Integration Manual T3

FieldBus



















*** SAFETY REGULATIONS ***

Being under voltage the device must not be opened. Danger of electric shock.

Service works at the weighing equipment are permitted only for qualified

Personnel. In case of works at the weighing system ALL drives must be switched off and locked.



The related device/system may only be set-up and operated in connection with this documentation. Start-up and operation of a devices/system may only be carried out by **qualified personnel**. Qualified personnel in terms of safety notes of this documentation are persons being authorized to take into operation, to ground and to label the devices, systems and circuits in accordance with the standards of safety engineering.



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Revision list

Revision	Datum	Autor	Kapitel	Beschreibung
T3_FBUS7A_V1_0en	12.03.2015	Ratzinger		First Edition
	20.06.2015	Leibner		Basic Translation
T3_FBUS7A_V1_1en	15.09.2015	Ratzinger		General Revision / Einfügen neuer Befehle
T3_FBUS7A_V1_2en	25.07.2016	Krichbaum		General Revision / Insert new status
T3_FBUS7A_V1_26en	17.11.2016	Ratzinger		Corp. Design + Bus-Command4

Software indication

These instructions are based on following Software versions

W.00.01.26 (Weighing system) P.00.01.26 (Service modules)

In course of the technical progress changes can be carried out at the software. At subsequent software versions therefore deviations are possible compared to these instructions.

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1 General description

This part of the Service instructions describes the details of communication possibilities by Fieldbus systems of the DWC-7A scale system. It is an extension of the T1-Service instructions but is no separate manual.

It has been moved into a separate part since the Fieldbus system is an option installed into the DWC-7A system only on client's request.

1.1Symbols

This manual is using the following symbols as special indications:



IMPORTANT INDICATION!

Marks an important indication.



WARNING!

Marks a general warning.



DANGER!

Means that death or severe personal injury may occur if the corresponding precautions are not taken.

* marks KUKLA-factory standard settings



2PROFIBUS-DP

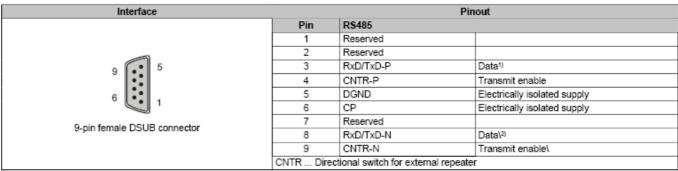
2.1 General

Scale computers of series DWC-7A can be equipped with a ProfiBus DP Interface. This Interface has to be indicated in the order. A subsequent installation on consultation with the manufacturer is possible, too. The interface is licenced by the manufacturer KUKLA and corresponds to the ProfiBus Norm 50170. Optionally beside many other communication solutions also a DP V1 or a ProfiNet-interface can be realised.



2.2 Data transfer rate / Connector assignment

The Interface supports the usual normed data transfer rates up to 12 MBit. In case of higher transfer rates absolutely plugs approved thereto have to be used..

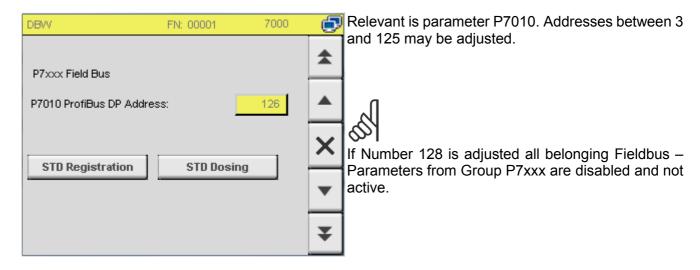


It is recommendable to use normed ProfiBus DP plug connectors. The cable heads have to be terminated with terminating resistors.

2.3 Station Address

The station address is adjusted via parameter P7XXX directly at the Operator panel.





AFTER CHANGING THE PROFIBUS-DP ADDRESS THE SCALE COMPUTER HAS TO BE TAKEN OFF VOLTAGE FOR ABOUT 5 SECONDS IN ORDER TO MAKE POSSIBLE TO TAKE OVER THE NEW ADDRESS.

2.4 LED Status messages

Figure	LED	Color	Status	Description
1000	STATUS	Green	On	Interface module active
		Red	On	CPU starting up
and the same of	RxD	Yellow	On	The module receives data via the PROFIBUS DP slave interface
X ZO IF 106X	TxD	Yellow	On	The module sends data via the PROFIBUS DP slave interface



2.5 Data structure / consistence

Please, find details concerning Data structure in the general part of section "General data structure".

2.6 GSD- File

The required master data are supplied on disk/CD along with the scale computer or can be acquired directly from the manufacturer. Other file sizes than the ones described in this documentation are not possible.

For S7 Classic Systems (300/400CPU's) a library can be requested by KUKLA, which significantly simplifies the integration of a KUKLA-Controller. Basically full communication is also – without the library described towards the end of the manual in details – possible.



3 PROFINET-IO

3.1 General

The scale computers of series DWC-7A can be equipped with an optional modular ProfiNet-IO-Interface. This Interface has to be indicated at the order. A subsequent installation on consultation with the manufacturer is possible, too. There must be a corresponding licence for the modules.



3.2 Data transfer rate / Connector assignment

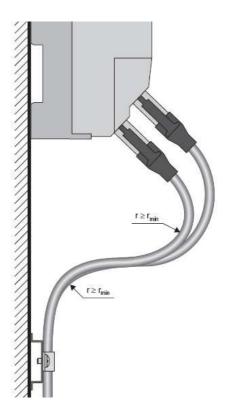
The ProfiNet-Busmodule works as ProfiNet-IO-Device at the ProfiNet. It supports the Data telegram usual at KUKLA. The transfer is done via Twisted-Pair-cable in Full-Duplex-operation with 100 MBit/s. The IP-address adjustments as usual with ProfiNet are set at configuration of the ProfiNet-IO-Controller and later on at run-up of the IO Controller transferred to the module via the DCP-protocol. Alternatively address adjustments can be done via the device-sided Software-interface.

Interface	Pinout		
	Pin	Ethernet	
	1	RXD	Receive data
	2	RXD\	Receive data\
	3	TXD	Transmit data
	4	Termination	
	5	Termination	
	6	TXD\	Transmit data\
Shielded RJ45 port	7	Termination	
	8	Termination	

Following cabling regulations have to be observed:

- Use of CAT5 SFTP cable
- Keeping of bend radius of the cable (Observe cable data sheet)
- Fix the cable beneath the module.





The fixing must be located vertically below the RJ45 connector of the module.

3.3 IP address

The station address – as usual with ProfiNet – is performed by the master program system by "baptism process".

3.4 LED Status messages / Module structure

Figure	LED	Color	Status	Description
The state of the s	READY/RUN	Green/red	Off	No power to module
		Red	Blinking	Boot error
-			On	Communication on the PCI bus has not yet been started
		Green	On	PCI bus communication in progress
	SF	Red	Off	No error
			Cyc. Blinking ¹⁾	DCP signal service triggered via bus
READY/RUN			On	System errors
BF	BF	Red	Off	No error
L/A IF1			Blinking	No data exchange
20 114			On	No configuration or physical connection error
×	L/A IF1/IF2	Green	Off	No link to remote station
	A STATE OF THE STA	Flickering	A link to the remote station has been established. The LED blinks when Etherne activity is taking place on the bus.	
	1		On	A link to the remote station has been established.

