fault:		INT
P2255	S55 XD3 fault:		INT
P2258	S58 XD4 fault:		INT
P2261	S61 XD5 fault:		INT
	Unit: S	Range:	-1 - 600
Cold start:	0 s		
Description:	With this parameter, the "Auxiliary drive fa delayed by n-seconds after the physical trig		additionally
Indication:	Typically, with this parameter, unwanted sho	ort faults can be blocked out	
P2250	S50 XD1 run:		INT
P2253	S53 XD2 run:		INT
P2256	S56 XD3 run:		INT



P2259	S59 XD	4 run:			INT
P2262	S62 XD5 run:				INT
	Unit:	S		Range:	-1 - 600
Cold start:	0 s				
Description:		s parameter, the "XD conds after the physi	x-Run message" of the additional di ical trigger.	rive can be a	dditionally delayed
Indication:	This par	ameter should alway	ys be set to 0 in order to avoid delay	ys the status	indication.

P2263	S63 Alarm 63:	NT
Indication:	currently not used / deactivated with -1	



#### 4.2.2 P23xx Ready-to-operate switch-off / warnings and error memory

Details as well as additional information concerning status and error messages are included in the T1service instructions.



This parameter group determines the influence of a status message on the error status of the system.

A tick in the column signals that this status gets triggered.

Signal deactivates "Ready-to-operate"

WA Signal activates "Warning"

MEM Signal will be stored (Confirmation)

P2300	S00 WC 0	error:			INT
P2301	S01 WC 1	error:			INT
P2302	S02 WC 2	error:			INT
P2303	S03 WC 3	error:			INT
P2304	S04 WC 4	error:			INT
P2305	S05 WC 5	error:			INT
	Unit: (	heckbox	ŗ	Range:	0x01 / 0x02 / 0x04
Cold start:	RDY M	ΞM			
Description:		signals a severe problem i as to be switched off absolute		ı. Thus,	the Ready-to-operate
Indication:					

P2306	S06 Alarm 6:	Т
P2307	S07 Alarm 7:	Т
Indication:	currently not used	

P2308	S08 Scale empty:			INT
	Unit:	Checkbox	Range:	0x01 / 0x02 / 0x04
Cold start:	WA			
Description:		essage "Scale empty" is usually only indicated as y also a warning can be switched on.	status (GREY).	
Indication:				

P2309	S09 Min Load:	INT
-------	---------------	-----



	Unit: Checkbox	Range:	0x01 / 0x02 / 0x04
Cold start:	WA		
Description:	This message is usually only indicated as status (reasonable, in order to indicate that the dosing is bulk weight.		
Indication:			
P2310	S10 Max Load:		INT
	Unit: Checkbox	Range:	0x01 / 0x02 / 0x04
Cold start:	WA		
Description:	This message is usually only indicated as status ( reasonable, in order to indicate that the dosing is erroneous adjustment of the plate to adjust materi	endangered due to ve	ery high bulk weight or
Indication:			
P2311	S11 Alarm 11:		INT
Indication:	currently not used		
P2312	S12 Drive / Tacho error:		INT
	Unit: Checkbox	Range:	0x01 / 0x02 / 0x04
Cold start:	RDY MEM		
Description:	This message is usually indicated at least as warn It signals that there is a failure at the drive.	ning (YELLOW).	
Indication:	It must be decided whether, in case of this messag off.	ge, also Ready-to-oper	ate has to be switched
P2313	S13 Not recog. band start:		INT
	Unit: Checkbox	Range:	0x01 / 0x02 / 0x04
Cold start:	WA		
Description:	Typically, a warning (YELLOW) should occur in cathe short-term accuracy of the system is restricted		on mark error because
Indication:			
P2314	S14 Feeder fault:		INT
	Unit: Checkbox	Range:	0x01 / 0x02 / 0x04
Cold start:	WA		
Description:	This message is usually indicated at least as warn It signals that the feeder nominal value has achiev		
Indication:			



P2315	S15 Belt misrun:		INT			
	Unit: Checkbox	Range:	0x01 / 0x02 / 0x04			
Cold start:	RDY					
Description:	This message is usually used as Ready-to-operate switch- It signals that that the conveyor belt runs off laterally.	off (RED).				
Indication:	This message should also be stored, in order to prevent an automatic restart.					
P2316	S16 Belt-Slip error:		INT			
	Unit: Checkbox	Range:	0x01 / 0x02 / 0x04			
Cold start:	RDY MEM					
Description:	This message is usually indicated at least as warning (YEL	LOW).				
Indication:						
P2317	S17 Drive stopped:		INT			
	Unit: Checkbox	Range:	0x01 / 0x02 / 0x04			
Cold start:						
Description:	This is a pure status message.					
Indication:						
P2318	S18 Setvalue error: INT					
	Unit: Checkbox	Range:	0x01 / 0x02 / 0x04			
Cold start:	WA					
Description:	This message is usually indicated as warning (YELLOW).					
Indication:						
P2319	S19 Regulator Deviation:		INT			
	Unit: Checkbox	Range:	0x01 / 0x02 / 0x04			
Cold start:	WA					
Description:	This message indicates that the actual capacity deviates from the specified set point by more than allowed by the adjustable limit value. Therefore, no proper dosing process is ensured anymore.					
Indication:	This error can occur for instance if no, or too less material i	s at the dosin	g system.			
P2320	S20 Alarm 20:		INT			
Indication:	currently not used					
P2321	S21 Belt misrun LEFT:		INT			
F 202	32 F Deit IIIISTUIT SEFT.		INT			



	Unit: Checkbox	Range:	0x01 / 0x02 / 0x04
Cold start:	RDY		
Description:	This message is usually used as Ready-to-operate swit		
Indication:	It signals that the conveyor belt runs off on the left side.  This message should also be stored, in order to preven		start.

P2322	S22 Belt misrun RIGHT:		
	Unit: Checkbox	Range:	0x01 / 0x02 / 0x04
Cold start:	RDY		
Description:	This message is usually used as Ready-to-operate switch It signals that the conveyor belt runs off on the right side.	-off (RED).	
Indication:	This message should also be stored, in order to prevent a	n automatic re	start.

P2323	S23 Chain Tension error:		
	Unit: Checkbox	Range:	0x01 / 0x02 / 0x04
Cold start:	WA		
Description:	This message is usually indicated as warning (YELLOW). The as soon as possible, in order to prevent possible future damage.		ınit should be checked
Indication:			

P2324	S24 Tare error:		
	Unit: Checkbox	Range:	0x01 / 0x02 / 0x04
Cold start:	WA		
Description:	This message is usually indicated as warning (YELLOW).		
Indication:			

P2325	S25 Te	est error:	INT		
	Unit:	Checkbox	Range:	0x01 / 0x02 / 0x04	
Cold start:					
Description:	This m	essage can be indicated as warning (YELLO	W) if required.		
Indication:					

P2326	S26 Filling error:		
	Unit: Checkbox	Range:	0x01 / 0x02 / 0x04
Cold start:	WA		
Description:	This message is usually indicated as warning (YELLOW).		
Indication:			



P2327		nMovement error:		INT				
	Unit:	Checkbox	Range:	0x01 / 0x02 / 0x04				
Cold start:	WA							
Description:	This m	This message is usually indicated as warning (YELLOW).						
Indication:								
P2328	S28 D	ecentral IO offline:		IN <sup>-</sup>				
	Unit:	Checkbox	Range:	0x01 / 0x02 / 0x04				
Cold start:	RDY	<del></del>						
Description:		essage is usually used as Ready-to-op ant control parts are not online anymo		is necessary because				
Indication:								
P2329	S29 Al	arm 29:		IN				
Indication:	curren	tly not used						
P2330	S30 Eı	nergency stop active:		IN'				
	Unit:	Checkbox	Range:	0x01 / 0x02 / 0x04				
Cold start:	N	ИЕM						
Description:		se this is a pure status indication, a WA PRBIDDEN to realize a safety switch-c		is active permanently				
Indication:								
P2331	S31 Fi	eldbus Offline:		IN <sup>*</sup>				
	Unit:	Checkbox	Range:	0x01 / 0x02 / 0x0-				
Cold start:	WA							
Description:	This m	essage is usually indicated as warning	g (YELLOW).					
Indication:								
P2332	S32 M	M00 Error:		IN <sup>-</sup>				
P2336	S36 M	M01 Error:		IN <sup>*</sup>				
P2340	S40 M	M10 Error:		IN'				
P2344	S44 M	M11 Error:		IN <sup>*</sup>				
	Unit:	Checkbox	Range:					
Cold start:								
Colu Start.		<del></del>						



	If the drive does not have a high priority for pruseful.	oduction, a warning message (YELLOW) can be
Indication:	-	
P2333	S33 MM00 Inverter failure:	INT
P2337	S37 MM01 Inverter failure:	INT
P2341	S41 MM10 Inverter failure:	INT
P2345	S45 MM11 Inverter failure:	INT
	Unit: Checkbox	Range:
Cold start:		
Description:	the additional drive must lead to the shutdown	rate shutdown (RED) if the MM-Inverter failure of a of the entire system. oduction, a warning message (YELLOW) can be
Indication:	-	
P2334	S34 MM00 offline:	INT
P2338	S38 MM01 offline:	INT
P2342	S42 MM10 offline:	INT
P2346	S46 MM11 offline:	INT
	Unit: Checkbox	Range:
Cold start:		
Description:	the additional drive must lead to the shutdown	erate shutdown (RED) if the MM-offline status of of the entire system. oduction, a warning message (YELLOW) can be
Indication:	-	
P2335	S35 Alarm 35:	INT
P2339	S39 Alarm 39:	INT
P2343	S43 Alarm 43:	INT
P2347	S47 Alarm 47:	INT
Indication:	currently not used	
P2348	S48 XD1 speed monitoring:	INT
P2351	S51 XD2 speed monitoring:	INT
P2354	S54 XD3 speed monitoring:	INT
P2357	S57 XD4 speed monitoring:	INT
P2360	S60 XD5 speed monitoring:	INT



