



UNIVERSITY OF TALCA
ENGINEERING FACULTY
CIVIL COMPUTER ENGINEERING SCHOOL

**Experimental analysis of (I)IQS to fine-tune
support for arrays with repeated elements**

ERIK ANDRÉS REGLA TORRES

Supervisor: RODRIGO PAREDES

Thesis to apply for a Civil Com-
puter Engineer degree

Curicó – Chile
mes, año



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Guide: RODRIGO PAREDES

Advisor: HUEÓN 1

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This document was graded with a score of: _____

Curicó – Chile

mes, año

Dedicated to... someone ?

ACKNOWLEDGEMENTS

Agradecimientos a ... (how the fuck do I choose whom to acknowledge?)

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SUMMARY

I'm gonna write the summary as the last part.

1. Introduction

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1.1 Context

Aquí va el texto de la primera sección del capítulo 1...

1.2 Application areas

Aquí va el texto de la primera subsección de la primera sección del capítulo 1...

1.3 Problem description

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1.4 Goals

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1.4.1 General goals

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1.4.2 Specific goals

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1.6 Problem description

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2. Background

2.1 Sorting algorithms

One of the basic problems on algorithm design is the *sorting problem*, defined as for a given input sequence A of n numbers $\langle a_1, a_2, \dots, a_n \rangle$ to find a permutation $A' = \langle a'_1, a'_2, \dots, a'_n \rangle$ that yields $\forall a'_i \in A', a'_1 \leq a'_2 \leq \dots \leq a'_n$.

Sorting algorithms are commonly used as intermediate steps for other processes, making them one of the most fundamental procedures to execute on computing problems, and strategies for solving this problem can vary depending on the input case constraints. For example, the number of repeated elements, their distribution, if there is some known info beforehand to accelerate the process, etc.

2.1.1 Types of sorting algorithms

The best reference on how to classify and understand which algorithm is best suitable for a given case is *A survey of adaptive sorting algorithms* by Vladimir Estivil[1] which gathers all the information at that time regarding *adaptive sorting algorithms* [2], *disorder measures* and *expected-case and worst-case* sorting.

A sorting algorithm is said to be adaptive if the time taken to solve the problem is a smooth growing function of the size and the measure of disorder of a given sequence. Note that the term array is not used on this definition as it extrapolates any generic sequence that is not bound to be contiguous.

2.1.2 Measuring disorder

The concept of disorder measure is highly relative to the problem to be solved and as expected, not all measures work for all cases. One of the most common metrics used

on partition-based algorithms is the *number of inversions* required to sort a given array. While this holds true for algorithms like *insertsort* which have their running time affected by how the elements are arranged in the sequence, it's not the case of *mergesort*, which is not an adaptive algorithm given that has a stable running time regardless on how the elements are distributed. Whilst the running time is a function of the size, it's not in function of the sequence. Estivil [1] on his survey describes ten functions that can be used to measure disorder on an array when used on adaptive sorting algorithms.

Expected case and Worst-case adaptive internal sorting

One of the classification of adaptive sorting algorithms is the *Expected-case adaptive (internal) sorting*, on which their design is driven by that worst cases are unlikely to happen in practice so, there is no harm on using it, in contrast of the definition of *Worst-case adaptive (internal) sorting*, which assumes a pessimistic view hence the design is driven to ensure a deterministic worst case running time and asymptotic complexity.

The approach taken by such algorithms can be classified as *distributional*-in which a “natural distribution” of the sequence is expected to be solved- or *randomized* - on which their behaviour is not related on how the sequence is distributed at all-. There is a huge problem when dealing with distributional approaches as they tend to be very sensible to changes on the sequence distribution, making them suitable to highly constrained problems on specific-purpose algorithm.

On the other hand, randomized approaches have the benefit of generality and being rather simple to port to other implementations due to their nature.

By example, let's take as example the QuickSelect algorithm -which is the basis of IQS which will be explained in detail later- used to find the element that belongs to the $k - th$ position on a given sequence A . This searching algorithm can be classified as *partition-based*, given that the process in charge of preserving the invariant is the partition stage.

As it can be seen, the behaviour of *quickselect* depends on how the element is selected in the *select* procedure. Then, we can implement two versions of *select*, namely *select_{fixed}* and *select_{random}* which yields different values in order to introduce randomization into *quickselect*.

Algorithm 1 QuickSelect definition

```

1: procedure quickselect( $A, i, j, k$ )
2:    $pIdx \leftarrow select(i, j)$ 
3:    $pIdx \leftarrow partition(A, i, j)$ 
4:   if  $pIdx = k$  then return  $A_k$ 
5:   if  $pIdx < k$  then return quickselect( $A, k, j$ )
6:   if  $pIdx > k$  then return quickselect( $A, i, k$ )

```

Algorithm 2 Fixed Selection

```

1: procedure select_fixed( $i, j$ )
2:   return  $\frac{(i+j)}{2}$ 

```

In such cases, whilst the randomized version of QuickSelect will take average time of $n \log_2 n$ to complete the task, we can see that for the fixed pivot version, it depends on the distribution of data, which can bias the pivot result. Now we have two versions of QuickSelect algorithm, with both distributional and randomized strategies.

Algorithm 3 Random selection

```

1: procedure select_random( $i, j$ )
2:   return random_between( $i, j$ )

```

2.2 IQS and IIQS

2.2.1 IQS

Algorithm overview

Worst case

2.2.2 IIQS

Algorithm overview

Use cases

2.3 Experimental algorithms methodology overview

2.3.1 Design of experiments

Pilot experiments

Workhorse experiments

2.3.2 Data management and analysis

Random systematic data

Variance

3. Methodology

3.1 Experimental design and goals

3.1.1 Instances of test cases

Ordered unique

Random unique

Distributed repeated

Distributed repeated with random unique portion

3.1.2 Pilot experiments

Incremental version of BFPRT

Introspective step rule changes

Three-way partition pivot location bias

Three-way partition pivot store

Change rules to store pivots

3.2 Metrics

Number of inversions

Local entropy decay

Execution time (rsu)

BFPRT executions

Partitioner executions

3.3 Tuning

3.3.1 Data generation and execution control

4. Experiment stage

4.1 Experimental setup

4.2 Experimental results

4.3 Metrics and indicators

5. Segundo Capítulo

Glossary

El primer término: Este es el significado del primer término, realmente no se bien lo que significa pero podría haberlo averiguado si hubiese tenido un poco mas de tiempo.

El segundo término: Este si se lo que significa pero me da lata escribirlo...

Bibliography

- [1] Vladmir Estivill-Castro and Derick Wood. A survey of adaptive sorting algorithms. *ACM Comput. Surv.*, 24(4):441–476, December 1992.
- [2] Kurt Mehlhorn. *Data Structures and Algorithms 1*. Springer Berlin Heidelberg, 1984.

ANNEX

A. El Primer Anexo

Aquí va el texto del primer anexo...

A.1 La primera sección del primer anexo

Aquí va el texto de la primera sección del primer anexo...

A.2 La segunda sección del primer anexo

Aquí va el texto de la segunda sección del primer anexo...

A.2.1 La primera subsección de la segunda sección del primer anexo

B. El segundo Anexo

Aquí va el texto del segundo anexo...

B.1 La primera sección del segundo anexo

Aquí va el texto de la primera sección del segundo anexo...