3.5 Data structure / consistence

Please, find details concerning Data structure in the general part of section "General data structure".



3.6 GSDML- File

The required GSD-XML-files are supplied on disk/CD along with the scale computer or can be acquired directly from the manufacturer. Other file sizes than the ones described in this documentation are not possible.

For S7 Classic Systems (300/400CPU's) a library can be requested by KUKLA, which significantly simplifies the integration of a KUKLA-Controller. Basically full communication is also – without the library described towards the end of the manual in details – possible.



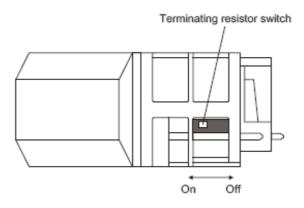
4 DeviceNet

4.1 General

The scale computers of series DWC-7A can be equipped with an optional modular DeviceNet (Slave) – Interface. This Interface has to be indicated at the order. A subsequent installation on consultation with the manufacturer is possible, too. There must be a corresponding licence for the modules.



At the interface module a terminating resistor is already integrated. By means of a switch at the case bottom the terminating resistor is switched on or off, an activated terminating resistor is indicated by the LED "TERM".



It is recommended to integrate the terminating resistor into the plug connector in order to ensure a clean bus termination after disconnecting the participant. The switch at the module thereto always has to be switched off!

4.2 Data transfer rate / Connector assignment

The interface module is equipped with a DeviceNet Slave (Adapter) interface. It supports the data telegram usual at KUKLA. The transfer is done via a specific and suitable DeviceNet-cable.



Interface			Pinout
(a 1	Terminal	DeviceNet	
\ _ '	1	CAN⊥ (V-)	CAN ground
\ _	2	CAN_L	CAN low
\ _	3	SHLD	Shield
\ \mathbb{n} \ \mathbb{1} 5	4	CAN_H	CAN high
	5	V+	Supply voltage ¹⁾
5-pin male multipoint connector			

1) A 24 V Supply voltage can be connected to this connection. The voltage is only led through. The module neither provides it nor needs it.

4.3 Node Number (Stationaddress)

The station address is adjusted via parameter P7XXX directly at the Operator panel.



AFTER CHANGING THE DEVICENET-ADDRESS THE SCALE COMPUTER HAS TO BE TAKEN OFF VOLTAGE FOR ABOUT 5 SECONDS IN ORDER TO MAKE POSSIBLE TO TAKE OVER THE NEW ADDRESS.

4.4 LED Status messages / Module structure

- 1	Figure	LED	Color	Status	Description
		READY/RUN	Green/red	Off	No power to module
		T .	Green	On	PCI bus communication in progress
			Red	On	Communication on the PCI bus has not yet been started
	No. of London	MOD/NET	Green/red	Off	Module supply not connected or module is not online
		Green	Blinking	Module is online but the I/O connection is not active	
			05.55c2-400.0c	On	Module is online and the I/O connection is active ("operating")
Ė.	MOD/NET DAT TERM TERM		Red	Blinking	The red LED blinks if at least one of the following errors has occurred: Minor fault (recoverable fault) Connection error No DeviceNet supply voltage
X				On	Critical fault or critical connection error (double MAC ID, bus failure or modul defect)
		TxD	Yellow	Flickering or on	Module sending data via the DeviceNet interface
		TERM	Yellow	On	Terminating resistor integrated in the module switched on

4.5 Data structure / consistence

Please, find details concerning Data structure in the general part of section "General data structure"

4.6 EDS- File

The required EDS-files are supplied on disk/CD along with the scale computer or can be acquired directly from the manufacturer. Other file sizes than the ones described in this documentation are not possible.

5ETHERNET-IP



5.1 General

The scale computers of series DWC-7A can be equipped with an Ethernet-IP Interface. This Interface has to be indicated at the order. A subsequent installation on consultation with the manufacturer is possible, too. There must be a corresponding licence for the modules.



5.2 Data transfer rate / Connector assignment

The interface module works as EtherNet/IP Adapter (Slave). The transfer is done via Ethernet-cable with /10100 MBit/s. The interface is designed with two RJ45-connectors. Both connections go to an integrated switch. By that Daisy-Chain-cablings at EtherNet/IP are easily possible.

- EtherNet/IP Adapter (Slave)
- Integrated switch for economic cabling

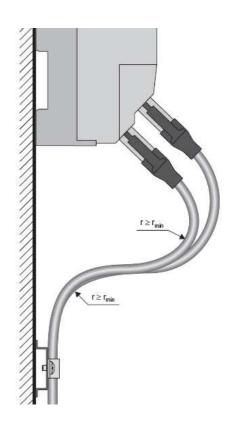
It supports the data telegram usual at KUKLA.

Interface	Interface		out
	Pin	Ethernet	
	1	RXD	Receive data
1	2	RXD\	Receive data\
	3	TXD	Transmit data
	4	Termination	
	5	Termination	
	6	TXD\	Transmit data\
Shielded RJ45 port	7	Termination	
	8	Termination	

Following cabling regulations have to be observed:

- Use of CAT5 SFTP cable
- Keeping of bend radius of the cable (Observe cable data sheet)
- Fix the cable beneath the module





The fixing has to be located in vertical direction beneath the RJ45 connector of the module.

5.3 Station address

The IP-address adjustments are - as usual with EthernetIP - set at configuration of the IO-Controller and are described with a well-established ConfigTool.

5.4 LED Statusmeldungen / Modulaufbau

Figure	LED	Color	Status	Description
	READY/RUN	Green/red	Off	No power to module
		Green	On	PCI bus communication in progress
		Red	Blinking	Boot error
		Lit	On	Communication on the PCI bus has not yet been started
	Mod status ¹⁾	Green	Blinking	Interface module not yet configured
Street, St.	0.000-0.0000000000000000000000000000000		On	Adapter (Slave) is operational
		Red	Blinking	Recoverable hardware error
	B		On	Irrecoverable hardware error
		Green/red	Blinking	Initialization / Self-test
READY/RUN Mod Status			Off	No power to module
Net Status	Net status ¹⁾	Green	Blinking	No active connection
L/A IF1			On	Indicates at least one active connection
20 1		Red	Blinking	Timeout occurred on at least one connection
×			On	An IP address has been used repeatedly
	**	Green/red	Blinking	Initialization / Self-test
			Off	No IP address assigned or module not supplied
	L/A IF1/IF2	Green	Off	No link to remote station
		Flie	Flickering	A link to the remote station has been established. The LED blinks when Etherne activity is taking place on the bus.
		100		A link to the remote station has been established.



5.5 Data structure / consistence

Please, find details concerning Data structure in the general part of section "General data structure".



6 General data structure

Generally always 10 Double words have to be transferred as nominal data by the superior control.

As usually the scale computer is able to collect a variety of data, always 14 Double words are signalled back to the superior system. To each process data double word via the corresponding parameter number individually can be allocated, which value exactly on this field is sent.