Cold start:						
Description:	of the add	age can be used as ready for operational drive has to lead to the shutd does not have as high priority for th	own of the entire sys	tem.		-
Indication:	-					
D0040	040 VD4	and the				INIT
P2349	S49 XD1					INT
P2352	S52 XD2					INT
P2355	S55 XD3					INT
P2358	S58 XD4					INT
P2361	S61 XD5		Don	901	0-04 / 0-00	INT
	Unit:	Checkbox	Ran	ge:	0x01 / 0x02	/ UXU4
Cold start:						
Description:	This message can be used as a ready for operation shutdown (RED) if a general malfunction of the auxiliary drive has to lead to the shutdown of the entire system.  If the drive does not have as high priority for the production, a warning message (YELLOW) can be useful.					
Description.	of the aux	liary drive has to lead to the shutdo	wn of the entire syste		sage (YELLOV	V) can
Indication:	of the aux	liary drive has to lead to the shutdo	wn of the entire syste		sage (YELLOV	V) can
	of the aux	liary drive has to lead to the shutdo does not have as high priority for th	wn of the entire syste		sage (YELLOV	,
Indication:	of the aux If the drive be useful.	liary drive has to lead to the shutdo does not have as high priority for th	wn of the entire syste		sage (YELLOV	INT
Indication:	of the aux If the drive be useful.	liary drive has to lead to the shutdo does not have as high priority for th	wn of the entire syste		sage (YELLOV	INT
Indication: P2350 P2353	of the aux If the drive be useful.  - S50 XD1 S53 XD2	liary drive has to lead to the shutdo does not have as high priority for the does not have a	wn of the entire syste		sage (YELLOV	INT
P2350 P2353 P2356	of the aux If the drive be useful.  - S50 XD1 S53 XD2 S56 XD3	liary drive has to lead to the shutdo does not have as high priority for the does not have a supplied the does not	wn of the entire syste		sage (YELLOV	INT INT
P2350 P2353 P2356 P2359	of the aux If the drive be useful.  -  S50 XD1  S53 XD2  S56 XD3  S59 XD4  S62 XD5	liary drive has to lead to the shutdo does not have as high priority for the does not have a supplied the does not	wn of the entire syste	ng mes	sage (YELLOV	INT INT INT
P2350 P2353 P2356 P2359	of the aux If the drive be useful.  -  S50 XD1  S53 XD2  S56 XD3  S59 XD4  S62 XD5	liary drive has to lead to the shutdo does not have as high priority for the does not have a supplied to the does not have a supplie	wn of the entire syste	ng mes	sage (YELLOV	INT INT INT
P2350 P2353 P2356 P2359 P2362	of the aux If the drive be useful.  S50 XD1 S53 XD2 S56 XD3 S59 XD4 S62 XD5 Unit:	liary drive has to lead to the shutdo does not have as high priority for the does not have a supplied to the does not have a supplie	wn of the entire syste	ng mes	sage (YELLOV	INT INT INT
P2350 P2353 P2356 P2359 P2362 Cold start:	of the aux If the drive be useful.	liary drive has to lead to the shutdo does not have as high priority for the does not have a supplied to the does not have a supplie	wn of the entire syste e production, a warni Ran	ge:		INT INT INT INT
P2350 P2353 P2356 P2359 P2362  Cold start: Description:	of the aux If the drive be useful.	liary drive has to lead to the shutdo does not have as high priority for the does not have a	wn of the entire syste e production, a warni Ran	ge:		INT INT INT INT



# 4.2.3 P29xx Loss-In-Weight-Feeder Systems LiW / Limits

P2910	Activat	e Refilling of Bin:	INT
	Unit:	S	Range:
Cold start:	20.0 %		
Description:		rameter determines the ntrol system switches to	activation limit value for the refilling process. volumetric mode.
Indication:			

P2912	Stop Refilling of Bin:		in: INT
	Unit:	s	Range:
Cold start:	80.0 %	)	
Description:	•	arameter defir s re-entered.	nes the end of the refilling process. After the settling time, the gravimetric
Indication:			t always be significantly higher than parameter P2910 in order to have a or the emptying cycle.

P2920	Movement error Bin:		
	Unit: S	Range:	
Cold start:	5.0 s		
Description:		ly the measured value from the weighing container. If the tolerance (relative to 100% container content) within a short ment fault" is triggered.	
Indication:			

P2930	LossInWeight Bin empty:	
	Unit: s	Range:
Cold start:	5.0 %	
Description:	If the actual weight is exceeded in the	material container, the internal state "EMPTY" is set. "
Indication:	After the EMPTY state has been activ while.	ated, the dosing process is interrupted within in a short

P2932	LossInWeight Bin max:		l)	INT
	Unit:	S	Range:	
Cold start:	80.0 %			
Description:	If the ac	tual weight is exceeded	in the material container, the internal state "MAX" is set.	
Indication:	The inte		AX" is used primarily for indication only, the dosing process	s is

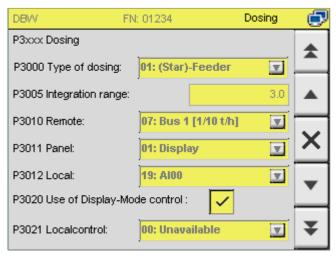
P2934	LossInWeight Bin min:	INT
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	Unit: s Range:	
Cold start:	20.0 %	
Description:	If the actual weight is exceeded in the material container, the internal state "MIN" is set.	
Indication:	The internal Bin- Status "MIN" is primarily intended to warn that the dosing process is in dan to be interrupted without a immediately refilling process.	iger



### 4.1 Parameter group P3xxx / Dosing



The parameter group includes all parameters having influence on the dosing process.

P3000	Type of dosing:	II	ΝT
	Selection: 0: not active 1: Feeder 2: PreHopper	Range: 0	)-2
Cold start:	0 or 1, based on selected Cold start		
Description:	are directly dosing onto the weighing belt or v	n for rotary vane feeders or feeding screws, whi veighing screw. at the scale, the variant "2: PreHopper" has to l	
Indication:			

P3005	Integration range:		INT
	Unit: %	Range:	1,00 - 10,00
Cold start:	3,0		
Description:	This parameter determines in which area at dosing to in case of a belt load change.  Integration range 3,0 means that the load value "gexample, at adjustment 4,0 "g" may be between 25%. At registration belt scales and flow meters with feeds since no speed control is possible.	g" may be between 33.3% % and 100%.	% and 100%. For
Indication:	The value indicated in the technical data of the scale	e must not be changed.	

P3010	Remote:		INT
	Selection: 00: not Active 01: Display 02: Display % 03: Bus 1 [%]	Range:	0-45
	04: Bus 2 [%] 05: Bus 3 [%]		



```
06: Bus 4 [%]
07: Bus 1 [1/10 t/h]
08: Bus 2 [1/10 t/h]
09: Bus 3 [1/10 t/h]
10: Bus 4 [1/10 t/h]
11: Bus 1 [kg/h]
12: Bus 2 [kg/h]
13: Bus 3 [kg/h]
14: Bus 4 [kg/h]
15: Bus 1 [1/10 kg/h]
16: Bus 2 [1/10 kg/h]
17: Bus 3 [1/10 kg/h]
18: Bus 4 [1/10 kg/h]
19: AI00
20: AI01
21: AI10
22: AI11
23: BCD0
24: BCD1
25: Al01 x Bus Prozent 1
26: Al00 x Panel
27: Al01 x Panel
28: Bus Prozent 2 x Panel
29: Bus Prozent 3 x Panel
30: Lv x TV1
31: Lv x TV2
32: ---
33: Lv x TV1 x WW
34: Lv x TV2 x WW
35: ---
36: ---
37: ---
38: ---
39: ---
40: Transfer value 1
41: Transfer value 2
42: ---
43: ---
44: P4701 Fixed value 1
45: P4702 Fixed value 2
```

Cold start: 07: Bus 1 [1/10 t/h]

Description: Describes the source of nominal values for operation mode "Remote". This operation mode is usually used as remote control mode if a superior control pre-sets nominal values and ON/OFF commands. Besides simple, direct nominal values, also the multiplication of several values is possible. Thus, for example, functionally the reference input similar to a guiding shaft can be realized. Also a changing working width (WW) can be included in the set point calculation as a third value.

Indication:

---

P3011	Panel:		INT	
	Selection: see Parameter P3010	Range:	0-45	
Cold start:	01: Display			



Description:	Describes the source of nominal values for operation mode "Panel". This operation mode is usually used as manual mode if the superior control is inactive or if maintenance works have to be carried out at the weighing system.
Indication:	

P3012	Local:		INT
	Selection: see Parameter P3010	Range:	0-45
Cold start:	19: Al00		
Description:	Describes the source of nominal values for o usually activated as local mode via a switch direction.	•	
Indication:			

P3020	Panelcontrol:		INT
	Selection: 00: Panel 01: Button 02: Switch 03: KUKLA BA switch	Range:	0x00 - 0x03
Cold start:	00: Panel		
Description:	This parameter determines whether the operating buttons for start and stop of the main drive.	g unit in the panel mode pr	ovides the control
Indication:	This option should only be activated when control display without further controls, such as buttons of	•	d directly from the

P3021	Localcontrol:		INT
	Selection: 00: Unavailable 01: Button 02: Switch 03: KUKLA BA switch	Range:	0-3
Cold start:	00: Unavailable		
Description:	Just in case that a real local control is desired, this can be activated here. Thereby it can be determined if the control should be done via switch, button or a special operating mode switce from KUKLA.		•
Indication:	It must be noted that eventually existing auxiliary	drives must also be considered.	

P3051	Guiding value:			INT
	Unit:	Absolute	Range:	1-100000
Cold start:	10000			
Description:		ninal values determined by multiplication (eo 100% = 10 000) with "Scaling1".	e.g. "Lv x TV1") the first valu	ue is set to 100%
Indication:				

P3052	Guiding weight:		INT	
	Unit:	depending on P3072	Range:	1-100000



Cold start:	10000
Description:	At nominal values determined by multiplication (e.g. $_{\text{u}}$ Lv x TV1") the second value is set to 100% with this parameter.
Indication:	

P3053	Work Width:	INT		
	Unit: depending on P3073	Range:	1-100000	
Cold start:	10000			
Description:	At nominal values determined by multiplication calculation value, the third value is scaled to 100%	<u> </u>	n additional	
Indication:				

P3061 AC	CT Guiding value:		INT
	ection: 00: not Active	Range:	INT 0-25
	22: P4701 Fixed value 1 23:		
	24: Transfer value 1		
	25: Transfer value 2		

Cold start:	00: not Active
Description:	This parameter determines the source of the current guiding value. Usually, the recording is done directly via an analogue sensor (e.g. Al00) or via Fieldbus if this value is transmitted by a central control.
Indication:	<del></del>

P3063	ACT work width:		INT
	Selection: 00: not Active 01: Abs pre set1	Range:	0-25



```
02: Abs pre set2
                         03: Pr pre set1
                         04: Pr pre set2
                         05: ---
                         06: Bus 1 [%]
                         07: Bus 2 [%]
                         08: Bus 3 [%]
                         09: Bus 4 [%]
                         10: ---
                         11: Bus 1 [abs]
                         12: Bus 2 [abs]
                         13: Bus 3 [abs]
                         14: Bus 4 [abs]
                         15: ---
                         16: AI00
                         17: AI01
                         18: AI10
                         19: AI11
                         20: ---
                         21: P4702 Fixed value 2
                         22: P4701 Fixed value 1
                         23: ---
                         24: Transfer value 1
                         25: Transfer value 2
Cold start:
               00: not Active
Description:
               This parameter determines the source of the current working width.
Indication:
```

P3072	Unit guiding weight:	INT
	Selection: 0: [g/m²] 1: [kg/m²] 2: [l] 3: [%]	Range: 0-3
Cold start:	0: [g/m²]	
Description:	This parameter determines the unit in which t can be displayed and entered as a set point.	he guiding weight is defined and how this number
Indication:	In the insulating material production very ofte (g/m²), are prescribed.	n basis weights, such as grams per square meter

P3073	Unit work width:		INT
	Selection: 0: [mm] 1: [%]	Range:	0-1
Cold start:	0: [mm]		
Description:	This parameter determines in which unit this se and set point screens.	t point proportion is displayed in the o	operating
Indication:			

P3100 Regulator Limit: IN	NT
---------------------------	----



	Unit:	%		Range:	0,00 - 60,00
Cold start:	33,33				
Description:	This value determines up to which minimal load at discharge point g3 the speed of the driv motor for keeping the nominal value is readjusted.  If a value lower than the minimal value permitted by the "Integration range" is adjusted here, nominal value can be kept even for capacities below the nominal capacity.		,		
Indication:			of 100% cannot be eal speed of the dosing	fore, this possibili	ty only works up to

P3110	Regulator difference:		INT		
	Unit: %	Range:	0,00 - 20,00		
Cold start:	3,00				
Description:	If the difference between nominal value and a here, the error message "Deviation" appears.	ctual value is greater than t	he value adjusted		
Indication:					

P3120	Minimum Set Point:		INT		
	Unit: %	Range:	0,00 - 80,00		
Cold start:	10,00				
Description:	This parameter describes the lowest permitted plummets below this value, the associated error materials and the second se		ent nominal value		
Indication:	The nominal value 0 itself does not result in an err	ror message.			

