## Numerical Optimization - Handin 3

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### 3.2

When  $0 < c_2 < c_1 < 1$ , it means that there will be a *Line of Sufficient Decrease* which is steeper than the *desired slope* line. In figure 1, I've placed the Line of Sufficient Decrease in such a way, that the interval of the function which upholds the Line of Sufficient Decrease is too does not intersect with the desired slope of the function.

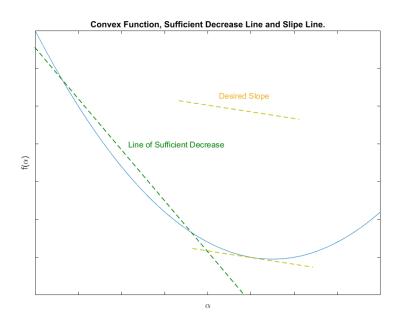


Figure 1: Function where Wolfe Conditions doesn't hold.

This results in no stepline being able to be chosen for the function in figure 1.

The strongly convex quadratic function has form

$$f(x) = \frac{1}{2}x^T Q x - b^T x$$

From page 42 in the book it's given that

$$\nabla f(x) = Qx - b \tag{1}$$

The descent direction can be defined as

$$\phi(\alpha) = f(x + \alpha p)$$

Which has the derivative (page 33 in the book)

$$\phi'(\alpha) = \nabla f(x_k + \alpha_k p_k)^T p_k$$

Which means the minimizer must fulfil the following:

$$\nabla f(x_k + \alpha_k p_k)^T p_k = 0 \tag{2}$$

Combining these two  $\nabla$ 's into a singular expression, gives

$$(Q(x + \alpha p) - b)^{T} p = 0$$
$$(Qx + Q\alpha p - b)^{T} p = 0$$
$$(Qx - b)^{T} p + \alpha p^{T} Q p = 0$$
$$\alpha = -\frac{(Qx - b)^{T} p}{p^{T} Q p}$$

And remembering (1):

$$\alpha_k = -\frac{\nabla f_k^T p_k}{p_k^T Q p_k} \tag{3}$$

#### 3.1

#### Steepest Descent

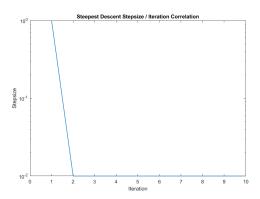


Figure 2: Stepsize  $\alpha$  for Steepest Descent on Rosenbrock starting in  $[1.2, 1.2]^T$ 

Figure 2 shows my stepsize,  $\alpha$ , after having implemented Backtracking - Steepest Descent in matlab for the rosenbrock function. The implementation ended having to break its search loop due to max iterations reached, but ended at a coordinate of  $x^* = (0.9949, 0.9781)$  which is close, in my opinion, to the real minimum of (1,1). The stepsizes reduce in size rapidly within the first iterations, after which my implementation settles with the same stepsize.

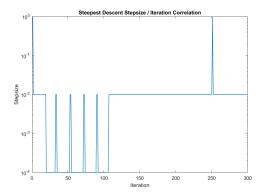


Figure 3: Stepsize  $\alpha$  for Steepest Descent on Rosenbrock starting in  $[-1.2,1]^T$ 

Looking at Figure. 3, as mentioned in the exercise the second start location was a bit harder for my implementation to handle. Approximating a minimum at  $x^* = (0.9945, 0.9780)$ , it did come close, but when looking at the stepsizes they vary quite a bit in the first 100 iterations, clearly having problems with the rosenbrock function, after which the stepsize remains steady, until it suddenly jumps to a stepsize of 1 before returning to the previous stepsize.

#### Newton Method

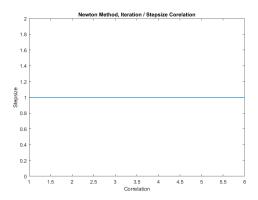


Figure 4: Stepsize  $\alpha$  for Newton Method on Rosenbrock starting in  $[1.2, 1.2]^T$ 

Within 5 iterations my Newton Method found the minimum, within a certainty of  $10^{-7}$ , but the stepsize remained 1 through all the iterations.

#### Newton Method

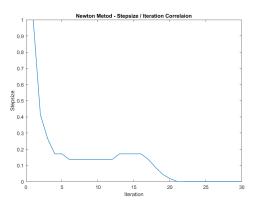


Figure 5: Stepsize  $\alpha$  for Newton Method on Rosenbrock starting in  $[-1.2, 1]^T$ 

This time my Newton Method failed to find the right answer. Only getting to other locations such as (-0.8254, 0.6584), depending on the initial values for c and p.