6.1 Set point - and process data fields

	PLC > DWC	DWC < PLC
00 Double word	BusIn DW00 (P7200)	BusOut DW00 (P7400)
01 Double word	BusIn DW01 (P7201)	BusOut DW01 (P7401)
02 Double word	BusIn DW02 (P7202)	BusOut DW02 (P7402)
03 Double word	BusIn DW03 (P7203)	BusOut DW03 (P7403)
04 Double word	BusIn DW04 (P7204)	BusOut DW04 (P7404)
05 Double word	BusIn DW05 (P7205)	BusOut DW05 (P7405)
06 Double word	BusIn DW06 (P7206)	BusOut DW06 (P7406)
07 Double word	BusIn DW07 (P7207)	BusOut DW07 (P7407)
08 Double word	BusIn DW08 (P7208)	BusOut DW08 (P7408)
09 Double word	BusIn DW09 (P7209)	BusOut DW09 (P7409)
10 Double word		BusOut DW10 (P7410)
11 Double word		BusOut DW11 (P7411)
12 Double word		BusOut DW12 (P7412)
13 Double word		BusOut DW13 (P7413)

Absolute values are transferred as 1/10 kg numbers or in kg (see detail indications). Per cent values are transferred as values with 1/100 per cent resolution (e.g. 74.83 % corresponds to number value 7483).



6.2 Data structure recommended by KUKLA:

(Details see following chapter)

\ <u> </u>	<u> </u>	
00 Double word	12: Bus ABS 1 [kg/h] *	50: P3 Capacity [kg/h] *
01 Double word	21: Bus Command 1 *	44: Counter A [kg] *
02 Double word	22: Bus Command 2 *	45: Counter B [kg] *
03 Double word	00:	32: BusControlBits *1
04 Double word	04: Bus percent 1 *	33: BusControlBits 2 *
05 Double word	05: Bus percent 2 *	35: BusStatusBits 1 *
06 Double word	00:	36: BusStatusBits 2 *
07 Double word	00:	02: Drive WB [%] *
08 Double word	23: Bus Command 3	01: Feeder setpoint [%] *
09 Double word	24: Bus Command 4	08: g3-load [%] *
10 Double word		22: Speed [%] *
11 Double word		03: 0% output [%] / Spare *
12 Double word		03: 0% output [%] / Spare *
13 Double word		03: 0% output [%] / Spare *

6.3 Details Bus Setpoints (Process In)

BusSet - Doublewords		
Denomination	Description	Format
00:	Data FIELD is unused	
01:	reserved	
02:	reserved	
03:	reserved	
04: Bus percent 1	Bus Setpoint percent 1	%-Value
05: Bus percent 2	Bus Setpoint percent 2	%-Value
06: Bus percent 3	Bus Setpoint percent 3	%-Value
07: Bus percent 4	Bus Setpoint percent 4	%-Value
08: Bus ABS 1	BusAbsolute value - buffer 1	Absolut
09: Bus ABS 2	BusAbsolute value - buffer 2	Absolut
10: Bus ABS 3	BusAbsolute value - buffer 3	Absolut
11: Bus ABS 4	BusAbsolute value - buffer 4	Absolut
12: Bus ABS 1 [kg/h]	Bus Kilo Setpoint 1 (e.g. Capacity Setpoint)	kg
13: Bus ABS 2 [kg/h]	Bus Kilo Setpoint 2	kg
14: Bus ABS 3 [kg/h]	Bus Kilo Setpoint 3	kg



15: Bus ABS 4 [kg/h]	Bus Kilo Setpoint 4	kg
16: Bus ABS 1 [1/10 kg/h]	Bus Dekagramm -Setpoint 1	1/10 kg
17: Bus ABS 2 [1/10 kg/h]	Bus Dekagramm -Setpoint 2	1/10 kg
18: Bus ABS 3 [1/10 kg/h]	Bus Dekagramm -Setpoint 3	1/10 kg
19: Bus ABS 4 [1/10 kg/h]	Bus Dekagramm -Setpoint 4	1/10 kg
20:	reserved	
21: Bus Command 1	BusCommand-Double word 1 (see following Bit-list)	Bitfield[32]
22: Bus Command 2	BusCommand-Double word 2 (see following Bit-list)	Bitfield[32]
23: Bus Command 3	BusCommand-Double word 3 (see following Bit-list)	Bitfield[32]
24:	reserved	
25: Parameter Number	Special function on consultation with manufacturer	
26: Parameter Value	Special function on consultation with manufacturer	
27:	reserved	
28:	reserved	
29:	reserved	
30: DWC3/5 CMD	Compatiblity for old DWC3/5 Systems Commands	
31: DWC3/5 SW1_2	Compatiblity for old DWC3/5 Systems Systemen SW	
32: DWC3/5 SW3_4	Compatiblity for old DWC3/5 Systems SW	
33: DWC3/5 SL1	Compatiblity for old DWC3/5 Systems SL	
34: DWC3/5 SL2	Compatiblity for old DWC3/5 Systems SL	
C.	1	



Digital control commands to the scale computer	
ommand 1 0x00000002 01: QUANTITY COUNTER B PRINT / CLEAR 0x00000004 02: QUANTITY COUNTER C PRINT / CLEAR	
0x00000004 02: QUANTITY COUNTER C PRINT / CLEAR	
0x00000004 02: QUANTITY COUNTER C PRINT / CLEAR	
0x00000010 04: CONVEYOR SYSTEM RUNS	
0x00000000	
0x00000040 06: PANEL-MODE	
0x00000080 07: MIS RUN	
0x00000100 08: SYNC-PULSE (Absolute value tare)	
0x00000200 09: DRIVE FAULT	
0x00000400 10: DELETE ERROR	
0x00000800 11: PANEL START (rising edge)-	
0x00001000 12: FIELD INPUT 1 (switches FIELD RELAY 1)	
0x00002000 13: FIELD INPUT 2 (switches FIELD RELAY 2)	
0x00004000 14: FIELD INPUT 3 (switches FIELD RELAY 3)	
0x00008000 15: FIELD INPUT 4 (switches FIELD RELAY 4)	
0x00010000 16: FIELD INPUT 5 (switches FIELD RELAY 5)	
0x00020000 17: FIELD INPUT 6 (switches FIELD RELAY 6)	
0x00040000 18: FIELD INPUT 7 (switches FIELD RELAY 7)	
0x00080000 19: LIVE BIT	
0x00100000 13. EIVE BIT 0x00100000 20: TENSION CLEANING CHAIN	
0x00200000 20. TENSION CLEANING CHAIN 0x00200000 21: >0< START	
0x00400000 22: START TEST (Testweight)	
0x00800000 23: START MATERIALTEST	
0x01000000 24: SUSPEND MEASURING	
0x02000000 25: ENABLE REGULATOR (Feeder operation)	
0x04000000 26: FEEDER REDUCTION (Feeder operation)	
0x08000000 27: JOG Feeder	
0x10000000 28: -	
0x20000000 29: REFILLING INDICATOR (Loss-in-weight-dosing)	
0x40000000 30: START BATCH (Batch mode)	
0x80000000 31: INTERRUPT BATCH (Batch mode)	
us 0x00000001 32: EMPTYING SYSTEM (Batch mode)	
ommand 2	
0x00000004 34: BATCH REMOT SETPOINT (Batch mode)	
0x00000008 35: FEEDINGCHANNEL x1 (Batch mode)	
0x00000000 35: TEEDINGCHANNEL x1 (Batch mode)	
0x00000000 37	
0x00000040 38: COUNTING TO G2	
0x00000080 39: CALCULATE DRY WEIGHT	
0x00000100 40: ADAPT SPAN (Check weigher)	
0x00000200 41: –	
0x00000400 42: BELT MISRUN LEFT-	
0x00000800 43: BELT MISRUN RIGHT	
0x00001000 44: BELT EDGE SENSOR ON (Belt steering device)	
0x00002000 45: BELT EDGE SENSOR OFF (Belt steering device)	
0x00004000 46: STEERING DEV EXTENDED (Belt steering device)	
0x00008000 47: STEERING DEV RETRACTED (Belt steering device)	
0x00010000 48: –	
0x00020000	
0x00040000 50: TACHO INPUT (not usable for Bus / too fast pulses)	
0x00080000 51: EMERGENCY DEVICE (indication only)	
, , , , , , , , , , , , , , , , , , , ,	
0x00200000 53:-	
0x00400000 54: DRIVE LOCK	
0x00800000	
0x01000000 56: LOCAL START (edge controlled)	
0x02000000 57: LOCAL STOP (edge controlled)	
0x04000000 58: CENTRAL OPERATION	
0x08000000 59: -	
0x10000000 60: JOG MAIN DRIVE	