P3130	Set to zero:		INT		
	Unit: %	Range:	0,00 - 50,00		
Cold start:	2,00				
Description:	This parameter describes the lowest permitted plummets below this value, it is automatically se		ent nominal value		
Indication:	This parameter permits a suppression of low sources of nominal values.	values and is primarily relev	ant for analogue		

P3170	Test-Tare Speed:		INT		
	Unit: %	Range:	0,00 - 120,00		
Cold start:	50,00				
Description:	The speed of taring and test with test weight from operational speed to the speed adjuprocedure.				
Indication:					

P3170	Test-Tare Speed:		INT
	Unit: %	Range:	0,00 - 100,00



Cold start:	50,00
Description:	The speed of taring and test with test weight is set with this parameter. The switchover from operational speed to the speed adjusted here is done after the start of the tare or test procedure.
Indication:	



### 4.3.1 P33xx Feeder Parameters

P3300	SetPoint Load:	INT
	Selection: 00: not Active	0-38
Cold start:	01: Pre set 1	
Description:	This parameter determines the source of nominal values for the feeder regulator. A p feeder will always try to achieve as much as possible the load adjusted here on the belt, in order to enable preferably small speed changes for the output dosing at belt. The load nominal value should ideally be in the middle of the permitted integration remains the source of the permitted integration.	e conveyor end.
Indication:	For controlled belt scales with an integration range of 1,0 this parameter is not rele it is tried to get as close as possible to a capacity value.	vant, since

P3305	Funct. at Off:		INT
	Selection: 00: last Value 01: Mean Value 02: SetPoint out	Range:	0-2



Cold start:	0
Description:	This parameter determines the behaviour of the feeder regulator in case of a missing control release (e.g. in case of plant stop). It can be determined with which dosing factor a restart is done.  For adjustment 0 the ratio for the feeder correcting variable will be set to the mean value between "Feeder-Min-Limit" and "Feeder-Max-Limit".  Alternatively, it is possible to keep the last calculated ratio or to take over the current nominal value.
Indication:	

P3310	Feeder	-Min-Limit:		INT
	Unit:	%	Range:	0,00 - 90,00
Cold start:	50,00			
Description:	value s Basical	lue determines the smallest possible fee maller than the value adjusted here, this ly, this limit should never be reached by message in the status/error message sys- mits.	s value is limited by the valu the feeder regulator in norma	le adjusted here.
Indication:				

P3312	Feeder-Max-Limit:		
	Unit: %	Range:	50,00 - 180,00
Cold start:	100,00		
Description:	This value determines the greatest possible feeder factor. If the feeder regulator calculates a value greater than the value adjusted here, this value is limited by the value adjusted here. Basically, this limit should never be reached by the feeder regulator in normal operation, thus, also a message in the status/error message system indicates that the feeder has reached one of the limits.		ralue adjusted here. mal operation, thus,
Indication:			

P3320	F RegulationLimit-DOWN:		
	Unit: %	Range:	50,00 - 100,00
Cold start:	70,00		
Description:	For adjustment 100% at each control process the entire deviation is reduced. If the feeder does not behave linearly to the feeder correcting variable, such as in case of a conveyor trough, an improvement of control behaviour can be obtained by reducing the readjustment factor.		
Indication:	Experience has shown that values between 70 a reassurance of the control process, since the feed		

P3322	F RegulationLimit-UP:		INT
	Unit: %	Range:	50,00 - 100,00
Cold start:	70,00		



Description:	This parameter is functionally equivalent to the previous parameter, but is responsible for delaying the feeder speed.
Indication:	Also here rather values between 70 and 90% should be used.

P3332	Feeder controller enable:	Т
	Selection: 00: not Active Range: 0- 01: Active 02: Greater min	-2
Cold start:	02: Greater min	
Description:	This parameter determines when and how the feeder regulator is enabled. This prevent undesired material flow at a change of the operation mode.	ts
Indication:	For the adjustment "01: Active" the release must be activated via the associated, digital command bit.	al

P3340	FeederEnableLevel:		INT
	Unit: %	Range:	50,00 - 100,00
Cold start:	20.00		
	30,00		
Description:	If the feeder is set to "02: Greater min ", the feed measuring length is greater than the value adjust		sed if the load of the
Indication:	This value should be adjusted to the set integration	on range.	

P3342	F- regular window:		
	Unit: %	Range:	50,00 - 100,00
Cold start:			
Description:	This parameter determines up to what percentage i changes are made, in order to avoid micro-vibration		nanipulated variable
Indication:			

P3350	Feeder delay way:		
	Unit: m	Range:	0,01 - 50,00
Cold start:	30,00		
Description:	At the end of the dead length the feeder reg	ulator always implements a reca	alculation.
Indication:	The distance between feeder and middle of measuring length in discharge direction plus approx. 10% reserve should be entered. In case of a stronger averaging of the weighing signal, this parameter has to be selected correspondingly longer.		

P3355	Fv_Follower:		INT	
	Unit:	Checkbox	Range:	0-1
Cold start:	0			
Description:	Parame	eter for special applications		



Indication: Only use after consultation with the manufacturer.

P3360	Pre-bin source:		INT
	Selection: see P3300	Range:	0-38
Cold start:	21: WC1		
Description:	This parameter determines the source of actual v	values of the pre-bin weight signal.	
Indication:			

P3362	DelayTime of Pre-bin:	IN'
	Unit: 8	Range: 1 - 50
Cold start:	2	
Description:	It is determined how fast the pre-bin control work executed.	ks. After this time a new regulation step i
Indication:		

P3368	PBv r	egulator:		INT
	Unit:	Checkbox	Range:	0-1
Cold start:	0			
Description:		be prescribed here that the pre-bin conveyor belt.	set point should act proportionally to the	actual speed
Indication:				



## 4.3.2 P36xx Automatic adjustment of the occupancy set point / AutoSg

P3600	Feeder reduction:		INT
	Selection: 00: not active 01: Pr pre set1 02: Pr pre set2 03: 04: Bus 1 [%] 05: Bus 2 [%] 06: Bus 3 [%] 07: Bus 4 [%] 08: Al00 09: Al01 10: Al10 11: Al11 12: Al00 x Al01 13: Al10 x Al11 14: Al01 x Bus 1 [%] 15: Al00 x Panel 16: Al01 x Panel 17: Bus 2 [%] x Panel 18: Bus 3 [%] x Panel 19: P4701 Fixed value 1 20: P4702 Fixed value 2 21: WC 1 22: WC 2 23: WC 3 24: WC 4 25: WC 5 26: Bin-Sim 27: PB total in pr 28: 29: 30: Transfer value 1 31: Transfer value 2 32: 33: DWC3/5 SW1 34: DWC3/5 SW2 35: DWC3/5 SW4 37: DWC3/5 SL1 38: DWC3/5 SL1 38: DWC3/5 SL1	Range:	0-38
Cold start:	00: not active		
Description:			
Indication:			

P3601	Sg at 20%:		INT
	Unit: %	Range:	0-100,00
Cold start:	50,00		
Description:	The desired occupancy set point at 20% This value is never fallen below and is in		
Indication:			



P3602	Sg at 100%:		INT
	Unit:	Range:	0-100,00
Cold start:	40,00		
Description:		00% nominal capacity must be set here. interpolated downwards to the 20% value	
Indication:	This value should be adjusted to the	set integration range.	
P3605	Total time:		INT
	Unit: s	Range:	10-1000
Cold start:	300		
Description:	Describes the total time after which a	new regulation step is performed.	
Indication:			
P3610	Step minus:		INT
	Unit: S	Range:	10-1000
Cold start:	200		
Description:	Defines when the set point should be reduced by one step value (0,1). If the reduction probe is covered longer than the here set number of seconds within a total time, the correction factor will immediately be reduced by 0,1% after the expiration of the total time.		
Indication:	This value must be absolutely <b>greate</b>	r than "Step plus"!	
P3611	Step plus:		INT
	Unit: S	Range:	10-1000
Cold start:	10		
Description:	Defines when the set point should be increased by one step value (0,1). If the reduction probe is covered less than the here set number of seconds within a total time, the correction factor will immediately be increased by 0,1% after the expiration of the total time.		
Indication:	This value must be absolutely less the	nan "Step minus"!	

P3615	Max Step:		INT
	Unit: %	Range:	10-100,00
Cold start:	10,00		
Description:	With this parameter the correction value in negative direction.	e can be limited. This value acts in po	sitive as well as
Indication:	This value should be adjusted to the se	t integration range.	

The regulation time only counts when the conveyor belt RUNS and the actual load g1 is greater than the "feeder release" percentage value.

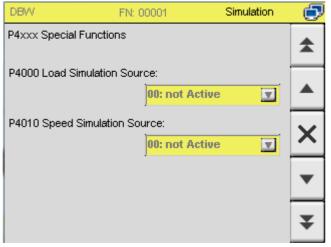


If the actual load g1 falls below the adjusted release threshold, the correction factor is set to 0. Thereby, the entire system will start from a neutral level and so it is able to find again the perfect level by itself.

P3620	Auto S	Sg Correction 1	:		INT
P3621	Auto S	Sg Correction 2	2:		INT
	Unit:	%		Range:	10-100,00
Cold start:	10,00				
Description:		•	allow an increase or rec	duction of the setpoint value for υ al input.	ip to 2 different
Indication:	-				

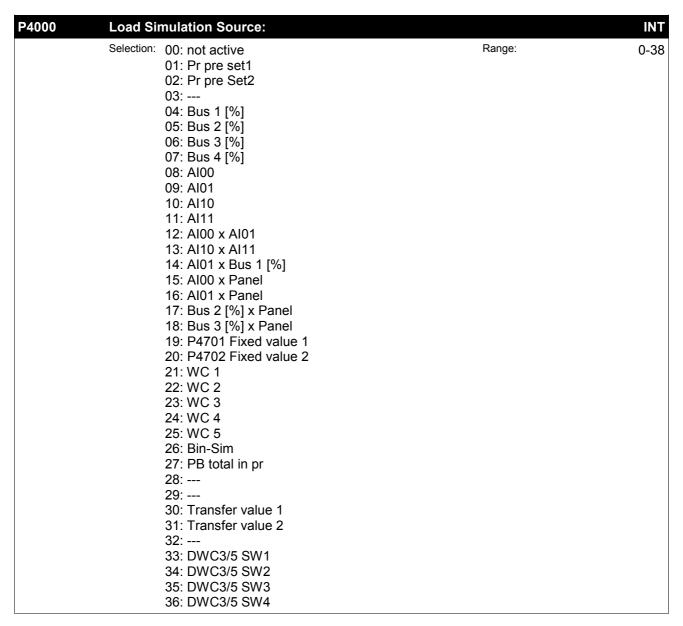


### 4.4 Parameter group P4xxx / Special functions



The parameter group "Special functions" includes parameters, which cannot be allocated to another group.

