

Date

Time

Examination : B.Tech Semester-IV

: 20/03/2024

: 01:00 P.M.-02:15 P.M.

## DHARMSINH DESAI UNIVERSITY, NADIAD FACULTY OF TECHNOLOGY THIRD SESSIONAL

SUBJECT: (CE-417) COMPUTER SYSTEM ARCHITECTURE

Seat No Day

Max. Marks : 36

: Wednesday

	I	NST	RUCTI	ONS:	
	199	1.		s to the right indicate maximum marks for that question.	
		2.	The sy	mbols used carry their usual meanings.	
		3.		e suitable data, if required & mention them clearly.	
		4.	Draw 1	neat sketches wherever necessary.	
			51 13		
Q.1	Do as				[12]
	CO <sub>3</sub>	E	(a)	Identify the 8085 instruction from information of Timing Diagram: Instruction Size is	[2]
				1-Byte. It has 2 Machine cycles: Opcode Fetch, Memory Write. Justify.	
	CO <sub>3</sub>	A	(b)	Calculate the timing delay for the following code. Assume the frequency of the	[2]
				microprocessor is 4 MHz.	
				MVI B, 0AH; 7 T-states	
				REPEAT: DCR B; 4 T-states	
				JNZ REPEAT; 7/10 T-states	
	CO <sub>3</sub>	R	(c)		[2]
	COS	11	(0)	issue?	[-]
	CO2	TT	(4)	What is structural Hazard in the pipelined system? Give suitable example and write	[2]
	COZ	U	(u)		[2]
	COA		( )	possible solution for the structural hazard.	<b>503</b>
	CO <sub>2</sub>	A	(e)	Consider Instruction Pipeline with 4 stages each with combinational circuit only. Buffer	[2]
				registers are required between each stage and at the end of last stage. Delays for the	
				stages are 5,6,11,8ns respectively. Delay for buffer register is 1ns. Find out the speedup	
				of the pipeline.	
	CO <sub>2</sub>	N	(f)	Compare and contract Hardwined and Microprogrammed Control Unit	
	-	14	(1)	Compare and contrast Hardwired and Microprogrammed Control Unit.	[2]
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## Q.3 Attempt the following questions.

[12]

CO2 U (a) Considering control hazards in the pipeline, explain how branch delay can be reduced from 3-Cycle to 1-Cycle?

[2] [4]

What is Branch Target Buffer? How can that be used with 2-bit dynamic branch ii. predictor to reduce branch delay?

[6]

CO2 A (b) Consider Micro-programmed Control Unit which supports 240 instructions, each of which on an average takes 16 Micro-operations. They support 16 flag conditions and 150 control signals. Find out the length of Micro-Instruction and size of the Control Memory for each of the following control unit design strategy:

- Horizontal Micro-programming.
- ii. Vertical Micro-programming.
- iii. Control signals are divided into 5 mutually exclusive groups, each group having 30, 60, 12, 40, 8 control signals respectively.

**CO2** N (a) Consider the sequence of machine instructions using R0 to R8 registers:

[6]

MUL R5, R0, R1; R5=R0\*R1 DIV R6, R2, R3; R6=R2/R3 ADD R7, R5, R6; R7=R5+R6 SUB R8, R7, R4; **R8=R7-R4** 

This sequence of instructions is to be executed in a pipelined instruction processor with the following 5 stages: (1) Instruction Fetch (IF) (2) Decode (ID), (3) Operand Fetch (OF), (4) Perform Operation (PO) and (5) Write back the Result (WB).

The IF, ID, OF and WB stages take 1 clock cycle each for any instruction.

The PO stage takes 1 clock cycle for ADD or SUB instruction, 3 clock cycles for MUL instruction and 5 clock cycles for DIV instruction.

The pipelined processor uses operand forwarding from the PO stage to the OF stage. Find out the number of clock cycles taken for the execution of the above sequence of instructions. Show the detailed space-time diagram for the execution of above sequence.

**CO2 C** (b) Consider the following state diagram.

Is it Mealy machine or Moore Machine? Why? i.

[1]

[4]

ii. Assume One-Hot Encoding technique is used, how many flipflops are required to implement the control unit? Write equations for obtaining next states of flipflops. Write equations for obtaining output control signals C<sub>0</sub> C<sub>1</sub>,C<sub>2</sub>,C<sub>3</sub>,C<sub>4</sub>,C<sub>5</sub>.

[1]

If you have used Classical Method for Control unit design, how many flipflops iii. are required to implement the control unit?