	0x20000000	61: -
	0x40000000	62: -
	0x80000000	63: -
Bus	0x00000001	64: CHANNEL 1 START (support drives)
Command 3	0x000000007	65: CHANNEL 1 STOP (support drives)
Oommand 5	0x00000002	66: -
	0x00000004	67: -
	0x00000000	68: CHANNEL 2 START (support drives)
	0x000000000000000000000000000000000000	69: CHANNEL 2 START (support drives)
	0x00000020	70: -
	0x00000040	71: -
	0x00000000	72: CHANNEL 3 START (support drives)
	0x00000100	73: CHANNEL 3 START (support drives)
	0x00000200	73. CHANNEL 3 31 OF (support drives)
	0x00000400	74 75: -
	0x000000000	
	0x00001000	76: CHANNEL 4 START (support drives) 77: CHANNEL 4 STOP (support drives)
		\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \
	0x00004000	78: -
	0x00008000	79: -
	0x00010000	80: CHANNEL 5 START (support drives)
	0x00020000	81: CHANNEL 5 STOP (support drives)
	0x00040000	82: -
	0x00080000	83: -
_	-	reserved
Bus	0x00000001	96: XD1 pulse (speed monitor sensor auxiliary drive 1)
Command 4	0x00000002	97: XD1 run (run indication from auxiliary drive 1)
	0x00000004	98: XD1 fault (external fault at auxiliary drive 1)
	0x00000008	99: -
	0x00000010	100: -
	0x00000020	101: XD2 pulse (speed monitor sensor auxiliary drive 2)
	0x00000040	102: XD2 run (run indication from auxiliary drive 2)
	0x00000080	103: XD2 fault (external fault at auxiliary drive 2)
	0x00000100	104: -
	0x00000200	105: -
	0x00000400	106: XD3 pulse (speed monitor sensor auxiliary drive 3)
	0x00000800	107: XD3 run (run indication from auxiliary drive 3)
	0x00001000	108: XD3 fault (external fault at auxiliary drive 3)
	0x00002000	109: -
	0x00004000	110: -
	0x00008000	111: XD4 pulse (speed monitor sensor auxiliary drive 4)
	0x00010000	112: XD4 run (run indication from auxiliary drive 4)
	0x00020000	113: XD4 fault (external fault at auxiliary drive 4)
	0x00040000	114: -
	0x00080000	115: -
	0x00100000	116: XD5 pulse (speed monitor sensor auxiliary drive 5)
	0x00200000	117: XD5 run (run indication from auxiliary drive 5)
	0x00400000	118: XD5 fault (external fault at auxiliary drive 5)
	0x00800000	119: -
	0x01000000	120: -
		reserved
Please, find deta	ails concerning th	e BusCommands in the Parameter description of the Digital inputs (P60xx). Th

Please, find details concerning the BusCommands in the Parameter description of the Digital inputs (P60xx). The physical inputs as well as the BusCommands are connected in parallel.



6.4 Description of Bus actual values (Process data out)

ProcessData / BusOut- Dou	ible words	
Denomination	Description	Format
00: P3 Capacity [%]	Current actual capacity at discharge point	%-Value
01: Feeder setpoint [%]	Variable for Feeder drive	%-Value
02: Drive WB [%]	Variable for dosing Drive (weighing belt,dosing screw etc.)	%-Value
03: 0% output [%]	Zero value Output (primarily for adjustment works)	%-Value
04: 50% output [%]	50% - value Output (primarily for adjustment works)	%-Value
05: 100% output [%]	100% - value Output (primarily for adjustment works)	%-Value
06: g1-load [%]	Current load on measuring length Output	%-Value
07: g2-load [%]	Current load at dosing point g2 Output	%-Value
08: g3-load [%]	Current load am dosing point Output	%-Value
09: Scaling 2 [%]	Scaling factor 2 for internal data scalings	%-Value
10: Setpoint output [%]	Feedback of current Set point	%-Value
11: P2 Capacity [%]	Current dosing capacity at dosing point in per cent	%-Value
12: P1 Capacity [%]	Current Capacity on measuring length in per cent	%-Value
13: Deviation [%]	Deviation between nominal and actual dosing capacity	%-Value
14: Batch Finestream [%]	Batch control: variable for analog Fine stream	%-Value
15: Feeder Deviation [%]	Current Feeder deviation	%-Value
16: Distance-FIFO	Special functions: Path delay fifo	%-Value
17: Transfervalue 1	Special functions: Transfer value 1 for Data transfer	%-Value
18:Transfervalue 2	Special functions: Transfer value 2 for Data transfer	%-Value
19: Gross-Load [%]	Subtraction system: Gross weight for downstream scale	%-Value
20: Bin Load [%]	Currently Bin weight in %	%-Value
21: PreBin-Regulator [%]	Variable for Pre-bin regulator	%-Value
22: Speed [%]	Current Belt speed in per cent	%-Value
24: TW [%]	Currently used test weight in %	%-Value
25: g1RR-Load [%]	Side weight evaluation: Load rightmost	%-Value
26: g1R-Load [%]	Side weight evaluation: Load right	%-Value
27: g1L-Load [%]	Side weight evaluation: Load left	%-Value
28: g1LL-Load [%]	Side weight evaluation: Load leftmost	%-Value
29: g1 total [g]	Absolute weight at g1 section in g	Gramm
30: g3 total [g]	Absolute weight at g3 section in g	Gramm
32: BusControlBits 1	Bus Controlbits-Doubleword 1 (see following List)	Bitfield[32]
33: BusControlBits 2	Bus Controlbits-Doubleword 2 (see following List)	Bitfield[32]
34: BusControlBits 3	Bus Controlbits-Doubleword 3 (see following List)	Bitfield[32]