Mostly, they describe special options of the weighing system, which are primarily needed for specific special applications.





	37: DWC3/5 SL1 38: DWC3/5 SL2
Cold start:	00: not active
Description:	This parameter describes the source of nominal values for a weight simulation.  This option permits an emergency operation of weigh feeders or is sometimes also used for presentations and Fieldbus tests of weighing systems, in order to simulate a not existing load cell.
Indication:	

P4010	Speed Simulation Source:		INT
	Selection: see previous parameter	Range:	0-38
Cold start:	00: not active		
Description:	This parameter describes the source of nominal values for a speed simulation.  This option permits an emergency operation of weigh feeders or is sometimes also used presentations and Fieldbus tests of weighing systems, in order to simulate a not existing tachometer.		
Indication:	The speed simulation is only active if the associa 0-simulation is done. For impact flow meters a speed simulation is abshave a tachometer. The feedback is usually derive	olutely necessary, since these de	evices do not

## 4.4.1 P41xx Electric or pneumatic belt steering control

P4100	Belt steering device:		INT
	selection: 00: inactive 01: Delaytime regulator 02: 2-Point control 03: Electrical steering device	Range:	0-3
Cold start:	00: inactive		
Description:	Belt steering devices are able to reliably prevent a lateral leaving of a conveyor belt's permitt working area. It is important to distinguish if it is a pure mechanic solution (adjustment "inactive") or an electric / pneumatic solution.  In this case it is distinguished whether only one belt edge is scanned ("01: Delaytime regulato whereby the belt steering signal counter regulates automatically after a period adjustable in following parameters, or whether there is really a switchover between the sensors of each soft the belt.		justment "00: ne regulator"), ustable in the
Indication:	It must be noted that the correct digita	inputs and outputs are used.	
Dependency:	Binary inputs for belt steering sensors Binary output for belt steering signal (I	(P60xx) or via Fieldbus Bus Command P64xx) or via Fieldbus BusControlBits	

P4110	Steering delay off:		INT
	Unit: s	Range:	-1 - 600
Cold start:	2,0		



Description:	This parameter describes after how many seconds at the adjustment "01: Delaytime regulator" in the previous parameter the automatic counter regulation starts.
Indication:	<del></del>

P4111	Steering delay on:		INT
	Unit: s	Range:	-1 - 600
Cold start:	2,0		
Description:	This parameter describes after how many in parameter P4100 the steering direction v		aytime regulator"
Indication:			

P4120	Delayt	ime v=100%:		INT
	Unit:	S	Range:	-1 - 600
Cold start:	0,0			
Description:	This pa	arameter describes the delay	time between two steering commands.	
Indication:				

P4121	Working time:			INT	
	Unit:	S	Range:	-1 - 600	
Cold start:	0,0				
Description:	This pa	arameter describes the	duration of the active time per steering command.		
Indication:					

### 4.4.2 P413x Loosening injector

Belt Weighers often convey material with difficult flow properties. Air injectors or vibrators are often used to improve that flow properties. These systems can be controlled directly via the corresponding output. The timing of this output can be controlled by the following parameter group.

P4130	Loosening injector active:	INT
	Unit: s	Range:
Cold start:	0.0 s	
Description:	Duration of the on signal	
Indication:	The value usually determines the air volume fo	r air injectors.

P4132	Loosening injector delaytime:			INT
	Unit:	s	Range:	
Cold start:	0.0 s			
Description:	Duratio	n of the pause time between two on-signals		



Indication:

P4134	Loosening injector min limit:	INT
	Unit: %	Range:
Cold start:	0.0 s	
Description:	material on / in the measuring syste	of the material are very different. If there is already a lot of em, an additional loosening would be counterproductive. eter, the loosening output will be DEACTIVATED to prevent
Indication:	0.0 disables this function	

#### 4.4.3 P414x Cleaning device



A cleaning device is usually made of scratch strips on both sides guided by chains.

This device is arranged underneath the conveyor belt and thus allows to remove dropped product.

The following parameters determine how often and for how long the drive of the cleaning system is switched on and off.

P4140	Cleaning device active:		
	Unit: Min.	Range:	0-999
Cold start:	0		
Description:	Duration of ON-period (cleaning is run	ning)	
Indication:			

P4142	Cleaning device delaytime:		INT
	Unit:	Min.	Range:
Cold start:	0		
Description:	Duratio	on of the OFF period (cle	eaning process stopped)
Indication:	accum		e chosen too high as otherwise very much dust may have shed directly into the discharge area and thus leads to a higher me!

## 4.4.4 P415x Slip tachometer



Unlike to commercial evaluation systems, slip detection is not implemented on time basis, but distance based.

P4150	Slip tacho:			
	Unit:	Pulses	Range:	1- 100000
Cold start:	0			
Description:	Therel more t	by the number of tacho pulse	a run monitoring can be realised. s is adjusted, after which one control pul e are counted, the corresponding status r	
Indication:				

### 4.4.5 P419x AW g Config (Area weight display)

Sometimes, instead of the typical weight display for the material load in percent, an alternative display of, for example, g / m2 or kg / m3 is desired. This can be realized with the following parameters.

P4190	AW g weight:	INT
	Unit:	Range:
Cold start:	0	
Description:	This parameter determines which a output value.	absolute number corresponds to 100% of the measured
Indication:		

P4192	AW g unit:		
	Selection: 0: 1[g/m²] 1: 0,01[kg/m²] 2: 0,1[kg/m²] 3: 1[kg/m²] 4: 1[l]	Range:	0-4
Cold start:	0		
Description:	This parameter defines the unit and the comma sc	aling of the desired value.	
Indication:			

P4194	Grafikbildanzeige:			INT
	Auswahl:	0: inaktiv 1: AW p 2: AW g1 3: AW p / AW g1	Bereich:	0-3
Kaltstart:				
Beschreibung:	This par	ameter defines which	value is used as the basis for the display.	
Hinweis:		sible to select both, the nthe graphic screen.	e material load and the flow capacity as the basis for the des	sired



# 4.4.6 P42xx Weighing bin

This parameter group allows the additional integration of a container which is equipped with a level measurement.

P4200	Bin 100%:		INT
	Unit: g	Range:	0-100000
			_
Cold start:	0		
Description:	This parameter describes the nominal range of a weighin instance, for a checkweigher.	g bin, which might b	e used for
Indication:			

P4202	Display unit bin:		INT
	Selection: 00: [g] 01: [kg] 02: [t]	Range:	0-2
Cold start:	00		
Description:	The display unit is already roughly defined by the size of the bin. While the setting 00: [g] can be meaningful for very small bins, this would not make sense for a huge bin with many tonnes.		
Indication:			

P4205	WC nu	umber for container:		INT
	Unit:	Absolut	Range:	0-4
Cold start:	0			
Description:	This parameter describes the number of weighchannels used for the weighing bin.			
Indication:				

P4210	Fill on:		INT
	Unit: %	Range:	0-150,00
Cold start:	0,00		
Description:	Limit for the activation of the weighing bin refilling.		
Indication:			

P4215	Fill off:		INT
	Unit: %	Range:	0-150,00
Cold start:	0,00		
Description:	Limit for the deactivation of the weighing bin refilling.		
Indication:			



P4220	Bin empty at:		INT
	Unit: %	Range:	0-150,00
Cold start:	0,00		
Description:	Limit for the empty detection of the weighing bin.		
Indication:			

#### 4.4.7 P43xx Checkscale

P4300	Checkscale:		INT
	Selection: 00: inactive 01: Checkscale active	Range:	0-1
Cold start:	00: inactive		
Description:	This option enables the semi-automatic correction of the weighing system via a re-measuring by a pre-installed weighing bin. The real correction must be initiated via a binary input.		
Indication:	The application of this option requires a very specific structure of the entire system.		



## 4.4.8 P45xx Batchmode Parameters

P4510	Batch Setpoint Internal:	INT
P4511	Batch Setpoint External:	INT
	Selection: 00: not Active	0-16
Cold start:		
Description:	This parameter determines the source of nominal values for the internal/external batch	set point.
Indication:	Percentages like at the selection "02: Panel %" are not useful. It is only reasonable absolute values.	e to use

P4520	Pre-switch-off-quantity1:				
P4521	Pre-switch-off-quantity2:			INT	
P4522	Pre-switch-off-quantity	3:		INT	
P4523	Pre-switch-off-quantity	4:		INT	
	Unite: depending on F	21310	Range:	0-100000	
Cold start:					
Description:	These parameters deterr	nine the source of nominal val	lues for the external bat	ch set point.	
Indication:	Percentages like at the selection "02: Panel %" are not useful. It is only reasonable to use absolute values.				

P4530	Post-Runtime: INT		
	Unit: S	Range:	-1 - 600
Cold start:	2,0		
Description:	This parameter describes how long the after EMPTY was recognized at g3-poi	conveyor drive of the weighing system r nt.	emains activated
Indication:			



## 4.4.9 P47xx Fixed and Transfervalues

P4701	Fixed value 1:		INT
P4702	Fixed value 2:		INT
	Unit: %	Range:	0,00 - 150,00
Cold start:	0,00		
Description:	These parameters permit the deposit of fix adjustican be used in almost all nominal value selection 1" or "31: Fixed value 2".		
Indication:	As pre-set nominal value this parameter can relia in normal operation mode.	ably prevent a subsequent	change by the user

P4711	Transfer value 1:		INT
P4712	Transfer value 2:		INT
	Selection: 00: not active 01: Pr pre set1 02: Pr pre set2 03: 04: Bus 1 [%] 05: Bus 2 [%] 06: Bus 3 [%] 07: Bus 4 [%] 08: Al00 09: Al01 10: Al10 11: Al11 12: Al00 x Al01 13: Al10 x Al11 14: Al01 x Bus 1 [%] 15: Al00 x Panel 16: Al01 x Panel 17: Bus 2 [%] x Panel 18: Bus 3 [%] x Panel 19: P4701 Fixed value 1 20: P4702 Fixed value 2 21: WC 1 22: WC 2 23: WC 3 24: WC 4 25: WC 5 26: Bin-Sim 27: PB total in pr 28: 29: 30: 31: 31: 32: 33: DWC3/5 SW1 34: DWC3/5 SW2 35: DWC3/5 SW4 37: DWC3/5 SL1 38: DWC3/5 SL1 38: DWC3/5 SL2	Range:	0-46



39: ---40: Bus ABS 1 41: Bus ABS 2 42: Bus ABS 3 43: Bus ABS 4 44: ---45: BCD0 46: BCD1 Cold start: 00: not active Description: These parameters allow setpoint formation from the listed sources. Indication: The two transfer values can then in turn be used as setpoint sources for analog outputs or fieldbus communication. This results in an extremely flexible structure as data can be passed on.