35: BusStatusBits1	Error / Status-Doubleword 1 (see following List)	Bitfield[32]
36: BusStatusBits2	Error / Status-Doubleword 2 (see following List)	Bitfield[32]
41: Counter A [Countingunit]	EndlessCounter A in parameterized Counter unit	
42: Counter B [Countingunit]	ShiftCounter B in parameterized Counter unit	
43: Counter C [Countingunit]	ShiftCounter C in parameterized Counter unit	
44: Counter A [kg]	non-resettable Endless counter A in kg	kg
45: Counter B [kg]	ShiftCounter B in kg	kg
46: Counter C [kg]	ShiftCounter C in kg	kg
47: Counter A [1/10 kg]	non-resettable EndlessCounter A in 100g resolution	1/10 kg
48: Counter B [1/10 kg]	ShiftCounter B in in 100g resolution	1/10 kg
49: Counter C [1/10 kg]	ShiftCounter C in in 100g resolution	1/10 kg
50: P3 Capacity [kg/h]	Current Conveying capacity at discharge point P3 in kg/h	kg
51: P3 Capacity [1/10 kg/h]	Curr. Conveying capacity at discharge point P3 in 1/10 kg/h	1/10 kg
53: WC 1 [%]	Current value at weighing channel 1	%
54: WC 2 [%]	Current value at weighing channel 2	%
55: WC 3 [%]	Current value at weighing channel 3	%
56: WC 4 [%]	Current value at weighing channel 4	%
57: WC5 [%]	Current value at weighing channel 5	%
58: Target occupancy [%]	Load Setpoint	%
59: PreBin Zone1 [g]	PreBin weight in Area 1	g
60: PreBin Zone2 [g]	PreBin weight in Area 2	g
61: PreBin Zone3 [g]	PreBin weight in Area 3	g
62: PreBin Zone4 [g]	PreBin weight in Area 4	g
63: PreBin Sum [%]	PreBin Total weight in percent	%-Value
64: PreBin Absolut [g]	PreBin Total weight absolute in percent	g
65: Parameter- Number	Special function on consultation with manufacturer	
66: Parameter- Value	Special function on consultation with manufacturer	
68: g1Rright [abs]	Total weight Belt section right hand side	
69: g1Left [abs]	Total weight Belt section left hand side	
74: AW[%]		
75: DWC 3/5 Statusword	Compatibility to former DWC3/5 Statusword	
76: DWC3/5 Relaisword	Compatibility to former DWC3/5 Relaisword	
77: DWC3/5 IW1_2	Compatibility to former DWC3/5 Inputwords	



78: DWC3/5 IW 3_4	Compatibility to former DWC3/5 Inputwords	
79: DWC3/5 IL1	Compatibility to former DWC3/5 Input double word	
80: DWC3/5 IL2	Compatibility to former DWC3/5 Input double word	



```
Digital control commands from scale computer
Bus
                0x00000001
ControlBits 1
                0x00000002
                              01: WARNING ( Sum signal )
                0x00000004
                              02: READY TO OPERATE
                0x00000008
                              03: CONVEYING SYSTEM STOPPED (inversely usable as Belt runs)
                0x00000010
                              04: EMPTY-MESSAGE
                0x00000020
                              05: G3 MIN-LOAD
                              06: G3 MAX LOAD
                0x00000040
                0x00000080
                              07: PANEL Mode active--
                              08 REMOTE- Mode active
                0x00000100
                0x00000200
                              09: DEVIATION
                0x00000400
                              10: SLIP
                0x00000800
                              11: TEST / TARE RUNS
                              12: LAY ON TEST WEIGHT
                0x00001000
                0x00002000
                              13: MAIN DRIVE ON
                0x00004000
                              14: FEEDER ON
                0x00008000
                              15: FEEDER REDUCTION
                              16: FEEDER DIRECTION (dosing drum control)
                0x00010000
                0x00020000
                              17: FEEDER OPEN (dosing drum control)
                0x00040000
                              18: FEEDER CLOSED (dosing drum control)
                0x00080000
                              19: -
                0x00100000
                              20: MOTOR SCALE (Batch mode)
                0x00200000
                              21: BATCH ENABLE (Batch mode)
                0x00400000
                              22: COARSE STREAM (Batch mode)
                0x00800000
                              23: FINE STREAM (Batch mode)
                0x01000000
                              24: -
                              25: FILLING WEIGHING BIN (Loss-in-weight dosing)
                0x02000000
                0x04000000
                              26: BIN EMPTY (Loss-in-weight dosing)
                0x08000000
                              27: MOVEMENT ERROR (Loss-in-weight dosing)
                0x10000000
                              28: DEVIATION DETECTED (Check weigher)
                0x20000000
                              29: -
                0x40000000
                              30: COUNTER SIGNAL (not usable via Bus!)
                0x80000000
                              31: LIVE BIT (inverted to Input signal)
                Digital control commands from the scale computer
                              32: FIELDRELAY 1 (reads FIELD OPTO 1)
Rus
                0x00000001
ControlBits 2
                0x00000002
                              33: FIELDRELAY 2 (reads FIELD OPTO 2)
                0x00000004
                              34: FIELDRELAY 3 (reads FIELD OPTO 3)
                0x00000008
                              35: FIELDRELAY 4 (reads FIELD OPTO 4)
                0x00000010
                              36: FIELDRELAY 5 (reads FIELD OPTO 5)
                0x00000020
                              37: FIELDRELAY 6 (reads FIELD OPTO 6)
                0x00000040
                              38: FIELDRELAY 7 (reads FIELD OPTO 7)
                0x00000080
                              39: -
                0x00000100
                              40: -
                0x00000200
                              41: STEERING-COMMAND (2 point regulator)
                0x00000400
                              42: -
                0x00000800
                              43: BELT MISRUN
                0x00001000
                              44: -
                              45: LOCAL ACTIVE
                0x00002000
                0x00004000
                              46: -
                0x00008000
                              47: -
                0x00010000
                              48: -
                              49: BELTSTEERING PULL
                0x00020000
                0x00040000
                              50: BELTSTEERING PUSH
                0x00080000
                              51: AUXILIARY DRIVE 1 ON
                0x00100000
                              52: AUXILIARY DRIVE 2 ON
                              53: AUXILIARY DRIVE 3 ON
                0x00200000
                0x00400000
                              54: AUXILIARY DRIVE 4 ON
                              55: AUXILIARY DRIVE 5 ON
                0x00800000
                0x01000000
                              56:
                0x02000000
                              57:
```



	0x04000000	58:
	0x08000000	59:
	0x10000000	60: Behälter max
	0x20000000	61: Behälter min
	0x40000000	62: SF Waagenantrieb EIN
	0x80000000	63: SF
	Digital control of	commands from the scale computer
Bus	0x00000001	reserved
CommandBits 3	to	
	0x80000000	
0	1.6	

See details about function of control bits under digital Outputs (P64xx). BusCommandbits are similar to physical digital Outputs (DO).