## 4.4.10 P48xx Linearisation - Parameter

P4800	Lineartable 0:		INT
	Unit: %	Range:	-50,00 - 50,00
Cold start:	0,00		
Description:	Some weighing systems have due to the internal st weight signal. The parameter group P48xx permi signal subtractive as well as additive.  Each parameter is responsible for a specific weight	ts a corresponding adap	
Indication:	If a measured actual weight is between two characters done. Thus, the Linearisationtable, which is locate more.		
P4801	Lineartable 1:		INT
Description:	see P4800 / Parameter is relevant for load raw sign	als of 8.0%.	
P4802	Lineartable 2:		INT
Description:	see P4800 / Parameter is relevant for load raw sign	als of 16.0%.	
P4803	Lineartable 3:		INT
Description:	see P4800 / Parameter is relevant for load raw sign	als of 24.0%.	
P4804	Lineartable 4:		INT
Description:	see P4800 / Parameter is relevant for load raw sign	als of 32.0%.	
P4805	Lineartable 5:		INT
Description:	see P4800 / Parameter is relevant for load raw sign	nals of 40.0%.	
P4806	Lineartable 6:		INT
Description:	see P4800 / Parameter is relevant for load raw sign	nals of 48.0%.	
P4807	Lineartable 7:		INT
Description:	see P4800 / Parameter is relevant for load raw sign	nals of 56.0%.	
P4808	Lineartable 8:		INT
Description:	see P4800 / Parameter is relevant for load raw sign	nals of 64.0%.	
P4809	Lineartable 9:		INT
Description:	see P4800 / Parameter is relevant for load raw sign	nals of 72.0%.	
P4810	Lineartable 10:		INT
Description:	see P4800 / Parameter is relevant for load raw sign	nals of 80.0%.	

INT

P4811

Lineartable 11:



Description:	see P4800 / Parameter is relevant for load raw signals of 88.0%.	
P4812	Lineartable 12:	INT
Description:	see P4800 / Parameter is relevant for load raw signals of 96.0%.	
P4813	Lineartable 13:	INT
Description:	see P4800 / Parameter is relevant for load raw signals of 104.0%.	
P4814	Lineartable 14:	INT
Description:	see P4800 / Parameter is relevant for load raw signals of 112.0%.	
P4815	Lineartable 15:	INT
Description:	see P4800 / Parameter is relevant for load raw signals of 120.0%.	
P4816	Lineartable 16:	INT
Description:	see P4800 / Parameter is relevant for load raw signals of 128.0%.	
P4817	Lineartable 17:	INT
Description:	see P4800 / Parameter is relevant for load raw signals of 136.0%.	



## 4.4.11 P485x Subtraction system

P4850	Sub g:		INT
		00: not active 01: Pr pre set1 02: Pr pre set2 03: 04: Bus 1 [%] 05: Bus 2 [%] 06: Bus 3 [%] 07: Bus 4 [%] 08: Al00 09: Al01 10: Al10 11: Al11 12: Al00 x Al01 13: Al10 x Al11 14: Al01 x Bus 1 [%] 15: Al00 x Panel 16: Al01 x Panel 17: Bus 2 [%] x Panel 18: Bus 3 [%] x Panel 19: P4701 Fixed value 1 20: P4702 Fixed value 2 21: WC 1 22: WC 2 23: WC 3 24: WC 4 25: WC 5 26: Bin-Sim 27: PB total in pr 28: 29: 30: Transfer value 1 31: Transfer value 2 32: 33: DWC3/5 SW1 34: DWC3/5 SW2 35: DWC3/5 SW4 37: DWC3/5 SW4 37: DWC3/5 SL1 38: DWC3/5 SL1 38: DWC3/5 SL2	0-38
Cold of att	00 1		
Cold start:	00: not a		
Description:	Normally	rameter is used when several belt scales are installed in the same conveyor, the following belt weigher always measures the material of the previous belt we parameter, a net display can be realized.	
Indication:	net displ	he internal complexity of such a net system, it is strongly discouraged to use it ays can be realized much more easily in modern visualization systems and PLC ameter has been mainly integrated for compatibility with previous devices.	



# 4.4.12 P486x Dry weight calculation

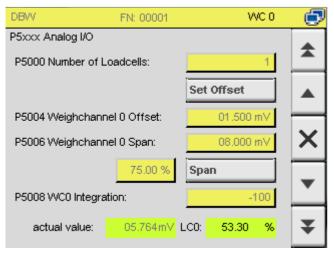
P4860	Moisture source:		INT
	Selection: see P4850	Range:	0-38
Cold start:	00: not active		
Description:	If the weighing system should detect the dr here. This parameter determines which sour is usually determined by a product moisture Alternatively, this value also can be transmit	ce is used for the actual moisture val sensor, which is connected via an a	ue. This value
Indication:	A dry weight calculation without continuous	moisture sensor is usually not reason	nable.

P4862	Moisture baselevel:		INT
	Unit: %	Range:	0,00 - 50,00
Cold start:	0,00		
Description:	The basic moisture adjusted here is always sub This is done independently from the measured ad		
Indication:			

P4864	Moisture spanlevel:		INT
	Unit: %	Range:	0,00 - 80,00
Cold start:	0,00		
Description:	The moisture range adjusted here is moisture sensor additionally to the bar from the measured moisture weight if	. 0,	value is subtracted
Indication:			



# 4.5 Parameter group P5xxx / Analog I/O



The parameter group "Analog I/O" includes all parameters, which are relevant for the connected load cell inputs as well as for the conventional analogue inputs and outputs.

### 4.5.1 P50xx Weighchannel - Parameters

P5000	Number of Loadcells:		
	Unit: Absolute	Range:	1-4
Cold start:	1		
Description:	This parameter describes how many low weight on the measuring length (main measurements, such as pre-bin weight or	neasuring). All following load cells are	
Indication:			
P5004	Weighchannel 0 Offset:		INT
P5014	Weighchannel 1 Offset:		INT
P5024	Weighchannel 2 Offset:		INT
P5034	Weighchannel 3 Offset:		INT
P5044	Weighchannel 4 Offset:		INT
P5054	Weighchannel 5 Offset:		INT
<u>-</u>	Unit: mV	Range:	0,550 - 10,000
Cold start:	1,000		
Description:	This parameter describes the zero point Via the grey key "Set Offset" the actually the parameter.		y transferred into
Indication:	How many load cell cards are inserted?	(R9500)	
-D.F.0.0.0			
P5006	Weighchannel 0 Span:		INT
P5016	Weighchannel 1 Span:		INT
P5026	Weighchannel 2 Span:		INT



P5036	Weighchannel 3 Span:		INT
P5046	Weighchannel 4 Span:		INT
P5056	Weighchannel 5 Span:		INT
	Unit: mV	Range:	0,500 - 12,000
Cold start:	2,000		
Description:	This parameter describes the measuring span (1009). Via the grey key "Span" the actually measured value parameter. Thereby the value is automatically scale.	e can be automatically to	ransferred into the
Indication:	This parameter is the most important parameter system. In general, a reduction of the parameter caresp. counts MORE. Vice versa a raise of the parameters LESS, since due to the higher measurin necessary.	auses that the weighing rameter causes that the	system measures weighing system
P5008	WC0 Integration:		INT
P5018	WC1 Integration:		INT
P5028	WC2 Integration:		INT
P5038	WC3 Integration:		INT
P5048	WC4 Integration:		INT
P5058	WC5 Integration:		INT
	Unit: Absolute	Range:	-1000 - 1000
Description:	This parameter permits the smoothing of the input signal.  Positive numbers smooth the signal by means of an additive averaging. Continuously, n-values are added and after expiration it is divided by this number.  With negative values, the steepness of a signal change can be limited. Thus, small changes are completely controlled and larger changes are limited.		
Indication:	This parameter is only offered if the associated inp system.		recognized by the
P5019	WC1 Tara:		INT
P5029	WC2 Tara:		INT
P5039	WC3 Tara:		INT
P5049	WC4 Tara:		INT
P5059	WC5 Tara:		INT
	Unit: Checkbox	Range:	0/1
Cold start:	0		
Description:	Describes how the tare of a weighing canal is forme This may vary depending on the application. (e.g. B		detection)
	, , , , , , , , , , , , , , , , , , , ,		,



## 4.5.2 P52xx Analog input channels - Parameters

P5202	Al 00 Signaltype:		INT
P5212	Al 01 Signaltype:		INT
P5222	Al 10 Signaltype:		INT
P5232	Al 11 Signaltype:		INT
	Selection: 00: U / Voltage 01: I / Current (mA)	Range:	0-1
Description:	This parameter describes the operation mode of the It is possible to select between voltage signal (V) ar noted that also the input contact on the card is different contact.	nd current signal (mA), where	
Indication:	This parameter is only offered if the associated input system.	out card is inserted and reco	ognized by the
Dependency:	Analog input card inserted? (R9520)		
P5204	Al 00 Offset:		INT
P5214	Al 01 Offset:		INT
P5224	Al 10 Offset:		INT
P5234	Al 11 Offset:		INT
	Unit: Absolute	Range:	-200 - 5000
Description:	This parameter describes the zero point of the responsible to the grey key "Set Offset" the actually measured the parameter.  If a 420mA - output is desired, this parameter has to set the basic signal to 4mA.	value can be automatically t	ransferred into
Indication:	This parameter is only offered if the associated inpaystem.	out card is inserted and reco	ognized by the
P5206	ALOO Coope		INT
P5216	Al 00 Span: Al 01 Span:		INT INT
P5216	Al 10 Span:		INT
P5236	Al 11 Span:		INT
1 3230	Unit: Absolute	Range:	1000 - 12000
Description:	This parameter describes the range of the output span of the respective analogue input channel. Via the grey key "Span" the actually measured value (full scale deflection) can be automatically transferred into the parameter.  If a 420mA - output is desired, this parameter has to be adjusted to 8000 (80.00%), in order to set the working range of the signal to 16mA.		
Indication:	This parameter is only offered if the associated inpaystem.	out card is inserted and reco	ognized by the
DE200	AL 00 Integrations		_INT
P5208	Al 00 Integration:		INT
P5218	Al 01 Integration:		INT



P5228	Al 10 Integration: Al 11 Integration:		INT
P5238			INT
	Unit: Absolute	Range:	-1000 - 1000
Description:	This parameter permits the smoothing of the input signal.  Positive numbers smooth the signal by means of an additive averaging. Continuously, n-valu are added and after expiration it is divided by this number.  With negative values, the steepness of a signal change can be limited. Thus, small chang are completely controlled and larger changes are limited.		
Indication:	This parameter is only offered if the associated system.	input card is inserted and	recognized by the

# 4.5.3 P55xx Analog output channels - Parameters

P5500	AO 00:		INT
P5510	AO 01:		INT
P5520	AO 02:		INT
P5530	AO 03:		INT
P5540	AO10:		INT
P5550	AO11:		INT
P5560	AO12:		INT
P5570	AO13:		INT
	Selection: 00: P3 Capacity 01: Feeder setpoint 02: Drive WB 03: 0% output 04: 50% output 05: 100% output 06: g1-load 07: g2-load 08: g3-load 09: Scaling 2 10: Setpoint output 11: P2 Capacity 12: P1 Capacity 13: Deviation % 14: Batch Finestream 15: Feeder Deviation 16: g3 - brutto-Load 17: Transfervalue 1 18: Transfervalue 2 19: Brutto-Load 20: Bin Load % 21: PreBin-Regulator 22: Speed 23: AW 24: Test weight 25: g1RR-Load 26: g1R-Load 27: g1L-Load	Range:	0-31



	28: g1LL-Load		
	29: g1 total [g]		
	30: g3 total [g] 31:		
	J1		
Cold start:	06: g1-load		
Description:	This parameter determines the output signal,	which is displayed on the channel.	
Indication:	This parameter is only offered if the associate system.	ed output card is inserted and reco	gnized by the
Dependency:	Analog output card inserted? (R9550)		
P5502	AO 00 Signaltype:		INT
P5512	AO 01 Signaltype:		INT
P5522	AO 02 Signaltype:		INT
P5532	AO 03 Signaltype:		INT
P5542	AO10 Signaltype:		INT
P5552	AO11 Signaltype:		INT
P5562	AO12 Signaltype:		INT
P5572	AO13 Signaltype:		INT
	Selection: 00: U / Voltage 01: I / Current (mA)	Range:	0-1
Description:	This parameter describes the operation mode It is possible to select between voltage sign noted that also the output pin on the card is contact.	al (V) and current signal (mA), whe	
Indication:	This parameter is only offered if the associate system.	ed output card is inserted and reco	gnized by the
P5504	AO 00 Offset:		INT
P5514	AO 01 Offset:		INT
P5524	AO 02 Offset:		INT
P5534	AO 03 Offset:		INT
P5544	AO10 Offset:		INT
P5554	AO11 Offset:		INT
P5564	AO12 Offset:		INT
P5574	AO13 Offset:		INT
	Unit: Absolute	Range:	0 - 5000
Description:	This parameter describes the zero point of the If a 420mA - output is desired, this parameter set the basic signal to 4mA.		
Indication:	This parameter is only offered if the associat system.	ed output card is inserted and reco	gnized by the



P5506	AO 00 Span:		INT
P5516	AO 01 Span:		INT
P5526	AO 02 Span:		INT
P5536	AO 03 Span:		INT
P5546	AO10 Span:		INT
P5556	AO11 Span:		INT
P5566	AO12 Span:		INT
P5576	AO13 Span:		INT
	Unit: Absolute	Range:	0 - 10000
Description:	This parameter describes the range of the output channel.  If a 420mA - output is desired, this parameter has set the working range of the signal to 16mA.	•	
Indication:	This parameter is only offered if the associated output card is inserted and recognized by the system.		
P5508	AO 00 Integration:		INT
P5518	AO 01 Integration:		INT
P5528	AO 02 Integration:		INT
P5538	AO 03 Integration:		INT
P5548	AO10 Integration:		INT
P5558	AO11 Integration:		INT
P5568	AO12 Integration:		INT
P5578	AO13 Integration:		INT
	Unit: Absolute	Range:	-1000 - 1000
Description:	This parameter permits the smoothing of the output signal.  Positive numbers smooth the signal by means of an additive averaging. Continuously, n-values are added and after expiration it is divided by this number.  With negative values the steepness of a signal change can be limited. Thus, small changes are completely controlled and larger changes are limited.		
Indication:	This parameter is only offered if the associated our system.		ecognized by the



### 4.5.4 P58xx MoviMot - Parameters

The following parameter group describes the direct control of a SEW-MoviMot frequency converter via RS485 communication module. Logically, the control is primarily comparable to an analog output. Instead of a volt or milli-amp signal, the digital value is transmitted digitally.

Offset, span and averaging can be adapted for signal optimization as with a conventional analog output. The first communication card MM1yx can control two MoviMots (MM00 - MM01).

The second communication card MM2yx can also control two MoviMots (MM02 - MM03).

P5800	MM00 set value:	INT
P5810	MM01 set value:	INT
P5820	MM10 set value:	INT
P5830	MM11 set value:	INT
	Selection: 00: P3 Capacity 01: Feeder setpoint 02: Drive WB 03: 0% output 04: 50% output 05: 100% output 06: g1-load 07: g2-load 08: g3-load 09: Scaling 2 10: Setpoint output 11: P2 Capacity 12: P1 Capacity 13: Deviation % 14: Batch Finestream 15: Feeder Deviation 16: g3 - brutto-Load 17: Transfervalue 1 18: Transfervalue 2 19: Brutto-Load 20: Bin Load % 21: PreBin-Regulator 22: Speed 23: AW 24: Test weight 25: g1RR-Load 26: g1R-Load 27: g1L-Load 29: g1 total [g] 30: g3 total [g] 31:	0-31
Cold start:	00: P3 Capacity	
Description:	This parameter determines the output signal, which is transferred as number	
Indication:	Most common Setpoints are no 03: for the Conveyor Belt drive and 01: for a	feeder setpoint
Dependency:	This parameter is only offered if the associated MoviMot card is plugged in an system.	d detected by the



P5831   MM10 switch on by:   INT
Selection: 00;   Range: 0.95
01: Warning 02: Ready to operate 03: Stopped 04: Empty 05: g3 - min load 06: g3 - max load 07: Panel 08: Remote 09: Deviation 10: Slip 11: Test/tare runs 12: Lay on testweight 13: Main drive on 14: Feeder on 15: Feeder reduction 16: Direction 17: Feeder open 18: Feeder closed 19: REM/RDY 20: Motor scale 21: Batch enable 22: Coarse stream 23: Fine stream 24: 25: Filling weighing bin 26: Bin empty 27: Movement error 28: Deviation detected 29: 30: Counter signal 31: Live bit 32: Fieldrelais1 33: Fieldrelais3 35: Fieldrelais3 35: Fieldrelais4 36: Fieldrelais5
37: Fieldrelais6 38: Fieldrelais7 39: 40: 41: Steering-Command 42: 43: Belt misrun 44:



	54: XD4 Auxiliary drive 4 on 55: XD5 Auxiliary drive 5 on		
	56:		
	57:		
	58: Parmode active 59: Save parameters		
	60: Bin max		
	61: Bin min		
	62: SF Main drive on 1		
	63: SF Main drive on 2 64 – 87:		
	88: BCD0_Scan_XXX1		
	89: BCD0_Scan_XX1X		
	90: BCD0_Scan_X1XX		
	91: BCD0_Scan_1XXX 92: BCD1_Scan_XXX1		
	93: BCD1_Scan_XX1X		
	94: BCD1_Scan_X1XX		
	95: BCD1_Scan_1XXX		
Cold start:	00:		
Description:	This parameter describes the enable signal (ON) with stopped.	which the MoviMot	drive is started and
Indication:	The most common setpoints are number 13: for the m arbiter.	ain drive and 14: for	the MoviMot of the
Dependency:	This parameter is only offered if the associated MoviMosystem.	ot card is plugged in a	and detected by the
P5802	MM00 Direction of rot:		INT
P5812	MM01 Direction of rot:		INT
P5822	MM10 Direction of rot:		INT
P5832	MM11 Direction of rot:		INT
	Selection: 00: CW (clockwise) 01: CCW (counter clockwise)	Range:	0-1
Cold start:	00: CW		
Description:	Depending on the mechanical arrangement of the determined so that the conveyor belt or the screw turned		
Indication:	It is not possible to change the phase sequence on the	: MoviMot!	
P5804	MM00 Offset:		INT
P5814	MM01 Offset:		INT
P5824	MM10 Offset:		INT
P5834	MM11 Offset:		INT
	Unit:	Range:	-1000 - +1000
Cold start:	0		
Description:	This parameter defines the zero point of the MoviMot of	channel.	



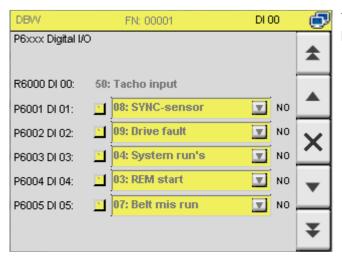
Indication:	The output signal is normalized as a number from 0 - 10000 for 0.00 -100.00%.
Dependency:	This parameter is only offered if the associated MoviMot card is plugged in and detected by the system.

Dependency:	This parameter is only offered if the associated MoviMot card is plugged in and detected by the system.		
Indication:	The output signal is normalized as a number from 0 - 10000 for 0.00 -100.00%.		
Description:	This parameter defines the span of the MoviMot channel.		
Cold start:	10000		
	Offit.	Kange.	8000 – 12000
P5836	MM11 Span: Unit:	Range:	INT
P5826	MM10 Span:		INT
P5816	MM01 Span:		INT
P5806	MM00 Span:		INT

P5808	MM00 Integration:		INT
P5818	MM01 Integration:		INT
P5828	MM10 Integration:		INT
P5838	MM11 Integration:		INT
	Unit:	Range:	-1000 - 1,000
Description:	-1		
Indication:	This parameter permits the smoothing of the output signal.  Positive numbers smooth the signal by means of an additive averaging. Continuously, n-values are added and after expiration it is divided by this number.  With negative values the steepness of a signal change can be limited. Thus, small changes are completely controlled and larger changes are limited.		
Dependency:	This parameter is only offered if the associ	iated MoviMot card is plugged in a	and detected by the



# 4.6 Parameter group P6xxx / Digital In- and Output



The parameter group "**Digital I/O**" permits the parameterisation of all digital inputs and outputs.

## 4.6.1 P60xx Digital inputs - Parameters

R6000	DI 00:		INT
	Selection: 50: Tacho input	Range:	50
Cold start:			
Description:	This parameter describes the tacho input.		
Indication:	For internal reasons the tacho has to be located by the user.	d on the DI00-channel and CANNOT be	changed

P6001	DI 01:			INT
	Selection:	00: 01: Counter B clear 02: Counter C clear 03: REM start 04: System runs 05: Remote 06: Panel 07: Belt mis run 08: SYNC-Sensor 09: Drive fault 10: Delete errors 11: Panel start 12: Field input 1 13: Field input 2 14: Field input 3 15: Field input 4 16: Field input 5 17: Field input 6 18: Field input 7 19: Live Bit 20: Tension cleaning chain 21: Start >0< 22: Start TEST (Testweight)	Range:	0-127



23: Start Materialtest 24: Suspend measuring 25: Enable regulator 26: Feeder reduction 27: JOG Feeder 28: ---29: Refilling Indicator 30: Start Batch 31: Interrupt Batch 32: Emptying system 33: Fine stream 34: Batch Remote setpoint 35: Feedingchannel x 01 36: Feedingchannel x 02 37: Panel stop 38: Counting at g2 39: Calculate dry material 40: Adapt span 41: ---42: Belt misrun LEFT 43: Belt misrun RIGHT 44: Beltedgesensor on 45: Beltedgesensor off 46: Steering dev extended 47: Steering dev retracted 48: --49: Slipdetection 50: Tacho input (not usable!) 51: Emergency device 52: ---53: ---54: Drive lock 55: Local 56: LOC start 57: LOC stop 58: Central operation 59: ---60: JOG main drive 61: ---62: ---63: ---64: Channel 1 start 65: Channel 1 stop 66: ---67: ---68: Channel 2 start 69: Channel 2 stop 70: ---71: ---72: Channel 3 start 73: Channel 3 stop 74: ---75: ---76: Channel 4 start 77: Channel 4 stop 78: ---79: ---80: Channel 5 start 81: Channel 5 stop



Cold start: Description: Indication:
Description:
P6003
Indication:
Description:
Cold start:
P6002
Indication:
Description:
Cold start:

Range:

0-127

Selection: see P6001



Cold start:	00:		
Description:		DIO4 is used in the weighing ave	
Indication:	This parameter describes how the digital input	Dio4 is used in the weighing sys	tem.
indication.	This input is arranged on the TM1yx card.		
P6005	DI 05:		INT
	Selection: see P6001	Range:	0-127
Cold start:	07: Belt mis run		
Description:	This parameter describes how the digital input	DI05 is used in the weighing sys	tem.
Indication:	This input is arranged on the TM1yx card.		
P6010	DI 10:		INT
P6011	DI 11:		INT
P6012	DI 12:		INT
P6013	DI 13:		INT
	Selection: see P6001	Range:	0-127
Cold start:	00:		
Description:	This parameter describes how the digital input DI10 – DI13 is used in the weighing system.		
Indication:	This input is arranged on the first DI1yx card.		
P6020	DI 20:		INT
P6021	DI 21:		INT
P6022	DI 22:		INT
P6023	DI 23:		INT
	Selection: see P6001	Range:	0-127
Cold start:	00:		
Description:	This parameter describes how the digital input	s DI20 - DI23 are used in the wei	ghing system.
Indication:	These inputs are arranged on the second DI2 the system.	yx card if this card is inserted and	recognized by
Dependency:	Input card inserted? (R9600)		
P6030	DI 30:		INT
P6031	DI 31:		INT
P6032	DI 32:		INT
P6033	DI 33:		INT
	Selection: see P6001	Range:	0-127
Cold start:	00:		
	This parameter describes how the digital inputs DI30 – DI33 are used in the weighing system.		