	Digital status i	information's from the scale computer
Bus	0x00000001	S00: WC 0 fault LOAD CELL mV FAULT CHANNEL 1 (Standard)
StatusBits 1	0x00000002	S01: WC 1 fault LOAD CELL mV FAULT CHANNEL 2
	0x00000004	S02: WC 2 fault LOAD CELL mV FAULT CHANNEL 3
	0x00000008	S03: WC 3 fault LOAD CELL mV FAULT CHANNEL 4
	0x00000010	S04: WC 4 fault LOAD CELL mV FAULT CHANNEL 5
	0x00000020	S05: WC 5 fault LOAD CELL mV FAULT CHANNEL 6
	0x00000040	S06: -
	0x00000080	S07: -
	0x00000100	S08: BELT EMPTY
	0x00000200	S09: DISCHARGE END WEIGHT LESS THAN MIN
	0x00000400	S10: DISCHARGE END WEIGHT GREATER THAN MAX
	0x00000800	S11: -
	0x00001000	S12: DRIVE/ TACHO FAULT
	0x00002000	S13: SYNC ERROR (Belt Startmarker)
	0x00004000	S14: FEEDER ERROR
	0x00008000	S15: BELT MIS RUN
	0x00010000	S16: SLIP
	0x00020000	S17: DRIVE STOPPED
	0x00040000	S18: Set point ERROR
	0x00080000	S19: DEVIATION –
	0x00100000	S20: -
	0x00200000	S21: BELT MIS RUN LEFT
	0x00400000	S22: BELT MIS RUN RIGHT
	0x00800000	S23: TENSION CLEANING CHAIN (autom. cleaning device)
	0x01000000	S24: TARE ERROR
	0x02000000	S25: TEST ERROR
	0x04000000	S26: FILLING REQUIREMENT (Loss-in-weight-dosing)
	0x08000000	S27: MOVEMENT ERROR (Loss-in-weight-dosing)
	0x10000000	S28: DECENTRALE IO OFFLINE
	0x20000000	S29: -
	0x40000000	S30: EMERGENCY AKTIV
	0x80000000	S31: FELDBUS OFFLINE (Kommunikation zur übergeordneten Steuerung)
		information's from the scale computer
Bus	0x00000001	S32: MM00 Error
StatusBits 2	0x00000002	S33: MM00 Inverter failure
	0x00000004	S34: MM00 Offline
	0x00000008	S35: -
	0x00000010	S36: MM01 Error
	0x00000020	S37: MM01 Inverter failure
	0x00000040	S38: MM01 Offline
	0x00000080	S39: -
	0x00000100	S40: MM10 Error
	0x00000200	S41: MM10 Inverter failure
	0x00000400	S42: MM10 Offline
	0x00000800	S43: -

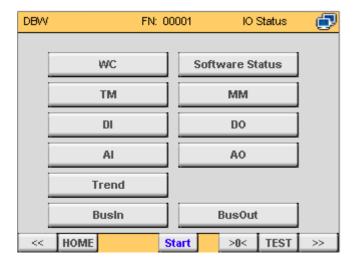


```
0x00001000
             S44: MM11 Error
0x00002000
             S45: MM11 Inverter failure
0x00004000
             S46: MM11 Offline
0x00008000
             S47: -
0x00010000
             S48: XD1 speed monitoring
0x00020000
             S49: XD1 fault
0x00040000
             S50: -
0x00080000
             S51: XD2 speed monitoring
0x00100000-
             S52: XD2 fault
0x00200000
             S53: -
0x00400000
             S54: XD3 speed monitoring
0x00800000
             S55: XD3 fault
0x01000000
             S56: -
             S57: XD4 speed monitoring
0x02000000
0x04000000
             S58: XD4 fault
0x08000000
             S59: -
0x10000000
             S60: XD5 speed monitoring
0x20000000
             S61: XD5 fault
             S62: -
0x40000000
0x80000000
             S63: -- -
```

See details about function of status bits under error messages Outputs (P22xx andP23xx). Bus Statusbits are similar to status display messages.



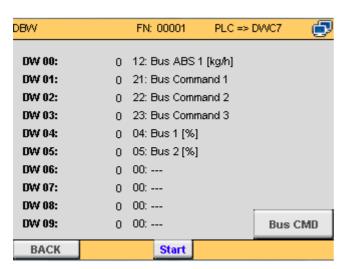
7 Testscreen for Fieldbus-Interface



It is possible to control the data transfer of the Fieldbus interface. Thereto the arrow keys bottom left or right have to be pressed so often until this selection appears.

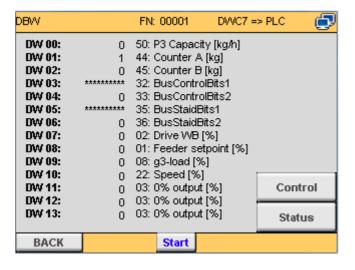
BusIn indicates the DWC-7 Set points

BusOut indicates the DWC-7 actual values



BusIn / DWC-7 Set points

The input values transferred by the central control are represented.

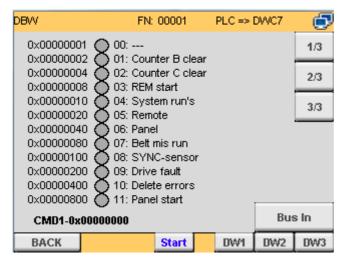


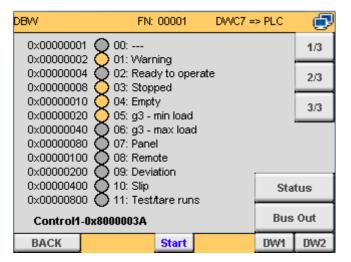
BusOut / DWC-7 actual values

The process data transferred to the central control are represented.

The representation of the number values is done in the decimal number system. Additionally the denomination of the data field is represented in clear text corresponding to the parameterisation in group P71xx.







BusIn / DWC-7 BusCommand DW 1-3

Via "Bus CMD" button the detail display of the possible BusCommands are activated. Hereby the respective double word is broken into bits. By pressing the button DW1-DW3 (bottom right) it can be switched between the double words.

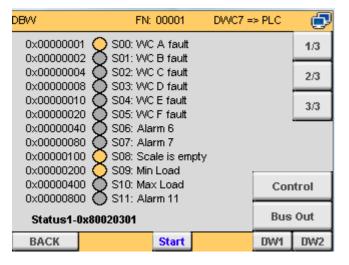
The switching takes place through the button "1/3", "2/3" and "3/3" on the right top of the page.

In the first column the bit mask is represented in HEX. In the second column the switch status of the respective command is located and in the last column the digital control command is located.

BusOut / DWC-7 Control Bits 1-3

The detailed representation of control bits DW1 and DW2 will be presented by the control button among Feld Bus Out.

The operation takes place as described in the previously image.



BusOut / DWC-7 Control Bits 1-3

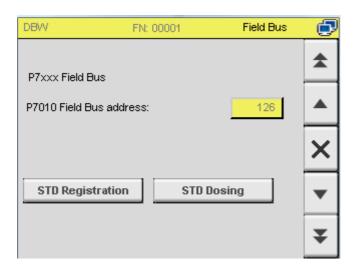
The detailed representation of the status double word 1 and 2 will be presented by the status button among Feld Bus Out.

The handling is identical to the double words for control bits and command bits.



8 PARAMETER DESCRIPTION (P7xxx)

8.1 General Fieldbus Parameters (P70xx)



Parameter group "Fieldbus" permits adjustment and change of communication possibilities to a central control.

These functions are available only if a Fieldbus option has been acquired and licenced by the manufacturer.

P7010	ProfiBus DP address:		INT
	Selection see P7200	Range:	1-124
Description:	This parameter determines the Profibus address.		
Indication:	This parameter is visible only if into the scale con and correctly recognized by the system.	nputer a licenced Profibus card has	been installed
Dependence:	Profibus card installed and licenced. (R9700)		

8.2 Setpoints and Commands via Fieldbus (P72xx)

P7200	Busin DW0:		INT
	Selection: 00:	Range:	0-34
	01:		
	02:		
	03:		
	04: Bus Percent 1		
	05: Bus Percent 2		
	06: Bus Percent 3		
	07: Bus Percent 4		
	08: Bus ABS 1		
	09: Bus ABS 2		
	10: Bus ABS 3		
	11: Bus ABS 4		
	12: Bus ABS 1 [kg/h]		



Indication:

range is used

	13: Bus ABS 2 [kg/h]
	14: Bus ABS 3 [kg/h]
	15: Bus ABS 4 [kg/h]
	16: Bus ABS 1 [1/10 kg/h]
	17: Bus ABS 2 [1/10 kg/h]
	18: Bus ABS 3 [1/10 kg/h]
	19: Bus ABS 4 [1/10 kg/h]
	20:
	21: Bus Command 1
	22: Bus Command 2
	23: Bus Command 3
	24:
	25: Parameter Number
	26: Parameter Value
	27:
	28:
	29:
	30: DWC3/5 CMD
	31: DWC3/5 SW1_2
	32: DWC3/5 SW3_4
	33: DWC3/5 SL1
	34: DWC3/5 SL2
scription:	This parameter determines how the 1st input Set point-Double word DW0 of the Fieldbus-Set po

P7201	Busin DW1:		INT
	Selection: see P7200	Range:	0-30
Description:	This parameter determines how the 2nd i range is used.	nput Set point-Double word DW1 of the Fiel	dbus-Set point
Indication:	Please, find details concerning function in	n the previous chapters.	

Please, find details concerning function in the previous chapters.

P7202	BusSoll DW2:		INT
	Selection: see P7200	Range:	0-30
Description:	This parameter determines how the 3rd inprange is used.	out Set point-Double word DW2 of the Fiel	dbus-Set point
Indication:	Please, find details concerning function in	the previous chapters.	

P7203	Busin DW3:		INT
	Selection: see P7200	Range:	0-30
Description:	This parameter determines how the 4th inpurange is used.	ut Set point-Double word DW3 of the Fiel	dbus-Set point
Indication:	Please, find details concerning function in the	ne previous chapters.	

P7204	Busin DW4:	IN'
-------	------------	-----



	Selection: see P7200	Range:	0-30
Description:	This parameter determines how the 4th inprange is used.	out Set point-Double word DW4 of the Field	lbus-Set point
Indication:	Please, find details concerning function in	the previous chapters.	

P7205	Busin DW5:		INT
	Selection: see P7200	Range:	0-30
Description:	This parameter determines how the 5th ingrange is used.	out Set point-Double word DW5 of the Fig	eldbus-Set point
Indication:	Please, find details concerning function in	the previous chapters.	

P7206	Busin DW6:		INT
	Selection: siehe P7200	Range:	0-30
Description:	This parameter determines how the 6th inpurange is used.	ut Set point-Double word DW6 of the Fig	eldbus-Set point
Indication:	Please, find details concerning function in the	ne previous chapters.	

P7207	BusIn DW7:		INT
	Selection: siehe P7200	Range:	0-30
Description:	This parameter determines how the 7th inprange is used.	ut Set point-Double word DW7 of the Fig	eldbus-Set point
Indication:	Please, find details concerning function in the	ne previous chapters.	

P7208	Busin DW8:		INT
	Selection: siehe P7200	Range:	0-30
Description:	This parameter determines how the 8th ingrange is used.	out Set point-Double word DW8 of the Fie	eldbus-Set point
Indication:	Please, find details concerning function in	the previous chapters.	

P7209	Busin DW9:		INT
	Selection: siehe P7200	Range:	0-30
Description:	This parameter determines how the 9th inp range is used.	ut Set point-Double word DW9 of the Fi	eldbus-Set point
Indication:	Please, find details concerning function in t	he previous chapters.	

8.3 Actual values and Control/Statusbits via Fieldbus (P74xx)



P7400	BusOut	DW0:		INT
		00: P3 Capacity [%]	Range:	0-80
		01: Feeder setpoint [%]	•	0 00
		02: Drive WB [%]		
		03: 0% output [%]		
		04: 50% output [%]		
		05: 100% output [%]		
		06: g1-load [%] 07: g2-load [%]		
		07. g2-load [%] 08: g3-load [%]		
		09: Scaling 2 [%]		
		10: Setpoint output [%]		
		11: P2 Capacity [%]		
		12: P1 Capacity [%]		
		13: Deviation [%]		
		14: Batch Finestream [%]		
		15: Feeder Deviation [%] 16: Distance-FIFO		
		17: Transfervalue 1		
		18:Transfervalue 2		
		19: Gross-Load [%]		
		20: Bin Load [%]		
		21: PreBin-Regulator [%]		
		22: Speed [%]		
		23:		
		24: TW [%]		
		25: g1RR-Load [%] 26: g1R-Load [%]		
		27: g1L-Load [%]		
		28: g1LL-Load [%]		
		29: g1 total [g]		
		30: g3 total [g]		
		31:		
		32: BusControlBits1 33: BusControlBits2		
		34: BusControlBits3		
		35: BusStatusBits1		
		36: BusStatusBits2		
		37:		
		38:		
		39:		
		40: 41: Counter A [CountingUnit]		
		42: Counter B [CountingUnit]		
		43: Counter C [CountingUnit]		
		44: Counter A [kg]		
		45: Counter B [kg]		
		46: Counter C [kg]		
		47: Counter A [1/10 kg]		
		48: Counter B [1/10 kg]		
		49: Counter C [1/10 kg] 50: P3 Capacity kg/h		
		51: P3 Capacity 1/10 kg/h		
		52:		
		53: LC 1 [%]		
		54: LC 2 [%]		
		55: LC 3 [%]		
		56: LC 4 [%]		
		57: LC5 [%]		
		58: Load Setpoint [%]		



	59: PreBin weight in Zone 1
	60: PreBin weight in Zone 2
	61: PreBin weight in Zone 3
	62: PreBin weight in Zone 4
	63: PreBin Total weight in percent
	64: PreBin Total weight absolute in gram
	65: Parameter- Number
	66: Parameter- Value
	67:
	68: g1Rright [abs]
	69: g1Left [abs]
	70:
	74: AW[%]
	75: DWC 3/5 Statuswort
	76: DWC3/5 Relaiswort
	77: DWC3/5 IW1_2
	78: DWC3/5 IW 3_4
	79: DWC3/5 IL1
	80: DWC3/5 IL2
Description:	This parameter determines which value via the 1st actual value-Double word DW00 of the Fieldbus
	output range is transferred to a central control.
Indication:	Please, find details concerning function in the previous chapters.
· · · · · · · · · · · · · · · · · · ·	

P7401	BusOut DW1:		INT
	Selection: see P7200	Range:	0-80
Description:	This parameter determines which value via the output range is transferred to a central control		of the Fieldbus
Indication:	Please, find details concerning function in the	previous chapters.	

P7402	BusOut DW2:		INT
	Selection: see P7200	Range:	0-80
Description:	This parameter determines which value via the output range is transferred to a central control		of the Fieldbus
Indication:	Please, find details concerning function in the	e previous chapters.	

P7403	BusOut DW3:		INT
	Selection: see P7200	Range:	0-80
Description:	This parameter determines which value via output range is transferred to a central cont		3 of the Fieldbus
Indication:	Please, find details concerning function in the	ne previous chapters.	