Indication:	These inputs are arranged on the third DI3yz system.	c card if this card is inserted and recognize	zed by the
Dependency:	Input card inserted? (R9600)		
	71.00		
P6040	DI 40:		INT
P6041	DI 41:		INT
P6042	DI 42:		INT
P6043	DI 43: Selection: see P6001	Range:	INT 0.137
	See Pour	range.	0-127
Cold start:	00:		
Description:	This parameter describes how the digital inp	uts DI40 – DI43 are used in the weighing	g system.
Indication:	These inputs are arranged on the fourth DI the system.	1yx card if this card is inserted and reco	ognized by
Dependency:	Input card inserted? (R9600)		
P6050	DI 50:		INT
P6051	DI 51:		INT
P6052	DI 52:		INT
P6053	DI 53:		INT
	Selection: see P6001	Range:	0-127
Cold start:	00:		
Description:	This parameter describes how the digital inp	uts DI50 – DI53 are used in the weighing	g system.
Indication:	These inputs are arranged on the fifth DI5yx system.	card if this card is inserted and recognize	zed by the
Dependency:	Input card inserted? (R9600)		
D0400	DI 00 I marting		INIT
R6100	DI 00 Inverter:	Range:	INT
	Selection: 00: normally open	range.	0-3
Description:	This parameter cannot be changed.		
Indication:	see Tacho input (R6000)		
P6101	DI 01 Inverter:		INT
P6102	DI 02 Inverter:		INT
P6103	DI 03 Inverter:		INT
P6104	DI 04 Inverter:		INT
P6105	DI 05 Inverter:		INT
	Selection: 00: normally open 01: normally closed 02: forced to 1: 03: forced to 0:	Range:	0-3



Description:	This parameter permits a change of swite to the values 0 or 1.	ching characteristics as well as a forced	setting (force)
Indication:	The forced-functions primarily serve for activate certain functionalities permanen		d, in order to
P6110	DI 10 Inverter:		INT
P6111	DI 11 Inverter:		INT
P6112	DI 12 Inverter:		INT
P6113	DI 13 Inverter:		INT
	Selection: see P6101	Range:	0-3
Description:	This parameter describes the input chara	acteristics of the digital inputs DI10 - DI13	3.
Indication:	These inputs are arranged on the first DI		
P6120	DI 20 Inverter:		INT
P6121	DI 21 Inverter:		INT
P6122	DI 22 Inverter:		INT
P6123	DI 23 Inverter:		INT
	Selection: see P6101	Range:	0-3
Description:	This parameter describes the input chara	ncteristics of the digital inputs DI20 - DI23	3.
Indication:	This input is arranged on the second DIS system.	2xx card if this card is inserted and reco	gnized by the
P6130	DI 30 Inverter:		INT
P6131	DI 31 Inverter:		INT
P6132	DI 32 Inverter:		INT
P6133	DI 33 Inverter:		INT
	Selection: see P6101	Range:	0-3
Description:	This parameter describes the input chara	ncteristics of the digital inputs DI20 - DI23	3.
Indication:	This input is arranged on the third DI3y system.	x card if this card is inserted and reco	gnized by the
P6140	DI 40 Inverter:		INT
P6141	DI 41 Inverter:		INT
P6142	DI 42 Inverter:		INT
P6143	DI 43 Inverter:		INT
	Selection: see P6101	Range:	0-3
Description:	This parameter describes the input chara		



Indication:	This input is arranged on the fourth DI4 system.	yx card if this card is inserted and recogniz	ed by the
P6150	DI 50 Inverter:		INT
P6151	DI 51 Inverter:		INT
P6152	DI 52 Inverter:		INT
P6153	DI 53 Inverter:		INT
	Selection: see P6101	Range:	0-3
Description:	This parameter describes the input char	acteristics of the digital inputs DI20 - DI23.	
Indication:	This input is arranged on the fifth DI5y system.	x card if this card is inserted and recogniz	ed by the



# 4.6.2 P64xx Digital outputs - Parameters

P6400	DO 00:			INT
	Selection:	00:	Range:	0-95
	Colcolion.	01: Warning	range.	0-95
		02: Ready to operate		
		03: Stopped		
		04: Empty		
		05: g3 - min load		
		06: g3 - max load		
		07: Panel		
		08: Remote		
		09: Deviation		
		10: Slip		
		11: Test/tare runs		
		12: Lay on testweight 13: Main drive on		
		14: Feeder on		
		15: Feeder reduction		
		16: Direction		
		17: Feeder open		
		18: Feeder closed		
		19: REM/RDY		
		20: Motor scale		
		21: Batch enable		
		22: Coarse stream		
		23: Fine stream 24:		
		25: Filling weighing bin		
		26: Bin empty		
		27: Movement error		
		28: Deviation detected		
		29:		
		30: Counter signal		
		31: Live bit		
		32: Fieldrelais1		
		33: Fieldrelais2 34: Fieldrelais3		
		35: Fieldrelais3		
		36: Fieldrelais5		
		37: Fieldrelais6		
		38: Fieldrelais7		
		39:		
		40:		
		41: Steering-Command		
		42: 43: Belt misrun		
		43: Belt misrun 44:		
		45: Local		
		46: ACK OUT		
		47: Drives locked		
		48:		
		49: Beltsteering pull		
		50: Beltsteering push		
		51: XD1 Auxiliary drive 1 on		
		52: XD2 Auxiliary drive 2 on		
		53: XD3 Auxiliary drive 3 on		
		54: XD4 Auxiliary drive 4 on 55: XD5 Auxiliary drive 5 on		
		 33. ADS Auxiliary unive S Off		



	56: 57: 58: Parmode active 59: Save parameters 60: Bin max 61: Bin min 62: SF Main drive on 1 63: SF Main drive on 2 64 – 87: 88: BCD0_Scan_XXX1 89: BCD0_Scan_XXX1 90: BCD0_Scan_XXXX 91: BCD0_Scan_IXXX 91: BCD0_Scan_IXXX 92: BCD1_Scan_XXX1 93: BCD1_Scan_XXXX 94: BCD1_Scan_XXXX	
Cold start:	04: Worning	
Description:	01: Warning  This parameter describes how the digital output DO00 is used in the weighing system.	
Indication:	This parameter describes how the digital output DO00 is used in the weighing system.  This output is arranged on the TM1yx card.	
maioation.	This output is arranged on the Tivityx Card.	
P6401	DO 01:	INT
	selection: see P6400 Range:	0-95
Cold start:	02: Ready to operate	
Description:	This parameter describes how the digital output DO01 is used in the weighing system.	
Indication:	This output is arranged on the TM1yx card.	
P6410	DO 10:	INT
1 0-110	Selection: see P6400 Range:	0-95
	3001 0400	0 00
Cold start:	30: Counter signal	
Description:	This parameter describes how the digital output DO10 is used in the weighing system.	
Indication:	This output is arranged on the first DO1yx card.	
dependency:	Output card installed? (R9640)	
P6411	DO 11:	INT
	Selection: see P6400 Range:	0-95
Cold start:	03: Stopped	
Description:	This parameter describes how the digital output DO11 is used in the weighing system.	
Indication:	This output is arranged on the first DO1yx card.	
P6412	DO 12:	INT
F041Z	Selection: see P6400 Range:	0-95
	30010400	0-90



Cold start:	06: g3 - max load		
Description:	This parameter describes how the digital output DO12 is used in the weighing system.		
Indication:	This output is arranged on the first DO1yx card.		
P6413	DO 13:		INT
	Selection: see P6400	Range:	0-95
Cold start:	00:		
Description:	This parameter describes how the digital output DO	13 is used in the weighing sys	stem.
Indication:	This output is arranged on the first DO1yx card.		
P6414	DO 14:		INT
	Selection: see P6400	Range:	0-95
Cold start:	08: Remote		
Description:	This parameter describes how the digital output DO	14 is used in the weighing sys	stem.
Indication:	This output is arranged on the first DO1yx card.		
P6415	DO 15:		INT
	Selection: see P6400	Range:	0-95
Cold start:	09: Deviation		
Description:	This parameter describes how the digital output DO	15 is used in the weighing sys	stem.
Indication:	This output is arranged on the first DO1yx card.		
P6420	DO 20:		INT
P6421	DO 21:		INT
P6422	DO 22:		INT
P6423	DO 23:		INT
P6424	DO 24:		INT
P6425	DO 25: Selection: see P6400	Range:	INT 0-95
	3001 0400	g	0 00
Cold start:	00:		
Description:	This parameter describes how the digital outputs DC	20 – DO25 is used in the weig	ghing system.
Indication:	This output is arranged on the second DO2yx card.		
P6430	DO 30:		INT
P6431	DO 31:		INT
P6432	DO 32:		INT
P6433	DO 33:		INT
P6434	DO 34:		INT



P6435	DO 35:		INT
	Selection: see P6400	Range:	0-95
Cold start:	00:		
Description:	This parameter describes how the digital outpo	uts DO30 – DO35 is used in the weig	hing system.
Indication:	This output is arranged on the second DO3yx	card.	
P6500	DO 00 Inv:		INT
	Selection: 00: normally open 01: normally closed 02: forced to 1: 03: forced to 0:	Range:	0-3
Description:	This parameter permits a change of the swit (force) to the values 0 or 1.	ching characteristics as well as a fo	orced setting
Indication:	The forced-functions primarily serve for sim activate certain functionalities permanently.	ulation tests, but can also be used	l, in order to
P6501	DO 01 Inv:		INT
	Selection: see P6500	Range:	0-3
Description:	This parameter describes the output characte	ristics of the digital output DO01.	
Indication:	This output is arranged on the TM1yx card.		
P6510	DO 10 Inv:		INT
P6511	DO 11 Inv:		INT
P6512	DO 12 Inv:		INT
P6513	DO 13 Inv:		INT
P6514	DO 14 Inv:		INT
P6515	DO 15 Inv:		INT
	Selection: see P6500	Range:	0-3
Description:	This parameter describes the output characte	ristics of the digital outputs DO10 - E	OO15.
Indication:	These outputs are arranged on the first DO1y	x card.	
	DO 20 Inv:		INT
P6520			INIT
P6520 P6521	DO 21 Inv:		INT
	DO 21 Inv: DO 22 Inv:		INT
P6521			
P6521 P6522	DO 22 Inv:		INT
P6521 P6522 P6523	DO 22 Inv: DO 23 Inv:		INT INT

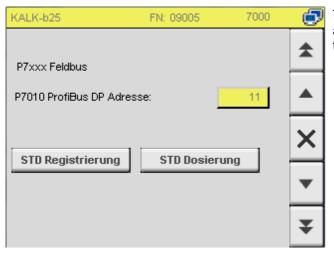


Description:	This parameter describes the output characteristics of the digital outputs DO20 - DO25.
Indication:	These outputs are arranged on the second DO2yx card if this card is inserted and recognized by the system.

P6531	DO 31 Inv:		INT	
P6532	DO 32 Inv:		INT	
P6533	DO 33 Inv:		INT	
P6534	DO 34 Inv:		INT	
P6535	DO 35 Inv:		INT	
	Selection: see P6500	Range:	0-3	
Description:	This was waster described the custout chara	atoviation of the digital autoute DO20	DOSE	
Description.	This parameter describes the output characteristics of the digital outputs DO30 – DO35.			
Indication:	These outputs are arranged on the third DO3yx card if this card is inserted and recognized by the system.			



## 4.7 Parameter group P7xxx / Fieldbus



The parameter group "Fieldbus" permits the adjustment and change of communication possibilities to a central control.

Please, find details on configuration in

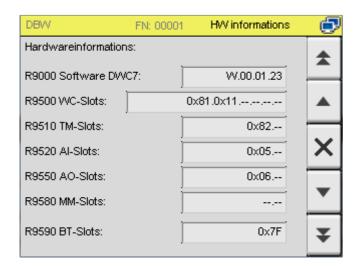
T3-Fieldbus manual.

These functions are only available if a Fieldbus option was acquired and licensed by the manufacturer. Since the parameters of this group partly interact very detailed with the Fieldbus inserted, the description of the parameter group P7xxx is done in the Fieldbus manual.

## 4.8 Parameter group P8xxx / reserved for future use

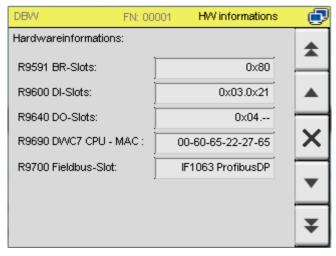


## 4.9 Parameter group P9xxx / Hardware and Operating Unit Parameters



The parameter group "Hardware information" provides information about the current structure of the weighing system.

These parameters cannot be changed. Thus, they are labelled as "R" for "ReadOnly" (only read rights).



R9000	Software DWC7:		String[16]
	Unit:	Range:	A-Z,a-z,0-9, Special character
Description:	Describes the currently installed program Usually, the number standing behind mapanel (R9700). Deviations are only poss	ust coincide with the program ve	rsion of the operator
Indication:	Program versions of the weighing compu	uter DWC-7A are always prefixed	with the letter "W".



### 4.9.1 P95xx Detailed information about the actually detected Hardware Structure



Especial regulations apply for the slot numbers. The system can be established centrally in one rack as well as decentral solution two racks. The maximum distance between the main rack and the local E/A rack is 100m. For more information please contact KUKLA as manufacturer.

R9500	WC-Slots:		String[16]
	Unit:	Range:	0-9 Special character
Description:	Shows the slot numbers of the load cell	cards (WMxyx) currently recogniz	ed by the system.
R9510	TM-Slots:		String[16]
13310	Unit:	Range:	0-9 Special character
Description:	Shows the slot number of the tacho com Usually, also some digital inputs and out		zed by the system.
R9520	Al-Slots:		String[16]
	Unit:	Range:	0-9 Special character
Description:	Shows the slot numbers of the analogue	input cards (Alxyx) currently recog	gnized by the system
R9550	AO-Slots:		String[16]
	Unit:	Range:	0-9 Special character
Description:	Shows the slot numbers of the analogous system.	ue output cards (AOxyx) currentl	ly recognized by the
R9580	MM-Slots:		String[16]
	Unit:	Range:	0-9 Special character
Description:	Shows the slot numbers of the MoviMosystem. Actually, communication with interface, but functionally seen it is an ar	MoviMot frequency converters	
R9590 R9591	BT-Slots: BR-Slots:		String[16] String[16]
	Unit:	Range:	0-9 Special character
Description:	Shows the slot numbers of the bus transcards. These cards are only installed in		



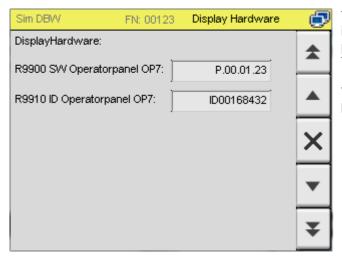
R9600	DI-Slot	ts:			String[16]
	Unit:			Range:	0-9,
					Special character
Description:	Shows	the slot numbers of the dig	gital input cards (Dlxyx	) currently recogn	ized by the system.
R9640	DO-SIG	ots:			String[16]
	Unit:			Range:	0-9,
					Special character
Description:	Shows	the slot numbers of the dig	gital output cards (DOxy	yx) currently recog	gnized by the system.
R9690	DWC7	CPU - MAC:			String[16]
	Unit:	MAC-ID (hex)		Range:	xx-xx-xx-xx-xx
Description:		AC (media access control a pase unit.	address) of the first Etho	ernet interface is o	displayed on the CPU
R9700	Fieldb	us-Slot:			String[16]
	Unit:			Range:	Text
Description:	Display recogn	ys which Fieldbus module ized.	is inserted at the slo	ot on the left side	e of the CPU and is
Indication:	which is Examp	ernal reasons, if a fieldbus s stored in the internal firm le: Profinet module is phys 063 ProfibusDP" is display	ware of the base unit. ically plugged in, basic	-	



### 4.9.2 P99xx Software Version OP-7A



The following parameters refer to the operator panel unit and **NOT** to the base unit (belt scale). They can therefore appear in the parameter lists of several basic units, depending on where they were requested.



The parameter group "Display Hardware" provides information exclusively relating to the current operator panel.

These parameters get NOT stored in the base unit.

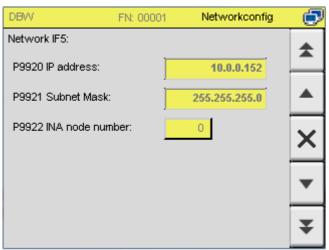
These parameters cannot be changed. Thus, they are labelled as "R" for "ReadOnly" (only read rights).

R9900	SW Operatorpanel OP7:		String[16]
	Unit:	Range:	A-Z,a-z,0-9,
Description:	Describes the currently installed software version	of the program on the ope	rating unit.
Indication	Program versions of the operating unit OP-7A are the number standing behind must coincide with the (R9000). Deviations are only possible after consul	e program version of the co	nnected base unit

R9910	ID Operatorpanel OP7:		String[16]
	Unit:	Range:	ID,0-9
Description:	Shows the internal serial number of the OP7 operation	ng unit.	
Indication	This number is NOT identical with the fabrication num	nber (FN)!	



### 4.9.3 P992x IP-Settings for LAN – Access to local IT Network



The parameter group P992x is relevant for the connection into a IT network provided by the costumer. This communication is made via the Ethernet interface IF5.

The internal communication between the operator panel and the base unit is only possible via the interface IF4.

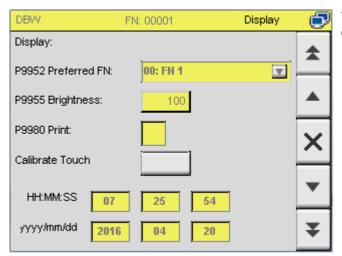
P9920	IP Address:		String[16]
	Selection: IP	Range:	xxx.xxx.xxx
Description:	This parameter permits the setting of t to the customer's network.	the IP address, by which the operatin	ng unit OP7 connects
Indication	It must be noted that an access from to operating unit OP-7A. A direct access	` •	,

P9921	Subnet Mask:		String[16]
	Selection: IP-Subnet-Mask	Range:	xxx.xxx.xxx
Description:	In this parameter, the system-wide Subnet mask of the entered.	e superordinate	IP system must be
Indication			

P9922	INA Node number:		INT
	Selection:	Range:	0-19
Description:	This parameter is usually used for the man updates) and should not be changed by the		g. for software
Indication:			



## 4.9.4 P995x Display - Basic Settings



This parameter group contains settings, which are only relevant for the display.

P9952	Preferred FN:		String[16]
	Selection:	Range:	0-15
Description:	This parameter determines which basic unit restart.	s the initial favorite communication	partner after a
Indication	In this way it can be achieved that different co to different base units. Thereby, it is prevente others have to be selected manually after a g	ed that all displays only show the fir	

P9955	Brightness:		INT
	Selection:	Range:	20 - 100
Cold start:			
Description:	With this parameter the brightness of the backlight of the displa	ay is determined.	
Indication			



### 4.9.5 P998x External process data printout

P9980	Print:			INT
	Unit:	Checkbox	Range:	0/1
Cold start:	0			
Description:	A spec	ial print log, which uses an optiona	I, serial interface in the OP-7A can be activated	d.
Indication				

For printing a document, a text file named "Print.txt" is required. Note that the file name is case sensitive. The text file can be created in an editor like Notepad. The file size of the text document must be at least 31 bytes. The content of this file is basically arbitrary. Certain wildcards, which are always prefixed with a percent sign, are replaced by the actual values from the control during the transformation process (creation of the log). Thus, the actual printout with the included process data results.

The most important wildcards are:

%RA	Counter A
%RB	Counter B
%RC	Counter C
%RP	Capacity
%Rp	Capacity in percent
%Rg	Actual load in percent (g1)
%RV	Actual speed absolute
%Rv	Actual speed in percent
%RT	Time
%Rd	Date
%RF	Fabrication number FN
%RN	Counting ID

#### Note that wildcards are case sensitive!

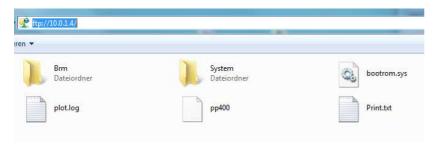
A print file might look as follows:

Rawdata (not transformed):	Transformed:
Kukla	Kukla
Count A: %RA	Count A: 2544kg
Count B: %RB	Count B: 2544kg
Count C: %RC	Count C: 2544kg
Set value: %RP	Set value: 20,00 t/h
Set value: %Rp	Set value: 100%
Load: %Rg	Load: 63,54%
Speed: %RV	Speed: 192,0 m/s
Speed: %Rv	Speed: 76,80%
Time: %RT	Time: 08:51
FM: %RF	FM: 9597
Pressure number: %RN	Pressure number: 12
Datum: %Rd	Datum: 26.02.2015

The IP Address (see R9920) of the Panel must be known, in order to be able to copy the file to the Panel.



Via Windows, the Explorer permits a connection by means of "ftp://IP address/". Simply copy the file into the main directory of the Panel by drag and drop.



When counter B or counter C are cleared, the actual printing is performed.



### 4.9.6 Touchscreen Calibration



In order to perform the operation, the four calibration points must be pressed as precisely and centrally as possible successively.



Logically, this calibration can only be performed locally on the display and NOT via the VNC remote connection.

### 4.9.7 Clock setup at Operator Panel

In the represented area the time can be adjusted manually.



An automatic setting via time server and an automatic switchover to winter / summer time can be expected in future versions.



# 5 Annex

# 5.1 Remarks