P7404	BusOut DW4:		INT
	Selection: see P7200	Range:	0-80
Description:	This parameter determines which value via the output range is transferred to a central control		4 of the Fieldbus
Indication:	Please, find details concerning function in the	previous chapters.	



P7405	BusOut DW5:		INT
	Selection: see P7200	Range:	0-80
Description:	This parameter determines which value via th output range is transferred to a central contro		5 of the Fieldbus
Indication:	Please, find details concerning function in the	previous chapters.	

P7406	BusOut DW6:		INT
	Selection: see P7200	Range:	0-80
Description:	This parameter determines which value via the output range is transferred to a central control.	7th actual value-Double word DW06	of the Fieldbus
Indication:	Please, find details concerning function in the p	revious chapters.	

P7407	BusOut DW7:		INT
	Selection: see P7200	Range:	0-80
Description:	This parameter determines which value via the output range is transferred to a central control.		7 of the Fieldbus
Indication:	Please, find details concerning function in the	e previous chapters.	

P7408	BusOut DW8:		INT
	Selection: see P7200	Range:	0-80
Description:	This parameter determines which value via the output range is transferred to a central control.		of the Fieldbus
Indication:	Please, find details concerning function in the p	previous chapters.	

P7409	BusOut DW9:		INT
	Selection: see P7200	Range:	0-80
Description:	This parameter determines which value via the output range is transferred to a central control.		of the Fieldbus
Indication:	Please, find details concerning function in the	orevious chapters.	

P7410	BusOut DW10:		INT
	Selection: see P7200	Range:	0-80
Description:	This parameter determines which value via the output range is transferred to a central control.		of the Fieldbus
Indication:	Please, find details concerning function in the	previous chapters.	

P7411	BusOut DW11:		INT
	Selection: siehe P7200	Range:	0-80
Description:	This parameter determines which value via output range is transferred to a central control con		f the Fieldbus

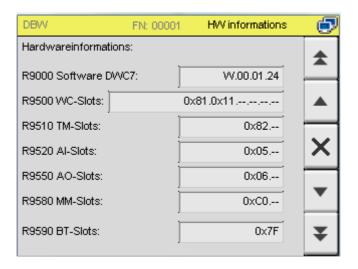


Indication: Please, find details concerning function in the previous chapters.

P7412	BusOut DW12:		INT
	Selection: siehe P7200	Range:	0-80
Description:	This parameter determines which value via the output range is transferred to a central control.		2 of the Fieldbus
Indication:	Please, find details concerning function in the	e previous chapters.	

P7413	BusOut DW13:		INT
	Selection: siehe P7200	Range:	0-80
Description:	This parameter determines which value via the 14th actual value-Double word DW13 of the Fieldbus output range is transferred to a central control.		of the Fieldbus
Indication:	Please, find details concerning function in the previous chapters.		

R9700	FieldbusSlot:	
	Selection: none	Range:
Beschreibung:	This read only parameter shows the type of the Fieldbus card recognized by the system.	
Indication:	This parameter is set by the scale computer itself and is unchangeable by the user.	



8.4 Compatiblity-mode to former DWC-5 Systems

In critical cases, the parameters Bus in- and output parameters can be set to compatibility mode, largely represent the bit patterns of old KUKLA DWC-5 devices.

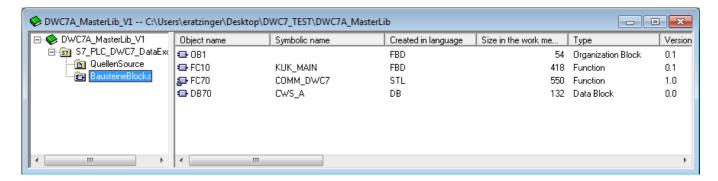
This mode should only be used if a short-term adaptation of the higher-level control program in the PLC is not possible. The DWC-7 communication standard must be used in any case for new systems.

The hardware description files, depending on the bus system used (GSD, EDS, GDML, etc.), must be changed in any case due to hardware IDs differences.



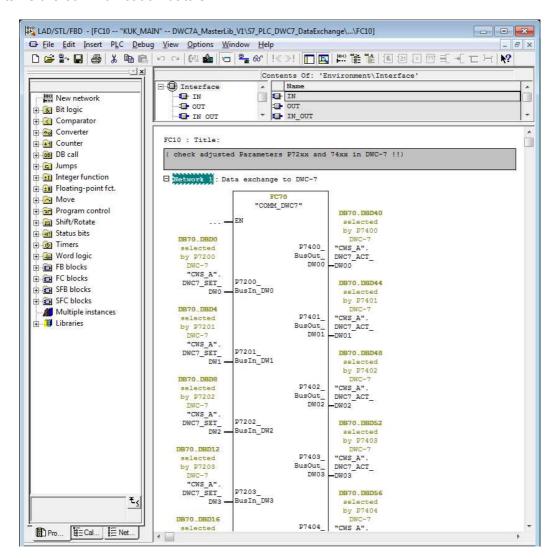
9 Library for S7-Classic (Profibus / Profinet)

For easy integration of DWC-7 devices in a local S7 a suitable library can be requested by KUKLA



Following blocks are relevant:

FC 10 calls on the KUKLA prepared real communication block FC70. DB70 contains the communication data's.



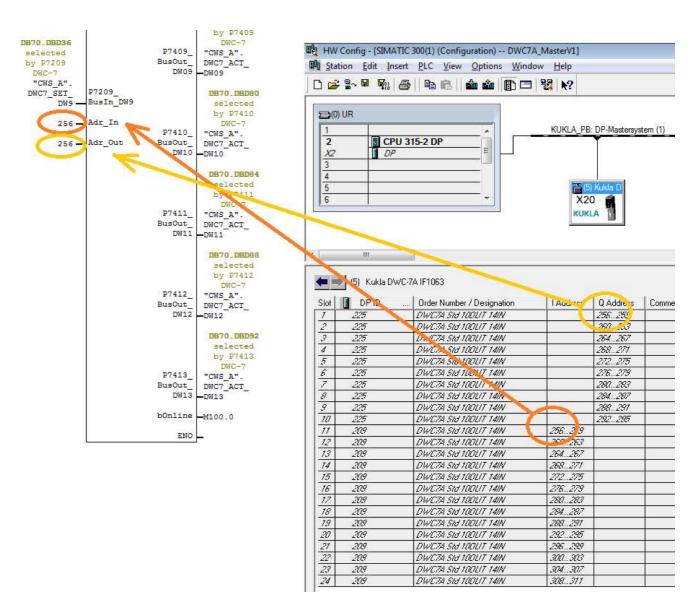
All nominal values, who will be sent from SPS to DWC-7, are connected on the left chip side. All process data values, who be sent from the scale to the central SPS, are connected on the right side.



In this example the dates will be saved in data block DB70, the user can also connect other data blocks or flags.

9.1 Integration Hardware-Addresses

Very important is the right connection of the variables Adr_In and Adr_Out at the bottom of the block.



The basic addresses provide the connection between the decentralized peripherals and the communication block FC70. If more DWC-7 are coupled onto one SPS are the necessarily result a new address for every new device.

For each additionally DWC-7 on the same bus the FC70 must be called again in a new network. In this case of course new memory variables have to be connected (e.g. by copy DB70 to DB7x).



Notes: